4. Fully-Connected Deep Networks

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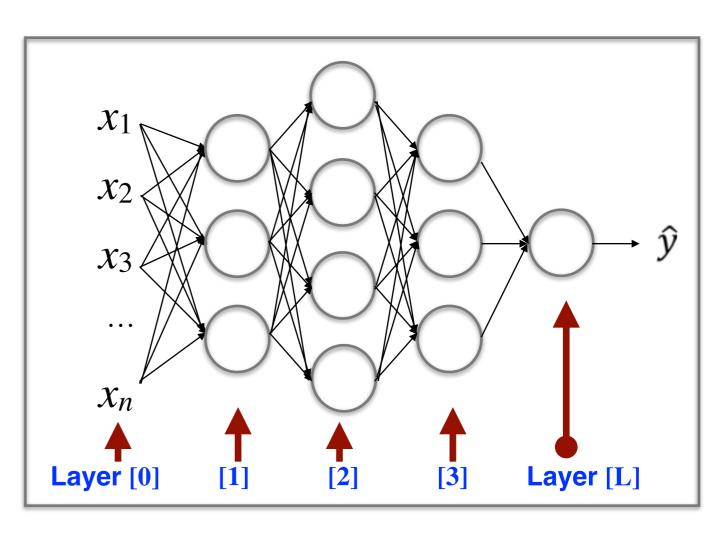
· Choosing the right optimizer will speed up the efficiency of computation.

4.1 << Batch Gradient Descent >> : using the entire training dataset

$$X = [x^{(1)} \ x^{(2)} \ x^{(3)} \ \cdots \ x^{(m)}] : feature data, dim = (n, m)$$
 $Y = [y^{(1)} \ y^{(2)} \ y^{(3)} \ \cdots \ y^{(m)}] : target (labeled data), dim = (1, m)$

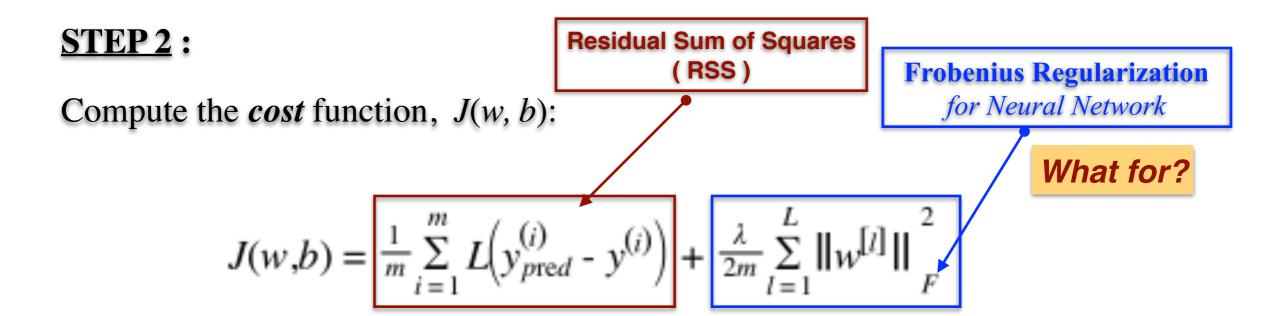
STEP 1:

Forward propagation on X using vectorization:



4.1 << Batch Gradient Descent >>

(cont'd)



STEP 3:

Back propagation to compute **gradients** with respect to J(w, b):

Ref: Andrew Ng, "15. Vectorization" https://youtu.be/9YHWgxwzwD8

4.1 << Batch Gradient Descent >>

(cont'd)

One epoch computation passing through the entire training dataset:

{

STEP 1:

Forward propagation on X using vectorization

STEP 2:

Compute the **cost** function,
$$J(w,b) = \frac{1}{m} \sum_{i=1}^{m} L(y_{pred}^{(i)} - y_{pred}^{(i)}) + \frac{\lambda}{2m} \sum_{l=1}^{L} ||w_{pred}^{[l]}||_{F}^{2}$$

STEP 3:

Back propagation to compute **gradients** with respect to J(w, b)

}

[NEXT]: Running a number of epochs till the approximation converged.

