Linear projections

Topics we'll cover

- 1 Why dimensionality reduction?
- **2** Choosing informative coordinates
- 3 Projecting onto an informative direction

Dimensionality reduction

Why reduce the number of features in a data set?

- 1 It reduces storage and computation time.
- 2 High-dimensional data often has a lot of redundancy.
- 3 Remove noisy or irrelevant features.

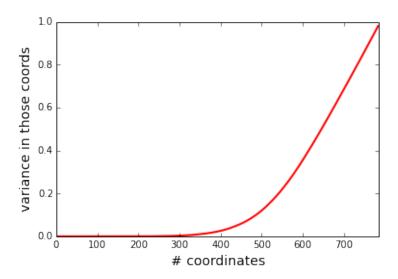
Example: are all the pixels in an image equally informative?



If we were to choose a few pixels to discard, which would be the prime candidates?

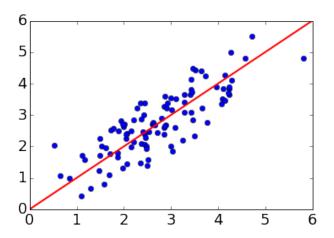
Eliminating low variance coordinates

MNIST: what fraction of the total variance lies in the 100 (or 200, or 300) coordinates with lowest variance?



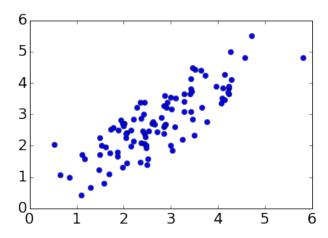
The effect of correlation

Suppose we wanted just one feature for the following data.



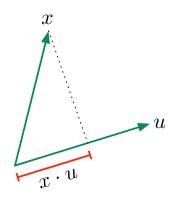
This is the direction of maximum variance.

Comparing projections



Projection: formally

What is the projection of $x \in \mathbb{R}^d$ in the **direction** $u \in \mathbb{R}^d$? Assume u is a unit vector (i.e. ||u|| = 1).



Projection is

$$x \cdot u = u \cdot x = u^T x = \sum_{i=1}^d u_i x_i.$$

Examples

What is the projection of $x = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ along the following directions?

- 1 The x_1 -axis?
- **2** The direction of $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$?

Principal component analysis I: one-dimensional projection

Topics we'll cover

- 1 The variance of a projection
- 2 Finding the best single direction

The best direction

Suppose we need to map our data $x \in \mathbb{R}^d$ into just **one** dimension:

$$x \mapsto u \cdot x$$
 for some unit direction $u \in \mathbb{R}^d$

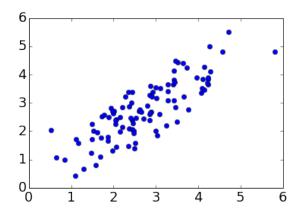
What is the direction u of maximum variance?

Useful fact 1:

- Let Σ be the $d \times d$ covariance matrix of X.
- The variance of X in direction u (the variance of $X \cdot u$) is:

$$u^T \Sigma u$$
.

Best direction: example



Here covariance matrix
$$\Sigma \ = \ \begin{pmatrix} 1 & 0.85 \\ 0.85 & 1 \end{pmatrix}$$

The best direction

Suppose we need to map our data $x \in \mathbb{R}^d$ into just **one** dimension:

$$x \mapsto u \cdot x$$
 for some unit direction $u \in \mathbb{R}^d$

What is the direction u of maximum variance?

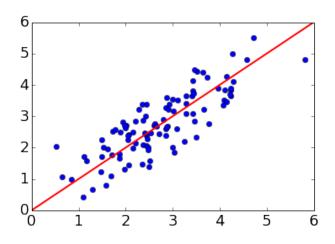
Useful fact 1:

- Let Σ be the $d \times d$ covariance matrix of X.
- The variance of X in direction u is given by $u^T \Sigma u$.

Useful fact 2:

- $u^T \Sigma u$ is maximized by setting u to the first **eigenvector** of Σ .
- The maximum value is the corresponding **eigenvalue**.

Best direction: example



Direction: **first eigenvector** of the 2×2 covariance matrix of the data.

Projection onto this direction: the top **principal component** of the data

Principal component analysis II: the top *k* directions

Topics we'll cover

- 1 Projecting onto multiple directions
- 2 Principal component analysis
- **3** Reconstruction from projections

Projection onto multiple directions

Projecting $x \in \mathbb{R}^d$ into the k-dimensional subspace defined by vectors $u_1, \ldots, u_k \in \mathbb{R}^d$.

