# DATA MINING 2 TP 2.4 Multi-class SVM

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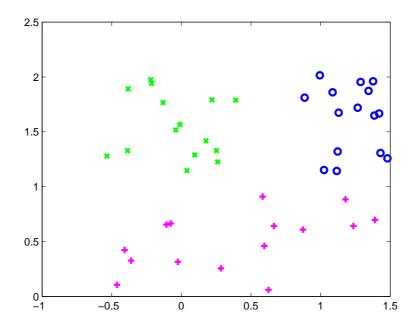
### Introduction

L'objectif de ce TP est de réaliser un SVM 3 classes par diverses méthodes : linéaire 1 vs all, linéaire all together, avec kernel.

### **Dataset**

On génère un jeu de données

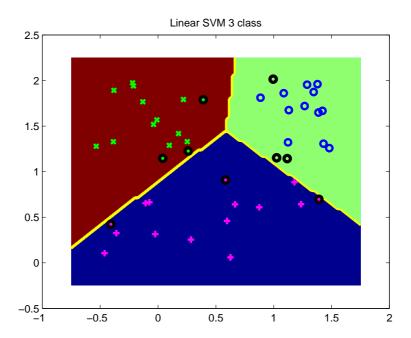
```
 \begin{array}{l} \text{1 } \text{ni} = 15; \\ \text{2 } \text{of} = 1; \\ \text{3 } \text{X1} = \text{rand}(\text{ni},2) \ ; \\ \text{4 } \text{X1}(:\ ,1) = 2*\text{X1}(:\ ,1) - .5; \\ \text{5 } \text{X2} = \text{rand}(\text{ni},2) + \text{of} * \text{ones}(\text{ni},1) * [.55 \ 1.05]; \\ \text{6 } \text{X3} = \text{rand}(\text{ni},2) + \text{of} * \text{ones}(\text{ni},1) * [-.55 \ 1.05]; \\ \text{7 } \text{Xi} = [\text{X1}; \text{X2}; \text{X3}]; \\ \text{8 } [\text{n,p}] = \text{size}(\text{Xi}); \\ \text{9 } \text{yi} = [[\text{ones}(\text{ni},1) \ ; -\text{ones}(\text{ni},1) \ ; -\text{ones}(\text{ni},1) \ ; \text{ones}(\text{ni},1) \ ; \text{ones}(\text{ni},1) \ ; \\ \text{10 } -\text{ones}(\text{ni},1) \ ; \ [-\text{ones}(\text{ni},1) \ ; -\text{ones}(\text{ni},1) \ ; \text{ones}(\text{ni},1) \ ]]; \\ \text{12 } \text{nt} = [\text{ones}(\text{ni},1) \ ; 2*\text{ones}(\text{ni},1) \ ; 3*\text{ones}(\text{ni},1) \ ]; \\ \text{13 } \text{X1t} = \text{rand}(\text{nt},2); \\ \text{14 } \text{X1t}(:\ ,1) = 2*\text{X1t}(:\ ,1) - .5; \\ \text{15 } \text{X2t} = \text{rand}(\text{nt},2) + \text{of} *\text{ones}(\text{nt},1) * [.55 \ 1.05]; \\ \text{16 } \text{X3t} = \text{rand}(\text{nt},2) + \text{of} *\text{ones}(\text{nt},1) * [-.55 \ 1.05]; \\ \text{17 } \text{Xt} = [\text{X1t}; \text{X2t}; \text{X3t}]; \\ \text{18 } \text{yt} = [\text{ones}(\text{nt},1) \ ; 2*\text{ones}(\text{nt},1) \ ; 3*\text{ones}(\text{nt},1) \ ]; \\ \text{19 } \text{plot}(\text{X1}(:\ ,1) \ ,X1(:\ ,2) \ , '+m' \ , 'LineWidth' \ ,2) \ ; hold on \\ \text{20 } \text{plot}(\text{X2}(:\ ,1) \ ,X2(:\ ,2) \ , 'ob' \ , 'LineWidth' \ ,2) \ ; \\ \text{21 } \text{plot}(\text{X3}(:\ ,1) \ ,X3(:\ ,2) \ , 'xg' \ , 'LineWidth' \ ,2) \ ; \\ \end{array}
```



