## Hsiang-Jui Lin

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## Academic Record

2012-2016 National Taiwan University, Bachelor of Computer Science and Information Engineering

2017-2021 National Taiwan University, Master of Computer Science and Information Engineering

Tasks: System Programming course TA (2016-2017)

# Work Experience

2010 - 2016 Software Developer at CAVEDU教育團隊

Tasks: AppInventor project, Author of LeJOS tutorial book

2016 Jul. - 2017 Jul. Substitute Military Service at 臺灣盲人重建院

Tasks: General affairs, develop automatic official documents image to text

2018 Jun. - 2019 Jun. R&D Assistant at Microsoft Taiwan

Tasks: Bing's Reverse Geocoder backend development

2021 Sep. - 2021 Sep. R&D Assistant at ADLINK Technology Inc.

Tasks: Develop distributed decision using Zenoh

# Projects and Publications

graph theory (2016)

Author of 機器人程式設計 A book introduces leJOS (http://www.lejos.org/) framework on LEGO NXT robots.

*與實作: 使用 Java book* ISBN: <u>9789862768228</u>

(2013) (http://isbn.ncl.edu.tw/NCL\_ISBNNet

 $/main\_DisplayRecord.php?PHPSESSID=c8kchinqo5ncq873i47c4sqkb0\&Pact=Display\&Pstart=1)$ 

MIT AppInventor project Task: Focus on robotic related features WYSIWYG Android programming

(2016 - 2018) Developed Lego EV3 (link (https://github.com/mit-cml/appinventor-sources/pull/729)) and

 $Media Tek\ MT7697\ \underline{link}\ (https://github.com/mit-cml/appinventor-extensions/pull/12)\ features.$ 

**Undergraduate study on** The study focuses on total and paired domination problems on distance-hereditary graph.

Discovered an alternative optimal solution to total domination based on split decomposition. The handout can be found in the <u>link</u>

(https://drive.google.com/file/d/18H1fvSZ7td3vArSJaeoTKkLjJ-DqApaP/view?usp=sharing).

**TorFS (2019)** It's a side project that exploits free storage from Tor's Onion service.

We successfully built a virtual file system that stores data blocks into RSA public keys, and

distributed them to the rest of Onoin network.

The repository can be found in the <u>link</u> (https://github.com/jerry73204/cns-final-tor-store).

Hacky Arm (2020)

A side project to design a robotic arm capable of grabbing objects using RealSense. It combines computer vision and position estimation of objects using Intel RealSense depth camera, and instructs the arm to grab objects accordingly.

The repository can be found in the <u>link</u> (https://github.com/jerry73204/hacky-arm).

Wayside (2019-2021)

The lab project develops a complete data processing system for Taiwanese traffic scenes. The tasks conver the data collection, sensor hardware design, data format design and pipelining and data analysis. It aims to combine the data from cameras and LiDARs, and develop fusing algorithms to get the best of the both sensors.

The reference information can be found in the <u>page</u> (https://newslabntu.github.io/DanielFolio/projects/3\_project/).

typ (2020) A side project to develop the type level programming language for Rust.

It achieves compile-time, type-level arithmetic computations. It was developed to pave the way for building type-safe tensor types in Rust. The repository can be found in the <u>link</u>

(https://github.com/jerry73204/typ).

par-stream (2020) A side project to develop building blocks of asynchronous parallel stream for Rust. It

provides high-level stream types with parallelism and asynchronous programming in mind. The repository can be found in the <u>link</u> (https://github.com/jerry73204/par-stream).

#### Honors & Awards

104 年金盾獎 2nd place (2015) Reference 行政院國家資通安全會報

s=60F37FB45AC653BD)

102 年金盾獎 潛力無窮

獎 (2013)

Reference Web archive for official site

(https://web.archive.org/web/20140321005458/http://security.cisanet.org.tw:80/?i=3&mc=302)