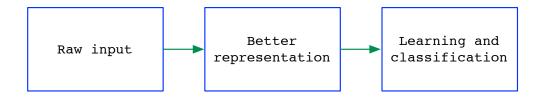
Representation learning

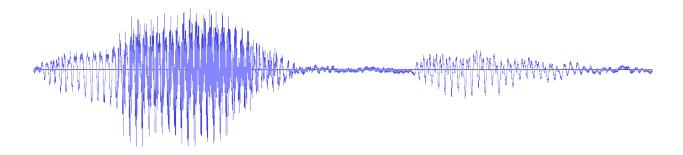
Representation learning



Good representations make learning easier.

- They bring out the true degrees of freedom in the data.
- They capture relevant structure at multiple scales.
- They screen out noisy or irrelevant structure.

Degrees of freedom



Usual representation of speech:

- Take overlapping windows of the speech signal
- Apply many filters within each window
- More filters ⇒ higher dimensional

Yet it comes from a physical system with a few degrees of freedom.

Multiscale structure



Commonly-occurring structure at many levels.

Representation learning: goals

Learn underlying degrees of freedom and multiscale structure from the statistics of unlabeled data, e.g.:

- Clustering
- Linear projections
- Embedding and manifold learning
- Metric learning
- Autoencoders

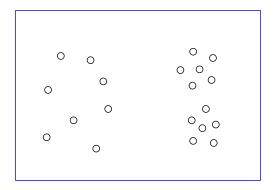
Or learn a representation in tandem with the classifier: deep learning.

Clustering with the *k*-means algorithm I

Topics we'll cover

- 1 The clustering problem
- 2 Two uses of clustering
- \odot The k-means cost function and algorithm
- 4 Initializing Lloyd's algorithm

Clustering in \mathbb{R}^d



Two common uses of clustering:

- Vector quantization
 Find a finite set of representatives that provides good coverage of a complex, possibly infinite, high-dimensional space.
- Finding meaningful structure in data Finding salient grouping in data.

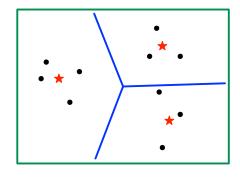
Widely-used clustering methods

- 1 K-means and its many variants
- 2 EM for mixtures of Gaussians
- 3 Agglomerative hierarchical clustering

The *k*-means optimization problem

- Input: Points $x_1, \ldots, x_n \in \mathbb{R}^d$; integer k
- Output: "Centers", or representatives, $\mu_1, \ldots, \mu_k \in \mathbb{R}^d$
- Goal: Minimize average squared distance between points and their nearest representatives:

$$cost(\mu_1, ..., \mu_k) = \sum_{i=1}^n \min_j ||x_i - \mu_j||^2$$

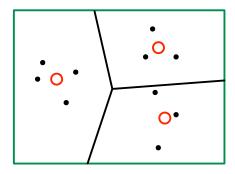


The centers partition \mathbb{R}^d into k convex regions: μ_j 's region consists of points for which it is the closest center.

Lloyd's *k*-means algorithm

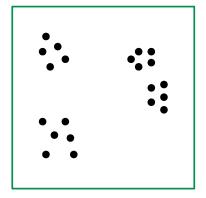
The k-means problem is NP-hard. Most popular heuristic: "k-means algorithm".

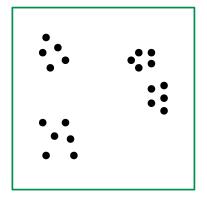
- Initialize centers μ_1, \ldots, μ_k in some manner.
- Repeat until convergence:
 - Assign each point to its closest center.
 - Update each μ_i to the mean of the points assigned to it.



Each iteration reduces the cost \Rightarrow convergence to a local optimum.

Initialization matters





Initializing the *k*-means algorithm

Typical practice: choose k data points at random as the initial centers.

Another common trick: start with extra centers, then prune later.

