

# *Wavelet Video Coding – Principles, Applications and Standardization*

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# Outline

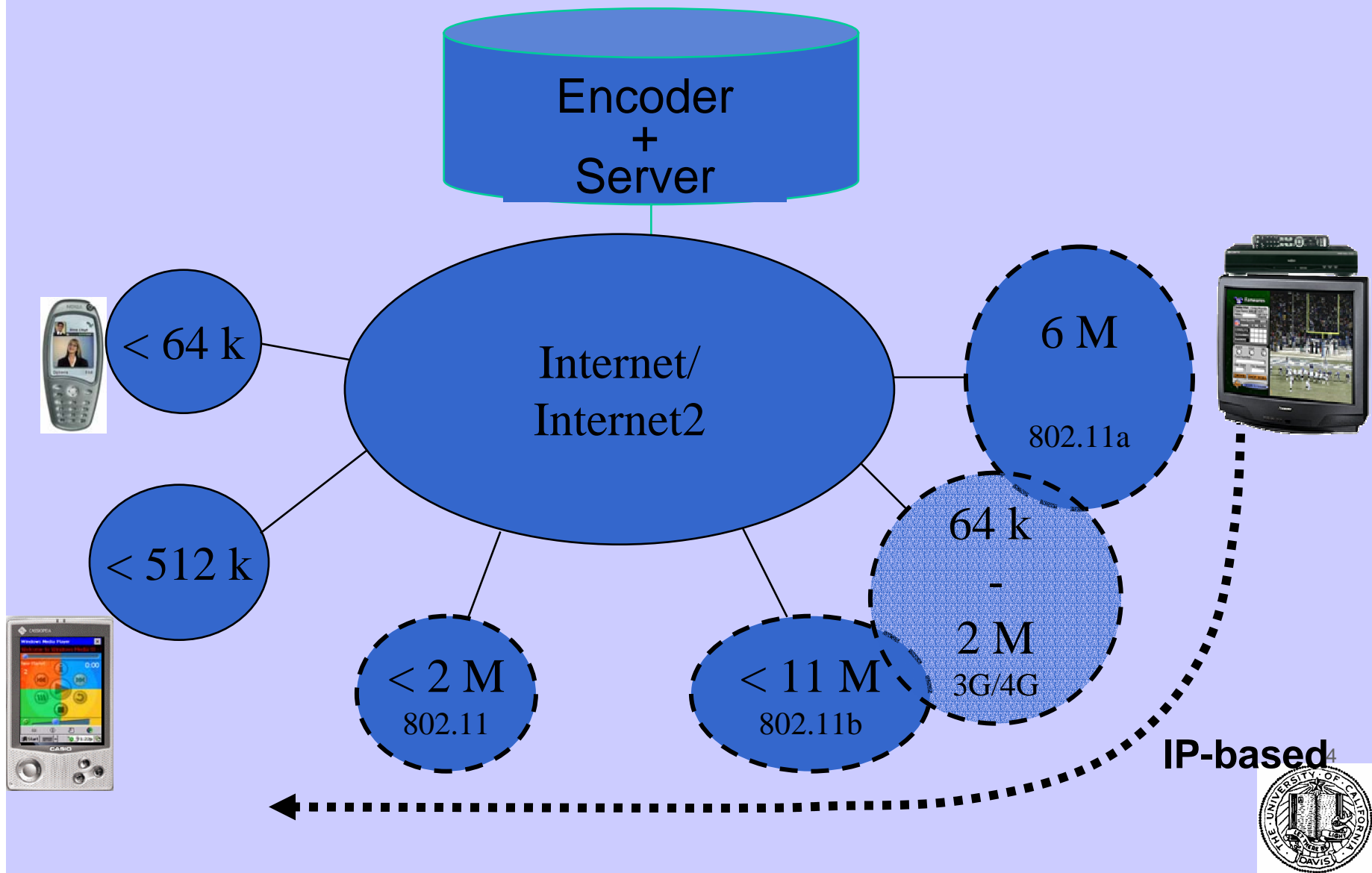
- Introduction
- Scalable coding – principles (review)
- Basic principles of wavelets (review)
- Motion Compensated Wavelet Coding – basic principles and classification
- Motion Compensation Temporal Filtering (MCTF)
- Overcomplete Motion Compensated Wavelet Coding
- Encoding of spatio-temporal wavelet coefficients
- Scalable coding of motion information
- Error resilience aspects
- Current status in MPEG standardization
- Comparisons with state-of-the-art non-scalable coding techniques



# *Introduction*



# Challenges for ubiquitous multimedia communication



## ***Sample of concrete problems/questions***

- **Signal processing**

- compression efficiency versus quality of signal reproduction (rate-distortion tradeoffs)
- compression efficiency versus robustness to losses

- **Networking**

- realistic channel models for effective joint source/channel coding
- source-channel interface control strategies for efficient network resource usage and high quality signal reproduction

- **Computer Architecture**

- compression efficiency versus computational complexity



# Possible solution: compression meets the network

- Do not require the transport mechanism to be flawless (modulation, channel coding, transmission protocol etc.), just design the coding system and transmission *jointly*
- Do not design for worst-case scenario - just adapt on the fly based on the network and device characteristics

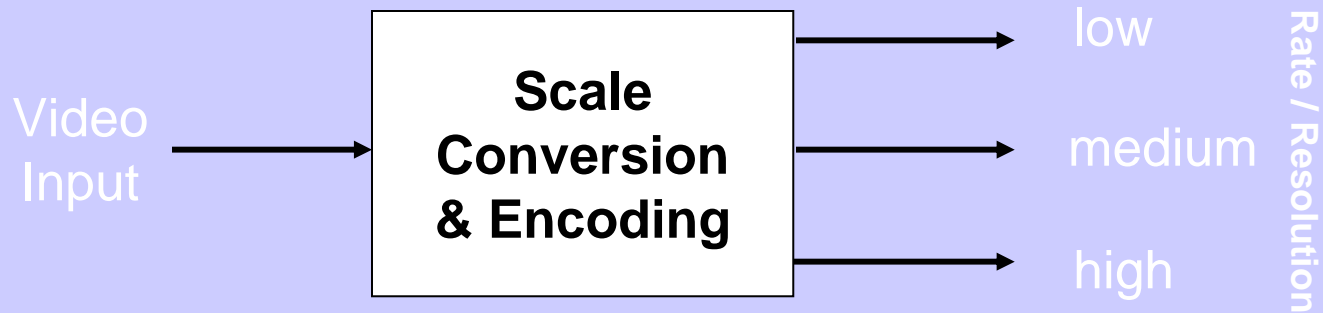
**Hence:**

- **A. Scalable Coding**
- **B. Adaptive Streaming**



# *Principles of Scalable Coding*

- Encoding of video signal with different resolution scales

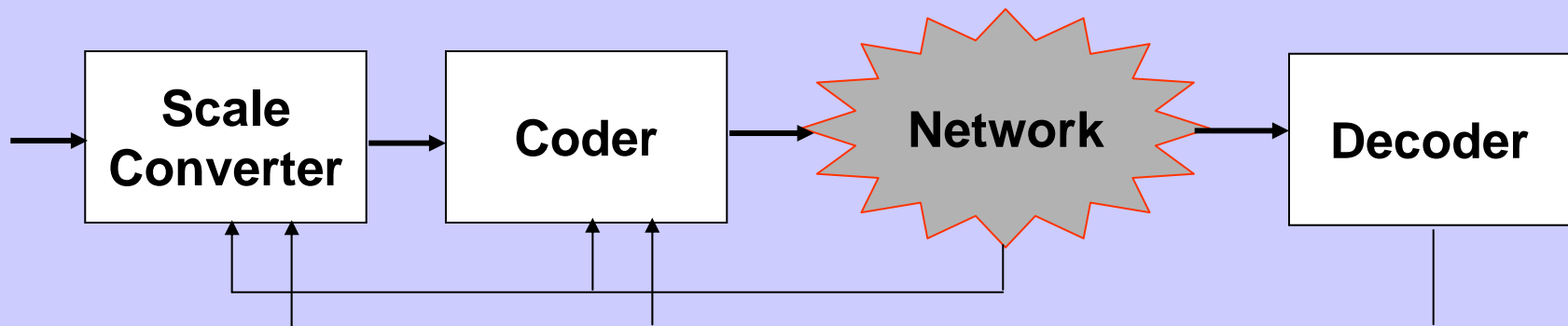


- Downscaling of video signal by
  - Coding noise insertion – **SNR Scalability**
  - Spatial subsampling – **Spatial Scalability**
  - Sharpness reduction – **Frequency Scalability**
  - Temporal subsampling – **Temporal Scalability**
  - Selection of content – **Content related Scalability**



## *The Simple Way – Advance Scaling*

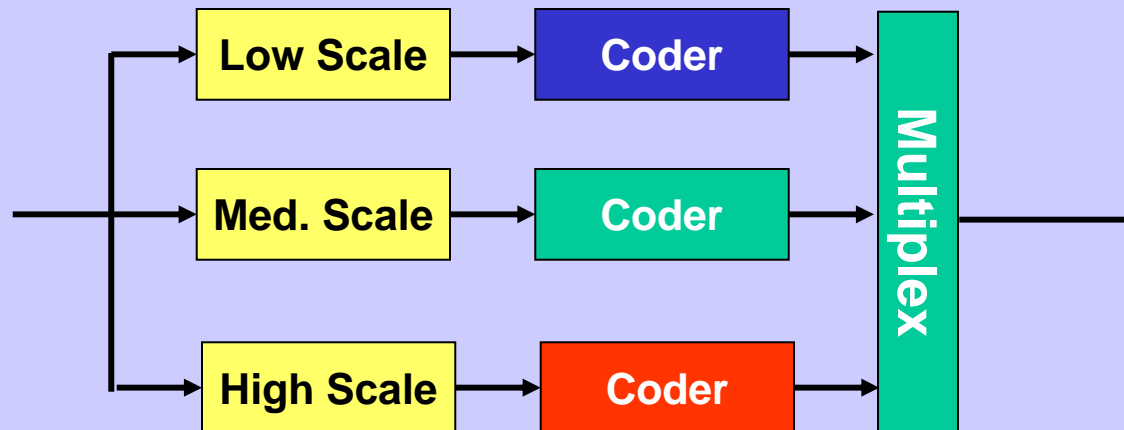
- Requires feedback about channel / decoder status
- Only point-to-point connection supported
- Example : Stream switching





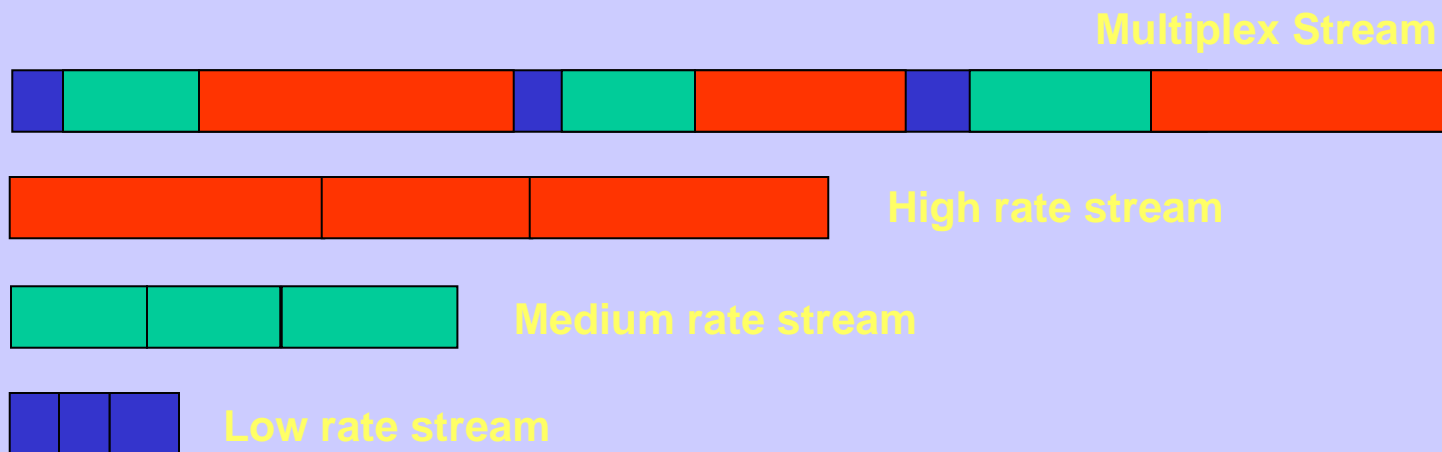
## *The Parallel Way - Simulcast*

- Run independent encoders in parallel
- Requires a priori knowledge about network and decoder capabilities to select optimum scaling levels
- Point-to-multipoint connections possible



# Simulcast

- Multiplexed transmission of streams

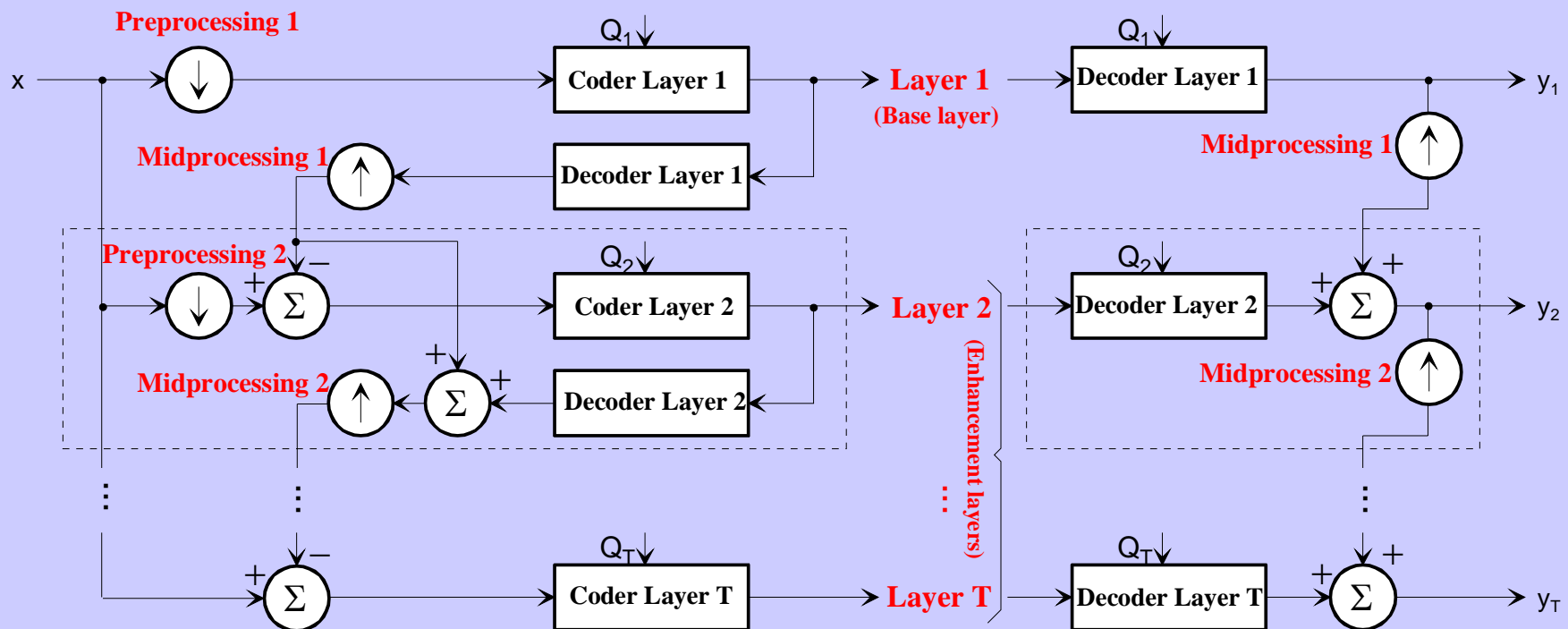


- Loss in efficiency due to multiple streams
  - Can cause network overload
  - Restricted number of scales



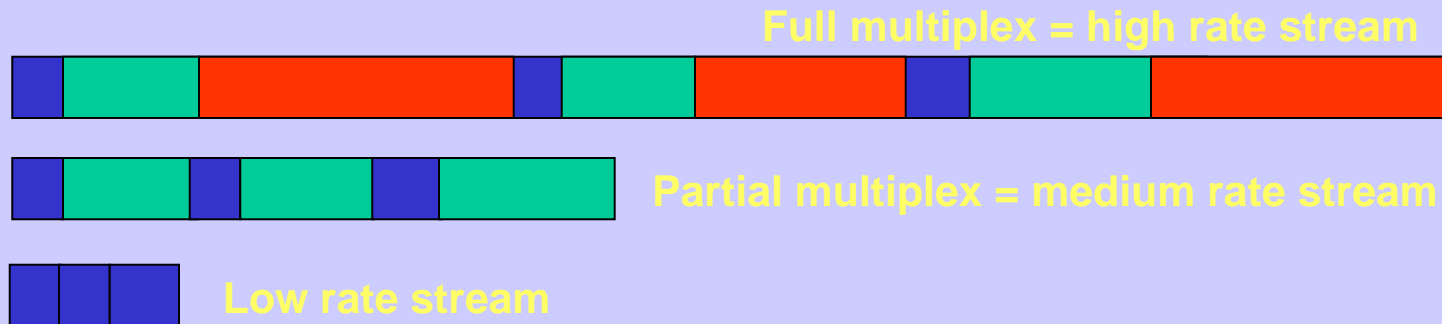
# The Embedded Way – Layered Coding

- "Chain of layers" - information from low resolution utilized to encode next-higher resolution



# Layered Coding

- Layered coding supports embedded streams
  - Re-configuration of bit stream for reconstruction with different spatial/temporal/quality resolution

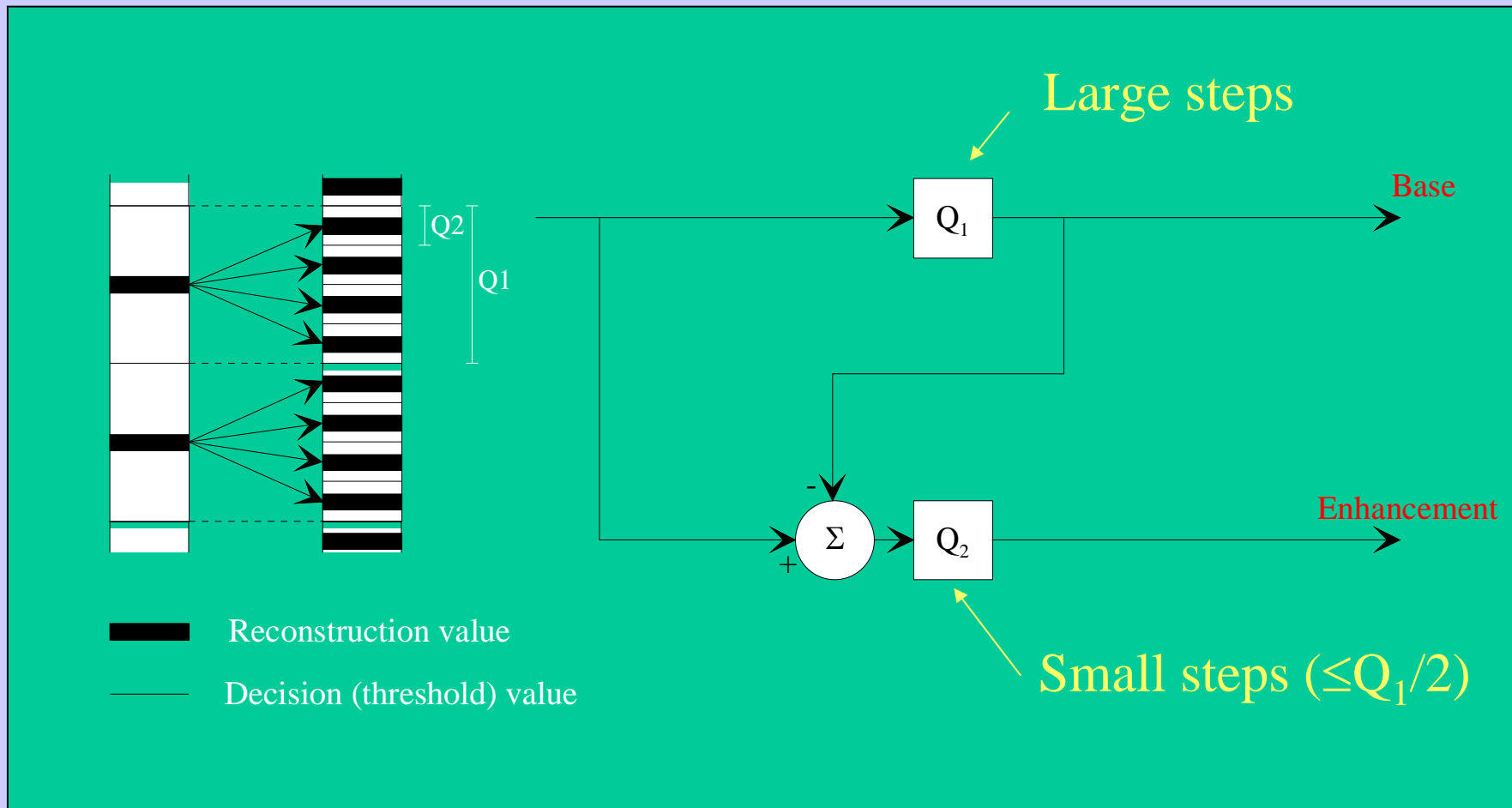


- Possible loss in efficiency depends on coding scheme
- In theory, arbitrary number of scales could be achieved



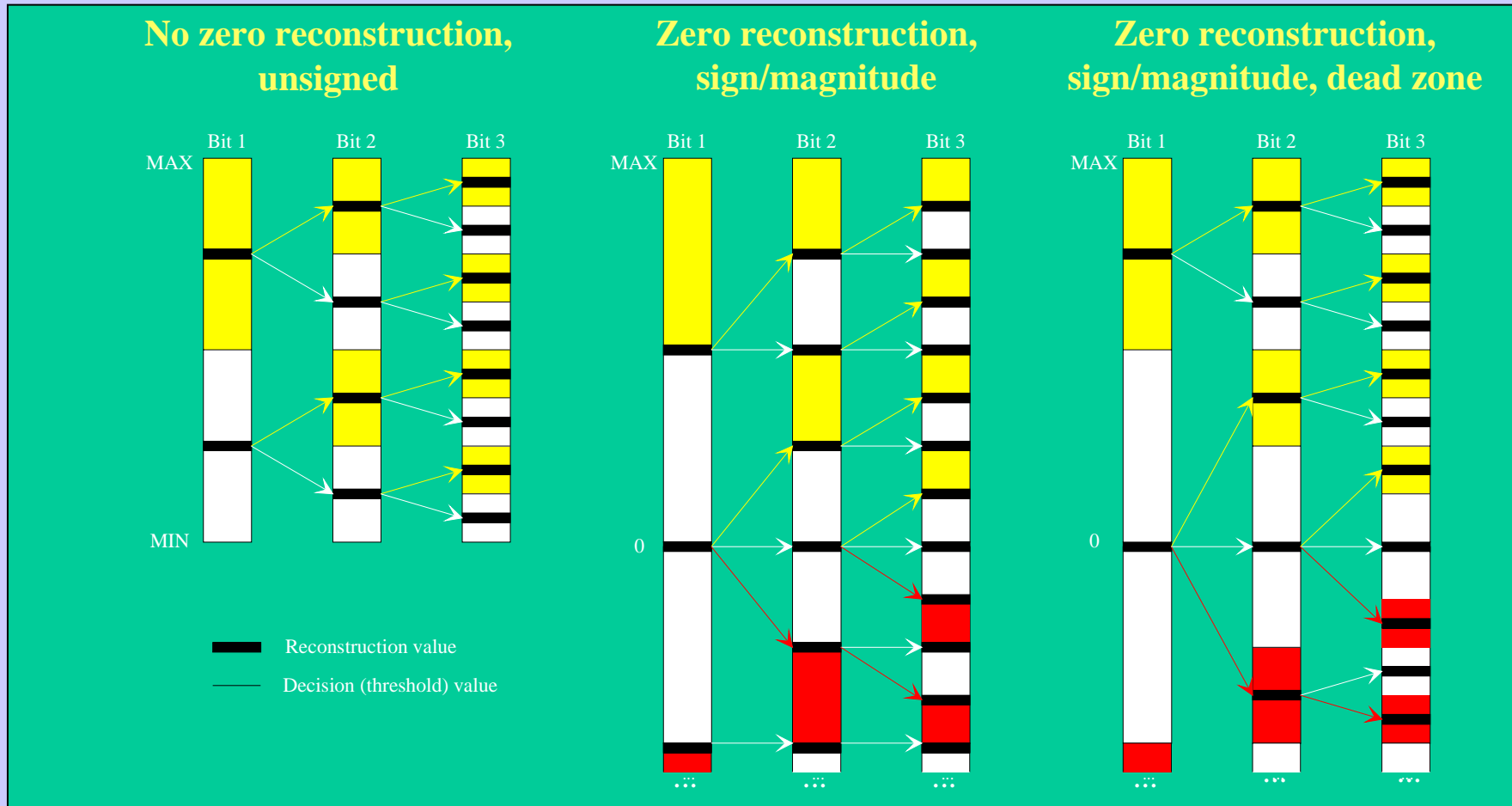
# SNR Scalability – Re-quantisation

- Example : 2-stage quantizer



# SNR Scalability – Bit-plane Coding

- Quantization related to bit planes



# SNR Scalability – Bit-plane Coding

- Magnitude of MSB encoded by run-length or binary entropy coding
- Sign and remaining bits encoded binary, conditional on MSB

	Sample														
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Bit 1	0	0	0	0	1	0	0	0	0	0	0	0	0	0	1
Bit 2	0	0	1	0	1	0	0	0	0	0	0	0	0	0	0
Bit 3	0	0	0	0	0	1	0	0	0	0	0	1	0	0	0
Bit 4	0	0	1	0	0	1	1	0	0	0	0	0	1	0	0
Bit 5	1	0	1	1	1	0	0	0	1	1	0	1	0	0	1
Sign	1	0	0	0	1	0	1	0	1	0	0	1	0	0	1

