

# TPMS

Tire Pressure Monitoring Sensor

## SP37

High integrated single-chip TPMS sensor with a low power embedded micro-controller and wireless FSK/ASK UHF transmitter

SP370 Version A4

## ROM Library Function Guide

Revision 1.0, 2010-01-27

**Edition 2010-01-27**

**Published by  
Infineon Technologies AG  
81726 Munich, Germany**

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Revision History: 2010-01-27, Revision 1.0

Previous Version: Revision 0.4

Page	Subjects (major changes since last revision)
<a href="#">Page 16</a>	Updated Note about measurements of charge consumption and execution times
<a href="#">Page 17</a>	Updated Restricted RAM areas, from 69 Bytes to 63 Bytes
<a href="#">Page 19</a>	Updated Resource Usage of all functions
<a href="#">Page 21</a>	Updated Actions of Meas_Sensor()
<a href="#">Page 24</a>	Added Footnote to Underflow/Overflow condition for Meas_Sensor()
<a href="#">Page 24</a>	Updated Output Value SensorResult+1 of Meas_Sensor()
<a href="#">Page 28</a>	Updated Actions of Meas_Pressure()
<a href="#">Page 31</a>	Added Footnote to Underflow/Overflow condition for Meas_Pressure()
<a href="#">Page 37</a>	Updated Actions of Meas_Acceleration()
<a href="#">Page 40</a>	Added Footnote to Underflow/Overflow condition for Meas_Acceleration()
<a href="#">Page 71</a>	Updated Code Example of StopXtalOsc()
<a href="#">Page 92</a>	Updated Output description of ManuRevNb()
<a href="#">Page 94</a>	Updated Input Parameters of FW_Revision_Nb()
<a href="#">Page 100</a>	Updated Output description of FlashSetLock()
<a href="#">Page 102</a>	Updated Output description of ECC_Check()
<a href="#">Page 118</a>	Updated Execution Time / Charge Consumption for Send_RF_Telegram()
<a href="#">Page 120</a>	Added Code Example for Send_RF_Telegram()
<a href="#">Page 121</a>	Added new function Internal_SFR_Refresh()

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## 1 Introduction

### 1.1 General Considerations

This document describes the ROM Library functions that are available in the SP37 Version A4 step device. When the ROM Library Function **"FW\_Revision\_Nb()" on Page 94** is called, these devices will return the value 0131<sub>H</sub> for the ROM revision.

In order for the application to use these ROM Library functions, the following files have to be included to the software project:

- SP37\_ROMLibrary.h (the header file including the function prototypes)
- SP37\_ROMLibrary.lib (the precompiled ROM Library functions)

#### Notes

1. *The application must ensure that no IDLE-RESUME event source is active before any call of the ROM Library\_functions.*
2. *All typical charge consumptions and typical execution times stated throughout this document were obtained from measurements of 10 devices at  $V_{BAT} = 3.0\text{ V}$  and  $T_{Ambient} = 25^{\circ}\text{C}$ .*
3. *Analysis of General Register, SFR, and Stack resource usage was performed on object code generated by Keil uVision3 (Assembler version: 8.00d, Compiler version: 8.08, Linker version: 6.05, Hex converter version: 2.6.0.1).*

### 1.2 Type definitions

The following table defines the parameter types used throughout this document.

**Table 1 Definition of types**

Type	Description	Range	
		Minimum	Maximum
Unsigned char	8 bit value without sign bit	0	255
Signed char	8 bit value with sign bit	-128	127
Unsigned int	16 bit value without sign bit	0	65,535
Signed int	16 bit value with sign bit	-32,768	32,767
Unsigned long	32 bit value without sign bit	0	4,294,967,295
Signed long	32 bit value with sign bit	-2,147,483,648	2,147,483,647

The Keil C51 Compiler stores data in big endian format (MSB first).

### 1.3 Wakeup Handler

The Wakeup-Handler is executed every time the device wakes up from POWER DOWN state. Possible wakeup sources are listed in SP37 Datasheet [\[1\]](#).

**Table 2 Wakeup Handler**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Wakeup from POWER DOWN state (independent of Wakeup source)	$t_{wakeup}$	—	1.0	2.1	ms	

## **1.4 Restricted RAM and FLASH areas**

The ROM Library functions use certain address areas in RAM and FLASH. To ensure that the ROM Library functions operate properly, the application may not use these locations for storage, nor alter the contents of these memory locations

### **1.4.1 Restricted RAM areas**

The RAM area C1<sub>H</sub> through FF<sub>H</sub> (upper 63 Bytes) of the 256 Bytes RAM is used and overwritten by the ROM Library functions.

### **1.4.2 Restricted FLASH areas**

The FLASH area 57FA<sub>H</sub> through 57FC<sub>H</sub> is reserved for storage of the crystal frequency to be used in the application. The crystal frequency (divided by two) has to be written to that location during FLASH programming in the production in order to provide the ROM Library functions with the correct timebase for calibration purposes. For 315 MHz applications a 19.6875 MHz crystal is used and the crystal frequency divided by two has to be written to that location.

$$19,687,500 \text{ Hz} : 2 = 9,843,750 \text{ Hz} = 963426_{\text{H}} \text{ Hz}$$

The values in FLASH have to be written in the following way:

- Flash address 57FA<sub>H</sub>: 96<sub>H</sub>
- Flash address 57FB<sub>H</sub>: 34<sub>H</sub>
- Flash address 57FC<sub>H</sub>: 26<sub>H</sub>

For 433.92 MHz applications an 18.0800 MHz crystal is used and the crystal frequency divided by two has to be written to that location.

$$18,080,000 \text{ Hz} : 2 = 9,040,000 \text{ Hz} = 89F080_{\text{H}} \text{ Hz}$$

The values in FLASH have to be written in the following way:

- Flash address 57FA<sub>H</sub>: 89<sub>H</sub>
- Flash address 57FB<sub>H</sub>: F0<sub>H</sub>
- Flash address 57FC<sub>H</sub>: 80<sub>H</sub>

The FLASH address 57FF<sub>H</sub> is reserved for Lockbyte 3. This value must not be changed by the application otherwise it might result in an unintentionally locked FLASH User Configuration Sector. Locking this sector is irreversible and shall only be done by either programming the Lockbyte 3 together with writing and locking the FLASH Code Sector or by a dedicated ROM Library function **FlashSetLock()**.

*Note: If **Erase\_UserConfigSector()** or **WriteFlashUserConfigSectorLine()** are used by the application it has to be ensured that these restricted Flash locations are restored to the proper values.*

## **1.5 8051 Instruction Set Summary**

As the SP37 incorporates an 8051 compatible microcontroller, **Figure 1** shows the SP37 OpCode Map.

		Least Significant Nybble															
		0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0		NOP 1/1	AJMP page0 2/2	LJMP addr16 3/2	RR A 1/1	INC A 1/1	INC dir 2/1	INC @R0 1/1	INC @R1 1/1	INC R0 1/1	INC R1 1/1	INC R2 1/1	INC R3 1/1	INC R4 1/1	INC R5 1/1	INC R6 1/1	INC R7 1/1
	1	JBC bit,rel 3/2	ACALL page0 2/2	LCALL addr16 3/2	RRC A 1/1	DEC A 1/1	DEC dir 2/1	DEC @R0 1/1	DEC @R1 1/1	DEC R0 1/1	DEC R1 1/1	DEC R2 1/1	DEC R3 1/1	DEC R4 1/1	DEC R5 1/1	DEC R6 1/1	DEC R7 1/1
2		JB bit,rel 3/2	AJMP page1 2/2	RET 1/2	RL A 1/1	ADD A,#imm 2/1	ADD A,dir 2/1	ADD A,@R0 1/1	ADD A,@R1 1/1	ADD A,R0 1/1	ADD A,R1 1/1	ADD A,R2 1/1	ADD A,R3 1/1	ADD A,R4 1/1	ADD A,R5 1/1	ADD A,R6 1/1	ADD A,R7 1/1
	3	JNB bit,rel 3/2	ACALL page1 2/2	RETI 1/2	RLC A 1/1	ADDC A,#imm 2/1	ADDC A,dir 2/1	ADDC A,@R0 1/1	ADDC A,@R1 1/1	ADDC A,R0 1/1	ADDC A,R1 1/1	ADDC A,R2 1/1	ADDC A,R3 1/1	ADDC A,R4 1/1	ADDC A,R5 1/1	ADDC A,R6 1/1	ADDC A,R7 1/1
4		JC rel 2/2	AJMP page2 2/2	ORL dir,A 2/1	ORL dir,#imm 3/2	ORL A,#imm 2/1	ORL A,dir 2/1	ORL A,@R0 1/1	ORL A,@R1 1/1	ORL A,R0 1/1	ORL A,R1 1/1	ORL A,R2 1/1	ORL A,R3 1/1	ORL A,R4 1/1	ORL A,R5 1/1	ORL A,R6 1/1	ORL A,R7 1/1
	5	JNC rel 2/2	ACALL page2 2/2	ANL dir,A 2/1	ANL dir,#imm 3/2	ANL A,#imm 2/1	ANL A,dir 2/1	ANL A,@R0 1/1	ANL A,@R1 1/1	ANL A,R0 1/1	ANL A,R1 1/1	ANL A,R2 1/1	ANL A,R3 1/1	ANL A,R4 1/1	ANL A,R5 1/1	ANL A,R6 1/1	ANL A,R7 1/1
6		JZ rel 2/2	AJMP page3 2/2	XRL dir,A 2/1	XRL dir,#imm 3/2	XRL A,#imm 2/1	XRL A,dir 2/1	XRL A,@R0 1/1	XRL A,@R1 1/1	XRL A,R0 1/1	XRL A,R1 1/1	XRL A,R2 1/1	XRL A,R3 1/1	XRL A,R4 1/1	XRL A,R5 1/1	XRL A,R6 1/1	XRL A,R7 1/1
	7	JNZ rel 2/2	ACALL page3 2/2	ORL C,bit 2/2*	JMP @A+DPTR 1/2	MOV A,#imm 2/1	MOV dir,#imm 3/2	MOV @R0,#imm 2/1	MOV @R1,#imm 2/1	MOV R0,#imm 2/1	MOV R1,#imm 2/1	MOV R2,#imm 2/1	MOV R3,#imm 2/1	MOV R4,#imm 2/1	MOV R5,#imm 2/1	MOV R6,#imm 2/1	MOV R7,#imm 2/1
8		SJMP rel 2/2	AJMP page4 2/2	ANL C,bit 2/2*	MOVC A,@A+PC 1/2	DIV AB 1/4	MOV dir,dir 3/2	MOV dir,@R0 2/2*	MOV dir,@R1 2/2*	MOV dir,R0 2/2*	MOV dir,R1 2/2*	MOV dir,R2 2/2*	MOV dir,R3 2/2*	MOV dir,R4 2/2*	MOV dir,R5 2/2*	MOV dir,R6 2/2*	MOV dir,R7 2/2*
	9	MOV DPTR,#imm 3/2	ACALL page4 2/2	MOV bit,C 2/2*	MOVC A,@A+DPTR 1/2	SUBB A,#imm 2/1	SUBB A,dir 2/1	SUBB A,@R0 1/1	SUBB A,@R1 1/1	SUBB A,R0 1/1	SUBB A,R1 1/1	SUBB A,R2 1/1	SUBB A,R3 1/1	SUBB A,R4 1/1	SUBB A,R5 1/1	SUBB A,R6 1/1	SUBB A,R7 1/1
A		ORL C,bit 2/2*	AJMP page5 2/2	MOV C,bit 2/1	INC DPTR 1/2*	MUL AB 1/4		MOV @R0,dir 2/2*	MOV @R1,dir 2/2*	MOV R0,dir 2/2*	MOV R1,dir 2/2*	MOV R2,dir 2/2*	MOV R3,dir 2/2*	MOV R4,dir 2/2*	MOV R5,dir 2/2*	MOV R6,dir 2/2*	MOV R7,dir 2/2*
	B	ANL C,bit 2/2*	ACALL page5 2/2	CPL bit 2/1	CPL C 1/1	CJNE A,#imm 3/2	CJNE A,dir 3/2	CJNE @R0,#imm 3/2	CJNE @R1,#imm 3/2	CJNE R0,#imm 3/2	CJNE R1,#imm 3/2	CJNE R2,#imm 3/2	CJNE R3,#imm 3/2	CJNE R4,#imm 3/2	CJNE R5,#imm 3/2	CJNE R6,#imm 3/2	CJNE R7,#imm 3/2
C		PUSH dir 2/2*	AJMP page6 2/2	CLR bit 2/1	CLR C 1/1	SWAP A 1/1	XCH A,dir 2/1	XCH A,@R0 1/1	XCH A,@R1 1/1	XCH A,R0 1/1	XCH A,R1 1/1	XCH A,R2 1/1	XCH A,R3 1/1	XCH A,R4 1/1	XCH A,R5 1/1	XCH A,R6 1/1	XCH A,R7 1/1
	D	POP dir 2/2*	ACALL page6 2/2	SETB bit 2/1	SETB C 1/1	DA A 1/1	DJNZ dir,rel 3/2	XCHDA, @R0 1/1	XCHD A,@R1 1/1	DJNZ R0,rel 2/2	DJNZ R1,rel 2/2	DJNZ R2,rel 2/2	DJNZ R3,rel 2/2	DJNZ R4,rel 2/2	DJNZ R5,rel 2/2	DJNZ R6,rel 2/2	DJNZ R7,rel 2/2
E		MOVX A,@DPTR 1/2	AJMP page7 2/2	MOVX A,@R0 1/2	MOVX A,@R1 1/2	CLR A 1/1	MOV A,dir 2/1	MOV A,@R0 1/1	MOV A,@R1 1/1	MOV A,R0 1/1	MOV A,R1 1/1	MOV A,R2 1/1	MOV A,R3 1/1	MOV A,R4 1/1	MOV A,R5 1/1	MOV A,R6 1/1	MOV A,R7 1/1
	F	MOVX @DPTR,A 1/2	ACALL page7 2/2	MOVX @R0,A 1/2	MOVX @R1,A 1/2	CPL A 1/1	MOV dir,A 2/1	MOV @R0,A 1/1	MOV @R1,A 1/1	MOV R0,A 1/1	MOV R1,A 1/1	MOV R2,A 1/1	MOV R3,A 1/1	MOV R4,A 1/1	MOV R5,A 1/1	MOV R6,A 1/1	MOV R7,A 1/1

mnemonic

inst. length (bytes)

INC

DPTR

1/2\*

addressing mode

inst. cycles (\* indicates optimized)

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Figure 1 SP37 OpCode Map

## 2 ROM Library Functions

The following library functions are available for application usage:

**Table 3 ROM Library functions**

ROM Library function	Description	Page
Meas_Sensor()	Measures the ambient air pressure or acceleration	<a href="#">Page 21</a>
Meas_Pressure()	Measures the ambient air pressure	<a href="#">Page 28</a>
Scale_Pressure()	Scale pressure into a single byte for RF transmission	<a href="#">Page 34</a>
Meas_Acceleration()	Measures the acceleration	<a href="#">Page 37</a>
Meas_Temperature()	Measures the ambient temperature	<a href="#">Page 43</a>
Raw_Temperature()	Measures the raw temperature	<a href="#">Page 46</a>
Comp_Temperature()	Compensates raw temperature data	<a href="#">Page 48</a>
Meas_Supply_Voltage()	Measures the battery voltage	<a href="#">Page 51</a>
Start_Supply_Voltage()	These three functions perform a Battery Voltage measurement during an RF Transmission.	<a href="#">Page 54</a>
Trig_Supply_Voltage()		<a href="#">Page 56</a>
Get_Supply_Voltage()		<a href="#">Page 58</a>
ADC_Selftest()	Returns the delta of ADC test measurements	<a href="#">Page 61</a>
Powerdown()	Forces the device to POWER DOWN state	<a href="#">Page 64</a>
ThermalShutdown()	Forces the device to THERMAL SHUTDOWN state	<a href="#">Page 66</a>
StartXtalOsc()	Enables the Crystal Oscillator	<a href="#">Page 68</a>
StopXtalOsc()	Stops the Crystal Oscillator	<a href="#">Page 70</a>
PLL_Ref_Signal_Check()	Evaluates Crystal Resonator signal	<a href="#">Page 72</a>
VCO_Tuning()	Tunes the VCO frequency	<a href="#">Page 74</a>
IntervalTimerCalibration()	Calibrates the Interval Timer precounter	<a href="#">Page 76</a>
LFBaudrateCalibration()	Calibrates the LF baudrate divider	<a href="#">Page 78</a>
SMulIntInt()	Multiplies two signed values (16 bit * 16 bit)	<a href="#">Page 80</a>
UDivLongLong()	Divides two unsigned values (32 bit : 32 bit)	<a href="#">Page 82</a>
UDivIntInt()	Divides two unsigned values (16 bit : 16 bit)	<a href="#">Page 84</a>
CRC8_Calc()	Calculates an 8 Bit CRC with polynom 83 <sub>H</sub>	<a href="#">Page 86</a>
CRC_Baicheva_Calc()	Calculates an 8 Bit CRC with polynom 97 <sub>H</sub>	<a href="#">Page 88</a>
Read_ID()	Returns the unique device ID	<a href="#">Page 90</a>
ManuRevNb()	Returns the device revision number	<a href="#">Page 92</a>
FW_Revision_Nb()	Returns the ROM- and Flash library revision number	<a href="#">Page 94</a>
Erase_UserConfigSector()	Erases the FLASH user configuration sector	<a href="#">Page 96</a>
WriteFlashUserConfigSectorLine()	Writes one FLASH line (32 Bytes) in the FLASH user configuration sector	<a href="#">Page 98</a>
FlashSetLock()	Sets the Lockbyte to protect the User Configuration sector	<a href="#">Page 100</a>
ECC_Check()	Evaluates the ECC result bit	<a href="#">Page 102</a>
CRC16_Check()	Evaluates the CRC16 result of a memory block	<a href="#">Page 104</a>
HIRC_Clock_Check()	Evaluates the 12 MHz_RC_Oscillator frequency	<a href="#">Page 106</a>

**Table 3** ROM Library functions (cont'd)

ROM Library function	Description	Page
GetCompValue()	Returns a compensated value from look up table	<a href="#">Page 108</a>
Wait100usMultiples()	Performs a delay of 100 $\mu$ s multiples	<a href="#">Page 112</a>
Send_RF_Telegram()	Configures and transmits RF frames	<a href="#">Page 114</a>
Internal_SFR_Refresh()	Loads default values into the internal SFRs	<a href="#">Page 121</a>

## 2.1 Meas\_Sensor()

### 2.1.1 Description

This function performs a pressure or acceleration sensor measurement determined by **SensorConfig**.

