< Deep Learning - PART2 TF2 CNNs > ¶

Ch 5. CNNs Workshop 7 - ResNet on CIFAR10

2021/10/01

'2.2.0'

[REFERENCE]:

- 1. "Trains a ResNet on the CIFAR10 dataset."

 https://keras.io/zh/examples/cifar10_resnet/

 (https://keras.io/zh/examples/cifar10_resnet/)
- 2. ResNet v1: Deep Residual Learning for Image Recognition https://arxiv.org/pdf/1512.03385.pdf (<a href="https://arxiv.org/pd
- 3. ResNet v2: Identity Mappings in Deep Residual Networks https://arxiv.org/pdf/1603.05027.pdf (https://arxiv.org/pdf/ (https://arxiv.org/pdf/<a

[NOTE]: Run this program on Google Colab (or Kaggle) with GPU setting.

```
In [1]:

1 import tensorflow as tf
2 tf.__version__
Out[1]:
```

```
In [2]:
```

```
from __future__ import print_function

from tensorflow.keras.layers import Dense, Conv2D, BatchNormalization, Acti
from tensorflow.keras.layers import AveragePooling2D, Input, Flatten
from tensorflow.keras.optimizers import Adam
from tensorflow.keras.callbacks import ModelCheckpoint, LearningRateSchedul
from tensorflow.keras.callbacks import ReduceLROnPlateau
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras.regularizers import 12
from tensorflow.keras.models import Model
from tensorflow.keras.models import Model
from tensorflow.keras.datasets import cifar10
import numpy as np
import os
```

In [3]:

```
# Training parameters
batch_size = 32  # orig paper trained all networks with batch_size=128
# epochs = 200
epochs = 30
data_augmentation = True
num_classes = 10

# Subtracting pixel mean improves accuracy
subtract_pixel_mean = True
```

In [4]: ▶

```
1 # Model parameter
 2 # -----
3 # | | 200-epoch | Orig Paper| 200-epoch | Orig Paper| sec/ep
          | n | ResNet v1 | ResNet v1 | ResNet v2 | ResNet v2 | GTX108
 5 # |v1(v2)| %Accuracy | %Accuracy | %Accuracy | v1 (v2
 6 # -----
14 | # -----
15 n = 3
16
17 # Model version
18 # Orig paper: version = 1 (ResNet v1), Improved ResNet: version = 2 (ResNet
19 version = 1
20
21 # Computed depth from supplied model parameter n
22 if version == 1:
23 depth = n * 6 + 2
24 elif version == 2:
25 depth = n * 9 + 2
26
27 # Model name, depth and version
28 model_type = 'ResNet%dv%d' % (depth, version)
```

In [5]:

```
1 # Load the CIFAR10 data.
 2 (x_train, y_train), (x_test, y_test) = cifar10.load_data()
 4 # Input image dimensions.
 5 input_shape = x_train.shape[1:]
 7 # Normalize data.
 8 x_train = x_train.astype('float32') / 255
 9 | x_test = x_test.astype('float32') / 255
10
11 # If subtract pixel mean is enabled
12 if subtract_pixel_mean:
13
       x_train_mean = np.mean(x_train, axis=0)
14
       x_train -= x_train_mean
       x_test -= x_train_mean
15
16
17 print('x_train shape:', x_train.shape)
18 print(x_train.shape[0], 'train samples')
19 print(x_test.shape[0], 'test samples')
20 print('y_train shape:', y_train.shape)
21
22 # Convert class vectors to binary class matrices.
23 y_train = tf.keras.utils.to_categorical(y_train, num_classes)
24 y_test = tf.keras.utils.to_categorical(y_test, num_classes)
```

