

Lecture 17: Markov Chain Monte Carlo (MCMC)

Sampling: given a potentially incomplete description of a probability distribution, or indirect access to it, generate new, fresh samples from this distribution.

e.g. generative models:

Stable diffusion:

"generate a picture of a cat" →



input: a dataset of images of cats

output: another picture of a cat

not from dataset! But still from
distribution of images of cats!

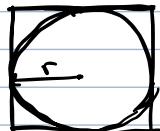
next lecture: diffusion models!

Monte Carlo methods:

Sometimes, sampling is a useful way of efficiently computing/approximating some hard process or system.

Such approaches are referred to as Monte Carlo Simulations

e.g. approximating π : suppose I have the following dartboard:



What is the probability that a random dart falls in the circle?

$$= \frac{\text{area of circle of radius } r}{\text{area of square w/ sidelength } 2r} = \frac{\pi r^2}{(2r)^2} = \frac{\pi}{4}.$$

Idea: throw n darts, and guess $\pi \approx 4 \cdot (\text{fraction of darts in circle})$.

Let $X_i = \mathbb{1}[\text{i}^{\text{th}} \text{ dart is in circle}]$.

Then fraction of darts in circle = $\frac{1}{n} \sum_{i=1}^n X_i$ ✓ independent.

$$\mathbb{E}[X_i] = \pi/4.$$

$$\text{Chernoff: } \Pr\left[\left|\frac{1}{n} \sum X_i - \frac{\pi}{4}\right| \geq \varepsilon\right] \leq \exp(-cn\varepsilon^2)$$

So if we want an ε -approximation of $\pi/4$ w.p. 1- δ , can take $n = O\left(\frac{\log(1/\delta)}{\varepsilon^2}\right)$.

See also: Buffon's needle

An important special case of Monte-Carlo methods: Markov Chain Monte Carlo (MCMC).

Def: A Markov process is specified by :

1. A set of states $S = \{s_1, \dots\}$

2. A transition function

$$P: S \times S \rightarrow [0, 1].$$

Here, for any s_i, s_j , $P(s_i, s_j) = \Pr[\text{1 transition to } s_j \mid \text{in state } s_i]$.

In particular, $\forall s_i, \sum_{s_j} P(s_i, s_j) = 1$.

Given a Markov process, and an initial state X_0 , this defines a random walk

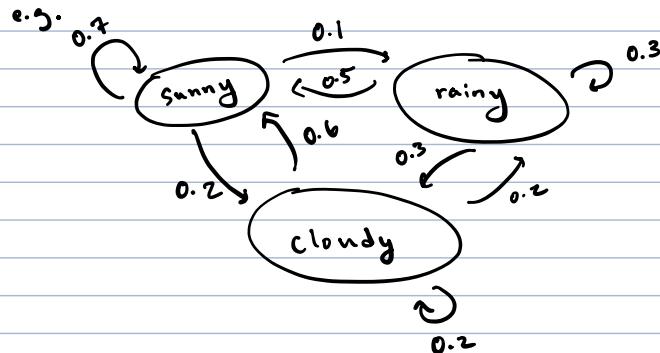
$X_0 \ X_1 \ X_2 \ \dots$
↑
↑
at random!

where for all $i \geq 1$, we sample X_i by choosing a random transition from X_{i-1}

$$\Pr[X_i = s_i \mid X_{i-1} = t] = P(s_i, t).$$

When there are n states, we usually represent transitions as a $n \times n$ transition matrix

$$P_{ij} = P(s_i, s_j).$$



	sunny	cloudy	rainy
sunny	0.7	0.2	0.1
cloudy	0.6	0.2	0.2
rainy	0.5	0.2	0.3

Key property of Markov Chains : the transition probability at time t depends only on the state X_t , and not how we got to X_t .

"Markov property".

"memory-less"

Examples:

- weather systems
- (some) board games : Monopoly, snakes + ladders
- genetics and inheritance

Some examples of not Markov chains:

- blackjack (if you track state of deck)
- stock market (if people learn from the past...?)

Computing with Markov Chains:

Suppose we have initial state $X_0 = s$. Let v_t be the probability distribution of X_t , i.e.:

$$v_t(x) = \Pr[X_t = x \mid X_0 = s].$$

1). How can we compute v_t ?

2). What is the behavior of v_t as $t \rightarrow \infty$?

Def: A probability distribution π on $\{s_1, \dots, s_n\}$ is a stationary distribution if for all initial states X_0 ,

$$v_t(x) \rightarrow \pi(x) \quad \forall x \in \{s_1, \dots, s_n\}.$$

e.g. PageRank (Google's claim to fame).

states = {webpages on the internet}.

transition: w.p. 0.8, choose a random outgoing link from current website.

w.p. 0.2, transition to uniformly random website.

Claim: π (the stationary distribution) roughly corresponds to importance of pages

π is known as the PageRank distribution.

Approach 1: Think of v_t as a n -dimensional row vector.

Initially, $v_0 = (0, 0, \dots, 1, 0, \dots 0)$

\uparrow
s

Claim: $v_t = v_{t-1} \cdot P$

Pf: Fix j . Then

$$\Pr[X_{t+1}=j \mid X_0=s] = \sum_i \Pr[X_{t+1}=j \mid X_t=i] \cdot \Pr[X_t=i \mid X_0=s]$$

$\uparrow \qquad \qquad \qquad \uparrow$
 $P_{ij} \qquad \qquad v_t(:)$

$$[\qquad] \left[\begin{matrix} 0 \\ \vdots \end{matrix} \right]$$

So by induction,

$$v_t = v_0 \cdot P^t. \quad \text{← power iteration!}$$

under appropriate conditions, $v_t \rightarrow \pi$ quite quickly as we'll discuss later.