#### Linéaire 1 vs all

On test d'abord une approche linéaire 1 vs all. On obtient un taux d'erreur de 10%.

```
kernel= 'poly'; d=1;
 _{2} C = 1000000000;
 a = 1e - 8;
 8 % support vector
 9 vsup = [ind_sup1; ind_sup2; ind_sup3];
_{11} % test
_{12}\ ypred1\ =\ svmval\left(Xt\,,xsup1\ ,w1\,,w01\,,kernel\ ,d\right)\ ;
\label{eq:symplectic} \mbox{\sc 13 ypred2} \ = \ svmval\left(Xt\,, xsup2 \ , w2\,, w02\,, kernel \ , d\right) \ ;
_{14} ypred3 = svmval(Xt, xsup3 ,w3, w03, kernel ,d);
_{15} [v yc] = \max([ypred1 , ypred2 , ypred3]');
_{17} % error rate
18 nbbienclasse = length(find(yt ==yc'));
19 freq err = 1 - nbbienclasse/(3*nt)
21 % plot
_{22} [xtest1 xtest2] = meshgrid([ -0.75:.025:1.75] ,[-.25:0.025:2.25]);
[nnl nnc] = size(xtest1);
 24 \ Xtest = [reshape(xtest1 , nnl*nnc , 1) \ reshape(xtest2 , nnl*nnc , 1)]; 
{\tt 25 \ ypred1 = svmval(Xtest \ , xsup1 \ , w1, w01, kernel \ , d)} \ ;
29 ypred1 = reshape(ypred1 , nnl, nnc);
30 ypred2 = reshape(ypred2 , nnl, nnc);
31 ypred3 = reshape(ypred3 , nnl, nnc);
32 yc = reshape(yc, nnl, nnc);
32 yc = reshape(yc,nnl,nnc);
33 contourf(xtest1 ,xtest2 ,yc,50); shading flat; hold on
34 plot(X1(: ,1) ,X1(: ,2) , '+m' , 'LineWidth' ,2);
35 plot(X2(: ,1) ,X2(: ,2) , 'ob' , 'LineWidth' ,2);
36 plot(X3(: ,1) ,X3(: ,2) , 'xg' , 'LineWidth' ,2);
37 h3=plot(Xi(vsup ,1) ,Xi(vsup ,2) ,'ok' , 'LineWidth' ,2);
38 [cc, hh]=contour(xtest1 ,xtest2 ,yc,[1.5 1.5] , 'y-' , 'LineWidth' ,2);
39 [cc, hh]=contour(xtest1 ,xtest2 ,yc,[2.5 2.5] , 'y-' , 'LineWidth' ,2);
40 plot (X1(: ,1) ,X1(: ,2) , '+m' , 'LineWidth' ,2) ; hold on
41 plot (X2(: ,1) ,X2(: ,2) , 'ob' , 'LineWidth' ,2) ;
42 plot (X3(: ,1) ,X3(: ,2) , 'xg' , 'LineWidth' ,2) ;
43 h3=plot (Xi(vsup ,1) ,Xi(vsup ,2) ,'ok' , 'LineWidth' ,3) ;
44 title ('Linear SNM ,2 class');
44 title ('Linear SVM 3 class');
    freq_err =
           0.1030
```



## All together

On teste ensuite la méthode all together qui consiste à résoudre un seul problème de minimisation pour trouver plusieurs SVM.

On notera que ce problème contient énormément de contraintes.

On obtient un taux d'erreur de 7%. Cependant, lors des tests, on trouve généralement un moins bon résultat avec cette méthode qu'avec l'approche 1 vs all.

```
cvx_begin
       variables w1(p) w2(p) w3(p) b1(1) b2(1) b3(1)
2
       dual variables lam12 lam13 lam21 lam23 lam31 lam32
3
       minimize( .5*(w1*w1 + w2*w2 + w3*w3) )
       subject to
           lam 12:
                    (X1*(w1-w2) + b1 - b2) >= 1;
6
                    (X1*(w1-w3) + b1 - b3) >= 1;
           lam 13:
           lam21 : (X2*(w2-w1) + b2 - b1) >= 1;
           lam23 : (X2*(w2-w3) + b2 - b3) >= 1;
9
           lam31 : (X3*(w3-w1) + b3 - b1) >= 1;
10
           lam32 : (X3*(w3-w2) + b3 - b2) >= 1;
11
12 cvx end
13
_{14} % error rate
_{15} \text{ ypred1} = Xt*w1 + b1;
16 \text{ ypred2} = \text{Xt*w2} + \text{b2};
_{17} \text{ ypred3} = \text{Xt*w3} + \text{b3};
                            ypred2 , ypred3]') ;
[v \ yc] = \max([ypred1]
nbbienclasse = length(find(yt ==yc'));
20 freq_err = 1 - nbbienclasse/(3*nt)
  freq_err =
       0.0720
```

