



MICROCHIP

Peripheral Trigger Generator



Goals

- **What is the PTG?**
- **Why use it?**
- **How is it used?**
- **What can it do?**
- **Where can I learn more?**



What is the PTG?

- **The PTG is a programmable step sequencer...**

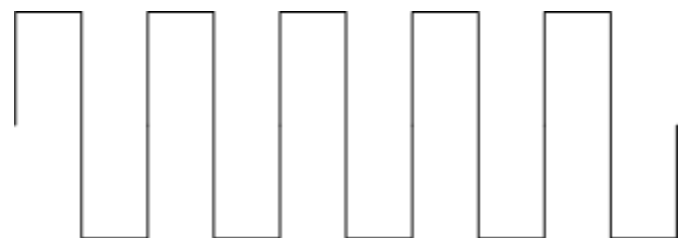
dsPIC/PIC	PTG
Program Memory (Flash)	Step Queue (Ram)
Instruction Set	<Command,Option> pairs form 8-bit Instructions
Operates on data	Operates on triggers and Delays
Program Counter	Queue Pointer (QPTR)
General Purpose RAM	Limit Register
Configuration Bits	Configuration SFRs



Step Queue

```
void main(void) {  
    _TRISB15 = 0; _LATB15 = 0;  
    _PTG0IF = 0; _PTG0IE = 1;  
    PTGCONbits.PTGCLK = 1;  
    PTGQPTR = 0;  
    _STEP0 = PTGIRQ | 0;  
    _STEP1 = PTGJMP | 0;  
    PTGCSTbits.PTGEN = 1;  
    PTGCSTbits.PTGSTRT = 1;  
    while(1) { Nop(); }  
}  
void _ISR _PTG0Interrupt() {  
    _LATB15 ^= 1;  
    _PTG0IF = 0;  
}
```

Step Queue



LATB15 Waveform



Command Categories

Output	Input	Branching	Control
PTGIRQ	PTGWHI	PTGJMP	PTGCTRL
PTGTRIG	PTGWLO	PTGJMPC0	PTGADD
PTGSTRB		PTGJMPC1	PTGCOPY



