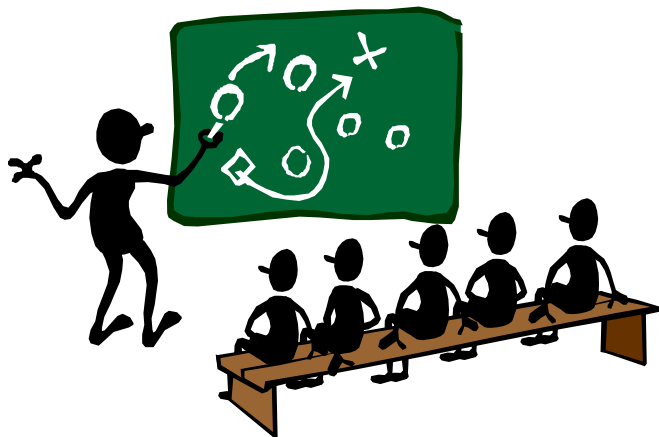


C++ Programming Language

Chapter 11 Namespace and Separate Compilation



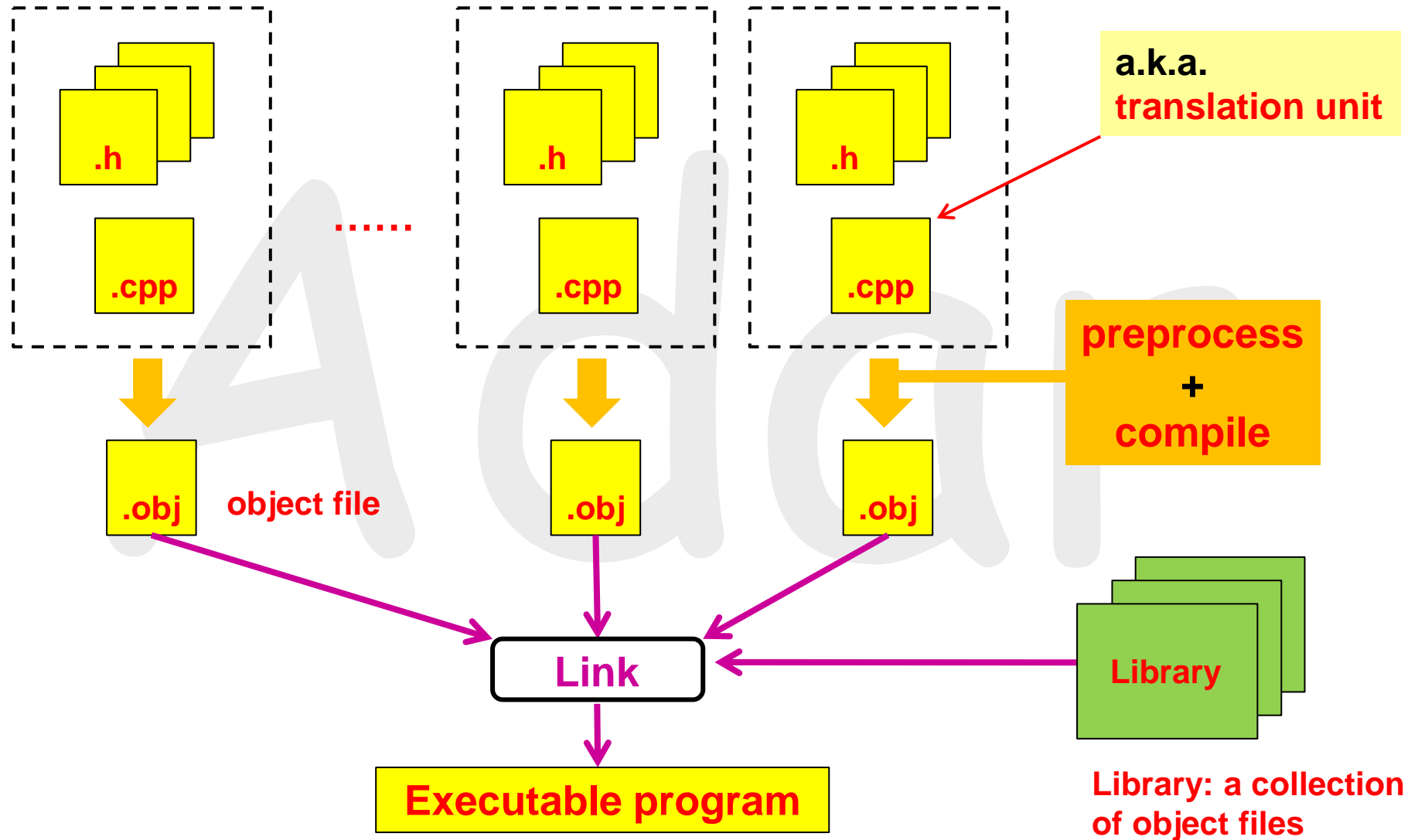
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Learning Objectives