In [6]: ▶

```
def lr schedule(epoch):
        """Learning Rate Schedule
 2
 3
 4
        Learning rate is scheduled to be reduced after 80, 120, 160, 180 epochs
 5
        Called automatically every epoch as part of callbacks during training.
 6
 7
        # Arguments
 8
            epoch (int): The number of epochs
 9
10
        # Returns
11
            lr (float32): learning rate
12
13
        lr = 1e-3
        if epoch > 180:
14
            lr *= 0.5e-3
15
        elif epoch > 160:
16
17
            lr *= 1e-3
18
        elif epoch > 120:
19
            lr *= 1e-2
        elif epoch > 80:
20
21
            lr *= 1e-1
22
        print('Learning rate: ', lr)
        return lr
23
24
25
    def resnet_layer(inputs,
26
                     num_filters=16,
27
28
                     kernel_size=3,
29
                     strides=1,
30
                     activation='relu',
31
                     batch_normalization=True,
32
                     conv first=True):
        """2D Convolution-Batch Normalization-Activation stack builder
33
34
35
        # Arguments
36
            inputs (tensor): input tensor from input image or previous layer
37
            num_filters (int): Conv2D number of filters
38
            kernel_size (int): Conv2D square kernel dimensions
            strides (int): Conv2D square stride dimensions
39
40
            activation (string): activation name
41
            batch_normalization (bool): whether to include batch normalization
42
            conv_first (bool): conv-bn-activation (True) or
43
                bn-activation-conv (False)
44
45
        # Returns
            x (tensor): tensor as input to the next layer
46
47
48
        conv = Conv2D(num_filters,
49
                      kernel_size=kernel_size,
50
                      strides=strides,
51
                      padding='same',
                      kernel_initializer='he_normal',
52
                      kernel_regularizer=12(1e-4))
53
54
55
        x = inputs
```

```
56
         if conv first:
 57
             x = conv(x)
 58
             if batch normalization:
 59
                 x = BatchNormalization()(x)
             if activation is not None:
 60
                 x = Activation(activation)(x)
 61
 62
         else:
             if batch normalization:
 63
 64
                 x = BatchNormalization()(x)
 65
             if activation is not None:
                 x = Activation(activation)(x)
 66
 67
             x = conv(x)
 68
         return x
 69
70
    def resnet_v1(input_shape, depth, num_classes=10):
71
72
         """ResNet Version 1 Model builder [a]
73
 74
         Stacks of 2 x (3 x 3) Conv2D-BN-ReLU
 75
         Last ReLU is after the shortcut connection.
 76
         At the beginning of each stage, the feature map size is halved (downsan
 77
         by a convolutional layer with strides=2, while the number of filters is
 78
         doubled. Within each stage, the layers have the same number filters and
 79
         same number of filters.
         Features maps sizes:
 80
         stage 0: 32x32, 16
 81
 82
         stage 1: 16x16, 32
         stage 2: 8x8, 64
 83
 84
         The Number of parameters is approx the same as Table 6 of [a]:
 85
         ResNet20 0.27M
 86
         ResNet32 0.46M
 87
         ResNet44 0.66M
 88
         ResNet56 0.85M
 89
         ResNet110 1.7M
 90
 91
         # Arguments
 92
             input_shape (tensor): shape of input image tensor
 93
             depth (int): number of core convolutional layers
 94
             num_classes (int): number of classes (CIFAR10 has 10)
 95
 96
         # Returns
 97
             model (Model): Keras model instance
 98
99
         if (depth - 2) % 6 != 0:
             raise ValueError('depth should be 6n+2 (eg 20, 32, 44 in [a])')
100
         # Start model definition.
101
102
         num filters = 16
103
         num_res_blocks = int((depth - 2) / 6)
104
         inputs = Input(shape=input_shape)
105
         x = resnet_layer(inputs=inputs)
106
         # Instantiate the stack of residual units
107
108
         for stack in range(3):
             for res_block in range(num_res_blocks):
109
110
                 strides = 1
                 if stack > 0 and res block == 0: # first layer but not first s
111
112
                     strides = 2 # downsample
```

```
113
                 y = resnet layer(inputs=x,
114
                                   num filters=num filters,
115
                                   strides=strides)
                 y = resnet_layer(inputs=y,
116
                                   num_filters=num_filters,
117
118
                                   activation=None)
                 if stack > 0 and res block == 0: # first Layer but not first s
119
                     # linear projection residual shortcut connection to match
120
121
                     # changed dims
122
                     x = resnet_layer(inputs=x,
123
                                       num_filters=num_filters,
124
                                       kernel_size=1,
125
                                       strides=strides,
                                       activation=None,
126
127
                                       batch_normalization=False)
128
                 x = tf.keras.layers.add([x, y])
                 x = Activation('relu')(x)
129
130
             num_filters *= 2
131
132
         # Add classifier on top.
133
         # v1 does not use BN after last shortcut connection-ReLU
134
         x = AveragePooling2D(pool_size=8)(x)
135
         y = Flatten()(x)
136
         outputs = Dense(num_classes,
137
                         activation='softmax',
                         kernel_initializer='he_normal')(y)
138
139
140
         # Instantiate model.
         model = Model(inputs=inputs, outputs=outputs)
141
142
         return model
143
144
    def resnet_v2(input_shape, depth, num_classes=10):
145
         """ResNet Version 2 Model builder [b]
146
147
148
         Stacks of (1 \times 1)-(3 \times 3)-(1 \times 1) BN-ReLU-Conv2D or also known as
149
         bottleneck layer
150
         First shortcut connection per layer is 1 x 1 Conv2D.
         Second and onwards shortcut connection is identity.
151
         At the beginning of each stage, the feature map size is halved (downsan
152
         by a convolutional layer with strides=2, while the number of filter map
153
154
         doubled. Within each stage, the layers have the same number filters and
155
         same filter map sizes.
        Features maps sizes:
156
157
         conv1 : 32x32, 16
158
         stage 0: 32x32, 64
         stage 1: 16x16, 128
159
         stage 2: 8x8, 256
160
161
162
         # Arguments
             input_shape (tensor): shape of input image tensor
163
             depth (int): number of core convolutional layers
164
165
             num_classes (int): number of classes (CIFAR10 has 10)
166
         # Returns
167
168
             model (Model): Keras model instance
169
```

```
170
         if (depth - 2) % 9 != 0:
171
             raise ValueError('depth should be 9n+2 (eg 56 or 110 in [b])')
172
         # Start model definition.
         num filters in = 16
173
         num_res_blocks = int((depth - 2) / 9)
174
175
         inputs = Input(shape=input shape)
176
         # v2 performs Conv2D with BN-ReLU on input before splitting into 2 path
177
178
         x = resnet_layer(inputs=inputs,
                          num filters=num filters in,
179
                          conv_first=True)
180
181
         # Instantiate the stack of residual units
182
         for stage in range(3):
183
184
             for res_block in range(num_res_blocks):
                 activation = 'relu'
185
                 batch_normalization = True
186
187
                 strides = 1
                 if stage == 0:
188
                     num_filters_out = num_filters_in * 4
189
                     if res block == 0: # first layer and first stage
190
191
                         activation = None
192
                         batch_normalization = False
193
                 else:
                     num filters out = num filters in * 2
194
                     if res_block == 0: # first layer but not first stage
195
196
                         strides = 2
                                        # downsample
197
                 # bottleneck residual unit
198
                 y = resnet_layer(inputs=x,
199
200
                                   num_filters=num_filters_in,
201
                                   kernel size=1,
                                   strides=strides,
202
203
                                   activation=activation,
                                   batch_normalization=batch_normalization,
204
                                   conv_first=False)
205
206
                 y = resnet_layer(inputs=y,
                                   num_filters=num_filters_in,
207
208
                                   conv_first=False)
209
                 y = resnet_layer(inputs=y,
210
                                   num_filters=num_filters_out,
211
                                   kernel_size=1,
                                   conv first=False)
212
213
                 if res block == 0:
                     # linear projection residual shortcut connection to match
214
                     # changed dims
215
216
                     x = resnet_layer(inputs=x,
217
                                       num_filters=num_filters_out,
                                       kernel size=1,
218
219
                                       strides=strides,
                                       activation=None,
220
221
                                       batch_normalization=False)
222
                 x = keras.layers.add([x, y])
223
224
             num_filters_in = num_filters_out
225
226
         # Add classifier on top.
```

```
227
         # v2 has BN-ReLU before Pooling
228
        x = BatchNormalization()(x)
229
        x = Activation('relu')(x)
230
         x = AveragePooling2D(pool_size=8)(x)
        y = Flatten()(x)
231
         outputs = Dense(num_classes,
232
233
                         activation='softmax',
                         kernel initializer='he normal')(y)
234
235
         # Instantiate model.
236
237
        model = Model(inputs=inputs, outputs=outputs)
238
         return model
239
240
241
    if version == 2:
         model = resnet_v2(input_shape=input_shape, depth=depth)
242
    else:
243
244
         model = resnet_v1(input_shape=input_shape, depth=depth)
245
246
    model.compile(loss='categorical_crossentropy',
                   optimizer=Adam(lr=lr_schedule(0)),
247
                   metrics=['accuracy'])
248
    model.summary()
249
    print(model_type)
250
```

```
Learning rate:
               0.001
Model: "model"
Layer (type)
                              Output Shape
                                                  Param #
Connected to
_____
input_1 (InputLayer)
                              [(None, 32, 32, 3)] 0
conv2d (Conv2D)
                              (None, 32, 32, 16)
                                                  448
input_1[0][0]
batch normalization (BatchNorma (None, 32, 32, 16)
                                                  64
conv2d[0][0]
activation (Activation)
                              (None, 32, 32, 16)
batch_normalization[0][0]
conv2d_1 (Conv2D)
                              (None, 32, 32, 16)
                                                  2320
activation[0][0]
batch_normalization_1 (BatchNor (None, 32, 32, 16)
                                                  64
conv2d_1[0][0]
```

