

# Orthogonal Tensors

i)  $Q \in \text{Orth}$ , i.e.  $QQ^T = I$

ii)  $Q_{\underline{u}} Q_{\underline{v}} = \underline{u} \cdot \underline{v} \quad \forall \underline{u}, \underline{v} \in V$

iii)  $\|Q_{\underline{u}}\| = \|\underline{u}\| \quad \forall \underline{u} \in V$

iv)  $\|Q_{\underline{u}} - Q_{\underline{v}}\| = \|\underline{u} - \underline{v}\|, \quad \forall \underline{u}, \underline{v} \in V$

Assum  $Q_{\underline{u}} \cdot Q_{\underline{v}} = \underline{u} \cdot \underline{v} \quad \forall \underline{u}, \underline{v} \in V$

$\Rightarrow \underline{u} \cdot Q^T Q_{\underline{v}} = \underline{u} \cdot \underline{v}$

$\underline{u} (Q^T Q_{\underline{v}} - \underline{v}) = 0$

$\Rightarrow Q^T Q_{\underline{v}} - \underline{v} = 0 \quad \forall \underline{v} \in V$

Given a unit vector  $\underline{n}$   
and an angle of rotation - can  
we construct a  $Q \in \text{Orth}$ ? at going backwards

## Cross Product:

$(\underline{u} \times \underline{v})_i = \epsilon_{ijk} u_j v_k$

$\hookrightarrow \epsilon_{123} u_2 v_3 + \epsilon_{132} u_3 v_2$

$= u_2 v_3 - u_3 v_2$

1)  $\underline{v} \times \underline{u} = -\underline{u} \times \underline{v}$  (Anti-Commutative)

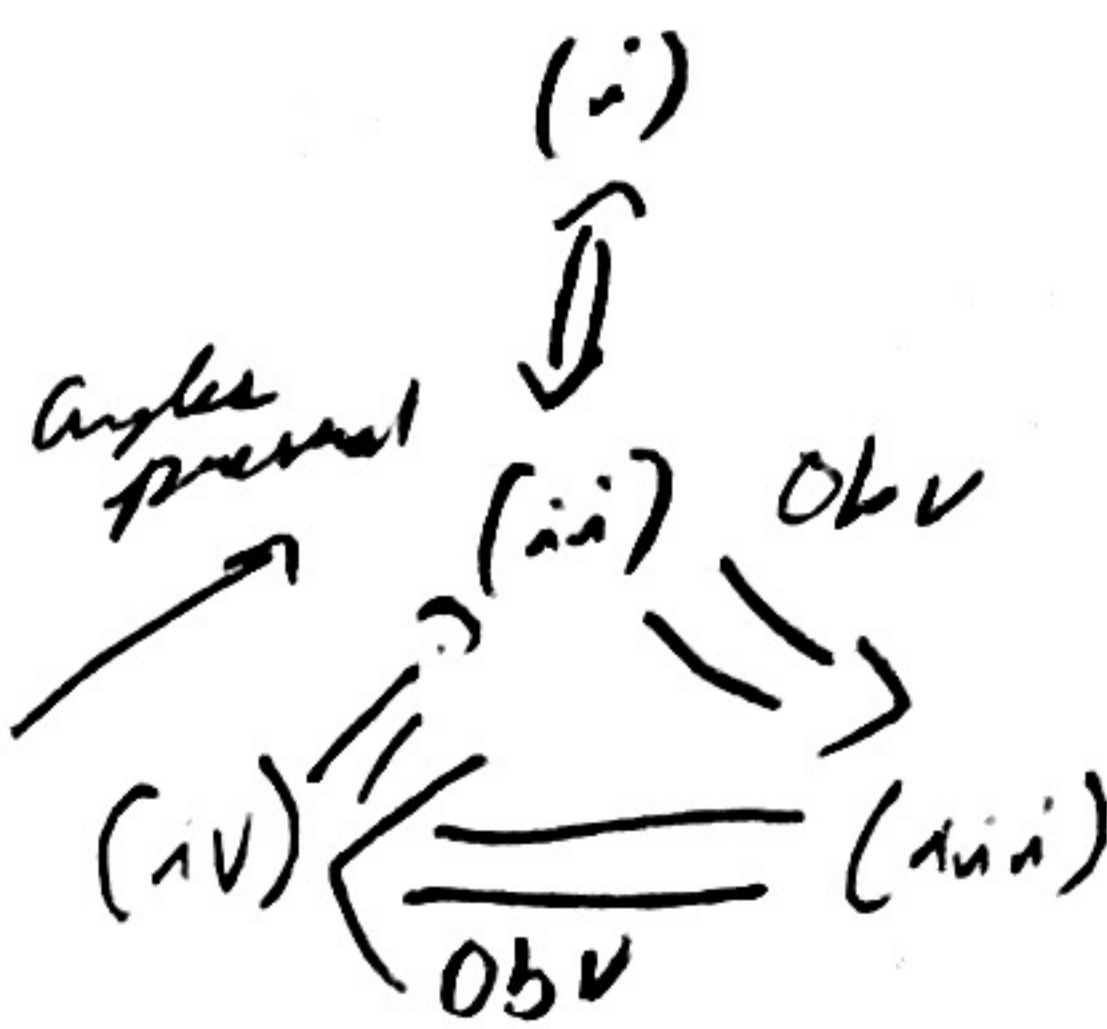
2)  $\underline{u} \times (\underline{v} + \underline{w}) = \underline{u} \times \underline{v} + \underline{u} \times \underline{w}$  (Distributive over addition)

