TAM-445 **HW** 8

Problem 1.

1.

$$\mathbf{a}_s = \frac{\partial \mathbf{v}_s}{\partial t} + \operatorname{grad} \mathbf{v}_s \mathbf{v}_s(\mathbf{x}, t)$$

$$= \begin{bmatrix} -ce^{-ct+x_3}\cos(\omega t) - \omega e^{-ct+x_3}\sin(\omega t) \\ -ce^{-ct+x_3}\sin(\omega t) + \omega e^{-ct+x_3}\cos(\omega t) \\ 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & e^{-ct+x_3}\cos(\omega t) \\ 0 & 0 & e^{-ct+x_3}\sin(\omega t) \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} e^{x_3-ct}\cos(\omega t) \\ e^{x_3-ct}\sin(\omega t) \\ c \end{bmatrix}$$
(2)

Computing $\mathbf{a}_s \cdot \mathbf{v_s}$ where:

$$\mathbf{v}_s = \begin{bmatrix} e^{x_3 - ct} \cos(\omega t) \\ e^{x_3 - ct} \sin(\omega t) \\ c \end{bmatrix}$$

$$\mathbf{a}_s \cdot \mathbf{v}_s = 0$$

2.

$$\mathbf{a}_{s} = \begin{bmatrix} -\omega e^{-ct+x_{3}} \sin(\omega t) \\ \omega e^{-ct+x_{3}} \cos(\omega t) \\ 0 \end{bmatrix}$$
(3)

3.

$$D(\mathbf{x}, t) = \frac{1}{2} (\operatorname{grad} \mathbf{v}_s + \operatorname{grad} \mathbf{v}_s^{\mathrm{T}})$$
 (4)

$$D(\mathbf{x},t) = \frac{1}{2}(\operatorname{grad}\mathbf{v}_s + \operatorname{grad}\mathbf{v}_s^{\mathrm{T}})$$

$$= \begin{bmatrix} 0 & 0 & \frac{1}{2}e^{-ct+x_3}\cos(\omega t) \\ 0 & 0 & \frac{1}{2}e^{-ct+x_3}\sin(\omega t) \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{2}e^{-ct+x_3}\cos(\omega t) & \frac{1}{2}e^{-ct+x_3}\sin(\omega t) & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{2} \end{bmatrix}$$

$$(5)$$

$$= \begin{bmatrix} \frac{1}{4}e^{-ct}\cos(\omega t) \\ \frac{1}{4}e^{-ct}\sin(\omega t) \\ \frac{1}{4}e^{-ct}\cos(\omega t) \end{bmatrix}$$
 (6)

Taking the dot product to obtain the scalar value:

$$D \cdot \text{dir}$$
 (7)

$$= \frac{1}{2}e^{-ct+x_3}\cos(\omega t) \tag{8}$$

Integrating the third component of \mathbf{v}_s :

$$x_3 = c(t+1) + X_3 (9)$$

(10)

Substituting the above into \mathbf{v}_s :

$$\mathbf{v}_{s} = \begin{bmatrix} e^{ct+c-ct+X_{3}}\cos(\omega t) \\ e^{ct+c-ct+X_{3}}\sin(\omega t) \\ c \end{bmatrix}$$

$$= \begin{bmatrix} e^{X_{3}+c}\cos(\omega t) \\ e^{X_{3}+c}\sin(\omega t) \\ c \end{bmatrix}$$
(11)

$$= \begin{bmatrix} e^{X_3+c}\cos(\omega t) \\ e^{X_3+c}\sin(\omega t) \\ c \end{bmatrix}$$
 (12)

Integrating the components of \mathbf{v}_s :

$$\mathbf{x} = \begin{bmatrix} e^{X_3 + c} \sin(\omega t) \\ e^{X_3 + c} \cos(\omega t) \\ c(t+1) \end{bmatrix}$$
(13)

Problem 2.

$$\lambda_3 \to n = v_3 \tag{14}$$

$$|N| = |T\mathbf{n} \cdot \mathbf{n}| \le |T\mathbf{v}_3 \cdot v_3| \tag{15}$$

$$= |\lambda \mathbf{v}_3 \cdot \mathbf{v}_3| \tag{16}$$

$$\implies || T\mathbf{n} \cdot \mathbf{n} || \le |\lambda_3| \tag{17}$$

$$|T\mathbf{n} \cdot \mathbf{n}| = \tag{18}$$

$$|T(k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + k_3\mathbf{v}_3) \cdot (k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + k_3\mathbf{v}_3)|$$
 (19)

$$= |k_1 T \mathbf{v}_1 + k_2 T \mathbf{v}_2 + k_3 T v_3 \cdot k_1 T \mathbf{v}_1 + k_2 T \mathbf{v}_2 + k_3 T v_3| \tag{20}$$

$$= |\lambda k_1 \mathbf{v_1} + \lambda_2 k_2 \mathbf{v_2} + \lambda_3 k_3 \mathbf{v_3} \cdot \lambda_1 k_1 \mathbf{v_1} + \lambda_2 k_2 \mathbf{v_2} + \lambda_3 k_3 \mathbf{v_3}|$$

$$(21)$$

$$= |\lambda_1 k_1^2 + \lambda_2 k_2^2 + \lambda_3 k_3^2| \tag{22}$$

$$\lambda_1 \cos^2 \theta_1 + \lambda_2 \cos^2 \theta_2 + \lambda_3 \cos^2 \theta_3 \le |\lambda_3| (\cos^2 \theta_1 + \cos^2 \theta_2 + \cos^2 \theta_3) \le |\lambda_3| \tag{23}$$