Output Commands

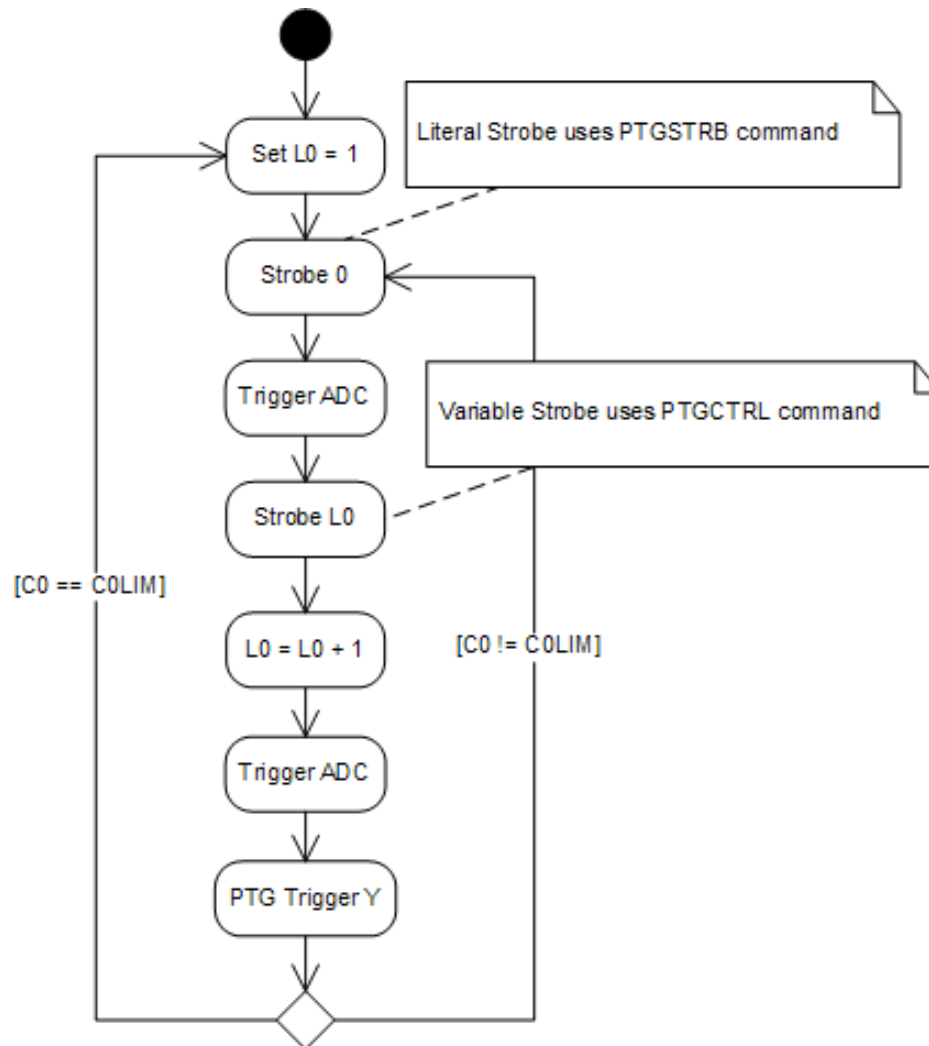
- **PTGTRIG (dsPIC33EPXXXGP50X)**

PTG Output Number	Description
PTGO0	Trigger/Synchronization Source for OC1
PTGO4	Clock Source for OC1
PTGO8	Trigger/Synchronization Source for IC1
PTGO12	Sample Trigger for ADC
PTGO16	PWM Time Base Synchronous Source for PWM
PTGO18	Mask Input Select for Op Amp/Comparator
PTGO30	PTG Output to PPS Input Selection



Output Commands

• PTGSTRB



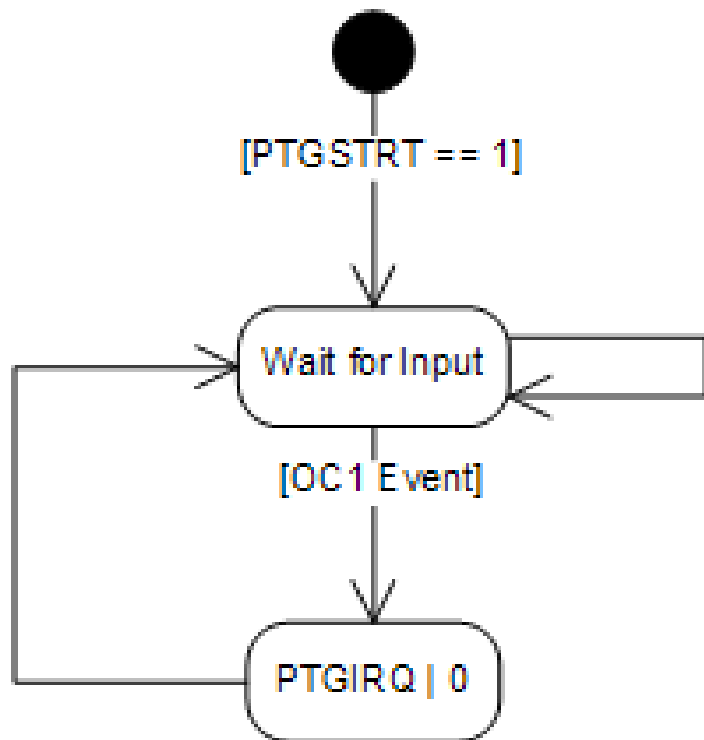


Input Commands

● PTGWHI / PTGWLO

- PWM Special event Trigger
- PWM Master time base synchronization output
- PWM[1,3] Interrupt
- OC[1,2] Trigger Event
- IC1 Trigger Event
- CMP[1,4]Trigger Event
- ADC conversion done interrupt
- INT2 external Interrupt