When n is small, can approximate quickly via iterated squaring.

$$P \rightarrow P^2 \rightarrow (P^2)^2 = P^4 \rightarrow (P^4)^2 = P^8 \dots$$

What to do when n is very large?

MCMC: A way of approximating stationary distributions for "nice" Markov chains, even when the # of states can be huge.

Idea: just directly simulate the Markov Chain!

Initialize X_0 somehow

for $t=1, \dots, T$

- pick X_t at random from transition probability given X_{t-1} .

Common Algorithmic Framework:

1. Define a random walk/Markov chain so that transition probability induces a stationary distribution π w/ desirable properties
 - it encodes useful info
 - it puts more weight on good solns.

2. Run MCMC

3. Hope it finds a good solution.

Often, even when # of states is very large, MCMC "mixes" rapidly to a good solution.

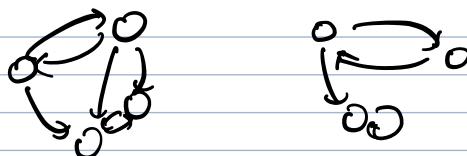
Analyzing mixing times

Q. Is the stationary distribution unique?

Q. How long do we have to run MCMC / power iteration to sample from something close to the stationary distribution?

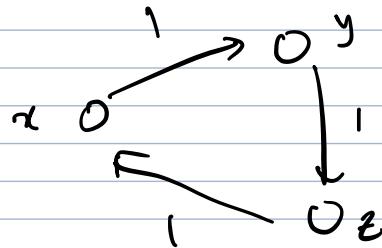
Two barriers to unique stationary distributions:

- 1). Not strongly connected



Def: A MC is reducible if its digraph is not strongly connected.
Otherwise, it is irreducible.

2. Periodicity



$$X_0 = x$$

$$X_t = x \Leftrightarrow t = 0 \pmod{3}.$$

No stationarity for this starting distribution!

Def: A chain is aperiodic if

$$\gcd(\{t : P_t(x, y) > 0\}) = 1 \quad \forall x, y \in S.$$

prob 1 transition from x to y in t steps.

In above: $\gcd = 3$ so chain is periodic.

Fundamental theorem of Markov Chains: If a Markov Chain is irreducible and aperiodic, then it has a unique stationary distribution.

How quickly do we mix? ← what does it even mean to be "close" to a stationary distribution?

Def: Given two probability distributions μ, ν on S , the total variation distance is defined as

$$\begin{aligned} d_{TV}(\mu, \nu) &= \frac{1}{2} \sum_x |\mu(x) - \nu(x)| = \frac{1}{2} \|\mu - \nu\|_1 \\ &= \max_E |\Pr_{\mu}[E] - \Pr_{\nu}[E]|. \end{aligned}$$

Def: The mixing time of a chain is defined to be:

$$T_{\text{mix}} = \min_t \left\{ d_{TV}(\pi, P_t) \leq \frac{1}{4} \right\} \text{ for all initial state } x_0 \in S.$$

↑
specific const not very important

Fact: After $c \cdot T_{\text{mix}}$ steps, $d_{TV}(\pi, P_t) \leq e^{-c}$.

How to understand mixing time? One approach: spectral

Consider the special case where P is symmetric "reversible":

$$P(x, y) = P(y, x).$$

Recall: For any initial distribution v_0 ,

$$v_t = v_0 \cdot P^t$$

For a stationary distribution π , note that

$$\lim_{t \rightarrow \infty} v_t = \pi$$

$$\lim_{t \rightarrow \infty} v_t P = \pi P$$

$$= \lim_{t \rightarrow \infty} v_{t+1} = \lim_{t \rightarrow \infty} v_t = \pi$$

so $\pi = \pi P \Rightarrow \pi$ is a eigenvector of P w/ eigenvalue 1.

Let $\lambda_1 \leq \dots \leq \lambda_n$ be the eigenvalues of P .

Fact: $|\lambda_i| \leq 1 \forall i$

Fact: If P is irreducible, then $\lambda_{n-1} < 1$.

Fact: If P is aperiodic, then $\lambda_1 > -1$.

} \Rightarrow FT of Markov Chains!

Let $v_1, \dots, v_n \propto \pi$ be the eigenvectors of P . Since P is symmetric, it admits a spectral decomposition:

$$P = \sum \lambda_i v_i v_i^T = \frac{\pi \pi^T}{\|\pi\|_2^2} + \sum_{i \neq n} \lambda_i v_i v_i^T.$$

$$P^t = \sum \lambda_i^t v_i v_i^T = \frac{\pi \pi^T}{\|\pi\|_2^2} + \sum_{i \neq n} \lambda_i^t v_i v_i^T$$

$$\text{so } v P^t = \frac{\langle v, \pi \rangle}{\|\pi\|_2^2} \pi^T + \sum_{i \neq n} \lambda_i^t \langle v, v_i \rangle v_i^T$$

$\xrightarrow{\quad \text{as } t \rightarrow \infty \quad}$

(actually, this shows that for symmetric MC, π is uniform!).