activation_1 (Activation) batch_normalization_1[0][0]	(None,	32,	32,	16)	0
conv2d_2 (Conv2D) activation_1[0][0]	(None,	32,	32,	16)	2320
batch_normalization_2 (BatchNor conv2d_2[0][0]	(None,	32,	32,	16)	64
add (Add) activation[0][0]	(None,	32,	32,	16)	0
<pre>batch_normalization_2[0][0]</pre>					
activation_2 (Activation) add[0][0]	(None,	32,	32,	16)	0
conv2d_3 (Conv2D) activation_2[0][0]	(None,	32,	32,	16)	2320
batch_normalization_3 (BatchNor conv2d_3[0][0]	(None,	32,	32,	16)	64
activation_3 (Activation) batch_normalization_3[0][0]	(None,	32,	32,	16)	0
conv2d_4 (Conv2D) activation_3[0][0]	(None,	32,	32,	16)	2320
batch_normalization_4 (BatchNor conv2d_4[0][0]	(None,	32,	32,	16)	64
add_1 (Add) activation_2[0][0]	(None,	32,	32,	16)	0
<pre>batch_normalization_4[0][0]</pre>					
activation_4 (Activation) add_1[0][0]	(None,	32,	32,	16)	0
conv2d_5 (Conv2D) activation_4[0][0]	(None,	32,	32,	16)	2320