This is easiest when the u_i 's are **orthonormal**:

- They have length one.
- They are at right angles to each other: $u_i \cdot u_i = 0$ when $i \neq j$

The projection is a k-dimensional vector:

$$(x \cdot u_1, x \cdot u_2, \dots, x \cdot u_k) = \underbrace{\begin{pmatrix} \longleftarrow & u_1 & \longrightarrow \\ \longleftarrow & u_2 & \longrightarrow \\ & \vdots & & \\ \longleftarrow & u_k & \longrightarrow \end{pmatrix}}_{\text{call this } U^T} \begin{pmatrix} \uparrow \\ \chi \\ \downarrow \end{pmatrix}$$

U is the $d \times k$ matrix with columns u_1, \ldots, u_k .

Projection onto multiple directions: example

E.g. project data in \mathbb{R}^4 onto the first two coordinates.

Take vectors
$$u_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \quad u_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$
 (notice: orthonormal)

Write $U^T = \begin{pmatrix} \longleftarrow & u_1 & \longrightarrow \\ \longleftarrow & u_2 & \longrightarrow \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$

The projection of
$$x \in \mathbb{R}^4$$
 is $U^T x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$

The best *k*-dimensional projection

Let Σ be the $d \times d$ covariance matrix of X. In $O(d^3)$ time, we can compute its **eigendecomposition**, consisting of

- real **eigenvalues** $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_d$
- corresponding **eigenvectors** $u_1, \ldots, u_d \in \mathbb{R}^d$ that are orthonormal (unit length and at right angles to each other)

Fact: Suppose we want to map data $X \in \mathbb{R}^d$ to just k dimensions, while capturing as much of the variance of X as possible. The best choice of projection is:

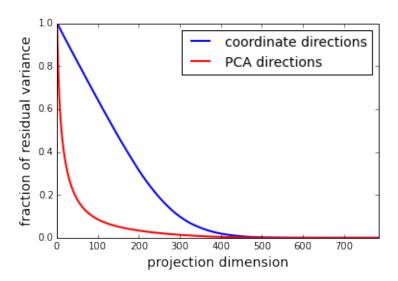
$$x \mapsto (u_1 \cdot x, u_2 \cdot x, \dots, u_k \cdot x),$$

where u_i are the eigenvectors described above.

This projection is called **principal component analysis** (PCA).

Example: MNIST

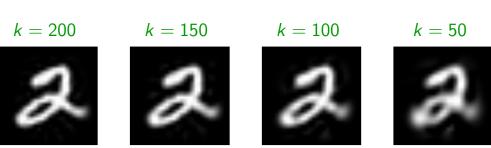
Contrast coordinate projections with PCA:



Applying PCA to MNIST: examples

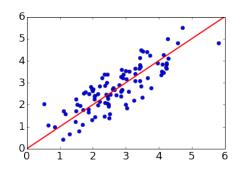


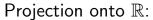
Reconstruct this original image from its PCA projection to k dimensions.

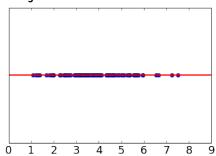


How do we get these **reconstructions**?

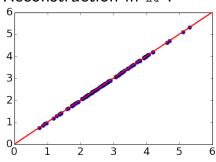
Reconstruction from a 1-d projection







Reconstruction in \mathbb{R}^2 :



Reconstruction from projection onto multiple directions

Projecting into the *k*-dimensional subspace defined by **orthonormal** $u_1, \ldots, u_k \in \mathbb{R}^d$.

The projection of x is a k-dimensional vector:

$$(x \cdot u_1, x \cdot u_2, \dots, x \cdot u_k) = \underbrace{\begin{pmatrix} \longleftarrow & u_1 & \longrightarrow \\ \longleftarrow & u_2 & \longrightarrow \\ & \vdots & & \\ \longleftarrow & u_k & \longrightarrow \end{pmatrix}}_{\text{call this } U^T} \begin{pmatrix} \uparrow \\ \chi \\ \downarrow \end{pmatrix}$$

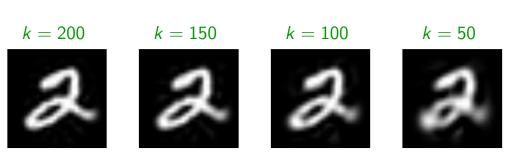
The reconstruction from this projection is:

$$(x \cdot u_1)u_1 + (x \cdot u_2)u_2 + \cdots + (x \cdot u_k)u_k = UU^Tx.$$

MNIST: image reconstruction



Reconstruct this original image x from its PCA projection to k dimensions.



Reconstruction UU^Tx , where U's columns are top k eigenvectors of Σ .

Case study: personality assessment

Quantifying personality

What are the dimensions along which personalities differ?

