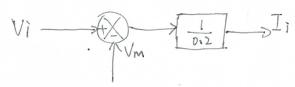
Assignment | ECEN315 Xiaobin (Jerry) Zhuang 300519184

Q1: In S-domain. We have DVi-Vm=0-2I; DIm=Ii-Io.BVm=45Im, QVm-Vo=0./Io BVo=5Io

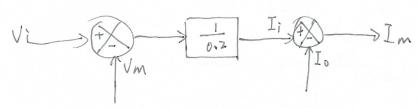
For () $V_1 - V_m = 0.2I_7 \Rightarrow (V_1 - V_m) = 0.2 = I_1$ drawing block diagram:



For @ Im= I; - Io



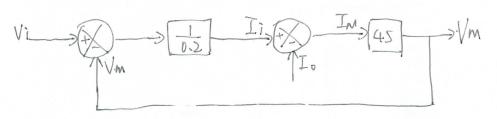
> Combine block diagram D&D:

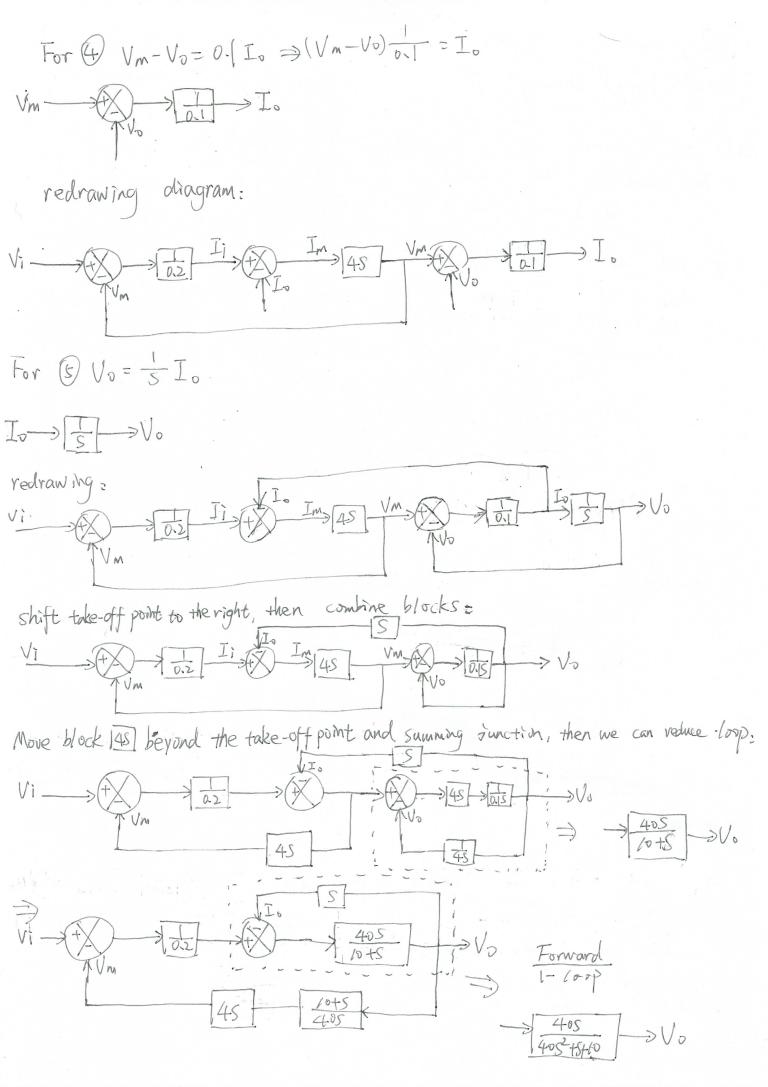


For B Vm=4sIm

$$I_m \longrightarrow 4S \longrightarrow V_m$$

> redrawing block diagram:





combine the rest of blocks:

$$\frac{Vo(s)}{Vi(s)} = \frac{I - vop}{I - vop} = \frac{2vvs}{4vs^2 + s + vo} = \frac{$$