Run-length code

4,9

2,10

3,5,2

3,4,1

0,1,1,0,2

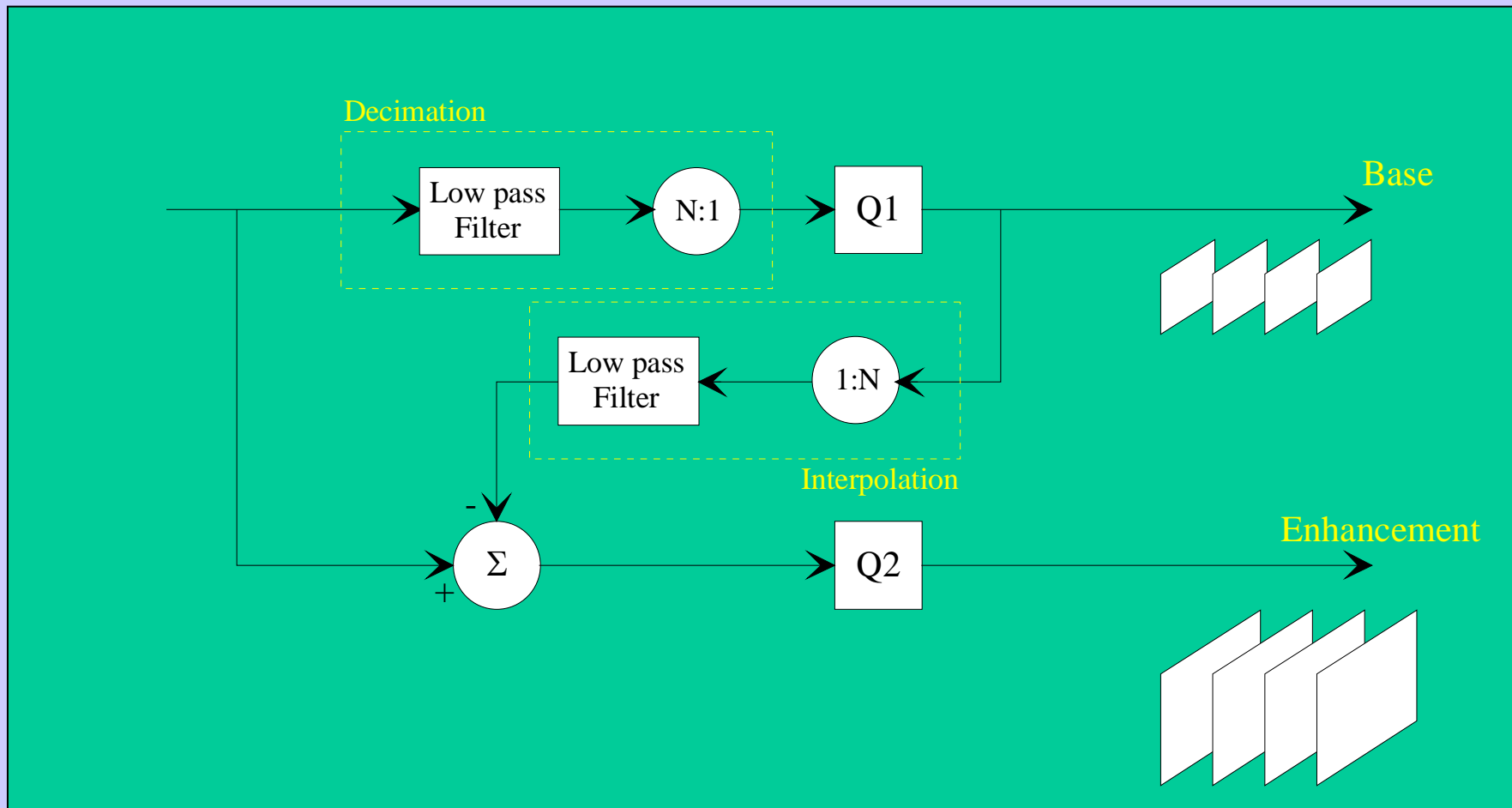


binary coded



# Spatial Scalability

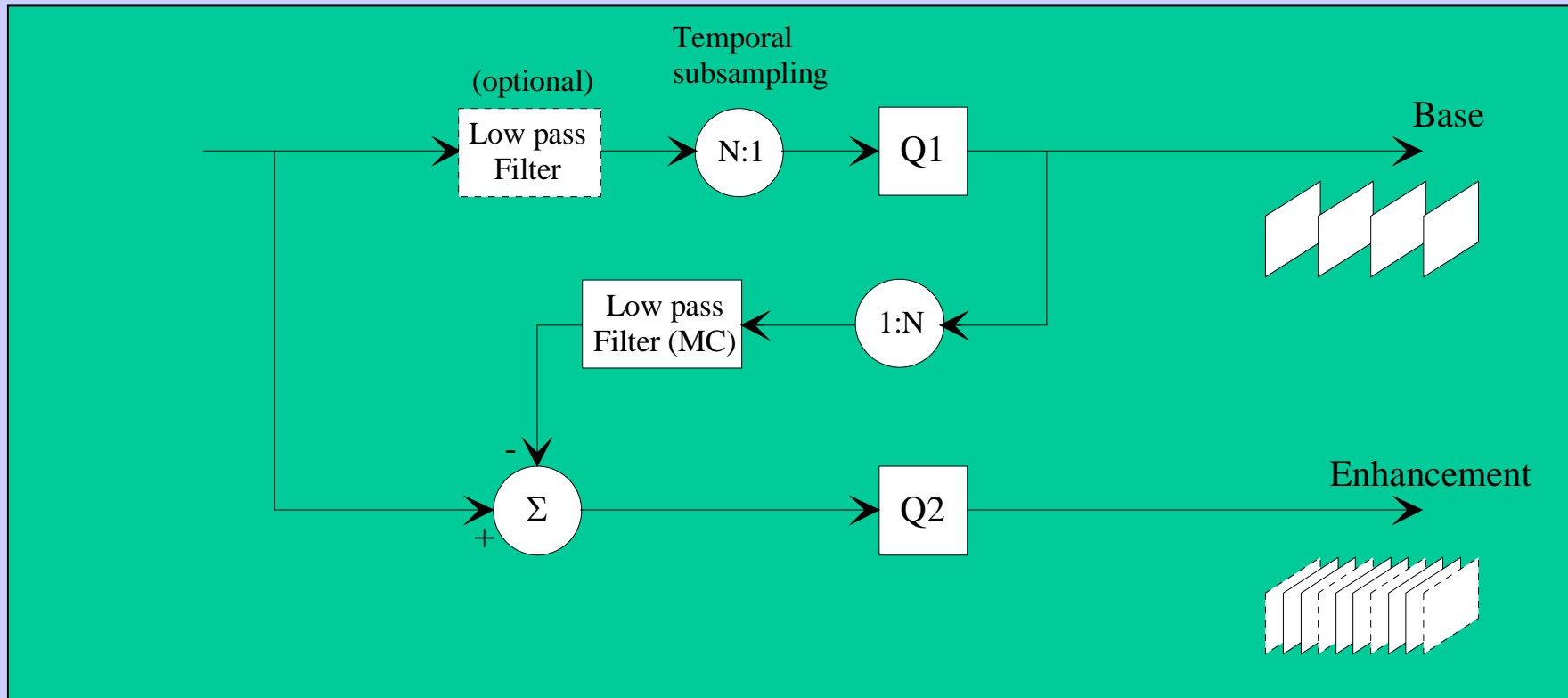
- Base-to enhancement prediction





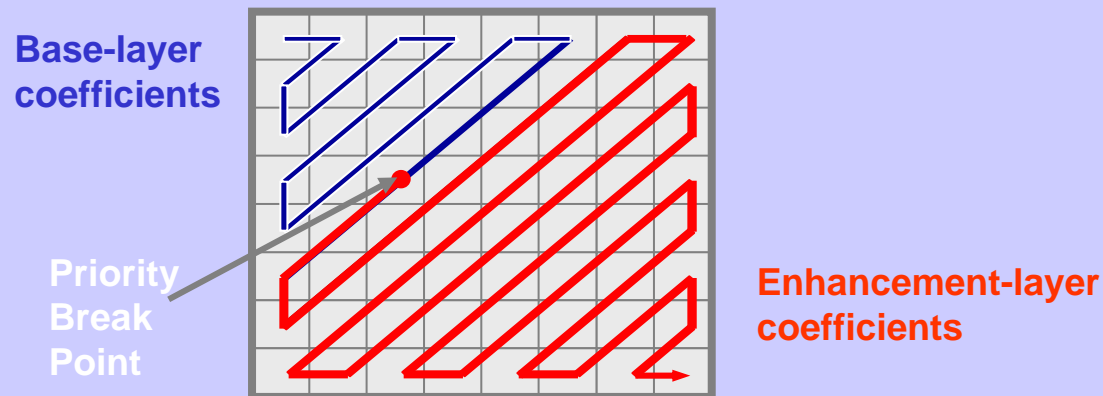
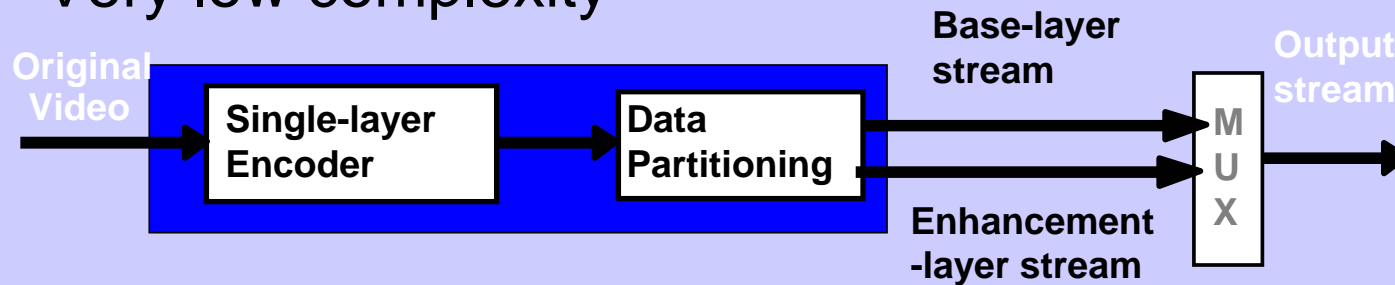
# Temporal Scalability

- Temporal downsampling with temporal anti-alias filter or by frame skipping
- Temporal upsampling by MC prediction



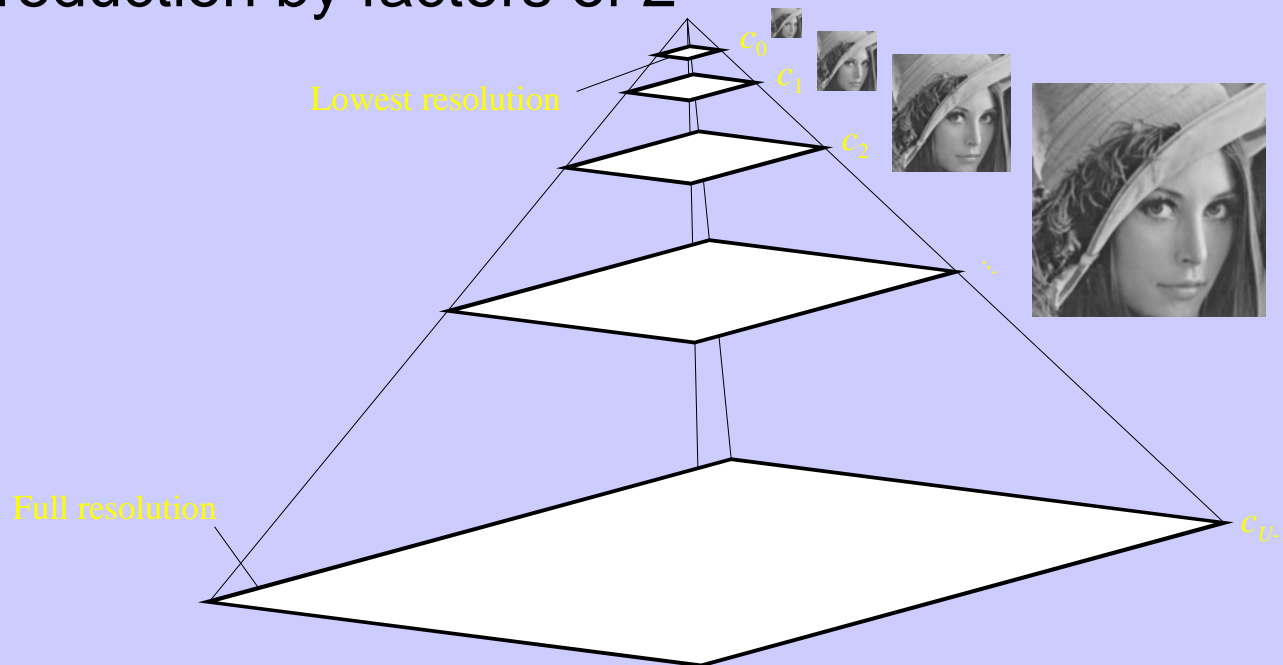
# Frequency Scalability / "Data Partitioning"

- Popular in context of Transform Coding
- Allocation of coefficients to different layers depending on frequency
- Very low complexity



# Multiresolution Concepts

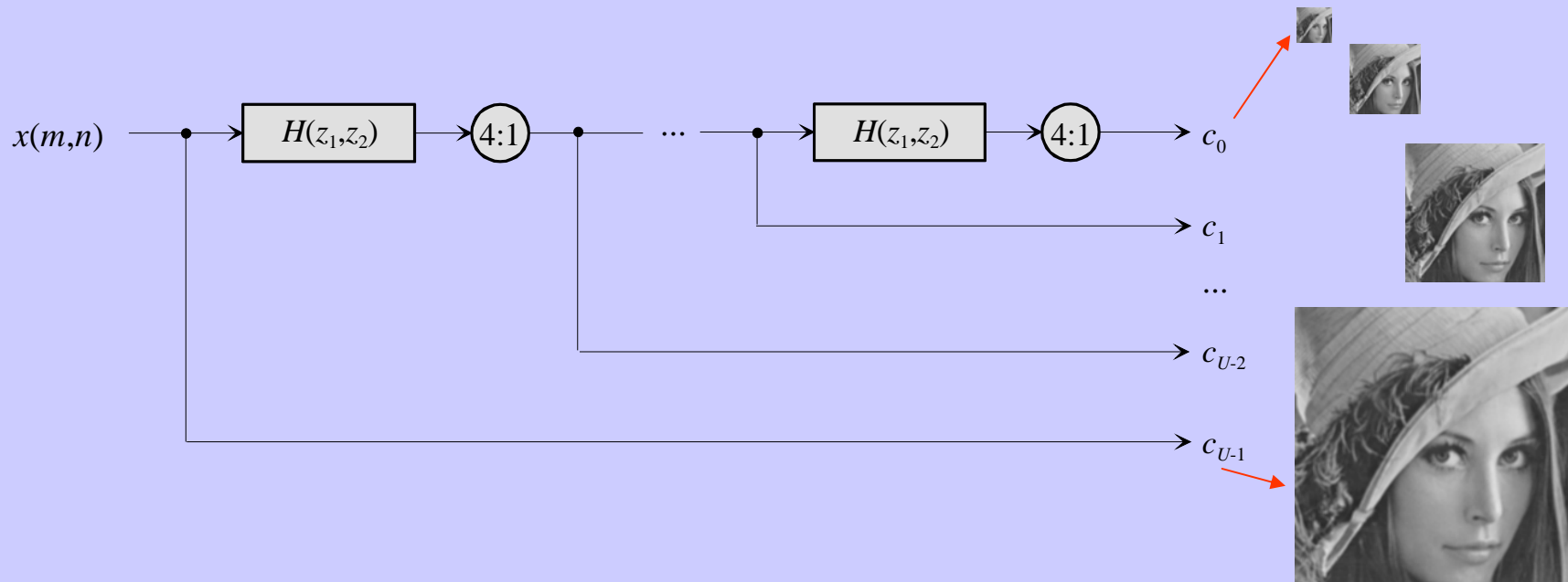
- Generate different resolution levels by successive down/upsampling operations
- Resolution pyramids example : Spatial resolution reduction by factors of 2



# Multiresolution Concepts – Pyramids

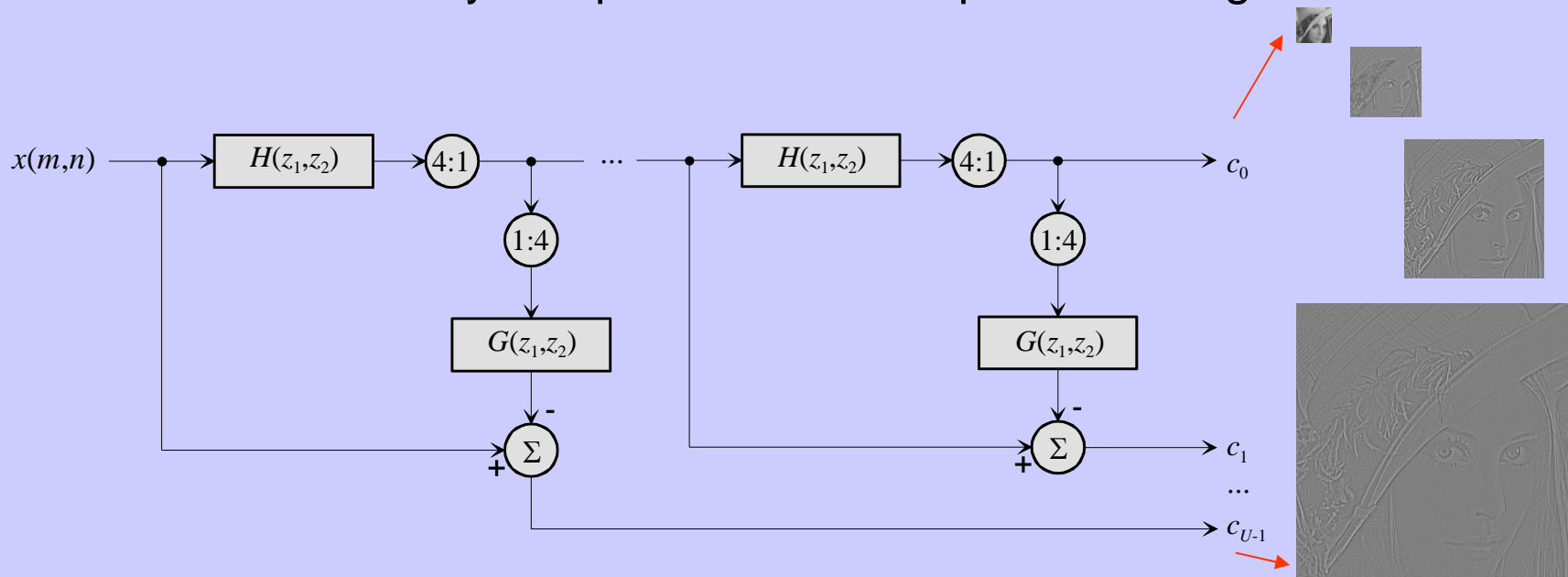
## ■ Gaussian Pyramid

- Each layer is self-contained
- Corresponds to Simulcast concept
- More samples to be encoded



# Multiresolution Concepts – Pyramids

- **Laplacian Pyramid** (Differential Pyramid)
  - All lower-resolution layers required to reconstruct high-resolution layers
  - Corresponds to Layered Coding concept
  - Not critically sampled – more samples than original



# ***Multiresolution Concepts – Pyramids***

- **Advantages :**
  - Pyramids can be combined with any coding scheme for the different resolution levels
  - Downsampling can be made alias-free
- **Disadvantages :**
  - Number of pixels higher than in original signal
  - Higher data rate than one-layer coding
- **Possible solution :**
  - Critically sampled pyramids (Wavelets)
  - Disadvantage : Downsampled signals bear alias

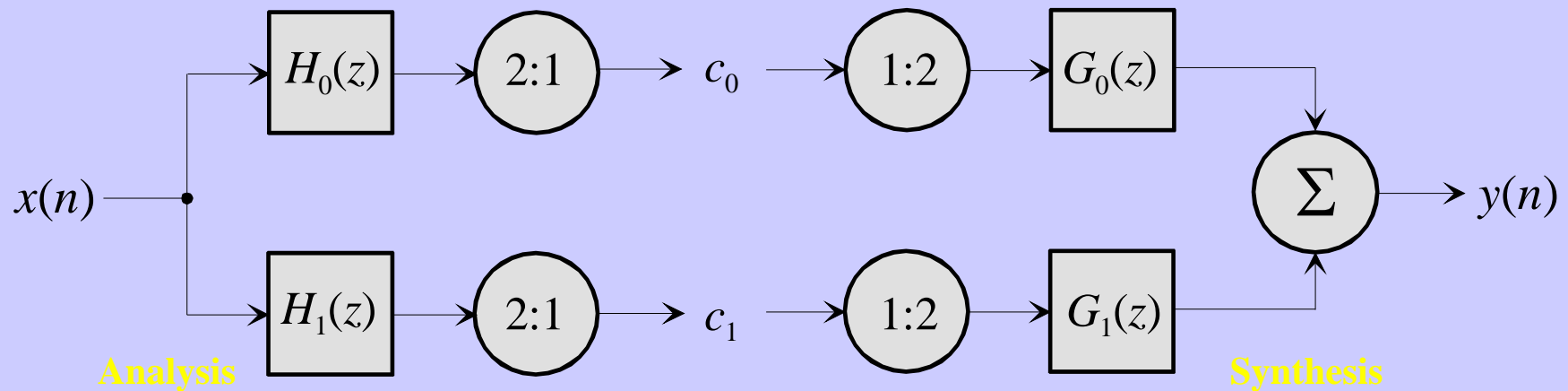


# *Basic Principles of Wavelets*



## Filter Pairs

- Critically sampled filter bank with 2 bands



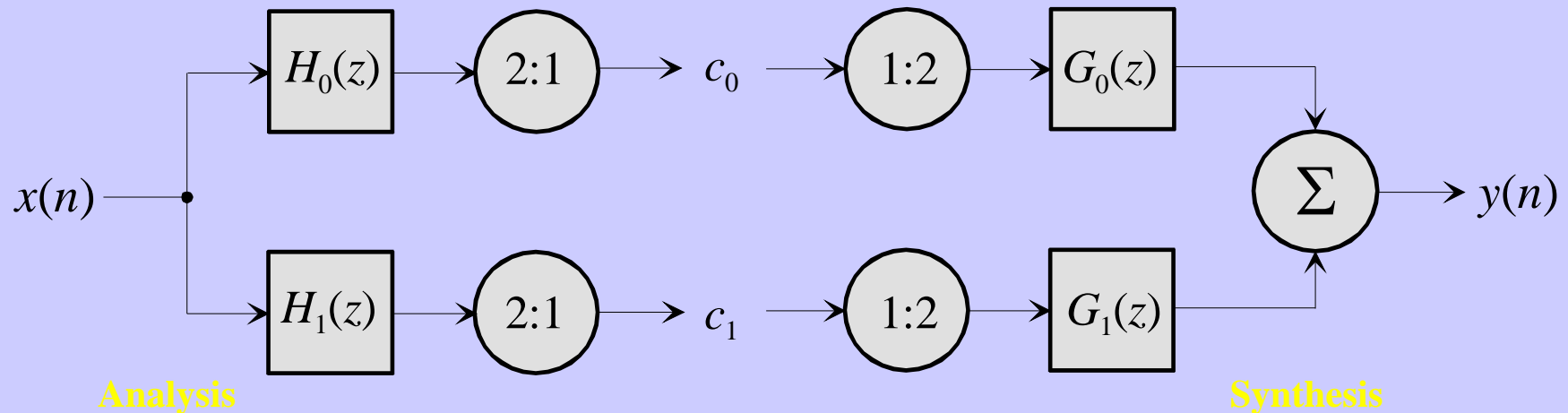
- Analysis low-/highpass filter pairs  $H_0/H_1$
- Synthesis low-/highpass filter pairs  $G_0/G_1$
- Number of samples  $c$  in frequency bands equal to total number of samples in signal  $x$





## Filter Pairs

- Perfect reconstruction is possible



$$\begin{aligned}
 Y(z) = & \frac{1}{2} \left[ H_0(z) \cdot G_0(z) + H_1(z) \cdot G_1(z) \right] \cdot X(z) \quad \quad \quad = 2 \cdot z^{-k} \\
 & + \frac{1}{2} \left[ H_0(-z) \cdot G_0(z) + H_1(-z) \cdot G_1(z) \right] \cdot X(-z) \quad \quad \quad = 0
 \end{aligned}$$

- Subsampled signals  $c$  usually bear alias !

# Biorthogonality Principle

- Perfect reconstruction conditions

$$Y(z) = \frac{1}{2} [H_0(z) \cdot G_0(z) + H_1(z) \cdot G_1(z)] \cdot X(z) \\ + \frac{1}{2} [H_0(-z) \cdot G_0(z) + H_1(-z) \cdot G_1(z)] \cdot X(-z).$$

$$G_0(z) = z^k \cdot H_1(-z) \quad \Rightarrow \quad H_0(-z) \cdot z^k \cdot H_1(-z) \\ G_1(z) = -z^k \cdot H_0(-z) \quad \Rightarrow \quad -H_1(-z) \cdot z^k \cdot H_0(-z) = 0$$

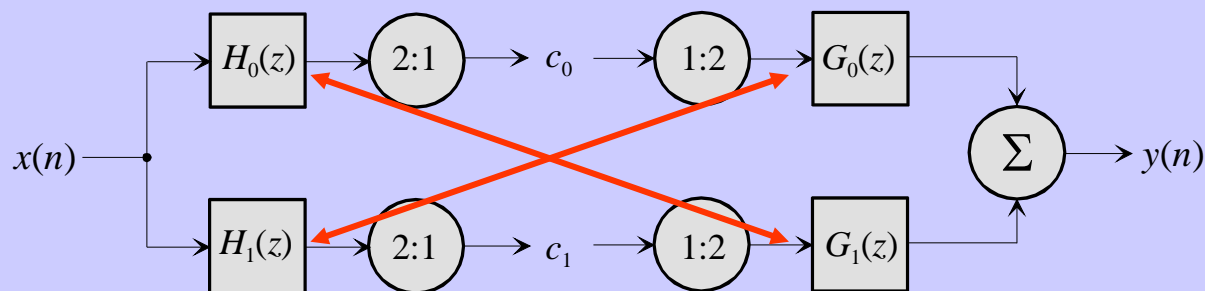
$$Y(z) = \frac{1}{2} [H_0(z) \cdot H_1(-z) - H_1(z) \cdot H_0(-z)] \cdot X(z) \cdot z^k$$

$$\Rightarrow P(z) - P(-z) = 2 \cdot z^{-k} \quad \text{with} \quad P(z) = H_0(z) \cdot H_1(-z)$$



## Biorthogonality Principle

- $H_0(z)/G_1(-z)$  and  $H_1(z)/G_0(-z)$  constitute orthogonal pairs
- Low-/Highpass transfer functions not symmetric
- Linear phase or non-linear phase filters possible
- Low-/Highpass impulse responses may have different length

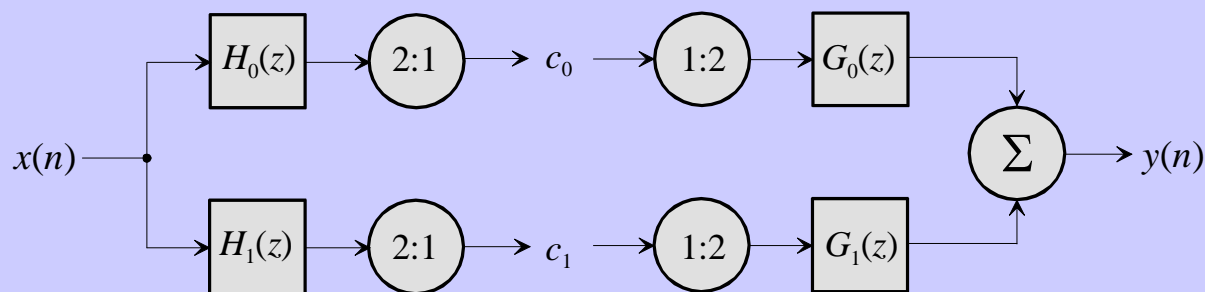


## Biorthogonality Principle

- A simple biorthogonal filter pair (5/3 integer)

$$H_0^{(5/3)}(z) = \frac{1}{8}(-z^2 + 2 \cdot z^1 + 6 + 2 \cdot z^{-1} - z^{-2})$$

$$G_0^{(5/3)}(z) = \frac{1}{2}(z^{-1} + 2 + z^{-1})$$



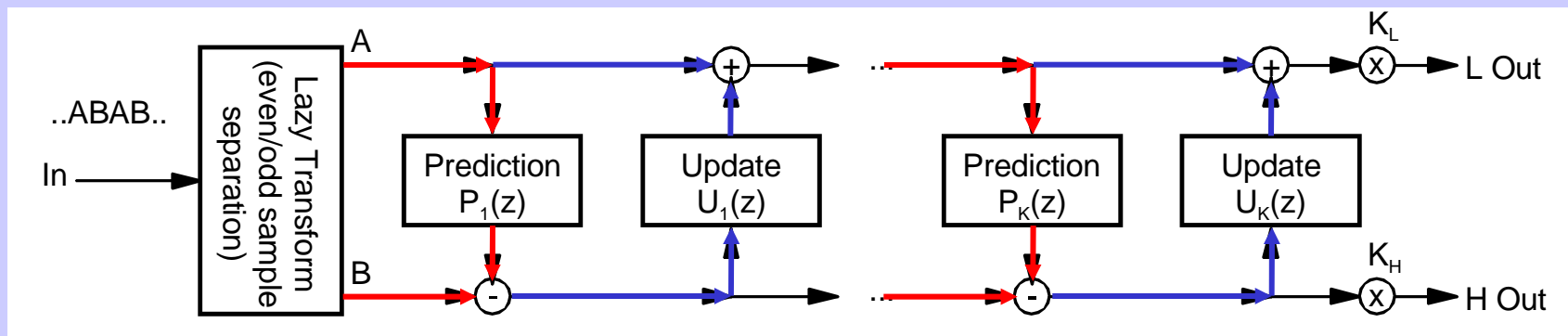
$$H_1^{(5/3)}(z) = \frac{1}{2}(-1 + 2 \cdot z^{-1} - z^{-2})$$

$$G_1^{(5/3)}(z) = \frac{1}{8}(-z^1 + 2 + 6 \cdot z^{-1} + 2 \cdot z^{-2} - z^{-3})$$



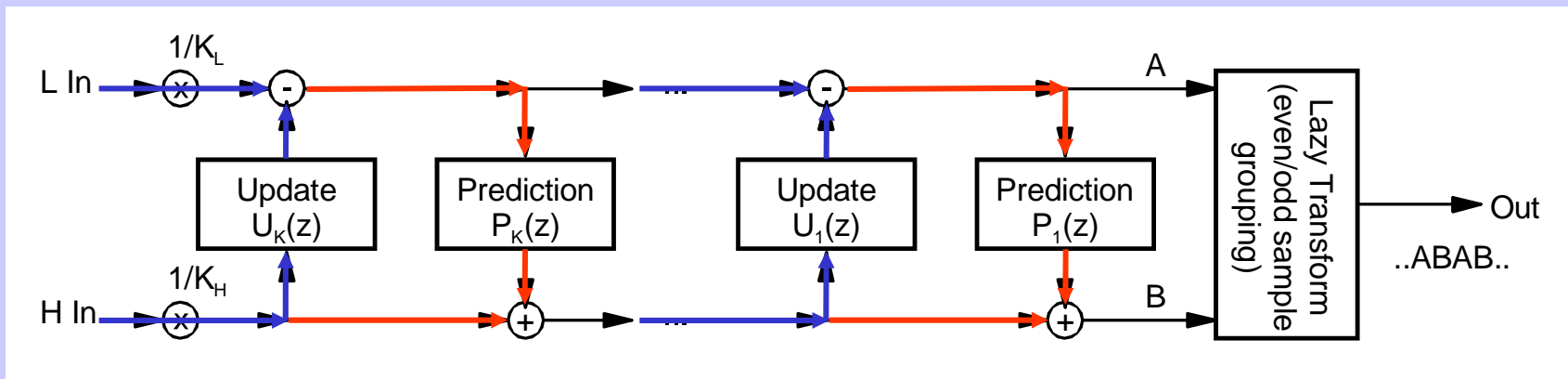
# Lifting Filters

- Biorthogonal filter pairs can be factorized to be implementable in a "ladder structure"
- "Prediction" and "Update" steps using very short filter kernels are then iteratively performed
- "Lifting scheme" is most efficient implementation of wavelet filters available so far



## Lifting Filters

- Synthesis filter pair is implemented by inverse signal flow
- Perfect reconstruction is obvious