- Lexical hypothesis: most important personality characteristics have become encoded in natural language.
- Allport and Odbert (1936): identified 4500 words describing personality traits.
- Group these words into (approximate) synonyms, by manual clustering.
 E.g. Norman (1967):

Spirit Jo
Talkativeness Ta
Sociability Cc
Spontaneity Im
Boisterousness M
Adventure Br
Energy AA
Conceit Bc
Vanity Af
Indiscretion No

Jolly, merry, witty, lively, peppy
Talkative, articulate, verbose, gossipy
Companionable, social, outgoing
Impulsive, carefree, playful, zany
Mischievous, rowdy, loud, prankish
Brave, venturous, fearless, reckless
Active, assertive, dominant, energetic
Boastful, conceited, egotistical
Affected, vain, chic, dapper, jaunty
Nosey, snoopy, indiscreet, meddlesome
Sexy, passionate, sensual, flirtatious

Data collection: subjects whether these words describe them.

Personality assessment: the data

Matrix of data (1 = strongly disagree, 5 = strongly agree)

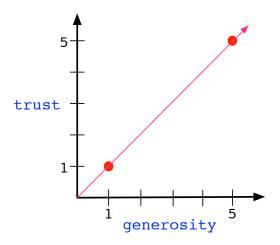
	145	Mer	tense	90909	10, chu.	duist duis
Person 1	4	1	1	2	5	5
Person 2	1	4	4	5	2	1
Person 3	2	4	5	4	2	2
		:				

How to extract important directions?

- Treat each column as a data point, find tight clusters
- Treat each row as a data point, apply PCA
- Or factor analysis, independent component analysis, etc.

What would PCA accomplish?

E.g.: Suppose two traits (generosity, trust) are so highly correlated that each person either answers "1" to both or "5" to both.



A single PCA dimension would entirely account for both traits.

Personality assessment: the data

Matrix of data (1 = strongly disagree, 5 = strongly agree)

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	135	Met	tens	609	10 20 TU	10/11/6
Person 1	4	1	1	2	5	5
Person 2	1	4	4	5	2	1
Person 3	2	4	5	4	2	2
		:				

Methodology: apply PCA to the rows of this matrix.

The "Big Five" taxonomy

Extraversion

- -: quiet (-.83), reserved (-.80), shy (-.75), silent (-.71)
- +: talkative (.85), assertive (.83), active (.82), energetic (.82)

Agreeableness

- -: fault-finding (-.52), cold (-.48), unfriendly (-.45), quarrelsome (-.45)
- +: sympathetic (.87), kind (.85), appreciative (.85), affectionate (.84)

Conscientousness

- -: careless (-.58), disorderly (-.53), frivolous (-.50), irresponsible (-.49)
- +: organized (.80), thorough (.80), efficient (.78), responsible (.73)

Neuroticism

- -: stable (-.39), calm (-.35), contented (-.21)
- +: tense (.73), anxious (.72), nervous (.72), moody (.71)

Openness

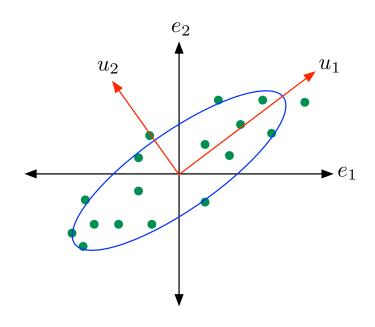
- -: commonplace (-.74), narrow (-.73), simple (-.67), shallow (-.55)
- +: imaginative (.76), intelligent (.72), original (.73), insightful (.68)

Linear algebra V Eigenvectors and eigenvalues

Topics we'll cover

- Moving between coordinate systems
- 2 Eigenvectors and eigenvalues of a square matrix
- 3 Orthonormal basis of eigenvectors for symmetric matrix

Moving between coordinate systems



The linear function defined by a matrix

- Any matrix M defines a linear function, $x \mapsto Mx$. If M is a $d \times d$ matrix, this maps \mathbb{R}^d to \mathbb{R}^d .
- This function is easy to understand when *M* is **diagonal**:

$$\underbrace{\begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix}}_{M} \underbrace{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}}_{\times} = \underbrace{\begin{pmatrix} 2x_1 \\ -x_2 \\ 10x_3 \end{pmatrix}}_{Mx}$$

In this case, M simply scales each coordinate separately.

General symmetric matrices also just scale coordinates separately...
 but in a different coordinate system!

Eigenvector and eigenvalue: definition

Let M be a $d \times d$ matrix. We say $u \in \mathbb{R}^d$ is an **eigenvector** of M if

$$Mu = \lambda u$$

for some scaling constant λ . This λ is the **eigenvalue** associated with u.

Key point: *M* maps eigenvector *u* onto the same direction.

Question: What are the eigenvectors and eigenvalues of:

$$M = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix} ?$$

Eigenvectors of a real symmetric matrix

Fact: Let M be any real symmetric $d \times d$ matrix. Then M has

- d eigenvalues $\lambda_1, \ldots, \lambda_d$
- corresponding eigenvectors $u_1, \ldots, u_d \in \mathbb{R}^d$ that are orthonormal

Can think of u_1, \ldots, u_d as the axes of the natural coordinate system for M.

