

# Optical Communication Using WDM

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Cluster 5: Photonics: Light-based  
Technologies in Everyday Life



# Cosmos Life



# Introduction

Have you wondered how you can send and receive texts from someone miles away from you?

- Optical communication serves as the basis for quick transmissions of data
- Nearly all forms of modern communications involve Wavelength Division Multiplexing (WDM)
  - Combines different colors of light into white light and splits it back up
  - Allows large amounts of data to be transmitted at once



## Main Goal

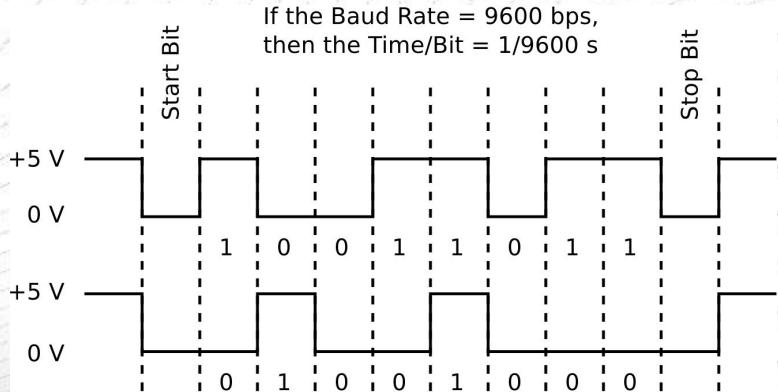
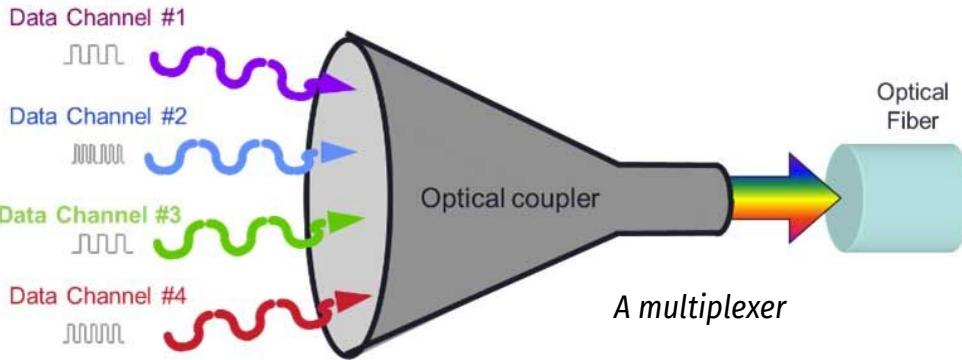
**Test the efficiency of a free-space Wavelength Division Multiplexing system  
and the impact the length of a message has on the accuracy and speed of  
transmission.**

# Key Concepts



## **Multiplexer/Demultiplexer:**

**Component of WDM system that combines or separates different wavelengths of optical signals to be sent and received through a single channel, usually optical fiber**