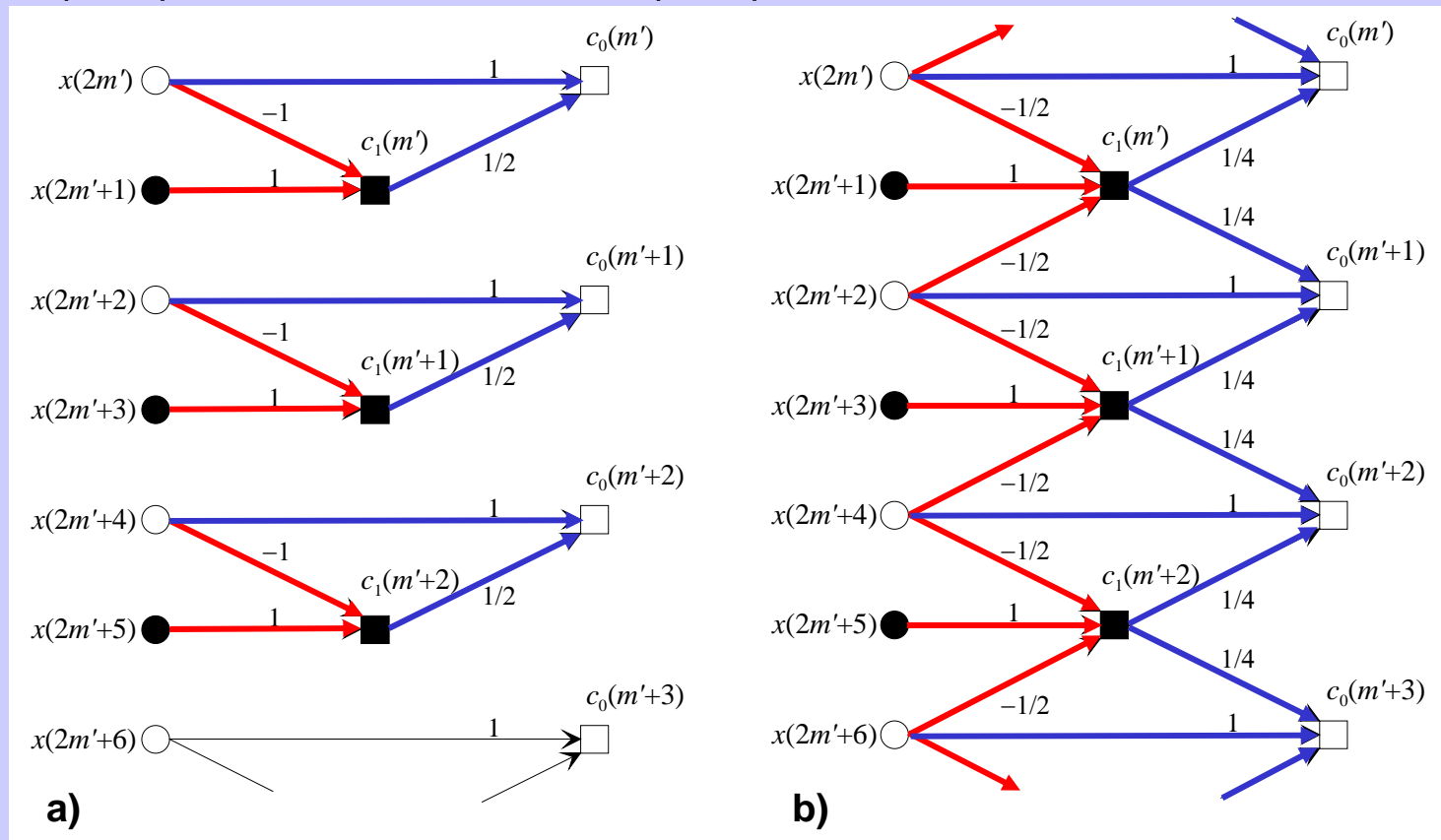


- Quantization of signals in the ladder branches gives integer realization of analysis and synthesis



# Lifting Filters

- Signal flow diagrams of lifting implementations for (5/3) filters and Haar (2/2) filters



# *Motion Compensated Wavelet Coding – basic principles and classification*





## *Wavelet Video Coding - Classification*

- Intraframe coding (e.g. MJPEG)
- 3D wavelet coding without MC
- Hybrid video coding using wavelet-based texture coding
- In-Band Motion Compensation Prediction
- Motion Compensated Temporal Filtering
- In-Band Motion Compensated Temporal Filtering



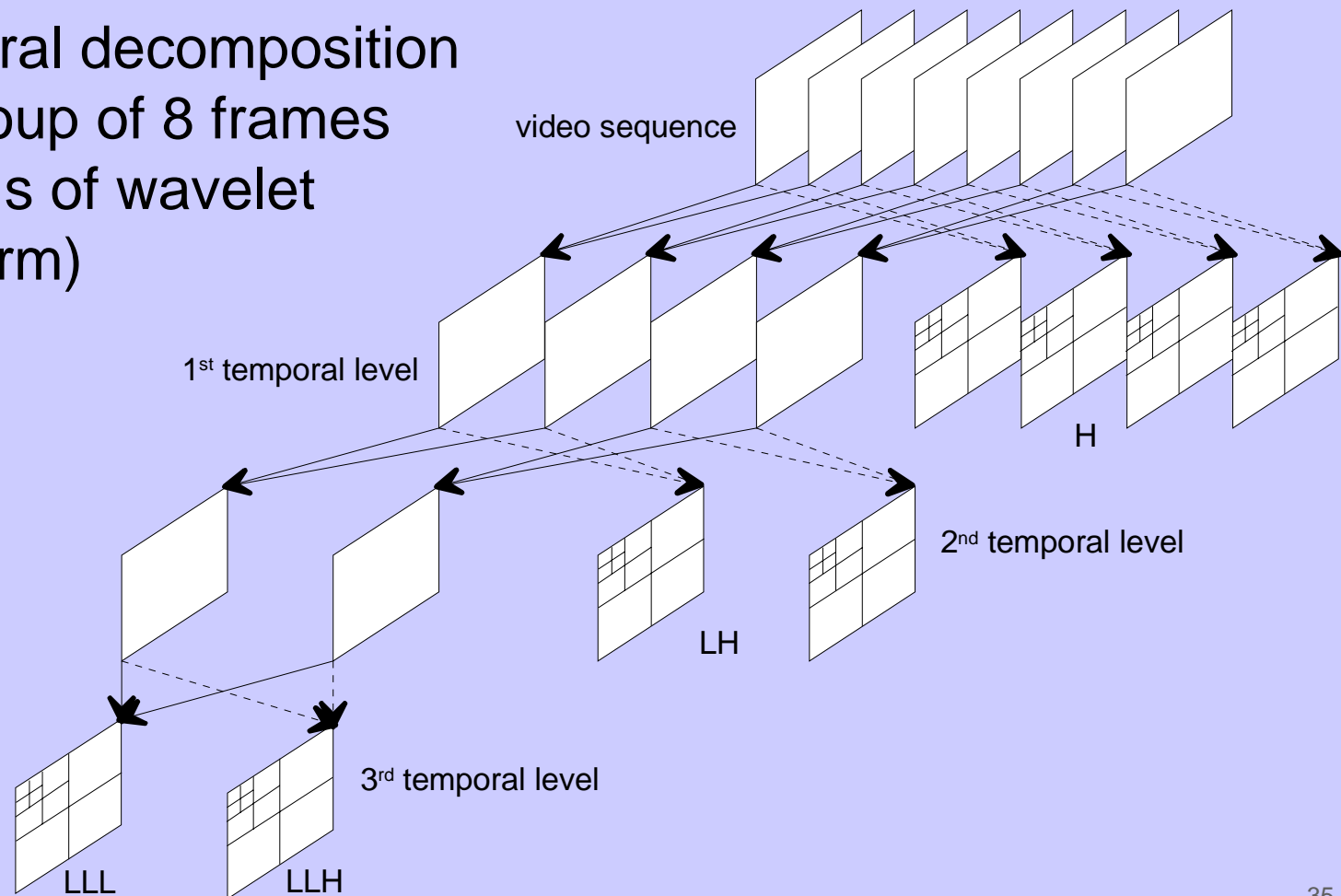
# History

- Using transforms for interframe coding goes back to the 1970/1980s (e.g. Karlsson/Vetterli)
- Drawback was **lack of motion compensation** – first approach to filter over motion trajectories proposed by Kronander (1990)
- Solution **avoiding an overcomplete transform** developed by Ohm (1991,1994)
- Solution for **perfect reconstruction in case of half-pel motion** by Ohm/Rümmeler (1997), Hsiang and Woods (1999)
- Different researchers proposed combination with **temporal axis lifting scheme** which makes virtually **any MC** possible : Pesquet/Bottreau, Luo/Li/Zhang, Secker/Taubman (2001)



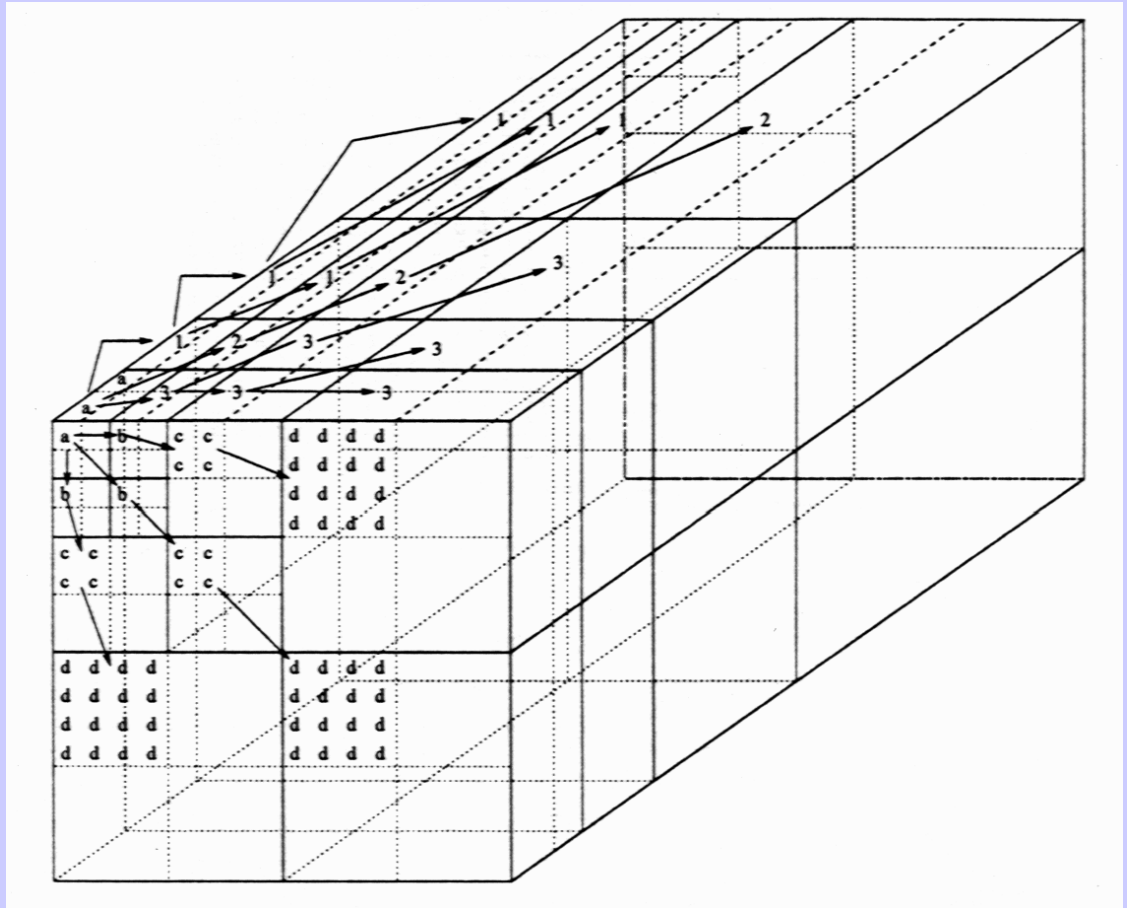
# Three-dimensional Wavelet

- Temporal decomposition of a group of 8 frames (3 levels of wavelet transform)



# Three-dimensional Wavelet Coding

- Extension of zero tree approach to temporal dimension
- Non-recursive coding structure



Examples:

- "3D SPIHT" by Pearlman et al.
- Layered Zero Coding (LZC) by Taubman and Zakhor (only constant displacement motion compensation)



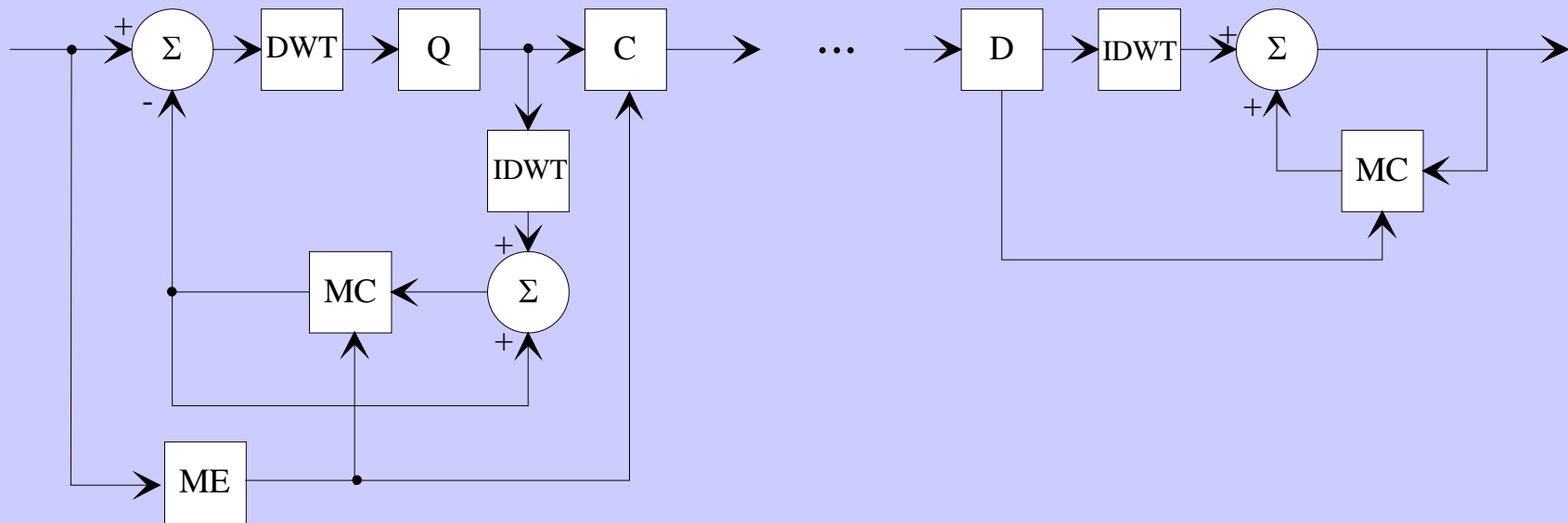
# *Wavelets and Motion Compensation*

- **Motion compensation is key**
  - To achieve good compression performance
  - To guarantee visual quality – non MC/interframe coding with same SNR usually looks worse
- **Motion-compensated Wavelet video coding**
  - Temporal MC prediction followed by Wavelet Transform
  - Wavelet Transform followed by temporal MC prediction in wavelet domain
  - 3D Wavelet with MC



# Hybrid Video Coding using Wavelets

- Replacement of DCT by Wavelet for 2D encoding in MC prediction loop



# *Hybrid Video Coding using Wavelets*

- **Problems and possible solutions:**
  - Wavelet analysis is block-overlapping, discontinuities in motion vector field cause problems
    - Overlapping-block MC
  - Local switching between Intra/inter modes not block-wise
    - Symmetric extension at block discontinuities
- **Drift problem in MC loop is not solved**
  - This is not a real scalable solution



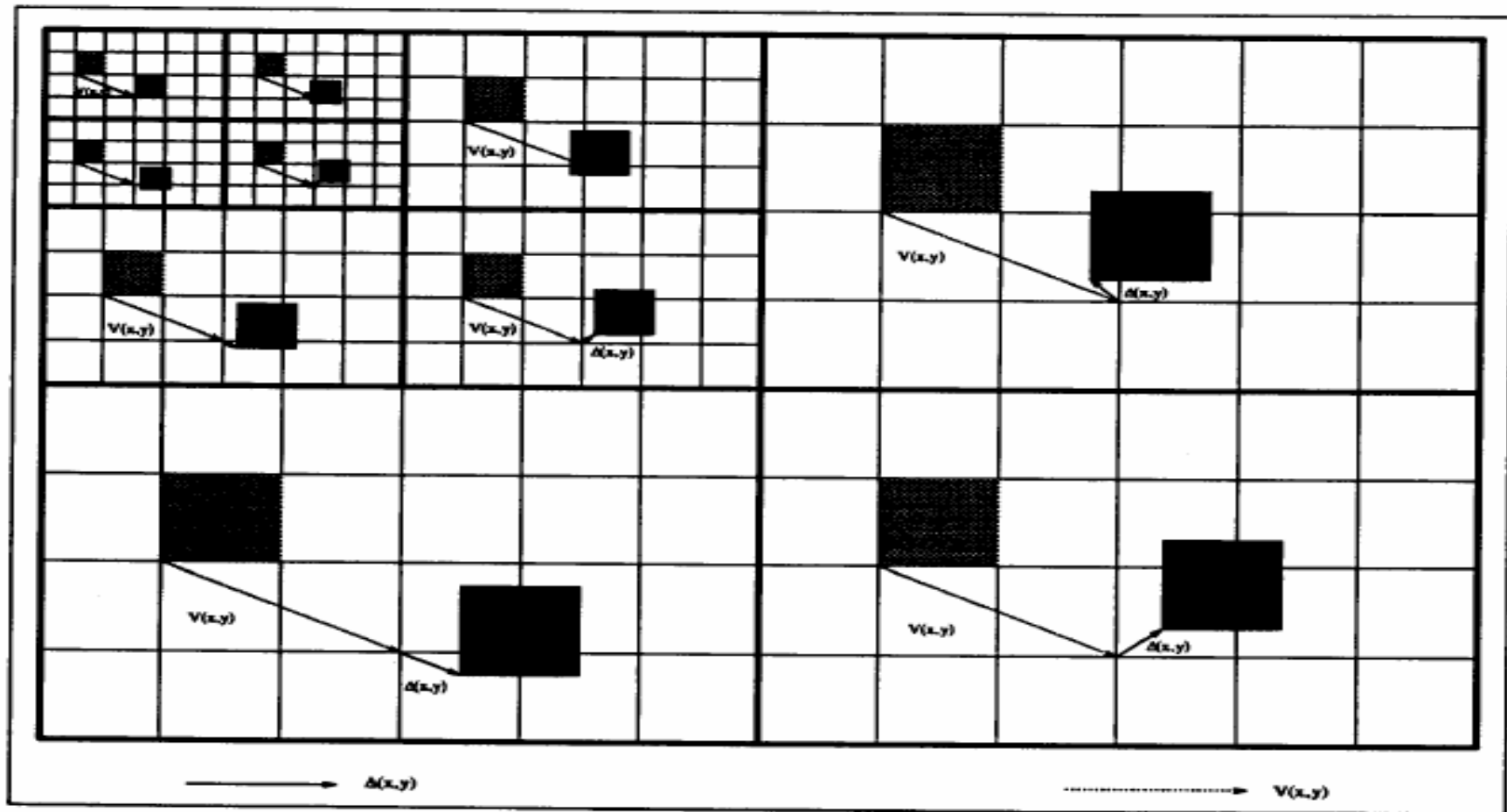
# ***Motion compensation in the wavelet domain***

- Multi-resolution nature of wavelet decomposition is ideal for providing spatially scalable video (QCIF, CIF, SD, and HD)
- Subbands are highly correlated in the temporal direction
  - Motion estimation and compensation can significantly reduce the temporal correlation
- Classical approach
  - - *Ref: Y. Zhang and S. Zafar, IEEE CSVT, Sept. 1992.*

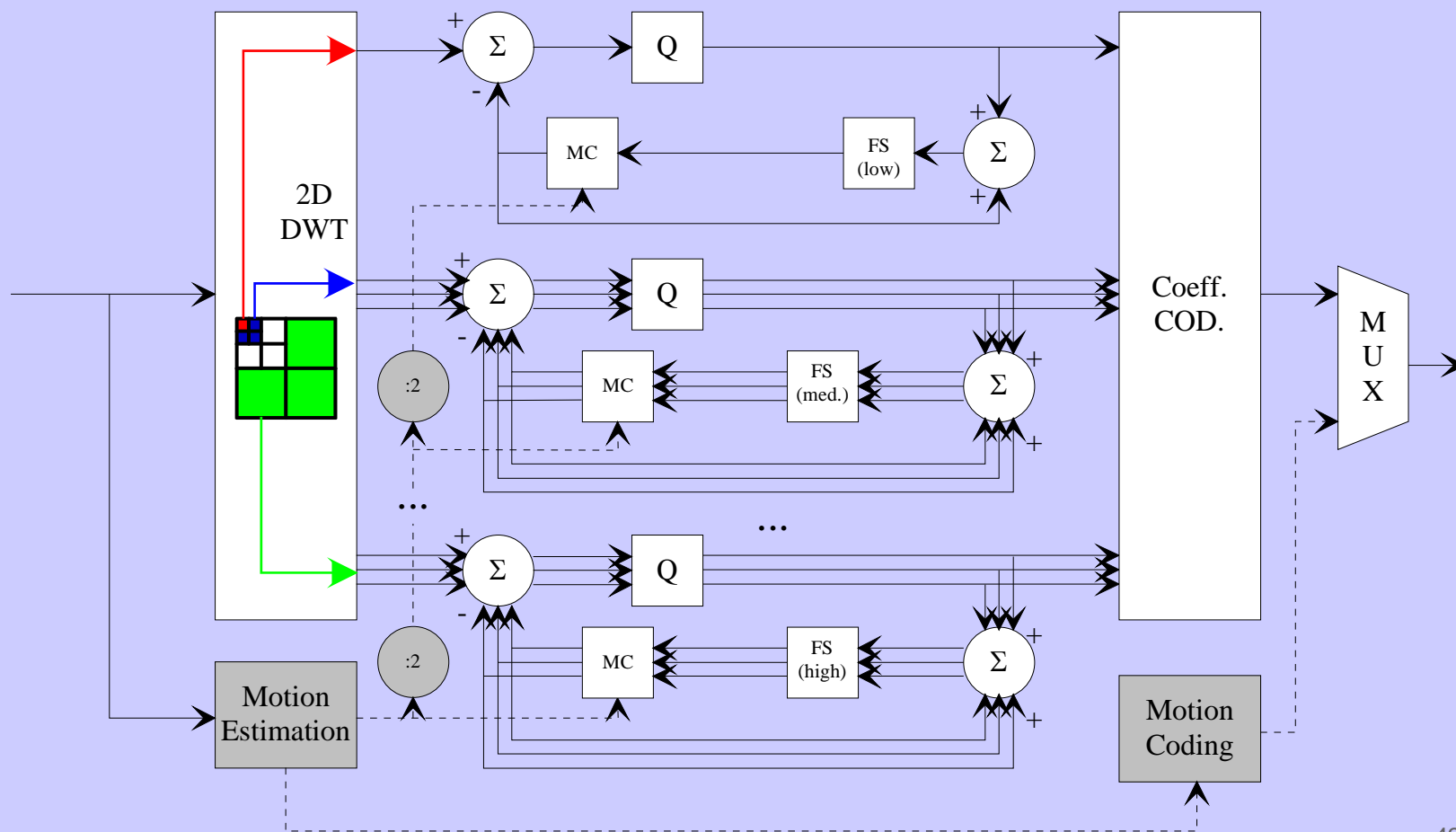




# Multi-Resolution Motion Compensation



# MC in Wavelet Domain - Encoder



## MC in Wavelet Domain

- Variable block size of the m-th layer subbands for M-level decomposition

$$p2^{M-m} \times p2^{M-m}$$

- Motion vector for each subband ( $j=1,\dots,3$ )

$$V_{i,j}^{(m)}(x, y) = V_{i,0}^{(m)}(x, y)2^{M-m} + \Delta_{i,j}^{(m)}(x, y)$$

i: frame number, j: subband index ( $j=0,\dots,3$ ), m: layer number

- Adaptive search range for each subband



## ***MC in Wavelet Domain – Advantages and Drawbacks***

- **Multiple (separate) MC loops for wavelet bands**
  - one set of motion parameters may be used for all
- **No drift problem in spatial scalability**
  - Possible to skip higher frequency bands
- **Switching to "intra" coding mode without penalty**
  - Inverse DWT is applied to images (not differences)
- **Inefficiency of MC prediction in high bands**
  - Significant performance loss compared to ME/MC in spatial domain (e.g. 1-2dB)
  - **The shift variant property** of wavelet decomposition



# *Motion-Compensated Temporal Filtering*



# Motion Compensated Haar Filters

- Non-orthonormal Haar filter basis

$$H_0(z) = \frac{1}{2} \left( 1 + \tilde{z}_1^{\tilde{k}} \cdot \tilde{z}_2^{\tilde{l}} \cdot \tilde{z}_3^{-1} \right)$$

MC shift

Delay by one frame

$$H_1(z) = -\tilde{z}_1^k \cdot \tilde{z}_2^l + \tilde{z}_3^{-1}.$$

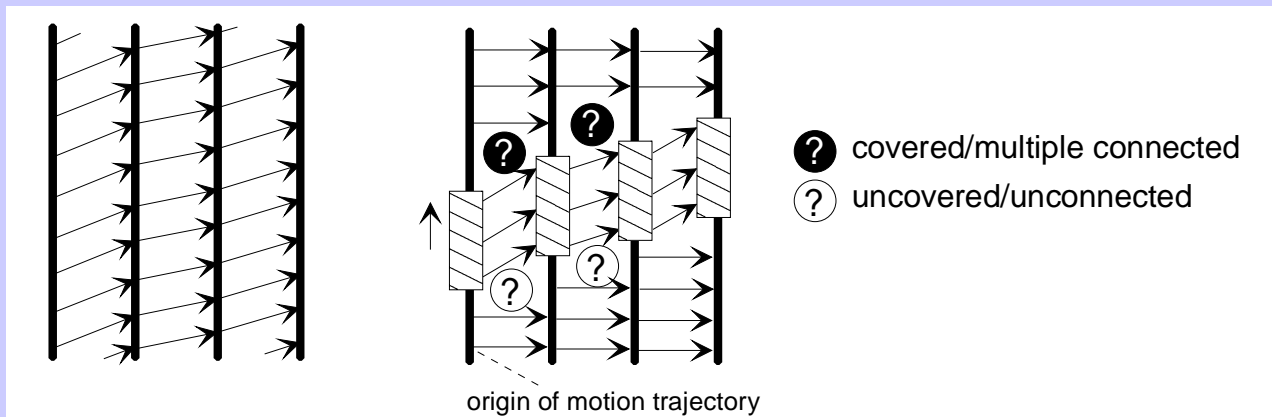


## Motion Compensated Haar Filters

- This motion-compensated filtering is no problem whenever unique sample-wise correspondences exist between two frames

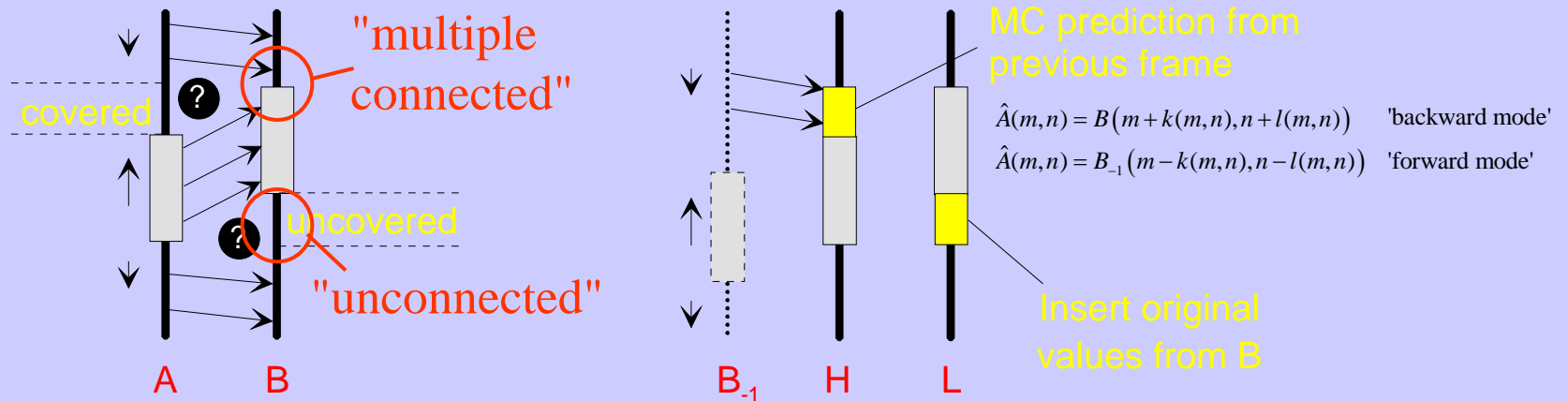
$$\begin{aligned} \tilde{k}(m_B, n_B) &= -k(m_A, n_A) \\ \tilde{l}(m_B, n_B) &= -l(m_A, n_A) \end{aligned} \quad \text{with} \quad \begin{cases} m_B = m_A + k(m_A, n_A) \\ n_B = n_A + l(m_A, n_A). \end{cases}$$

- Real motion vector fields are discontinuous, such that correspondences may not be unique