- Preprocess, compile, and link
- Separate compilation: why and how
- External and internal linkage
- Header files
 - consistency and encapsulation
- Namespaces: why and how

Making an Executable Program



Separate Compilation (1/2)

- Why break down a program into several files
 - code size of a source file $\uparrow \rightarrow$ compile time \uparrow
 - a (cpp) file must be recompiled whenever a change (however small) has been made to it or to something on which it depends (including .h files)
 - partition source code based on logical structure \rightarrow better readability and maintainability
 - for encapsulation issue \rightarrow Have you ever seen the source code implementing `rand()` in standard library `cstdlib`?

Separate Compilation (2/2)

- To enable separate compilation
 - you must provide enough information required to compile a source file **in isolation** from the rest of the program
 - e.g.,
if you want to use **rand()**, you need to inform compiler in advance that “**rand()** takes no argument and returns int” by **#include <cstdlib>**

```
// file1.cpp
```

```
#include <cstdlib>
```

```
// in <cstdlib>, you can find a line of declaration → “int rand();”
```

```
void f() {
```

```
    int num = rand();
```

```
    // ok to use rand() here since compiler knows you make a correct call;
```

```
    // though rand() is defined elsewhere, it will be correctly linked later
```

```
}
```

Preprocessing

- file1.h

```
#define ABC 1  
void f(int);  
#define MIN(a,b) ( (a) < (b) ) ? (a) : (b) )
```

- file1.cpp

```
#include "file1.h"  
int main() {  
    int x = ABC;  
    int y = 2;  
    int z = MIN(x, y);  
    return 0;  
}
```

Preprocessor



```
void f(int);  
int main() {  
    int x = 1;  
    int y = 2;  
    int z = ( (x) < (y) ) ? (x) : (y) );  
    return 0;  
}
```

Avoid using macros anymore

Linkage (1/2)

- Programmer must ensure that all declarations referring to the same entity are consistent

// file1.cpp

```
int x = 1;    // global x is defined here
int f() { /* definition here */ }
```

// file2.cpp

```
extern int x; // declaration of x, x is defined somewhere
int f();      // declaration of f, f is defined somewhere
void g() { x = f(); } // use x and f in g
```

Linkage (2/2)

- An **object**
 - must be **DEFINED exactly ONCE** in an entire program
 - can be **DECLARED many times** as long as all of those declarations are **consistent**
 - **object** mentioned here →
data variables, and
functions (excluding inline functions and template functions)
- A definition can serve as a declaration, but a declaration can not be considered as a definition

Example (1/2)

// file1.cpp

int x = 1;	// definition of x
int b = 1;	// definition of b
extern int c;	// declaration of c

// file2.cpp

int x;	// definition of x
extern double b;	// declaration of b
extern int c;	// declaration of c

- Three **link** errors here (detected by **linker**)
 - x is defined twice
 - b is declared twice with different types
 - c is declared twice but not defined at all
- Link errors **cannot** be detected by compiler that looks at **only one** translation unit at a time

Example (2/2)

// file1.cpp

```
int x;                // ➔ int x = 0;  
int f() { return x; } // definition of f
```

// file2.cpp

```
int x;                // ➔ int x = 0;  
extern double b;      // declaration of b  
int g() { return f(); } // definition of g
```

- Two errors here
 - x is defined twice (link error)
 - in file2.cpp, f() is used **BEFORE** declared (compilation error)
- If a nonlocal data variable is not explicitly initialized
 - user-defined type ➔ call default ctor
 - built-in type and pointer ➔ 0

External and Internal Linkage

- External linkage
 - a name can be used in files different from the one in which it is defined
 - data variables and (non-inline & non-template) functions
- Internal linkage
 - a name can be used only in the file in which it is defined
 - e.g., consts, typedefs, inline functions, template functions, ...
- Beware of internal linkage
 - it will surprise you if you don't pay attention!

