

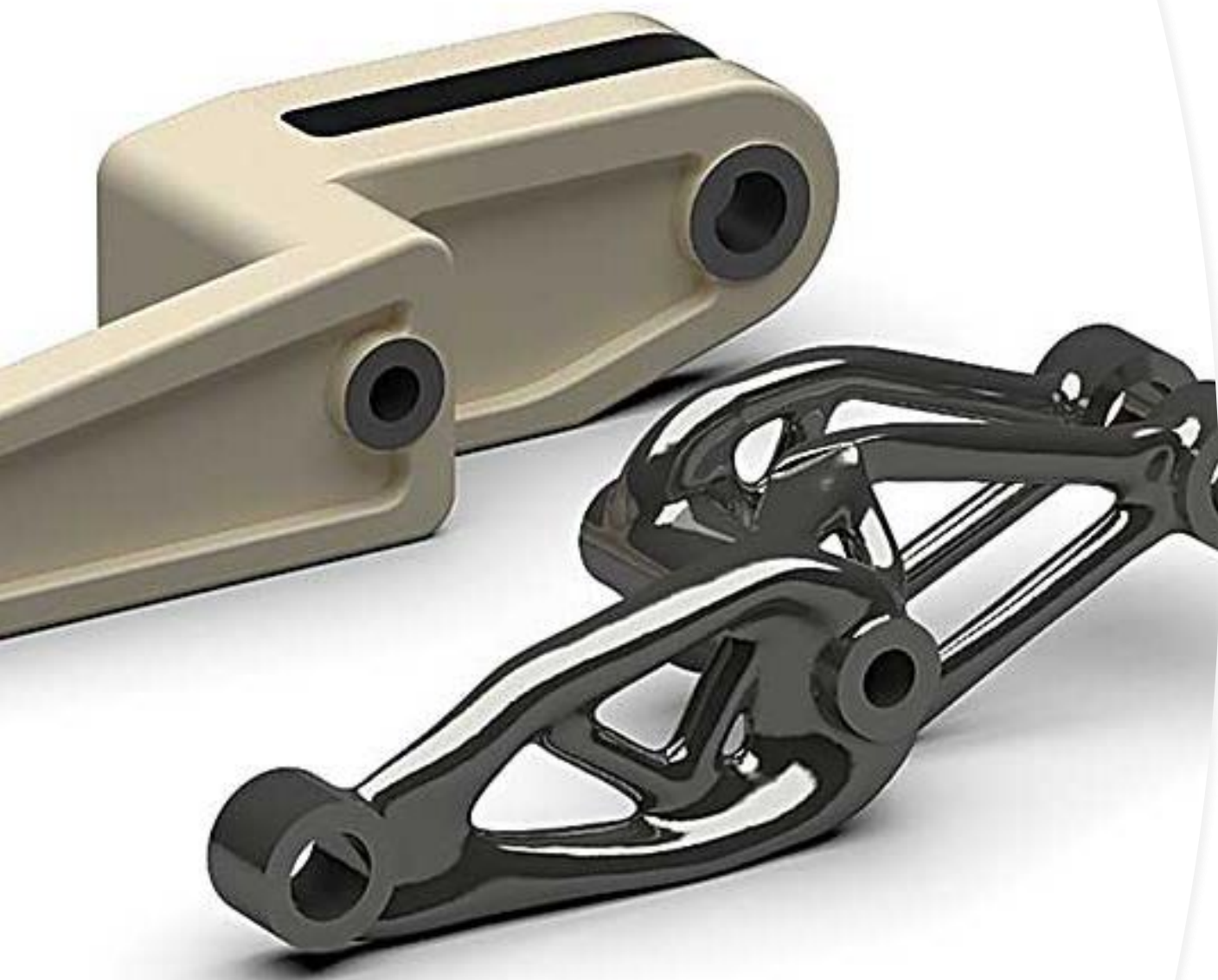
RIACT 2020

Optimization of quadcopter frame using generative design and comparison with DJI F450 drone frame

Jerrin Bright et al 2021 IOP Conf. Ser.: Mater. Sci. Eng. 1012 012019



VIT[®]
Vellore Institute of Technology
(Deemed to be University under section 3 of UGC Act, 1956)
CHENNAI



What is Generative design?