Example

$$M=egin{pmatrix} 1 & -2 \ -2 & 1 \end{pmatrix}$$
 has eigenvectors $u_1=rac{1}{\sqrt{2}}egin{pmatrix} 1 \ 1 \end{pmatrix},\ u_2=rac{1}{\sqrt{2}}egin{pmatrix} -1 \ 1 \end{pmatrix}$

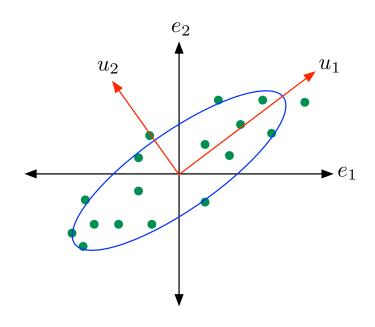
- 1 Are these orthonormal?
- 2 What are the corresponding eigenvalues?

Linear algebra VI Spectral decomposition

Topics we'll cover

- 1 The eigenbasis as a natural coordinate system for a matrix
- 2 Spectral decomposition of a symmetric matrix
- 3 Principal component analysis revisited

Moving between coordinate systems



Eigenvectors and eigenvalues

Let M be a $d \times d$ matrix. We say $u \in \mathbb{R}^d$ is an **eigenvector** of M if

$$Mu = \lambda u$$

for some scaling constant λ . This λ is the **eigenvalue** associated with u.

Key point: M maps eigenvector u onto the same direction.

Fact: Let M be any real symmetric $d \times d$ matrix. Then M has

- d eigenvalues $\lambda_1, \ldots, \lambda_d$
- ullet corresponding eigenvectors $u_1,\ldots,u_d\in\mathbb{R}^d$ that are orthonormal

Eigenvectors: axes of a natural coordinate system for M.

Spectral decomposition

Fact: Let M be any real symmetric $d \times d$ matrix. Then M has orthonormal eigenvectors $u_1, \ldots, u_d \in \mathbb{R}^d$ and corresponding eigenvalues $\lambda_1, \ldots, \lambda_d$.

Spectral decomposition: Another way to write *M*:

$$M = \underbrace{\begin{pmatrix} \uparrow & \uparrow & \uparrow \\ u_1 & u_2 & \cdots & u_d \\ \downarrow & \downarrow & \downarrow \end{pmatrix}}_{U: \text{ columns are eigenvectors}} \underbrace{\begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_d \end{pmatrix}}_{\Lambda: \text{ eigenvalues on diagonal}} \underbrace{\begin{pmatrix} \leftarrow & u_1 & \longrightarrow \\ \leftarrow & u_2 & \longrightarrow \\ \vdots & \vdots & \ddots & \vdots \\ \leftarrow & u_d & \longrightarrow \end{pmatrix}}_{U^T}$$

Thus $Mx = U\Lambda U^T x$:

- U^T rewrites x in the $\{u_i\}$ coordinate system
- Λ is a simple coordinate scaling in that basis
- U sends the scaled vector back into the usual coordinate basis

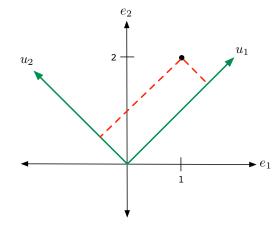
Apply spectral decomposition to the matrix we saw earlier: $M = \begin{pmatrix} 1 & -2 \\ -2 & 1 \end{pmatrix}$

• Eigenvectors
$$u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \ u_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

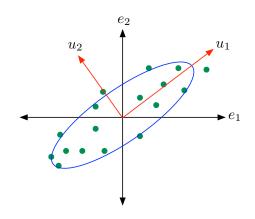
• Eigenvalues $\lambda_1 = -1, \ \lambda_2 = 3.$

$$M = \begin{pmatrix} 1 & -2 \\ -2 & 1 \end{pmatrix} = \underbrace{\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}}_{U} \underbrace{\begin{pmatrix} -1 & 0 \\ 0 & 3 \end{pmatrix}}_{\Delta} \underbrace{\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}}_{U^{T}}$$

$$M\begin{pmatrix}1\\2\end{pmatrix} = U\Lambda U^T\begin{pmatrix}1\\2\end{pmatrix}$$



Principal component analysis revisited



Data vectors $X \in \mathbb{R}^d$

- Covariance matrix Σ is a $d \times d$ symmetric matrix.
- Eigenvalues $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_d$ Eigenvectors u_1, \ldots, u_d .
- u_1, \ldots, u_d : another basis in which to represent data.
- Variance of X in direction u_i is λ_i .
- Projection to k dimensions: $x \mapsto (x \cdot u_1, \dots, x \cdot u_k)$.

What is the covariance of the projected data?