Beware of Internal Linkage (1/2)

```
#include <iostream>
using namespace std;

inline int f(int i) { return i; }
typedef int T;
const int x = 7;
struct X { int a, b; };
void h(); void print_X(const X& x);

int main() {
    int i = x;
    T v = 8.8;
    cout << f(i) << '\t' << v << endl;
    h();
    X x; x.a = 10, x.b = 100;
    print_X(x);
    return 0;
} // file1.cpp
```

Output:

```
=====
7          8
78         8.8
100        10
```

```
#include <iostream>
using namespace std;

inline int f(int i) { return i+1; } // internal
typedef double T; // internal
const int x = 77; // internal
struct X { int b, a; }; // internal

void h() { // external
    int i = x;
    T v = 8.8;
    cout << f(i) << '\t' << v << endl;
}

void print_X(const X& x) { // external
    cout << x.a << '\t' << x.b << endl;
} // file2.cpp
```

Beware of Internal Linkage (2/2)

- It is an error to have multiple definitions for an inline function in different files
 - unfortunately, it is nearly impossible for compiler/linker to catch this kind of faults
- Though the followings are legal
 - `T → int` in file1.cpp while `T → double` in file2.cpp
 - `const int x = 7` in file1.cpp while `const int x = 77` in file2.cpp
 - avoid doing so! it's very confusing
- How to ensure above definitions are consistent across all translation units?
 - answer: use **header files!**

Header Files (1/2)

- Rule of thumb, a header file usually contains

– type definitions	<code>class XYZ { /* ... */ };</code>
– type declarations	<code>class ABC;</code>
– template definitions	<code>template<typename T> class V { /* ... */ };</code>
– template declarations	<code>template<typename T> class Z;</code>
– declarations/definitions of template functions	
– function declarations	<code>int f(double);</code>
– inline function definitions	<code>inline void g(char ch) { /* ... */ }</code>
– data declarations	<code>extern int a;</code>
– constant definitions	<code>const float pi = 3.141593;</code>
– include directives	<code>#include <cstdlib></code>
– macro definitions	<code>#define VERSION 12</code>
– named namespaces	<code>namespace N { /* ... */ } // discuss later</code>

- Ensure definitions/declarations are consistent across all files

Header Files (2/2)

- A header file should **NEVER** contain

- ordinary function definitions
- data definitions
- aggregate definitions
- unnamed namespaces

```
char get(char* p) { /* ... */ }
```

```
int a;
```

```
short table[] = { 1, 2, 3};
```

```
namespace { /* ... */ } // later
```

Adrar

Encapsulation (1/3)

- Encapsulation (information hiding)
 - separate implementation details and user interface
- How to achieve that?
 - take the following class Example as a simple example

- In **example.h**

```
class Example {  
    int x, y;
```

```
public:
```

```
    Example(int xx = 0, int yy = 0) : x(xx), y(yy) { };
```

```
    void inc_x(int);
```

```
    void inc_y(int);
```

```
    int sum_xy() const;
```

```
    friend const Example operator+(const Example&, const Example&);
```

```
};
```

**example.h specifies
user interface of class Example**

Encapsulation (2/3)

- In **example.cpp**

```
#include "example.h"
```

```
void Example::inc_x(int val) { x += val; }
```

```
void Example::inc_y(int val) { y += val; }
```

```
int Example::sum_xy() const { return x+y; }
```

```
const Example operator+(const Example& lhs, const Example& rhs) {  
    return Example(lhs.x+rhs.x, lhs.y+rhs.y);  
}
```