4.2 << Mini-Batch Gradient Descent >>

Q: But what if m = 5,000,000? (A huge training data size...) Batch Gradient Descent Optimizer will slow down processing.

A: Splitting the entire training dataset into the "mini-batch" training datasets:

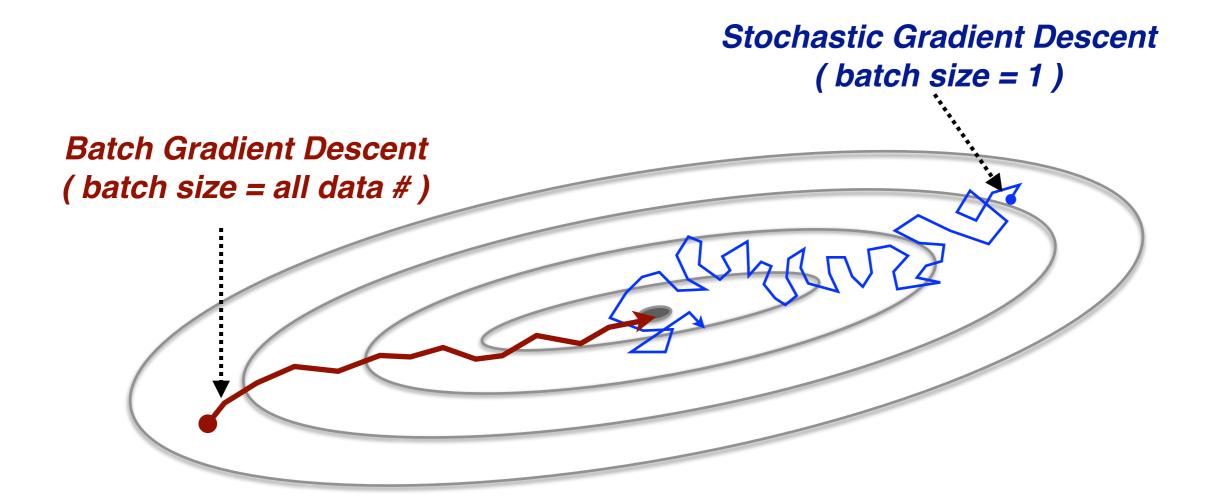
$$X = \begin{bmatrix} x^{(1)} & x^{(2)} & \cdots & x^{(1000)} \\ x^{(1)} & x^{(2)} & \cdots & x^{(2000)} \\ x^{(2)} & x^{(2)} & \cdots & x^{(5000)} \end{bmatrix} : dim = (n, 5,000,000)$$

$$Y = \begin{bmatrix} y^{(1)} & y^{(2)} & \cdots & y^{(1000)} \\ y^{(1001)} & y^{(2000)} & \cdots & y^{(m)} \end{bmatrix} : dim = (1, 5,000,000)$$

$$y^{(1)} & y^{(2)} & \cdots & y^{(5000)} \end{bmatrix} : mini-batches$$

- => **5000 mini-batches** with 1000 samples/ mini-batch
- => "Mini-Batch Gradient Descent" Optimizer

Mini-Batch Gradient Descent => batch size = 64, 128, 256 or 512



Stochastic vs. Batch Gradient Descent

4.3 Cost Functions for Logistic Regression

(Ref: "Cross entropy" from Wikipedia, https://en.wikipedia.org/wiki/Cross_entropy)

Binary Cross Entropy — for Binary Classifier

Loss Function : $p \in \{y, 1-y\}$ and $q \in \{\hat{y}, 1-\hat{y}\}$

$$L(p,q) \ = \ - \sum_i p_i \log q_i \ = \ - y \log \hat{y} - (1-y) \log (1-\hat{y})$$