The pressure or acceleration result can be either:

- Compensated for sensitivity, offset and temperature
- Output as raw value without performing the compensation

The function can measure either pressure or acceleration with up to 64 samples at a specified sample rate. The function will return the average (arithmetic mean) pressure or acceleration value in order to compensate for noise. Optionally, an acceleration measurement can return the maximum value of the samples. The function performs a new temperature measurement for compensating the pressure or acceleration measurements, unless a previously measured raw temperature value is supplied. Number of samples and raw temperature source are both determined by **SensorConfig**. SampleRate controls how frequently the measurement acquisitions occur and will not influence the measurement result under stable input pressure or acceleration conditions. The device is set to IDLE mode during the delay between measurement acquisitions.

### 2.1.2 Actions

Pressure Measurement

- Measure pressure sensor with gain, channel and number of samples for averaging given by **SensorConfig**
- Check wire bonds between the ASIC and the sensor die
- Average the measurement result(s) to obtain a raw pressure value
- (optionally) Perform a raw temperature measurement
- (optionally) Compensate the raw pressure value

Acceleration Measurement

- Measure acceleration sensor with gain, channel and number of samples for averaging given by **SensorConfig**
- Check wire bonds between the ASIC and the sensor die & sensor beam integrity
- Average the measurement(s), or (optionally) use the maximum raw measurement, to obtain a raw acceleration value
- (optionally) Perform a raw temperature measurement
- (optionally) Compensate the raw acceleration value

### 2.1.3 Prototype

unsigned char **Meas\_Sensor** (unsigned int **SensorConfig**, unsigned char **SampRate**, signed int idata **\*SensorResult** )

## 2.1.4 Inputs

**Table 4 Meas\_Sensor: Input Parameters**

Register / Address	Type	Name	Description
R6 (MSB) R7 (LSB)	unsigned int	SensorConfig	Defines Sensor Configuration (refer to <a href="#">Table 5</a> and <a href="#">Table 6</a> )
R5	unsigned char	SampleRate	Defines the number of system clock cycles (12 MHz RC Oscillator) divided by 8 which is waited between consecutive measurements. <i>Note: Only applicable if SensorConfig.2-0 [2POWN2:0] greater than 1 Sample</i>
R3	signed int idata*	SensorResult	Pointer to an integer array in RAM to receive the measurement result
*(SensorResult+2)	signed int	Raw Temperature	Previous Raw Temperature value can optionally be used as input parameter. Refer to bit RAWTemp in SensorConfig.



**Table 5 Meas\_Sensor: Input Parameter: SensorConfig[15:8]**

Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
RES	RES	RES	RES	RES	RES	RES	RAWTemp
RAWTemp		Selects source of raw temperature data for compensation 0 <sub>B</sub> : Perform new raw temperature measurement 1 <sub>B</sub> : Use raw temperature data supplied in *(PressResult+2)					

**Table 6 Meas\_Sensor: Input Parameter: SensorConfig[7:0]**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Sens_Type	RAW	Gain.1	Gain.0	MODE	2POWN.2	2POWN.1	2POWN.0
Sens_Type		Select Pressure or Acceleration Measurement 0 <sub>B</sub> : Acceleration Measurement 1 <sub>B</sub> : Pressure Measurement					
RAW		Defines if the raw ADC result is compensated 0 <sub>B</sub> : Temperature compensation is performed. Returns Compensated & raw value 1 <sub>B</sub> : No compensation is performed. Returns only raw value. If SensorConfig bit RAWTemp is set to 1 <sub>B</sub> , no RAW temperature measurement is performed. <i>Note: See <a href="#">Table 8</a> for impact on ROM Library function output</i>					
Gain[1:0]		Specifies the Sensor Gain depending on Sens_Type: Sens_Type set to 0 <sub>B</sub> : Gain: must be set to 00 <sub>B</sub> for acceleration measurement Sens_Type set to 1 <sub>B</sub> : Gain: must be set to 00 <sub>B</sub> for 450 kPa pressure range Sens_Type set to 1 <sub>B</sub> : Gain: must be set to 11 <sub>B</sub> for 900 kPa pressure range					
Mode		Acceleration Measure Mode: Sens_Type set to 0 <sub>B</sub> : Acceleration Measure Mode 0 <sub>B</sub> : Average value Sens_Type set to 0 <sub>B</sub> : Acceleration Measure Mode 1 <sub>B</sub> : Maximum value <i>Note: For Pressure Measurement this bit must be set to 0<sub>B</sub> (average value).</i>					
2POWN[2:0]		Number of ADC measurements that are taken and averaged 111 <sub>B</sub> : 64 Samples 110 <sub>B</sub> : 64 Samples 101 <sub>B</sub> : 32 Samples 100 <sub>B</sub> : 16 Samples 011 <sub>B</sub> : 8 Samples 010 <sub>B</sub> : 4 Samples 001 <sub>B</sub> : 2 Samples 000 <sub>B</sub> : 1 Sample					

**Table 7 Meas\_Sensor: Input Parameter: SampleRate**

Bit7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SR.7	SR.6	SR.5	SR.4	SR.3	SR.2	SR.1	SR0
SR[7:0]		Number of systemclock cycles divided by 8 between two consecutive samples (only applicable if more than one sample is taken and averaged): 00 <sub>H</sub> : No delay (fastest possible sample rate) 01 <sub>H</sub> ..4F <sub>H</sub> : Not allowed 50 <sub>H</sub> ..FF <sub>H</sub> : 1/sample rate (sample rate in systemclocks divided by 8)					

## 2.1.5 Outputs

**Table 8 Meas\_Sensor: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	StatusByte	0000.0000 <sub>B</sub> : Success xxxx.xxx1 <sub>B</sub> : Underflow of ADC Result <sup>1)</sup> xxxx.xx1x <sub>B</sub> : Overflow of ADC Result <sup>1)</sup> xxxx.x1xx <sub>B</sub> : Sensor Fault Wire Bond Check xxxx.1xxx <sub>B</sub> : Sensor Fault Diagnosis Resistor (only for acceleration measurement) xxx1.xxxx <sub>B</sub> : VMIN warning
*(SensorResult+0)	signed int	Compensated Pressure	If Input Bit SensorConfig.7[Sens_Type] == 1; If Input Bit SensorConfig.6[RAW] == 0: 8000 <sub>H</sub> = -2048.0 kPa (Only theoretical) 0000 <sub>H</sub> = 0.0 kPa 7FFF <sub>H</sub> = 2047.9375 kPa (= 2048 kPa - 1 LSB where 1 LSB = 1/16 kPa)  If Input Bit SensorConfig.6[RAW] == 1: 8000 <sub>H</sub> since no compensation is performed
		Compensated Acceleration	If Input Bit SensorConfig.7[Sens_Type] == 0; If Input Bit SensorConfig.6[RAW] == 0: 8000 <sub>H</sub> = -2048.0 g 0000 <sub>H</sub> = 0.0 g 7FFF <sub>H</sub> = 2047.9375 g (= 2048 g - 1 LSB where 1 LSB = 1/16 g)  If Input Bit SensorConfig.6[RAW] == 1: 8000 <sub>H</sub> since no compensation is performed
*(SensorResult+1)	signed int	Raw Pressure	10 Bit ADC Result Value: 0000.00xx.xxxx.xxxx <sub>B</sub>
		Raw Acceleration	10 Bit ADC Result Value: 0000.00xx.xxxx.xxxx <sub>B</sub>
*(SensorResult+2)	signed int	Raw Temperature	If Input Bit SensorConfig.6[RAW] == 0: 16Bit scaled signed ADC Result Value  If Input Bit SensorConfig.6[RAW] == 1: 8000 <sub>H</sub> since no temperature measurement is performed

1) If the sensor measurement result is within the input range for which its accuracy is specified, then the ADC underflow/overflow condition is due to a measurement failure and the measurement results are not valid. Otherwise, if the sensor measurement result is outside of this input range, then the ADC underflow/overflow bits may be ignored.

## 2.1.6 Resource Usage

**Table 9 Meas\_Sensor: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0 <sup>1)</sup> , CFG1, CFG2, DIVIC, DPH, DPL, PSW, TCON <sup>1)</sup> , TH0 <sup>1)</sup> , TL0 <sup>1)</sup> , TMOD <sup>1)</sup>
Stack	11 Bytes

1) Only affected if more than 1 sample is taken

## 2.1.7 Execution Information

**Table 10 Meas\_Sensor: Preassure Measurement: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time Compensated with new raw temperature measurement, 2 samples	$t_{comp,new}$	—	893	970	$\mu s$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0081 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time Compensated when supplied with previously obtained raw temperature value, 2 samples	$t_{comp,prev}$	—	665	722	$\mu s$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0181 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time Raw (uncompensated) pressure result, 2 samples	$t_{RAW}$	—	271	294	$\mu s$	DIVIC = 00 <sub>H</sub> , SensorConfig = 00C1 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time for each additional sample for averaging	$t_{sample}$	—	56	61	$\mu s$	SampleRate = 00 <sub>H</sub> Only 1, 2, 4, 8, 16, 32, 64 samples possible
Charge Consumption Compensated with new raw temperature measurement, 2 samples	$Q_{comp,new}$	—	1,62	2,42	$\mu C$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0081 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption Compensated when supplied with previously obtained raw temperature value, 2 samples	$Q_{comp,prev}$	—	1,12	1,78	$\mu C$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0181 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption Raw (uncompensated) pressure result, 2 samples	$Q_{RAW}$	—	0,51	0,727	$\mu C$	DIVIC = 00 <sub>H</sub> , SensorConfig = 00C1 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption for each additional sample for averaging	$Q_{sample}$	—	0,118	0,151	$\mu C$	SampleRate = 00 <sub>H</sub> Only 1, 2, 4, 8, 16, 32, 64 samples possible

**Table 11 Meas\_Sensor: Acceleration Measurement: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time Compensated with new raw temperature measurement, 2 samples	$t_{\text{comp,new}}$	—	906	985	$\mu\text{s}$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0001 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time Compensated when supplied with previously obtained raw temperature value, 2 samples	$t_{\text{comp,prevt}}$	—	678	737	$\mu\text{s}$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0101 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time Raw (uncompensated) acceleration result, 2 samples	$t_{\text{RAW}}$	—	286	311	$\mu\text{s}$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0041 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time for each additional sample for averaging	$t_{\text{sample}}$	—	66	71	$\mu\text{s}$	SampleRate = 00 <sub>H</sub>
Charge Consumption Compensated with new internal raw temperature measurement, 2 samples	$Q_{\text{comp,new}}$	—	1,63	2,44	$\mu\text{C}$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0001 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption Compensated when supplied with previously obtained raw temperature value, 2 samples	$Q_{\text{comp,prev}}$	—	1,11	1,80	$\mu\text{C}$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0101 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption Raw (uncompensated) acceleration result, 2 samples	$Q_{\text{RAW}}$	—	0,54	0,754	$\mu\text{C}$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0041 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption for each additional sample for averaging	$Q_{\text{sample}}$	—	0,136	0,17	$\mu\text{C}$	SampleRate = 00 <sub>H</sub>

## 2.2 Meas\_Pressure()

### 2.2.1 Description

This function performs a pressure sensor measurement.

The result can be either:

- Compensated for sensitivity, offset and temperature
- Output as raw value without performing the compensation

The function can measure pressure with up to 64 samples at a specified sample rate. The function will return the average (arithmetic mean) pressure value in order to compensate for noise. The function performs a new temperature measurement for compensating the pressure measurements, unless a previously measured raw temperature value is supplied. Number of samples and raw temperature source are both determined by **SensorConfig**. SampleRate controls how frequently the measurement acquisitions occur and will not influence the measurement result under stable input pressure conditions. The device is set to IDLE mode during the delay between measurement acquisitions.

### 2.2.2 Actions

- Measure pressure sensor with gain, channel and number of samples for averaging given by **SensorConfig**
- Check wire bonds between the ASIC and the sensor die
- Average the measurement result(s) to obtain a raw pressure value
- (optionally) Perform a raw temperature measurement
- (optionally) Compensate the raw pressure value

### 2.2.3 Prototype

unsigned char **Meas\_Pressure** (unsigned int **SensorConfig**, unsigned char **SampRate**, signed int idata **\*PressResult** )

## 2.2.4 Inputs

**Table 12 Meas\_Pressure: Input Parameters**

Register / Address	Type	Name	Description
R6 (MSB) R7 (LSB)	unsigned int	SensorConfig	Defines Sensor Configuration (refer to <a href="#">Table 13</a> and <a href="#">Table 14</a> )
R5	unsigned char	SampleRate	Defines the number of system clock cycles (12 MHz RC Oscillator) divided by 8 which is waited between consecutive measurements. <i>Note: Only applicable if SensorConfig.2-0 [2POWN2:0] greater than 1 Sample</i>
R3	signed int idata*	PressResult	Pointer to an integer array in RAM to receive the measurement result
*(PressResult+2)	signed int	Raw Temperature	Previous Raw Temperature value can optionally be used as input parameter. Refer to bit RAWTemp in SensorConfig.



**Table 13 Meas\_Pressure: Input Parameter: SensorConfig[15:8]**

Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
RES	RES	RES	RES	RES	RES	RES	RAWTemp
RAWTemp		Selects source of raw temperature data for compensation 0 <sub>B</sub> : Perform new raw temperature measurement 1 <sub>B</sub> : Use raw temperature data supplied in *(PressResult+2)					

**Table 14 Meas\_Pressure: Input Parameter: SensorConfig [7:0]**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Sens_Type	RAW	GAIN.1	GAIN.0	RES	2POWN.2	2POWN.1	2POWN.0
Sens_Type		Select Pressure Measurement Must be set to 1 <sub>B</sub> for Pressure Measurement					
RAW		Defines if the raw ADC result is compensated 0 <sub>B</sub> : Temperature compensation is performed. Returns Compensated & raw value 1 <sub>B</sub> : No compensation is performed. Returns only raw value. If SensorConfig bit RAWTemp is set to 1 <sub>B</sub> , no RAW temperature measurement is performed. <i>Note: See <a href="#">Table 16</a> for impact on ROM Library function output</i>					
GAIN[1:0]		Specifies the Sensor Gain: Use 00 <sub>B</sub> for 450 kPa range Use 11 <sub>B</sub> for 900 kPa range					
RES		Reserved Must be set to 0 <sub>B</sub>					
2POWN[2:0]		Number of ADC measurements that are taken and averaged 111 <sub>B</sub> : 64 Samples 110 <sub>B</sub> : 64 Samples 101 <sub>B</sub> : 32 Samples 100 <sub>B</sub> : 16 Samples 011 <sub>B</sub> : 8 Samples 010 <sub>B</sub> : 4 Samples 001 <sub>B</sub> : 2 Samples 000 <sub>B</sub> : 1 Sample					

**Table 15 Meas\_Pressure: Input Parameter: SampleRate**

Bit7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SR.7	SR.6	SR.5	SR.4	SR.3	SR.2	SR.1	SR0
SR[7:0]		Number of systemclock cycles divided by 8 between two consecutive samples (only applicable if more than one sample is taken and averaged): 00 <sub>H</sub> : No delay (fastest possible sample rate) 01 <sub>H</sub> ..4F <sub>H</sub> : Not allowed 50 <sub>H</sub> ..FF <sub>H</sub> : 1/sample rate (sample rate in systemclocks divided by 8)					

## 2.2.5 Outputs

**Table 16 Meas\_Pressure: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	StatusByte	0000.0000 <sub>B</sub> : Success xxxx.xxx1 <sub>B</sub> : Underflow of ADC Result <sup>1)</sup> xxxx.xx1x <sub>B</sub> : Overflow of ADC Result <sup>1)</sup> xxxx.x1xx <sub>B</sub> : Sensor Fault Wire Bond Check xxx1.xxxx <sub>B</sub> : VMIN warning
*(PressResult+0)	signed int	Compensated Pressure	If Input Bit SensorConfig.6[RAW] == 0: 8000 <sub>H</sub> = -2048.0 kPa (Only theoretical) 0000 <sub>H</sub> = 0.0 kPa 7FFF <sub>H</sub> = 2047.9375 kPa ( = 2048 kPa - 1 LSB where 1 LSB = 1/16 kPa)  If Input Bit SensorConfig.6[RAW] == 1: 8000 <sub>H</sub> since no compensation is performed
*(PressResult+1)	signed int	Raw Pressure	10 Bit ADC Result Value: 0000.00xx.xxxx.xxxx <sub>B</sub>
*(PressResult+2)	signed int	Raw Temperature	If Input Bit SensorConfig.6[RAW] == 0: 16 Bit scaled signed ADC Result Value  If Input Bit SensorConfig.6[RAW] == 1: 8000 <sub>H</sub> since no temperature measurement is performed

1) If the pressure measurement result is within the input range for which its accuracy is specified (e.g. 100 kPa - 450 kPa), then the ADC underflow/overflow condition is due to a measurement failure and the measurement results are not valid. Otherwise, if the pressure measurement result is outside of this input range, then the ADC underflow/overflow bits and the pressure measurement results may be ignored.