# Motion Compensated Haar Filters

- Substitution technique for covered/uncovered areas allows perfect reconstruction at motion discontinuities



$$L(m, n) = 0.5 \cdot B(m, n) + 0.5 \cdot A(m + \tilde{k}(m, n), n + \tilde{l}(m, n))$$

$$H(m, n) = A(m, n) - B(m + k(m, n), n + l(m, n))$$

$$L(m, n) = B(m, n) \quad \text{if 'unconnected'}$$

$$H(m, n) = A(m, n) - \hat{A}(m, n) \quad \text{if 'multiple connected'}$$



## ***Motion Compensated Haar Filters***

- Synthesis is straightforward in case of full-pixel correspondences

$$\tilde{A}(m,n) = L(m + k(m,n), n + l(m,n)) + 0.5H(m,n)$$

$$\tilde{B}(m,n) = L(m,n) - 0.5H(m + \tilde{k}(m,n), n + \tilde{l}(m,n)),$$

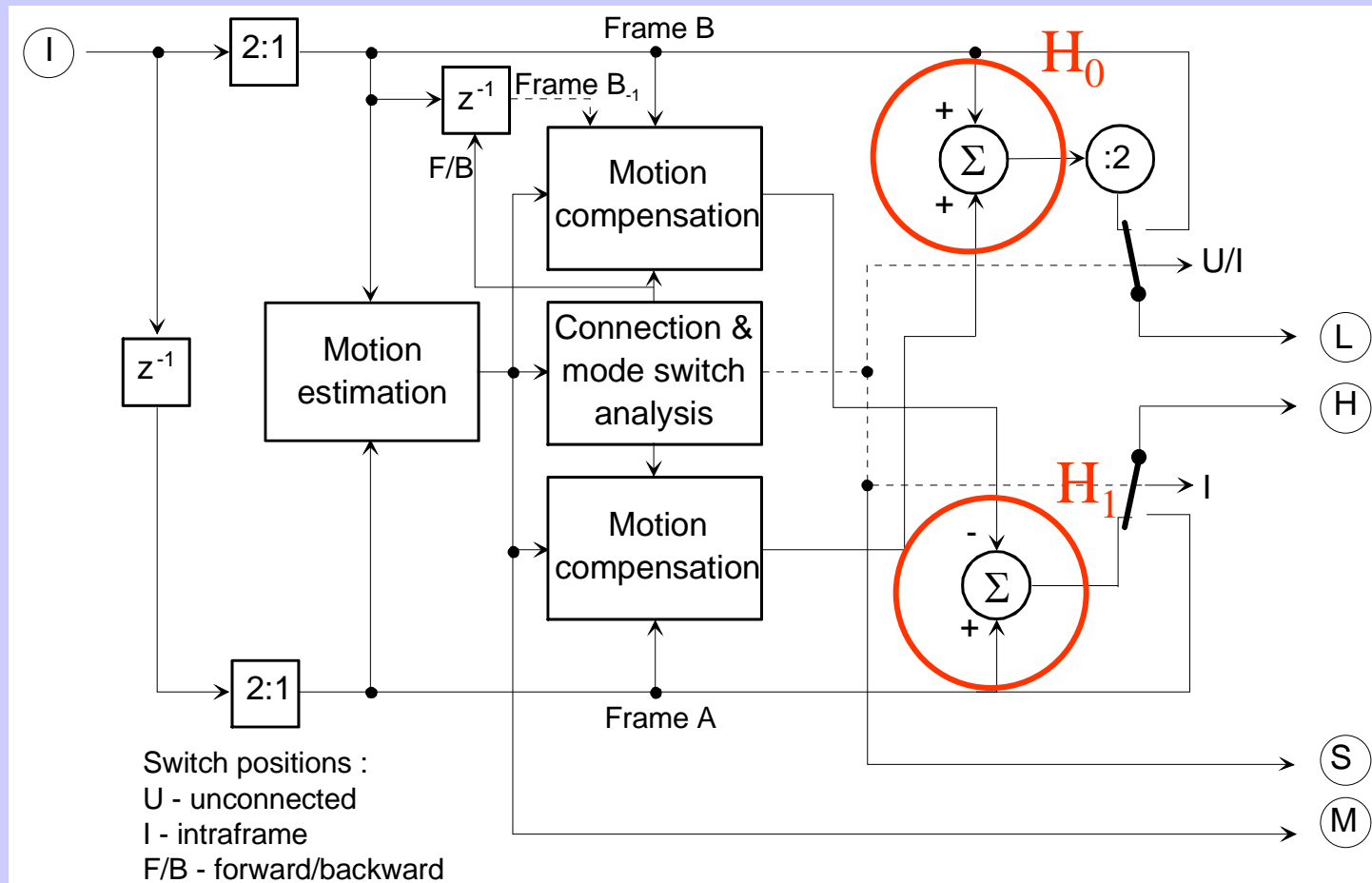
$$\tilde{B}(m,n) = L(m,n) \quad \text{if 'unconnected'}$$

$$\tilde{A}(m,n) = \hat{A}(m,n) + H(m,n) \quad \text{if 'multiple connected'}$$



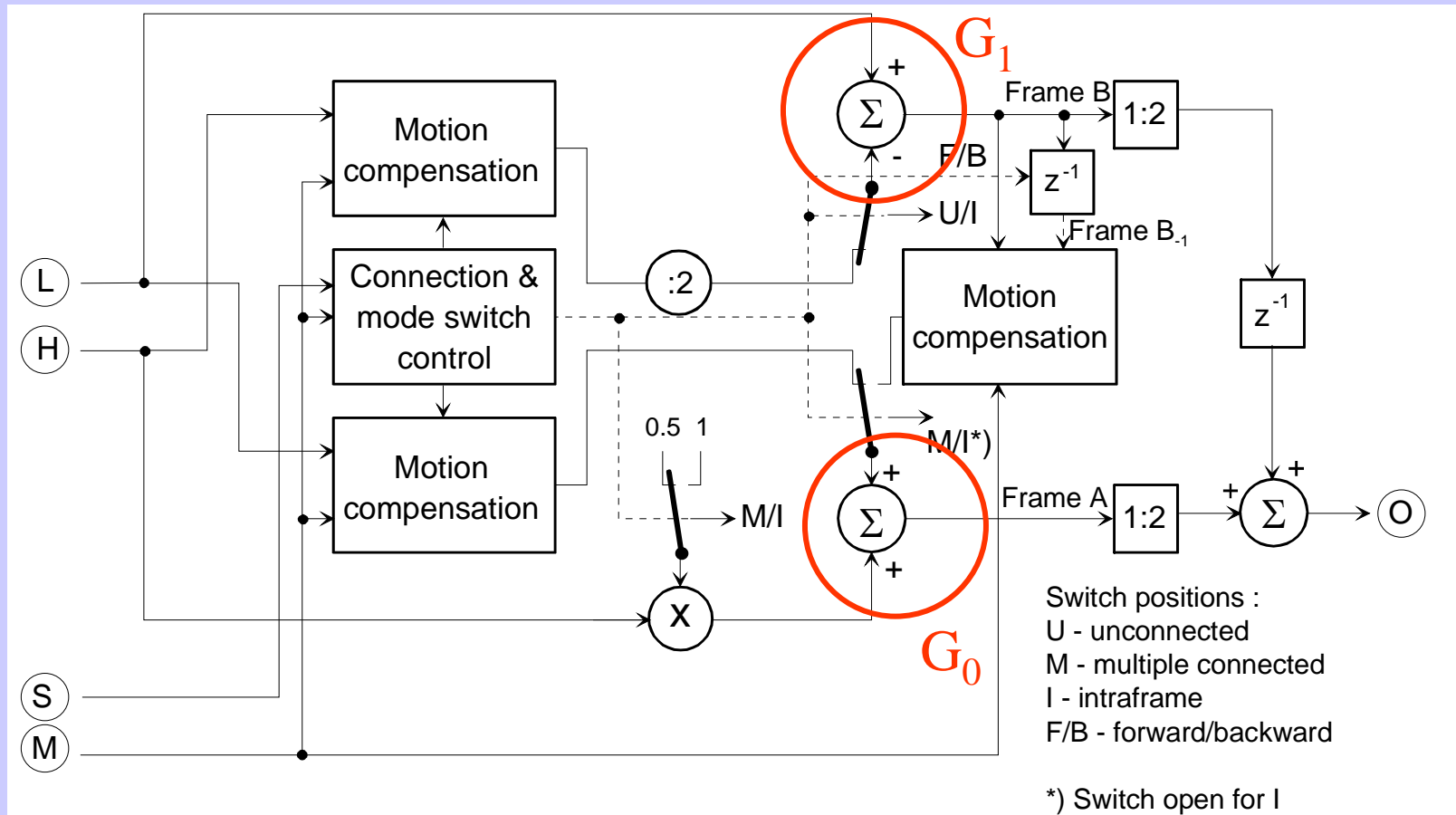
# Motion Compensated Haar Filters

- 2-band temporal Haar analysis filter

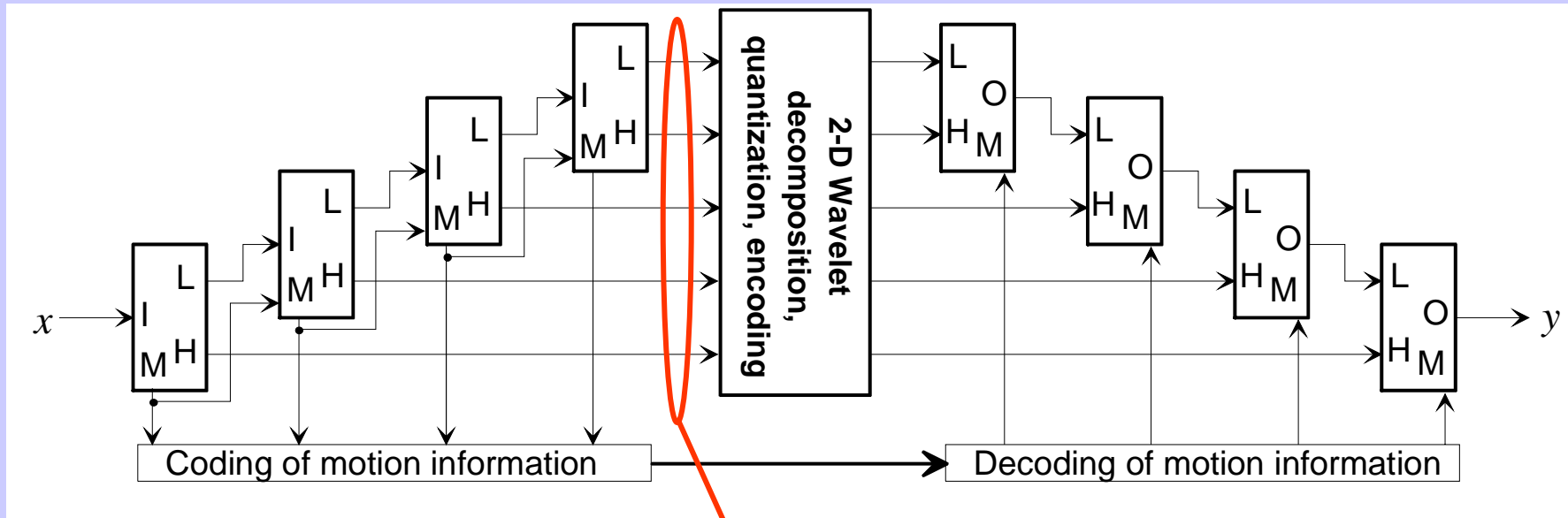


# Motion Compensated Haar Filters

- 2-band temporal Haar synthesis filter



# Motion Compensated Temporal Wavelet Tree



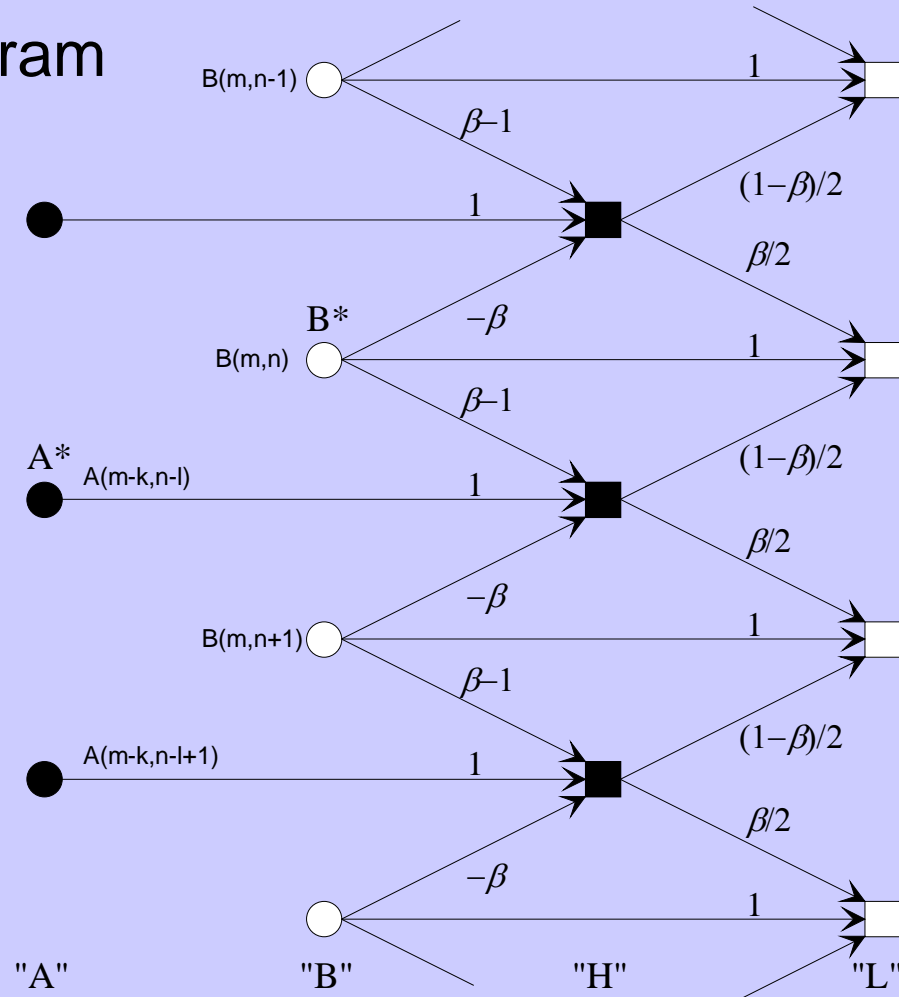
Scaling and Wavelet coefficients  
from temporal analysis (arranged as 2D images)



# Motion-compensated Lifting Filters

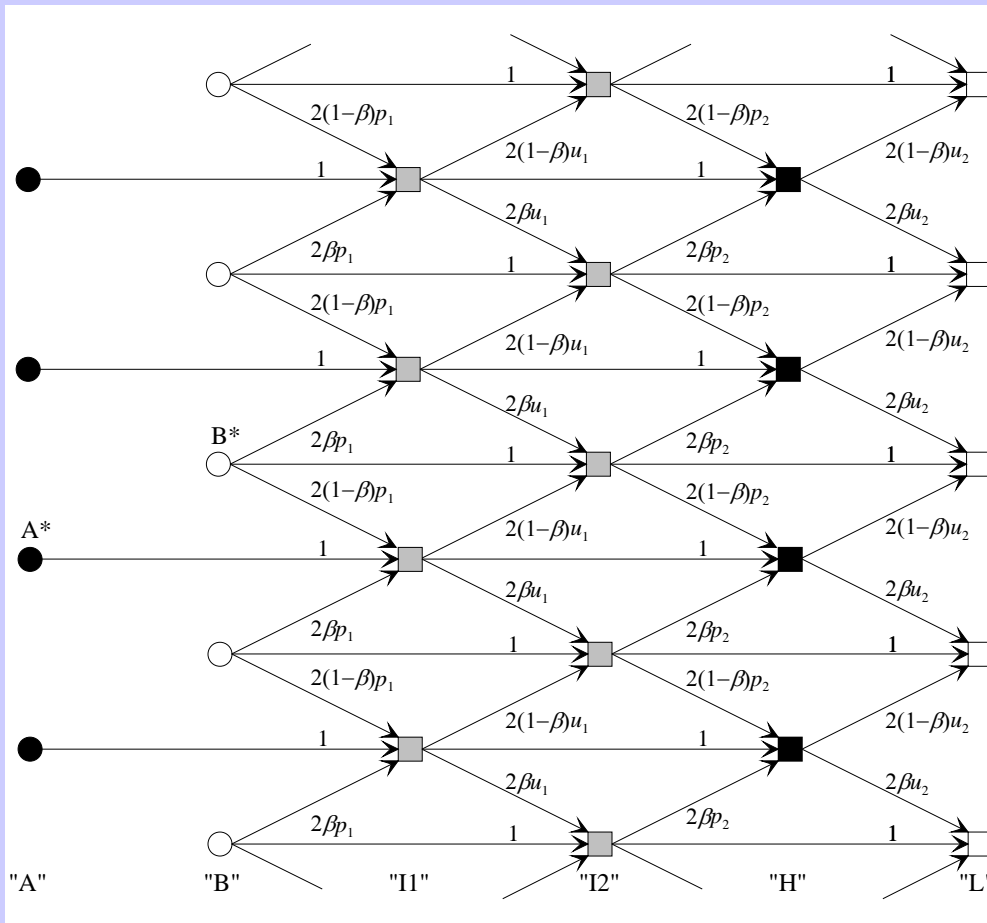
- Signal flow diagram

Vertical shift  
by  $l + \beta$   
pixels



# Motion-compensated Lifting Filters

- Extensible to longer interpolation filters, e.g. (9/7)



With  $\beta=0.5$ :  
 Equivalent to the half-pel  
 P.R. method proposed in  
 [Ohm, Rummeler 97]  
 and used in  
 [Hsiang, Woods 99]



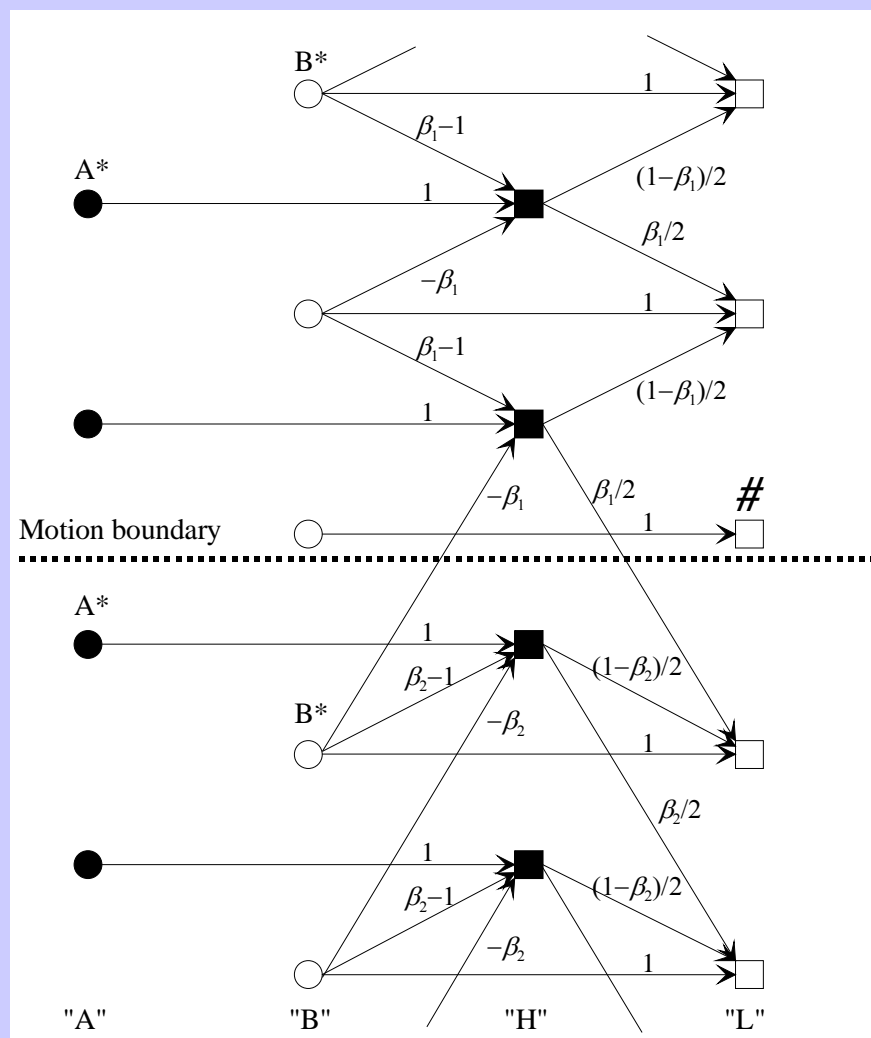
## ***Motion-compensated Lifting filters***

- The principle is straightforwardly extensible to
  - longer wavelet filters
  - separable (or non-separable 2D filters)
  - change of a with any position (e.g. MC based on affine model, dense motion vector fields)
- Coincidence of motion correspondences in adjacent prediction and update steps must be observed
- Lifting implementation of temporal wavelet filtering also leads to an elegant interpretation of previous covered/uncovered pixel substitution
- Very efficient implementation



# Motion-compensated Lifting filters

- Adaptation at motion boundaries :  
"uncovered/unconnected" case
- Additional "lazy" pixel(s) in frame B

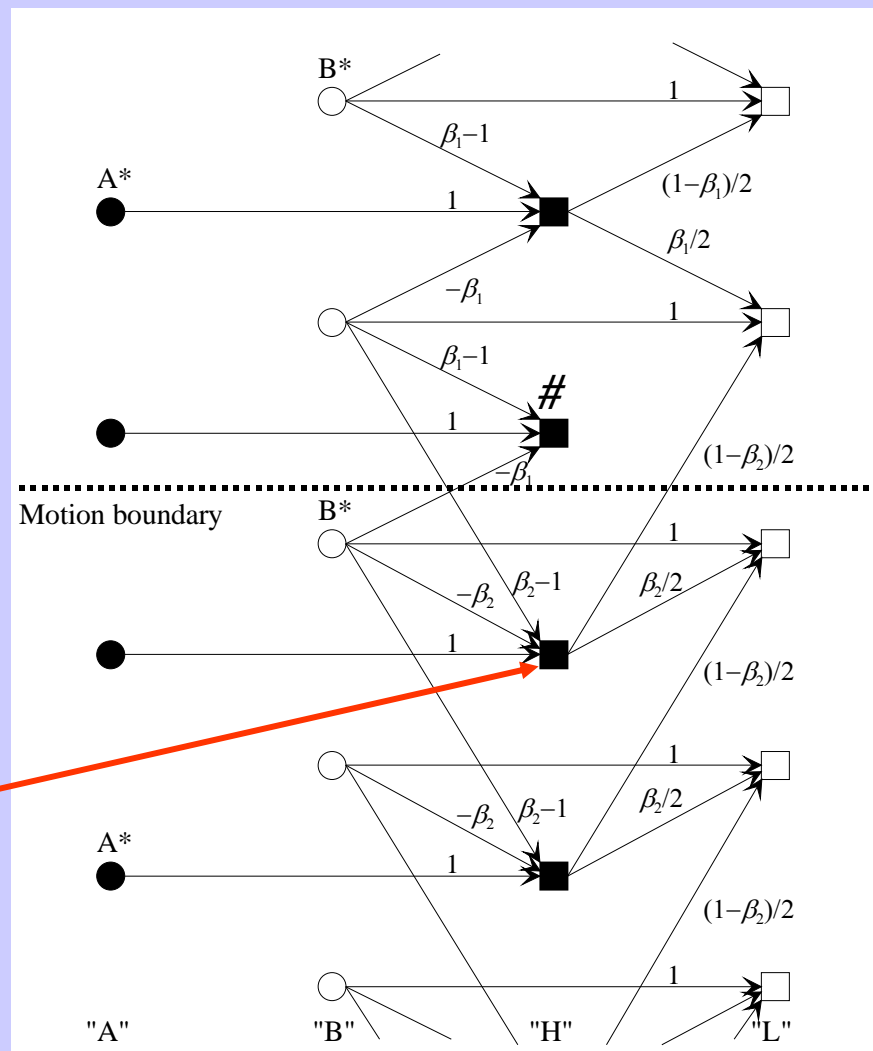




# Motion-compensated Lifting filters

- Adaptation at motion boundaries :  
"Covered/multiple connected" case
- Additional prediction pixel(s) in frame A/H

This pixel might also take the 'unconnected' role!



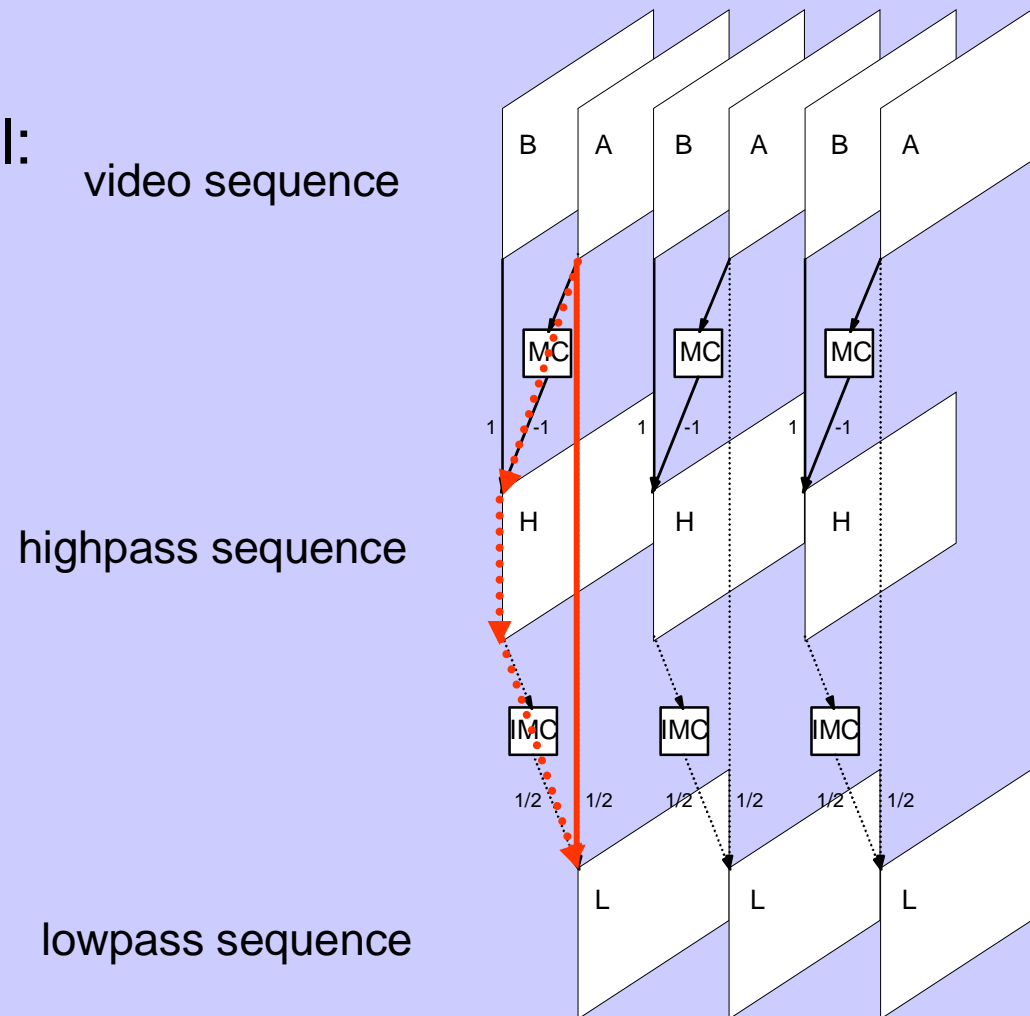
## ***Motion-compensated Lifting filters***

- **Frame-wise or localized implementation of intra coding is a key concept in MC prediction coders**
  - Switching to **intra mode** is applied whenever no motion correspondence can be found, e.g. scene changes or uncovered areas
- In MC temporal filtering
  - the equivalent is an **adaptation of wavelet tree depth**
  - but intra coding could also be applied individually in the prediction and update steps
- In general, **localized mode switching** can be included in a simple way in the lifting structure



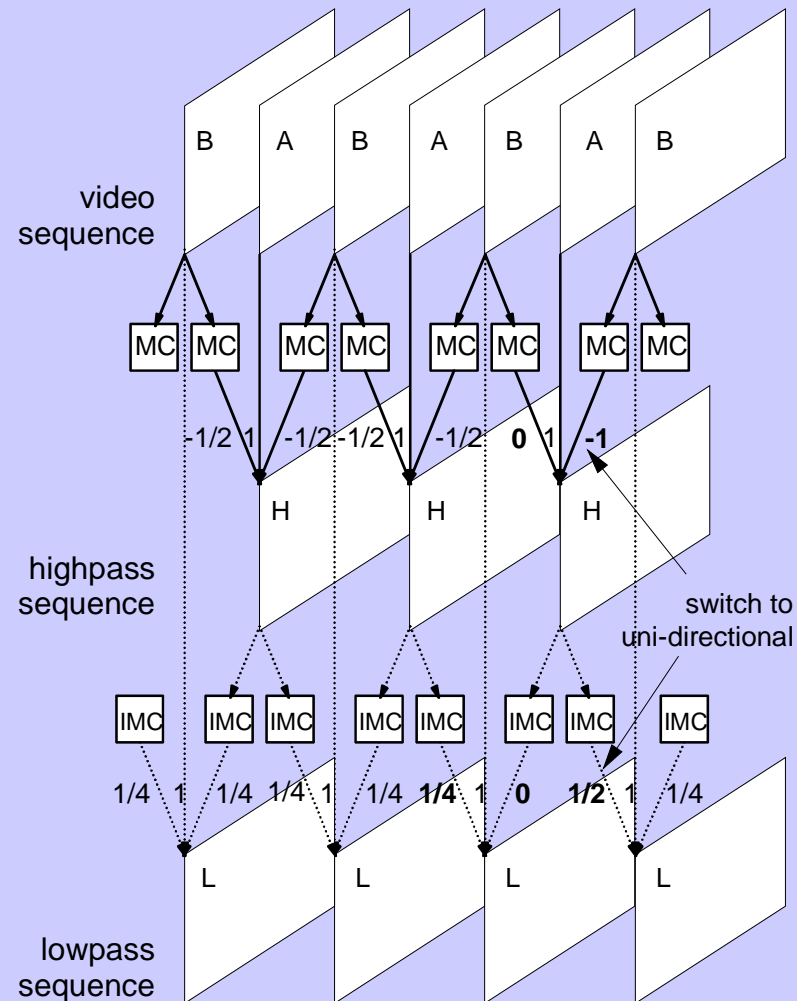
## More Flexibility in MC Lifting Filters

- Different view of one transform level: Temporal-axis lifting filters, including 2D MC in cross paths
- MC and IMC should be related such that pixels from A correspond to L