- Compiler will warn any inconsistencies between **example.h** and **example.cpp**

example.cpp specifies
the actual implementation

Separate compilation:
example.cpp → **example.obj**

Encapsulation (3/3)

- In **user.cpp**
`#include "example.h"`
`int main() {`
 `Example a(1, 3), b, c;`
 `a.inc_x(2);`
 `b.inc_y(1);`
 `c = a + b;`
 `int d = c.sum_xy();`
 `return 0;`
`}`

Separate compilation:

user.cpp → **user.obj**

Link together:

user.obj + example.obj → **executable program**

- Users of class Example only need
 - **example.h** ; text file specifying **user interface**
 - **example.obj** ; binary file containing **implementation code**
 - **NO** need for **example.cpp** → **Encapsulation**

Multiple Header Files

- In abc.h

```
class abc { /* ... */ };  
// ...
```
- In xyz.h

```
#include "abc.h"  
class xyz : public abc { /* ... */ };  
// ...
```
- In user.cpp

```
#include "abc.h"  
#include "xyz.h"  
void user() {  
    abc m; xyz n;  
    // ...  
}
```

**user.cpp won't pass compilation
because class abc are defined twice**

Conditional Compilation

- Use **include guards** in header files
 - in abc.h (do the same thing for xyz.h)
`#ifndef ABC_H`
`#define ABC_H`
`class abc { /* ... */ };`
`// ...`
`#endif`
- **#ifndef** and **#endif** for **conditional compilation**
 - handled by **preprocessor**
- Now user.cpp can pass compilation
 - no multiple definition issue

Why Namespaces

- Assume that
 - you get a software library, which contains a function `void common()` , from Company ABC
 - you also get a software library, which also contains a function `void common()` , from Company XYZ
 - once you need to use functions from both libraries in your program, **you run into a big trouble**
 - **multiple** definition for a function → **link error**
- Traditionally, functions are usually in **global scope**
 - **name clash** issue
- Namespaces are solutions for **name clash** issue

Motivational Example

- Company ABC

// in ABC.h

```
namespace ABC { void common(); }
```

- Company XYZ

// in XYZ.h

```
namespace XYZ { void common(); }
```

- In user's program

```
#include "ABC.h"
```

```
#include "XYZ.h"
```

```
void func() {
```

```
    ABC::common();
```

```
    XYZ::common();
```

```
    // ...
```

```
}
```

Namespace and Scope

- Scope resolution
 - local scope → class scope → namespace scope → global scope
- A namespace is also a scope!

... ⑥ ...

```
namespace Adar {
```

```
    // ... ⑤ ...
```

```
    class B { /* ... ④ ... */ };
```

```
    class D : public class B { public: void mf(); /* ... ③ ... */ };
```

```
}
```

```
void Adar::D::mf1() {
```

```
    // ... ② ...
```

```
    { /* ... ① ... */    x = 5; /* ... */ }
```

```
    // ...
```

```
}
```

Qualified Names

```
namespace Crystal {  
    void func3();  
    void func4();  
}
```

```
namespace Adar {  
    void func1();  
    void func2();  
}
```

```
void Adar::func1() {  
    func2();  
    func3();  
    Crystal::func3();  
}
```

// in Adar's scope
// call Adar::func2()
// **error!** no func3 in Adar's scope
// ok, call Crystal::func3();

Using Declarations (1/2)

- When a name is frequently used outside its namespace

```
void Adar::func2() {      // in Adar's scope
    Crystal::func4();
    // ...
    Crystal::func4();
    // then call Crystal::func4() 10 times ...
}
```

Alternative →

```
void Adar::func2() {      // in Adar's scope
    using Crystal::func4;
    func4();               // call Crystal::func4()
    // ...
    func4();               // call Crystal::func4()
    // then call func4() 10 times ...
}
```

Using Declarations (2/2)

- Even more,

```
namespace Adar {  
    void func1();  
    void func2();  
    using Crystal::func3;           // Crystal::func3 now in Adar's scope  
}
```

- while defining `Adar::func1()` and `Adar::func2()` →
no need to explicitly call `Crystal::func3()`, just call `func3()`
- A using-declaration introduces a name from other scope into the current scope
 - a using-declaration introduces a local synonym

