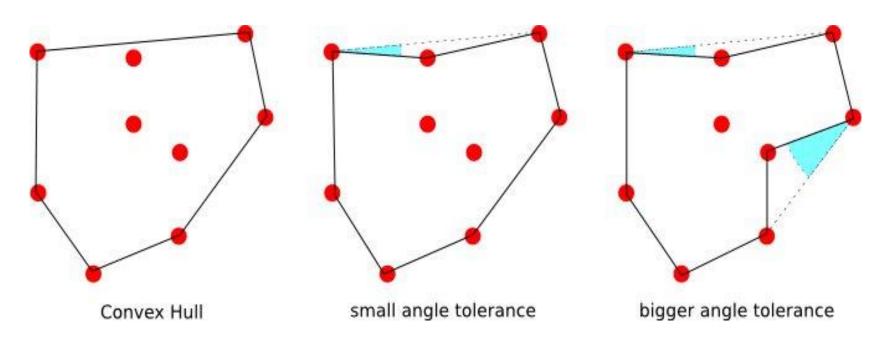
# Divide and Conquer Algorithms

#### DIVIDE AND CONQUER THE PARADIGM

#### Given a problem of size n :

- Decompose it into smaller (similar) problems
- Solve the smaller (easier) problems
- Combine the partial solution into the overall solution to the initial problem

Convex Hull Problem: Given a set of n point in the plane, find the smallest convex polygon that encloses all the points



Convex Hull Problem: Given a set of n point in the plane, find the smallest convex polygon that encloses all the points

Brute force: Algorithm

Given two points, if all other points are on the same side of the segment joining those points, then that segment is a vertex of the convex hull

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What is the time complexity of the brute force algorithm to find the convex hull of n points?

Convex Hull Problem: Given a set of n point in the plane, find the smallest convex polygon that encloses all the points

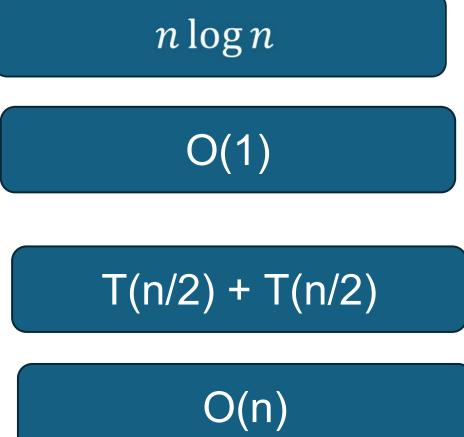
- Sort the points on the x coordinates (Done once)
- Divide the Points in A on the left and B on the right based on the x coordinates
- (Recursively) Find the CH(A) and CH(B)
- Merge the two convex hulls

#### HOW TO MERGE TWO CONVEX HULLS?

CHECK Every pair of points  $(a_i, b_j)$  to determine if the corresponding segment is part of the overall convex hull

Convex Hull Problem: Given a set of n point in the plane, find the smallest convex polygon that encloses all the points

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# What is the time complexity of the brute merge?

# Two finger Algorithm for merging convex hulls

```
i=1
j=1
While(y(i, j + 1) > y(i, j) or y(i + 1, j) > y(i, j)):
   if(y(i, j + 1) > y(i, j))
     j= j+1 mod q //move the right finger clockwise
   else if (y(i + 1, j) > y(i, j))
     i=i+1 mod p //move the left finger
counterclockwise
Return (a_i, b_i) as the upper tangent
```

# Median finding: Given a set of n numbers find the median

Given a set of n numbers, the rank of a number x in the number of elements  $\leq x$ 

Lower median has rank = floor( $\frac{n+1}{2}$ )
Upper Median has rank=Ceil( $\frac{n+1}{2}$ )

# Select(S,i) is a function that returns the element of rank i in S

```
Select (S,i) {
  Pick element x in S
  A = \{y \text{ in S such that } y < x \}
  B=\{y \text{ in } S \text{ such that } y > x\}
  if (k==i) return x
  else if (k >i ) return Select( A,i)
 else return Select(B,i-k)
```