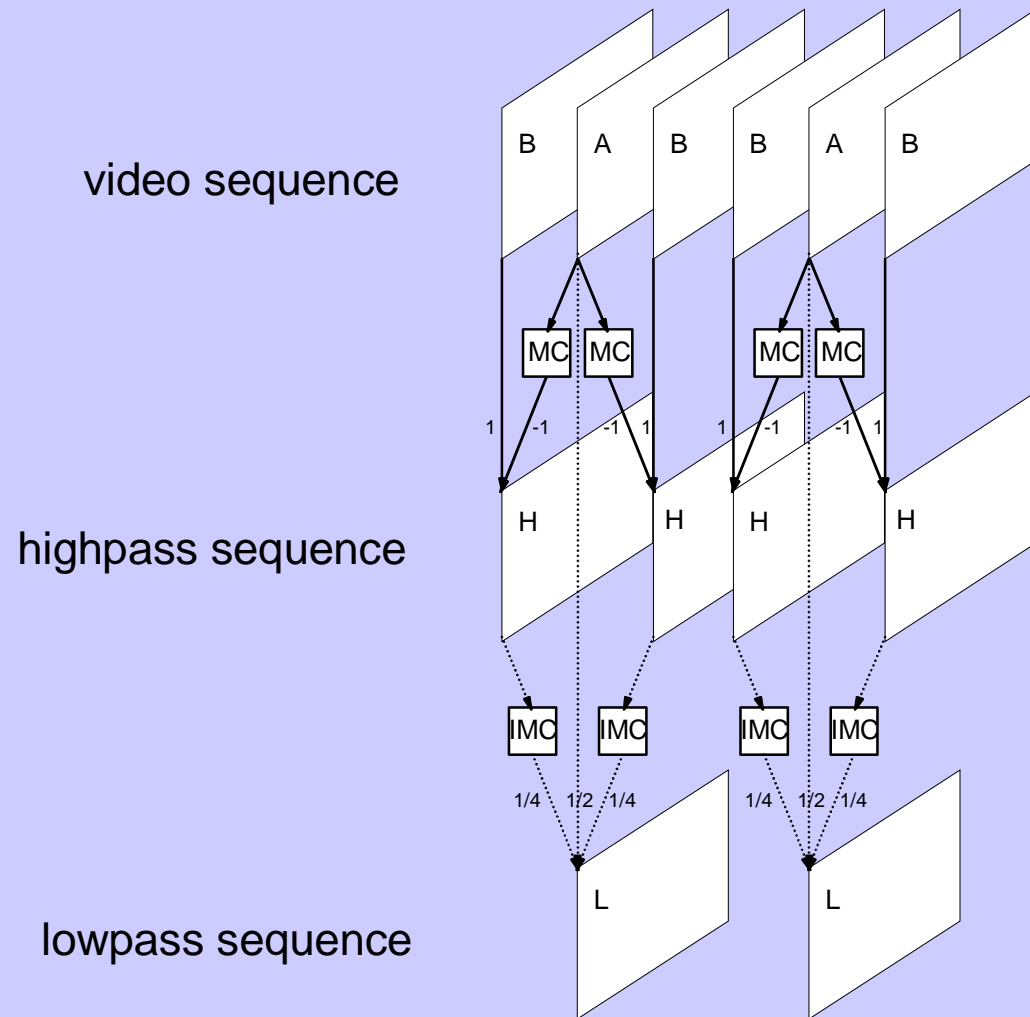
## More Flexibility in MC Lifting Filters

- Extension to longer temporal filters (5/3)
- H frames equivalent to bidirectional prediction
- Forward/backward switching possible
- Better coding efficiency
- No temporal blocking
- More memory
- Higher delay
- More motion vectors



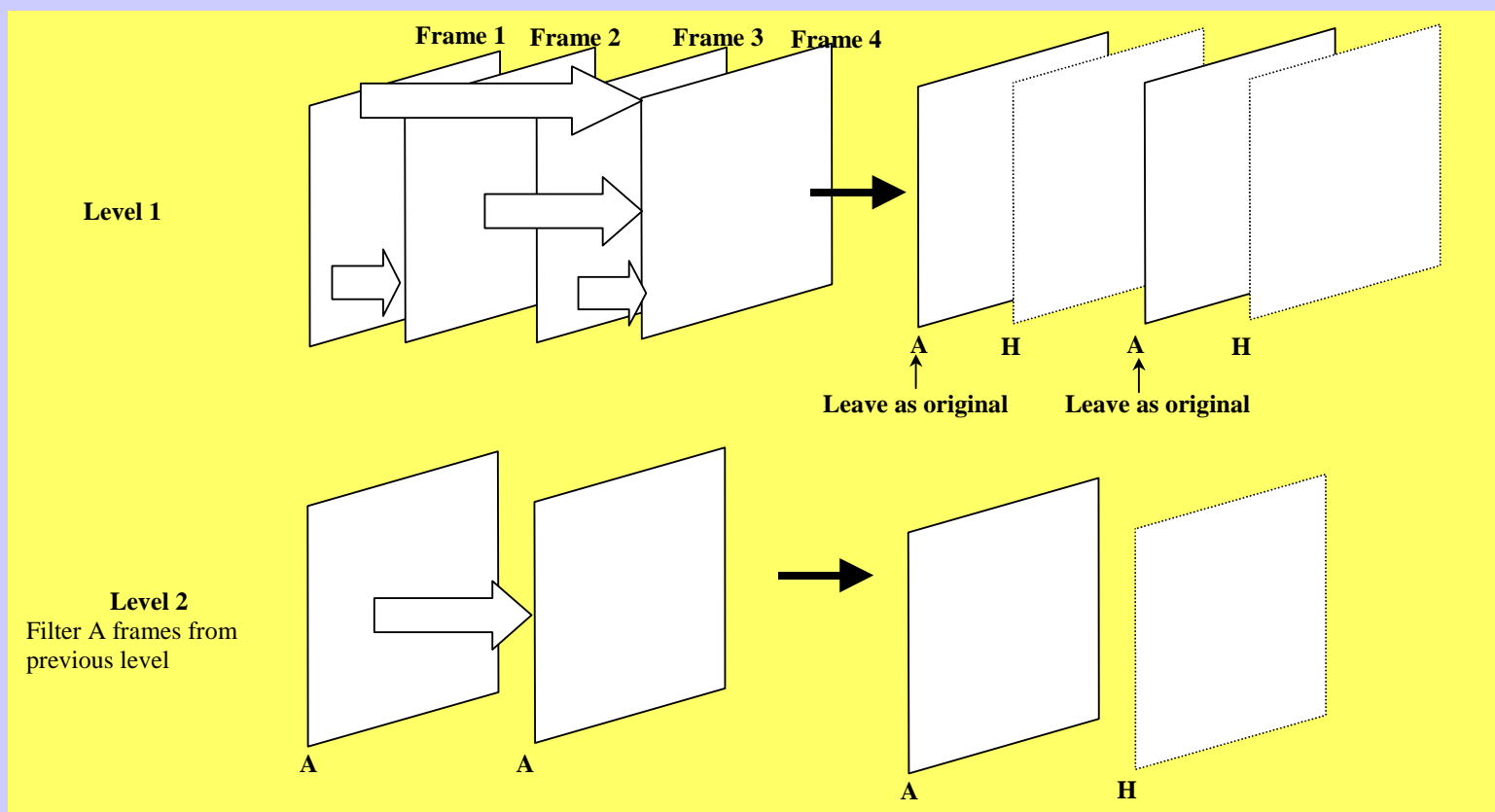
## More Flexibility in MC Lifting Filters

- Non-dyadic decomposition
- Temporal block units of 3 frames
- E.g. 30/10 Hz temporal scalability
- Can be extended to bidirectional MC in prediction step



## Low-Delay modes in MC Temporal Filtering

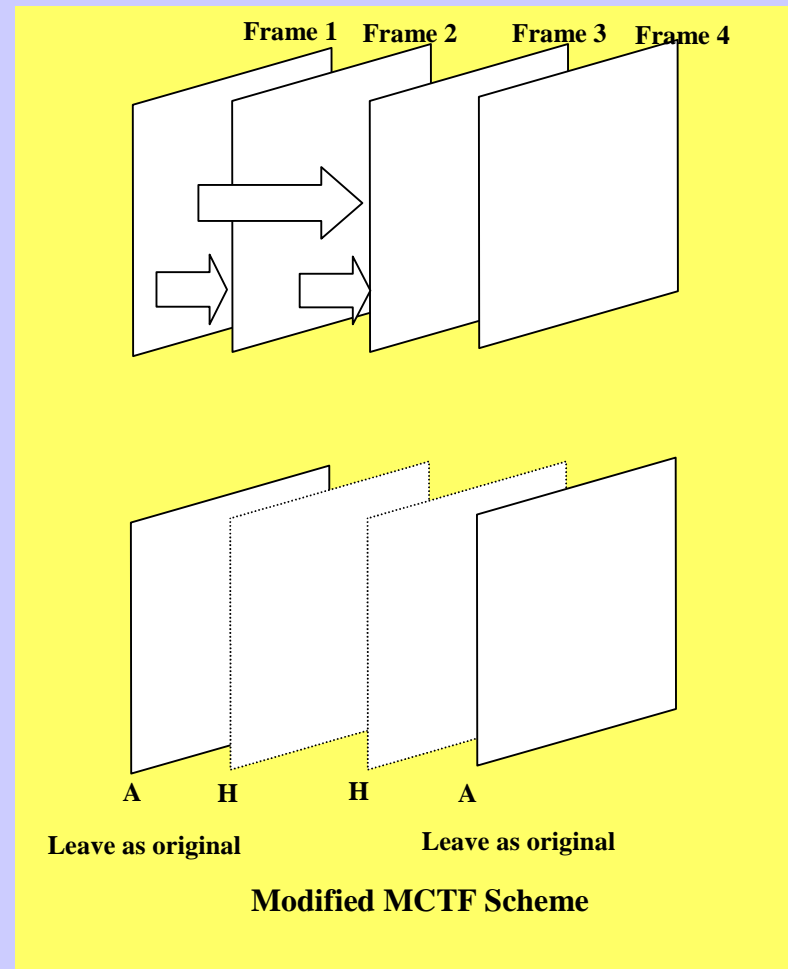
- Temporal pyramid decomposition with **omission of update step** ("A" frames left as originals)



# *Low-Delay modes in MC Temporal Filtering*

**"A" frames can be inserted at arbitrary locations ->**

the sequence can be decoded at non-dyadic lower frame rates



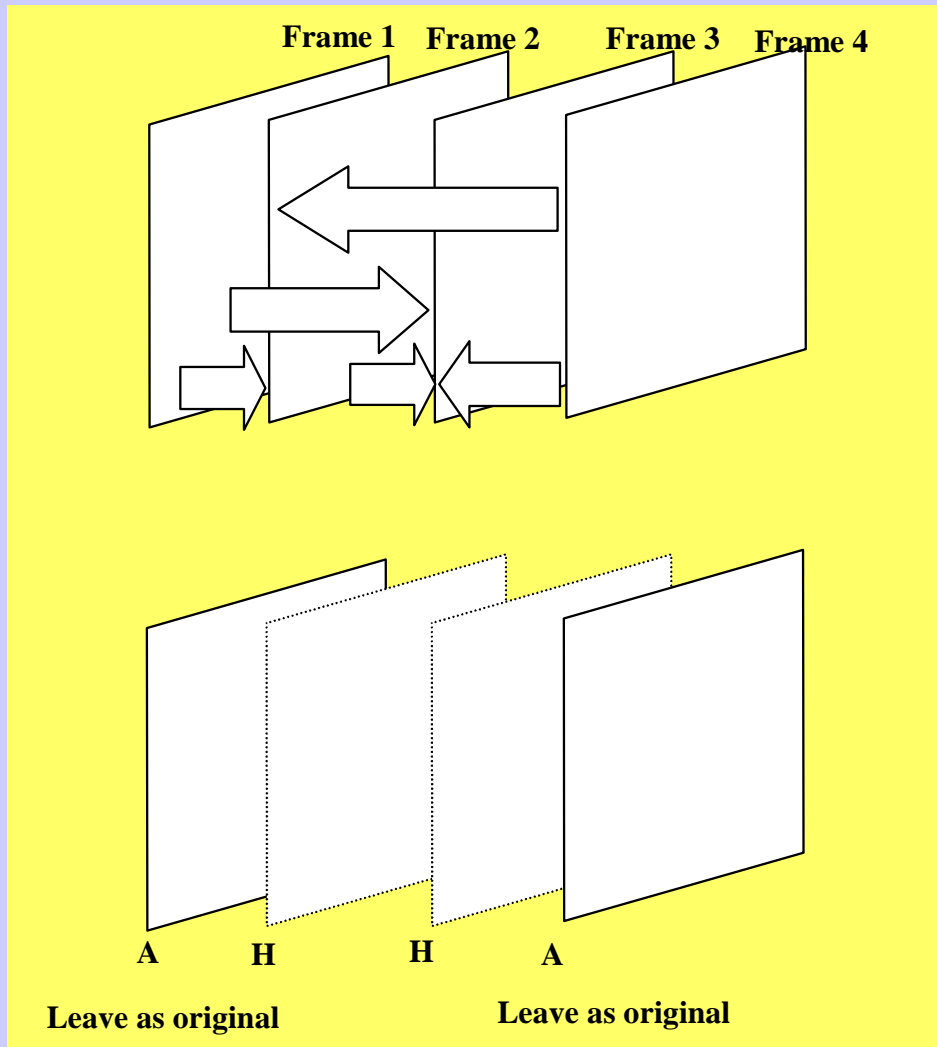
## *Low-Delay modes in MC Temporal Filtering*

- **A frames allow implementation of a low-delay mode**
  - A frames can be encoded and transmitted immediately, but must be stored for future reference
  - H frames can be encoded and transmitted immediately in any of the schemes
- **Disadvantage :**
  - lower coding efficiency
  - May be compensated by improved prediction





# Low-Delay modes in MC Temporal Filtering



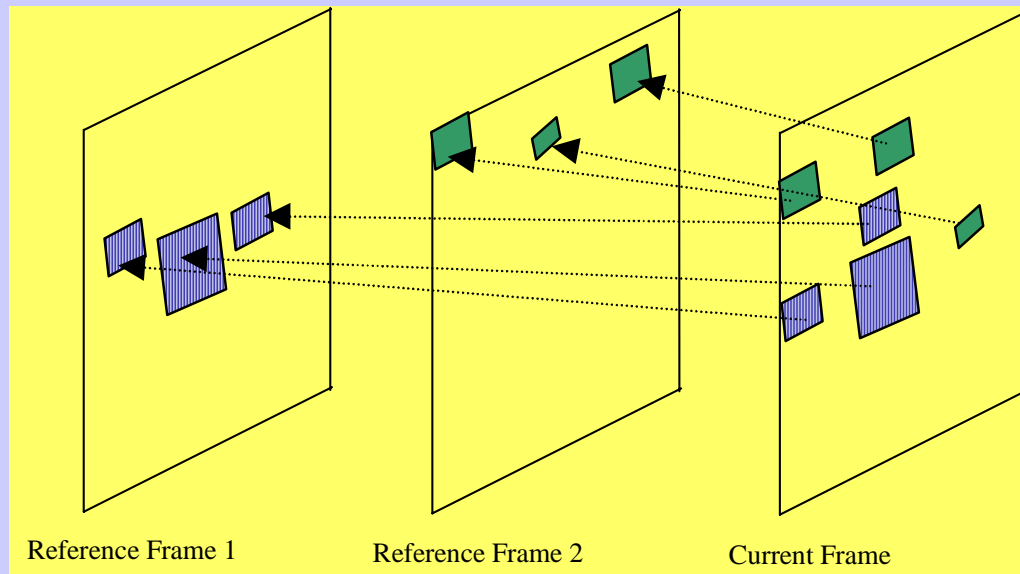
## Inclusion of bi-directional prediction

Choice between 3 modes:

- Use backward prediction
- Use forward prediction
- Use the average block of the backward and forward predictions while filtering

# Low-Delay modes in MC Temporal Filtering

- Prediction step can be enriched by selecting multiple reference frames



## Advantages

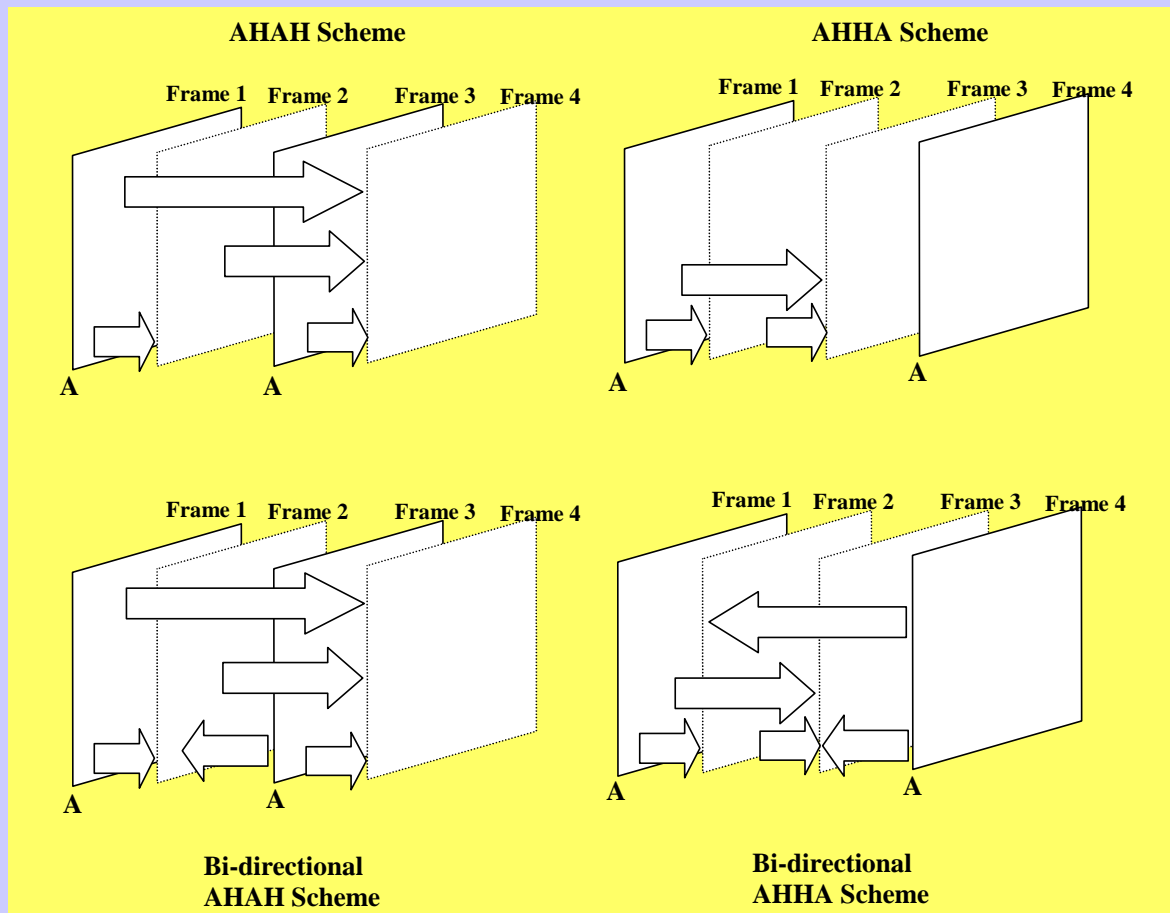
- Improved coding efficiency
- Easy to incorporate the advanced MC & ME options used by predictive coders (H.264/AVC, MPEG-4 etc.)
- Reduced no. of unconnected pixels

## Disadvantages

- Sacrifice Temporal Scalability
- Prediction drift can become a problem when decoding at lower bit-rates

# Low-Delay modes in MC Temporal Filtering

- Different configurations at any level of pyramid



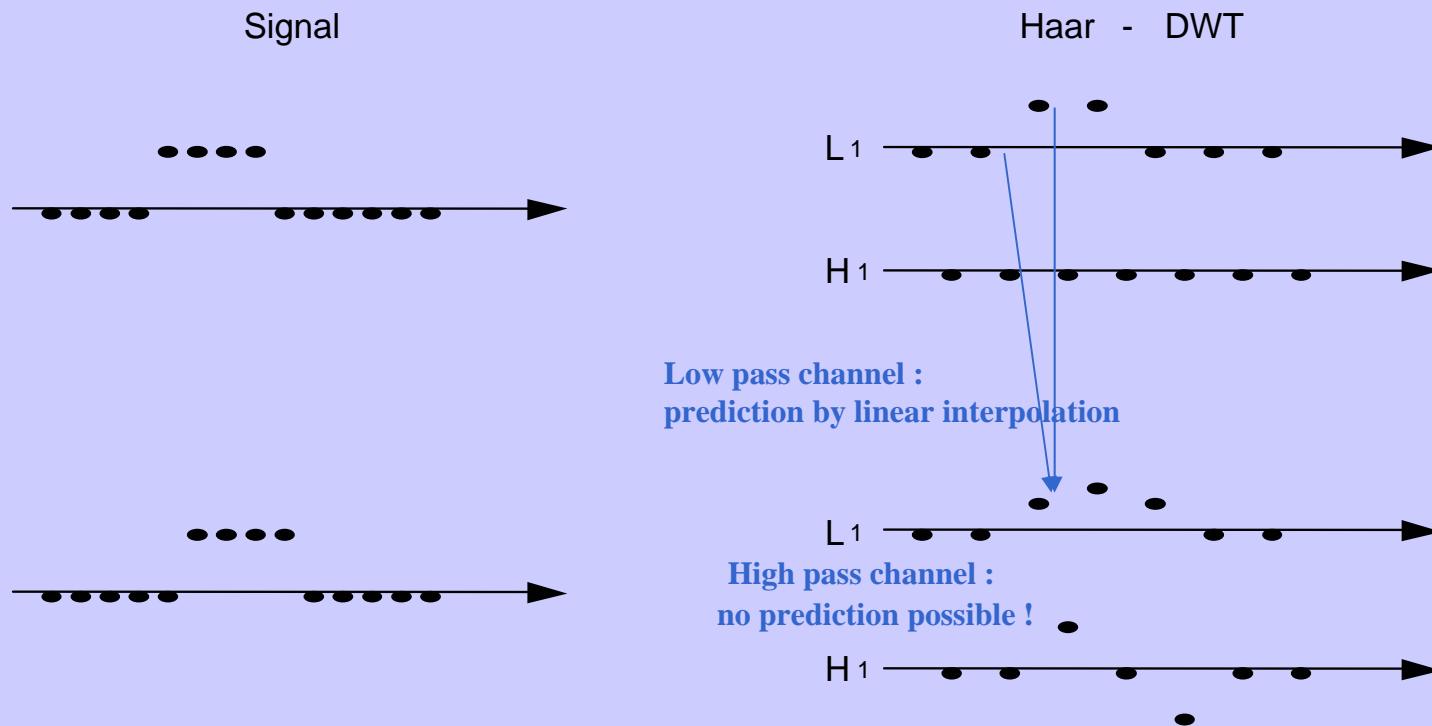
# *Overcomplete Motion Compensated Wavelet Coding*

- **Shift-variant property of wavelets**
- **Frame theory - overcomplete wavelets**
- **Low band shifting method**
- **Inband motion compensated temporal filtering**
- **Simulation results**

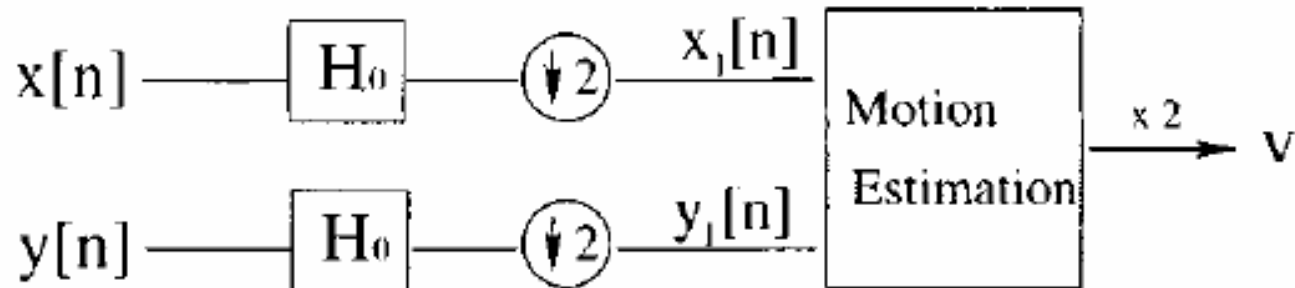


# *The Shift Variance Property of Wavelets*

- Haar filter output of step edges



## *The Shift Variance Property of Wavelets*



$$X_1(\omega) = \frac{1}{2} \left( H_0 \left( \frac{\omega}{2} \right) X \left( \frac{\omega}{2} \right) + H_0 \left( \frac{\omega}{2} + \pi \right) X \left( \frac{\omega}{2} + \pi \right) \right)$$

$$Y_1(\omega) = \frac{1}{2} \left( H_0 \left( \frac{\omega}{2} \right) Y \left( \frac{\omega}{2} \right) + H_0 \left( \frac{\omega}{2} + \pi \right) Y \left( \frac{\omega}{2} + \pi \right) \right)$$



## *The Shift Variance Property of Wavelets*

- Suppose  $y[n] = x[n - v]$ .
- By substituting  $Y(\omega) = X(\omega)e^{-j\omega v}$

$$Y_1(\omega) = \frac{1}{2} \left( H_0 \left( \frac{\omega}{2} \right) X \left( \frac{\omega}{2} \right) e^{-j(\omega/2)v} + H_0 \left( \frac{\omega}{2} + \pi \right) X \left( \frac{\omega}{2} + \pi \right) e^{-j((\omega/2)+\pi)v} \right).$$

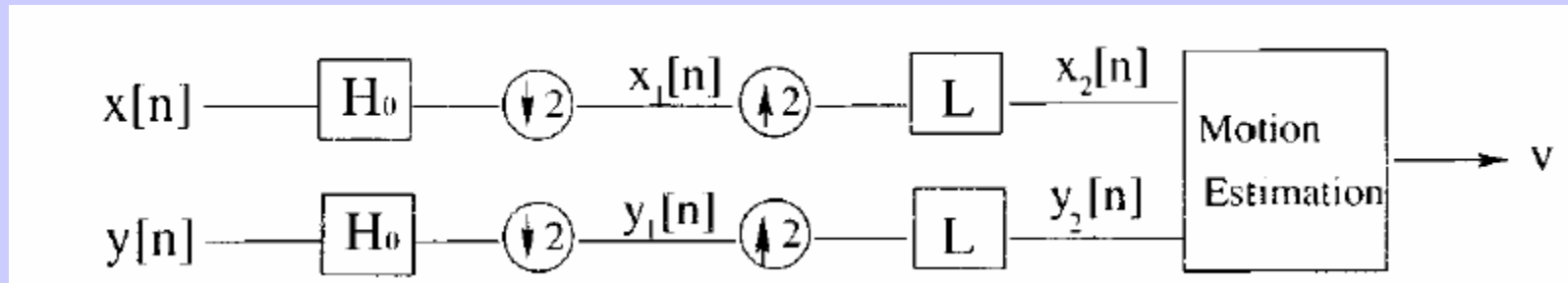
- Hence,

$$Y_1(\omega) - X_1(\omega)e^{-j(\omega/2)v} = \frac{1}{2} H_0 \left( \frac{\omega}{2} + \pi \right) X \left( \frac{\omega}{2} + \pi \right) (1 - e^{-j\pi v}) e^{-j\omega/2}$$

Aliasing components (zero only when  $v = \text{even}$ )

## Optimal Aliasing Reduction Filter Approach

- In order to minimize the aliasing in wavelet domain ME/MC (X.Yang, K. Ramchandran, IEEE-TIP, May, 2000)



- $L$  : aliasing reduction filter





# Optimal Aliasing Reduction Filter Approach

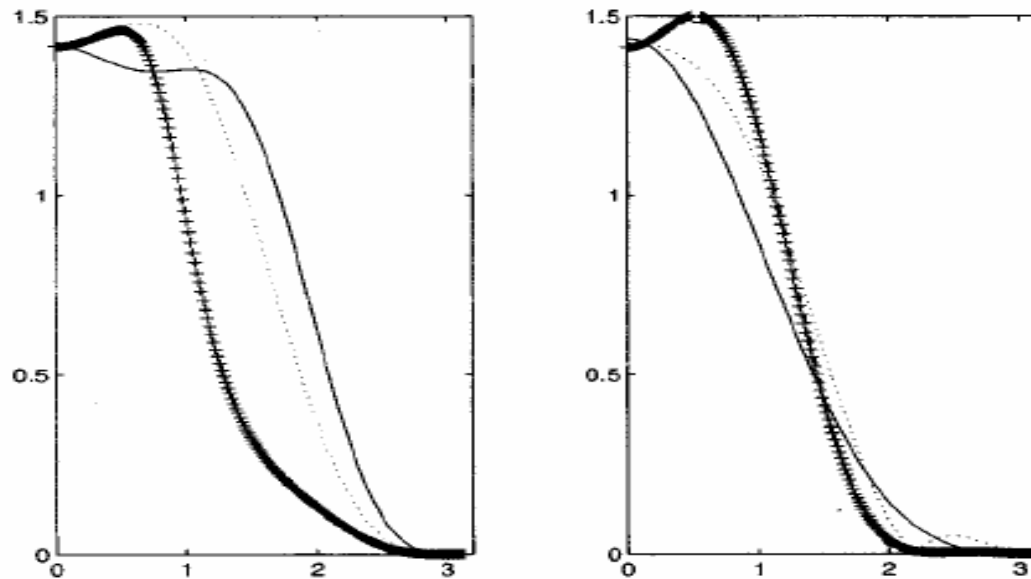


Fig. 3. Various filter responses in our design of  $L(\omega)$ , for Daubechies 9-7 filter bank and AR(1) input process with  $\rho = 0.95$ . On the left, the solid curve is  $H_0(\omega)$ , “...” is  $G_0(\omega)$ , and “+” is the optimal IIR filter given by (9). On the right, the solid, “...,” “-,” and “+” curves are our optimized FIR filters at lengths five, seven, nine, and 11, respectively. Note that the last two curves are almost overlapped.