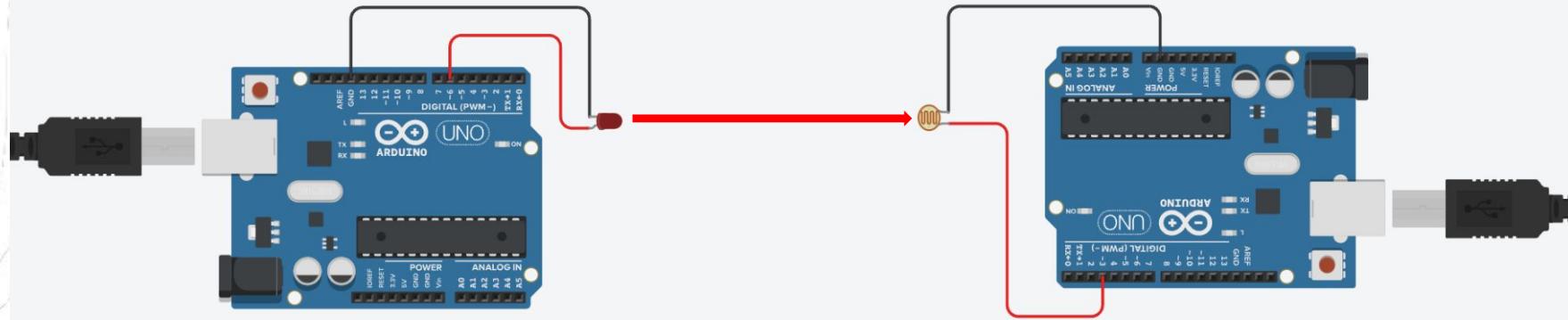


## **Wavelength: Determines color and energy of a light wave**

## **Modulation: The way waves are manipulated**

**Photoresistor:** Sensor whose resistance varies with the amount of light on its surface

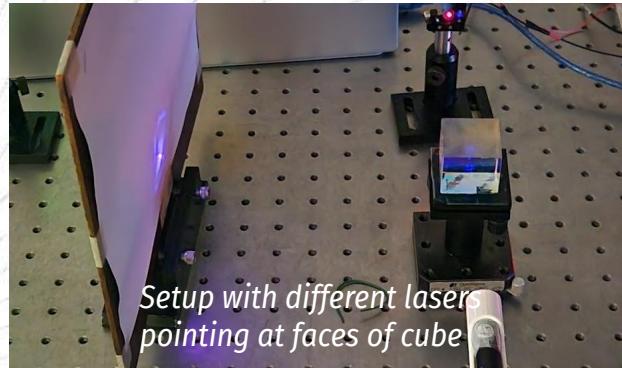
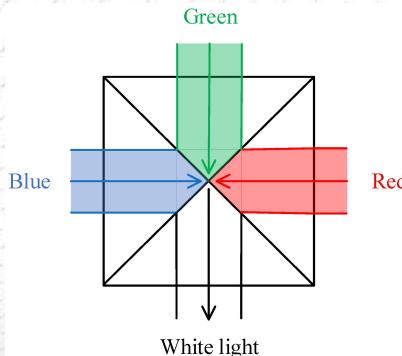
# Basic Principle: One-Beam System



- Instead of a wired connection, our setup uses pulses from a laser diode
- Received by light sensor
- Challenges: alignment, signal interpretation, obstruction

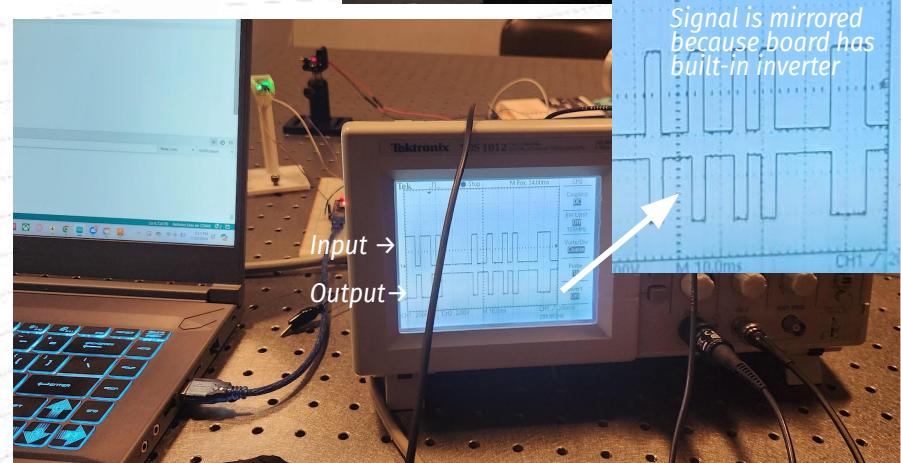
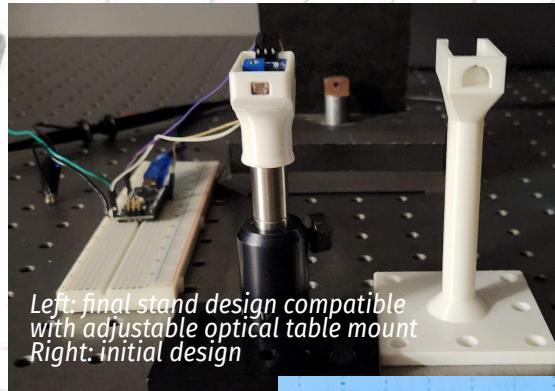
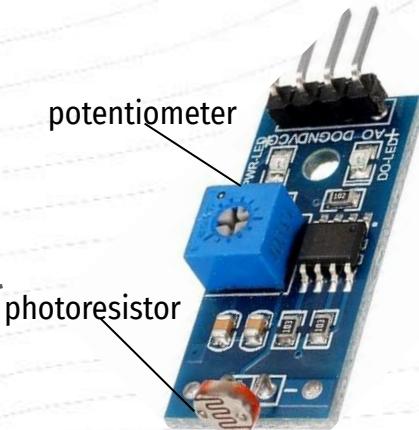
# Methodology: Beam Splitting

- Used trichroic prism
  - Combines and splits beams of different colors
- Red, green, and blue combine to make white light
- Prism has coatings/materials to split beam at right angles



