

Advanced Programming Languages for AI Constraint Logic Programming

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Constraint (Logic) Programming

1. Top-down search with passive constraints (Prolog)
2. Delaying automatically (arithmetic constraints) using the suspend library
3. Constraint propagation in ECLiPSe
the symbolic domain library (**sd**)
the interval constraints library (**ic**)
4. Top-down search with active constraints, also variable and value ordering heuristics
5. Optimisation with active constraints
6. Constraints on reals (**locate** library)
7. Linear constraints over continuous and integer variables (**eplex** library)

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1. TOP-DOWN SEARCH WITH PASSIVE CONSTRAINTS

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1. Top-down search with passive constraints

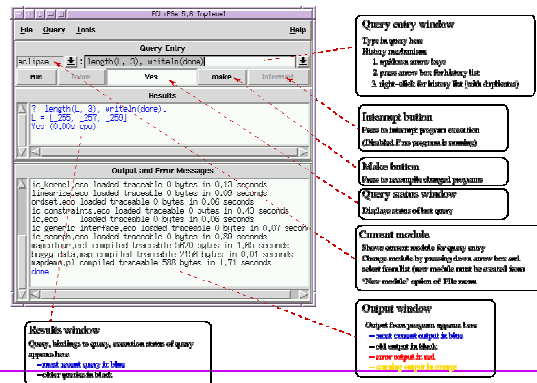
1. Solving finite CSPs using Prolog (ECLiPSe)
2. Backtracking search in Prolog
3. Incomplete search: credit+lds search
4. Counting the number of backtracks (to measure efficiency)
5. Prolog implies: constraints are passive and can only be used as tests

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Tools

TkEclipse

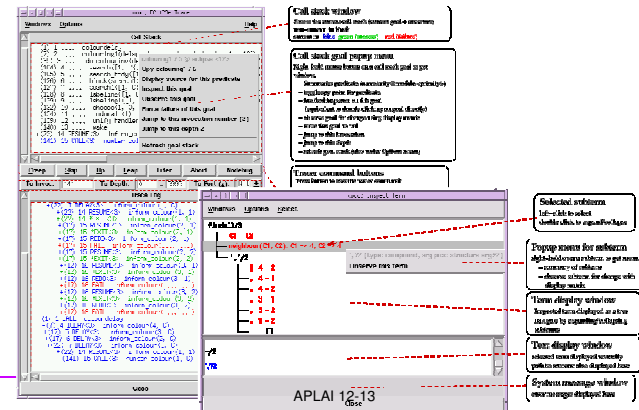


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Tools

Tracer and Data Inspector



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Arithmetic constraints: passive

- Compare $f(a,X) = f(Y,b)$ with $3^*X < Y + 2$

Both put restrictions on the variables

But arithmetic constraint can only be processed when all the variables are ground

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1. High level program for solving CSPs

```
solve(List) :-
    declareDomain(List),           %info about domains
    search(List),                  %launch search process
    testConstraints(List).
```

Generate and Test approach: INEFFICIENT

Example: SEND+ MORE = MONEY

number of decision variables: 8

number of leaves in the search tree: 10^8

(Better approach: interleave ...)

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2. Backtracking search in Prolog

- labelling as the branching method:
i.e. split a finite domain of a variable into singletons
- degrees of freedom:
 - order in which variables are labeled
 - which values are selected in the variable domains

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The variable ordering

- variables X and Y;
X has 2 possible values and Y has 4
 - number of leaves in the search tree?
 - number of internal nodes?
 - to keep the number of internal nodes low:
 - label the variables with fewer choices earlier
- ```
search(X,Y) :- member(X,[1,2]),
 member(Y,[1,2,3,4]),
 X + Y =:= 6 . % passive constraint
```

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## The value ordering

- Is the size of the search tree affected by different value orderings?
- No, as all values have to be explored.
- (Except in the case of incomplete search)

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## extra: iteration and recursion in ECLiPSe

- how do you write a predicate to write all elements of a given list on separate lines??
- iteration over the elements of a list:  
`[eclipse 1]: (foreach(E1, [a,b,c]) do writeln(E1)).`

```
foreach(E1,List) do Query(E1)
Iterate Query(E1) over each element E1 of the list
List
```

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## extra: The iterator `fromto` in ECLiPSe

`fromto(First, In, Out, Rest) do Query(In, Out)`  
**Iterate** `Query(In, Out)` starting with `In = First`, until  
`Out = Rest`

```
[eclipse 2]: (fromto([a,b,c], [H|Tail], Tail, []))
 do
 writeln(H)
).
a % [a,b,c] = [H |Tail] and Tail is threaded
b % [b,c] [c]
c % [c] []
% replaces recursion
% User Manual: Ch 5 ECLiPSe specific language features
```