Iterative Design
exploration process



Uses AI to generate
multiple Design in a
single computation



GAN is used to
generate surfaces
between constraints



Mainly used for
mass reduction and
structural
optimization

Steps involved in Generative Design



Define

Define preserved
Boundaries



Define obstacle
boundary



Define Fixed
Geometry



Define material



Define AM
technique



Generate

Define the loading
conditions



Generate All
possible outcomes



Remove all Under
defined outcomes



Explore

Check for the best
possible design
with optimized
properties



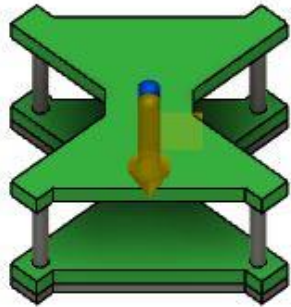
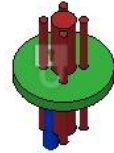
Smoothen the
surface using form
tools

Loading conditions

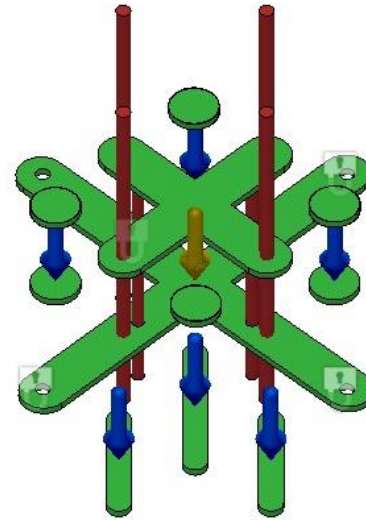
Component	Number of individual components	Weight of individual component (g)	Net Weight of individual component (g)
RS2205S Motor	4	28.8	115.2
Pixhawk FC	1	73	73
M8N GPS	1	32	32
5" Propeller	4	4	16
BL Heli ESC	4	14	56
PC Hub PDB	1	8.5	8.5
Camera	1	12	12
Telemetry	1	15	15
IA6B Receiver	1	14.6	14.6
LIPO Battery	1	200	200
TOTAL	19		542.3

- Approx. weight of Frame 250g
- By 15% buffer we get a total mass of 1000g
- $M=1000g=1Kg$
- $F=M*g=10N$
- So for hovering condition we need a minimum of 10N thrust from 4 Motors

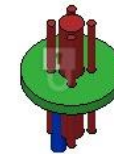
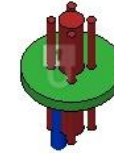
Defining a Generative design model



MODEL-1



MODEL-2



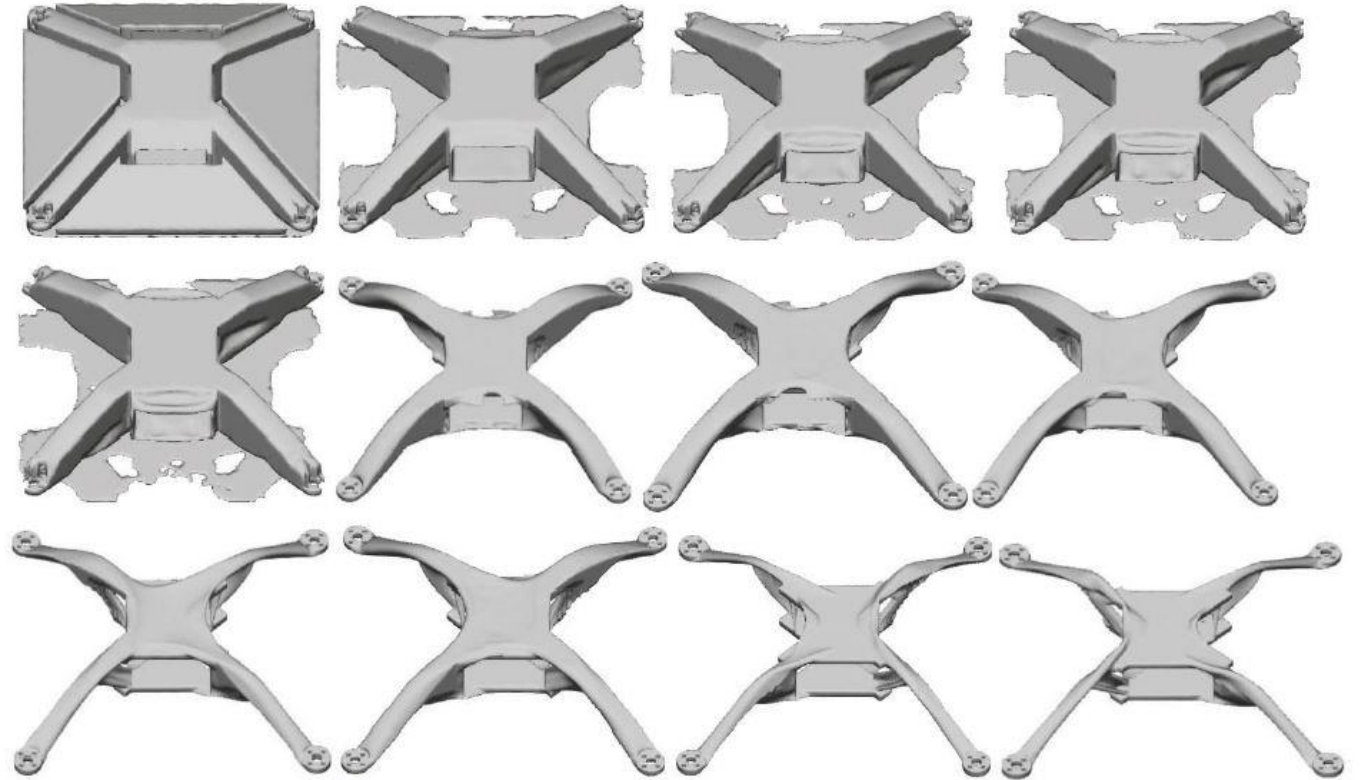
DRONE SPECS:

