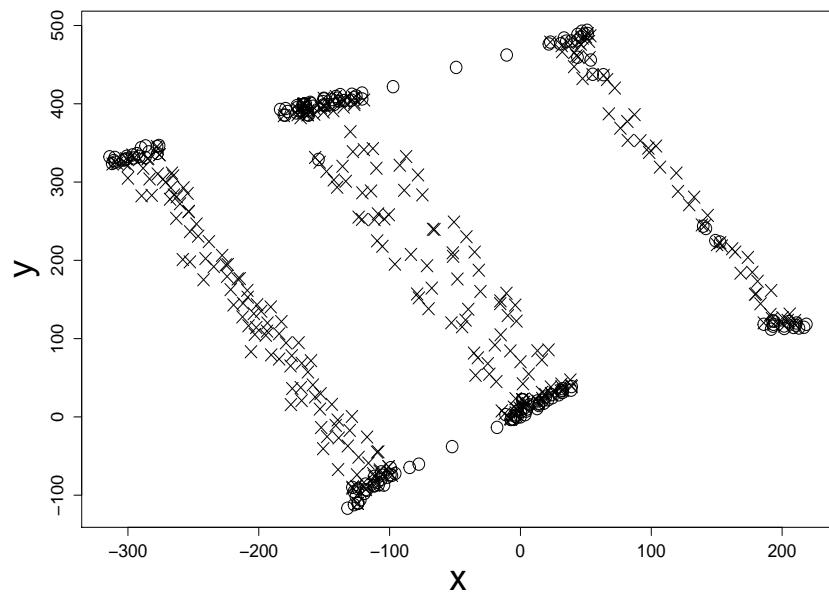
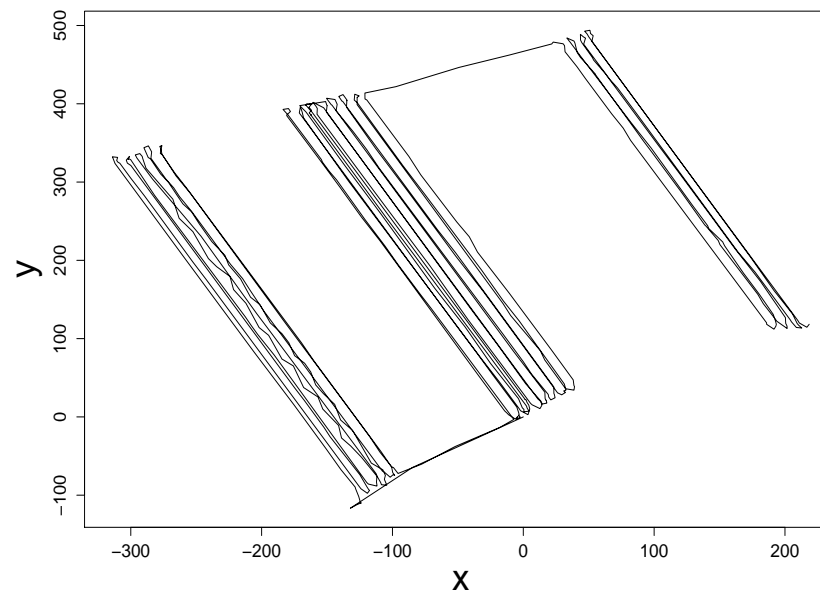


**512 original data points**



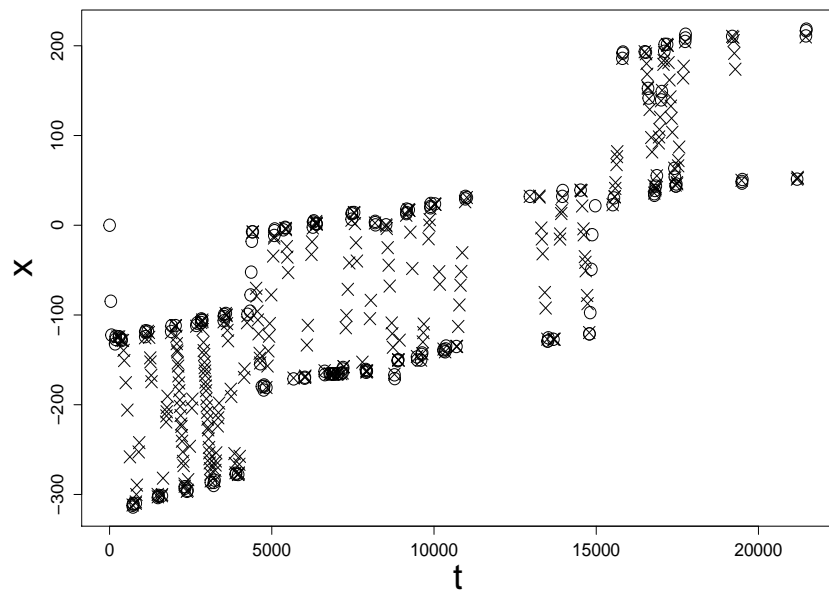
(a)

**original trajectory**



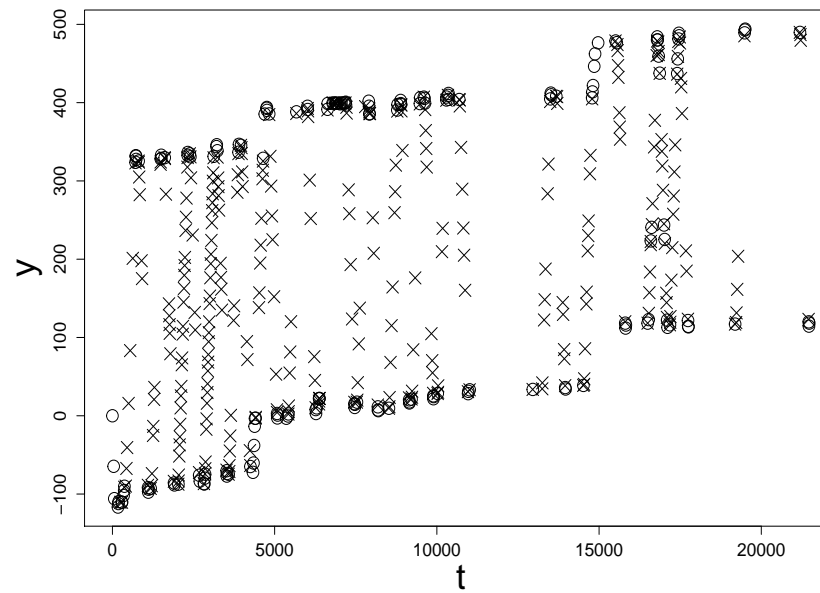
(b)

**original data points on x**



(c)

**original data points on y**



(d)