

Reader-Writer

Shared Object

Semaphore mutex = 1.
semaphore write = 1
int readcount = 0

Writer

do {
wait (&write)
// WRITER
post (&write)
} while (true).

Reader

do {
wait (&mutex);
readcount++;
if (readcount == 21) wait (&write);
post (&mutex);
// READ
wait (&mutex);
readcount--;
if (readcount == 0) post (&write);

Race Condition:

shared Object.
Multiple Process/Thread.
Access concurrently.

After Deadlock Attitude

Allow Recover.
Prevent
Ignore.

Critical Section Check

Mutual Exclusion.
Bounded Waiting (Starvation)
Progress (Deadlock)

After Deadlock

Terminate Process.
Preempt w/o killing.
Rollback action

DeadLock

Mutual Exclusion.
Hold And wait
No preemption.
Circular Wait

Prevent Deadlock

Life Time Resource.
No sharing
No priority
Request All need not seging.
Force Request order.

Achieve MR

Lock.
Spin-based
Lock-free.
Sleep-based.
CAS.
Versioning.

#0: Disable Interruption for
Unicore: correct but not
permissible.
(user x kernel v)
multicore: incorrect.
(process on other core).
may still change
shared object.

#1: Basic Lock.
write (true);
while (true) {
CS {
turn = 1;
remainder();
}
correct.
OK for short
spin < context
switch.
strict alternation.

#2: Spin Saver.
correct.
priority inversion problem.
#3: Semaphore.
need interact with scheduler
uninterruptable section entry/exit.
used as synchronization
primitive.

Bauker Algo

[Avail] = [Free Resources]
All node code to unfinished.

do {
done = true;
foreach node in unfinished {
if ([MAX] - [Alloc] ≤ [Avail]) {
remove node from UNFINISHED;
[Avail] = [Avail] + [Alloc]
done = false;
}

IO ctrl: IO instruction, mem-mapped IO.
IO trans: Programmed IO, DMA.
HDD: sector, track, cylinder.
Disk Time: Queue, ctrl, seek time.
rotational Delay, Transfer.

File size

$$12 \cdot 2^x + \frac{1 \cdot 2^x}{4} \times 2^x + \frac{1 \cdot 2^x}{4} \cdot 2^x + \frac{1 \cdot 2^x}{4} \cdot 2^x$$
$$= 12 \cdot 2^x + 2^{2x-2} + 2^{2x-4} + 2^{2x-6}$$

2^x : block size.

Parallel/Concurrency

Concurrency: structure Software.
Parallel: runing status. Hardware. multiple units.

Thread/Process

Process: Program in execution
Part of progress
Share memory.
More context switchy
Execution environment with restricted right.
instance of a program
Address space ✓ have its x don't.

Thread: Single unique.
Execution context
estate.
Part of progress
share memory.
Less.

4 Fundamental OS

Thread
Address Space.
Process.
Dual mode/Protection

Real D User+Sys

<: Multi: process.
Multi core.
>: IO-intensive.
Scheduling.
Mode. Change Overhead.

Life Cycle

Init → ready → running → finished
Wait.
Just forced.
Ready → running → finished
Wait.
Not unblock.
Blocked.

ForK

1. copy PCB
2. kernel space update.
parent - Add new child.
child - update PZD, runing time.
ptr to parent.
3. user space update.
copy memory, context
(COW).
4. finish.
update parent/child return value.

Don't change (v)

PC/Register Code, Memory,
Open File

Change (J)
return value.
PZD, parent.
runing time.
five locks.

ZPC

Shared File.
Pipe / FIFO.
Shared File.
Shared memory.
Semaphore.

Message Pass

Signal.
Message Queue.
Socket
MPI Library.

Binary semaphore ID mutex

Semantic: resource protection
resource assignment.
unlock: By container By Anyone.
Termine: Will not add up.
unlock.

Save of CS

Thread: TCB, reg, PC, stack ptr.
Process: + + PCB, file desc table.