3)  $(\lambda \underline{u}) \times \underline{v} = \lambda (\underline{u} \times \underline{v})$

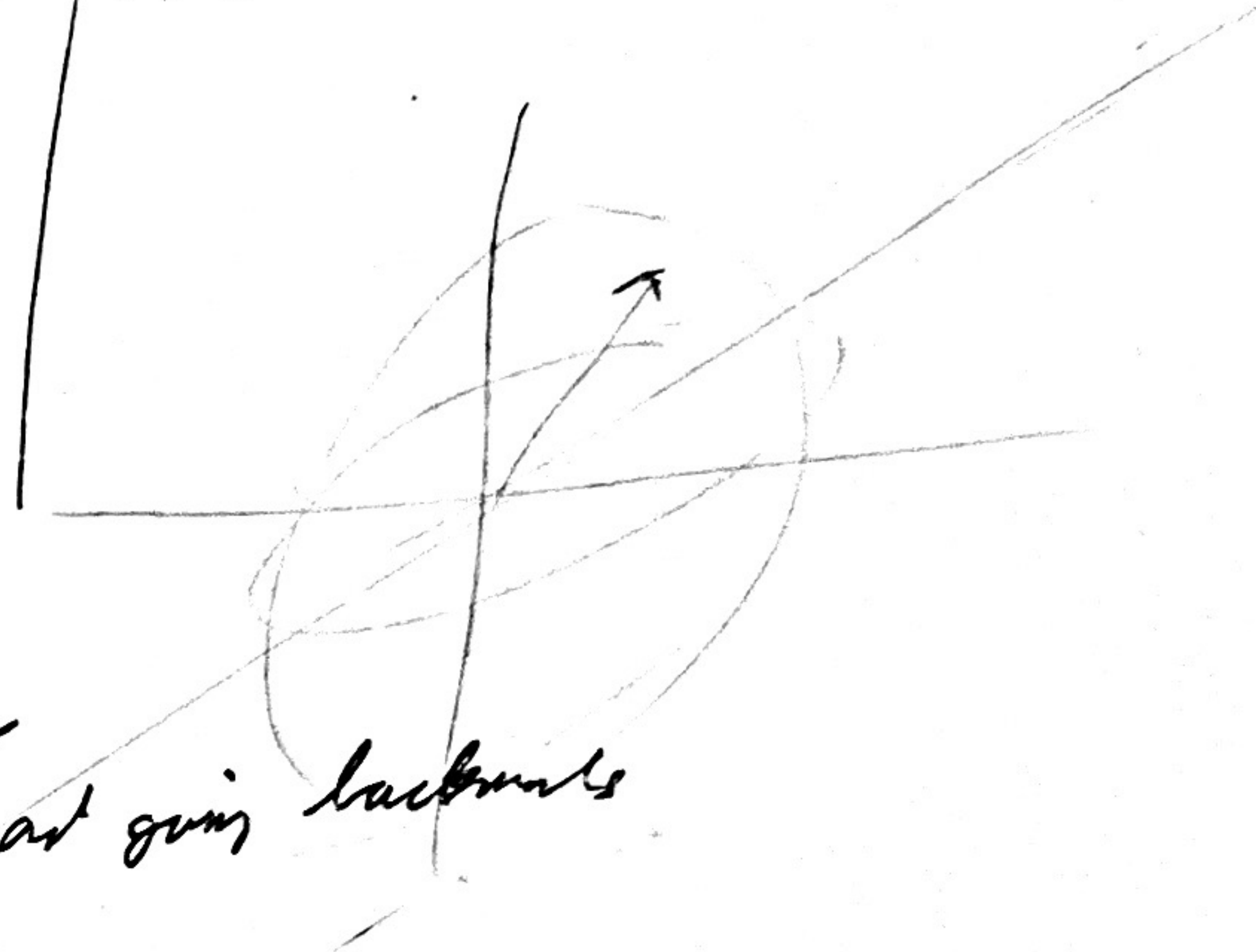
4)  $(\underline{u} \times \underline{v}) \times \underline{w} = (\underline{u} \cdot \underline{w}) \underline{v} - (\underline{v} \cdot \underline{w}) \underline{u}$