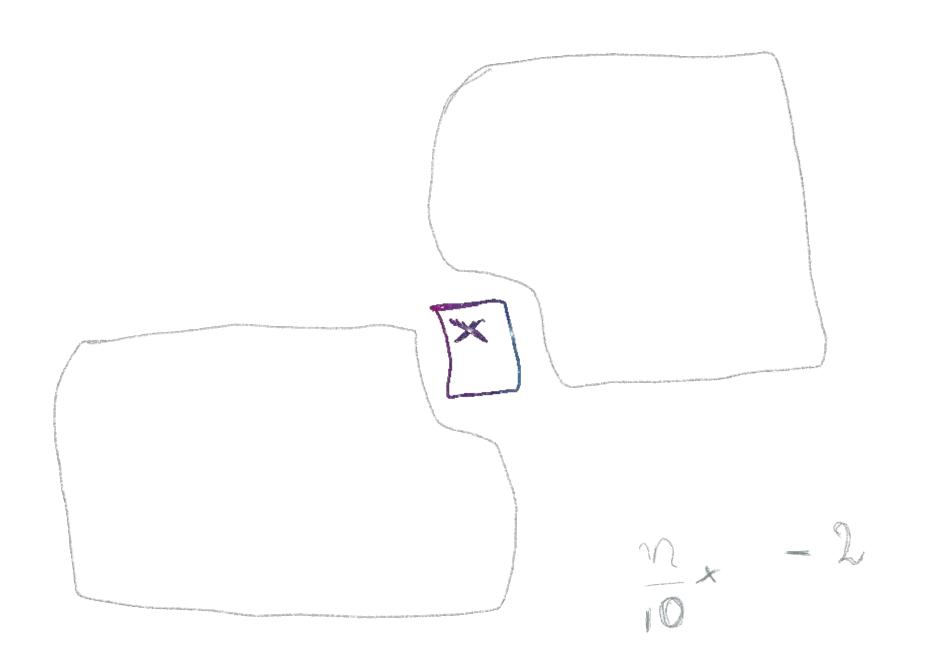
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# What is the worst case time complexity of the Select function?

# How to pick x in a clever, deterministic way?

Divide the Set into columns of size 5=>
Ceil(n/5) columns
Sort each column with biggest element at the top
Return the median of the medians of the
columns



#### The recurrence relation

$$T(n) = \begin{cases} O(1) & \text{if } n \le 140 \\ T\left(\left[\frac{n}{5}\right]\right) + T\left(\frac{7n}{10} + 6\right) + \theta(n) \end{cases}$$

### **Inversion Counting Algorithms**

Given an Array A, we have an inversion every time A[i] > A[j] and i < j

Given an Array A of size n, what is the maximum possible number of inversions?

Given an Array A of size n, How can we efficiently count the number of inversions?

### **Inversion Counting Algorithms**

- Divide the Array in two subarrays (equal)
- Recursively count the number of inversions in the left subarray
- Recursively count the number of inversions in the right subarray
- Count the number of inversions across the subarray

# **Inversion Counting Algorithms**

$$T(n) = 2 T(\frac{n}{2}) + O(n) = T(n) = n \log n$$

### Average Case of Quick Sort

#### **Worst Case**

$$T(n) = T(n-1) + O(n)$$
  
=>  $T(n) = O(n^2)$ 

#### **Best Case**

$$T(n) = 2 T\left(\frac{n}{2}\right) = O(n)$$
$$=> T(n) = O(n \log n)$$

### Average Case of Quick Sort

- Depends on the possible choices of the pivot
- For Simplicity, Assume that elements are unique all have the same chance of being selected as the pivot => Randomized choice of the pivot.
- What are the possible partitions => 0: n-1,1: n-2,...,n-1,0
- The expected time complexity is the average time complexity:

$$T(n) = 1/n(\sum_{k=0}^{n-1} (T(k) + T(n-k-1)) + O(n))$$

# Closest pair of points