

Rescue::getCompassValue



```
graph LR; A[Rescue::getCompassValue] --> B[Rescue::convert_bearing_to_degrees]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'Rescue::getCompassValue'. A dark blue arrow points from the right side of this box to the left side of the right box. The right box is white with a black border and contains the text 'Rescue::convert\_bearing\_to\_degrees'.

Rescue::convert\_bearing  
\_to\_degrees