## *Optimal Aliasing Reduction Filter Approach*

- Still not efficient as motion estimation in spatial domain
- Any ultimate solution ? → Shift invariant Overcomplete Wavelets



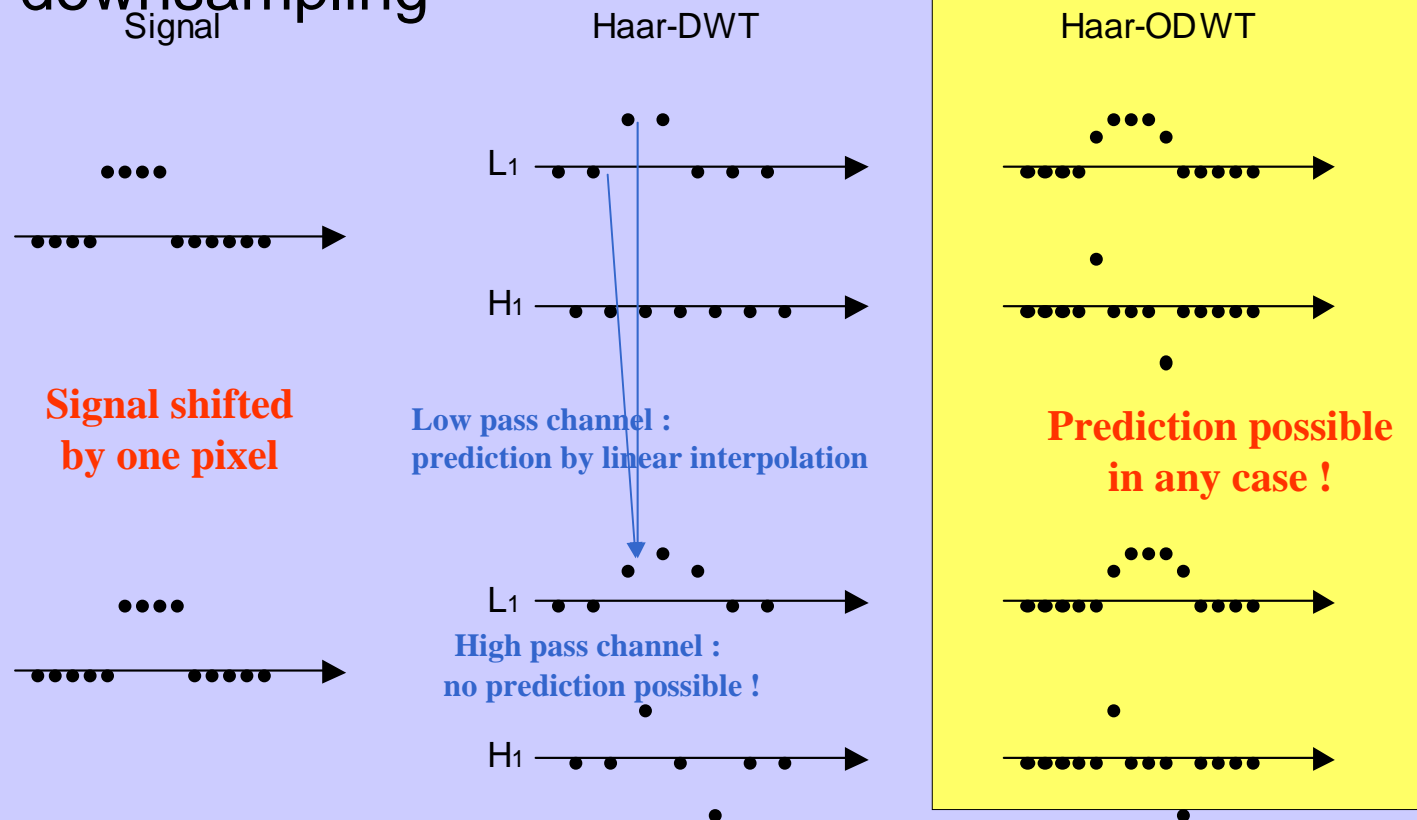
# *Frame Theory – Overcomplete Wavelets*

- Properties of redundant frame
  - Noise reduction
  - More sparse representation → matching pursuit
  - Redundant representation → multiple description coding
  - **Shift invariant property**
    - Improved motion estimation/compensation in wavelet domain
    - Only motion references need to be overcomplete
    - Texture coding is still in complete wavelet domain



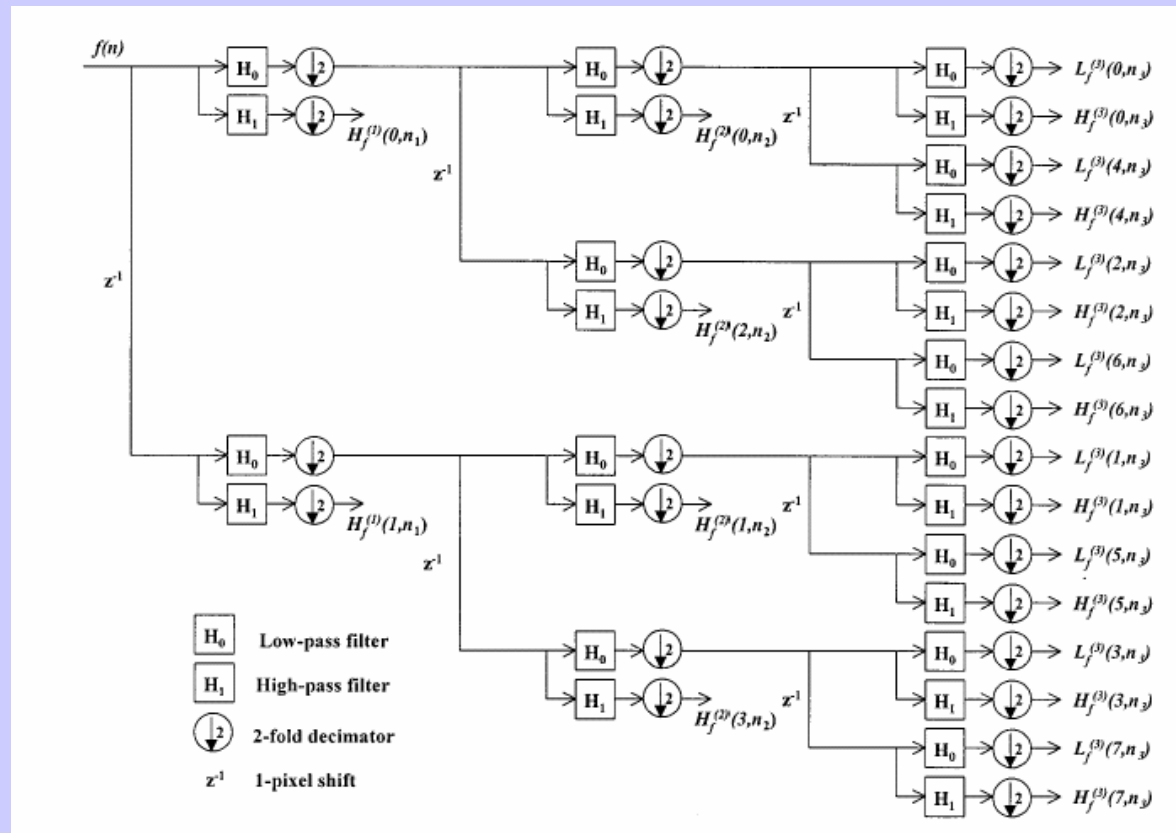
# Shift *Invariance* of Overcomplete Wavelets

- Overcomplete representation without downsampling



## Low-Band-Shift Method

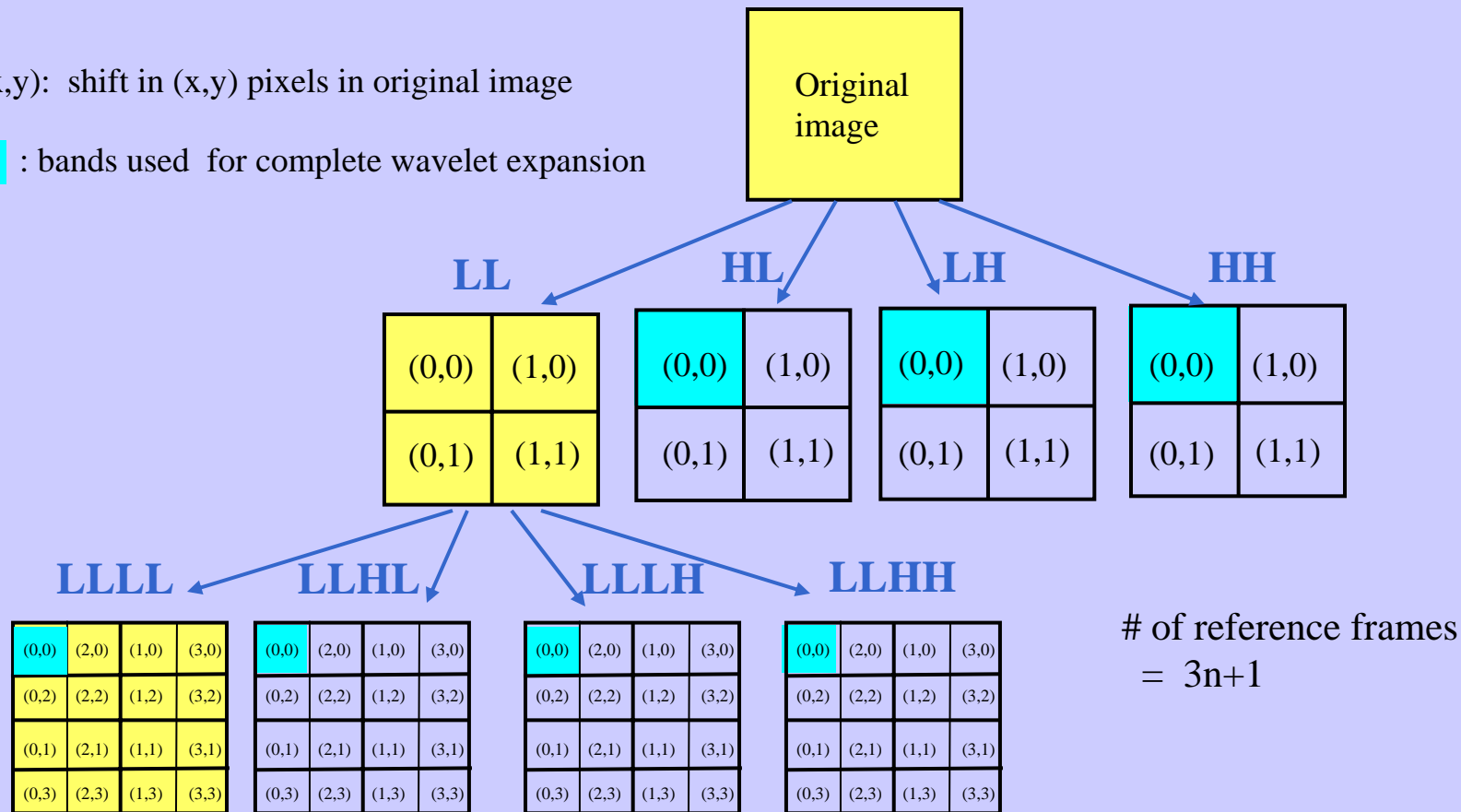
- Optimal way of generating overcomplete wavelet coefficients for every shift



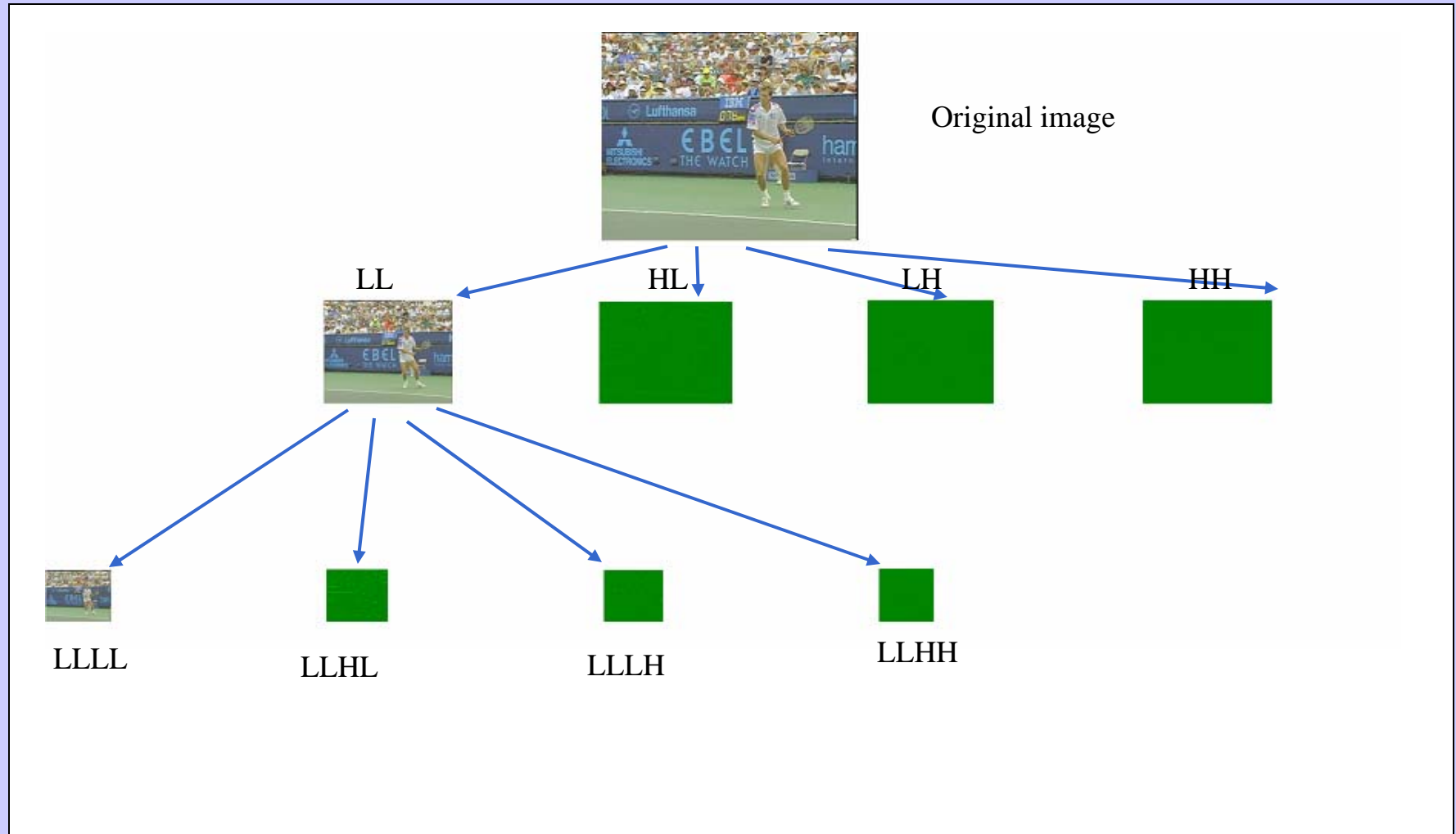
# Low Band Shift Method for 2-D

(x,y): shift in (x,y) pixels in original image

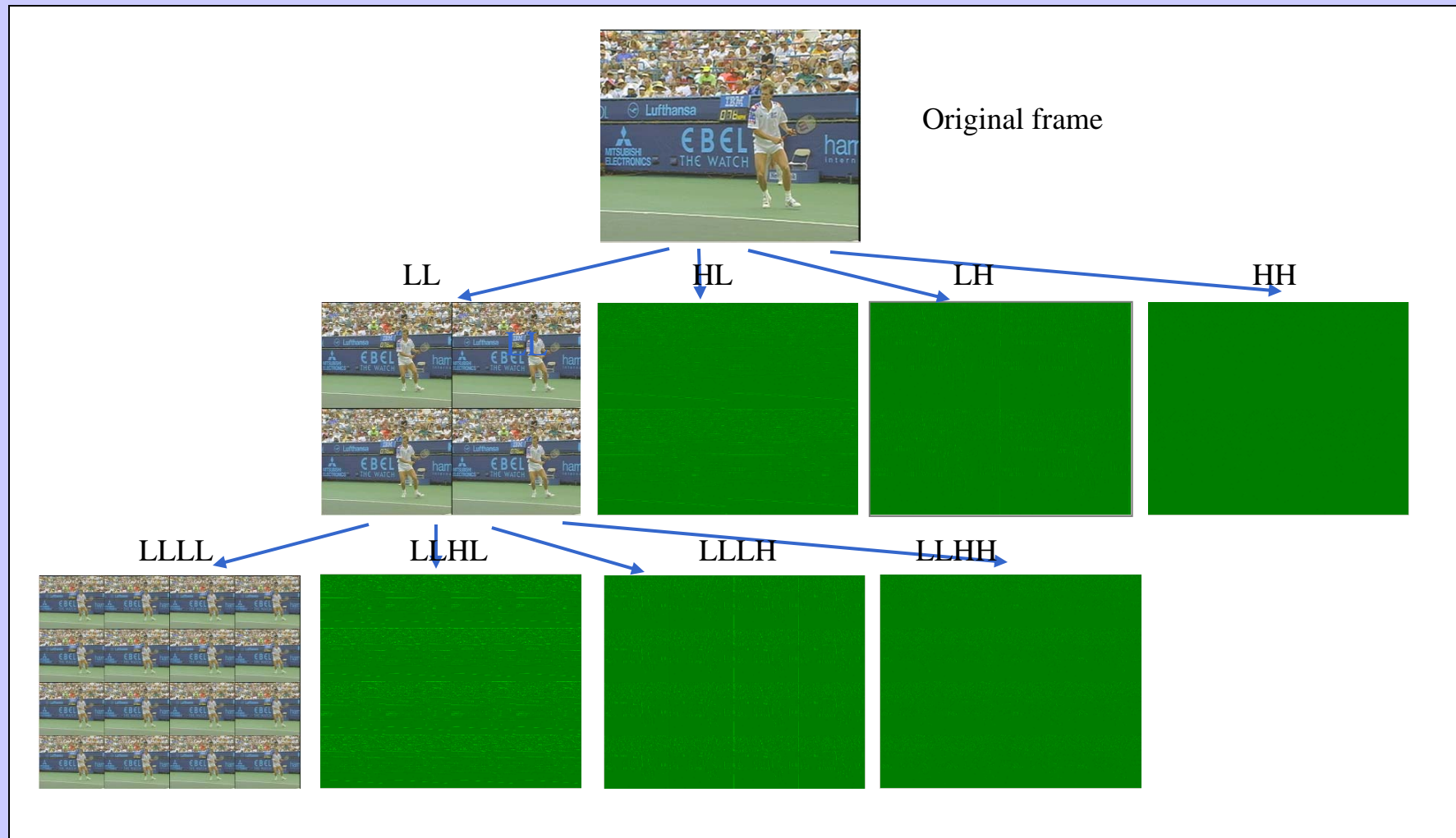
  : bands used for complete wavelet expansion



# Conventional Wavelet Transform

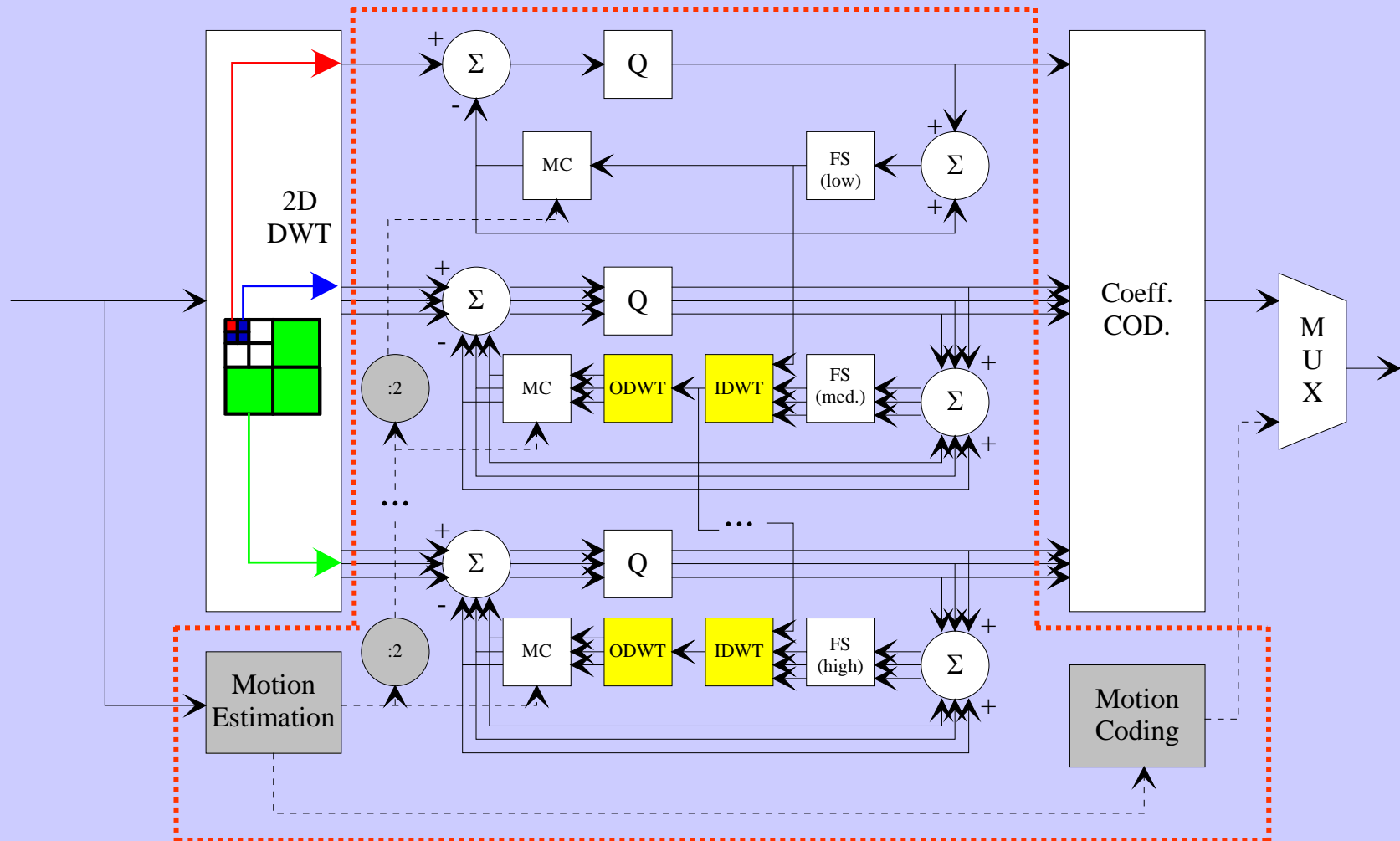


# Overcomplete Wavelet Transform by Low-Band Shift Method

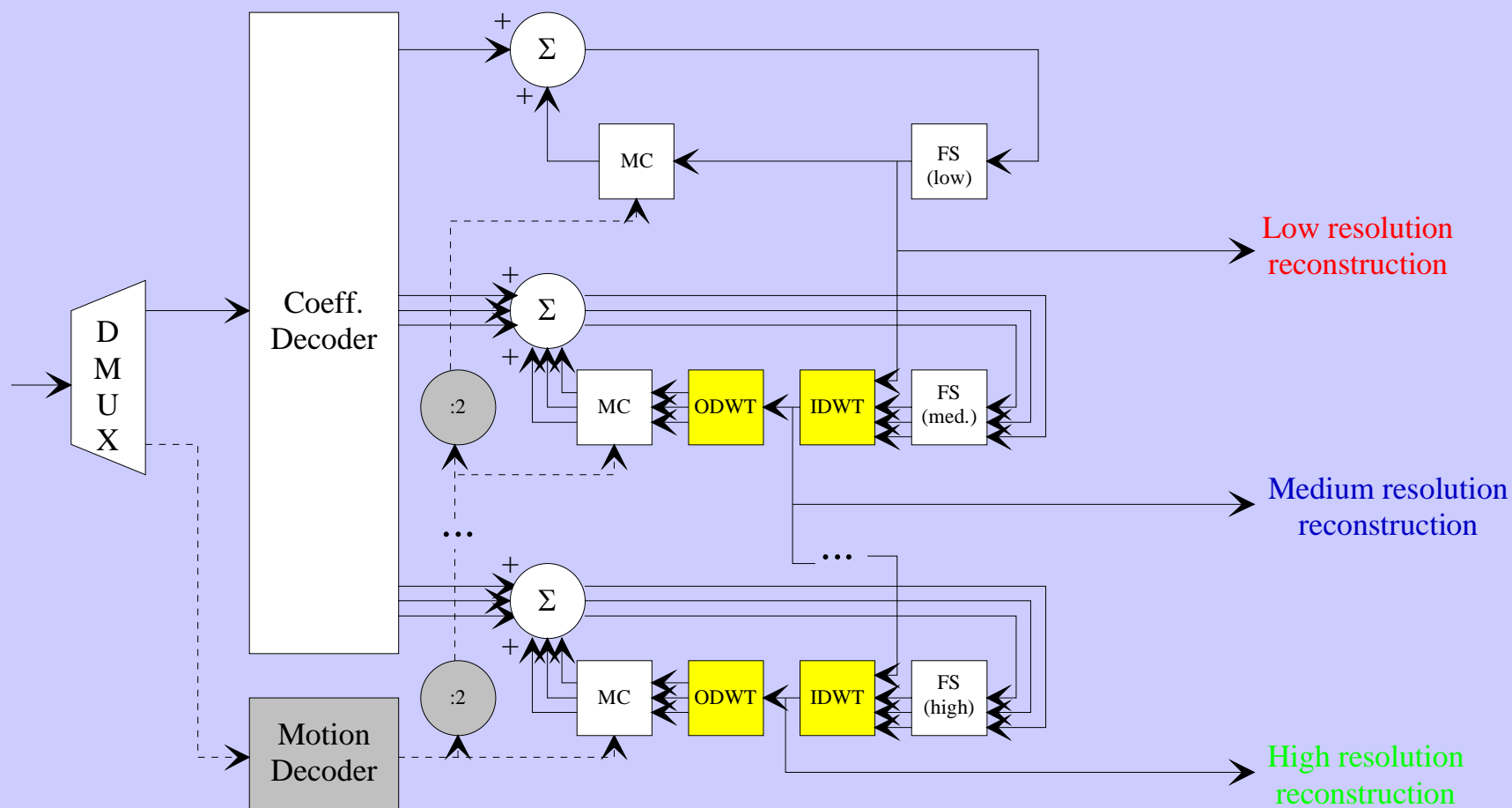




# Overcomplete Wavelet MC Coding - Coder



# Overcomplete Wavelet MC Coding - Decoder

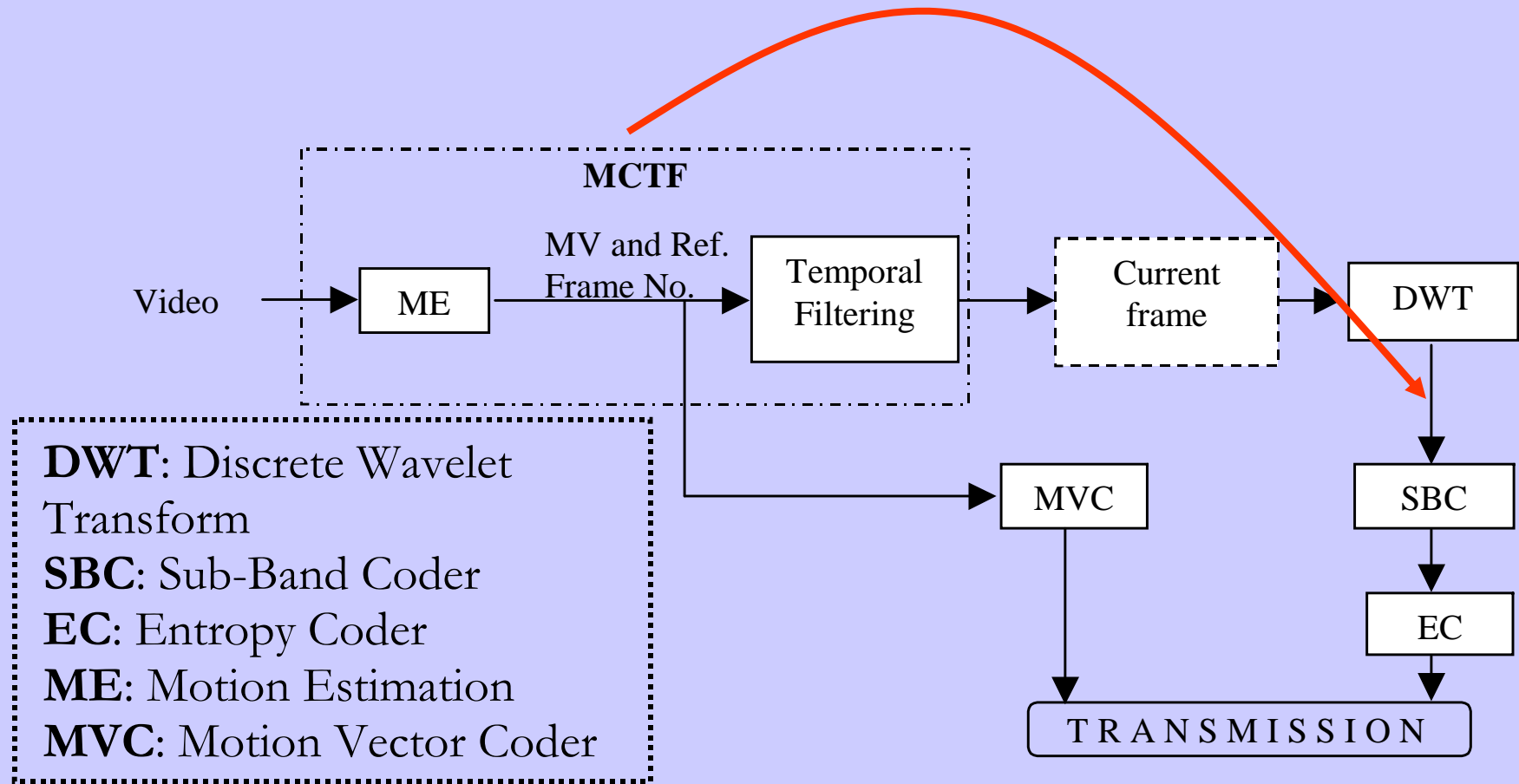


# Overcomplete Wavelet MC Coding

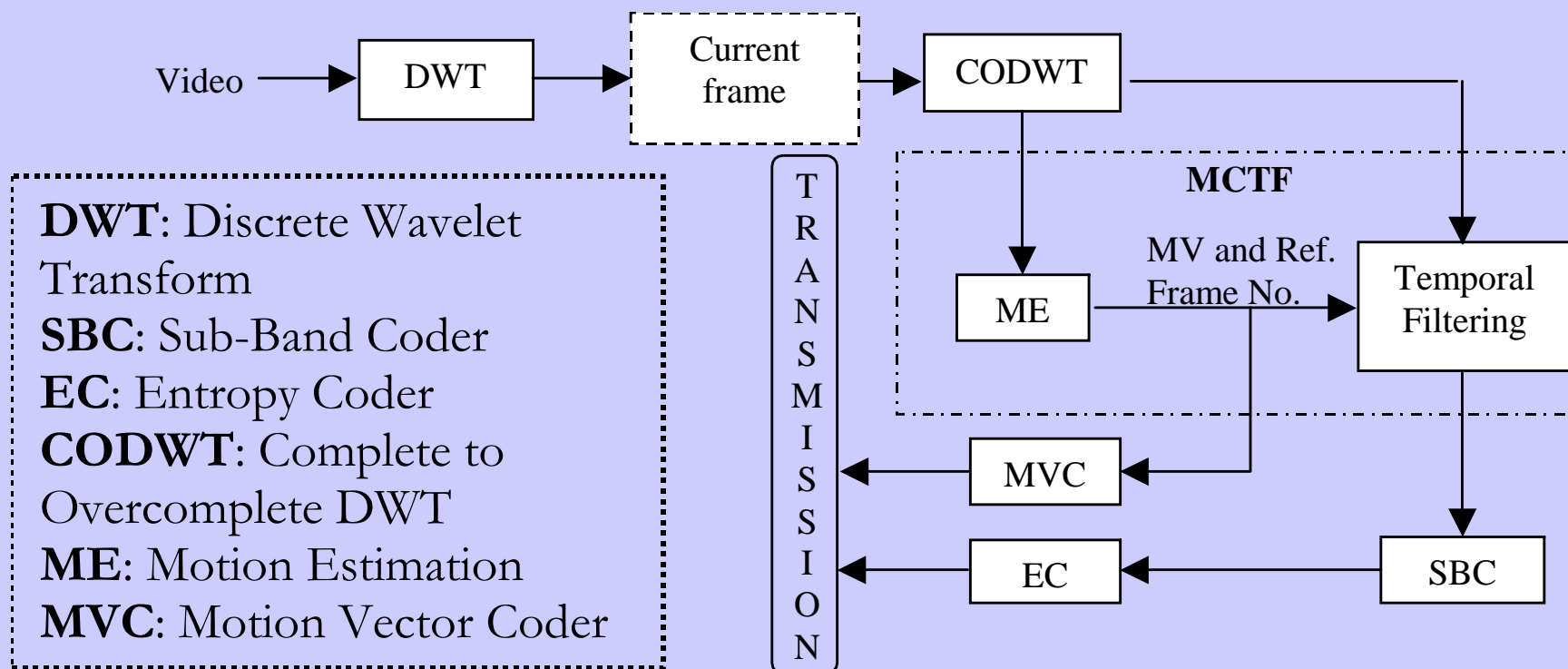
- **ODWT is Wavelet without subsampling**
  - More samples than original, like Pyramid representation
- **Allows Wavelet domain MC for high frequency components**
  - signal does not bear frequency-inversion alias component
- **Still only necessary to encode critically sampled coefficients**
  - Overcomplete transform coefficients can be generated locally within the decoder
- **Still does not resolve the drift in SNR scalability**
  - may be solved by multiple loops in each wavelet band
- **Solution: In-Band MCTF (IBMCTF)**