- 450 mm Size
- True X
- Centre of mass maintained at the exact center
- Symmetric in nature

RED COLOUR OBSTACLE BOUNDARY
GREEN COLOUR PRESERVED BOUNDARY

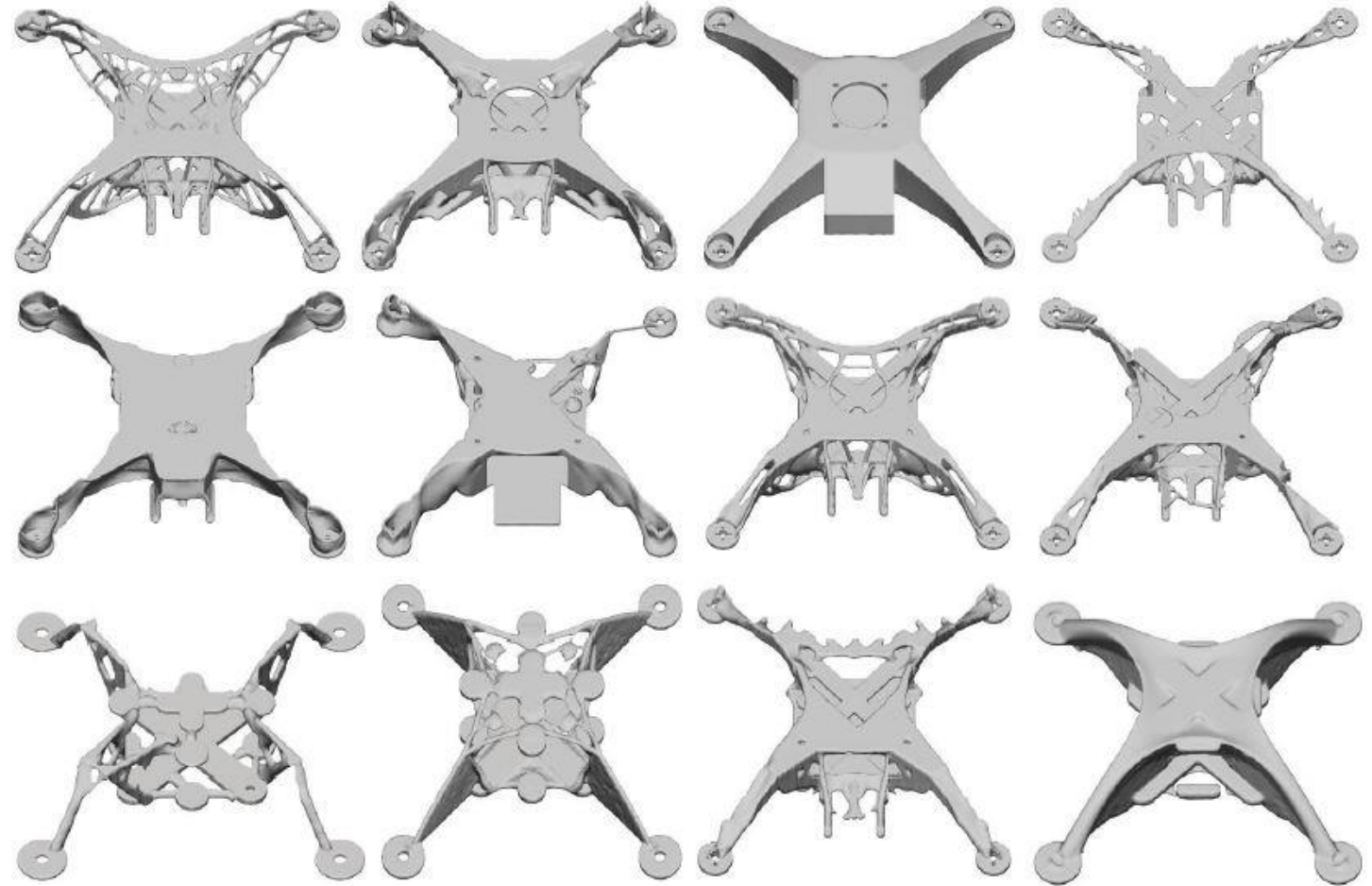
ITERATIONS

- GAN creates surfaces and overhangs
- The iterative mechanism removes mass from the surfaces while optimizing mechanical properties
- Final model is converged when no mass can be removed while having maximum mechanical strength



OUTCOMES

- Total of 74 designs were generated throughout the experiment
- Fusion 360 autonomously classifies the models based upon mass ,FOS, Von Misses Stress Etc.