## 2.2.6 Resource Usage

**Table 17 Meas\_Pressure: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0 <sup>1)</sup> , CFG1, CFG2, DIVIC, DPH, DPL, PSW, TCON <sup>1)</sup> , TH0 <sup>1)</sup> , TL0 <sup>1)</sup> , TMOD <sup>1)</sup>
Stack	11 Bytes

1) Only affected if more than 1 sample is taken

## 2.2.7 Execution Information

**Table 18 Meas\_Pressure: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time Compensated with new raw temperature measurement, 2 samples	$t_{comp,new}$	—	894	972	$\mu s$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0081 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time Compensated when supplied with previously obtained raw temperature value, 2 samples	$t_{comp,prev}$	—	667	724	$\mu s$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0181 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time Raw (uncompensated) pressure result, 2 samples	$t_{RAW}$	—	272	296	$\mu s$	DIVIC = 00 <sub>H</sub> , SensorConfig = 00C1 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time for each additional sample for averaging	$t_{sample}$	—	56	61	$\mu s$	SampleRate = 00 <sub>H</sub> Only 1, 2, 4, 8, 16, 32, 64 samples possible
Charge Consumption Compensated with new raw temperature measurement, 2 samples	$Q_{comp,new}$	—	1,62	2,43	$\mu C$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0081 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption Compensated when supplied with previously obtained raw temperature value, 2 samples	$Q_{comp,prev}$	—	1,13	1,78	$\mu C$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0181 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption Raw (uncompensated) pressure result, 2 samples	$Q_{RAW}$	—	0,51	0,731	$\mu C$	DIVIC = 00 <sub>H</sub> , SensorConfig = 00C1 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption for each additional sample for averaging	$Q_{sample}$	—	0,118	0,151	$\mu C$	SampleRate = 00 <sub>H</sub> Only 1, 2, 4, 8, 16, 32, 64 samples possible

## 2.2.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"

void main()
{
    // Return value of pressure measurement is stored in StatusByte
    unsigned char StatusByte;

    // Input parameters for pressure measurement
    unsigned int SensorConfig = 0x0081;
    unsigned char SampRate = 0x00;

    // struct for pressure measurement results
    struct{
        signed int Pressure;
        signed int Raw_pressure;
        signed int Raw_temperature;
    } idata Press_Result;

    // Pressure measurement function call
    StatusByte = Meas_Pressure(SensorConfig, SampRate, &Press_Result.Pressure);

    if(!StatusByte){
        // Pressure measurement was successful
    }
    else{
        // Pressure measurement was not successful, underflow or
        // overflow of ADC result, Sensor Fault Wire Bond Check,
        // or VMIN warning occurred
    }
}
```

**Figure 2** Code example for usage of Meas\_Pressure()

## 2.3 Scale\_Pressure()

### 2.3.1 Description

A 450 kPa range TPMS sensor will typically transmit the pressure value as a single byte within an RF telegram: the pressure range 100...450 kPa is represented with an unsigned byte ranging from 0...255. A scale factor of 1.373 kPa/LSB is required to meet this typical requirement. The SP37 Meas\_Pressure function, however, returns a signed integer value that represents pressure as 1/16 kPa/LSB. Conversion from 1/16 kPa/LSB to 1.373 kPa/LSB is therefore a commonly required task, but one that is not straightforward as care must be taken to avoid excessive rounding or loss of precision. The full scale error (FSE) of this function is less than 0.4%.

As a convenience, this Scale\_Pressure( ) function performs this conversion. In addition, pressure bounds checking is performed so that 0 and 255 are returned for input pressure values below 100 kPa and above 450 kPa, respectively. Finally, to reduce the amount of data handling required by the application program, note that the input value to Scale\_Pressure is passed as a pointer. This allows the same pointer to the [Meas\\_Pressure\(\)](#) output structure \*(PressResult+0) to be re-used as the input pointer to Scale\_Pressure().

### 2.3.2 Actions

- Check 16 bit input value against 100 kPa and 450 kPa bounds, if value is outside of these bounds return 0 or 255, respectively
- Convert input value to unsigned 8 bit return value between 0 and 255

### 2.3.3 Prototype

unsigned char **Scale\_Pressure**(signed int idata \* **PressureValue**)

### 2.3.4 Inputs

**Table 19 Scale\_Pressure: Input Parameters**

Register / Address	Type	Name	Description
R7	signed int idata*	PressureValue	Pointer to 16 bit input pressure value; Reuse of Meas_Pressure output structure *(PressResult+0)

### 2.3.5 Outputs

**Table 20 Scale\_Pressure: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	Result	8 bit output pressure value

### 2.3.6 Resource Usage

**Table 21 Scale\_Pressure: Resources**

Type	Used or Modified
Registers	R0, R2, R3, R4, R5, R6, R7
SFR	A, B, PSW
Stack	4 bytes

### 2.3.7 Execution Information

**Table 22 Scale\_Pressure: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	199	215	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,3	0,52	μC	DIVIC = 00 <sub>H</sub>

### 2.3.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"

void main()
{
    // Return value of pressure measurement is stored in StatusByte
    unsigned char StatusByte;

    // 8-bit pressure value is stored in PressureByte
    unsigned char PressureByte;

    // Input parameters for pressure measurement
    unsigned int SensorConfig = 0x0081;
    unsigned char SampRate = 0x00;

    // struct for pressure measurement results
    struct{
        signed int Pressure;
        signed int Raw_pressure;
        signed int Raw_temperature;
    } idata Press_Result;

    // Pressure measurement function call
    StatusByte = Meas_Pressure(SensorConfig, SampRate, &Press_Result.Pressure);

    if(!StatusByte){

        // Pressure measurement was successful
        PressureByte = Scale_Pressure(&Press_Result.Pressure);

    }
    else{
        // Pressure measurement was not successful, underflow or
        // overflow of ADC result, Sensor Fault Wire Bond Check,
        // or VMIN warning occurred
        PressureByte = 0;
    }

    // 8-bit scaled pressure value is in PressureByte. If pressure was
    // is 100kPa or less, or there was an error in measurement, PressureByte
    // is set to 0. If measured pressure was 450kPa or more, PressureByte
    // is set to 255. Otherwise, PressureByte contains a value proportional
    // to measured pressure, scaled by 1.373kPa/LSB for pressure above 100kPa.

}
}
```

**Figure 3** Code example for usage of Scale\_Pressure()



## 2.4 Meas\_Acceleration()

### 2.4.1 Description

This function performs an acceleration sensor measurement.

The result can be either:

- Compensated for sensitivity, offset and temperature
- Output as raw value without performing the compensation

The function can measure acceleration with up to 64 samples at a specified sample rate. The function will return the average (arithmetic mean) acceleration value in order to compensate for noise. Optionally, this function can return the maximum value of the samples. The function performs a new temperature measurement for compensating the acceleration measurements, unless a previously measured raw temperature value is supplied. Number of samples and raw temperature source are both determined by **SensorConfig**. SampleRate controls how frequently the measurement acquisitions occur and will not influence the measurement result under stable acceleration conditions. The device is set to IDLE mode during the delay between measurement acquisitions.

### 2.4.2 Actions

- Measure acceleration sensor with gain, channel and number of samples for averaging given by **SensorConfig**
- Check wire bonds between the ASIC and the sensor die & sensor beam integrity
- Average the measurement(s), or (optionally) use the maximum raw measurement, to obtain a raw acceleration value
- (optionally) Perform a raw temperature measurement
- (optionally) Compensate the raw acceleration value

### 2.4.3 Prototype

unsigned char **Meas\_Acceleration** (unsigned int **SensorConfig**, unsigned char **SampRate**, signed int idata \* **AccelResult** )

## 2.4.4 Inputs

**Table 23 Meas\_Acceleration: Input Parameters**

Register / Address	Type	Name	Description
R6 (MSB) R7 (LSB)	unsigned int	SensorConfig	Defines Sensor Configuration (refer to <a href="#">Table 24</a> and <a href="#">Table 25</a> )
R5	unsigned char	SampleRate	Defines the number of system clock cycles (12 MHz RC Oscillator) divided by 8 which is waited between consecutive measurements. <i>Note: Only applicable if SensorConfig.2-0 [2POWN2:0] greater than 1 Sample</i>
R3	signed int idata*	AccelResult	Pointer to an integer array in RAM to receive the measurement result
*AccelResult+2	signed int	Raw Temperature	Previous Raw Temperature value can optionally be used as input parameter. Refer to bit RAWTemp in SensorConfig.

**Table 24 Meas\_Acceleration: Input Parameter: SensorConfig [15:8]**

Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
RES	RES	RES	RES	RES	RES	RES	RAWTemp
RAWTemp		Selects source of raw temperature data for compensation 0 <sub>B</sub> : Perform new raw temperature measurement 1 <sub>B</sub> : Use raw temperature data supplied in *(AccelResult+2)					

**Table 25 Meas\_Acceleration: Input Parameter: SensorConfig [7:0]**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Sens_Type	RAW	GAIN.1	GAIN.0	MODE	2POWN.2	2POWN.1	2POWN.0
Sens_Type		Select Acceleration Measurement Must be set to 0 <sub>B</sub> for Acceleration Measurement					
RAW		Defines if the raw ADC result is compensated 0 <sub>B</sub> : Temperature compensation is performed. Returns Compensated & raw value 1 <sub>B</sub> : No compensation is performed. Returns only raw value. If SensorConfig bit RAWTemp is set to 1 <sub>B</sub> , no RAW temperature measurement is performed. <i>Note: See <a href="#">Table 16</a> for impact on ROM Library function output</i>					
GAIN[1:0]		Specifies the Sensor Gain: Must be set to 00 <sub>B</sub>					
MODE		Measure Mode: 0 <sub>B</sub> : Average value 1 <sub>B</sub> : Maximum value					
2POWN[2:0]		Number of ADC measurements that are taken and averaged 111 <sub>B</sub> : 64 Samples 110 <sub>B</sub> : 64 Samples 101 <sub>B</sub> : 32 Samples 100 <sub>B</sub> : 16 Samples 011 <sub>B</sub> : 8 Samples 010 <sub>B</sub> : 4 Samples 001 <sub>B</sub> : 2 Samples 000 <sub>B</sub> : 1 Sample					

**Table 26 Meas\_Acceleration: Input Parameter: SampleRate**

Bit7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SR.7	SR.6	SR.5	SR.4	SR.3	SR.2	SR.1	SR0
SR[7:0]		Number of systemclock cycles divided by 8 between two consecutive samples (only applicable if more than one sample is taken and averaged): 00 <sub>H</sub> : No delay (fastest possible sample rate) 01 <sub>H</sub> ..5E <sub>H</sub> : Not allowed 5F <sub>H</sub> ..FF <sub>H</sub> : 1/sample rate (sample rate in systemclocks divided by 8)					

## 2.4.5 Outputs

**Table 27 Meas\_Acceleration: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	StatusByte	0000.0000 <sub>B</sub> : Success xxxx.xxx1 <sub>B</sub> : Underflow of ADC Result <sup>1)</sup> xxxx.xx1x <sub>B</sub> : Overflow of ADC Result <sup>1)</sup> xxxx.x1xx <sub>B</sub> : Sensor Fault Wire Bond Check xxxx.1xxx <sub>B</sub> : Sensor Fault Diagnosis Resistor xxx1.xxxx <sub>B</sub> : VMIN warning
*AccelResult+0	signed int	Compensated Acceleration	If Input Bit SensorConfig.6[RAW] == 0: 8000 <sub>H</sub> = -2048.0 g 0000 <sub>H</sub> = 0.0 g 7FFF <sub>H</sub> = 2047.9375 g ( = 2048 g - 1 LSB where 1 LSB = 1/16 g)  If Input Bit SensorConfig.6[RAW] == 1: 8000 <sub>H</sub> since no compensation is performed
*AccelResult+1	signed int	Raw Acceleration Data	10 Bit ADC Result Value: 0000.00xx.xxxx.xxxx <sub>B</sub>
*AccelResult+2	Singed int	Raw Temperature	If Input Bit SensorConfig.6[RAW] == 0: 16 Bit scaled signed ADC Result Value  If Input Bit SensorConfig.6[RAW] == 1: 8000 <sub>H</sub> since no temperature measurement is performed

1) If the acceleration measurement result is within the input range for which its accuracy is specified (e.g. -115 g - 115 g), then the ADC underflow/overflow condition is due to a measurement failure and the measurement results are not valid. Otherwise, if the acceleration measurement result is outside of this input range, then the ADC underflow/overflow bits and the acceleration measurement results may be ignored.

## 2.4.6 Resource Usage

**Table 28 Meas\_Acceleration: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0 <sup>1)</sup> , CFG1, CFG2, DIVIC, DPH, DPL, PSW, TCON <sup>1)</sup> , TH0 <sup>1)</sup> , TL0 <sup>1)</sup> , TMOD <sup>1)</sup>
Stack	11 Bytes

1) Only affected if more than 1 sample is taken

## 2.4.7 Execution Information

**Table 29 Meas\_Acceleration: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time Compensated with new raw temperature measurement, 2 samples	$t_{comp,new}$	—	909	988	$\mu s$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0001 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time Compensated when supplied with previously obtained raw temperature value, 2 samples	$t_{comp,prevt}$	—	681	740	$\mu s$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0101 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time Raw (uncompensated) acceleration result, 2 samples	$t_{RAW}$	—	289	314	$\mu s$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0041 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Execution Time for each additional sample for averaging	$t_{sample}$	—	66	71	$\mu s$	SampleRate = 00 <sub>H</sub>
Charge Consumption Compensated with new internal raw temperature measurement, 2 samples	$Q_{comp,new}$	—	1,63	2,45	$\mu C$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0001 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption Compensated when supplied with previously obtained raw temperature value, 2 samples	$Q_{comp,prev}$	—	1,11	1,80	$\mu C$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0101 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption Raw (uncompensated) acceleration result, 2 samples	$Q_{RAW}$	—	0,54	0,76	$\mu C$	DIVIC = 00 <sub>H</sub> , SensorConfig = 0041 <sub>H</sub> , SampleRate = 00 <sub>H</sub>
Charge Consumption for each additional sample for averaging	$Q_{sample}$	—	0,136	0,17	$\mu C$	SampleRate = 00 <sub>H</sub>

## 2.4.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"

void main()
{
    // Return value of acceleration measurement is stored in StatusByte
    unsigned char StatusByte;

    // Input parameters for acceleration measurement
    unsigned int SensorConfig = 0x0001;
    unsigned char SampRate = 0x00;

    // struct for acceleration measurement results
    struct{
        signed int Acceleration;
        signed int Raw_acceleration;
        signed int Raw_temperature;
    } idata Accel_Result;

    // Acceleration measurement function call
    StatusByte = Meas_Acceleration(SensorConfig, SampRate, &Accel_Result.Acceleration);

    if(!StatusByte){
        // Acceleration measurement was successful
    }
    else{
        // Acceleration measurement was not successful, underflow or
        // overflow of ADC result, Sensor Fault Wire Bond Check,
        // Sensor Fault Diagnosis Resistor, or VMIN warning occurred
    }
}
```

**Figure 4** Code example for usage of Meas\_Acceleration()

## 2.5 Meas\_Temperature()

### 2.5.1 Description

This function performs a temperature measurement and returns both raw and compensated temperature results. The Compensated Temperature result is compensated for sensitivity and offset errors. The Raw Temperature result is uncompensated and may be used as input for [Meas\\_Sensor\(\)](#), [Meas\\_Pressure\(\)](#), [Meas\\_Acceleration\(\)](#) and [Comp\\_Temperature\(\)](#).

### 2.5.2 Actions

- Measures the temperature sensor with 2 ADC samples for averaging (arithmetic mean).
- Compensate for offset using calibration data stored in FLASH (Compensated Temperature)

### 2.5.3 Prototype

unsigned char **Meas\_Temperature** ( signed int idata \* **Temp\_Result** )

### 2.5.4 Inputs

**Table 30 Meas\_Temperature: Input Parameters**

Register / Address	Type	Name	Description
R7	signed int idata*	Temp_Result	Pointer to an integer array in RAM to receive the measurement result

### 2.5.5 Outputs

**Table 31 Meas\_Temperature: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	StatusByte	0000.0000 <sub>B</sub> : Success xxxx.xxx1 <sub>B</sub> : Underflow of ADC Result xxxx.xx1x <sub>B</sub> : Overflow of ADC Result xxx1.xxxx <sub>B</sub> : VMIN warning
*Temp_Result+0	signed int	Compensated Temperature	8000 <sub>H</sub> = -256.0 °C 0000 <sub>H</sub> = 0.0 °C 7FFF <sub>H</sub> = 255.9921875 °C ( = 256 °C - 1 LSB where 1 LSB = 1/128 °C)
*Temp_Result+1	signed int	Raw Temperature	16 Bit scaled signed ADC Result Value

## 2.5.6 Resource Usage

**Table 32 Meas\_Temperature: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0, CFG1, CFG2, DIVIC, DPH, DPL, PSW
Stack	9 Bytes

## 2.5.7 Execution Information

**Table 33 Meas\_Temperature: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t_{\text{comp}}$	–	668	726	μs	DIVIC = 00 <sub>H</sub> , by default 2 ADC measurements are taken and averaged
Charge Consumption	$Q_{\text{comp}}$	–	1,2	1,82	μC	DIVIC = 00 <sub>H</sub> , by default 2 ADC measurements are taken and averaged



## 2.5.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"

void main()
{
    // Return value of temperature measurement is stored in StatusByte
    unsigned char StatusByte;

    // struct for temperature measurement results
    struct{
        signed int Temperature;
        signed int Raw_temperature;
    } idata Temp_Result;

    // Temperature measurement function call
    StatusByte = Meas_Temperature(&Temp_Result.Temperature);

    if(!StatusByte){
        // Temperature measurement was successful
    }
    else{
        // Temperature measurement was not successful, underflow or
        // overflow of ADC result or VMIN warning occurred
    }
}
```

**Figure 5** Code example for usage of Meas\_Temperature()

## 2.6 Raw\_Temperature()

### 2.6.1 Description

This function performs a raw temperature measurement. The Raw Temperature result is uncompensated and may be used as input for [Meas\\_Sensor\(\)](#), [Meas\\_Pressure\(\)](#), [Meas\\_Acceleration\(\)](#) and [Comp\\_Temperature\(\)](#).