<pre>batch_normalization_5 (BatchNor conv2d_5[0][0]</pre>	(None,	32,	32,	16)	64
activation_5 (Activation) batch_normalization_5[0][0]	(None,	32,	32,	16)	0
conv2d_6 (Conv2D) activation_5[0][0]	(None,	32,	32,	16)	2320
batch_normalization_6 (BatchNor conv2d_6[0][0]	(None,	32,	32,	16)	64
add_2 (Add) activation_4[0][0]	(None,	32,	32,	16)	0
<pre>batch_normalization_6[0][0]</pre>					
activation_6 (Activation) add_2[0][0]	(None,	32,	32,	16)	0
conv2d_7 (Conv2D) activation_6[0][0]	(None,	16,	16,	32)	4640
batch_normalization_7 (BatchNor conv2d_7[0][0]	(None,	16,	16,	32)	128
activation_7 (Activation) batch_normalization_7[0][0]	(None,	16,	16,	32)	0
conv2d_8 (Conv2D) activation_7[0][0]	(None,	16,	16,	32)	9248
conv2d_9 (Conv2D) activation_6[0][0]	(None,	16,	16,	32)	544
batch_normalization_8 (BatchNor conv2d_8[0][0]	(None,	16,	16,	32)	128
add_3 (Add) conv2d_9[0][0]	(None,	16,	16,	32)	0
batch_normalization_8[0][0]					
activation_8 (Activation)	(None,	16,	16,	32)	0