- Best model is chosen based upon the mechanical properties

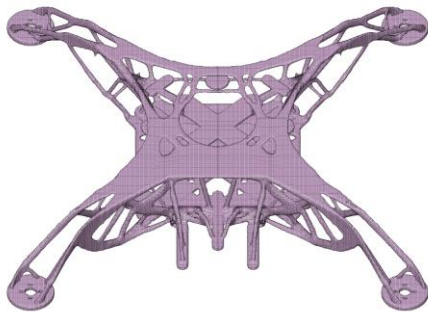


RESULTS

- Mechanical properties of generatively designed frame in comparison with DJI F450 Drone frame
- ABS plastic is used for Additive manufactured Drone frame



Model 1



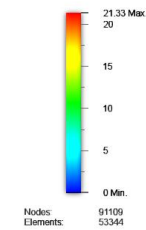
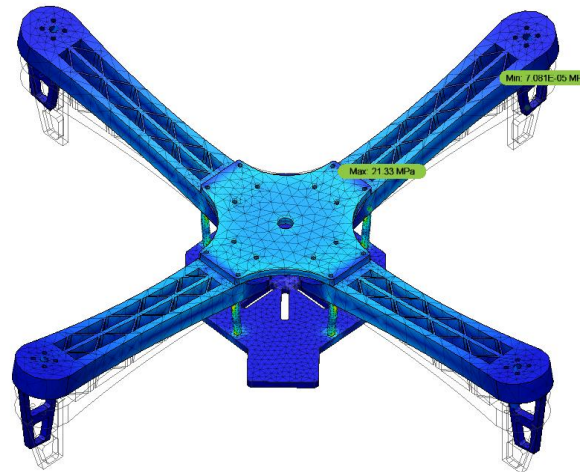
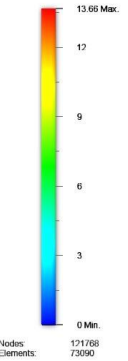
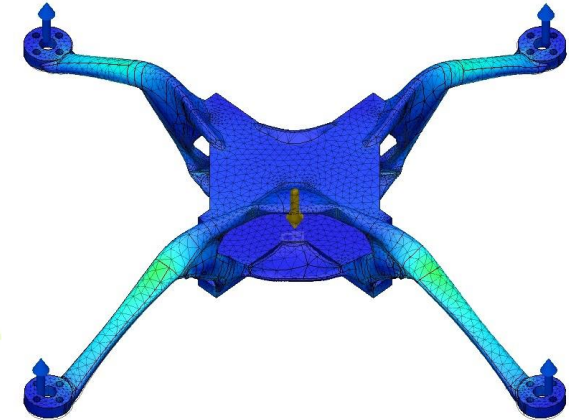
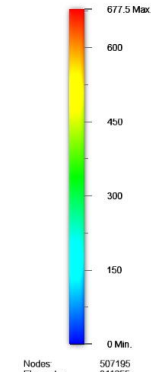
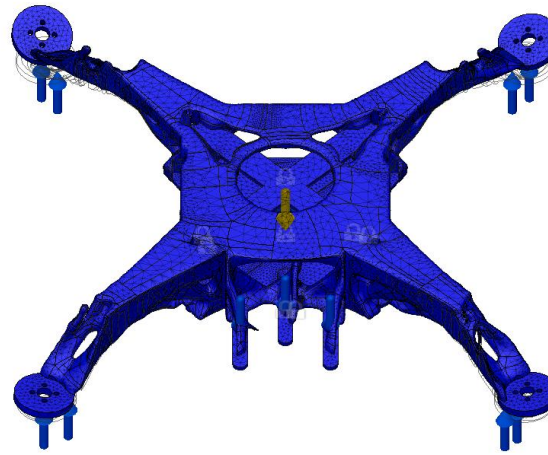
Model 2



