

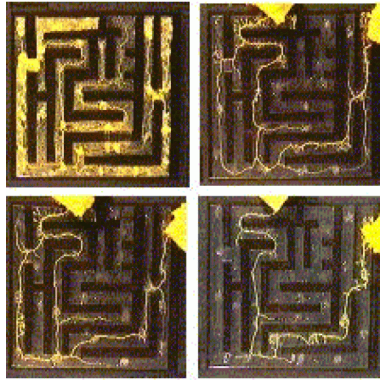
# Computational Aspects of Spiking Neural Networks

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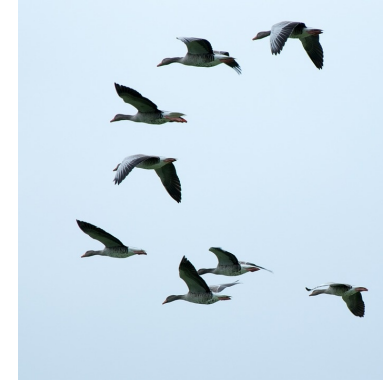
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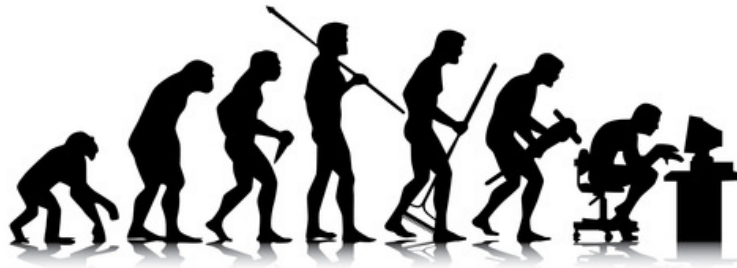
# Natural Algorithm



slime system  
[NYT00, TKN07, BMV12]



bird flocking  
[Cha12, Cha09]



Evolution  
[LP16, LPR+14]

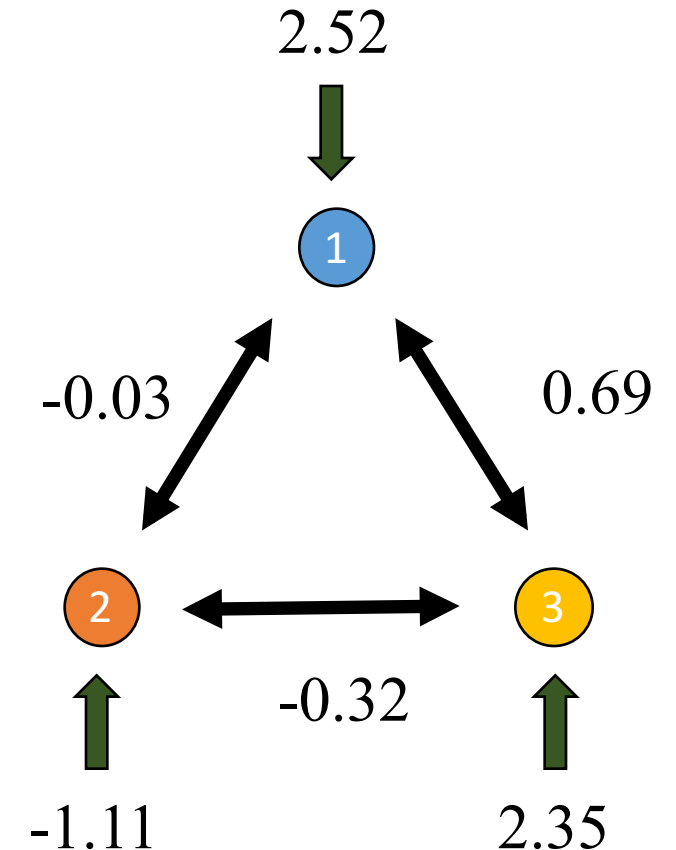


sandpile model  
[CV12]

*“understanding and explaining algorithms observed from natural systems and dynamics”*

# Spiking Neural Networks (SNN) Dynamics

- Neuron  $i$  has a time-varying **potential**  $\mathbf{u}_i(t)$ .
- **External charging rate**  $\mathbf{I} = (\mathbf{I}_1, \mathbf{I}_2, \dots, \mathbf{I}_n)$ .
- **Firing threshold**  $\eta > 0$ :  
neuron  $i$  fires a spike if  $\mathbf{u}_i(t) > \eta$  or  $\mathbf{u}_i(t) < \eta$ .
- **Spike** causes inhibition or exhibition:  
When neuron  $i$  fires a spike, neighbors'  $\mathbf{u}_j(t)$  decrease by  $C_{ij}$ .