### 2.6.2 Actions

- Measures the temperature sensor with 2 ADC samples for averaging (arithmetic mean)

### 2.6.3 Prototype

unsigned char **Raw\_Temperature** ( signed int idata \* **TempResult** )

### 2.6.4 Inputs

**Table 34 Raw\_Temperature: Input Parameters**

Register / Address	Type	Name	Description
R7	signed int idata*	TempResult	Pointer to an integer array in RAM to receive the measurement result

### 2.6.5 Outputs

**Table 35 Raw\_Temperature: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	StatusByte	0000.0000 <sub>B</sub> : Success xxxx.xxx1 <sub>B</sub> : Underflow of ADC Result xxxx.xx1x <sub>B</sub> : Overflow of ADC Result xxx1.xxxx <sub>B</sub> : VMIN warning
*Temp_Result+1	signed int	Raw Temperature	16 Bit scaled signed ADC Result Value

## 2.6.6 Resource Usage

**Table 36 Raw\_Temperature: Resources**

Type	Used or Modified
Registers	R0, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0, CFG1, CFG2, DPH, DPL, PSW
Stack	5 Bytes

## 2.6.7 Execution Information

**Table 37 Raw\_Temperature: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t_{RAW}$	–	235	255	μs	DIVIC = 00 <sub>H</sub> , by default 2 ADC measurements are taken and averaged
Charge Consumption	$Q_{RAW}$	–	0,451	0,652	μC	DIVIC = 00 <sub>H</sub> , by default 2 ADC measurements are taken and averaged

## 2.7 Comp\_Temperature()

### 2.7.1 Description

This function will convert a previously obtained raw temperature value into a compensated temperature value. This function can be called after a pressure, acceleration or raw temperature measurement to compensate the raw temperature. Thus, the current ambient temperature is obtained without taking an extra temperature measurement.

### 2.7.2 Actions

- Compensate raw temperature data using calibration data stored in FLASH.

### 2.7.3 Prototype

unsigned char **Comp\_Temperature** (signed int idata **TempRawIn**, signed int idata \* **TempResult**)

### 2.7.4 Inputs

**Table 38 Comp\_Temperature: Input Parameters**

Register / Address	Type	Name	Description
R6(MSB), R7(LSB)	signed int idata	TempRawIn	Raw measurement value (gathered from Meas_Pressure() or Meas_Acceleration() or Raw_Temperature)
R5	signed int idata*	Temp_Result	Pointer to an integer array in RAM to receive the measurement result

### 2.7.5 Outputs

**Table 39 Comp\_Temperature: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	StatusByte	0000.0000 <sub>B</sub> : Success xxxx.xxx1 <sub>B</sub> : Underflow of Result xxxx.xx1x <sub>B</sub> : Overflow of Result
*Temp_Result	signed int	Compensated Temperature	8000 <sub>H</sub> = -256.0 °C 0000 <sub>H</sub> = 0.0 °C 7FFF <sub>H</sub> = 255.9921875 °C ( = 256 °C - 1 LSB where 1 LSB = 1/128 °C)
*Temp_Result+1	signed int	Raw Temperature	16 Bit scaled signed ADC Result Value

## 2.7.6 Resource Usage

**Table 40**    **Comp\_Temperature: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, DPH, DPL, PSW
Stack	4 Bytes

## 2.7.7 Execution Information

**Table 41**    **Comp\_Temperature: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	420	454	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,63	1,089	μC	DIVIC = 00 <sub>H</sub>

## 2.7.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"

void main()
{
    // Return value of pressure and temperature measurement is stored in StatusByte
    unsigned char StatusByte;

    // Input parameters for pressure measurement
    unsigned int SensorConfig = 0x0081;
    unsigned char SampRate = 0x00;

    // struct for pressure measurement results
    struct{
        signed int Pressure;
        signed int Raw_pressure;
        signed int Raw_temperature;
    } idata Press_Result;

    // struct for compensated temperature results
    struct{
        signed int Temperature;
        signed int Raw_temperature;
    } idata Temp_Result;

    // Pressure measurement function call
    StatusByte = Meas_Pressure(SensorConfig, SampRate, &Press_Result.Pressure);

    if(!StatusByte){
        // Pressure measurement was successful
    }
    else{
        // Pressure measurement was not successful, underflow or
        // overflow of ADC result, Sensor Fault Wire Bond Check,
        // or VMIN warning occurred
    }

    // Compensate Temperature function call
    StatusByte = Comp_Temperature(Press_Result.Raw_temperature, &Temp_Result.Temperature);

    if(!StatusByte){
        // Temperature compensation was successful
    }
    else{
        // Temperature compensation was not successful, underflow or
        // overflow during compensation occurred
    }
}
```

**Figure 6** Code example for usage of Comp\_Temperature()

## 2.8 Meas\_Supply\_Voltage()

### 2.8.1 Description

This function performs a battery voltage measurement and returns both raw and compensated voltage results. The Compensated battery voltage result is compensated for offset error.

### 2.8.2 Actions

- Measure the supply voltage sensor with 2 ADC samples for averaging
- Compensate for offset using calibration data stored in FLASH

### 2.8.3 Prototype

unsigned char **Meas\_Supply\_Voltage** ( signed int idata \* **Batt\_Result** )

### 2.8.4 Inputs

**Table 42 Meas\_Supply\_Voltage: Input Parameters**

Register / Address	Type	Name	Description
R7	signed int idata*	Batt_Result	Pointer to an integer array in RAM to receive the measurement result

### 2.8.5 Outputs

**Table 43 Meas\_Supply\_Voltage: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	StatusByte	0000.0000 <sub>B</sub> : Success xxxx.xxx1 <sub>B</sub> : Underflow of ADC Result xxxx.xx1x <sub>B</sub> : Overflow of ADC Result
*Batt_Result+0	signed int	Compensated battery voltage	8000 <sub>H</sub> = -4096.0 mV (Only theoretical number) 0000 <sub>H</sub> = 0.0 mV 7FFF <sub>H</sub> = 4095.875 mV ( = 4096 mV - 1 LSB where 1 LSB = 1/8 mV)
*Batt_Result+1	signed int	Raw battery voltage	10 Bit ADC Result Value: 0000.00xx.xxxx.xxxx <sub>B</sub>

## 2.8.6 Resource Usage

**Table 44** Meas\_Supply\_Voltage: Resources

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0, CFG1, CFG2, DIVIC, DPH, DPL, PSW
Stack	3 Bytes

## 2.8.7 Execution Information

**Table 45** Meas\_Supply\_Voltage: Execution Time and Charge Consumption

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	373	405	μs	DIVIC = 00 <sub>H</sub> , by default 2 ADC measurements are taken and averaged
Charge Consumption	$Q$	–	0,634	1,01	μC	DIVIC = 00 <sub>H</sub> , by default 2 ADC measurements are taken and averaged



## 2.8.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"

void main()
{
    // Return value of battery voltage measurement is stored in StatusByte
    unsigned char StatusByte;

    // struct for battery voltage measurement results
    struct{
        signed int Voltage;
        signed int Raw_voltage;
    } idata Volt_Result;

    // Battery voltage measurement function call
    StatusByte = Meas_Supply_Voltage(&Volt_Result.Voltage);

    if(!StatusByte){
        // Battery voltage measurement was successful
    }
    else{
        // Battery voltage measurement was not successful, underflow or
        // overflow of ADC result occurred
    }
}
```

**Figure 7** Code example for usage of Meas\_Supply\_Voltage()

## 2.9 Start\_Supply\_Voltage()

### 2.9.1 Description

The battery voltage typically shows a significant drop during RF transmission, when a considerable current is drawn. Calling the monolithic function **Meas\_Supply\_Voltage()** during RF transmission is often not feasible because of its execution time.

A set of three functions to allow battery voltage measurement during RF transmission has been implemented; **Start\_Supply\_Voltage()**, **Trig\_Supply\_Voltage()** and **Get\_Supply\_Voltage()**. These functions must be called in this particular sequence, and each function is described in separate detail.

**Start\_Supply\_Voltage()** enables and configures the ADC, allows settling of the analogue ADC part, and places the ADC into standby state. It must be called prior to calling the **Trig\_Supply\_Voltage()** function.

### 2.9.2 Actions

- Prepare the ADC and the Supply Voltage Sensor for a measurement

### 2.9.3 Prototype

unsigned char **Start\_Supply\_Voltage** ( void )

### 2.9.4 Inputs

**Table 46 Start\_Supply\_Voltage: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.9.5 Outputs

**Table 47 Start\_Supply\_Voltage: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	Status Byte	Always returns 0

### 2.9.6 Resource Usage

**Table 48 Start\_Supply\_Voltage: Resources**

Type	Used or Modified
Registers	R7
SFR	ACC
Stack	0 Bytes

## 2.9.7 Execution Information

**Table 49 Start\_Supply\_Voltage: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	12	13	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,018	0,030	μC	DIVIC = 00 <sub>H</sub>

## 2.9.8 Code Example

See [Figure 8 “Code example for usage of the functions Start\\_Supply\\_Voltage, Trig\\_Supply\\_Voltage and Get\\_Supply\\_Voltage\(\)”](#) on Page 60

## 2.10 Trig\_Supply\_Voltage()

### 2.10.1 Description

Trig\_Supply\_Voltage() is the second part of a set of three functions to measure the battery voltage during RF transmission. It is called after Start\_Supply\_Voltage(), and triggers an ADC battery voltage measurement. Upon the call of this function the ADC resumes from standby, performs a measurement and then goes back to standby, keeping the result. Typically this function is called by the application immediately after an RF datagram byte is shifted into SFR RFD to prevent disruption of RF data transmission.

### 2.10.2 Actions

- Bring ADC from standby to active state
- Measure the supply voltage sensor with ADC
- Place ADC into standby state

### 2.10.3 Prototype

void Trig\_Supply\_Voltage ( void )

### 2.10.4 Inputs

**Table 50 Trig\_Supply\_Voltage: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.10.5 Outputs

**Table 51 Trig\_Supply\_Voltage: Output values**

Register/ Address	Type	Name	Description
None	---	---	---

### 2.10.6 Resource Usage

**Table 52 Trig\_Supply\_Voltage: Resources**

Type	Used or Modified
Registers	---
SFR	---
Stack	0 Bytes

## 2.10.7 Execution Information

**Table 53** Trig\_Supply\_Voltage: Execution Time and Charge Consumption

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t_{\text{DIVIC}=0}$	—	3	4	μs	DIVIC = 00 <sub>H</sub>
	$t_{\text{DIVIC}=3}$	—	192	208	μs	DIVIC = 03 <sub>H</sub>
Charge Consumption	$Q_{\text{DIVIC}=0}$	—	0,005	0,008	μC	DIVIC = 00 <sub>H</sub>
	$Q_{\text{DIVIC}=3}$	—	0,154	0,354	μC	DIVIC = 03 <sub>H</sub>

## 2.10.8 Code Example

See [Figure 8 “Code example for usage of the functions Start\\_Supply\\_Voltage, Trig\\_Supply\\_Voltage and Get\\_Supply\\_Voltage\(\)”](#) on Page 60

## 2.11 Get\_Supply\_Voltage()

### 2.11.1 Description

Get\_Supply\_Voltage() is the third part of a set of three functions to measure the battery voltage during RF transmission. It reads the measured value obtained during Trig\_Supply\_Voltage(), turns off the ADC, and performs battery voltage compensation. Typically this function is called by the application after the RF transmission is finished.

### 2.11.2 Actions

- Read the ADC result register
- Turn off ADC
- Compensate the result for offset using calibration data stored in FLASH

### 2.11.3 Prototype

unsigned char **Get\_Supply\_Voltage** ( signed int idata \* **Batt\_Result** )

### 2.11.4 Inputs

**Table 54 Get\_Supply\_Voltage: Input Parameters**

Register / Address	Type	Name	Description
R7	signed int idata*	Batt_Result	Pointer to an integer array in RAM to receive the measurement result

### 2.11.5 Outputs

**Table 55 Get\_Supply\_Voltage: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	StatusByte	0000.0000 <sub>B</sub> : Success xxxx.xxx1 <sub>B</sub> : Underflow of ADC Result xxxx.xx1x <sub>B</sub> : Overflow of ADC Result
*Batt_Result+0	signed int	Compensated battery voltage	8000 <sub>H</sub> = -4096.0 mV (Only theoretical number) 0000 <sub>H</sub> = 0.0 mV 7FFF <sub>H</sub> = 4095.875 mV ( = 4096 mV - 1 LSB where 1 LSB = 1/8 mV)
*Batt_Result+1	signed int	Raw battery voltage	10 Bit ADC Result Value: 0000.00xx.xxxx.xxxx <sub>B</sub>

## 2.11.6 Resource Usage

**Table 56**    **Get\_Supply\_Voltage: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG1, CFG2, DIVIC, DPH, DHL, PSW
Stack	3 Bytes

## 2.11.7 Execution Information

**Table 57**    **Get\_Supply\_Voltage: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	205	222	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,308	0,532	μC	DIVIC = 00 <sub>H</sub>

## 2.11.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"

void main()
{
    // Return value of battery voltage measurement is stored in StatusByte
    unsigned char StatusByte;

    // struct for battery voltage measurement results
    struct{
        signed int Voltage;
        signed int Raw_voltage;
    } idata Volt_Result;

    // ADC setup for supply voltage measurement is done before real time critical
    // function is executed
    Start_Supply_Voltage();

    // real time critical function starts here
    // ...
    Trig_Supply_Voltage();
    // ...
    // end of real time critical function

    // Get the measurement result after the real time critical function
    StatusByte = Get_Supply_Voltage(&Volt_Result.Voltage);