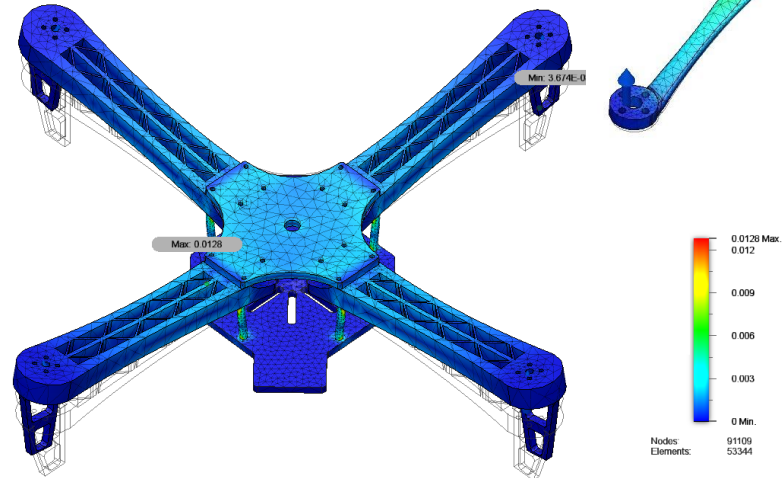
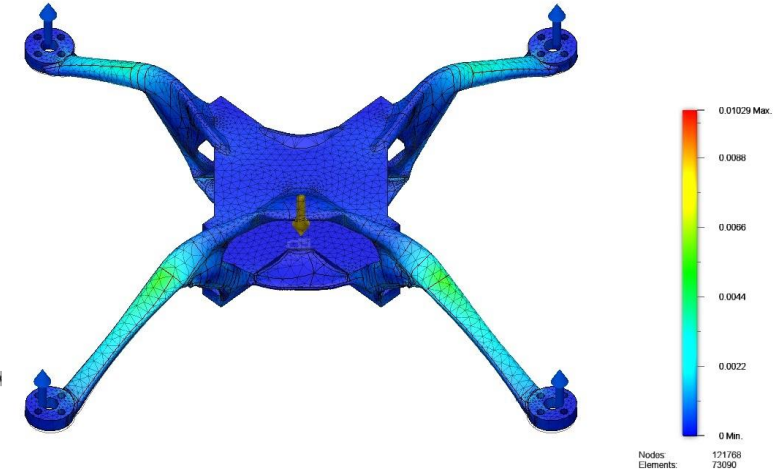
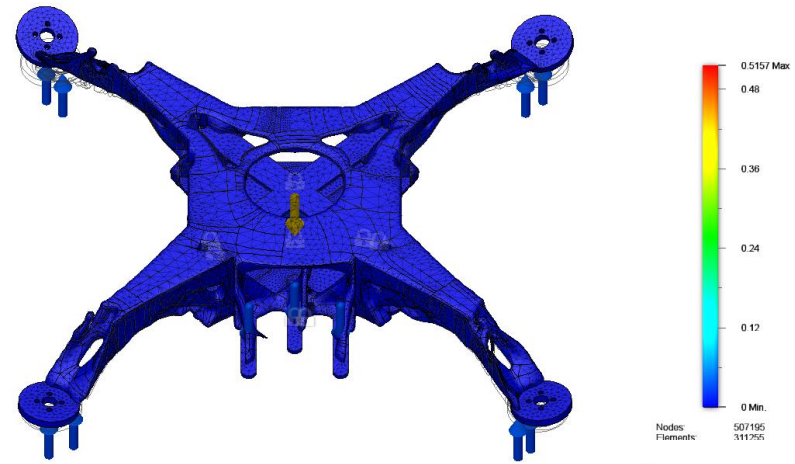
DJI F450 FRAME