# Motivation

- Mathematical models to **explain** and **predict** the behaviors of different neuron systems. (e.g., [I<sup>+</sup>03, Adr26, Lap07])

$$\frac{d\mathbf{u}(t)}{dt} = -C\mathbf{s}(t) + \mathbf{I}dt$$

- Barrett et al. [BDM13]: *spike firing rate* can be characterized as optimal solution of quadratic optimization problem (least square problem).

$$\min_{\mathbf{x}} \mathbf{x}^T C \mathbf{x} - 2\mathbf{I}^T \mathbf{x}$$

- Shapero et al. [SRH13,SZHR14]: SNN dynamics as algorithm for solving sparse optimization problems, e.g., Lasso.

# First Convergence Result

**Theorem** (discrete SNN to linear system)

For any  $\epsilon > 0$ , take  $\eta = \lambda_{\max}$ , the step size  $\Delta t < \frac{\sqrt{\lambda_{\min}}}{12 \cdot \sqrt{n} \|\mathbf{x}^*\|_{A^T A}}$ , and the discrete time  $T \geq \frac{2\kappa(A^T A) \cdot n}{\epsilon}$ , we have  $\|\hat{\mathbf{x}}(T) - \mathbf{x}^*\|_{A^T A} \leq \epsilon \cdot \|\mathbf{x}^*\|_{A^T A}$ .

# Key Observation

- Conservation argument:

$$\frac{\mathbf{u}(T) - \mathbf{u}(0)}{T \cdot \Delta t} = -A^T A \hat{\mathbf{x}}(T) + A^T \mathbf{b}$$

- Bounded potential

***Lemma (bounded potential)***

For any  $t > 0$ , take  $\eta = \lambda_{\max}$  and step size  $\Delta t < \frac{\sqrt{\lambda_{\min}}}{12 \cdot \sqrt{n} \|\mathbf{x}^*\|_{A^T A}}$ , we have

$$\|\mathbf{u}(t)\|_{(A^T A)^+} \leq 2\sqrt{\kappa(A^T A) \cdot \lambda_{\max} \cdot n}.$$

# Q: What Solution does SNN converges to?

- Observed that a simple SNN dynamics may solve the basis pursuit problem (a.k.a.  $\ell_1$  minimization problem).

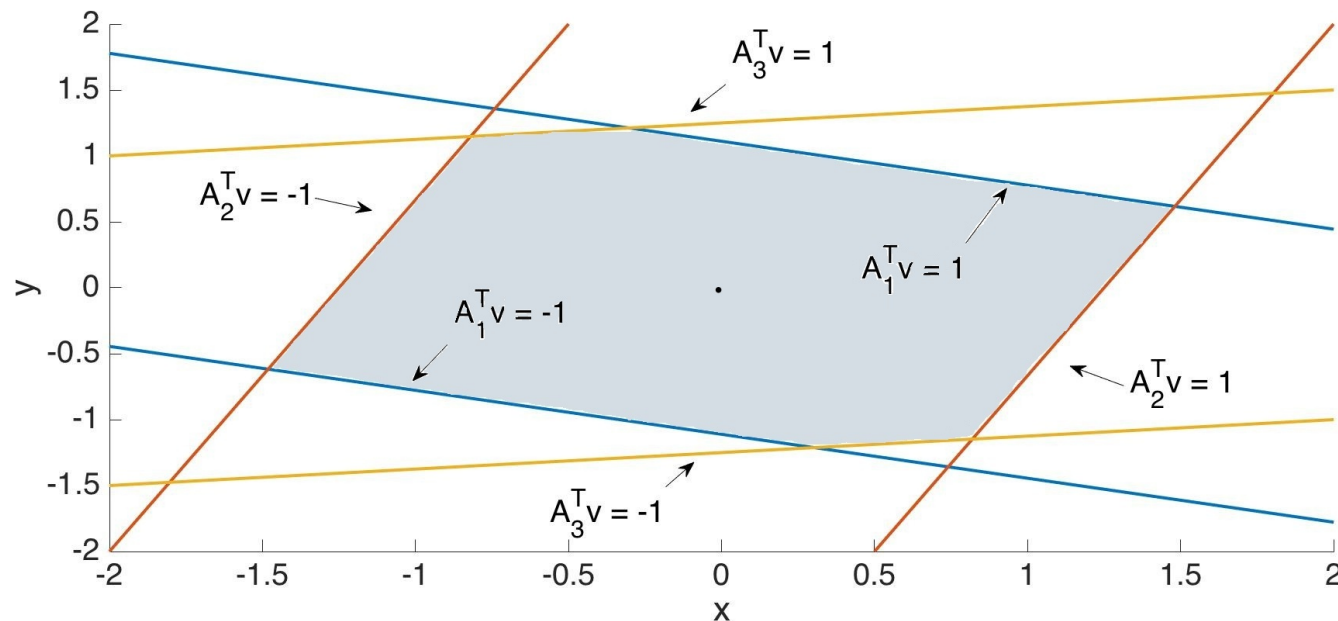
$$\begin{aligned} & \underset{\mathbf{x} \in \mathbb{R}^n}{\text{minimize}} && \|\mathbf{x}\|_1 \\ & \text{subject to} && A\mathbf{x} = \mathbf{b}, \end{aligned}$$