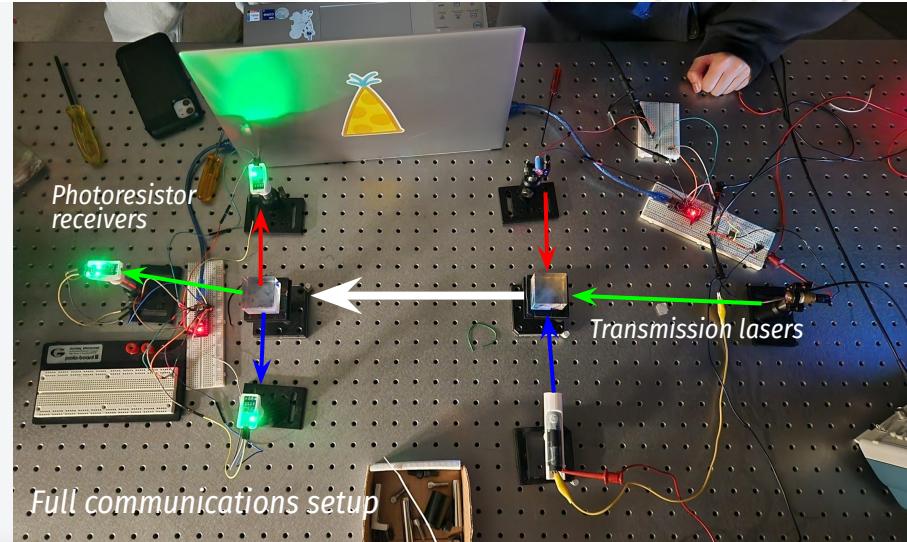
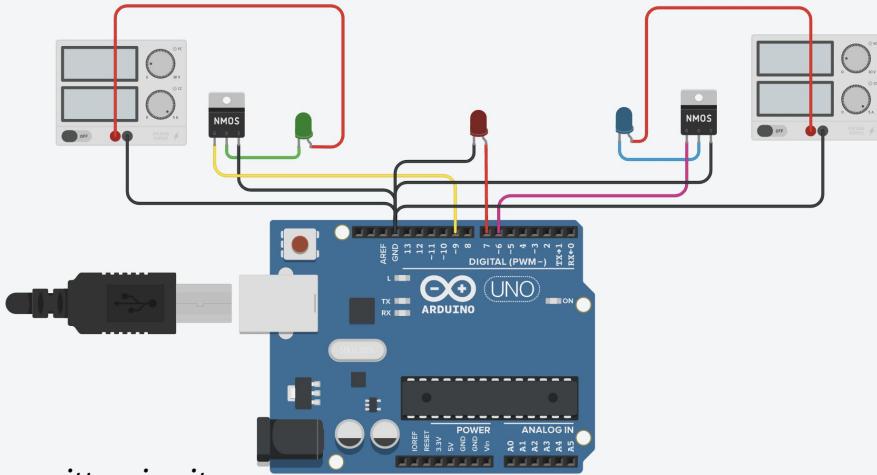
# Methodology: Receiving

- Used digital photoresistor board to convert optical pulses to digital signal (on/off)
- Sensor contains potentiometer to adjust on threshold
  - Can tune for different wavelengths and intensities
- Designed + 3D printed stands to hold sensors steadily
- Viewed sensor output on oscilloscope



Oscilloscope reading after tuning potentiometer

# Setup: Three-Beam System



- Needed power supply and MOSFET to control green and blue lasers because of Arduino current limit
- Challenges: leveling the lasers and combining them into one beam of white light, ensuring that the blue and green laser diodes don't receive too much power

# Communication Protocol

Time-Based: Each character is mapped to its ASCII code, and a pulse of a certain time is given to this character. We add a delay of 50 milliseconds for each character to ensure that even if there is a delay, it accurately reads in the time.

- Example: The character ‘A’ has an ASCII code of 65. Through processing:  $(65 - 32 + 1) * 50 = 1700$  ms. Thus to transmit the character A, we send a laser pulse of 1700 ms

Serial-Based: We used the built in serial communication on Arduino. This data is read at a rate of  $1/(baud\ rate)$  per second on the other Arduino. In our case we use a 300 baud rate.

- Asynchronous vs Synchronous Serial Communication

**ASCII TABLE**

Decimal	Hex	Char	Decimal	Hex	Char	Decimal	Hex	Char
0	00	NULL OR SPACES	32	20	DATA	44	2C	+
1	01	START OF TEXT	33	21	!	45	2D	*
2	02	END OF TRANSMISSION	34	22	,	46	2E	,
3	03	ACKNOWLEDGE	35	23	<	47	2F	<
4	04	ACKNOWLEDGE	36	24	>	48	30	>
5	05	ACKNOWLEDGE	37	25	=	49	31	=
6	06	ACKNOWLEDGE	38	26	?	50	32	?
7	07	ACKNOWLEDGE	39	27	;	51	33	;
8	08	ACKNOWLEDGE	40	28	:	52	34	:
9	09	ACKNOWLEDGE	41	29	,	53	35	,
10	0A	ACKNOWLEDGE	42	2A	.	54	36	.
11	0B	ACKNOWLEDGE	43	2B	‘	55	37	‘
12	0C	ACKNOWLEDGE	44	2C	’	56	38	’
13	0D	ACKNOWLEDGE	45	2D	;	57	39	;
14	0E	ACKNOWLEDGE	46	2E	:	58	3A	:
15	0F	ACKNOWLEDGE	47	2F	=	59	3B	=
16	10	ACKNOWLEDGE	48	30	?	60	3C	?
17	11	ACKNOWLEDGE	49	31	:	61	3D	:
18	12	ACKNOWLEDGE	50	32	,	62	3E	,
19	13	ACKNOWLEDGE	51	33	,	63	3F	,
20	14	DEVICE CONTROL	52	34	+	64	40	+
21	15	SYNCHRONOUS GLUE	53	35	,	65	41	,
22	16	SYNCHRONOUS GLUE	54	36	:	66	42	:
23	17	SYNCHRONOUS GLUE	55	37	=	67	43	=
24	18	SYNCHRONOUS GLUE	56	38	?	68	44	?
25	19	END OF MESSAGE	57	39	:	69	45	:
26	1A	SYNCHRONOUS GLUE	58	3A	,	70	46	,
27	1B	SYNCHRONOUS GLUE	59	3B	:	71	47	:
28	1C	SYNCHRONOUS GLUE	60	3C	=	72	48	=
29	1D	SYNCHRONOUS GLUE	61	3D	?	73	49	?
30	1E	SYNCHRONOUS GLUE	62	3E	:	74	4A	:
31	1F	SYNCHRONOUS GLUE	63	3F	,	75	4B	,