    if(!StatusByte){
        // Battery voltage measurement was successful
    }
    else{
        // Battery voltage measurement was not successful, underflow or
        // overflow of ADC result occurred
    }
}
```

**Figure 8** Code example for usage of the functions **Start\_Supply\_Voltage**, **Trig\_Supply\_Voltage** and **Get\_Supply\_Voltage()**



## 2.12 ADC\_Selftest()

### 2.12.1 Description

The ADC self test is a combination of three measurements that use various channels as input and reference for the ADC. The output of this function is the delta deviation from the ideal value.

### 2.12.2 Actions

- Perform three ADC measurements
- Calculate delta from ideal value

### 2.12.3 Prototype

unsigned char **ADC\_Selftest**(signed int idata \* **Delta**)

### 2.12.4 Inputs

**Table 58 ADC\_Selftest: Input Parameters**

Register / Address	Type	Name	Description
R7	signed int idata*	Delta	Pointer to an integer array in RAM to receive the ADC measurement result

### 2.12.5 Outputs

**Table 59 ADC\_Selftest: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	StatusByte	0000.0000 <sub>B</sub> : Success xxxx.xxx1 <sub>B</sub> : Underflow of ADC Result xxxx.xx1x <sub>B</sub> : Overflow of ADC Result
*Delta	signed int idata*	Delta	The ADC can be considered as working when the value of Delta is between +/-6 LSBs after a call of this function during which the supply voltage was constant.

## 2.12.6 Resource Usage

**Table 60 ADC\_Selftest: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0, DIVIC, DPH, DPL
Stack	7 Bytes

## 2.12.7 Execution Information

**Table 61 ADC\_Selftest: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	645	701	μs	DIVIC = 00 <sub>H</sub> , 3 Numbers of ADC measurements are taken
Charge Consumption	$Q$	–	1,2	1,84	μC	DIVIC = 00 <sub>H</sub> 3 ADC measurements are taken

## **2.13 Powerdown()**

### **2.13.1 Description**

This function forces the device to POWER DOWN state.

### **2.13.2 Actions**

- If an RF Transmission is in process, wait until it has completed
- If the SFR ITPR has been updated, wait for the Interval Timer to initialize
- Enter POWER DOWN state

### **2.13.3 Prototype**

void **Powerdown**(void)

### **2.13.4 Inputs**

**Table 62 Powerdown: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### **2.13.5 Outputs**

**Table 63 Powerdown: Output values**

Register/ Address	Type	Name	Description
None	---	---	---

### **2.13.6 Resource Usage**

**Table 64 Powerdown: Resources**

Type	Used or Modified
Registers	---
SFR	ACC, CFG0, RFS
Stack	0 Bytes

## 2.13.7 Execution Information

**Table 65 Powerdown: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	9	16,2	μs	DIVIC = 00 <sub>H</sub> , ITinit = 0, RFSE = 1 before entering PDWN
Charge Consumption	$Q$	–	0,014	0,04	μC	DIVIC = 00 <sub>H</sub> , ITinit = 0, RFSE = 1 before entering PDWN

## 2.14 ThermalShutdown()

### 2.14.1 Description

This function forces the device to THERMAL SHUTDOWN state.

The application should call this function whenever the ambient temperature is close to the maximum operating range (this can be detected by using [Meas\\_Temperature\(\)](#)) to protect the device while the ambient temperature is above the specified operating conditions.

If this function is called when the temperature is below the TMAX threshold, the function will return without any action and the application program will continue uninterrupted. If the temperature is above the TMAX threshold, the TMAX threshold will be reduced (software hysteresis) and the THERMAL SHUTDOWN state is entered.

### 2.14.2 Actions

- Turn on the TMAX Detector
- Enter THERMAL SHUTDOWN state with hysteresis if TMAX Detector is set.

### 2.14.3 Prototype

void **ThermalShutdown**(void)

### 2.14.4 Inputs

**Table 66 ThermalShutdown: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.14.5 Outputs

**Table 67 ThermalShutdown: Output values**

Register/ Address	Type	Name	Description
None	---	---	---

### 2.14.6 Resource Usage

**Table 68 ThermalShutdown: Resources**

Type	Used or Modified
Registers	R7
SFR	ACC, CFG0, DPH, DPL, PSW
Stack	0 Bytes

## 2.14.7 Execution Information

**Table 69 ThermalShutdown: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t_{T<TMAX}$	—	73	79	μs	Temp. < TMAX: function will return without any action, DIVIC = 00 <sub>H</sub>
	$t_{T>TMAX}$	—	71	77	μs	Temp. > TMAX: function will enter THERMAL SHUTDOWN state, DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q_{T<TMAX}$	—	0,109	0,188	μC	Temp. < TMAX: function will return without any action, DIVIC = 00 <sub>H</sub>
	$Q_{T>TMAX}$	—	0,106	0,183	μC	Temp. > TMAX: function will enter THERMAL SHUTDOWN state, DIVIC = 00 <sub>H</sub>

## 2.15 StartXtalOsc()

### 2.15.1 Description

This function enables the crystal oscillator clock and delays for a defined amount of time. The delay time should be long enough that the crystal oscillator is stable, which is determined by the crystal startup time (see [1]). The minimum/maximum tolerance of the delay time may be derived by considering the tolerance of the 12 MHz RC Oscillator (see [1]).

### 2.15.2 Actions

- Enable the crystal oscillator clock
- Wait in IDLE for set Delay time

### 2.15.3 Prototype

signed char **StartXtalOsc**(unsigned char **Delay**)

### 2.15.4 Inputs

**Table 70 StartXtalOsc: Input Parameters**

Register / Address	Type	Name	Description
R7	unsigned char	Delay	Delay time to wait in IDLE after XTAL is enabled. Duration[μs] = Delay x 42.67[μs]

### 2.15.5 Outputs

**Table 71 StartXtalOsc: Output values**

Register/Address	Type	Name	Description
R7	signed char	StatusByte	StatusByte: 0: XTAL started and delay passed -1: XTAL already on (no action)

### 2.15.6 Resource Usage

**Table 72 StartXtalOsc: Resources**

Type	Used or Modified
Registers	R7
SFR	ACC, B, CFG0, DPTR, DIVIC, PSW, REF, TCON, TH0, TL0, TMOD
Stack	0 Bytes



## 2.15.7 Execution Information

**Table 73 StartXtalOsc: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t_{30}$	–	1313	1430	μs	DIVIC is 0; delay is 30
	$t_{40}$	–	1740	1891	μs	DIVIC is 0; delay is 40
	$t_{\text{delta}}$	–	42,7	46,1	μs	DIVIC is 0; delta delay is 1
Charge Consumption	$Q_{30}$	–	1,21	2,13	μC	DIVIC is 0; delay is 30
	$Q_{40}$	–	1,59	2,81	μC	DIVIC is 0; delay is 40
	$Q_{\text{delta}}$	–	0,04	0,07	μC	DIVIC is 0; delta delay is 1

## 2.15.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"
#include "Reg_SP37.h"

void main()
{
    // Return value of start xtal oscillator is stored in StatusByte
    unsigned char StatusByte;

    // Input parameters for start xtal oscillator
    unsigned char Delay = 33;

    // Start xtal oscillator function call
    StatusByte = StartXtalOsc(Delay);
}
```

**Figure 9 Code example for usage of StartXtalOsc()**

## 2.16 StopXtalOsc()

### 2.16.1 Description

This function disables the crystal oscillator clock if no other peripherals are using it. Therefore, peripherals using the crystal oscillator should be disabled prior to calling this function.

### 2.16.2 Actions

- Attempt to disable the crystal oscillator clock.

### 2.16.3 Prototype

signed char **StopXtalOsc**(void)

### 2.16.4 Inputs

**Table 74 StopXtalOsc: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.16.5 Outputs

**Table 75 StopXtalOsc: Output values**

Register/Address	Type	Name	Description
R7	signed char	StatusByte	StatusByte: 0: XTAL stopped -1: XTAL already off (no action) -2: XTAL not stopped because it is still needed (e.g. due to an ongoing RF transmission)

### 2.16.6 Resource Usage

**Table 76 StopXtalOsc: Resources**

Type	Used or Modified
Registers	R7
SFR	ACC,B, CFG0, DPTR, PSW, RFS, TMOD
Stack	0 Bytes

## 2.16.7 Execution Information

**Table 77 StopXtalOsc: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	20	22	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,035	0,058	μC	DIVIC = 00 <sub>H</sub>

## 2.16.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"
#include "Reg_SP37.h"

// Defines
#define bitmask_TMOD_CLK 0x08
#define bitmask_RFS_RFSE 0x02

void main()
{
    // Return value of stop xtal oscillator is stored in StatusByte
    signed char StatusByte;

    while (!(RFS & bitmask_RFS_RFSE));           // Wait for RF Transmission to end
    RFC &= ~0x03;                                // Disable PA & PLL
    TMOD &= ~bitmask_TMOD_CLK;                   // Clear TMOD_CLK

    StatusByte = StopXtalOsc();                   // Stop XTAL oscillator

    if(StatusByte != -2){
        // Xtal oscillator is stopped or was already off
    }
    else{
        // XTAL oscillator not stopped; it is still needed (e.g. RF transmission not completed)
        // ...
    }
}
```

**Figure 10 Code example for usage of StopXtalOsc()**

## 2.17 PLL\_Ref\_Signal\_Check()

### 2.17.1 Description

This function can be called prior to [VCO\\_Tuning\(\)](#) routine to test the lowest and highest VCO tuning curves that are disjoint in terms of operating frequencies. If the PLL Lock Detector indicates lock for both of the disjoint VCO tuning curves, a malfunction of the Crystal Resonator is most likely the source of the fault.

### 2.17.2 Actions

- Select the lowest tuning curve and check the PLL Lock Detector result
- Select the highest tuning curve and check the PLL Lock Detector result

### 2.17.3 Prototype

signed char **PLL\_Ref\_Signal\_Check**(void)

### 2.17.4 Inputs

**Table 78 PLL\_Ref\_Signal\_Check: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.17.5 Outputs

**Table 79 PLL\_Ref\_Signal\_Check: Output values**

Register/Address	Type	Name	Description
R7	signed char	StatusByte	StatusByte: 0: PLL Reference Signal available -1: No PLL Reference Signal available

### 2.17.6 Resource Usage

**Table 80 PLL\_Ref\_Signal\_Check: Resources**

Type	Used or Modified
Registers	R7
SFR	ACC, B, PSW, DIVIC, DPTR
Stack	2 Bytes

## 2.17.7 Execution Information

**Table 81 PLL\_Ref\_Signal\_Check: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	273	295	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,41	0,71	μC	DIVIC = 00 <sub>H</sub>

## 2.18 VCO\_Tuning()

### 2.18.1 Description

This function selects an appropriate tuning curve for the VCO and enables the PLL. If no proper tuning curve could be selected the PLL will be disabled before the function returns with an error result.

#### Notes

1. If RF transmission is not performed immediately after this function is called, it is recommended to disable the PLL by clearing SFR bit RFC.1[ENPLL] to reduce the current consumption.
2. Re-Calibration of the tuning curve is necessary when  $V_{BAT}$  changes more than 800mV or  $T_{Ambient}$  changes more than 70 °C

### 2.18.2 Actions

- Select appropriate tuning curve
- Enable PLL for a RF transmission
- Wait until PLL is locked

### 2.18.3 Prototype

signed char **VCO\_Tuning**(void)

### 2.18.4 Inputs

**Table 82 VCO\_Tuning: Input Parameters**

Register / Address	Type	Name	Description
None	void	---	---

### 2.18.5 Outputs

VCO\_Tuning: Output values

Register/ Address	Type	Name	Description
R7	signed char	StatusByte	StatusByte: 0: Success of VCO Tuning -1: VCO Tuning not successful, PLL disabled -2: XTAL not enabled (crystal required)

## 2.18.6 Resource Usage

**Table 83 VCO\_Tuning: Resources**

Type	Used or Modified
Registers	R0, R1, R5, R6, R7
SFR	ACC, DIVIC, PSW, RFC
Stack	4 Bytes

## 2.18.7 Execution Information

**Table 84 VCO\_Tuning: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t_{\text{firstTUN}}$	–	2360	2560	μs	First tuning (after RESET), DIVIC is 00 <sub>H</sub>
	$t_{\text{reTUN}}$	–	915	989	μs	Re-tuning, DIVIC is 00 <sub>H</sub>
Charge Consumption	$Q_{\text{firstTUN}}$	–	14,2	24,1	μC	First tuning (after RESET), DIVIC is 00 <sub>H</sub>
	$Q_{\text{reTUN}}$	–	5,524	9,2	μC	Re-tuning, DIVIC is 00 <sub>H</sub>

## 2.19 IntervalTimerCalibration()

### 2.19.1 Description

This function initiates a calibration of the Interval Timer precounter (ITPL and ITPH) to obtain a specific interval timer timebase between 1Hz and 20Hz. The function can work with both clock sources (12MHz RC Clock and Crystal clock), utilizing a special timer mode.

*Note: To obtain the best possible Interval Timer accuracy, this function should be called after the crystal oscillator has already been enabled.*

In case the crystal oscillator is used the crystal frequency in Hz divided by 2 has to be stored in the FLASH user configuration sector at address 57FA<sub>H</sub> (MSByte) to 57FC<sub>H</sub> (LSByte). If the value found at this FLASH location is not within the range of 9 MHz to 10 MHz a default clock frequency of 9.843750 MHz (XTAL/2 for 315 MHz carrier) is assumed for the tuning.

In addition, this function automatically calibrates the LF On/Off Timer precounter (SFR LFOOTP) to 50 ms.

### 2.19.2 Actions

- Calibrate the interval timer precounter (SFR ITPL, SFR ITPH) to the value passed in WU\_Frequency
- Calibrate the LF On/Off Timer precounter (SFR LFOOTP) to 50 ms

### 2.19.3 Prototype

signed char IntervalTimerCalibration(unsigned char WU\_Frequency)

### 2.19.4 Inputs

**Table 85 IntervalTimerCalibration: Input Parameters**

Register / Address	Type	Name	Description
R7	unsigned char	WU_Frequency	Base frequency of the interval timer precounter [Hz] 1dec: 1 Hz (precounter time ~1000 ms) 2dec: 2 Hz (precounter time ~500 ms) ... 19dec: 19 Hz (precounter time ~53 ms) 20dec: 20 Hz (precounter time ~50 ms)



## 2.19.5 Outputs

**Table 86 IntervalTimerCalibration: Output values**

Register/ Address	Type	Name	Description
R7	signed char	StatusByte	StatusByte: 0: Success -1: No valid crystal frequency found in FLASH -2: Input parameter out of range

## 2.19.6 Resource Usage

**Table 87 IntervalTimerCalibration: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0, DPTR, ITPH, ITPL, LFOOTP, PSW, TCON, TH0, TH1, TL0, TL1, TMOD
Stack	2 Bytes

## 2.19.7 Execution Information

**Table 88 IntervalTimerCalibration: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t_{12\text{MHz}}$	—	1180	1670	μs	DIVIC = 00 <sub>H</sub> , Clock Source is 12 MHz RC HF Oscillator
Execution Time	$t_{\text{XTAL}}$	—	1120	1560	μs	DIVIC = 00 <sub>H</sub> , Clock Source is XTAL
Charge Consumption	$Q_{12\text{MHz}}$	—	1,22	2,54	μC	DIVIC = 00 <sub>H</sub> , Clock Source is 12 MHz RC HF Oscillator
Charge Consumption	$Q_{\text{XTAL}}$	—	1,58	3,02	μC	DIVIC = 00 <sub>H</sub> , Clock Source is XTAL

## 2.20 LFBaudrateCalibration()

### 2.20.1 Description

Calling this function calibrates the LF baudrate divider using the crystal oscillator as a frequency reference, thus reducing the impact of offset and the current drift of the LF RC Oscillator upon the LF baudrate accuracy.

It is mandatory to call this function prior to the first use of the LF Receiver.

The calibrated SFR LFDIV value may be stored in the FLASH and loaded into SFR LFDIV anytime the LF Receiver is operated. If this calibration is performed regularly by the application, the bitrate tolerance of the transmitted LF data may be increased beyond the value normally specified (see [1]).

Prior to calling this function the crystal oscillator must be enabled by calling StartXtalOsc() and the crystal frequency in Hz divided by 2 has to be stored in the FLASH user configuration sector at address 57FA<sub>H</sub> (MSByte) to 57FC<sub>H</sub> (LSByte). If the value found at this FLASH location is not within the range of 9 MHz to 10 MHz a default clock frequency of 9.843750 MHz (XTAL/2 for 315 MHz carrier) is used for the tuning and the function returns an error in the StatusByte and sets SFR LFDIV to a nominal value.

### 2.20.2 Actions

- Set SFR LFDIV according to the current frequency of the LF RC Oscillator

### 2.20.3 Prototype

signed char **LFBaudrateCalibration**(unsigned int **baudrate**)

### 2.20.4 Inputs

**Table 89 LFBaudrateCalibration: Input Parameters**

Register / Address	Type	Name	Description
R6, R7	unsigned int	baudrate	Baudrate 3900dec: 3900 baud

### 2.20.5 Outputs

**Table 90 LFBaudrateCalibration: Output values**

Register/ Address	Type	Name	Description
R7	signed char	StatusByte	StatusByte: 0: Success -1: XTAL frequency out of range -2: XTAL not enabled or input parameter out of range

## 2.20.6 Resource Usage

**Table 91 LFBaudrateCalibration: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0, DPTR, LFDIV, PSW, TCON, TMOD, TH0, TH1, TL0, TL1
Stack	4 Bytes

## 2.20.7 Execution Information

**Table 92 LFBaudrateCalibration: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t_{XTAL}$	–	973	1060	μs	Baudrate = 3900 DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q_{XTAL}$	–	1,55	2,54	μC	Baudrate = 3900 DIVIC = 00 <sub>H</sub>

## 2.21 **SMulIntInt() (16Bit \* 16Bit)**

### 2.21.1 **Description**

This function multiplies the first signed int value (16bit) Multiplicand1 by the second signed int value (16bit) Multiplicand2 and produces a 32-bit signed result.

### 2.21.2 **Actions**

- Perform multiplication

### 2.21.3 **Prototype**

void **SMulIntInt**(signed int idata \* **Multiplicand1**, signed int idata \* **Multiplicand2**, signed long idata \* **Product**)

### 2.21.4 **Inputs**

**Table 93 SMulIntInt: Input Parameters**

Register / Address	Type	Name	Description
R7	signed int idata*	Multiplicand1	Pointer to Multiplicand1
R5	signed int idata*	Multiplicand2	Pointer to Multiplicand2
R3	signed long idata*	Product	Pointer to an long array in RAM to the 32 Bit multiplication Product (Multiplicand1 * Multiplicand2)

### 2.21.5 **Outputs**

**Table 94 SMulIntInt: Output values**

Register/ Address	Type	Name	Description
None	---	---	---

### 2.21.6 **Resource Usage**

**Table 95 SMulIntInt: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, PSW
Stack	0 Bytes

## 2.21.7 Execution Information

**Table 96** SMullIntInt: Execution Time and Charge Consumption

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	75	81	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,112	0,194	μC	DIVIC = 00 <sub>H</sub>

## 2.22 UDivLongLong() (32Bit : 32Bit)

### 2.22.1 Description

This function divides the unsigned long value (32bit) Dividend by the unsigned long value (32bit) Divisor.

### 2.22.2 Actions

- Perform division

### 2.22.3 Prototype

unsigned long **UDivLongLong**(unsigned long idata \* **Dividend**, unsigned long idata \* **Divisor**)

### 2.22.4 Inputs

**Table 97 UDivLongLong: Input Parameters**

Register / Address	Type	Name	Description
R7	unsigned long idata*	Dividend	Pointer to 32 bit Dividend
R5	unsigned long idata*	Divisor	Pointer to 32 bit Divisor

### 2.22.5 Outputs

**Table 98 UDivLongLong: Output values**

Register/ Address	Type	Name	Description
R4(MSB), R5, R6, R7(LSB)	unsigned long	Quotient	32 bit Quotient of the division (Dividend / Divisor)

*Note: The output value for the remainder can be found in R0 (MSB), R1, R2, R3 (LSB).*

### 2.22.6 Resource Usage

**Table 99 UDivLongLong: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, DPH, DPL, PSW
Stack	0 Bytes

## 2.22.7 Execution Information

**Table 100 UDivLongLong: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	387	418	$\mu\text{s}$	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,581	1,004	$\mu\text{C}$	DIVIC = 00 <sub>H</sub>

## 2.23 UDivIntInt() (16Bit : 16Bit)

### 2.23.1 Description

This function divides the unsigned int value (16bit) Dividend by the unsigned int value (16bit) Divisor.

### 2.23.2 Actions

- Perform division

### 2.23.3 Prototype

unsigned int **UDivIntInt**(unsigned int **Dividend**, unsigned int **Divisor**)

### 2.23.4 Inputs

**Table 101 UDivIntInt: Input Parameters**

Register / Address	Type	Name	Description
R6(MSB) R7(LSB)	unsigned int	Dividend	16 bit Dividend
R4(MSB) R5(LSB)	unsigned int	Divisor	16 bit Divisor

### 2.23.5 Outputs

**Table 102 UDivIntInt: Output values**

Register/ Address	Type	Name	Description
R6(MSB), R7(LSB)	unsigned int	Quotient	16 bit Quotient of the division (Dividend / Divisor)

*Note: The output value for the remainder can be found in R4 (MSB) and R5 (LSB).*

### 2.23.6 Resource Usage

**Table 103 UDivIntInt: Resources**

Type	Used or Modified
Registers	R0, R4, R5, R6, R7
SFR	ACC, B, PSW
Stack	0 Bytes



## 2.23.7 Execution Information

**Table 104 UDivIntInt: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	104	113	$\mu\text{s}$	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,156	0,270	$\mu\text{C}$	DIVIC = 00 <sub>H</sub>

## 2.24 CRC8\_Calc()

### 2.24.1 Description

This function calculates the CRC-8 checksum for a memory area in RAM using a fixed polynomial ( $x^8+x^2+x+1$ ). The CRC-8 calculation starts with a defined preload value.

### 2.24.2 Actions

- Calculate CRC-8

### 2.24.3 Prototype

unsigned char **CRC8\_Calc**(unsigned char **Preload**, unsigned char idata \* **BlockStart**, unsigned char **BlockLength**)

### 2.24.4 Inputs

**Table 105 CRC8\_Calc: Input Parameters**

Register / Address	Type	Name	Description
R7	unsigned char	Preload	Preload Value for the CRC Calculation. According to CCITT a value FF <sub>H</sub> is recommended.
R5	unsigned char idata*	BlockStart	Pointer to first Byte of the Data that is to be used for calculating checksum
R3	unsigned char	BlockLength	Length in Bytes of Block that is used for calculation of the checksum, starting with *BlockStart.

### 2.24.5 Outputs

**Table 106 CRC8\_Calc: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	CRC_Result	Calculated CRC8 checksum

### 2.24.6 Resource Usage

**Table 107 CRC8\_Calc: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R7
SFR	ACC, PSW
Stack	0 Bytes

## 2.24.7 Execution Information

**Table 108 CRC8\_Calc: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	$8 + x \cdot 9$	$9 + x \cdot 10$	$\mu\text{s}$	DIVIC = 00 <sub>H</sub> , x is the number of bytes
Charge Consumption	$Q$	–	$0,012 + x \cdot 0,013$	$0,021 + x \cdot 0,023$	$\mu\text{C}$	DIVIC = 00 <sub>H</sub> , x is the number of bytes

## 2.25 CRC\_Baicheva\_Calc()

### 2.25.1 Description

This function calculates a 8-bit CRC checksum for a memory area in RAM using a fixed polynomial ( $x^8+x^5+x^3+x^2+x+1$ ). It supports the standardized TPMS data protocol from the German Association of the Automotive Industry (VDA) and is optimal for data word length of 119 bits and below. The CRC Baicheva calculation starts with a defined preload value. The VDA protocol requires that a preload value of AA<sub>H</sub> be used.

### 2.25.2 Actions

- Calculate CRC Baicheva

### 2.25.3 Prototype

unsigned char **CRC\_Baicheva\_Calc**(unsigned char **Preload**, unsigned char idata \* **BlockStart**, unsigned char **BlockLength**)

### 2.25.4 Inputs

**Table 109 CRC\_Baicheva\_Calc: Input Parameters**

Register / Address	Type	Name	Description
R7	unsigned char	Preload	Preload Value for the CRC Calculation. According to VDA protocol value AA <sub>H</sub> is used.
R5	unsigned char idata*	BlockStart	Pointer to first Byte of the Data that is to be used for calculating checksum.
R3	unsigned char	BlockLength	Length in Bytes of Block that is used for calculation of the checksum, starting with *BlockStart.

### 2.25.5 Outputs

**Table 110 CRC\_Baicheva\_Calc: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	CRC_Result	Calculated CRC Baicheva checksum

### 2.25.6 Resource Usage

**Table 111 CRC8\_Baicheva\_Calc: Resources**

Type	Used or Modified
Registers	R0, R3, R5, R6, R7

**Table 111 CRC8\_Baicheva\_Calc: Resources (cont'd)**

Type	Used or Modified
SFR	ACC, PSW
Stack	0 Bytes

## 2.25.7 Execution Information

**Table 112 CRC\_Baicheva\_Calc: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	11 + x*85	12 + x*92	μs	DIVIC = 00 <sub>H</sub> , x is the number of bytes
Charge Consumption	$Q$	–	0,016 + x*0,128	0,028 + x*0,221	μC	DIVIC = 00 <sub>H</sub> , x is the number of bytes

## 2.26 Read\_ID()

### 2.26.1 Description

This function returns the unique serial number of the device and a product description code.

### 2.26.2 Actions

- Read 4-byte ID (from Flash Address: 5850<sub>H</sub> (MSB)...5853<sub>H</sub> (LSB))
- Read 1 byte product code (from Flash Address: 584F<sub>H</sub>)

### 2.26.3 Prototype

void **Read\_ID** (struct ID\_Struct idata \* idata **ID\_Result**)

*Note: Structure ID\_Struct is defined in SP37\_ROMLibrary.h*

### 2.26.4 Inputs

**Table 113 Read\_ID: Input Parameters**

Register / Address	Type	Name	Description
R7	idata*	ID_Result	Pointer to a structure according to the following definition: idata struct ID_Struct {unsigned long ID; unsigned char ProdCode;} Product Code pressure range indication: xxxx.x000 <sub>B</sub> : reserved xxxx.x100 <sub>B</sub> : 450 kPa, Green Package <sup>1)</sup> xxxx.x001 <sub>B</sub> : reserved xxxx.x101 <sub>B</sub> : reserved xxxx.xx10 <sub>B</sub> : reserved xxxx.xx11 <sub>B</sub> : reserved

1) For definition "Green Package" please refer to [\[1\]](#)

### 2.26.5 Outputs

**Table 114 Read\_ID: Output values**

Register/ Address	Type	Name	Description
None	---	---	---

## 2.26.6 Resource Usage

**Table 115** Read\_ID: Resources

Type	Used or Modified
Registers	R0, R3, R4, R5, R6, R7
SFR	ACC, DPH, DPL, PSW
Stack	2 Bytes

## 2.26.7 Execution Information

**Table 116** Read\_ID: Execution Time and Charge Consumption

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	32	35	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,048	0,082	μC	DIVIC = 00 <sub>H</sub>

## 2.26.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"

// ID structure is defined in SP37_ROMLibrary.h
idata ID_Struct ID_Result;

void main()
{
    // Read Sensor ID function call
    Read_ID(&ID_Result);
}
```

