# JERRIN BRIGHT

# LINKEDIN | PORTFOLIO | GITHUB | MAIL | SCHOLAR | NGO | BLOGS

### PERSONAL PROFILE STATEMENT

I am a versatile and self-motivated engineer highly skilled in Autonomous Systems and Robotic Real-time Perception, focusing on autonomous cars and aerial systems. Driven by desire for challenges that push me beyond my limits and eventually aid in the advancement of society regardless of affordability and background.

## **QUALIFICATIONS**

Vellore Institute of Technology, Chennai, India

Bachelors of Technology in Mechanical Engineering

June 2018-April 2022 (expected) Cumulative GPA: 8.25/10.0

# **AREA OF EXPERTISE**

Design and Simulation Tools Programming Tools Other Tools Gazebo, RViz, MATLAB, SOFA, Fusion360, SolidWorks, Proteus Python, C++, Embedded System, Shell, HTML, CSS, JS, PHP ROS, Git, MoveIt, OpenCV, TensorFlow, PyTorch, PCL, Heroku

#### PROFESSIONAL EXPERIENCE

Research Intern @ Indian Institute of Science, Bangalore, India 🗹

July 2021 - Present

Designing, building and testing quadcopters and hexacopters and deploying autonomous stack into the aerial system and testing it. Also, developing of a custom SLAM approach for aerial system was targeted. (Supervised by Prof. Suresh Sundaram)

Globalink Research Intern @ McMaster University, Ontario, Canada 🗹

July 2021 - Present

Designing and testing software for controlling a pneumatically-powered soft robot arm. It will acquire real-time data from several sensors, and implement a suitable controller. (Supervised by Prof. Gary Bone)

Summer Research Intern @ Arizona State University, Phoenix, USA 🗹

May - July 2021

Using laser scanning, photogrammetry to digitalize environments via visualizing data collected from sensors fusing into a unified system. It will be processed to provide insights to stewards. (Supervised by Prof. Thomas Czerniawski)

Autonomous System Developer (ASD) - Intern @ Aero2Astro, India 🗹

Oct 2020-April 2021

Developing ROS based autonomous navigation firmware using Visual Inertial SLAM concepts for indoor environment. Implementation was based on Sensor Fusion (EKF) and is aimed to eradicate the use of GPS.

Data Science Intern @ BrainMagic InfoTech Pvt, Chennai, India 🗹

May – July 2020

Automobile fault detection using vison techniques resulting in an IOU of 95%. Dimensional analysis was done to locate defects and monitor it. Later, was deployed in AWS using Amazon Sagemaker and S3 Buckets.

Project Research Intern @ Yuan Ze University, Taoyuan City, Taiwan 🗹

April – June 2020

Built a robust smart parking system using semantic segmentation with Conv. Conditional Random Fields and Atrous Convolution enhancing the visual capability of the system. (Supervised by Wei-Tyng Hong)

Team Captain and Co-Founder @ Atom Robotics, VIT Chennai, India 🗹

Jan 2019 - Present

An Intelligent Robotics & Satellite exploration team consisting of 50+ aspiring young minds. The team focuses on Intelligent ground vehicles targeting IGVC, USA; Planetary Aerial System targeting IPAS, MSSA.

# RESEARCH AND PUBLICATIONS

Jerrin Bright et al 2021 IOP Conf. Ser.: Mater. Sci. Eng. 1012 012019

Optimization of quadcopter frame using generative design and comparison with DJI F450 drone frame

# RESEARCH PROJECT

3D Pose Estimation using Stereo Visual Odometry 🗹

Feb – April 2021

Techniques: SLAM, FLANN, ORB, PnP, RANSAC, KLT Optical Flow

Autonomous MAV enhanced with door-to-door delivery topographies &

Dec – Jan 2020

Techniques: ROS, PID Control, Gazebo, RViz, Navigation, AMCL, Path Planning

SLAM embedded AGV for autonomous navigation

Sep - Oct 2020

Techniques: SLAM, ROS, Kinect + IMU, Sensor Fusion, Gazebo, RViz, Mapping, Path Planning

An Autonomous Planetary Aerial System for Martian Exploration

Jan - Feb 2021

Techniques: VTOL CFD Analysis, PCB Designing, Orthomosaic stitching, XBee Communication

## ACCOLADES AND RECOGNITION

Outstanding Research Paper Award 
Recognized Galactic Problem Solver 
Top Ten Internationally

Second Runner-up, IEEE Hackathon 🗹

RIACT 2020 International Conference NASA International Space Challenge International Planetary Aerial System Challenge'21 Apogee'21, BITS Pilani Campus

## **EXTRA-CURRICULAR**

Machine Learning Contributor Contributing ML blogs to various blog-based companies. Have published 13 blogs. Madras Scientific Research Foundation, NGO Spreading awareness on robotics in schools, amongst unprivileged kids National Service Scheme Active Member of Indian Government sponsored public service program.