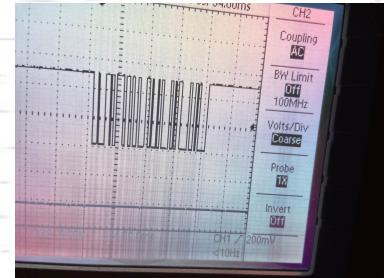
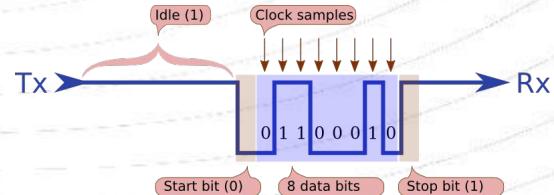


Image of Serial-Based Pulsing for “bob”

# Single Beam System - Code for Time-Based Pulsing:

Initialize variables and pinouts

Read and traverse the data  
from Serial

Map each character to a laser  
pulse that has a timer

Laser Diode

Photoresistor

Initialize variables and  
pinouts

Read the time to pulse and  
convert this to a character,  
with leeway added in

# Single Beam System - Code for Serial-Based Pulsing:

Initialize variables and pinouts

Read and traverse the data  
from Serial

Use an additional programmed serial  
to transmit data over built in Arduino  
Serial

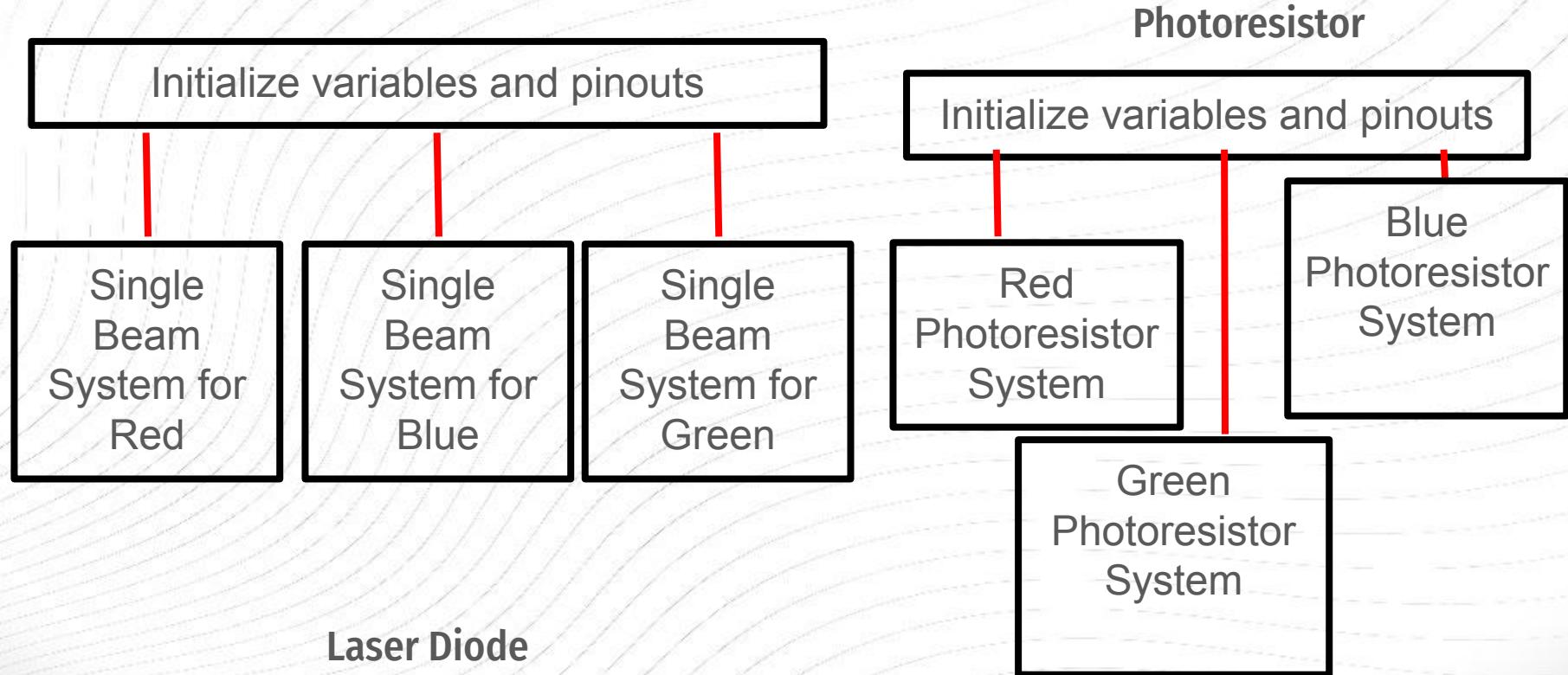
Laser Diode

Photoresistor

Initialize variables and  
pinouts

Each read byte transmitted  
is converted back to its  
ASCII Code value, thus a  
character