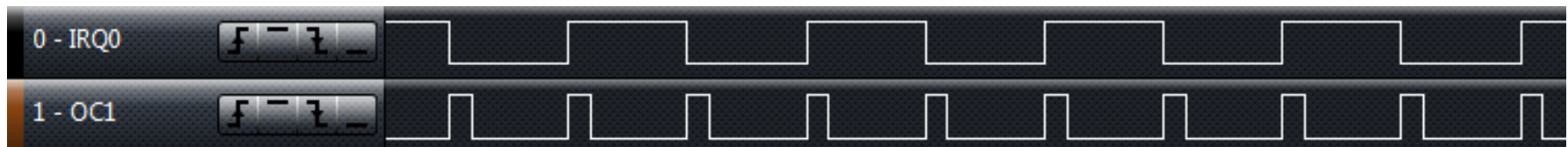
Input Commands



```

_STEP0 = PTGWHI | 7; // OC1 Trigger Event
_STEP1 = PTGIRQ | 0;
_STEP2 = PTGJMP | 0;

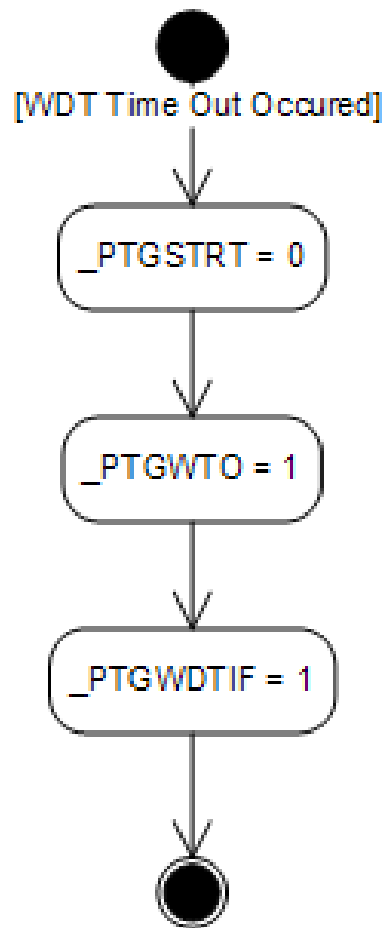
PTGCSTbits.PTGEN = 1;
PTGCSTbits.PTGSTRT = 1;
  
```



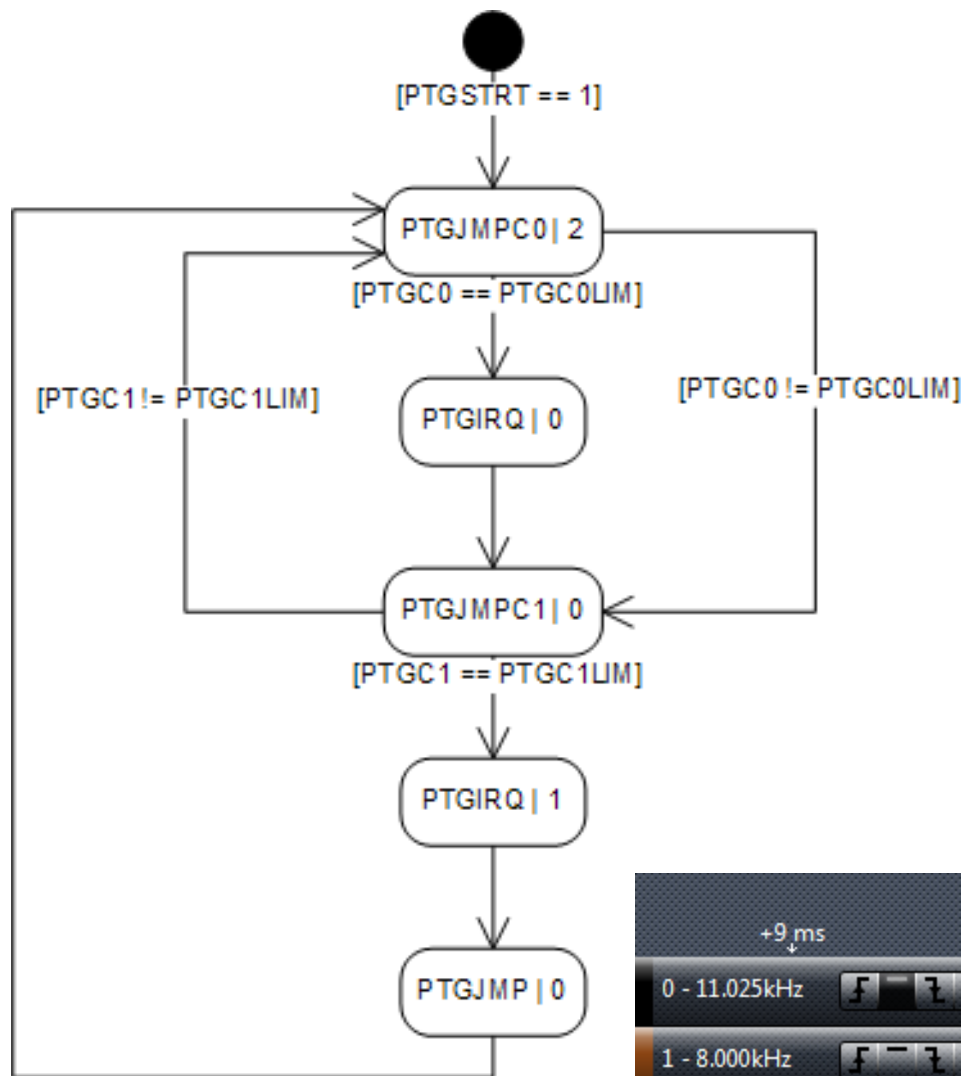


PTG Watchdog Timer

- What if the input doesn't come when expected?



