

## UEE1303 S18: Object-Oriented Programming

### LAB #8: TEMPLATE



#### *What you will learn from Lab 8*

In this laboratory session you will understand how to use function template and class template.

#### **LAB 8-1: Function Template**

- ✓ A function template defines a function that takes type parameters. Please execute lab8-1. Here is an example to maintain memory allocation for different types.

```
#include <iostream>
#include <cassert>
using namespace std;
template <class T>
T *new1D(int n, T k)
{
    T *vec = new T [n];
    for (int i = 0; i < n; i++)
        vec[i] = k;
    return vec;
}
template <class T>
void delete1D(T *vec)
{
    assert(vec != NULL);
    delete [] vec;
}
template <class T>
void display1D(T *vec, int n)
{
    for (int i = 0; i < n; i++)
        cout << vec[i] << " ";
    cout << endl;
}
int main(){
    int *ivec = new1D<int>(10,1);
    display1D<int>(ivec,10);
    delete1D<int>(ivec);
    double *dvec = new1D<double>(10,3.2);
    display1D<double>(dvec,10);
    delete1D<double>(dvec);
    return 0;
}
```

### LAB 8-2: FUNCTION TEMPLATE: SPECIALIZATION

- ✓ In program lab8-1, you can maintain a specific version of display1D() for double. Please add this specialization of display1D<T> to lab8-1 and execute the program again

```
template < >
void display1D(double *vec, int n)
{
    cout << fixed << setprecision(2);
    for (int i = 0; i < n; i++)
        cout << vec[i] << " ";
    cout << endl;
}
```

### LAB 8-3: CLASS TEMPLATE

- ✓ You can also define a class template by adding prefix template <class T>.

```
// lab8-3.cpp
#include <iostream>
#include <iomanip>
using namespace std;
template <class T>
class Point2D
{
    private:
        T x;
        T y;
    public:
        Point2D(): x(T(0)), y(T(0)){}
        Point2D(T a, T b): x(a), y(b){}
        void display() const;
};
template <class T>
void Point2D<T>::display() const
{
    cout << x << " " << y << endl;
}
int main()
{
    Point2D<int> p1;
    p1.display();
    Point2D<double> p2(1.9, 3.4);
    p2.display();
    return 0;
}
```

### LAB 8-4: CLASS TEMPLATE: SPECIALIZATION

- ✓ Here define a specialization of the template class Point2D<T> when its elements are complex number.

```
// lab8-4.cpp
#include <iostream>
using namespace std;
class Complex
{

```

```
private:
double real;
double image;
public:
Complex(const double a, const double b): real(a), image(b){ }
Complex(const Complex &c): real(c.real), image(c.image){ }
void display() const
{
    cout << real << " " << image << endl;
}
};
// template Point2D defined in lab8-3
template <T>
class Point2D <Complex>
{
private:
Complex x;
Complex y;
public:
Point2D(const Complex &a, const Complex &b):x(a),y(b){ }
void display() const;
};
void Point2D< Complex >::display() const
{
    x.display();
    y.display();
}
int main()
{
    Complex c1(1.9,3.4);
    Complex c2(2.0,1.3);
    Point2D<Complex> pc(c1,c2);
    pc.display();
    return 0;
}
```

- ✓ If we do not define a specialization of the template class Point2D<T> when its elements are complex number, there is a compiler error in this example. Please fix the compiler error to produce the same output.

## EXERCISE 8-1: Statistical Analysis

- ✓ Please finish the undefined function template in ex8-1.

```
#include <iostream>
#include <ctime>
#include <cstdlib>

using namespace std;

class Point2D
{
```

```
private:
    int x;
    int y;
public:
    // add any member if necessary

};

template<class T>
void analysis(int n, int k = 0)
{
    T *vec = new 1D<T> (n, k);
    rand1D<T>(vec,n);
    // for int 1~10, for double 0.00~10.00, for char a~z,
    // for Point2D x: 0~9 y:0~9
    display1D<T>(vec,n);
    sort1D<T>(vec,n);
    display1D<T>(vec,n);
}

int main()
{
    int n;
    cout << "Enter n: ";
    cin >> n;
    srand(1);
    analysis<int>(n);
    analysis<double>(n);
    analysis<char>(n);
    analysis<Point2D>(n);
    return 0;
}
```

- ✓ The output of the program should like as,

```
Enter n: 8
4 7 8 6 4 6 7 3
3 4 4 6 6 7 7 8
7.29 9.69 1.84 8.87 1.04 6.41 9.09 3.78
1.04 1.84 3.78 6.41 7.29 8.87 9.09 9.69
w k k y h i d d
d d h i k k w y
(0,2) (3,2) (5,7) (2,9) (8,2) (7,9) (6,3) (2,1)
(0,2) (2,1) (2,9) (3,2) (5,7) (6,3) (7,9) (8,2)
```

- ✓ Hint: use x coordinate first to compare Point2D and then compare y coordinate if x coordinates for two Point2Ds are the same.

## EXERCISE 8-2: VECTOR

- ✓ Please finish the undefined function template in ex8-2. The main function is like as follows.

```
int main()
{
    int n;
```

```
    cout << "Enter n: ";
    cin >> n;
    Vector<double> dvec(n,1);
    double *b = new double[n];
    for (int i = 0; i < n; i++)
        b[i] = i;
    Vector<double> dvec2(n,b);
    cout << "dvec = ";
    dvec.display();
    cout << "dvec2 = ";
    dvec2.display();
    dvec2 += dvec;
    cout << "new dvec = ";
    dvec2.display();
    double c = dot(dvec, dvec2);
    cout << "dot(dvec, dvec2) = " << c << endl << endl;
    srand(1);
    Point2D *v = new Point2D[n];
    rand1D<Point2D>(v, n); //0~9
    Vector<Point2D> vp1(n,1);
    Vector<Point2D> vp2(n,v);
    cout << "vp1 = ";
    vp1.display();
    cout << "vp2 = ";
    vp2.display();
    vp2 += vp1;
    cout << "new vp2 = ";
    vp2.display();
    Point2D d = dot(vp1, vp2);
    cout << "dot(vp1, vp2) = " << d << endl;
    return 0;
}
```

✓ The results are,

```
Enter n: 3
dvec = 1 1 1
dvec2 = 0 1 2
new dvec = 1 2 3
dot(dvec, dvec2) = 6

vp1 = (1,1) (1,1) (1,1)
vp2 = (6,3) (5,7) (5,3)
new vp2 = (7,4) (6,8) (6,4)
dot(vp1, vp2) = (19,16)
```

– Hint: dot operation for two vector is defined as  $\sum_{i=0}^{n-1} v_1(i) \times v_2(i)$ , and multiplication for two

Point2Ds is written as `Point2D(p1.x*p2.x, p1.y*p2.y);`

✓ Please declare class `Point2D` in `Point2D.h` and define its functionality in `Point2D.cpp`.

✓ Please declare template class `Vector` in `Vector.h` and define its functionality in `Vector.cpp`.

```
template <class T>
```

```
class Vector
{
    private:
        int len;
        T* vec;
    public:
        // add any member if necessary
        template<class S>
        friend S dot (const Vector<S> &, const Vector<S> &);
};
```