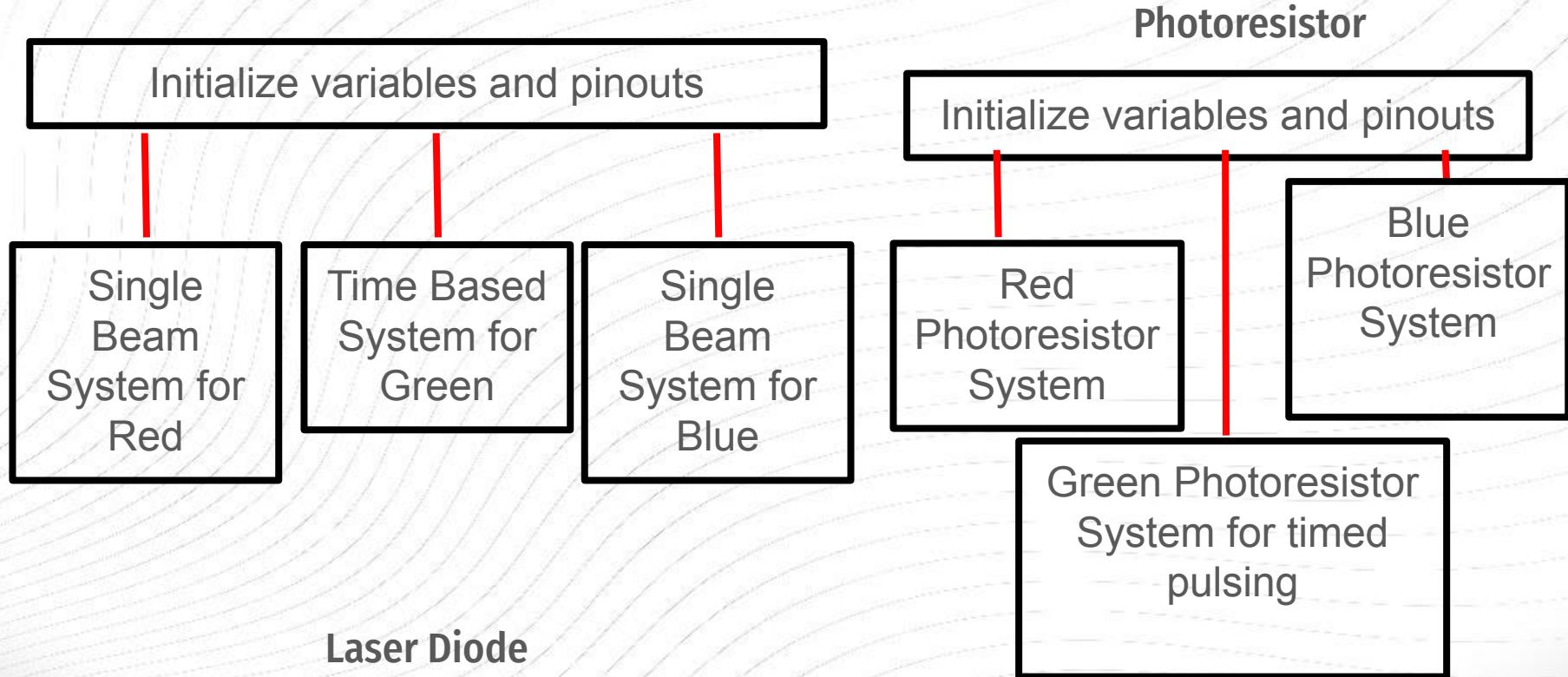
# Three Beam System - Code for Serial-Based Pulsing:



# Challenges

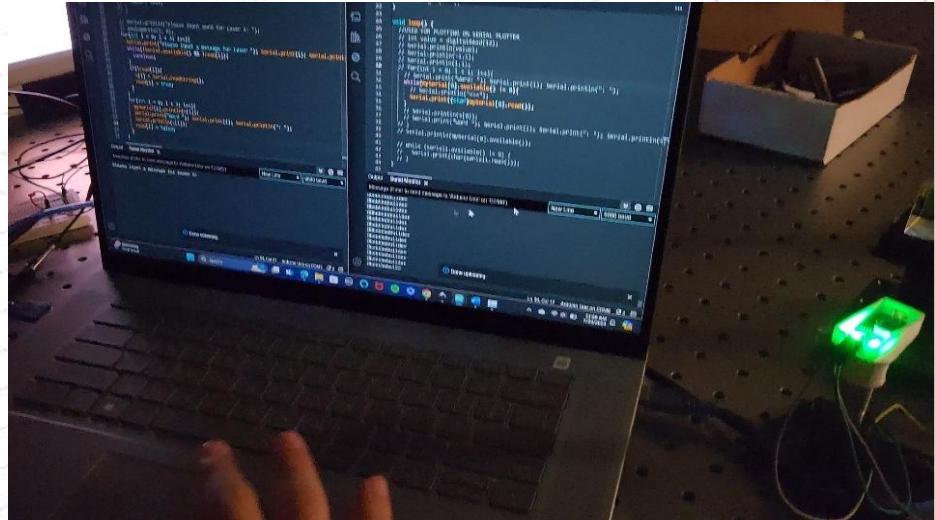
- **Precision**
  - Varies with calibration, power supplied to laser, small changes to position of equipment
- **Communication Protocol**
  - Unable to implement serial on green laser
  - Created own time-based protocol at cost of speed
- **Hardware limitations**
  - Arduino can only send one serial signal at a time
  - Not “true” WDM, but would be if using multiple arduinos for simultaneous serial transmission