Using Directives (1/2)

- Ultimately,

```
namespace Adar {  
    void func1();  
    void func2();  
    using namespace Crystal; // make ALL names from Crystal  
                             // accessible in Adar  
}
```

Using Directives (2/2)

- We've already used `using namespace std` for almost the entire course
- All stuffs provided by C++ standard library are declared in namespace `std`

```
#include <iostream>
#include <string>
// using namespace std;
int main() {
    std::string str("Hello world!");
    std::cout << str << std::endl;
    return 0;
}
```

- You should avoid using “`using namespace std`” in **global scope** from now on

Using Declarations vs. Using Directives

advanced

- A using-declaration **adds** a name into the current scope
- A using-directive does **NOT**
 - it just renders names accessible in the current scope

```
namespace X { extern int i, j, k; }
```

```
int k; // global k
```

```
void f1() {  
    int i = 0;  
    using namespace X;  
    ++i; // local i  
    ++j; // X::j  
    ++k; // error, X::k or ::k ?  
    ++::k; // global k  
    ++X::k // X's k  
}
```

using-directive

```
void f2() {  
    int i = 0;  
    using X::i; // error, multiple declaration  
    using X::j;  
    using X::k; // hides global k  
    ++j; // X::j  
    ++k; // X::k  
}
```

using-declaration

Unnamed Namespaces (1/2)

- By default, functions and data variables defined in global scope have external linkage
- What if you want to keep them local within a file (i.e., internal linkage)?
- Use **unnamed namespaces**!

```
// in file1.cpp
namespace {
    int a;
    void f() { /* ... */ }
    // ...
}

void g() {
    f(); // call f() in unnamed namespace
    // ...
}
```

There is no way to access **a** and **f** outside file1.cpp
Or, file2.cpp can define its own a and f without multiple definition issue
That is, **a** and **f** have **internal linkage**

Unnamed Namespaces (2/2)

- Unnamed namespace is equivalent to

```
namespace {  
    // declarations/definitions here  
}
```

equivalent to →

```
namespace $$$ { // $$$ is implicitly generated by compiler and invisible  
    // same declarations/definitions here  
}  
using namespace $$$;
```

Internal Linkage and Keyword static

- In C, internal linkage is achieved by adding prefix **static**
static void f(); // f is local to this file; i.e., internal linkage
static int a; // a is local to this file; i.e., internal linkage
- As you can see, the keyword **static** is overused in C/C++
 - lots of confusions!
- It's still legal to use the above way to achieve internal linkage in C++ but **you should never do that**
- Instead, use unnamed namespaces for internal linkage

Global vs. Unnamed Namespaces

- Global scope is also a namespace (**implicitly**) !
 - just use **(nothing)::** in qualified names
- Global and unnamed namespaces are different
- Global namespace
 - no name
 - **implicitly** defined
 - **global** scope → can be accessed by all files
 - only **one** global namespace in a program
- Unnamed namespace
 - no name
 - **explicitly** defined
 - **local** scope → can only be accessed within a file
 - each file can have **its own unique** unnamed namespace

Nested Namespaces

- Namespaces can be nested

```
void h();  
namespace X {  
    void g();  
    namespace Y { void f(); void ff(); }  
}  
void X::Y::ff() { f(); g(); h(); } // all ok  
void X::g() {  
    f(); // error, no f() in X  
    Y::f(); // ok  
}  
void h() {  
    f(); // error, no global f()  
    Y::f(); // error, no global Y  
    X::f(); // error, no f() in X  
    X::Y::f(); // ok  
}
```

Summary (1/2)

- Know what preprocessor, compiler, and linker do
- Know how to do separate compilation
- External linkage vs. internal linkage
- Use header files to ensure consistency of declarations
- Use header files to separate interface and implementation
 - enable encapsulation
- Know what are usually in a header file and what are not
- Use conditional compilation directives (`#ifndef` and `#endif`) for include guards

Summary (2/2)

- Namespaces are solutions for name clashes
- Namespaces and scopes
- Distinguish between using-declarations and using-directives
- Distinguish between unnamed namespace and global namespace
- Nested namespaces