

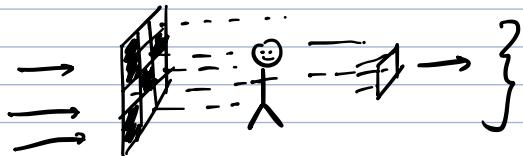
Lecture 13: Compressive sensing (aka compressed sensing) and linear programming.

How to find a sparse explanation of data.

e.g. images

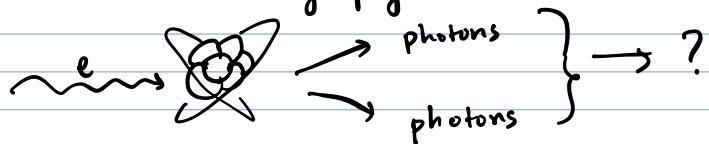


tend to be Fourier sparse.



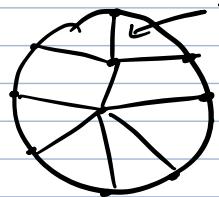
- MRI \rightarrow noisy measurements of Fourier signals through body, want to find underlying image.

- Quantum tomography



- Network tomography

individual delays.



send probes between boundary nodes.
total delay = \sum delays on path.

[Firooz, Roy '10]

UW EE

Framework: $x \in \mathbb{R}^N$ is an unknown signal. We are given n linear measurements $a_1, \dots, a_n \in \mathbb{R}^N$, $n \ll N$, i.e. we observe b_1, \dots, b_n , where $b_i = \langle a_i, x \rangle$.

Goal: given $\{(a_i, b_i)\}$, recover x .

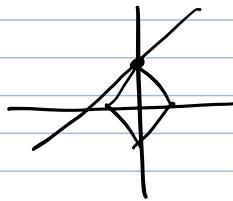
This is just linear regression! With no assumptions on x , this is impossible if $n \ll N$.

$$\begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} \left[\begin{array}{c} x \\ \vdots \\ x \end{array} \right] = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} \quad (n)$$

Fact: there is a $(N-n)$ -dim subspace of possible solutions.

to get around this, assume sparsity.

Recall: from previous lectures, we said to try ℓ_1 -regularization.



This lecture: (somewhat) formalize this intuition.

Recall: $\|x\|_0 = \#\{i : x_i > 0\}$ is the sparsity of x . For this lecture, let's assume $\|x\|_0 = k \ll N$.

Thm: [Candes - Tao '04, Candes - Romberg - Tao '04]. Choose a random $n \times N$ matrix A with independent entries $N(0, 1)$. If $n \geq \Omega(k \log(n/k))$, then w.h.p over the choice of A , there is a unique k -sparse solution to (*).

Moreover, it is also the solution to:

$$\min \|\hat{x}\|_1 \text{ s.t. } A\hat{x} = b. \quad (\text{basis pursuit})$$

Remarks:

- very similar to LASSO!

$$\min \|A\hat{x} - b\|^2 + \lambda \|\hat{x}\|_1.$$

- Also works for other types of random matrices, e.g. $\{\pm 1, 0\}$, as long as the entries of A are independent
- For MRIs, the random matrix A is not independent, but has nice Fourier structures, so you can almost recover the same guarantees.
- many, many, many variants of the problem ($> 20,000$ papers!).
 - faster algs
 - different A
 - sparse A
 - robustness \leftarrow [KLLTS'24] ..

"Proof" of correctness

Consider first the following, non-convex problem:

$$\min \|\hat{x}\|_0 \text{ s.t. } A\hat{x} = b. \quad (**)$$

Why does this work?

not standard

Def: we say a matrix A satisfies the no-sparse-kernel property if there is no nonzero $2k$ -sparse vector in $\ker(A)$.

$$\begin{bmatrix} | & | & | & | \\ | & | & | & | \end{bmatrix} \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} \neq 0.$$

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Thm: If A satisfies NSK, then x is the unique solution to $(Ax = b)$.

Pf: Suppose y is k -sparse and $Ay = b$. Then $A(x-y) = 0$, and
 $x-y$ is $2k$ -sparse.
 $\Rightarrow x-y = 0$.

$$\begin{aligned} & A(x-y) = 0 \\ & \uparrow \\ & x-y \in \ker(A) \end{aligned}$$

Thm: If A is random, $n = \Omega(k \log(m/k))$, then w.h.p., it satisfies NSK property.

In fact, we can show something even stronger:

Def: We say a matrix A has the (p, ε) -restricted isometry property (RIP) if for all x p -sparse, we have that

$$(1-\varepsilon)\|x\|_2 \leq \|Ax\|_2 \leq (1+\varepsilon)\|x\|_2.$$

[Candes-Tao '04, Candes-Romberg-Tao '04].

Thm: If A is an appropriately scaled random matrix w/ $n = \Omega\left(\frac{p \log(n/p)}{\varepsilon^2}\right)$, then w.h.p. A satisfies the $(2p, \varepsilon)$ -RIP.

Cor: A also satisfies NSK w.h.p.

Pf of Theorem: This is pretty much Johnson-Lindenstrauss!!

Recall: given m points $\{x_i\}_{i=1}^m$, a (suitably scaled) Gaussian matrix A w/

$n = \frac{\log m}{\varepsilon^2}$ rows satisfies

$$\|A(x_i - x_j)\|_2^2 \approx (1 \pm \varepsilon) \|x_i - x_j\|_2^2 \text{ w.h.p.}$$

pretty much equivalently,

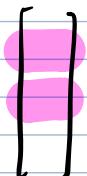
$$\|Ax_i\|_2^2 \approx (1 \pm \varepsilon) \|x_i\|_2^2 \quad \forall i.$$

How big is m ? technically, infinite

But like in generalization, $m \approx \# \text{ degrees of freedom}$.

To specify a vector w/ sparsity p :

1. Specify p coordinates $\rightarrow \binom{n}{p}$ choices
2. Specify values on coordinates $\rightarrow 2^p$ choices.



$$\begin{aligned} \log m &= \log \binom{n}{p} + 2^p \\ &\leq O(\log \binom{n}{p} + p) \end{aligned}$$

$$\binom{n}{p} \leq n^p, \text{ but slightly tighter: } \log(\binom{n}{p}) \leq p \log(n/p) \\ \leq O(p \log(1/p) + p).$$

What about for ℓ_1 -minimization?

need something stronger than NSK property.

Def: We say A has the restricted nullspace property (RNP) if $\forall z \in \ker(A)$, and any set S of $\leq k$ coordinates,

$$\sum_{i \in S} |x_i| < \sum_{i \notin S} |x_i|.$$

Fact: ℓ_1 -minimization recovers the true support $\Leftrightarrow A$ has RNP.

Fact: If A satisfies $(2k, \ell_1)$ -RIP, then A satisfies RNP.

So random matrix also works for ℓ_1 -minimization / basis pursuit.