# Three Beam System - Corrected Version:



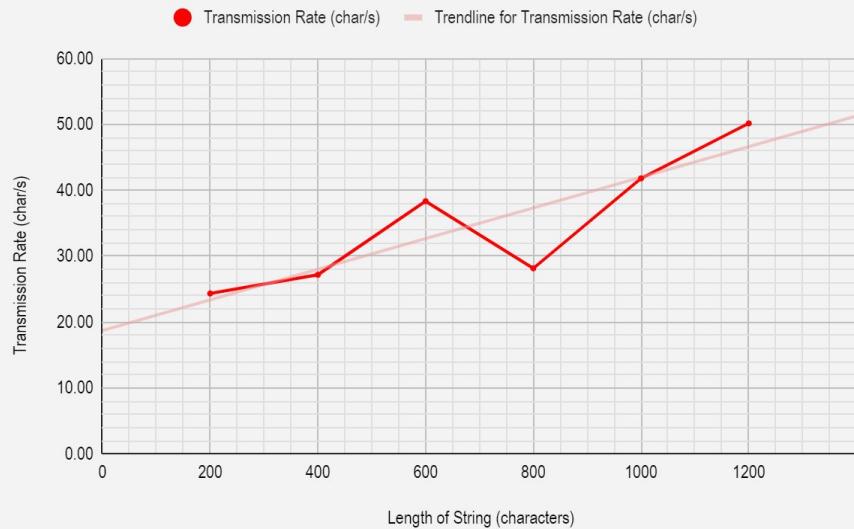
# Testing: Transmission Speed

- Timed the duration from sending message to completely receiving
- Calculated transmission rate  
(number of characters/total time)
- Sent messages from 200-1000 characters (200 char intervals)



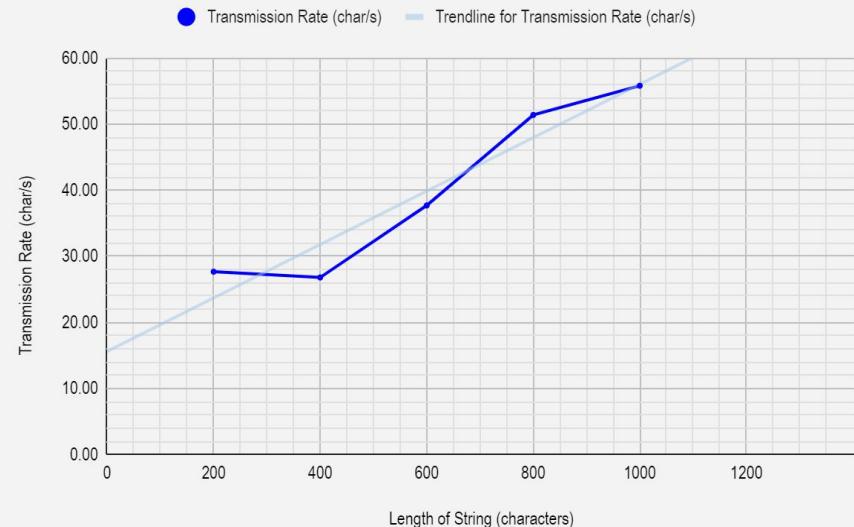
## Effect of String Length on Transmission Speed

