DifferentialWheels	
$\stackrel{\triangle}{ au}$	
Rescue	
_distance_sensor_forward_camera_left_speed_mode	
my_compass my_gps right_speed	
spherical_camera time_step - angle	
y 20 más	
+ addSpeed() + Back()	
+ bug0()	
+ cameraProcess() + controlForward()	
+ controlLine()	
+ convert_bearing_to degrees()	
+ folloWall()	
+ getSensorsValue()	
+ Go() y 8 más	