## All together matrix form

On écrit cette fois le problème "all together" de manière matricielle en primal puis en dual. Cela permet de résoudre ce problème avec mongp.

```
1 % all together primal
z = zeros(ni,p);
  X = [X1 - X1 Z;
       X1 \ Z - X1;
       -X2 X2 Z ;
       Z X2 - X2;
       -X3 Z X3;
       Z -X3 X3;
10 l = 10^{-12};
{}^{11} A = [1 \ 1 \ -1 \ 0 \ -1 \ 0 \ ; \ -1 \ 0 \ 1 \ 1 \ 0 \ -1];
12 A = kron(A, ones(1, ni));
13
14 cvx_begin
       cvx_precision best
       %cvx_quiet(true)
16
       variables w(3*p) b(2)
17
       dual variables lam
18
       minimize(.5*(w'*w))
19
20
       subject to
           lam : X*w + A'*b >= 1;
21
22 cvx_end
25 % all together dual
_{27} % compute G
28 K = Xi*Xi'; % kernel matrix
29 M = [1 -1 0; 1 0 -1; -1 1 0; 0 1 -1; -1 0 1; 0 -1 1];
```

```
30 MM = M*M';
31 MM = kron(MM, ones(ni));
{}_{32}\ Un23\ =\ [1\ 0\ 0;1\ 0\ 0\ ;\ 0\ 1\ 0\ ;\ 0\ 1\ 0;\ 0\ 0\ 1\ ;\ 0\ 0\ 1];
un23 = kron(Un23, eye(ni));
_{34} G = MM.*(Un23*K*Un23');
35
36 % solve problem
37
38 l = 10^{-6};
39 I = eye(size(G));
_{40} G = G + l*I;
_{41} e = ones(2*n,1);
42 cvx_begin
       variables al(2*n)
43
      dual variables eq po
      minimize( .5*al '*G*al - e'*al )
45
46
      subject to
47
          eq : A*al == 0;
          po : al >= 0;
48
49 cvx_end
50
51 % monqp
[alpha], b, pos = monqp(G, e, A', [0;0], inf, l, 0);
_{54} % results
55 [al lam [lam12; lam13; lam21; lam23; lam31; lam32]]
  ans =
      0.0000
                 0.0000
                            0.0000
      [...]
      0.0000
                 0.0000
                            0.0000
     16.3879
                16.3882
                           16.3882
      0.0000
                 0.0000
                            0.0000
      [...]
      0.0000
               0.0000
                            0.0000
      1.5504
                1.5505
                            1.5505
      0.0000
                 0.0000
                            0.0000
       [...]
      0.0000
                 0.0000
                            0.0000
      1.1136
                 1.1136
                            1.1136
      0.0000
                 0.0000
                            0.0000
      [...]
      0.0000
                 0.0000
                            0.0000
     19.0519
                19.0522
                           19.0523
      0.0000
                 0.0000
                            0.0000
       [...]
      0.0000
                 0.0000
                            0.0000
      5.1778
                 5.1778
                            5.1778
      0.0000
                 0.0000
                            0.00007
       [...]
      0.0000
                 0.0000
                            0.0000
      7.8418
                 7.8419
                            7.8419
      0.0000
                 0.0000
                            0.0000
       [...]
      0.0000
                 0.0000
                            0.0000
```

#### Kernelize multi-class SVM

On ajoute maintenant un kernel à notre calcul. Pour faire ce calcul, on crée 2 fonctions SVM3Class et SVM3val. Notons que ces fonctions sont perfectibles car ne fonctionnent que pour 3 classes de même taille.