Red Laser Channel



## Effect of String Length on Transmission Speed

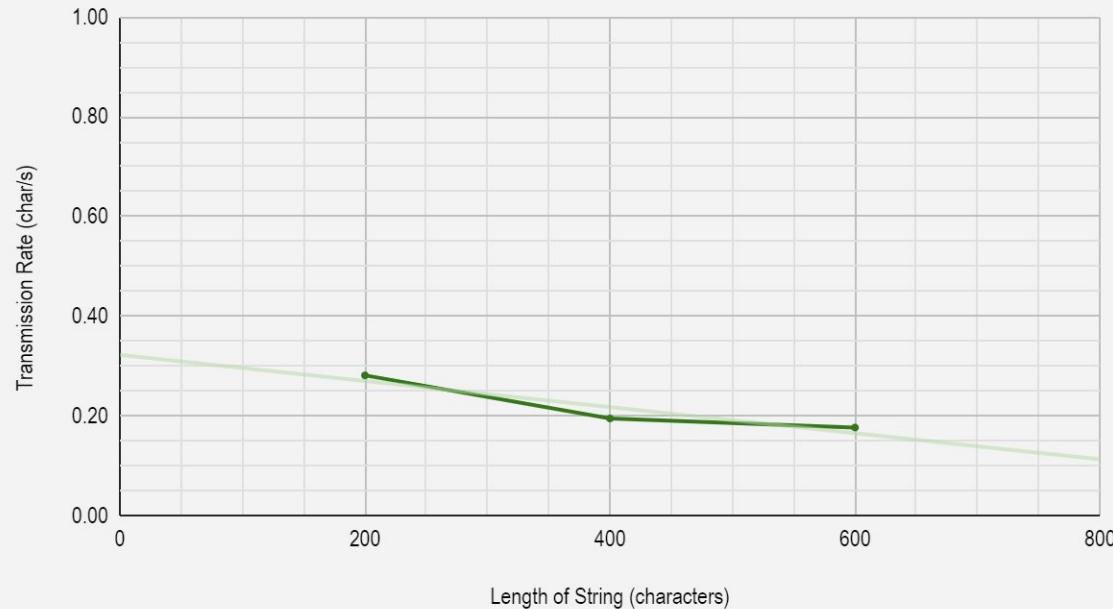
Blue Laser Channel



## Effect of String Length on Transmission Speed

Green Laser Channel

● Transmission Rate (char/s)    └ Trendline for Transmission Rate (char/s)



# Analysis: Transmission Speed

- Red and blue channels increased in rate as character count increased
  - Implies large fixed delay
  - Each additional character has less effect on duration
  - Hardware considerations: arduino, diode
  - Rate of change of characters per second per character was higher for blue
- Green channel remained slow
  - Since each character is a unique pulse length, transmission is slow
  - Very small rate of change

Average transmission speed (characters per second): Red - 34.99, Green - 0.22, Blue - 39.87

# Testing: Accuracy

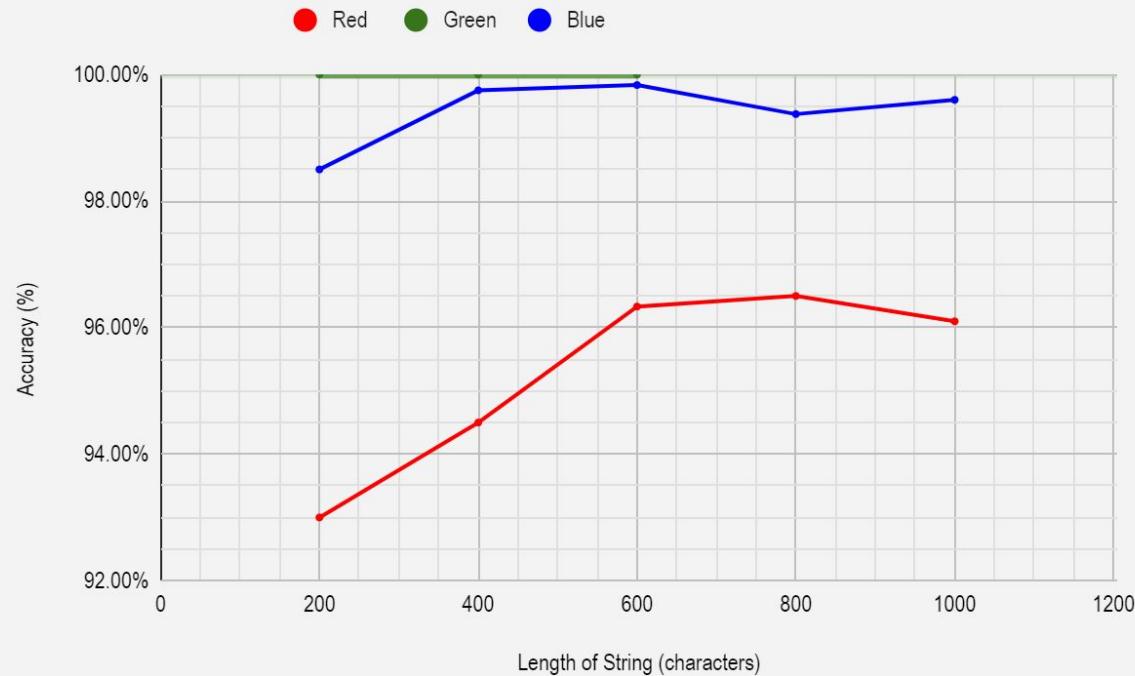
- Generated text with recognizable words
- Found number of changes from received text compared to original string
- Counts mutations, additions, subtractions
- Calculated accuracy rate:  $(\text{length of original string} - \# \text{ of errors})/\text{length}$

1 Jayden was a creature of habit, his days a predictable rhythm of coffee, code, and the occasional video game. Winter was a whirlwind, her laughter a contagious melody that disrupted the quietude of his existence. They met in the most mundane of places - the office coffee machine. A spilled cup and a shared laugh later, they found themselves drawn to each other like two magnets. Winter's world was a kaleidoscope of colors, her spirit as vibrant as the sunsets she adored. Jayden, in his grayscale world, found himself drawn to her warmth. Slowly, he began to see the world through her eyes, discovering hidden beauty in the ordinary. With Winter, every day was an adventure, a departure from the familiar. Their connection deepened with each shared moment. They explored hidden city corners, discove

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## Effect of String Length on Message Accuracy

All Channels



# Analysis: Accuracy

- **Text intelligible**
  - Always above 92% accuracy
  - Red channel tended to get more accurate over time, avg. 95%
- **Green and Blue channels**
  - Green and blue tended to stay consistent, green was always 100%, and blue averaged at 99%
- Very little disturbance in open air
- Likely would not vary with distance; subject of further investigation
- Error correction not implemented, but existing performance sufficient to be corrected

