Algorithmic Spectral Graph Theory Boot Camp

Speaker: David Stuerer

Hierarchies of Relaxations and their Strengths and Limitations

Simons Insitute (online)

Scribe: Chi-Ning Chou

Definition 1 (unique game) For any $\epsilon > 0$, define the unique game $\mathcal{UG}(\epsilon)$ as follows.

- Given n variables x_1, \ldots, x_n over alphabets [k], where most of the time set $k < \log n$.
- Consider a system of equations in the form $x_i x_j = c_{ij} \pmod{k}$ for arbitrary $i, j \in [n]$.
- Promise there exists solution satisfying at least 1ϵ fraction of constraints.
- The goal is to find a solution satisfying at least 0.9 fraction of constraints.

Basically, one can view an unique game as a graph with n vertices where the constraints $x_i - x_j = c_{ij}$ are edges with weight c_{ij} between the ith and jth vertex. The following is the statement of the unique game conjecture by Khot [Kho02].

Conjecture 2 (The unique game conjecture) For any $\epsilon > 0$, $\mathcal{UG}(\epsilon)$ is NP-hard.

Here, let's take a look at some examples to have more intuitions about the unique game.

- When $\epsilon = 0$, using Gaussian elimination based algorithm can sole the unique game in polynomial time.
- When k=2, the unique game is equivalent to MAX-Cut.

In this talk, the David Steurer is going to show a $O(2^{n^{\epsilon^{1/3}}})$ time algorithm based on SDP hierarchies to solve $\mathcal{UG}(\epsilon)$. The idea consists of two steps: first rewrite the unique game into boolean polynomial optimization problem, then construct pseudo-distribution for it.

Rewrite the unique game

Observe that, we can first formulate unique game as an optimization problem as follows.

- For any assignment $x \in [k]^n$, let value(x) be the fraction of satisfying constraints by x.
- Thus, the goal of unique game turns to solve the optimization problem $\max_{x \in [k]^n} \text{value}(x)$.

Nevertheless, we want value(x) to be a low-degree polynomial so that it would be easier to be optimized. Thus, define some new variables as follows.

• For any $i \in [n]$ and $a \in [k]$, define variable $[x_i = a]$ as an indicator function for $x_i = a$. Note that for any $i \in [n]$, exactly one $[x_i = a]$ is set to 1. Thus, we need to add additional constraints to our optimization problem. • Take value(x) = $\mathbb{E}_{x_i-x_j=c_{ij}} \sum_{a \in [k]} [x_i = a] \cdot [x_i = a - c_{ij}]$. The expectation here is that giving uniform weight to each constraints and one can see that value(x) is a degree 2 polynomial with these new variables.

Now, we successfully represent value(x): $[k]^n \to \mathbb{R}$ as a low degree boolean polynomial. Later on, we'll see that this formulation will fit the framework of SDP hierarchies and yield efficient algorithm.

Pseudo-distribution for unique game

First, let's recall the definition of pseudo-distribution.

Definition 3 (pseudo-distribution) For functions $D, f : [k]^n \to \mathbb{R}$, define the pseudo-expectation of D on f as

$$\widetilde{\mathbb{E}}_D f = \sum_{x \in [k]^n} D(x) \cdot f(x).$$

We say D is a degree-d pseudo-distribution if

- $\tilde{\mathbb{E}}_D \mathbf{1} = 1$.
- $\tilde{\mathbb{E}}_D p^2 \geq 0$ for any polynomial p of degree at most d/2.

Furthermore, for unique game, we D is degree-d pseudo-distribution for $\mathcal{UG}(\epsilon)$ if D is a degree-d pseudo-distribution and

$$\tilde{\mathbb{E}}_D p \cdot [\text{value}(x) - (1 - \epsilon)] = 0$$

for any polynomial p of degree at most d-2.

Note that by [Sho88, Nes00, Par00, Las01], if exists, a degree-d pseudo-distribution can be found in time $n^{O(d)}$.

Next, we are going to see how to use pseudo-distribution of $\mathcal{UG}(\epsilon)$ to produce good approximation.

References

- [Kho02] Subhash Khot. On the power of unique 2-prover 1-round games. In *Proceedings of the thiry-fourth annual ACM symposium on Theory of computing*, pages 767–775. ACM, 2002.
- [Las01] Jean B Lasserre. Global optimization with polynomials and the problem of moments. SIAM Journal on Optimization, 11(3):796–817, 2001.
- [Nes00] Yurii Nesterov. Squared functional systems and optimization problems. In *High performance optimization*, pages 405–440. Springer, 2000.
- [Par00] Pablo A Parrilo. Structured semidefinite programs and semialgebraic geometry methods in robustness and optimization. PhD thesis, Citeseer, 2000.
- [Sho88] Naum Zuselevich Shor. An approach to obtaining global extremums in polynomial mathematical programming problems. *Cybernetics*, 23(5):695–700, 1988.