conv2d_10 (Conv2D) activation_8[0][0]	(None,	16,	16,	32)	9248
batch_normalization_9 (BatchNor conv2d_10[0][0]	(None,	16,	16,	32)	128
activation_9 (Activation) batch_normalization_9[0][0]	(None,	16,	16,	32)	0
conv2d_11 (Conv2D) activation_9[0][0]	(None,	16,	16,	32)	9248
batch_normalization_10 (BatchNo conv2d_11[0][0]	(None,	16,	16,	32)	128
add_4 (Add) activation_8[0][0]	(None,	16,	16,	32)	0
batch_normalization_10[0][0]					
activation_10 (Activation) add_4[0][0]	(None,	16,	16,	32)	0
conv2d_12 (Conv2D) activation_10[0][0]	(None,	16,	16,	32)	9248
batch_normalization_11 (BatchNo conv2d_12[0][0]	(None,	16,	16,	32)	128
activation_11 (Activation) batch_normalization_11[0][0]	(None,	16,	16,	32)	0
conv2d_13 (Conv2D) activation_11[0][0]	(None,	16,	16,	32)	9248
batch_normalization_12 (BatchNo conv2d_13[0][0]	(None,	16,	16,	32)	128
add_5 (Add) activation_10[0][0]	(None,	16,	16,	32)	0
batch_normalization_12[0][0]					

activation_12 (Activation) add_5[0][0]	(None,	16, 16, 32)	0
conv2d_14 (Conv2D) activation_12[0][0]	(None,	8, 8, 64)	18496
batch_normalization_13 (BatchNo conv2d_14[0][0]	(None,	8, 8, 64)	256
activation_13 (Activation) batch_normalization_13[0][0]	(None,	8, 8, 64)	0
conv2d_15 (Conv2D) activation_13[0][0]	(None,	8, 8, 64)	36928
conv2d_16 (Conv2D) activation_12[0][0]	(None,	8, 8, 64)	2112
batch_normalization_14 (BatchNo conv2d_15[0][0]	(None,	8, 8, 64)	256
add_6 (Add) conv2d_16[0][0]	(None,	8, 8, 64)	0
<pre>batch_normalization_14[0][0]</pre>			
activation_14 (Activation) add_6[0][0]	(None,	8, 8, 64)	0
conv2d_17 (Conv2D) activation_14[0][0]	(None,	8, 8, 64)	36928
batch_normalization_15 (BatchNo conv2d_17[0][0]	(None,	8, 8, 64)	256
activation_15 (Activation) batch_normalization_15[0][0]	(None,	8, 8, 64)	0
conv2d_18 (Conv2D) activation_15[0][0]	(None,	8, 8, 64)	36928
batch_normalization_16 (BatchNo	(None,	8, 8, 64)	256

add_7 (Add) activation_14[0][0]	(None,	8, 8,	64)	0
<pre>batch_normalization_16[0][0]</pre>				
activation_16 (Activation) add_7[0][0]	(None,	8, 8,	64)	0
conv2d_19 (Conv2D) activation_16[0][0]	(None,	8, 8,	64)	36928
batch_normalization_17 (BatchNo conv2d_19[0][0]	(None,	8, 8,	64)	256
activation_17 (Activation) batch_normalization_17[0][0]	(None,	8, 8,	64)	0
conv2d_20 (Conv2D) activation_17[0][0]	(None,	8, 8,	64)	36928
batch_normalization_18 (BatchNo conv2d_20[0][0]	(None,	8, 8,	64)	256
add_8 (Add) activation_16[0][0]	(None,	8, 8,	64)	0
batch_normalization_18[0][0]				
activation_18 (Activation) add_8[0][0]	(None,	8, 8,	64)	0
<pre>average_pooling2d (AveragePooli activation_18[0][0]</pre>	(None,	1, 1,	64)	0
flatten (Flatten) average_pooling2d[0][0]	(None,	64)		0
dense (Dense) flatten[0][0]	(None,		:=====	650
Total params: 274 442	====			

Total params: 274,442 Trainable params: 273,066

```
Non-trainable params: 1,376
```