Binary Classifier: y = 0 or 1 (Sigmoid Function)

$$\begin{cases} y = 0: & L = -\log(1 - \hat{y}) \\ y = 1: & L = -\log \hat{y} \end{cases}$$

4.3 Cost Functions for Logistic Regression

(cont'd)

(Ref: "Cross entropy" from Wikipedia, https://en.wikipedia.org/wiki/Cross_entropy)

Categorical Cross Entropy — for Multiple-Output Classifier

Cost Function:

$$J(\mathbf{w}) \ = \ rac{1}{N} \sum_{n=1}^{N} L(p_n, q_n) \ = \ - rac{1}{N} \sum_{n=1}^{N} \left[y_n \log \hat{y}_n + (1-y_n) \log (1-\hat{y}_n)
ight]$$

Multiple-Output Classifier: Activation Function - Softmax

$$\sigma(\mathbf{z})_j = rac{e^{z_j}}{\sum_{k=1}^K e^{z_k}}$$
 for j = 1, ..., K .

(Ref. "Softmax" from Wikipedia, https://zh.wikipedia.org/wiki/Softmax%E5%87%BD%E6%95%B0)

4.4 Activation Functions

Sigmoid Function

• tanh Function

• ReLU Function (Rectifier Linear Unit)

Leaky ReLU

Softmax

4.5 Faster Gradient Descent Algorithms for Optimization

[Concept] : Exponentially Weighted Moving Average

— https://youtu.be/IAq96T8FkTw

< Optimizer > : Gradient Descent with Momentum

https://youtu.be/k8fTYJPd3_I

< Optimizer > : RMSProp Optimization Algorithm

https://youtu.be/_e-LFe_igno

< Optimizer > : Adam Optimization Algorithm

https://youtu.be/JXQT_vxqwls

4.6 Hyperparameter Tuning Process

- learning rate (a)
- momentum term (β)
- numbers of hidden layers
- numbers of hidden units (i.e., neurons)
- learning-rate decay
- mini-batch size

```
[ Tuning Rules for Hyperparameters ] :
```

- Try random values for hyperparameters : Don't use a grid.
- Coarse to Fine (https://youtu.be/AXDByU3D1hA)
- Using an Appropriate Scale (https://youtu.be/cSoK_6Rkbfg)

Advanced Topics

Batch Normalization & Swish Activation

Batch Normalization

- · 在 Neural Networks 開始訓練之前,通常會對輸入資料進行 normalization (正規化) 的前置處理;原因是這樣一來,將會提升 Neural Networks 的訓練效能。
- · 因此,如果能夠針對 Deep Neural Networks 的各個隱藏層 (hidden layers) 的輸入資料進行 batch normalization (批次正規化) 處理,除了增加效能之外,甚至於無須擔心 overfitting 的問題 (亦即,無須進行 dropout 或 regularization 修正)。

[REFERENCE]

- 1. "Fitting Batch Norm Into Neural Networks (C2W3L05)" https://youtu.be/nUUqwaxLnWs
- 2. "Why Does Batch Norm Work? (C2W3L06)" https://youtu.be/nUUqwaxLnWs
- 3. "Batch Normalization": http://violin-tao.blogspot.com/2018/02/ml-batch-normalization.html
- 4. "Advanced Tips for Deep Learning," Hung-yi Lee https://www.csie.ntu.edu.tw/~yvchen/f106-adl/doc/171116+171120_Tip.pdf

Swish Activation

[Activation Functions]:

- 1. Sigmoid Function
- 2. Relu Function
- 3. tanh Function
- 4. Softmax Function
- 5. Swish Function



Ref: "Experiments with SWISH activation function on MNIST dataset"

https://medium.com/@jaiyamsharma/experiments-with-swish-activation-function-on-mnist-dataset-fc89a8c79ff7