A particularly good initializer: k-means++

- Pick a data point x at random as the first center
- Let $C = \{x\}$ (centers chosen so far)
- Repeat until desired number of centers is attained:
 - Pick a data point x at random from the following distribution:

$$\Pr(x) \propto \operatorname{dist}(x, C)^2$$
,

where dist
$$(x, C) = \min_{z \in C} ||x - z||$$

• Add *x* to *C*

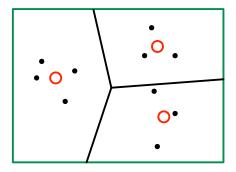
Clustering with the *k*-means algorithm II

Topics we'll cover

- 1 Two uses of k-means clustering
- 2 Clustering in a streaming or online setting

Lloyd's *k*-means algorithm

- Initialize centers μ_1, \ldots, μ_k in some manner.
- Repeat until convergence:
 - Assign each point to its closest center.
 - Update each μ_i to the mean of the points assigned to it.



Each iteration reduces the cost \Rightarrow convergence to a local optimum.

Two common uses of clustering

- Vector quantization
 Find a finite set of representatives that provides good coverage of a complex, possibly infinite, high-dimensional space.
- Finding meaningful structure in data Finding salient grouping in data.

Representing images using *k*-means codewords

How to represent a collection of images as fixed-length vectors?



- Take all $\ell \times \ell$ patches in all images. Extract features for each.
- Run *k*-means on this entire collection to get *k* centers.
- Now associate any image patch with its nearest center.
- Represent an image by a histogram over $\{1, 2, \dots, k\}$.

Looking for natural groups in data

"Animals with attributes" data set

- 50 animals: antelope, grizzly bear, beaver, dalmatian, tiger, ...
- 85 attributes: longneck, tail, walks, swims, nocturnal, forager, desert, bush, plains, . . .
- Each animal gets a score (0-100) along each attribute
- 50 data points in \mathbb{R}^{85}

Apply k-means with k = 10 and look at grouping obtained.

- zebra
- 2 spider monkey, gorilla, chimpanzee
- 3 tiger, leopard, wolf, bobcat, lion
- 4 hippopotamus, elephant, rhinoceros
- 5 killer whale, blue whale, humpback whale, seal, walrus, dolphin
- 6 giant panda
- 7 skunk, mole, hamster, squirrel, rabbit, bat, rat, weasel, mouse, raccoon
- 8 antelope, horse, moose, ox, sheep, giraffe, buffalo, deer, pig, cow
- 9 beaver, otter
- grizzly bear, dalmatian, persian cat, german shepherd, siamese cat, fox, chihuahua, polar bear, collie

- 1 zebra
- 2 spider monkey, gorilla, chimpanzee
- 3 tiger, leopard, fox, wolf, bobcat, lion
- 4 hippopotamus, elephant, rhinoceros, buffalo, pig
- **5** killer whale, blue whale, humpback whale, seal, otter, walrus, dolphin
- 6 dalmatian, persian cat, german shepherd, siamese cat, chihuahua, giant panda, collie
- beaver, skunk, mole, squirrel, bat, rat, weasel, mouse, raccoon
- **8** antelope, horse, moose, ox, sheep, giraffe, deer, cow
- 9 hamster, rabbit
- n grizzly bear, polar bear

Streaming and online computation

Streaming computation: for data too large to fit in memory.

- Make one pass (or maybe a few passes) through the data.
- On each pass:
 - See data points one at a time, in order.
 - Update models/parameters along the way.
- Only enough space to store a tiny fraction of data, or perhaps a short summary.

Online computation: even more lightweight, for data continuously being collected.

- Initialize a model.
- Repeat forever:
 - See a new data point.
 - Update model if need be.

Example: sequential *k*-means

- 1) Set the centers μ_1, \ldots, μ_k to the first k data points
- 2 Set their counts to $n_1 = n_2 = \cdots = n_k = 1$
- 3 Repeat, possibly forever:
 - Get next data point x
 - Let μ_i be the center closest to x
 - Update μ_j and n_j :

$$\mu_j = rac{n_j \mu_j + x}{n_i + 1}$$
 and $n_j = n_j + 1$

K-means: the good and the bad

The good:

- Fast and easy.
- Effective in quantization.