FACTORS	MODEL 1	MODEL 2	DJI F450
Mass of the frame(g)	267	227	330
Minimum FOS	133	13.3	3.301
Manufacturing Method	Additive Manufacturing	Additive Manufacturing	Advanced Manufacturing
Maximum Von Mises stress(MPa)	17.11	1.5	21.33
Maximum Displacement Global(mm)	0.01	6.22	4.016
Material used	ABS	ABS	Polyamide Nylon

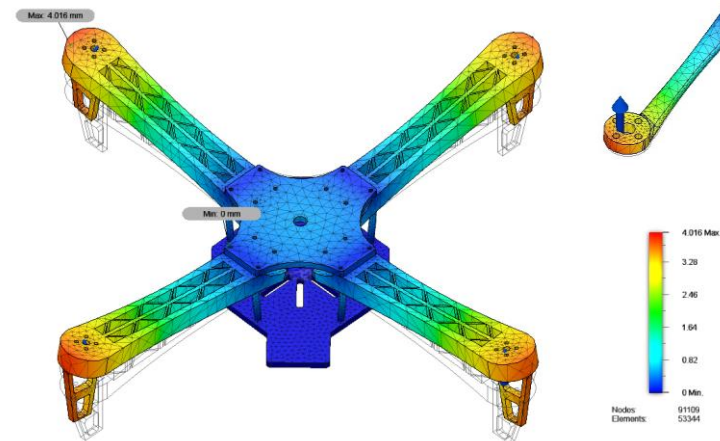
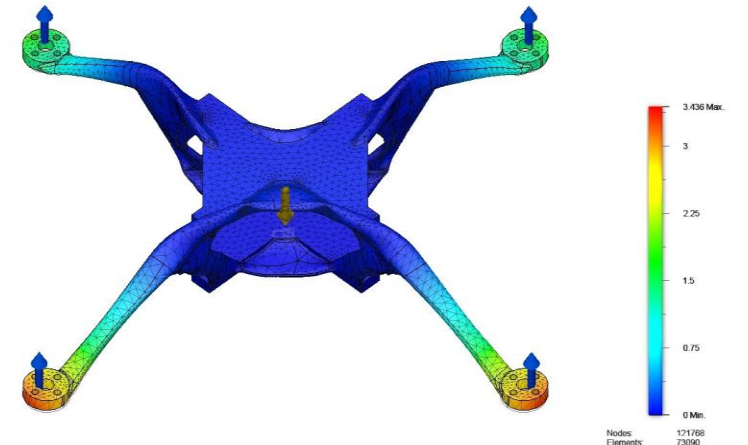
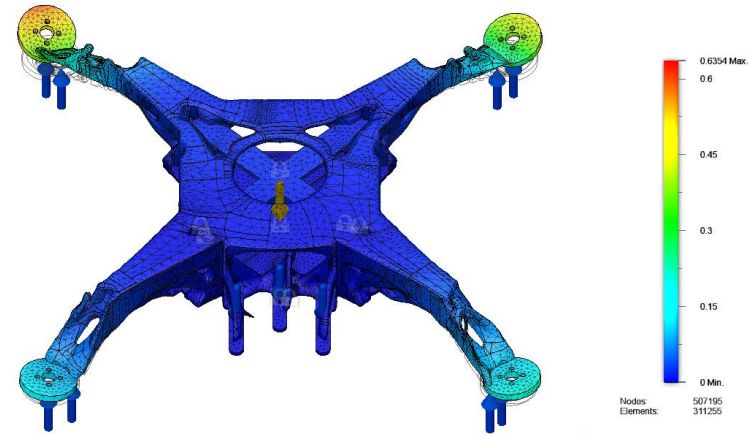
STRESS ANALYSIS