**Figure 11** Code example for usage of Read\_ID()

## 2.27 ManuRevNb()

### 2.27.1 Description

This function returns the Infineon SP37 revision number

### 2.27.2 Actions

- Read 2-byte Revision Number from ROM and return it

### 2.27.3 Prototype

signed int **ManuRevNb** (void)

### 2.27.4 Inputs

**Table 117 ManuRevNb: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.27.5 Outputs

**Table 118 ManuRevNb: Output values**

Register/ Address	Type	Name	Description
R6(MSB), R7(LSB)	signed int	Firmware Revision	37XY <sub>H</sub> : X = Design Step (A...F) Y = Version (0...9)

### 2.27.6 Resource Usage

**Table 119 ManuRevNb: Resources**

Type	Used or Modified
Registers	R6, R7
SFR	ACC, PSW, DPTR
Stack	0 Bytes



## 2.27.7 Execution Information

**Table 120** ManuRevNb: Execution Time and Charge Consumption

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	9	10	$\mu\text{s}$	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,013	0,023	$\mu\text{C}$	DIVIC = 00 <sub>H</sub>

## 2.28 FW\_Revision\_Nb()

### 2.28.1 Description

This function returns the ROM Library revision number and the FLASH Library revision number.

### 2.28.2 Actions

- Read 2-byte Revision Number from ROM and return it
- Read 2-byte Revision Number from FLASH Library and return it

### 2.28.3 Prototype

void **FW\_Revision\_Nb** (unsigned int idata \* **ROM\_Rev**, unsigned int idata \* **Lib\_Rev**)

### 2.28.4 Inputs

**Table 121 FW\_Revision\_Nb: Input Parameters**

Register/ Address	Type	Name	Description
R4(MSB), R5(LSB)	unsigned int idata*	Lib_Rev	Pointer to the RAM location where the FLASH Library code revision will be returned xxxx <sub>H</sub> = SP37 FLASH Library version
R6(MSB), R7(LSB)	unsigned int idata*	ROM_Rev	Pointer to the RAM location where the ROM code revision will be returned 0131 <sub>H</sub> = SP37 ROM Library Version A4

### 2.28.5 Outputs

**Table 122 FW\_Revision\_Nb: Output values**

Register/ Address	Type	Name	Description
None	---	---	---

### 2.28.6 Resource Usage

**Table 123 FW\_Revision\_Nb: Resources**

Type	Used or Modified
Registers	R0, R5, R7
SFR	ACC
Stack	2 Bytes

## 2.28.7 Execution Information

**Table 124 FW\_Revision\_Nb: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	12	13	μs	
Charge Consumption	$Q$	–	0,018	0,030	μC	

## 2.29 Erase\_UserConfigSector()

### 2.29.1 Description

This function erases the FLASH user configuration sector located at FLASH address 5780<sub>H</sub> -- 57FF<sub>H</sub> if the Lockbyte 3 is not set. If Lockbyte 3 is set this function will return -1 without any action.

This function returns -1 and has no effect if executed in DEBUG mode.

*Note: The application software has to ensure that FLASH is only programmed or erased when all required environmental conditions are fulfilled. Special care has to be taken that ambient temperature  $T_{FL}$ , supply voltage  $V_{batFL}$  and Endurance  $En_{FL}$  are within specified range (see [1]).*

### 2.29.2 Actions

- Erase the FLASH user configuration sector

### 2.29.3 Prototype

signed char **Erase\_UserConfigSector** (void)

### 2.29.4 Inputs

**Table 125 Erase\_UserConfigSector: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.29.5 Outputs

**Table 126 Erase\_UserConfigSector: Output values**

Register/ Address	Name	Type	Description
R7	signed char	Statusbyte	0: success -1: failed

### 2.29.6 Resource Usage

**Table 127 Erase\_UserConfigSector: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CRC0, CRC1, CRCC, CRCD, DIVIC, DPH, DPL, PSW, TCON, TH0, TH1, TL0, TL1
Stack	5 Bytes

## 2.29.7 Execution Information

**Table 128 Erase\_UserConfigSector: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	103000	111300	$\mu\text{s}$	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	222	358	$\mu\text{C}$	DIVIC = 00 <sub>H</sub>

## 2.30 WriteFlashUserConfigSectorLine()

### 2.30.1 Description

This function writes one line in the FLASH user configuration sector located at FLASH address 5780<sub>H</sub> -- 57FF<sub>H</sub> if the Lockbyte 3 is not set. If Lockbyte 3 is set this function will return -1 without any action.

This function returns -1 and has no effect if executed in DEBUG mode.

The written data is verified after the programming. In case the verification fails this function will return -1.

*Note: The application software has to ensure that FLASH is only programmed or erased when all required environmental conditions are fulfilled. Special care has to be taken that ambient temperature  $T_{FL}$ , supply voltage  $V_{batFL}$  and Endurance  $En_{FL}$  are within specified range (see [1]).*

### 2.30.2 Actions

- Write one 32 Byte FLASH Line of the FLASH user configuration sector

### 2.30.3 Prototype

signed char **WriteFlashUserConfigurationSectorLine** (unsigned int **Startaddress**, unsigned char idata \* **WrData**)

### 2.30.4 Inputs

**Table 129 WriteFlashUserConfigurationSectorLine: Input Parameters**

Register / Address	Type	Name	Description
R7 R6	unsigned int	Startaddress	Startaddress 5780 <sub>H</sub> : FLASH Line 0 57A0 <sub>H</sub> : FLASH Line 1 57C0 <sub>H</sub> : FLASH Line 2 57E0 <sub>H</sub> : FLASH Line 3
R5	unsigned char idata*	WrData	Pointer to first Byte of the 32 Byte Data array that is going to be written to the FLASH Line.

## 2.30.5 Outputs

**Table 130 WriteFlashUserConfigurationSectorLine: Output values**

Register/ Address	Type	Name	Description
R7	signed char	Statusbyte	0: success -1: failed

## 2.30.6 Resource Usage

**Table 131 WriteFlashUserConfigurationSectorLine: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, CFG1, CRC0, CRC1, CRCC, CRCD, DIVIC, DPH, DPL, PSW, TCON, TH0, TH1, TL0, TL1, TMOD
Stack	5 Bytes

## 2.30.7 Execution Information

**Table 132 WriteFlashUserConfigurationSectorLine: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	3907	4250	μs	DIVIC = 00 <sub>H</sub> , FLASH written with all bit 1
Charge Consumption	$Q$	–	8,94	11,9	μC	DIVIC = 00 <sub>H</sub> , FLASH written with all bit 1

## 2.31 FlashSetLock()

### 2.31.1 Description

This function sets the Lockbyte 3 which protects the User Configuration sector. This function returns -1 and has no effect if executed in DEBUG mode.

**Attention:** This function shows only effect if the Lockbyte 2 that protects the Code Sector is set.

*Note: The application software has to ensure that FLASH is only programmed or erased when all required environmental conditions are fulfilled. Special care has to be taken that ambient temperature  $T_{FL}$ , supply voltage  $V_{batFL}$  and Endurance  $En_{FL}$  are within specified range (see [1]).*  
This function returns -1 and has no effect if executed in DEBUG mode.

### 2.31.2 Actions

- Set the Lockbyte 3 protecting the User Configuration sector

### 2.31.3 Prototype

signed char **FlashSetLock**(void)

### 2.31.4 Inputs

**Table 133 FlashSetLock: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.31.5 Outputs

**Table 134 FlashSetLock: Output values**

Register/ Address	Type	Name	Description
R7	signed char	Statusbyte	0: success -1: failed

### 2.31.6 Resource Usage

**Table 135 FlashSetLock: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG1, CRC0, CRC1, CRCC, CRCD, DIVIC, DPH, DPL, TCON, TH1, TL1
Stack	8 Bytes



## 2.31.7 Execution Information

**Table 136 FlashSetLock: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	116020	126000	$\mu\text{s}$	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	290	404	$\mu\text{C}$	DIVIC = 00 <sub>H</sub>

## 2.32 ECC\_Check()

### 2.32.1 Description

This function evaluates the **Error Code Correction (ECC)** result bit. This bit shows if an error in the read/executed FLASH has been detected since the last call of this function.

*Note: When a FLASH byte is programmed, the ECC unit generates and stores four ECC bits. With these additional bits the ECC is able to correct single bit errors and detects two bit errors. The ECC is calculated from read/executed FLASH and the result is stored in the ECC result bit. It cannot distinguish between a single bit or two bit error.*

### 2.32.2 Actions

- Check the ECC result bit

### 2.32.3 Prototype

signed char **ECC\_Check**(void)

### 2.32.4 Inputs

**Table 137 ECC\_Check: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.32.5 Outputs

**Table 138 ECC\_Check: Output values**

Register/ Address	Type	Name	Description
R7	signed char	Statusbyte	0: success -1: ECC error detected

### 2.32.6 Resource Usage

**Table 139 ECC\_Check: Resources**

Type	Used or Modified
Registers	R7
SFR	ACC, PSW
Stack	0 Bytes

## 2.32.7 Execution Information

**Table 140 ECC\_Check: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	6	7	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,009	0,016	μC	DIVIC = 00 <sub>H</sub>

## 2.32.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"

void main()
{
    // Return value of ECC check is stored in StatusByte
    unsigned char StatusByte;

    // ECC check function call to reset the ECC check function
    StatusByte = ECC_Check();

    // CRC16 check function call to test User Data Sector
    StatusByte = CRC16_Check(0x5780,0x80);