The bad:

• Geared towards spherical clusters of roughly the same radius.

How to accommodate clusters of more general shape?

The EM algorithm for Gaussian mixture models

Topics we'll cover

- 1 Gaussian mixture models
- 2 The optimization problem
- 3 The EM algorithm
- 4 Examples

K-means: the good and the bad

The good:

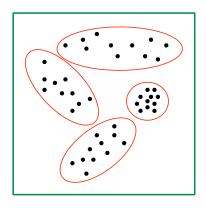
- Fast and easy.
- Effective in quantization.

The bad:

 Geared towards data in which the clusters are spherical, and of roughly the same radius.

Is there is a similarly-simple algorithm in which clusters of more general shape are accommodated?

Mixtures of Gaussians



Each of the *k* clusters is specified by:

- a Gaussian distribution $P_j = N(\mu_j, \Sigma_j)$
- a mixing weight π_j

Overall distribution over \mathbb{R}^d : a **mixture of Gaussians**

$$Pr(x) = \pi_1 P_1(x) + \cdots + \pi_k P_k(x)$$

The clustering task

We are given data $x_1, \ldots, x_n \in \mathbb{R}^d$.

For any mixture model $\pi_1, \ldots, \pi_k, P_1 = N(\mu_1, \Sigma_1), \ldots, P_k = N(\mu_k, \Sigma_k),$

$$\Pr\left(\text{data} \mid \pi_{1} P_{1} + \dots + \pi_{k} P_{k}\right)$$

$$= \prod_{i=1}^{n} \left(\pi_{1} P_{1}(x_{i}) + \dots + \pi_{k} P_{k}(x_{i})\right)$$

$$= \prod_{i=1}^{n} \left(\sum_{j=1}^{k} \frac{\pi_{j}}{(2\pi)^{d/2} |\Sigma_{j}|^{1/2}} \exp\left(-\frac{1}{2}(x_{i} - \mu_{j})^{T} \Sigma_{j}^{-1}(x_{i} - \mu_{j})\right)\right)$$

Find the maximum-likelihood mixture of Gaussians: the parameters $\{\pi_j, \mu_j, \Sigma_j : j = 1 \dots k\}$ that maximize this function.

Optimization surface

Minimize the negative log-likelihood,

$$L(\{\pi_j, \mu_j, \Sigma_j\}) = \sum_{i=1}^n \ln \left(\sum_{j=1}^k \frac{\pi_j}{(2\pi)^{d/2} |\Sigma_j|^{1/2}} \exp \left(-\frac{1}{2} (x_i - \mu_j)^T \Sigma_j^{-1} (x_i - \mu_j) \right) \right)$$

The EM algorithm

- 1 Initialize π_1, \ldots, π_k and $P_1 = N(\mu_1, \Sigma_1), \ldots, P_k = N(\mu_k, \Sigma_k)$.
- 2 Repeat until convergence:
 - Assign each point x_i fractionally between the k clusters:

$$w_{ij} = \Pr(\text{cluster } j \mid x_i) = \frac{\pi_j P_j(x_i)}{\sum_{\ell} \pi_{\ell} P_{\ell}(x_i)}$$

Update mixing weights, means, and covariances:

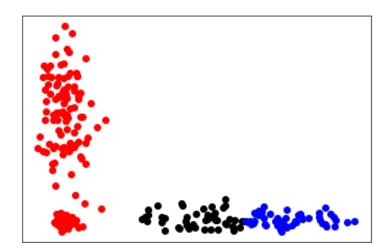
$$\pi_j = \frac{1}{n} \sum_{i=1}^n w_{ij}$$

$$\mu_j = \frac{1}{n\pi_j} \sum_{i=1}^n w_{ij} x_i$$

$$\Sigma_j = \frac{1}{n\pi_j} \sum_{i=1}^n w_{ij} (x_i - \mu_j) (x_i - \mu_j)^T$$