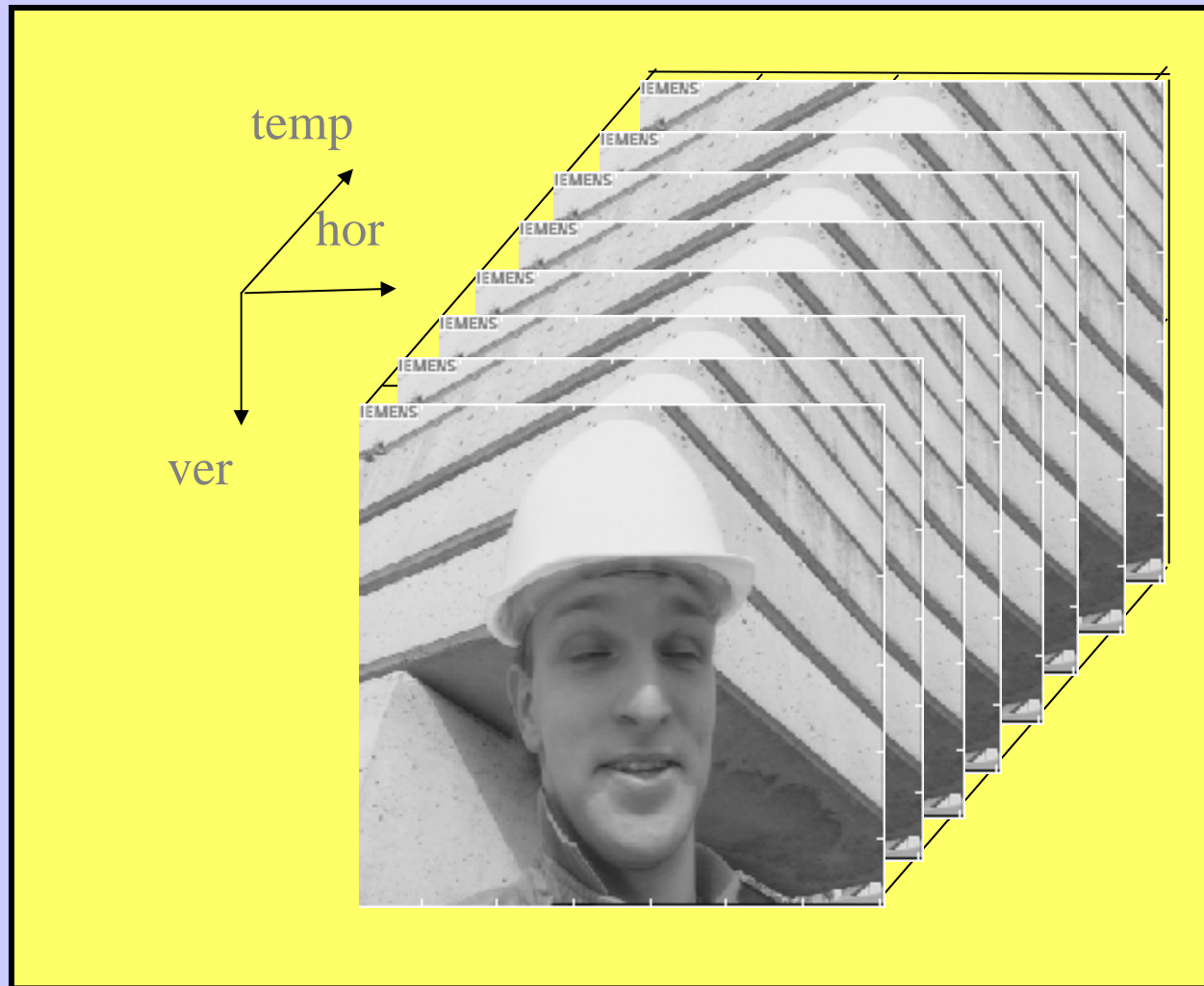
# *Spatial-Domain MCTF (SDMCTF)*



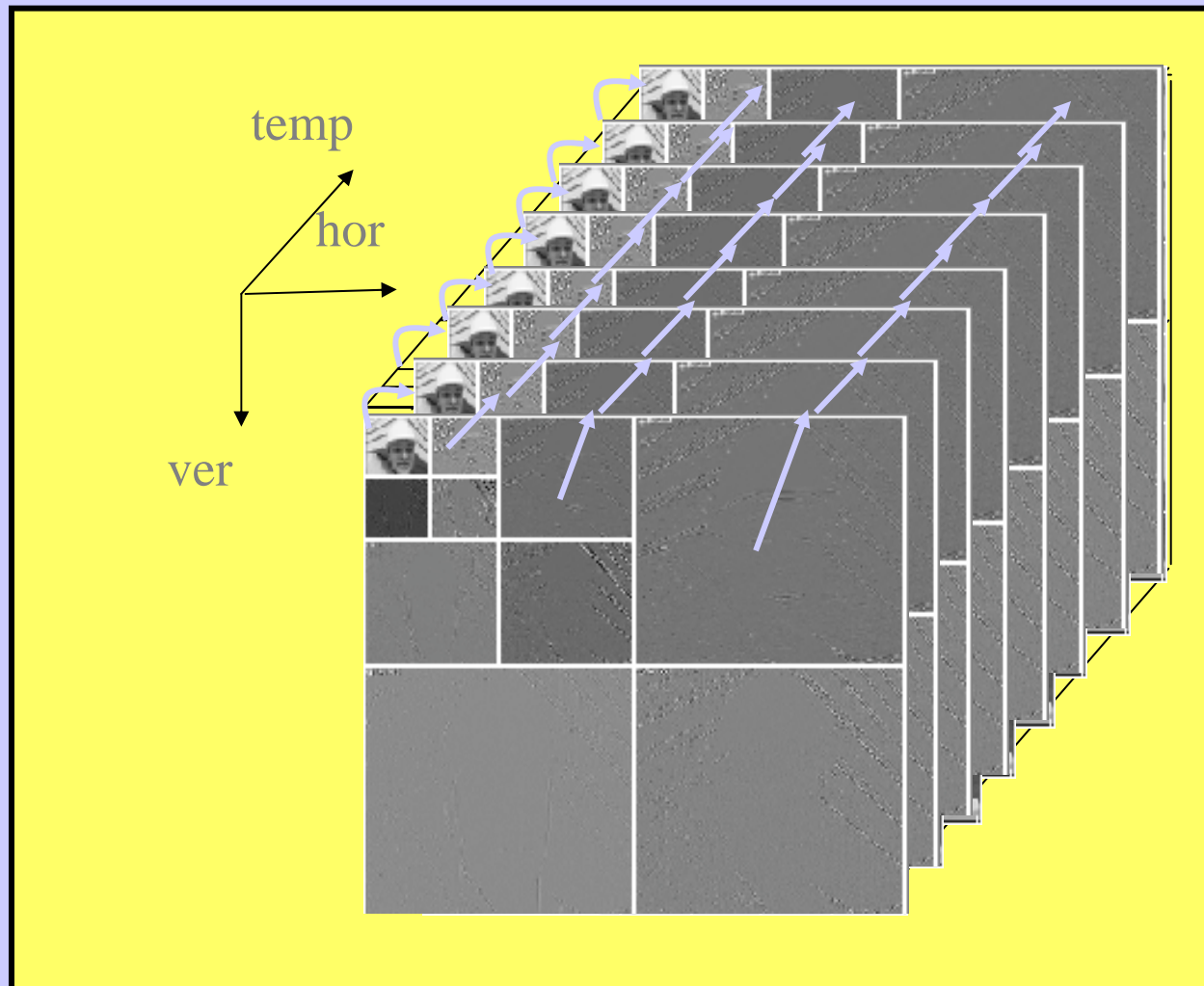
## *In-band MCTF (IBMCTF)*



# *IBMCTF: concept*

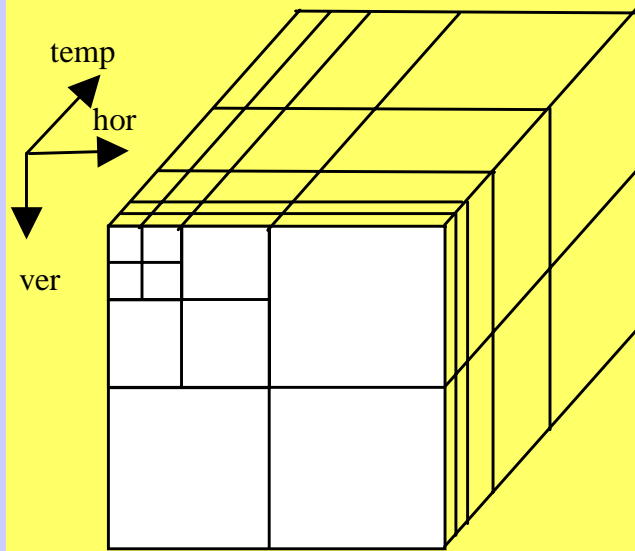


## *IBMCTF Wavelet Video*

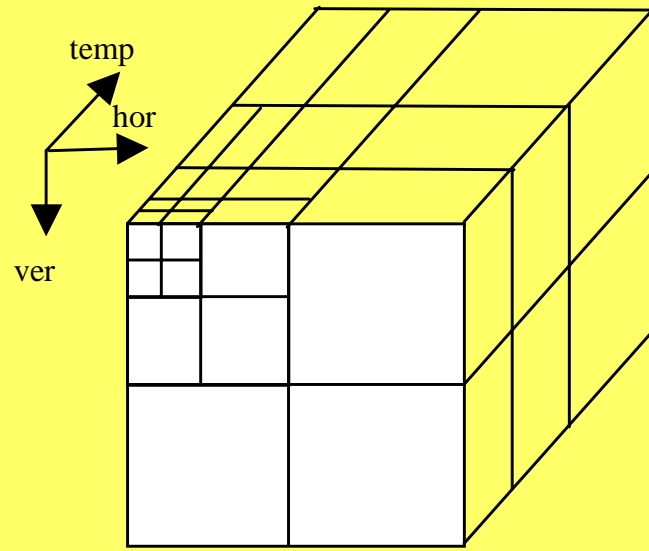


For efficient IBMCTF, ME should be performed in overcomplete wavelet domain

## 3-D decomposition structure



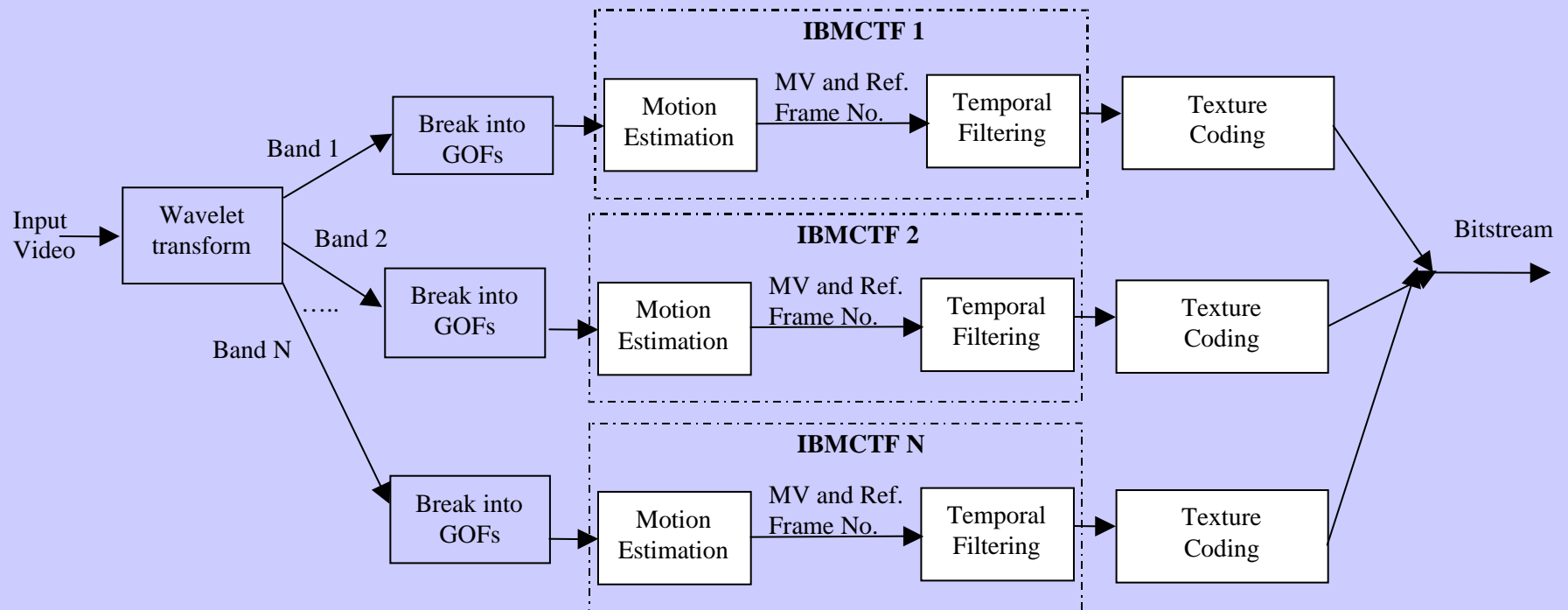
SD- MCTF



Inband MCTF



# Block diagram of IBMCTF coder

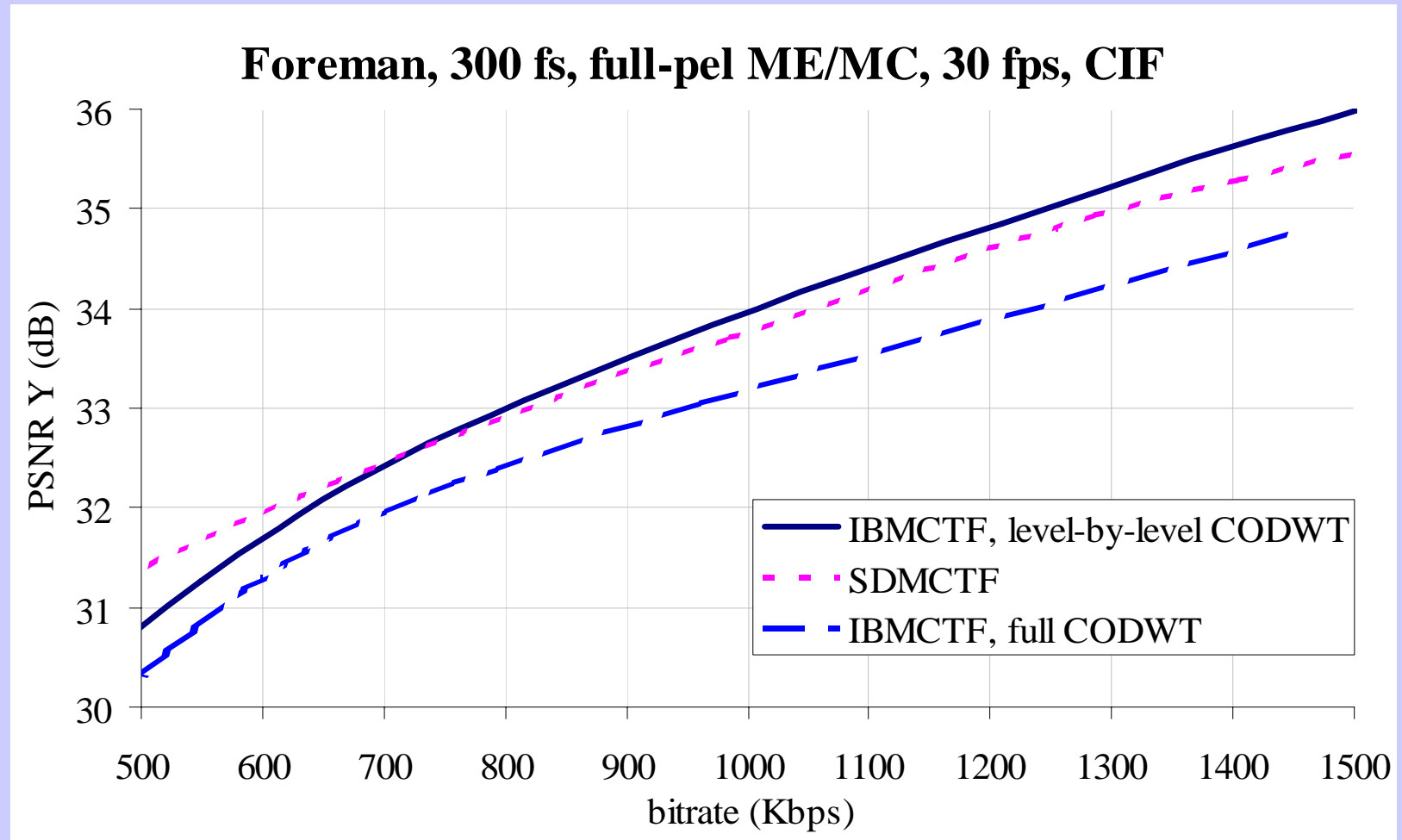


## *IBMCTF coding*

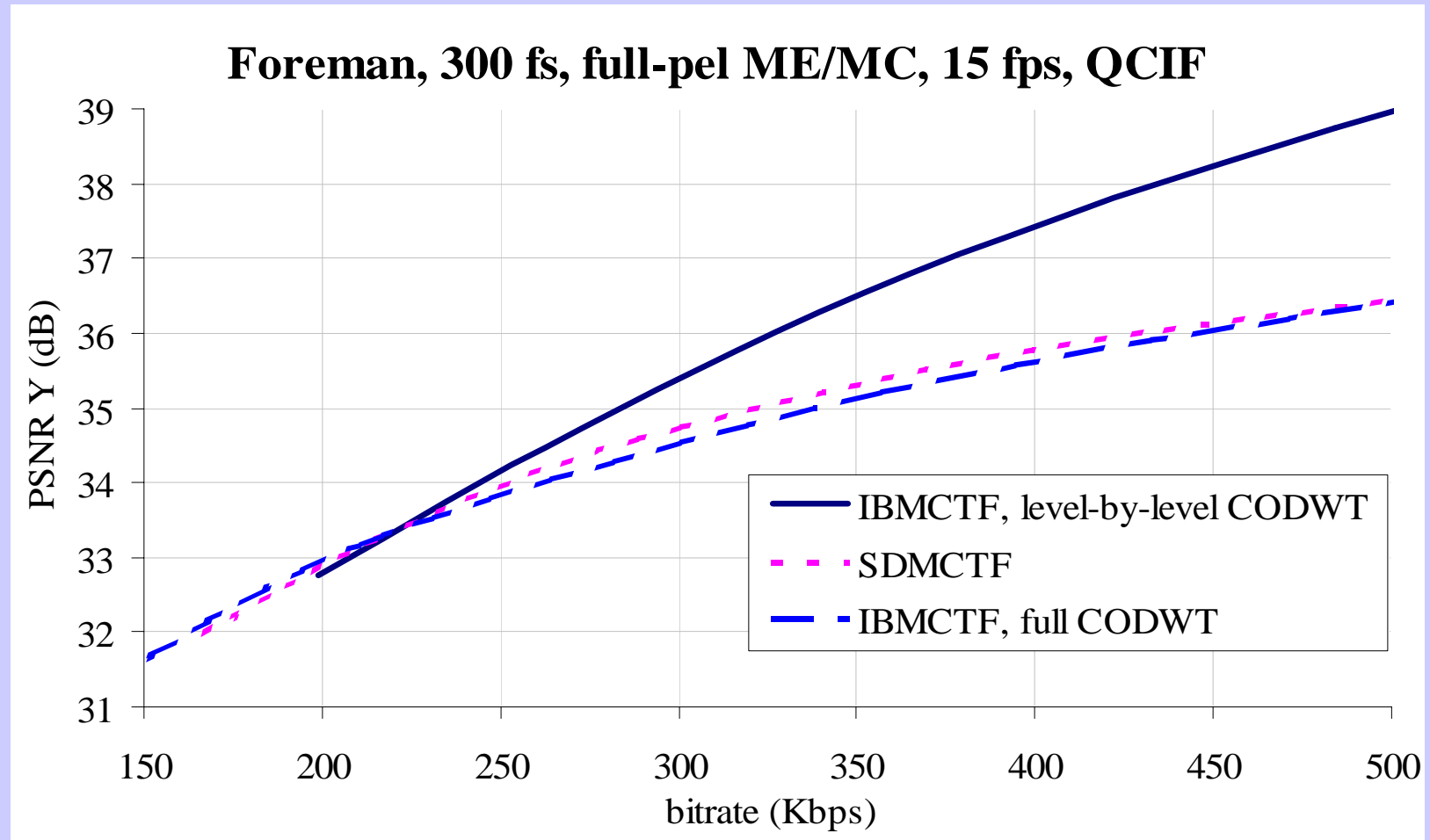
- Allows Wavelet domain MC using shift-invariant overcomplete waveltes by Low-Band Shift method
- Still only necessary to encode critically sampled coefficients
- Advantages in spatial scalability
- Resolve the drift in SNR scalability
- **Adaptive processing for each subband**
  - Different ME accuracy, interpolation filter, temporal filter taps, etc.
- **Very general framework which can be combined with other existing techniques (intra mode, UMCTF, etc)**



# Results

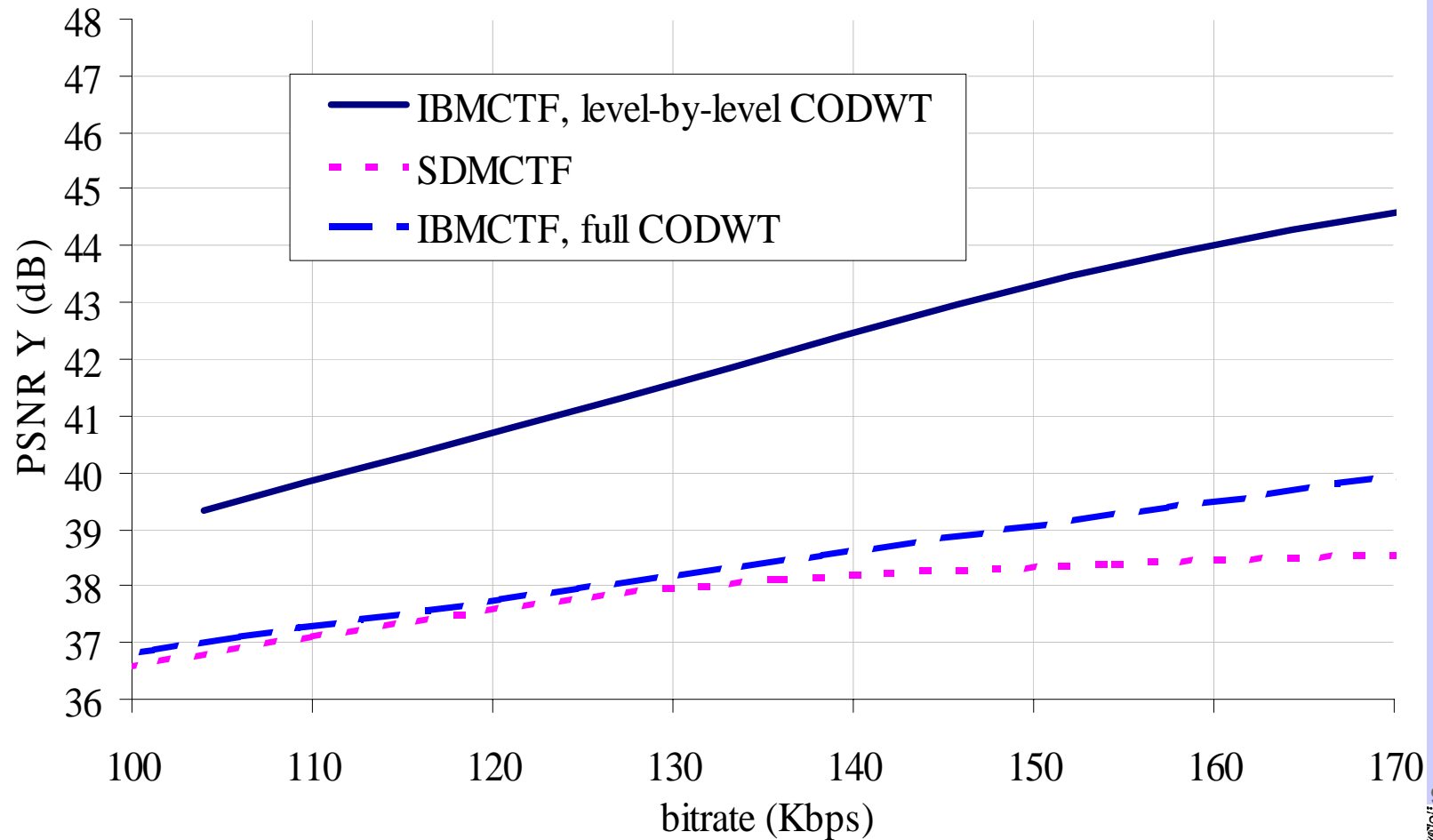


# Results



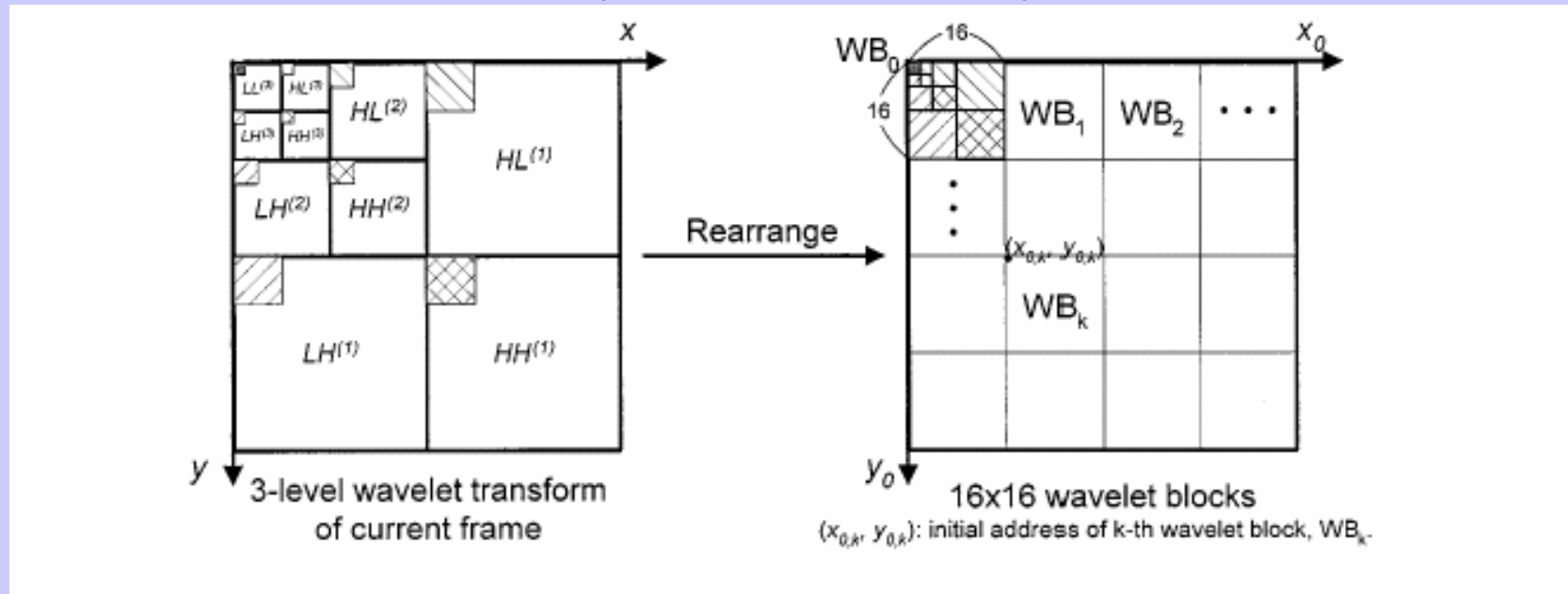
# Results

**Foreman, 300 fs, full-pel ME/MC, 7.5 fps, Q-QCIF**



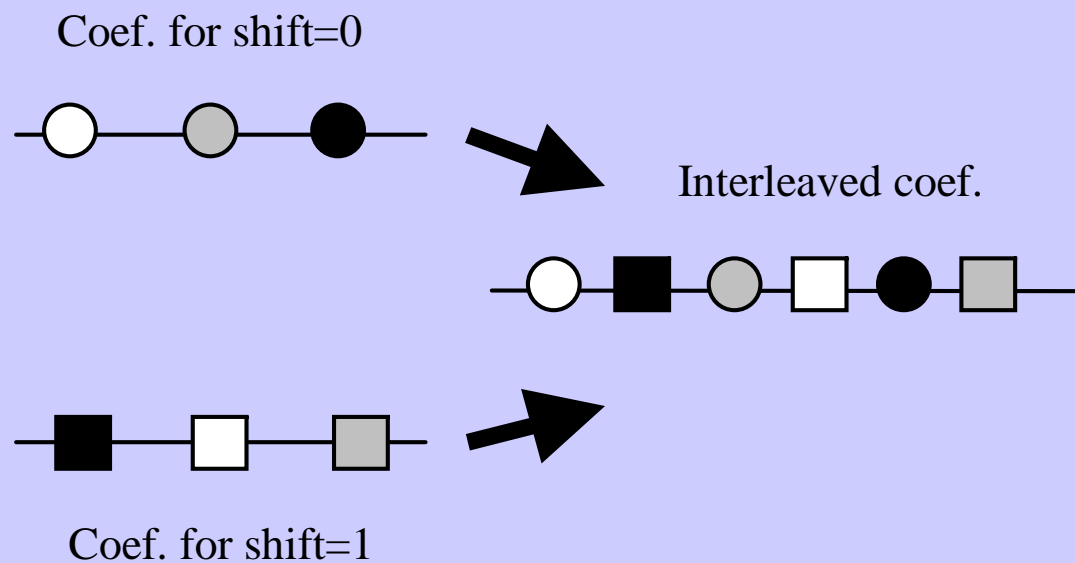
# Generation of Wavelet Blocks

- Wavelet block provides a direct association between the wavelet coefficients and what they represent spatially