    // ECC check function call
    StatusByte += ECC_Check();

    if(!StatusByte){
        // Both ECC and CRC16 check were successful
    }
    else{
        // ECC and or CRC16 check was not successful
    }
}
```

**Figure 12 Code example for usage of the functions ECC\_Check() and CRC16\_Check()**

## 2.33 CRC16\_Check()

### 2.33.1 Description

This function computes a 16-bit CRC of a code block from a start address with a defined length from FLASH, which includes a pre-computed 16-bit CRC, which is stored in the last 2 Bytes of the memory block ((StartAddr + Length - 2) is CRC High) and ((StartAddr + Length - 1) is CRC Low).

*Note: The pre-computed CRC value has to be written by the application for code blocks in FLASH.*

### 2.33.2 Actions

- Calculate 16-bit CRC
- Compare CRC with pre-computed CRC located in the last 2 Bytes of the code block

### 2.33.3 Prototype

signed char **CRC16\_Check**(unsigned char code \* **StartAddr**, unsigned int **Length**)

### 2.33.4 Inputs

**Table 141 CRC16\_Check: Input Parameters**

Register / Address	Type	Name	Description
R6 (MSB) R7 (LSB)	unsigned char code*	StartAddr	Pointer to first Byte of the Data that is used for calculating the checksum
R4 (MSB) R5 (LSB)	unsigned int	Length	Length in Bytes of the code block, including the pre-computed CRC value, that is used for calculating the checksum.

### 2.33.5 Outputs

**Table 142 CRC16\_Check: Output values**

Register/ Address	Type	Name	Description
R7	signed char	Statusbyte	0: CRC matches -1: CRC does not match

### 2.33.6 Resource Usage

**Table 143 CRC16\_Check: Resources**

Type	Used or Modified
Registers	R4, R5, R6, R7
SFR	ACC, B, CRC0, CRC1, CRCD, DPH, DPL, PSW
Stack	0 Bytes

### 2.33.7 Execution Information

**Table 144 CRC16\_Check: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	$22 + x \cdot 8$	$24 + x \cdot 9$	$\mu s$	DIVIC = 00 <sub>H</sub> , x is the number of bytes
Charge Consumption	$Q$	–	$0,033 + x \cdot 0,012$	$0,056 + x \cdot 0,020$	$\mu C$	DIVIC = 00 <sub>H</sub> , x is the number of bytes

### 2.33.8 Code Example

See [Figure 12 “Code example for usage of the functions ECC\\_Check\(\) and CRC16\\_Check\(\)” on Page 103](#)

## 2.34 HIRC\_Clock\_Check()

### 2.34.1 Description

This function measures the frequency of the 12 MHz RC Oscillator, using the crystal oscillator as a measurement standard. It evaluates whether the 12 MHz RC Oscillator is working in the specified range (see [1]).

The crystal oscillator is automatically started, if not already enabled, and allowed a fixed startup time of approximately 2.5ms (five 2 kHz RC LP Oscillator periods). The crystal frequency divided by 2 has to be stored in the FLASH user configuration sector at address 57FA<sub>H</sub> (MSByte) to 57FC<sub>H</sub> (LSByte). If the value found at this FLASH location is not within the range of 9 MHz to 10 MHz a default clock frequency of 9.843750 MHz is assumed for the checking. Before the function returns the previous clock settings are restored.

### 2.34.2 Actions

- Check the frequency of the 12 MHz RC Oscillator using the crystal oscillator as measurement standard

### 2.34.3 Prototype

signed char **HIRC\_Clock\_Check**(void)

### 2.34.4 Inputs

**Table 145 HIRC\_Clock\_Check: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.34.5 Outputs

**Table 146 HIRC\_Clock\_Check: Output values**

Register/ Address	Type	Name	Description
R7	signed char	Statusbyte	0: success -1: 12 MHz RC Oscillator out of specified range -2: No valid crystal frequency found in FLASH (12 MHz RC Oscillator in specified range for default crystal frequency) -3: No valid crystal frequency found in FLASH (12 MHz RC Oscillator out of specified range for default crystal frequency)

## 2.34.6 Resource Usage

**Table 147 HIRC\_Clock\_Check: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0, DIVIC, DPH, DPL, PSW, TCON, TH0, TH1, TL0, TL1, TMOD
Stack	5 Bytes

## 2.34.7 Execution Information

**Table 148 HIRC\_Clock\_Check: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t_{OFF}$	–	3430	5210	μs	DIVIC = 00H, XtalOSC is OFF at the start of the function
Execution Time	$t_{ON}$	–	820	891	μs	DIVIC = 00H, XtalOSC is ON at the start of the function
Charge Consumption	$Q_{OFF}$	–	3,81	8,69	μC	DIVIC = 00H, XtalOSC is OFF at the start of the function
Charge Consumption	$Q_{ON}$	–	1,48	2,35	μC	DIVIC = 00H, XtalOSC is ON at the start of the function

## 2.35 GetCompValue()

### 2.35.1 Description

This function retrieves an 8 bit value from a 2 dimensional lookup table depending on input values Value1 and Value2. The lookup table is a M by N matrix and can be of any size from 2 x 2 up to 15 x 15 holding 225 different values in its maximum configuration. This function may be used to obtain a compensation value from a lookup table with 2 threshold types (e.g. temperature and voltage), according to the measured input values (Value1 and Value2). The lookup table has to be stored in the FLASH.

The input values are compared against threshold points defined in the lookup table, and the thresholds must be sorted in increasing order. The column is chosen by Value1 thresholds and the row is selected by Value2 thresholds respectively. If Value1 is lower than its lowest threshold then the left-most column is selected, and likewise if Value2 is lower than its lowest threshold the top-most row is selected.

The matrix size is always 1 larger than the number of threshold points. Thus, a 12 by 7 matrix will have 6 threshold points for Value1 (column) and 11 threshold points for Value2 (row).

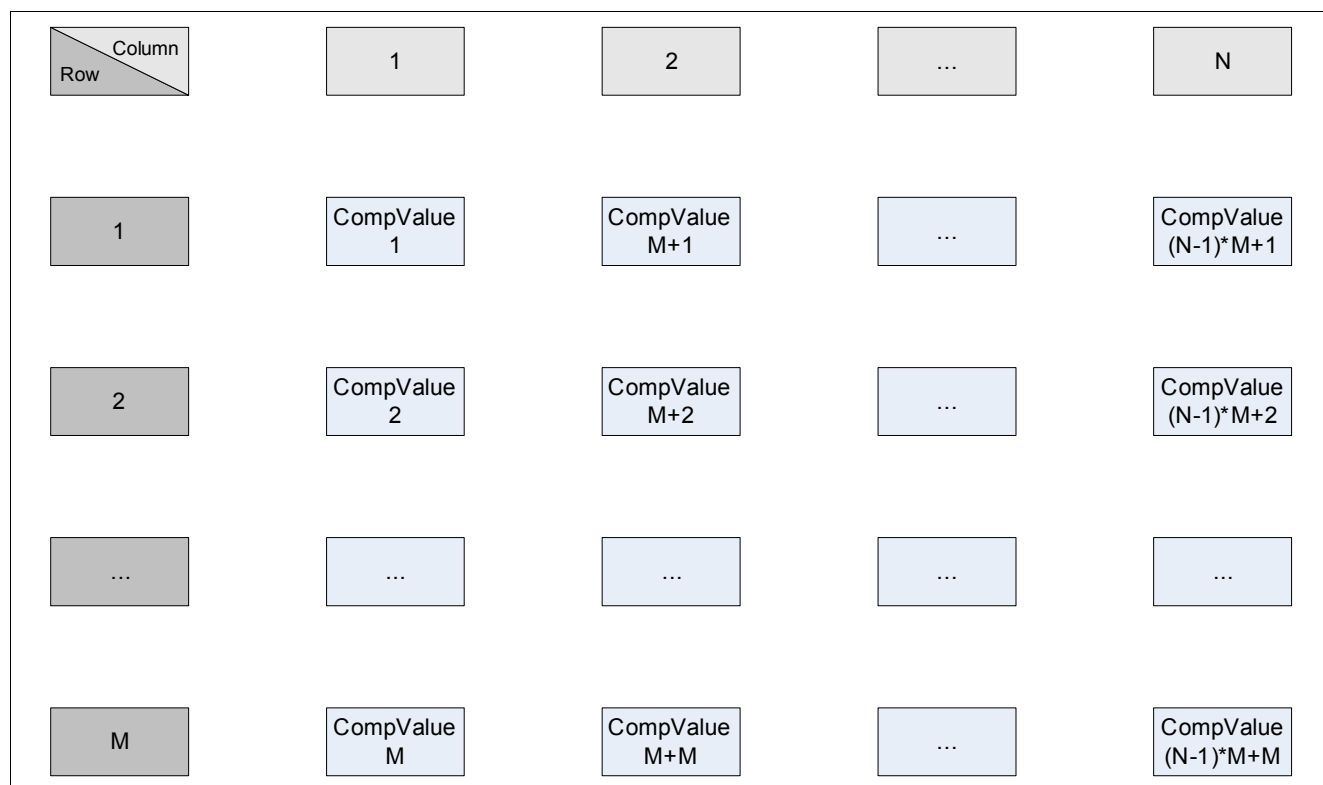


Figure 13 M by N matrix



## 2.35.2 Actions

- Compare Value1 with defined thresholds from threshold type 1
- Compare Value2 with defined thresholds from threshold type 2
- Return compensated value

## 2.35.3 Prototype

unsigned char **GetCompValue**(unsigned char code \* **TablePointer**, unsigned char **Value1**, unsigned char **Value2**)

## 2.35.4 Inputs

**Table 149 GetCompValue: Input Parameters**

Register / Address	Type	Name	Description
R6 (MSB) R7 (LSB)	unsigned char code*	TablePointer	Pointer to the first Byte of lookup table
R5	unsigned char	Value1	Measured Value1 for comparison with thresholds from threshold type 1 to select column
R3	unsigned char	Value2	Measured Value2 for comparison with thresholds from threshold type 2 to select row

**Figure 14** shows how the compensated value table must appear in FLASH memory.

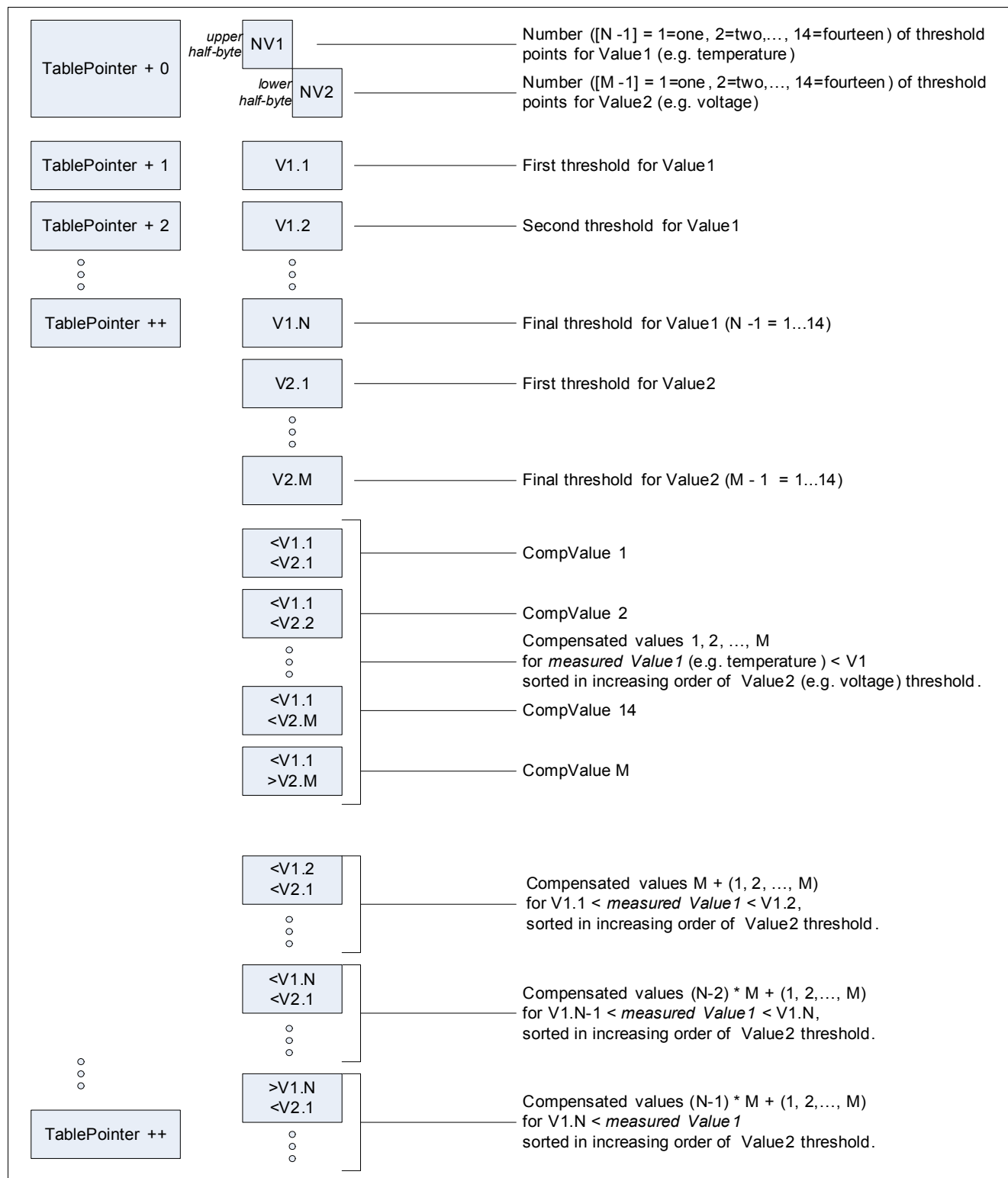


Figure 14 Lookup table organization

### 2.35.5 Outputs

**Table 150 GetCompValue: Output values**

Register/ Address	Type	Name	Description
R7	unsigned char	Compensated Value	Returns the compensated value from the lookup table defined by selected column and row

### 2.35.6 Resource Usage

**Table 151 GetCompValue: Resources**

Type	Used or Modified
Registers	R0, R1, R3, R5, R6, R7
SFR	ACC, DPH, DPL, PSW, SP
Stack	2 Bytes

### 2.35.7 Execution Information

**Table 152 GetCompValue: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	619	669	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,929	1,606	μC	DIVIC = 00 <sub>H</sub>

## 2.36 Wait100usMultiples()

### 2.36.1 Description

This function performs a delay of 100  $\mu$ s multiples. It clears the CPU clock divider SFR DIVIC, initializes the timers according to the delay time, and uses IDLE state during the delay time. In case an unexpected resume event occurs, the IDLE state will be left and the function remain in RUN state until the delay is elapsed. The total duration of the delay can be determined by an offset time of 28  $\mu$ s plus the multiplication of the input parameter value with 100 $\mu$ s. The maximum delay time is limited in practice by the watchdog timer, which may be reset by the application prior to the function call.

### 2.36.2 Actions

- Set SFR DIVIC = 00<sub>B</sub>
- Configure timers according to the delay time
- Enter IDLE state
- Delay until timer is elapsed

### 2.36.3 Prototype

void **Wait100usMultiples**(unsigned int **Counter**)

### 2.36.4 Inputs

**Table 153 Wait100usMultiples: Input Parameters**

Register / Address	Type	Name	Description
R6 (MSB) R7 (LSB)	unsigned int	Counter	Number of 100 $\mu$ s multiples. Duration[ $\mu$ s] = Counter x 100 $\mu$ s

### 2.36.5 Outputs

**Table 154 Wait100usMultiples: Output values**

Register/Address	Type	Name	Description

### 2.36.6 Resource Usage

**Table 155 Wait100usMultiples: Resources**

Type	Used or Modified
Registers	R6, R7
SFR	ACC, B, CFG0, CFG2, DIVIC, DPTR, PSW, TCON, TH0, TL0, TH1, TL1, TMOD
Stack	0 Bytes

## 2.36.7 Execution Information

**Table 156 Wait100usMultiples: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t_{100}$	–	127	138	μs	DIVIC is 00 <sub>H</sub> , counter = 1
	$t_{600}$	–	627	681	μs	DIVIC is 00 <sub>H</sub> , counter = 6
	$t_{+100}$	–	100	109	μs	DIVIC is 00 <sub>H</sub> , counter is increased
Charge Consumption	$Q_{100}$	–	0,11	0,19	μC	DIVIC is 00 <sub>H</sub> , counter = 1
	$Q_{600}$	–	0,4	0,787	μC	DIVIC is 00 <sub>H</sub> , counter = 6
	$Q_{+100}$	–	0,059	0,12	μC	DIVIC is 00 <sub>H</sub> , counter is increased

## **2.37 Send\_RF\_Telegram()**

This ROM Library Function performs many of the critical tasks required to transmit RF telegrams, resulting in simplified and smaller application code.

### **2.37.1 Description**

In principle, transmission of an RF telegram using the SP37 can be divided into two distinct portions: RF Peripheral Initialization, and RF Data Transmission. In the case of the Send\_RF\_Telegram() function, the application program must perform the Initialization, and the Send\_RF\_Telegram() function addresses Data Transmission. To permit arbitrary RF telegram formats, an interpreted table-driven approach is employed. The Data Transmission portion relies upon a Pattern Descriptor Table (PDT) to define the format and content of the RF telegram. At the end of the Data Transmission portion, the Crystal Oscillator and RF Transmitter circuitry are disabled.

Prior to calling the Send\_RF\_Telegram() function, the following Initialization actions must be completed:

- The RF Transmitter SFR RFTX must be configured to select the appropriate Frequency Band, Output Power, etc. Refer to the SFR RFTX description of the datasheet.
- The Crystal Oscillator must be enabled via the StartXtalOsc() ROM Library function (Ref. to [Chapter 2.15](#)).
- The RF PLL must be enabled and initialized via the VCO\_Tuning( ) ROM Library function (Ref. to [Chapter 2.18](#))
- An RF Telegram Pattern Descriptor Table must be placed into RAM (see below for more details).

*Note: Additionally, if the randomized delay capability of Send\_RF\_Telegram() is used, it is strongly recommended to seed the Pseudo-Random Number generator with a value unique to each sensor (e.g. the LSB of the unique Sensor ID) in order to obtain better randomization. This is particularly important if the random delay is used as part of an "anti-collision" technique to prevent overlapping RF telegrams from two different sensor modules.*

After successful Initialization, the application code may call the Send\_RF\_Telegram() function.

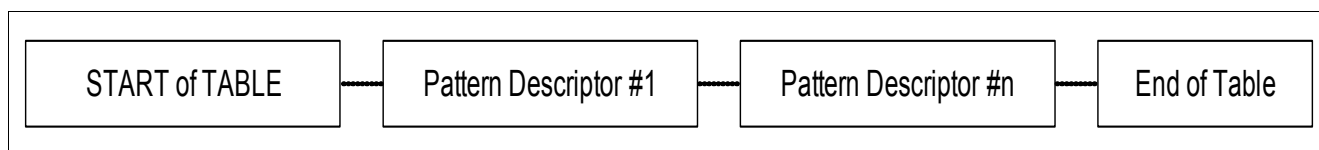
Only two parameters are required by this function to completely specify the RF telegram: the desired baud rate and the starting RAM address of the PDT. If an error is encountered while parsing the PDT, the Send\_RF\_Telegram() function will terminate with a return code of -1.

#### **2.37.1.1 Baud Rate parameter**

The baud rate parameter is a formal parameter passed to the Send\_RF\_Telegram() function. This is an integer value, 1LSB = 1BPS. The Send\_RF\_Telegram function configures the SP37 Timer peripheral with the appropriate mode, and calculates the required timer reload value using the crystal frequency stored in the flash User Configuration Sector (reference here). The baud rate parameter must be between 13 and 10000, the minimum and maximum supported baud rates.

#### **2.37.1.2 Pattern Descriptor table**

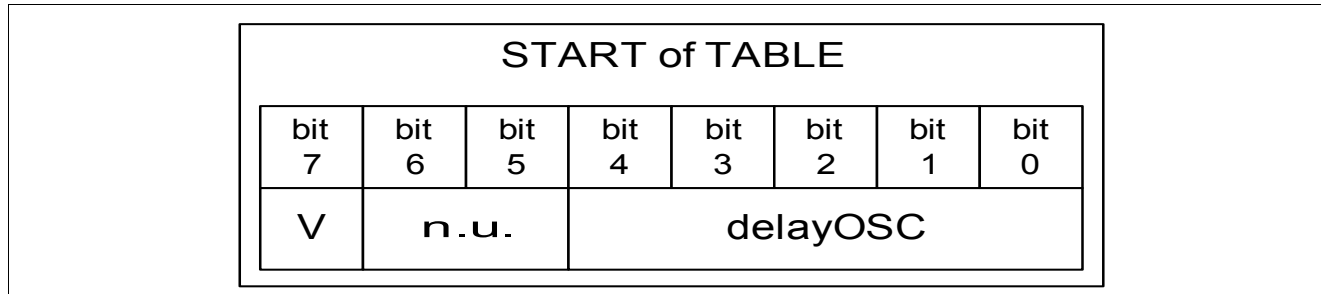
The Pattern Descriptor Table (PDT) provides a flexible means to transmit an RF telegram of arbitrary structure and content. A PDT begins with a Start of Table indicator, followed by one or more Pattern Descriptor entries, and concludes with an End of Table indicator. A conceptual diagram of a PDT is shown in [Figure 15](#).



**Figure 15 Datagram format**

### 2.37.1.3 Start of Table indicator

The Start of Table is always the first byte of the PDT. The Start of Table is detailed in [Figure 16](#).



**Figure 16** Datagram format

Bits 4..0 - delayOSC - define the delay for the StartXtalOsc() used in the RF\_Transmission routine. The delay is calculated as  $(30 + \text{delayOSC}) \times 42,67 \mu\text{s}$ . This delay is used as that for crystal oscillator startup, which takes place before transmission of each repeated frame.

Bits 6..5 - not used - these bits should be set to 0.

Bit7 - V - enables the measurement of the battery voltage at the end of each transmitted frame, by means of the ADC. Only the last measurement is stored into RAM and can be read by the application.

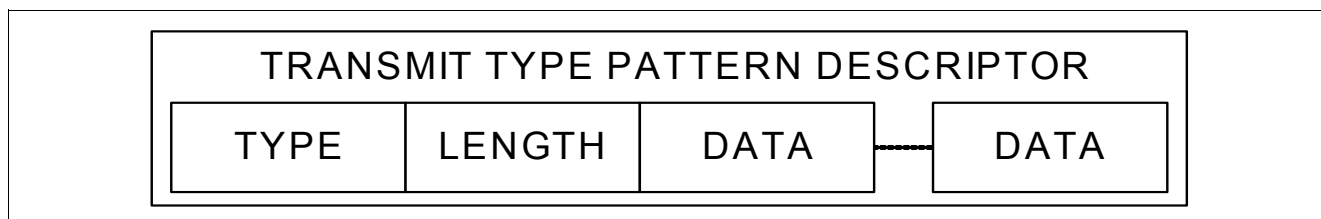
*Note: In order to operate the ADC for battery voltage measurements, Start\_Supply\_Voltage() must be called before Send\_RF\_Transmission is called. In order to read the measured supply voltage after the RF telegram has completed, the Get\_Supply\_Voltage function may be called. Note that the ADC is enabled and in standby mode during the duration of the Send\_RF\_Transmission function, therefore the total device current consumption during RF transmission will exceed the value typically specified.*

### 2.37.1.4 Pattern Descriptor entries

In general, the concept is to divide the RF telegram into blocks of similar bit encoding and modulation which can be described by one Pattern Descriptor entry. A collection of Pattern Descriptors form the bulk of the PDT. Consider the following example: an RF telegram with some number of Manchester coded Run-In (or "preamble") bits, followed by a special Start of Message symbol (a "code violation") followed by the Manchester coded Message Payload bits. The Run-In and Message Payload are transmitted bitwise (e.g. Manchester coded) while the Start of Message symbol must be transmitted as chips because it is not Manchester coded data. The PDT for this example consists of three Pattern Descriptors, appearing in the table in order of transmission. In addition to Pattern Descriptors that define data and how it is transmitted, a "delay" type of Pattern Descriptor is also supported. A Pattern Descriptor is composed of byte data in RAM and can be one of two types; a Transmit type or a Delay type. Each of these Pattern Descriptor types is discussed in detail below.

### 2.37.1.5 Transmit Type Pattern Descriptor

A Transmit type Pattern Descriptor provides the RF Transmitter circuitry with serial data to encode and modulate. The Transmit type is detailed in the figure below.



**Figure 17** Transmit Type Pattern Descriptor

The first byte 'TYPE' of a Transmit type Pattern Descriptor specifies the encoding and modulation scheme for that Pattern:

- 00<sub>H</sub> Manchester
- 01<sub>H</sub> Inverted Manchester
- 02<sub>H</sub> Differential Manchester
- 03<sub>H</sub> Biphase 0
- 04<sub>H</sub> Biphase 1
- 05<sub>H</sub> Chip Mode (at chiprate, i.e. double datarate)
- +00<sub>H</sub> for FSK Modulation
- +10<sub>H</sub> for ASK Modulation

So for example:

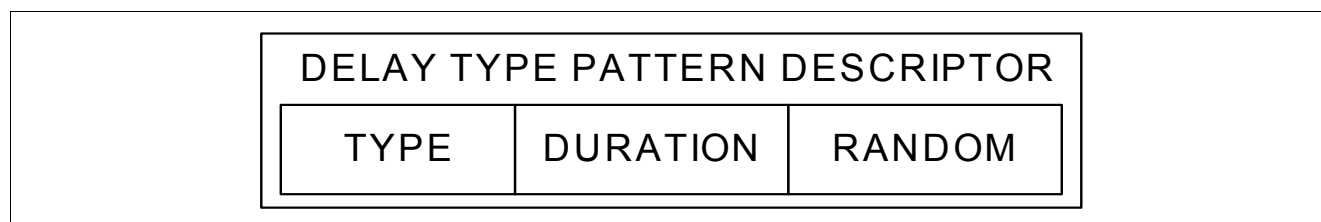
- 03<sub>H</sub> stands for Biphase 0 encoded data, FSK modulated
- 12<sub>H</sub> stands for Differential Manchester encoded data, ASK modulated

The second byte 'LENGTH' specifies the length of the Pattern in bits (or chips in the case of TYPE = 05<sub>H</sub> or 15<sub>H</sub>). LENGTH can be any value from 01<sub>H</sub> (1 bit/chip) to FF<sub>H</sub> (255 bits/chips), and 00<sub>H</sub> (256 bits/chips).

The remaining bytes in the Pattern Descriptor 'DATA' contain the data which has to be encoded and transmitted. Each byte in DATA is transmitted MSB first. In the case of a pattern with LENGTH that is not a multiple of eight, the final remaining bits are transmitted MSB first from the final DATA byte.

### 2.37.1.6 Delay Pattern descriptor

A Delay type Pattern Descriptor serves to disable the RF Transmitter circuitry for either a fixed or pseudo-random time delay. During Delay, the CPU is placed into IDLE mode to reduce overall current consumption. The Delay type is detailed in [Figure 18](#).



**Figure 18 Delay Type Pattern Descriptor**

The first byte 'TYPE' of a Delay type Pattern Descriptor is a fixed value of DD<sub>H</sub>.

The second byte 'DURATION' specifies a fixed duration of delay time, in milliseconds [ms].

The third byte 'RANDOM' specifies the maximum duration of a randomly generated delay time, in milliseconds [ms]. The Random Delay will be uniformly distributed between 0 and the value of 'RANDOM', in milliseconds [ms].

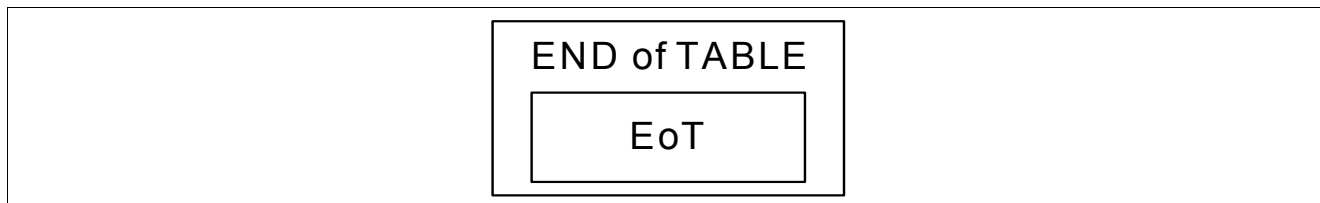
The total delay achieved with a Delay type Pattern Descriptor is the sum of the fixed and randomly generated delay times. To realize a Pattern with a fixed delay time, simply set the DURATION byte accordingly and set the RANDOM byte to zero. To realize a Pattern with a random delay time, set the DURATION byte and the RANDOM byte accordingly: the result will be a fixed amount of time on the top of which a random delay is added.

The random delay is obtained using the SP37 Pseudo Random Number (PRN) generator peripheral. In order to achieve some "randomness" between individual devices, it is recommended to seed the PRN generator with a value unique to each device. e.g. the LSB of the Sensor ID.

### 2.37.1.7 End of Table pattern descriptor

A PDT must end with an End of Table (EOT) entry. In addition to marking the end of the table, the EOT allows for one or more repetitions of the entire PDT. The EOT is detailed in [Figure 19](#).





**Figure 19 End of Table**

The exact value of the EOT byte indicates how many times the PDT should be processed.

- F1<sub>H</sub> process Pattern Descriptor once
- F2<sub>H</sub> process Pattern Descriptor twice
- ...
- FF<sub>H</sub> process Pattern Descriptor fifteen times
- F0<sub>H</sub> process Pattern Descriptor sixteen times

For example, the PDT describes a single RF telegram, and if four duplicate telegrams are desired, then an EOT marker of F4H is required. Note that with each processing of the PDT, any RANDOM delays are taken with a new random value obtained from the Random Number

## 2.37.2 Actions

- Set the Timer mode and reload values to achieve the appropriate baudrate
- Process the Pattern Descriptor Table (one or more repetitions, as determined by EOT byte) and transmit the data
- Disable the Crystal Oscillator and the RF transmitter PLL

## 2.37.3 Prototype

signed char **Send\_RF\_Telegram**(unsigned int baudrate, unsigned char idata \* descriptorPtr)

## 2.37.4 Inputs

**Table 157 Send\_RF\_Telegram: Input Parameters**

Register / Address	Type	Name	Description
R6 (MSB), R7 (LSB)	unsigned int	baudrate	Baudrate [bps] of transmitted data
R5	unsigned char idata *	descriptorPtr	Register address for data vector descriptor

### 2.37.5 Outputs

**Table 158 Send\_RF\_Telegram: Output values**

Register/ Address	Type	Name	Description
R7	signed char		StatusByte: 0: Success -1: Error in data vector descriptor

### 2.37.6 Resource Usage

**Table 159 Send\_RF\_Telegram: Resources**

Type	Used or Modified
Registers	R0, R1, R2, R3, R4, R5, R6, R7
SFR	ACC, B, CFG0, CFG1, CFG2, DIVIC, DPH, DPL, PSW, RFC, RFD, RFENC, RFTX, RFS, RNGD, TCON, TH0, TH1, TL0, TL1, TMOD
Stack	10 Bytes

### 2.37.7 Execution Information

**Table 160 Send\_RF\_Telegram: Execution Time**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Function overhead for 1 transmission burst	<i>t</i>	–	771	838	μs	
1 chip transmitted @9600 bps	<i>t</i>	–	52,1	52,6	μs	
1 chip transmitted @10000 bps	<i>t</i>	–	50	50,5	μs	
3 ms fixed delay	<i>t</i>	–	3062	3340	μs	
1 ms additional delay	<i>t</i>	–	1000	1087	μs	total delay >= 3ms

**Table 161 Send\_RF\_Telegram: Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Function overhead for 1 transmission burst	$Q$	–	3,44	4,15	$\mu\text{C}$	
1 chip transmitted @9600 bps	$Q$	–	0,278	0,512	$\mu\text{C}$	PA disabled (e.g. ASK off)
	$Q$	–	0,435	0,622	$\mu\text{C}$	SFR RFTX.PAOP = 00 <sub>b</sub> $P_{\text{out}} \sim 5 \text{ dBm}$ $Z_{\text{load},434\text{MHz}} \sim 500 \text{ Ohm}$ $Z_{\text{load},315\text{MHz}} \sim 650 \text{ Ohm}$
	$Q$	–	0,534	0,780	$\mu\text{C}$	SFR RFTX.PAOP = 01 <sub>b</sub> $P_{\text{out}} \sim 8 \text{ dBm}$ $Z_{\text{load},434\text{MHz}} \sim 300 \text{ Ohm}$ $Z_{\text{load},315\text{MHz}} \sim 450 \text{ Ohm}$
1 chip transmitted @10000 bps	$Q$	–	0,267	0,446	$\mu\text{C}$	PA disabled (e.g. ASK off)
	$Q$	–	0,418	0,597	$\mu\text{C}$	SFR RFTX.PAOP = 00 <sub>b</sub> $P_{\text{out}} \sim 5 \text{ dBm}$ $Z_{\text{load},434\text{MHz}} \sim 500 \text{ Ohm}$ $Z_{\text{load},315\text{MHz}} \sim 650 \text{ Ohm}$
	$Q$	–	0,512	0,749	$\mu\text{C}$	SFR RFTX.PAOP = 01 <sub>b</sub> $P_{\text{out}} \sim 8 \text{ dBm}$ $Z_{\text{load},434\text{MHz}} \sim 300 \text{ Ohm}$ $Z_{\text{load},315\text{MHz}} \sim 450 \text{ Ohm}$
3 ms fixed delay	$Q$	–	4,020	8,37	$\mu\text{C}$	
1 ms additional delay	$Q$	–	0,784	1,2	$\mu\text{C}$	total delay $\geq 3\text{ms}$

## 2.37.8 Code Example