User Thread

Same task, different data.
different independent task (CPU/IO).

Msg sys route

1. Don't put user state
2. efficiency.
freq. scheduling.
can easy switch.
no need to save kernel
stack every time.

Dining Philosopher

shared Object
 #define N 5
 #define LEFT ((i+N-1)%N)
 #define RIGHT ((i+1)%N)
 int state[N];
 semaphore mutex=1;
 semaphore p[N]=0;

Section Entry
 void take_chopsticks(int i){
 wait(&mutex);
 state[i]=HUNGRY;
 captain[i];
 post(&mutex);
 wait(&p[i]);
 }

Main Function
 void philosopher(int i){
 think();
 take_chopsticks(i);
 eat();
 put_chopsticks(i);
 }

Section Exit
 void put_chopsticks(int i){
 wait(&mutex);
 state[i]=THINKING;
 captain(LEFT);
 captain(RIGHT);
 post(&mutex);
 }

Semaphore.
 void wait(semaphore *s){
 disable_interrupt();
 *s=*s-1;
 if(*s<0){
 enable_interrupt();
 sleep();
 disable_interrupt();
 }
 enable_interrupt();
 }
 void post(semaphore *s){
 disable_intr();
 *s=*s+1;
 if(*s<=0){
 wakeup();
 }
 enable_intr();
 }

Helper.
 void captain(int i){
 if state[i]==HUNGRY && state[LEFT]!=EATING && state[RIGHT]!=EATING){
 state[i]=EATING;
 post(&p[i]);
 }

typedef struct
 int value;
 list process-id;
 } semaphore;

Producer - Consumer

Shared Object.
 #define N 100
 semaphore mutex=1;
 semaphore avail=N;
 semaphore full=0;

Producer.
 void producer(void){
 int item;
 while(TRUE){
 item=produce();
 wait(&avail);
 wait(&mutex);
 insert_item(item);
 post(&mutex);
 post(&full);
 }

Consumer
 void consumer{
 int item;
 while(TRUE){
 wait(&full);
 wait(&mutex);
 item=get_item();
 remove();
 post(&mutex);
 post(&avail);
 }
 }
 // consume

using only avail
 如果 consumer 的 get null 了。
 说明 buffer 满了。
 Buffer 满了。producer 的 item 无法放入。
 sleep. consumer 等待 mutex 的。
 deadlock.

Spin waiter. (Peterson)

int turn;
 int interested[2]={FALSE, FALSE};
 void lock(int process){
 in order;
 other = 1-process;
 interested[process]=TRUE;
 turn=process;
 while (turn==process &&
 interested[other]==TRUE){
 }

void unlock(int process){
 interested[process]=FALSE;
 }

← 每个 P 一个 CS.
 P0 P1

lock.
 turn=0
 ...
 [CS]

lock.
 interested[1]=TRUE;
 turn=1.
 while{
 ... //wait;
 }

[CS]

unlock.
 interested[0]=FALSE

//wait done
 [CS]

lock.
 i ← process no.
 for l from 0 to N-1 exclusive.
 level[i] ≤ l.
 last-to-enter[l] ≤ i
 while (last-to-enter[l]=i and
 wait

P0 P1. P1.
 lock.
 interested[0]=TRUE
 turn=0.

turn=1
 while{
 no wait
 }
 [CS]

lock.
 interested[1]=TRUE.
 turn=1.

while{
 wait.

Peter. Algo.
 level[N] = {-1}
 last-to-enter[N-1] = {-1}

unlock.
 level[i] = -1.
 等待方向。
 等待入 CS。
 按序以进所有
 房间。

turn = 3 for Mutual Exclusion.
 interest = 3 for strict alternation.
 问题: priority inversion problem

exist k ≠ i, s.t. level[k] ≥ l.
 1. 若 i 没有别的线程在更房间内存房。
 2. 别的前线程进入我的房间。即 wait 被通过。