# Conclusion

- **WDM optical communication is a very complex and precise method**
  - We needed to make work arounds because certain lasers were not precise enough
  - Spent a lot of time aligning and combining lasers
- **Different communication protocols have their own benefits**
  - Blue and Red lasers implemented serial based pulsing which is very fast but also has more errors
  - Green laser implemented time based pulsing which gave 100% accurate but was very very slow
- **Our system is not perfect and has a lot of flaws and limitations**
  - The lasers were not made to do optical communication
  - Made the most of what we had and implemented many work arounds
- **Other things we hope to test: how disturbances like water and dust affect the transmission**

# Acknowledgements

Thank you to our...

**Professors: Dr. Sahar, Dr. Tu, and Dr. Ilinykh**

**Teacher Fellow: Mr. Barrows**

**TAs: Karl, Daniel, and Jay**

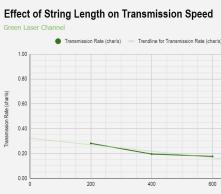
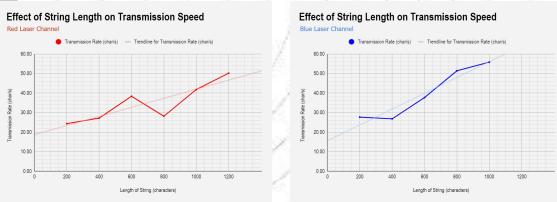
**And all of our classmates!**

## Arduino Code

Transmission Code      Receiver Code

\*Receiver code is the same for the 3 different Arduinos, only pin number changes.

Data



# Optical Communications

By: Jerry, Jeremy, Timothy, Alicia

## Goal

Test the efficiency of a free-space Wavelength Division Multiplexing system and the impact the length of a message has on the accuracy and speed of transmission.

## Background

Optical communication serves as the basis for quick transmissions of data like texting. Currently, almost all optical communications involve Wavelength Division Multiplexing (WDM) which allows large amounts of data to be sent through a single optical beam by splitting and combining different wavelengths of light.

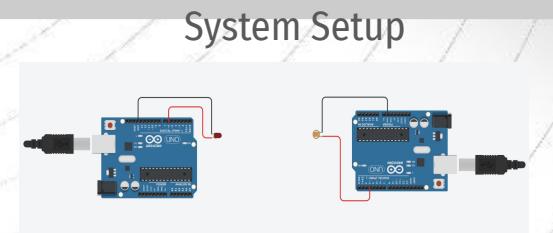


Diagram of one laser test system.  
Left is the laser connected to Arduino.  
Right is a photoresistor connected to  
arduino.

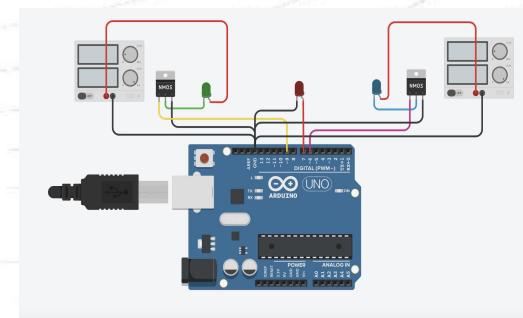
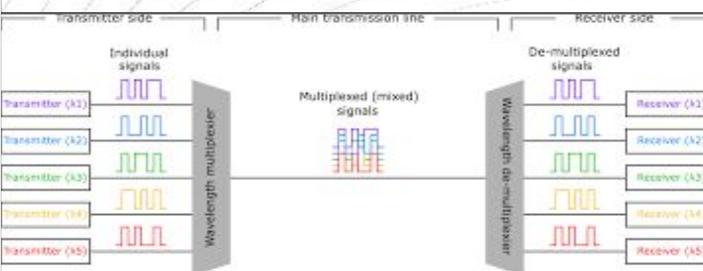
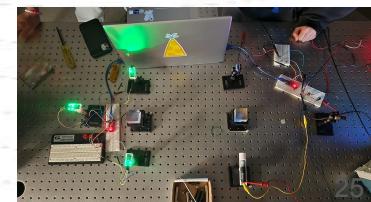


Diagram 3 laser transmission system.  
Receiver system is same as before.



Picture of final setup: laser diode on right, photoresistors on left



Code:



[jerry-zh0u/COSMOSCommProject](https://github.com/jerry-zh0u/COSMOSCommProject)  
([github.com](https://github.com))

# References

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[https://www.sciencedirect.com/science/article/abs/pii/S0030401818310265?casa\\_token=p9gwnOFNDmQAAAAA:Wx2jiIHhctB5nAwSfjvm6t9LDyf62GOswijvogUP65v7vGxRX09MDox5zgDw6CydpCPeB3j1EA](https://www.sciencedirect.com/science/article/abs/pii/S0030401818310265?casa_token=p9gwnOFNDmQAAAAA:Wx2jiIHhctB5nAwSfjvm6t9LDyf62GOswijvogUP65v7vGxRX09MDox5zgDw6CydpCPeB3j1EA)