```
// Library function prototypes
#include "SP37_ROMLibrary.h"

void main()
{
    // Return value of send RF telegram is stored in sendRF_StatusByte
    signed char sendRF_StatusByte;

    // Array for pattern descriptor table
    unsigned char idata descriptorPtr[10];

    // Start of table pattern indicator
    // battery measurement enabled, no delay for delayOSC
    descriptorPtr[0] = 0x80;

    // Transmit type pattern descriptor
    // Type: ASK, Manchester
    descriptorPtr[1] = 0x10;

    // Length: 14 bits
    descriptorPtr[2] = 14;

    // Data: 8 bits (7->0) transmitted: 01010101
    descriptorPtr[3] = 0x55;

    // Data: 6 bits (7->2) transmitted: 101001
    descriptorPtr[4] = 0xA5;

    // Transmit type pattern descriptor
    // Type: FSK, Manchester
    descriptorPtr[5] = 0x00;

    // Length: 16 bits
    descriptorPtr[6] = 16;

    // Data: 8 bits (7->0) transmitted: 10101010
    descriptorPtr[7] = 0xAA;

    // Data: 8 bits (7->0) transmitted: 01010101
    descriptorPtr[8] = 0x55;

    // End of table pattern descriptor
    descriptorPtr[9] = 0xF1;

    // These tasks need to be done, details are application dependent
    // RF Transmitter SFR Initialization
    // Start xtal oscillator function call
    // VCO tuning function call
    // Start supply voltage function call (if required)

    // Send RF telegram function call, baudrate = 9600 bit/s
    sendRF_StatusByte = Send_RF_Telegram(9600, descriptorPtr);

    // Get supply voltage function call (if required)
}
```

**Figure 20** Code example for usage of Send\_RF\_Telegram()

## 2.38 Internal\_SFR\_Refresh()

### 2.38.1 Description

This function refreshes on demand all internal registers which are refreshed by reset only.

### 2.38.2 Actions

- Loads default values into the internal SFRs which are refreshed at reset only

### 2.38.3 Prototype

void **Internal\_SFR\_Refresh**(void)

### 2.38.4 Inputs

**Table 162 Internal\_SFR\_Refresh: Input Parameters**

Register / Address	Type	Name	Description
None	---	---	---

### 2.38.5 Outputs

**Table 163 Internal\_SFR\_Refresh: Output values**

Register/ Address	Type	Name	Description
None	---	---	---

### 2.38.6 Resource Usage

**Table 164 Internal\_SFR\_Refresh: Resources**

Type	Used or Modified
Registers	---
SFR	ACC, DPTR
Stack	0 Bytes

## 2.38.7 Execution Information

**Table 165 Internal\_SFR\_Refresh: Execution Time and Charge Consumption**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Execution Time	$t$	–	27	29,2	μs	DIVIC = 00 <sub>H</sub>
Charge Consumption	$Q$	–	0,041	0,071	μC	DIVIC = 00 <sub>H</sub>

### 3 Reference Documents

This section contains documents used for cross- reference throughout this document.

[1] SP37 Datasheet

[www.infineon.com](http://www.infineon.com)