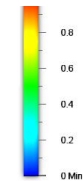
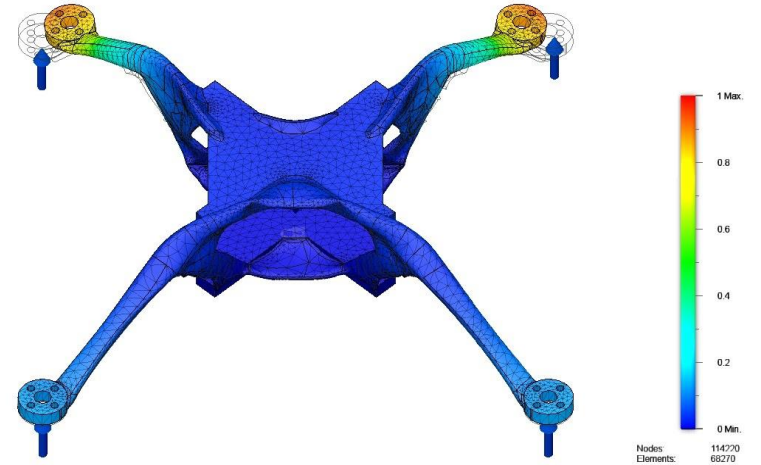
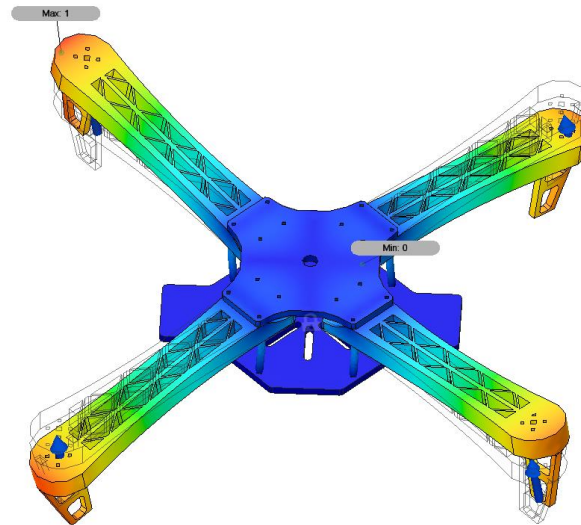
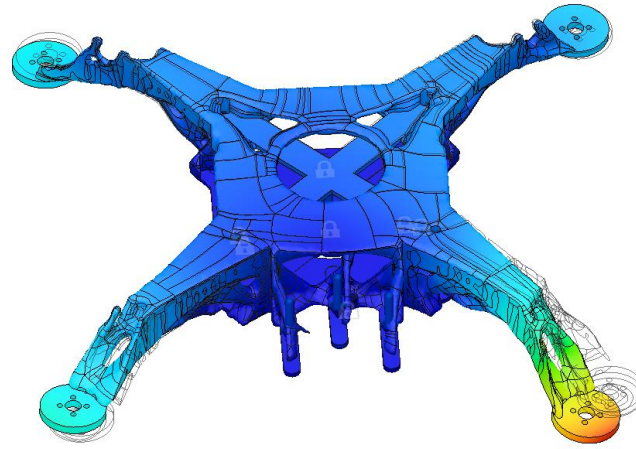
STRAIN ANALYSIS



DISPLACEMENT ANALYSIS



FREQUENCY ANALYSIS AT 300 Hz



Conclusions

All the designs generated are within the safety limit

Mass is comparatively less for generatively designed frames when compared to Traditionally designed drone frame

Factor of safety of model 1 is almost 40 times of DJI F450 Drone frame

Maximum displacement of model 2 is just about 0.1 mm under the loading conditions which is 400 times when compared to DJI Drone frame

Von mises stress is 11.4 times less for the model 2 frame in comparison to DJI F450 Frame

Model 1 and 2 can withstand cyclic load and can survive from failure for a longer period of time

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THANK YOU!