where  $C = A^T A$  and  $\mathbf{I} = A^T \mathbf{b}$ .

- Interpret SNN as a natural algorithm for solving its dual linear programming.
- Seems a new algorithm for the  $\ell_1$  minimization problem.

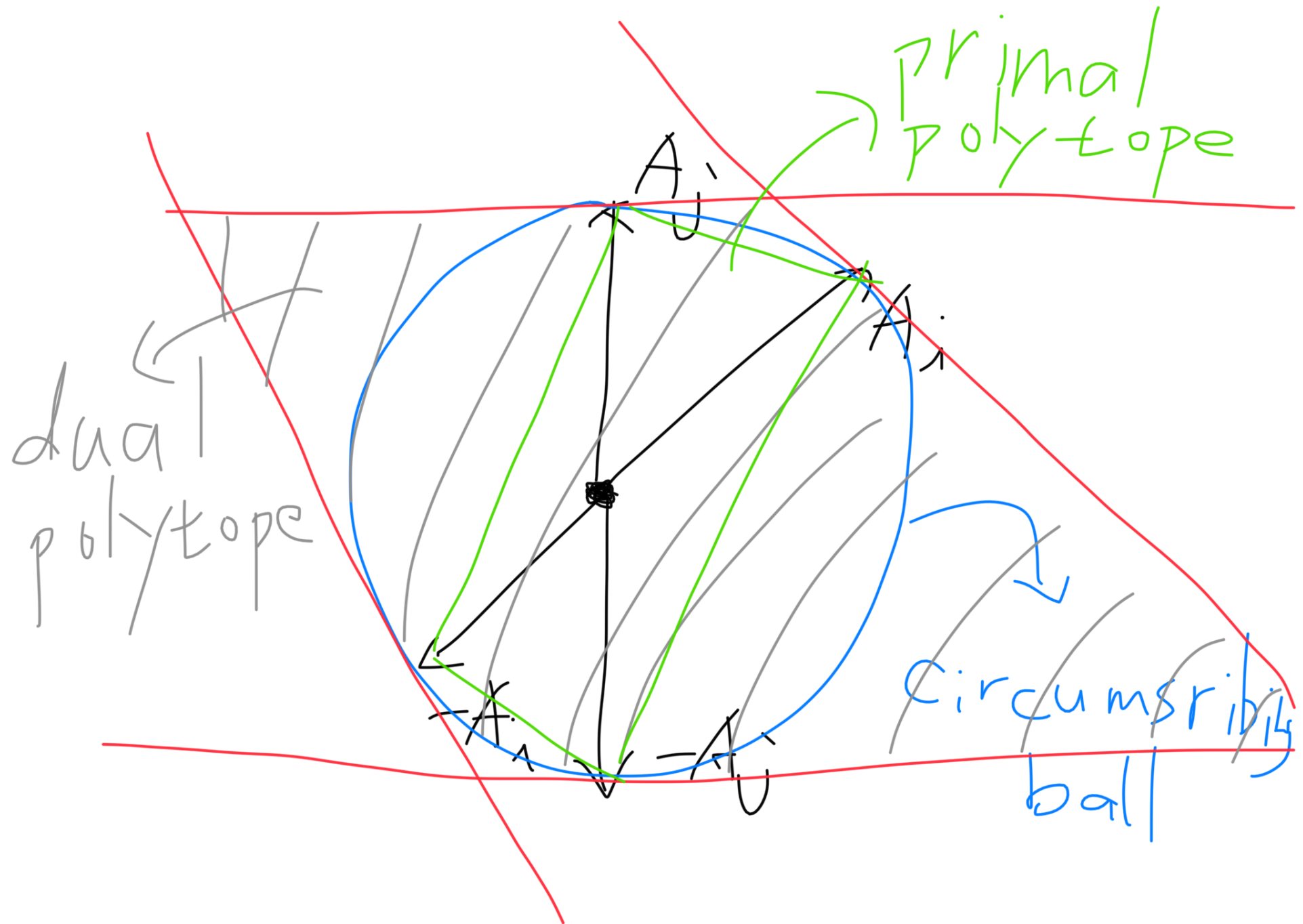
# Dual Interpretation of SNN Dynamics

- Dual **potential**:  $\mathbf{v}(t)$  where  $\mathbf{u}(t) = A^T \mathbf{v}(t)$ .
- **External charging rate**  $\mathbf{b}$  where  $\mathbf{I} = A^T \mathbf{b}$ : walk along  $\mathbf{b}$  direction.
- Spike when hit a ``wall''  $\{\mathbf{v}: A_i^T \mathbf{v} = \eta\}$ , and  $\mathbf{v}(t)$  is bounced back by  $A_i$ .



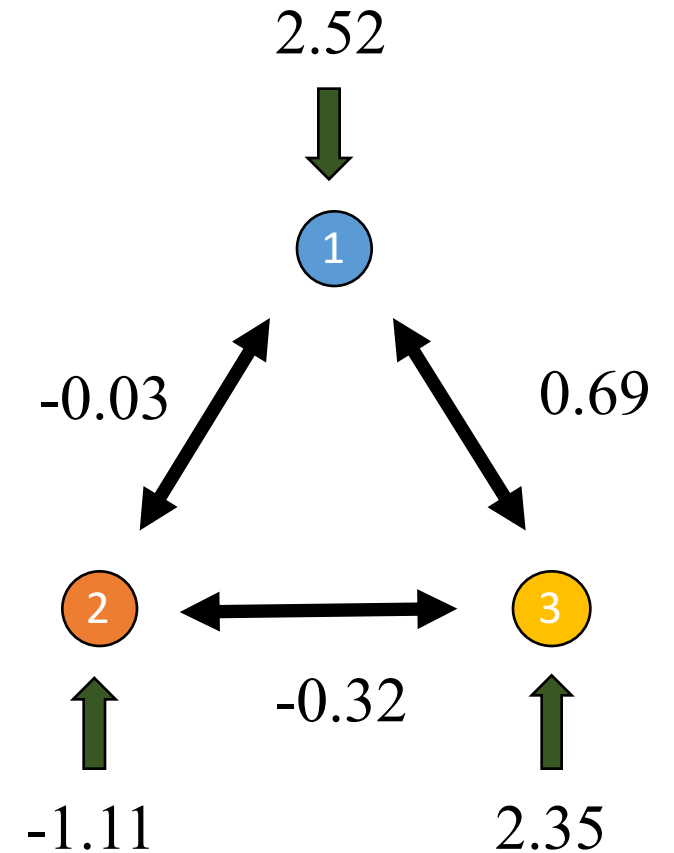
$$\begin{aligned} & \underset{\mathbf{v} \in \mathbb{R}^m}{\text{maximize}} && \mathbf{b}^T \mathbf{v} \\ & \text{subject to} && \|A^T \mathbf{v}\|_\infty \leq \eta. \end{aligned}$$





# Peculiar features of SNN algorithms

- Simple dynamics solves non-trivial optimization problems
- Distributed algorithm with extremely simple communication
- Solutions encoded as spike firing rate, not potential
- Potential practical efficiency for sparse optimization problem



# Research questions

- **Complexity of SNN:**

Prove convergence rate of firing rate to optimal solution.

- **Algorithms behind SNN:**

Understand the underlying algorithmic ideas.

- **Power of SNN:**

Understand the class of optimization problems solvable by SNN

- **Efficiency of SNN:**

Understand practical efficiency of SNN as optimization solver.