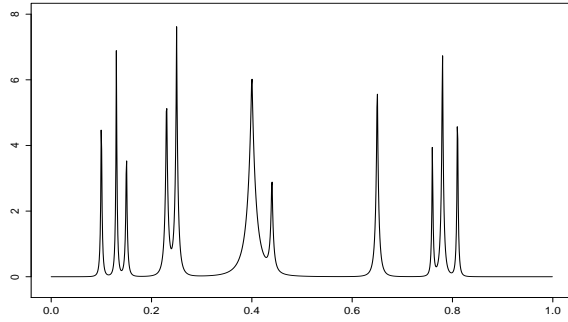
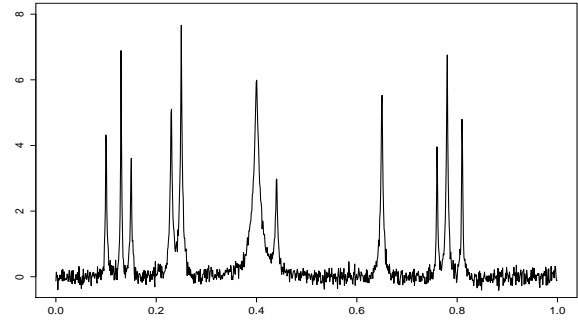


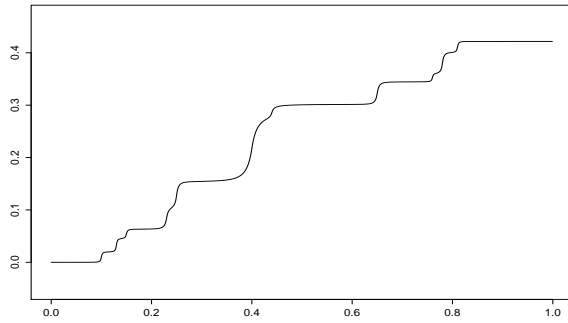
Bumps original function (velocity)



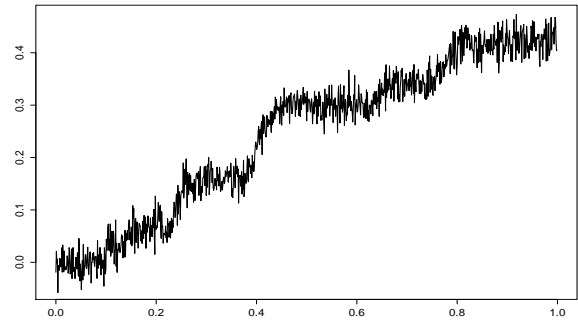
Bumps original function with noise



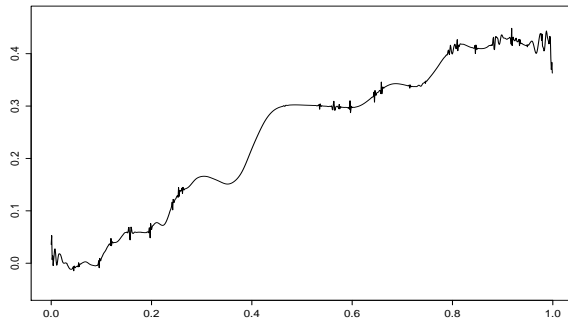
Generated position from Bumps



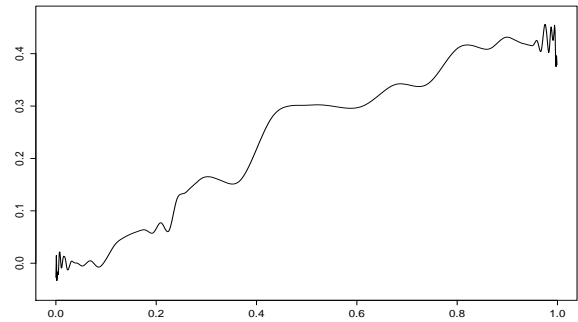
Generated position with noise



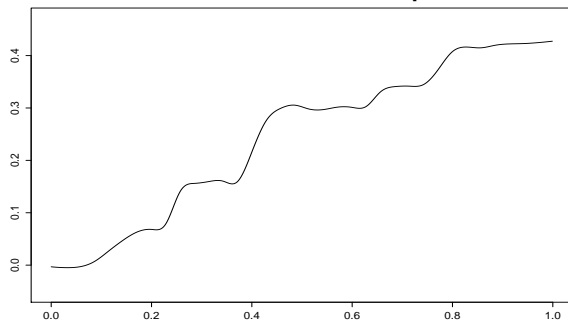
Reconstruction from Wavelet(sure)



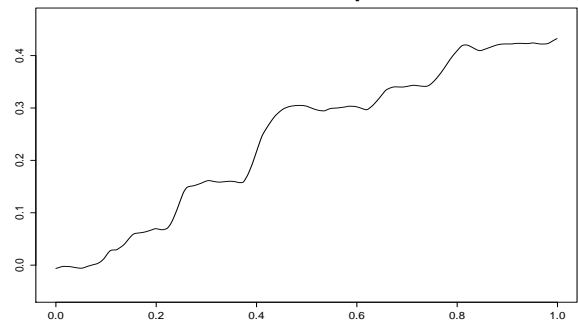
Reconstruction from Wavelet(BayesThresh)



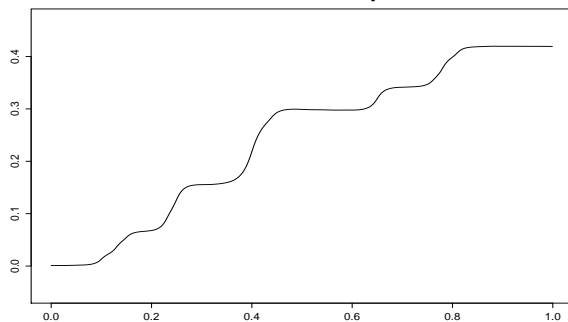
Reconstruction from P-spline



Reconstruction from Tractor Spline without Velocity



Reconstruction from Tractor Spline without APT



Reconstruction from Tractor Spline