b2-4ac

= 20. |2-4×6×1 > 0

.. System is overdamp

$$\Rightarrow V_0(s) = \frac{20s}{6s^2 + 20.|s+|} \cdot \frac{1}{5}$$

$$= \frac{20}{65^2 + 20.|st|}$$

$$= \frac{\left(\frac{1}{3}\right)}{(5 + 0.0505129)(5 + 3.29749)}$$

$$V_0(t) = L^{-1} \{V_0(s)\}$$

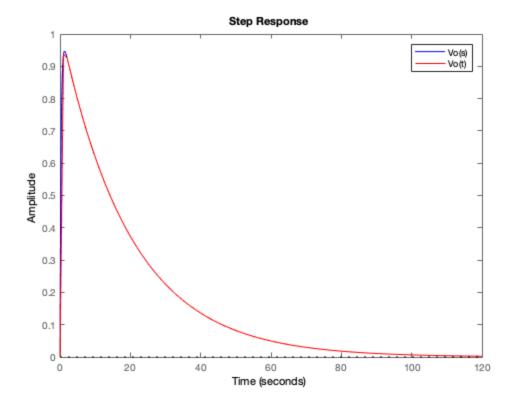
```
t=0:150
% Vo(s) transfer function
num=[20 0];
den=[6 20.1 1];
sys=tf(num,den)
stepplot(sys, 'b')
hold on
% Vo(t) when input is a unit step
F=1.02596*(exp(-0.0505129*t)-exp(-3.29949*t));
plot(t,F,'r')
legend('Vo(s)','Vo(t)')
hold off
t =
 Columns 1 through 13
    0 1 2 3 4 5 6
                                       7 8
                                                  9
                                                          10
 11 12
 Columns 14 through 26
                              18
                                    19
                                         20
                                               21
                                                    22
                                                          23
   13 14
            15 16
                        17
 24 25
 Columns 27 through 39
  26 27
              28
                   29
                         30
                              31
                                    32
                                         33
                                               34
                                                    35
                                                          36
 37 38
 Columns 40 through 52
   39 40
              41
                  42
                         43
                              44
                                    45
                                         46
                                               47
                                                    48
                                                          49
 50 51
 Columns 53 through 65
   52 53
              54
                   55
                         56
                              57
                                    58
                                         59
                                               60
                                                    61
                                                          62
 63 64
 Columns 66 through 78
  65 66
              67
                  68
                         69
                              70
                                    71
                                         72
                                               73
                                                    74
                                                          75
 76 77
 Columns 79 through 91
   78 79
              80
                   81
                         82
                              83
                                    84
                                         85
                                               86
                                                    87
                                                          88
 89 90
 Columns 92 through 104
```

91 102	92 103	93	94	95	96	97	98	99	100	101
Columns 105 through 117										
104 115	105 116	106	107	108	109	110	111	112	113	114
Columns 118 through 130										
117 128	118 129	119	120	121	122	123	124	125	126	127
Columns 131 through 143										
130 141	_	132	133	134	135	136	137	138	139	140
Columns 144 through 151										
143	144	145	146	147	148	149	150			

sys =

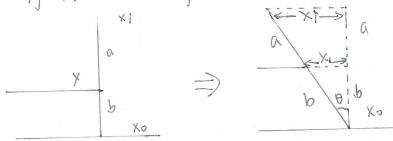
20 s ------6 s^2 + 20.1 s + 1

Continuous-time transfer function.



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if the lever fix at x, joint, when more lever, we can get:



$$X_1 = \sin \theta (a+b)$$

$$Q = \sin^{-1}(\frac{X_1}{b}) = \sin^{-1}(\frac{X_1}{a+b})$$

$$X_1 = \sin \theta b.$$

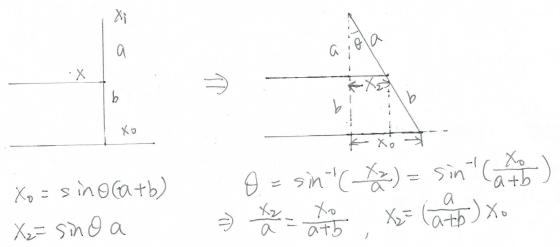
$$Q = \sin^{-1}(\frac{X_1}{b}) = \sin^{-1}(\frac{X_1}{a+b})$$

$$Z_1 = \sin \theta b.$$

$$Z_2 = \frac{X_1}{a+b} = \frac{X_1}{a+b} = \frac{X_1}{a+b}$$

$$Z_3 = \frac{X_1}{a+b} = \frac{X_1}{a+b} = \frac{X_1}{a+b}$$

if the lever fix at Xi point, when move it, we can get:



For example if we move lever to the left, it will cause displacement (X). Then oil goes in push piston back, which will cause the other displacement (X) with opposite direction. So the actual displacement (X) = the first displacement (X) - the second displacement (X)

$$X = X_1 - X_2 = \left(\frac{b}{a+b}\right)X_1 - \left(\frac{a}{a+b}\right)X_0$$

we have a=4cm, b=12cm, A=10cm2 and kv=20cm3/s/cm

$$= \chi_{(s)} = \left(\frac{b}{a+b}\right) \chi_{(s)} - \left(\frac{a}{a+b}\right) \chi_{(s)}$$

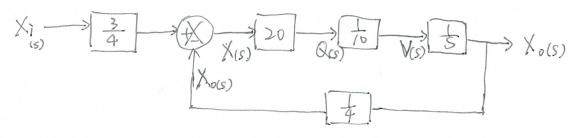
$$= \left(\frac{1^{2}}{4+12}\right) \chi_{(s)} - \left(\frac{4}{4+12}\right) \chi_{(s)}$$

$$= \frac{3}{4} \chi_{(s)} - \frac{1}{4} \chi_{(s)}$$

: flow rate q is proportional to x

$$\frac{dx_0}{dt} = v \quad \text{i. Sudt} = x_0 \quad \frac{Sdomain}{S} \quad \frac{V(s)}{S} = X_0(s)$$

Drawing block diagram:



$$=) \times I_{(5)} \longrightarrow (5)$$

$$= (5)$$

$$= (5)$$

$$= (5)$$

$$= (5)$$

$$= (5)$$

$$\frac{X_{0(0)}}{X_{1(0)}} = \frac{Forward}{1 - loop} = \frac{\frac{3}{25}}{1 - \frac{1}{25}} = \frac{3}{25} \cdot \frac{25}{25 - 1} = \frac{3}{25 - 1}$$