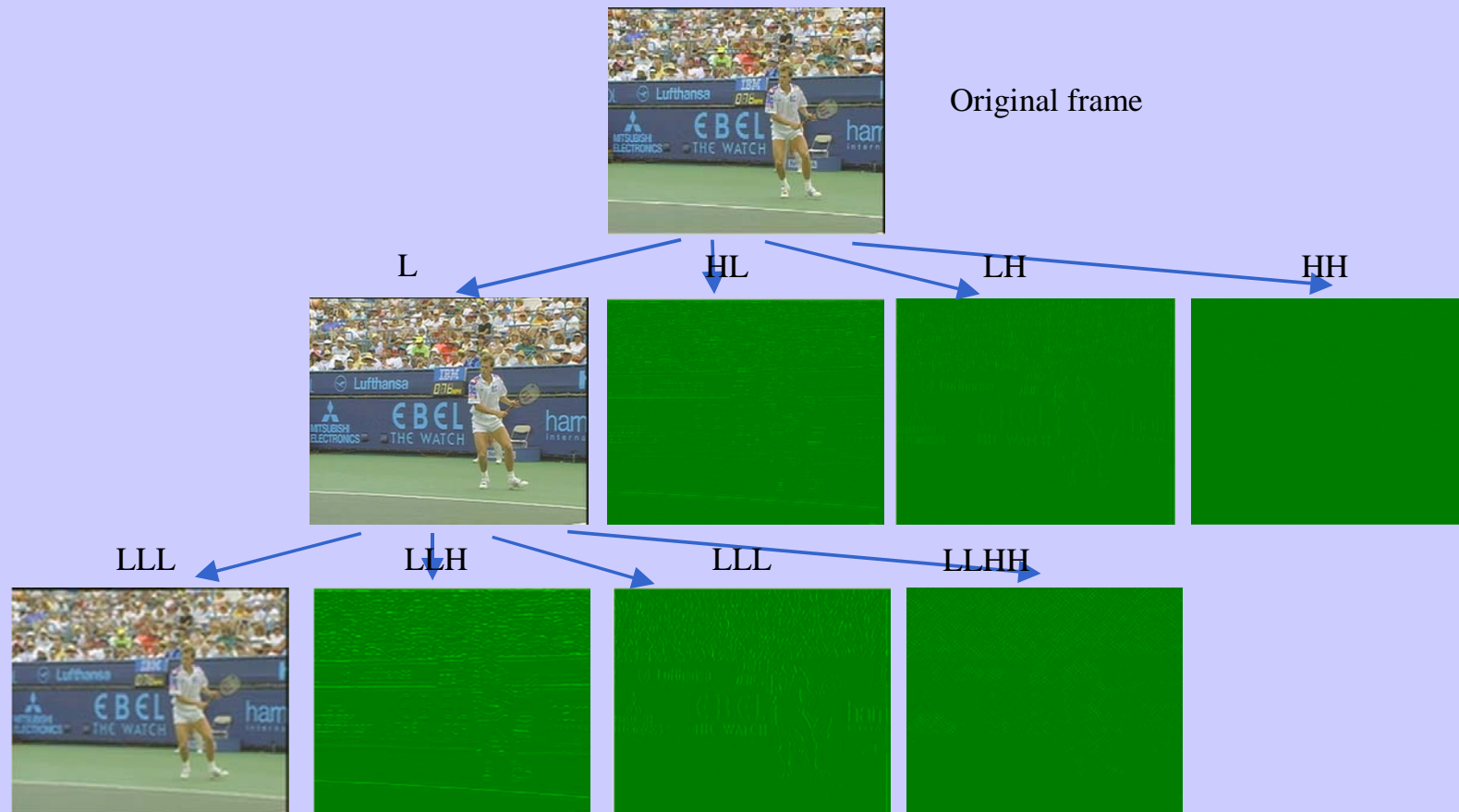


- No motion vector overhead because the number of the motion vector to be coded is the same as that of SDMCTF
- Perfectly aligned with tree structure entropy coder
  - Entropy based motion estimation criterion !!

# *Proposed interleaving of overcomplete wavelet coefficients*



# Overcomplete Wavelet Transform with Interleaving





## *Advantages of Interleaving*

- Interleaving algorithm enables *optimal* sub-pixel accuracy motion estimation and compensation in IBMCTF
- By interleaving, any existing ME module (HVSBM, FSBM, Intra Mode, etc) with any fractional pel accuracy can be used
- Can be easily used for MCTF framework with any fractional pel accuracy using **lifting structure**



## 3-D Lifting Structure for IBMCTF

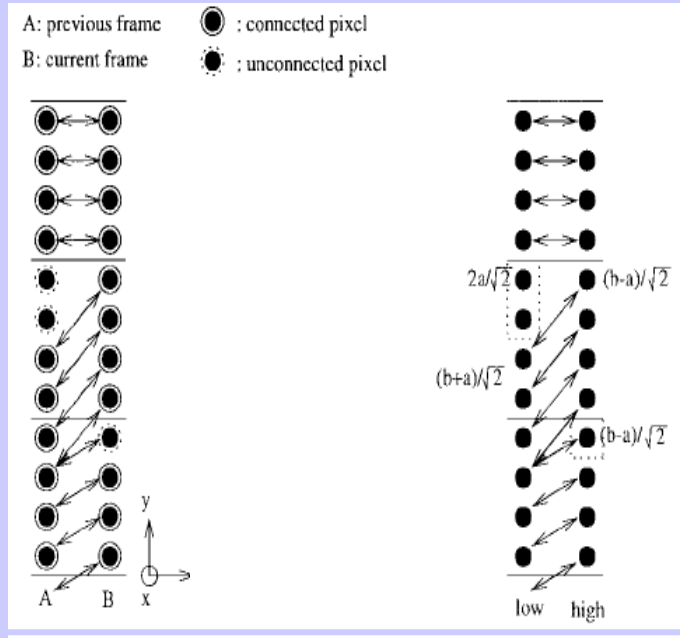
Direct extension of SD-MCTF lifting to IBMCTF:

$$H_j^i[m, n] = \left( B_j^i[m, n] - \tilde{A}_j^i[m - d_j^i(m), n - d_j^i(n)] \right) / \sqrt{2}, i = 0, \dots, 3$$

Interpolation operation for frame  $A_j^i$  is not optimal  
(no cross-phase dependencies incorporated)



# 3-D Lifting Structure for IBMCTF



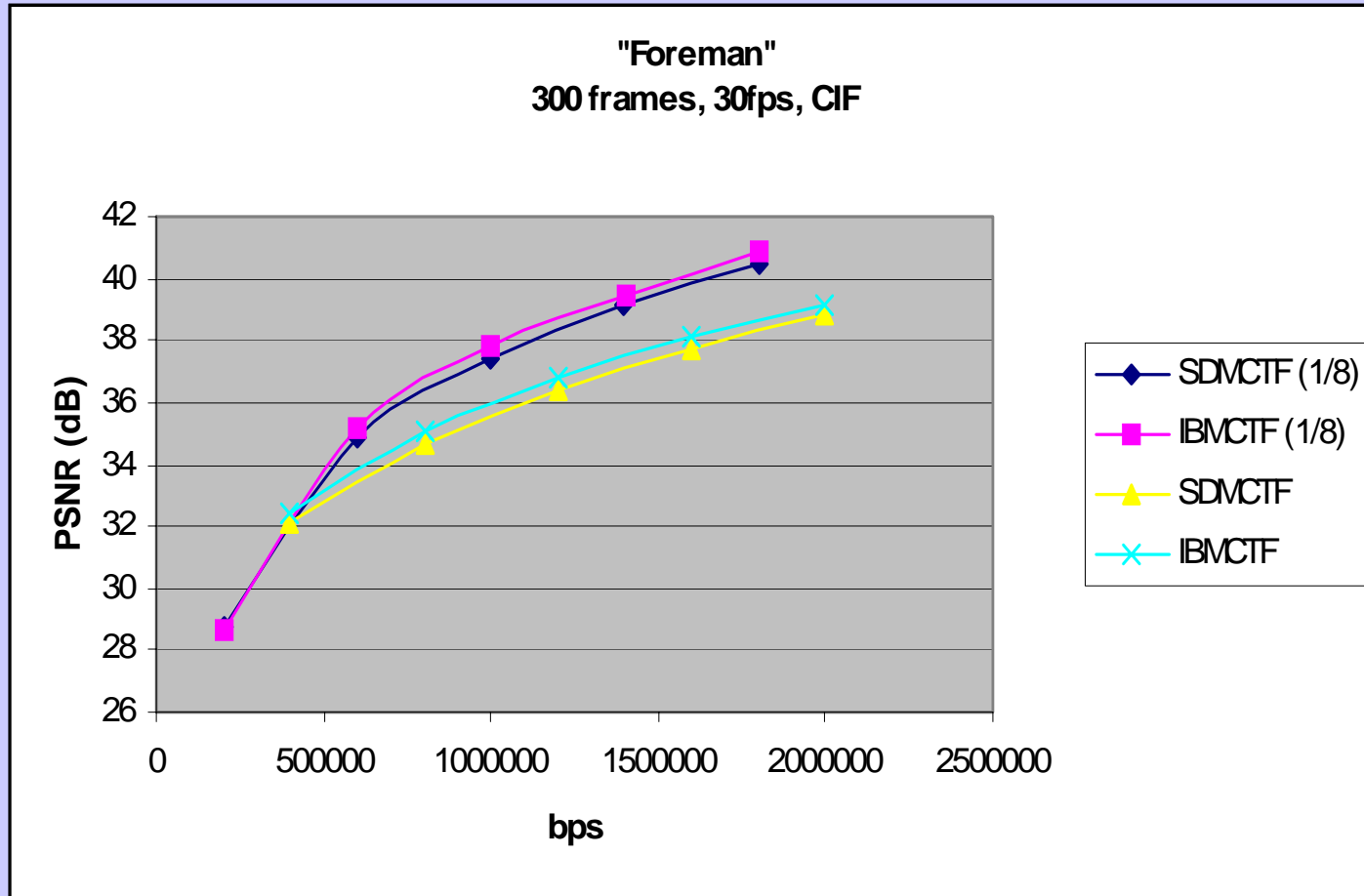
$B_2^0$	$B_2^2$	$B_1^2$
$B_2^1$	$B_2^3$	
$B_1^1$		$B_1^3$

$$H_j^i[m, n] = \left( B_j^i[m, n] - LBS - \tilde{A}_j^i[2^j m - d_m, 2^j n - d_n] \right) / \sqrt{2}, \quad i = 0, \dots, 3$$

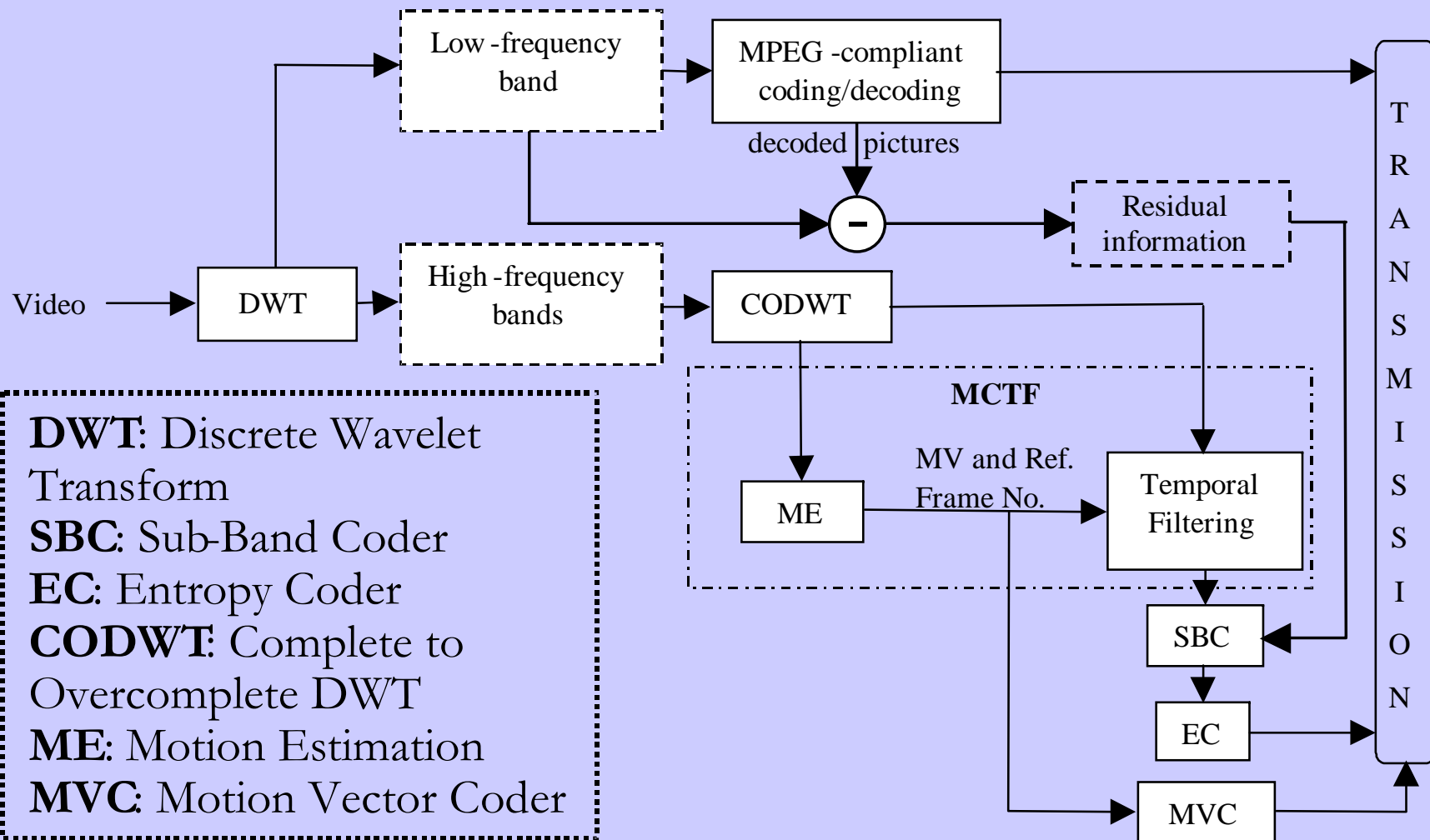
$$L_j^i[m - \bar{d}_j^i(m), n - \bar{d}_j^i(n)] = LBS - \tilde{H}_j^i[2^j m - \bar{d}_m + d_m, n - \bar{d}_n + d_n]$$

$$+ \sqrt{2} A_j^i[m - \bar{d}_j^i(m), n - \bar{d}_j^i(n)] \quad i = 0, \dots, 3$$

# Results



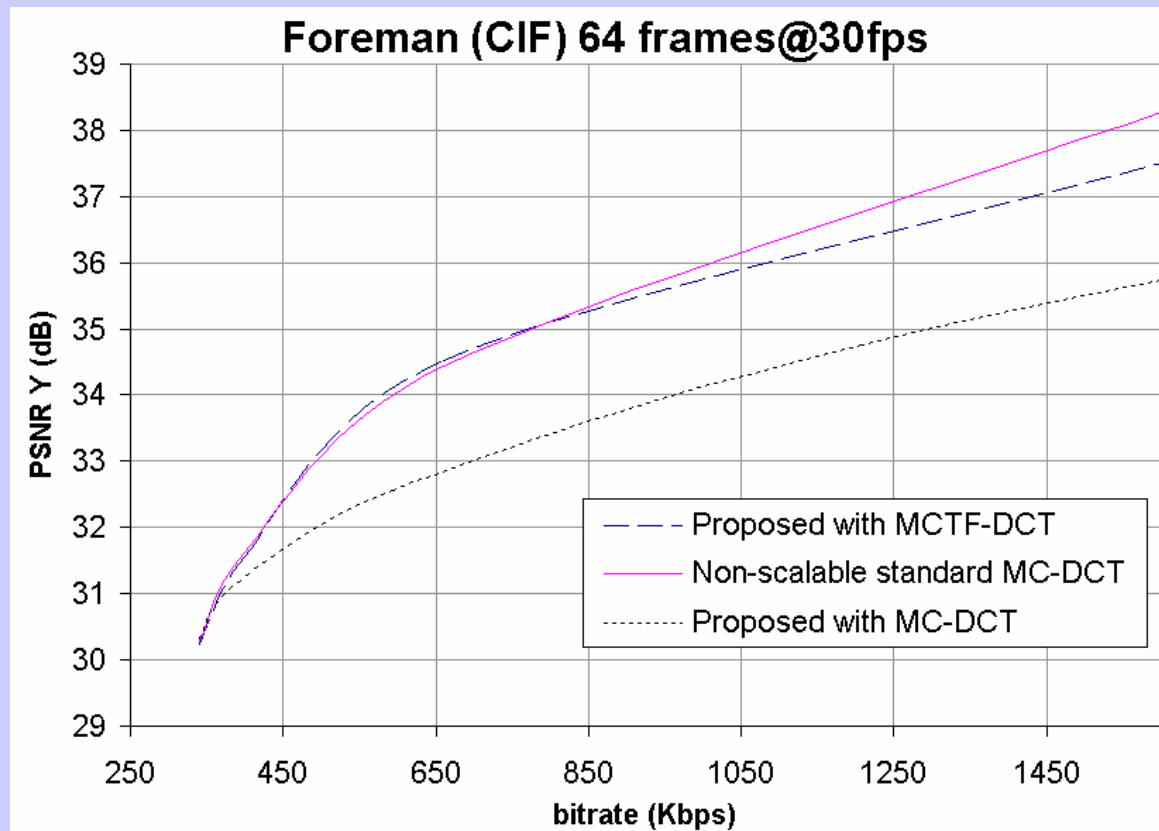
# Overcomplete wavelet coding using standard-compliant DCT base-layers



Proposed by Andreopoulos, van der Schaar, et al – ICIP 2003



# Results



# *Current Status in MPEG Standardization*



# ***MPEG's Scalable Coding History***

- **Development of scalable video coding** solutions has a **long history in MPEG**, starting from MPEG-2
  - Spatial, temporal and SNR scalability with at most 3 levels
  - MPEG-4 Fine granularity scalability
- So far, all standardized solutions have shown **deficiency in coding performance which is** mainly due to **recursive MC structure**
  - Drift occurs when not all information is available
  - Drift-free structures are less coding efficient





# ***MPEG's Interframe Wavelet Coding Exploration***

- New embedded wavelet solutions were proposed In the Digital Cinema Call for Proposals and in the Call for Proposals on improved coding efficiency (both due July 2001)
- At Pattaya meeting (Dec. 2001), MPEG started an Adhoc Group to explore Interframe Wavelet Coding
- Different methods were investigated
  - MC prediction with intraframe (2D) wavelet
  - In-band MC prediction based on overcomplete 2D wavelet decomposition
  - 3D (spatio/temporal) wavelet coding based on MCTF
- 3D (t+2D, 2D+t) showed most promising, providing excellent coding efficiency while being fully scalable in temporal, spatial and quality resolution
- Experimental software was used



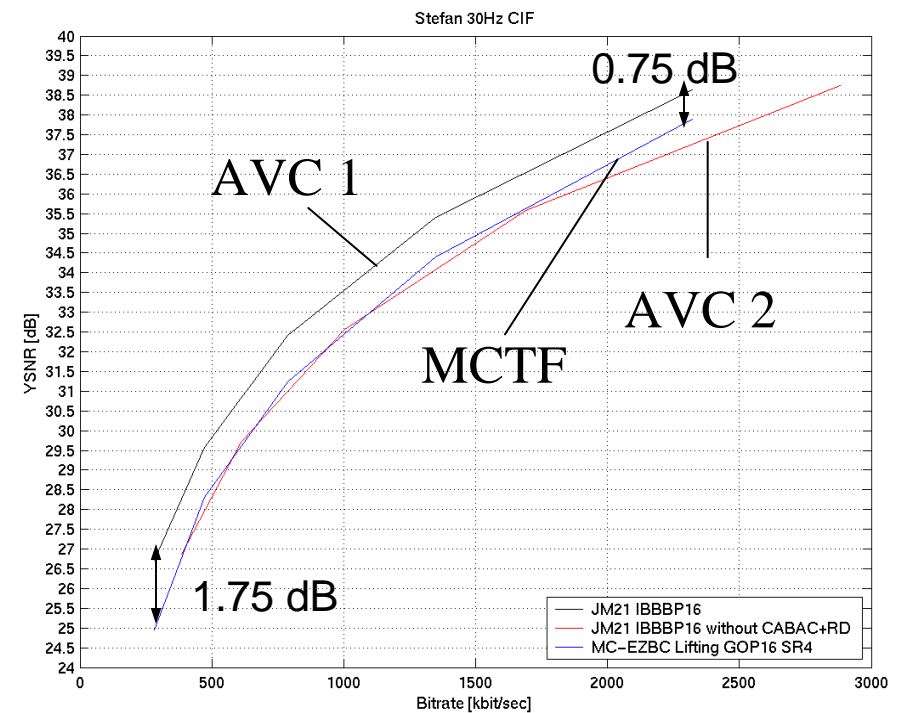
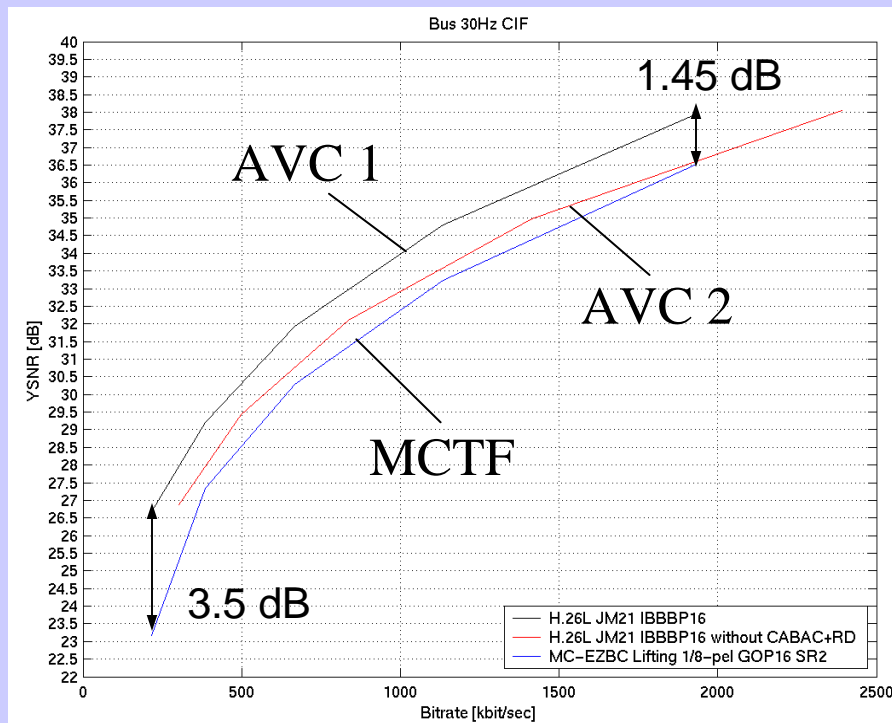
## ***MPEG's Interframe Wavelet Coding Exploration***

- The Interframe Wavelet exploration was successfully completed in October 2002
- 9 Call for Evidence on Scalable Coding Advances  
- July 2003
- 24 Call for Proposal Responses – March 2004



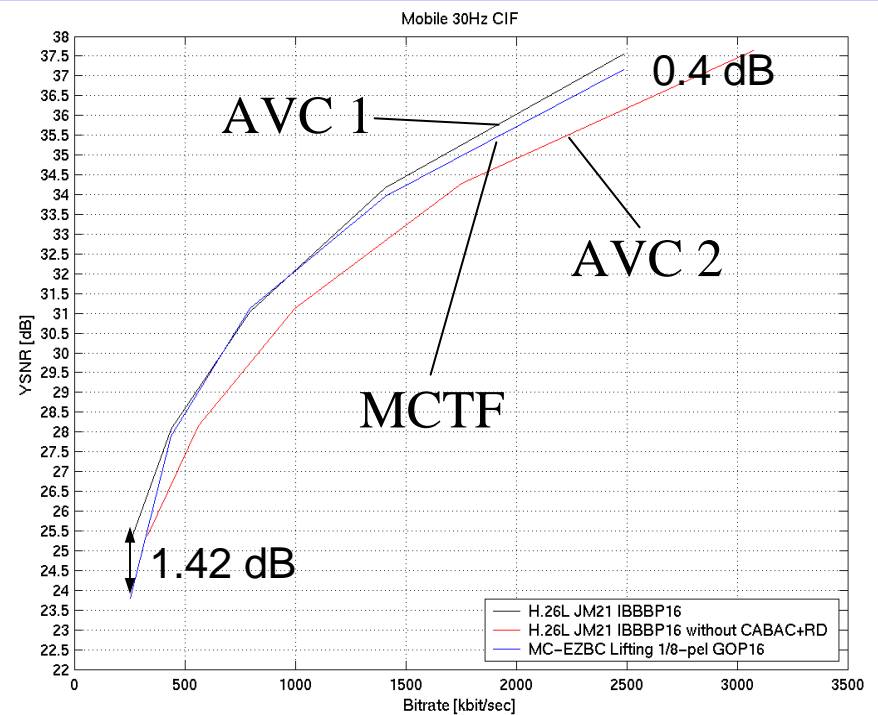
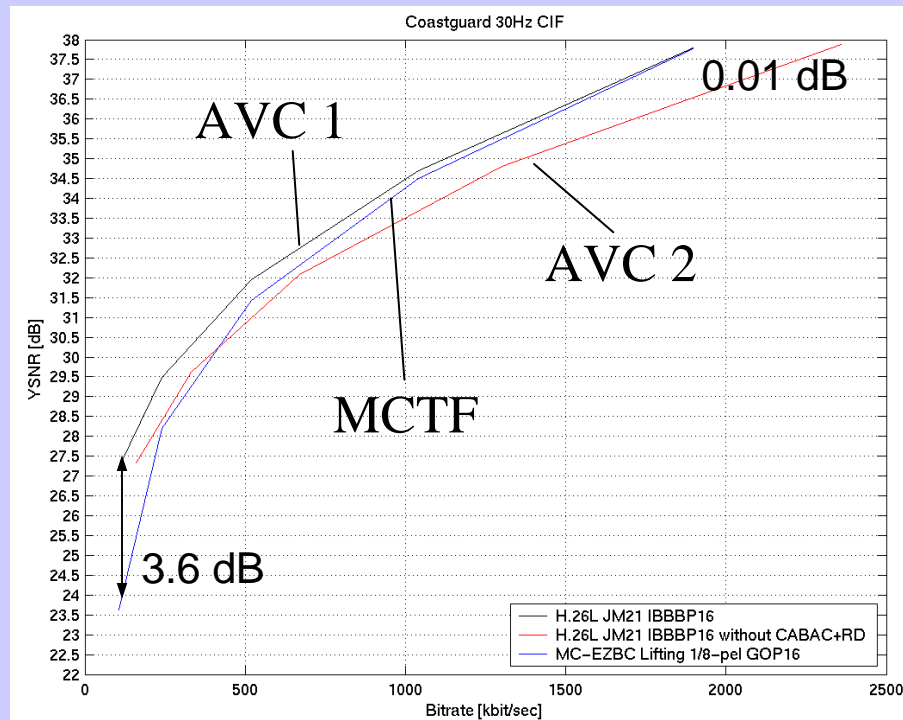
# SNR Results from MPEG's Intraframe Wavelet Coding Exploration

- Some less good results (out of 10 sequences)



# SNR Results from MPEG's Intraframe Wavelet Coding Exploration

- Some more good results (out of 10 sequences)



# *Acknowledgements*

- Jens Ohm
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- Thomas Rusert