ResNet20v1

4

In [7]: ▶

```
1 # Prepare model model saving directory.
2 | save_dir = os.path.join(os.getcwd(), 'saved_models')
 3 model_name = 'cifar10_%s_model.{epoch:03d}.h5' % model_type
4 if not os.path.isdir(save_dir):
       os.makedirs(save_dir)
6 filepath = os.path.join(save_dir, model_name)
8 # Prepare callbacks for model saving and for learning rate adjustment.
9 checkpoint = ModelCheckpoint(filepath=filepath,
                                monitor='val_acc',
10
11
                                verbose=1,
12
                                 save_best_only=True)
13
14 | lr_scheduler = LearningRateScheduler(lr_schedule)
15
16 lr_reducer = ReduceLROnPlateau(factor=np.sqrt(0.1),
17
                                   cooldown=0,
18
                                   patience=5,
19
                                  min_lr=0.5e-6)
20
21 callbacks = [checkpoint, lr_reducer, lr_scheduler]
```

In [8]: ▶

```
1 # Run training, with or without data augmentation.
   if not data augmentation:
        print('Not using data augmentation.')
 3
 4
        model.fit(x_train, y_train,
 5
                  batch_size=batch_size,
 6
                  epochs=epochs,
 7
                  validation data=(x test, y test),
 8
                  shuffle=True,
 9
                  callbacks=callbacks)
10
   else:
11
        print('Using real-time data augmentation.')
12
        # This will do preprocessing and realtime data augmentation:
13
        datagen = ImageDataGenerator(
            # set input mean to 0 over the dataset
14
15
            featurewise_center=False,
            # set each sample mean to 0
16
17
            samplewise_center=False,
18
            # divide inputs by std of dataset
19
            featurewise_std_normalization=False,
20
            # divide each input by its std
21
            samplewise_std_normalization=False,
            # apply ZCA whitening
22
23
            zca_whitening=False,
24
            # epsilon for ZCA whitening
25
            zca_epsilon=1e-06,
            # randomly rotate images in the range (deg 0 to 180)
26
27
            rotation_range=0,
28
            # randomly shift images horizontally
29
            width_shift_range=0.1,
30
            # randomly shift images vertically
31
            height_shift_range=0.1,
32
            # set range for random shear
33
            shear range=0.,
34
            # set range for random zoom
35
            zoom_range=0.,
36
            # set range for random channel shifts
37
            channel_shift_range=0.,
38
            # set mode for filling points outside the input boundaries
            fill_mode='nearest',
39
            # value used for fill_mode = "constant"
40
41
            cval=0.,
42
            # randomly flip images
43
            horizontal_flip=True,
44
            # randomly flip images
45
            vertical_flip=False,
            # set rescaling factor (applied before any other transformation)
46
47
            rescale=None,
48
            # set function that will be applied on each input
49
            preprocessing_function=None,
            # image data format, either "channels_first" or "channels_last"
50
51
            data format=None,
            # fraction of images reserved for validation (strictly between 0 an
52
            validation_split=0.0)
53
54
55
        # Compute quantities required for featurewise normalization
```

```
# (std, mean, and principal components if ZCA whitening is applied).
56
57
       datagen.fit(x_train)
58
59
       # Fit the model on the batches generated by datagen.flow().
       model.fit_generator(datagen.flow(x_train, y_train, batch_size=batch_siz
60
                          validation_data=(x_test, y_test),
61
                          epochs=epochs, verbose=1, workers=4,
62
63
                          callbacks=callbacks)
64
65 # Score trained model.
scores = model.evaluate(x_test, y_test, verbose=1)
    print('Test loss:', scores[0])
68 print('Test accuracy:', scores[1])
Using real-time data augmentation.
WARNING:tensorflow:From <ipython-input-8-ba87ea241f1e>:63: Mode
1.fit_generator (from tensorflow.python.keras.engine.training)
is deprecated and will be removed in a future version.
Instructions for updating:
Please use Model.fit, which supports generators.
Learning rate: 0.001
Epoch 1/30
5730 - accuracy: 0.4865WARNING:tensorflow:Can save best model o
nly with val_acc available, skipping.
```

y: 0.4826 - lr: 0.0010 Learning rate: 0.001

nlv with val acc available. skipping.

Epoch 2/30