Example

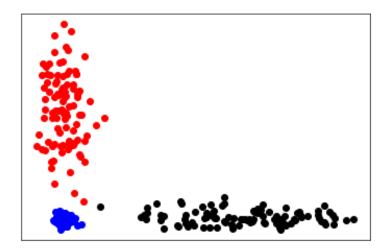
Data with 3 clusters, each with 100 points.



k-means solution 1

Example

Data with 3 clusters, each with 100 points.



EM for mixture of Gaussians

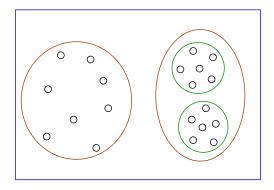
Hierarchical clustering

Topics we'll cover

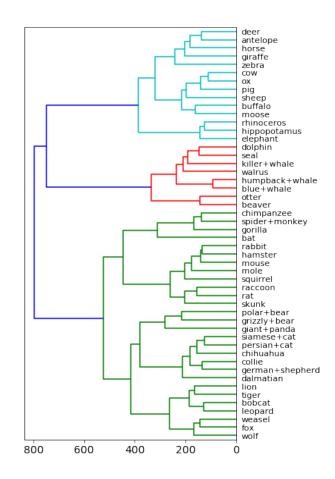
- 1 What is hierarchical clustering?
- 2 Single linkage
- **3** The other linkage schemes

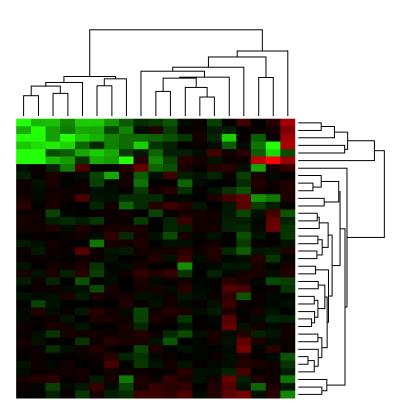
Hierarchical clustering

Choosing the number of clusters (k) is difficult.

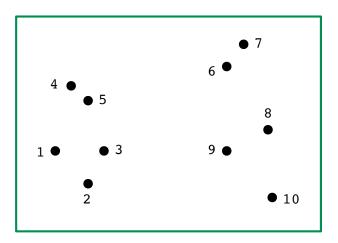


Often there is no single right answer, because of multiscale structure.





The single linkage algorithm

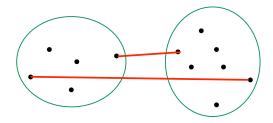


- Start with each point in its own, singleton, cluster
- Repeat until there is just one cluster:
 - Merge the two clusters with the closest pair of points

Linkage methods

- Start with each point in its own cluster
- Repeat until there is just one cluster:
 - Merge the two "closest" clusters

How to measure the distance between two clusters C, C'?



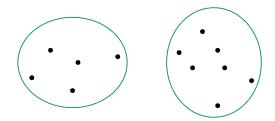
Single linkage

$$\operatorname{dist}(C,C') = \min_{x \in C, x' \in C'} \|x - x'\|$$

Complete linkage

$$\operatorname{dist}(C,C') = \max_{x \in C, x' \in C'} \|x - x'\|$$

Average linkage



1 Average pairwise distance between points in the two clusters

$$dist(C, C') = \frac{1}{|C| \cdot |C'|} \sum_{x \in C} \sum_{x' \in C'} \|x - x'\|$$

2 Distance between cluster centers

$$dist(C, C') = ||mean(C) - mean(C')||$$

 \odot Ward's method: increase in k-means cost from merging the clusters

$$\operatorname{dist}(C,C') = \frac{|C| \cdot |C'|}{|C| + |C'|} \|\operatorname{mean}(C) - \operatorname{mean}(C')\|^2$$