5)  $\underline{u} \times (\underline{v} \times \underline{w})$

$T^T \underline{u} \cdot \underline{x} = \underline{u} \cdot T \underline{x}$

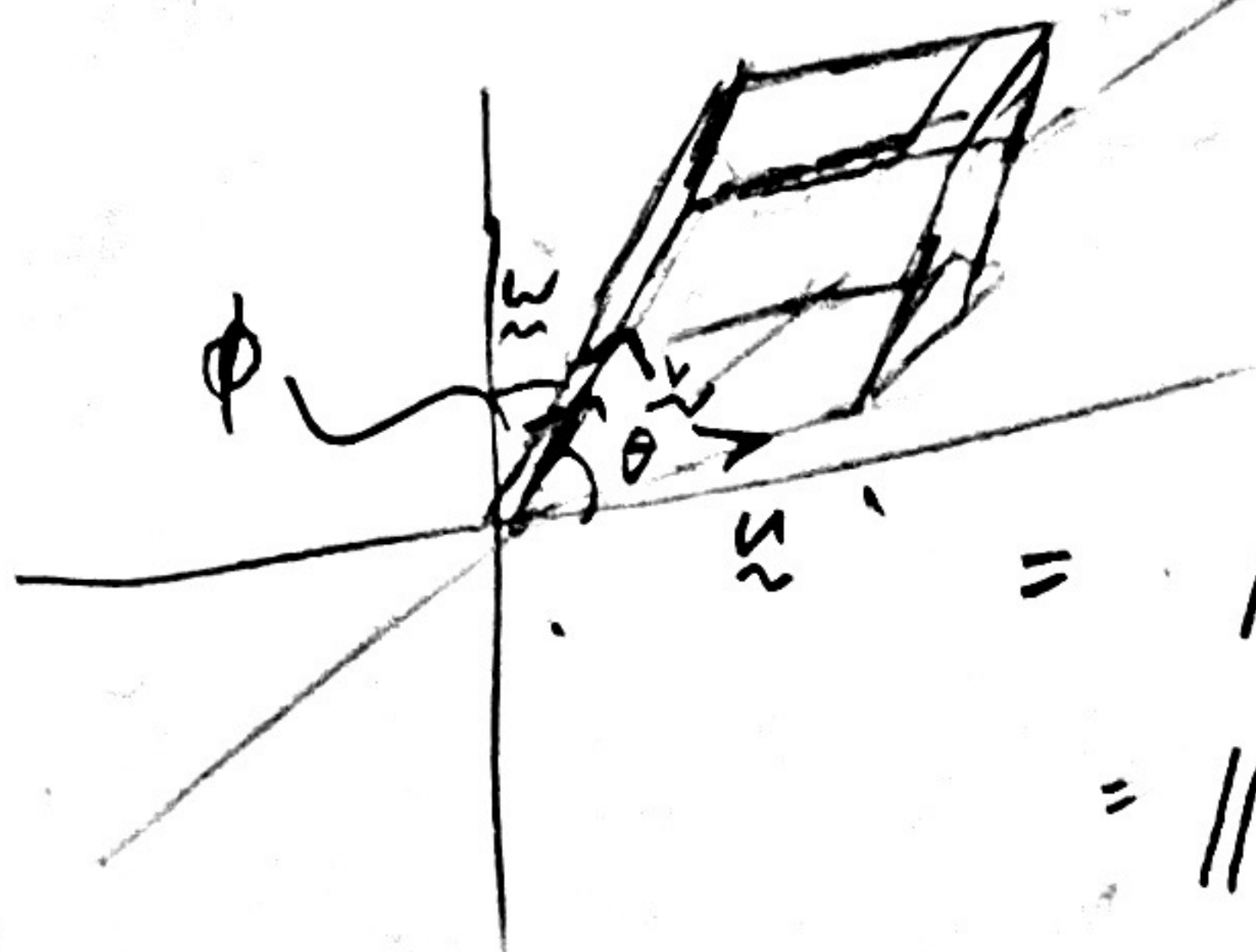


$\Rightarrow (Q^T Q - I) \underline{u} = 0 \quad \forall \underline{u} \in V$



$$(\underline{u} \times \underline{v}) \cdot \underline{w} = \epsilon_{ijk} u_j v_k w_i$$

$$= \det \begin{bmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{bmatrix}$$



$$= \|\underline{u} \times \underline{v}\| \|\underline{w}\| \cos \phi$$

$$= \|\underline{u}\| \|\underline{v}\| \sin \phi \|\underline{w}\| \cos \phi$$

Show that  $\underline{u} \times \underline{v} = 0 \Leftrightarrow \underline{u} = \alpha \underline{v}$

" "  $\underline{u} \times \underline{v} \perp \text{tr} \text{span} \{ \underline{u}, \underline{v} \}$

$$(\underline{u} \times \underline{v}) \cdot \underline{v} = 0$$

$$(\underline{u} \times \underline{v}) \cdot \underline{w} = (\underline{w} \times \underline{u}) \cdot \underline{v} = (\underline{v} \times \underline{w}) \cdot \underline{u}$$

Box product

Relationships between cross product and skew symmetric tensors

$$\underline{W} = -\underline{W}^T$$

Theorem:  $\underline{W} \in \text{Skw}$ . There exists a unique vector  $\underline{w} \in V$  s.t.

$$\underline{W} \underline{u} = \underline{w} \times \underline{u} \quad \forall \underline{u} \in V$$

$$\underline{W} = \begin{bmatrix} 0 & -c & b \\ c & 0 & -a \\ -b & a & 0 \end{bmatrix}, \quad \underline{w} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

Given a skew tensor, there are three vectors  $\underline{a}, \underline{b}, \underline{c}$  in  $V$  that when crossed, become a skew-tensor

$$w_i = -\frac{1}{2} \epsilon_{ijk} W_{jk}$$

$$\underline{W} \underline{u} = (\underline{u} \times \underline{w}) = \underline{v}$$

Conversely, for a given  $\underline{u} \in V$ ,  $\exists!$

we show given by

$$W_{ij} = -\epsilon_{ijk} w_k$$