#### Fonction SVM3class

```
{\tiny 1\  \  function\  \  [Xsup,\ alpha\,,\ b]\  \  =\  \  SVM3Class(Xi\,,\ yi\,,\ C,\ kernel\,,\ kerneloption\,,\ options)}
3 % note yi n'est pas utilisé pour simplifier les calculs. Normalement, il
4 % devrait influer sur la forme des matrices A, M et Un23.
[n, p] = size(Xi);
7 \text{ ni} = n/3;
9 % matrice A
A = \begin{bmatrix} 1 & 1 & -1 & 0 & -1 & 0 & ; & -1 & 0 & 1 & 1 & 0 & -1 \end{bmatrix};
A = kron(A, ones(1, ni));
13 % matrice M et MM
{}^{14}\ M = \ [1 \ -1 \ 0; \ 1 \ 0 \ -1 \ ; \ -1 \ 1 \ 0 \ ; \ 0 \ 1 \ -1; \ -1 \ 0 \ 1; \ 0 \ -1 \ 1];
_{15} \text{ MM} = \text{kron} (\text{M*M'}, \text{ones} (\text{ni}));
16
_{17} % matrice Un23
18 \ Un23 = [1 \ 0 \ 0; 1 \ 0 \ 0 \ ; \ 0 \ 1 \ 0; \ 0 \ 0 \ 1 \ ; \ 0 \ 0 \ 1];
19 \operatorname{Un23} = \operatorname{kron}(\operatorname{Un23}, \operatorname{eye}(\operatorname{ni}));
_{21} % calcul de G
22 K = svmkernel(Xi, kernel, kerneloption);
_{23} G = MM.*(Un23*K*Un23');
24
25 % QP
_{26} l = 10^{-} -5;
I = eye(size(G));
28 G = G + l*I; % kernel matrix
29 e = ones(2*n,1);
30 [al , \sim, pos] = monqp(G, e, A', [0;0], C, l, 0);
n23 = 2*ni;
32
33 % calcul de b
_{34} \text{ yp} = G(:, pos) * al;
55 \text{ b1} = 1 - \text{yp}(\text{pos}(1));
p2 = (find((pos > n23) & (pos <= 2*n23)));
b2 = 1 - yp(pos(p2(1)));
38 b3 = 1 - yp(pos(end));
40 b = [b1; b2; b3];
41
42 % calcul de alpha
_{43} \text{ alpha} = \text{zeros}(2*n,1);
alpha(pos) = al;
46 \text{ Xsup} = \text{Xi};
      Fonction SVM3val
1 function [y_pred] = SVM3Val(Xtest, Xsup, alpha, b, kernel, kerneloption)
[n, p] = size(Xsup);
4 \text{ n}23 = 2/3*n;
6 % split b
7 b1 = b(1);
b2 = b(2);
9 b3 = b(3);
11 % split alpha
12 \text{ al} 12 = \text{alpha} (1:n/3);
al13 = alpha(n/3+1:n23)
al21 = alpha(n23+1:n23+n/3)
al23 = alpha(n23+n/3+1:2*n23)
al31 = alpha(2*n23+1:2*n23+n/3);
17 \text{ al} 32 = \text{alpha} (2*n23+n/3+1:end);
_{19} % compute kernel
```

```
20 K = svmkernel(Xtest, kernel, kerneloption, Xsup);
21
 \begin{array}{l} {}_{22} \ \ K1 = K(: \ ,1\!:\!n/3) \ ; \\ {}_{23} \ \ K2 = K(: \ ,n/3\!+\!1\!:\!n23) \ ; \\ {}_{24} \ \ K3 = K(: \ ,n23\!+\!1\!:\!end) \ ; \\ \end{array} 
26 % predict
ypred1 = K1*al12 + K1*al13 - K2*al21 - K3*al31 + b1;
\begin{array}{l} {\rm 28\ ypred2} = {\rm K2*al21+K2*al23-K1*al12-K3*al32+b2;} \\ {\rm 29\ ypred3} = {\rm K3*al31+K3*al32-K1*al13-K2*al23+b3;} \end{array}
[\sim, yc] = \max([ypred1, ypred2, ypred3]');
32
y_pred = yc;
           Script de test
 1 kernel = 'gaussian';
 _{2} kerneloption = .25;
     [Xsup, alpha, b] = SVM3Class(Xi, yi, C, kernel, kerneloption);
  \mbox{7 yc} = SVM3Val(\,Xtest\,,\,\,Xsup\,,\,\,alpha\,,\,\,b\,,\,\,kernel\,,\,\,kerneloption\,)\,; 
     yc = reshape(yc, nnl, nnc);
10 % affichage
11
12 figure:
13 colormap ( 'autumn');
14 contourf(xtest1 ,xtest2 ,yc,50); shading flat; hold on 15 plot(X1(: ,1) ,X1(: ,2) , '+m' , 'LineWidth' ,2); 16 plot(X2(: ,1) ,X2(: ,2) , 'ob' , 'LineWidth' ,2); 17 plot(X3(: ,1) ,X3(: ,2) , 'xg' , 'LineWidth' ,2);
18
19 [cc, hh]=contour(xtest1 ,xtest2 ,yc,[1.5 1.5] , 'y-' , 'LineWidth' ,2) ;
20 [cc, hh]=contour(xtest1 ,xtest2 ,yc,[2.5 2.5] , 'y-' , 'LineWidth' ,2) ;
21 plot(X1(: ,1) ,X1(: ,2) , '+m' , 'LineWidth' ,2) ; hold on
22 plot(X2(: ,1) ,X2(: ,2) , 'ob' , 'LineWidth' ,2) ;
23 plot(X3(: ,1) ,X3(: ,2) , 'xg' , 'LineWidth' ,2) ;
24 title('SYM' 2 aloses with governor known)')
24 title ('SVM 3 class with gaussian kernel');
25 hold off
```