Looping



```

PTGCONbits.PTGLCK = 1; // FOSC
// Fosc / Fc0 = 70E6 / 11025 = 6349.206
PTGC0LIM = 6349;
// Fosc / Fc1 = 70E6 / 8000 = 8750.000
PTGC1LIM = 8750;
_STEP0 = PTGJMPC0 | 2;
_STEP1 = PTGIRQ | 0;
_STEP2 = PTGJMPC1 | 0;
_STEP3 = PTGIRQ | 1;
_STEP4 = PTGJMP | 0;
PTGCSTbits.PTGEN = 1;
PTGCSTbits.PTGSTRT = 1;
  
```





Control Commands

● PTGCTRL

- Enable/Disable Step Delay Timer
- Start and wait for the PTG Timer[0,1] to match the PTGT[0,1]LIM
- Wait for the software Trigger (Edge or Level sensitive)
- Copy the PTGC[0,1]LIM register to the AD1CHS0 register
- Copy the PTGL0 register contents to the AD1CHS0 register
- Broadcast Trigger

Control Commands

● PTGCTRL: Step Delay Timer

```
_STEP0 = PTGIRQ | 0;
_STEP1 = PTGJMP | 0;
```



```
PTGSDLIM = 0x600;
_STEP0 = PTGCTRL | 6; // Enable Step Delay Timer
_STEP1 = PTGIRQ | 0;
_STEP2 = PTGJMP | 1;
```



● PTGADD

- $PTGC0LIM \neq PTGADJ$
- $PTGC1LIM \neq PTGADJ$
- $PTGT0LIM \neq PTGADJ$
- $PTGT1LIM \neq PTGADJ$
- $PTGSDLIM \neq PTGADJ$
- $PTGL0 \neq PTGADJ$

● PTGCOPY

- $PTGC0LIM = PTGHOLD$
- $PTGC1LIM = PTGHOLD$
- $PTGT0LIM = PTGHOLD$
- $PTGT1LIM = PTGHOLD$
- $PTGSDLIM = PTGHOLD$
- $PTGL0 = PTGHOLD$



Control Commands

● PTGCTRL: Wait for Timer

```
PTGQPTR = 0; // Begin on _STEP0
PTGADJ = 0x0800;
PTGTOLIM = 0x0800;
_STEP0 = PTGIRQ | 0; // Assert _PTG0Interrupt() { LATB15 ^= 1; }
_STEP1 = PTGCTRL | 8; // T0 = 0; while(T0++ != PTGTOLIM) {}
_STEP2 = PTGADD | 2; // PTGTOLIM += PTGADJ;
_STEP3 = PTGJMP | 0; // Jump to _STEP0
PTGCSTbits.PTGEN = 1;
PTGCSTbits.PTGSTRT = 1;
```





Debugging Step Programs

- **PTCST<PTGSSEN> – Enable single stepping.**
- **PTCST<PTGIVIS> – Makes internal counters and timers visible.**
- **When single stepping is enabled, set PTGSTRT to execute the next Step Command.**
- **Step Interrupt ISR Available**

PTG Clock

- **FOSC or FCY**
- **T1/T2/T3 clock**
- **ADC clock**
 - Clock divisor
 - WDT counts PTG clock
- **Clock plays an important role**
 - Delay between PTG enable and start of command execution: 6 x PTG clock period (max)
 - Delay between PTGEN=0 and the complete disabling of the module: 2 x PTG clock period (max)

What happens when...

- The end of the Step Queue is reached?

```
PTGSDLIM = 0x1000;  
_STEP0 = PTGCTRL | 6; // Enable Step Delay Timer  
_STEP1 = PTGIRQ|1;  
_STEP2 = PTGIRQ|0;  
_STEP3 = PTGIRQ|0;  
_STEP4 = PTGIRQ|0;  
_STEP5 = PTGIRQ|0;  
_STEP6 = PTGIRQ|0;  
_STEP7 = PTGIRQ|0;  
_STEP8 = PTGIRQ|0;  
_STEP9 = PTGIRQ|0;  
_STEP10 = PTGIRQ|0;  
_STEP11 = PTGIRQ|0;  
_STEP12 = PTGIRQ|0;  
_STEP13 = PTGIRQ|0;  
_STEP14 = PTGIRQ|0;  
_STEP15 = PTGIRQ|0;
```



Resources

- **Code Examples**
- **FRM**
- **Datasheets**