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## Combining iterators:

!!! synchronous iteration

```
[eclipse 3]: (fromto([a,b,c], [H|Tail], Tail, []),
 foreach(E1, List)
 do
 E1 = H
).
[eclipse 4]: (fromto([], Tail, [H|Tail], [a,b,c]),
 foreach(E1, List)
 do
 E1 = H
).
```

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## extra: iterators

- write `ordered(List)` with `fromto`
- write `reverse/2` with `fromto` and `foreach`

```
ordered(List) :-
 (fromto(List, [E1|Rest], Rest, [])
 do
 ordered2(E1, Rest)
).

ordered2(_, []).
ordered2(X, [Y|_]) :- X <= Y.
```

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## Variable and value orderings in Prolog

```
% assign values from the variable domains to all the
% Var-Domain pairs in List
search(List) :-
 (fromto(List, Vars, Rest, [])
 do
 choose_var(Vars, Var-Domain, Rest),
 choose_val(Domain, Val),
 Var = Val
).
choose_var(List, Var, Rest) :- List = [Var|Rest].
choose_val(Domain, Val) :- member(Val, Domain).
```

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### 3. Incomplete search

- Assume: the 'better' values appear earlier in the domains of the variables
- Incomplete search : find values appearing earlier in the domains
- N best values
- Credit based search: allocate credit to each value choice, giving more credit to better vals; credit is available for the 'further' search
- Limited discrepancy search: measure a distance from the preferred left-hand branch

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```
search(List, Credit) :-
 (fromto(List, Vars, Rest, []),
 fromto(Credit, CurCredit, NewCredit, _)
 do choose_var(Vars, Var-Domain, Rest),
 choose_val(Domain, Val, CurCredit, NewCredit),
 Var = Val
).
choose_val(Domain, Val, CurCredit, NewCredit) :-
 share_credit(Domain, CurCredit, DomCredList),
 member(Val-NewCredit, DomCredList).
% share_credit(Domain, N, DomCredList) admits
% only the first N values.
share_credit(Domain, N, DomCredList) :-
 (fromto(N, CurCredit, NewCredit, 0),
 fromto(Domain, [Val|Tail], Tail, _),
 foreach(Val-NewCredit, DomCredList),
 param(N) % normally: to pass N into body of iterator
 do (Tail = [] -> NewCredit is 0 ;
 NewCredit is CurCredit - 1)
).
```

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### Credit based search

```
?- share_credit([1,2,3,4,5,6,7,8,9],5, Dlist).
Dlist = [1 - 5, 2 - 5, 3 - 5, 4 - 5, 5 - 5]
?- share_credit([1,2,3],5, Dlist).
Dlist = [1 - 5, 2 - 5, 3 - 5]
?-
```

- How to allocate half the credit to the first value of the domain, half of the remaining value to the second value, and so on. When only 1 credit is left, the next value is selected and is the last.

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### Credit based search: binary chop

```
% share_credit(Domain, N, DomCredList)
% Allocate credit N by binary chop
share_credit(Domain, N, DomCredList) :-
 (fromto(N, CurCredit, NewCredit, 0),
 fromto(Domain, [Val|Tail], Tail, _),
 foreach(Val-Credit, DomCredList)
 do (Tail = [] -> Credit is CurCredit
 ;
 Credit is fix(ceiling(CurCredit/2))
 % smallest integer >= CurCredit/2
),
 NewCredit is CurCredit - Credit
).
```

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```
?- share_credit([1,2,3,4,5,6,7,8,9],5, Dlist).
Dlist = [1 - 3, 2 - 1, 3 - 1]
```

```
?- share_credit([1, 2, 3, 4, 5, 6, 7, 8, 9], 1000,
 Dlist).
Dlist = [1 - 500, 2 - 250, 3 - 125, 4 - 63, 5 - 31, 6 -
 16, 7 - 8, 8 - 4, 9 - 3]
```

```
?- search([X-[1,2,3,4,5,6,7,8,9], Y-[1,2,3,4], Z-[1,2,3,4]],5).
% only 5 solutions: 1 1 1 ; 1 1 2; 1 2 1; 2 1 1 ; 3 1 1
```

```
?- search([X-[1,2,3], Y-[1,2,3], Z-[1,2,3]],8).
% 1 1 1 ; 1 1 2; 1 2 1; 1 3 1 ; 2 1 1 ; 2 2 1 ; 3 1 1 ;
 3 2 1
```

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```
?- share_credit([1,2,3,4,5,6,7,8,9],8, Dlist).
Dlist = [1 - 4, 2 - 2, 3 - 1, 4 - 1]
```

```
?- search([X-[1,2,3], Y-[1,2,3], Z-[1,2,3]], 8).
% 1 1 1 ; 1 1 2; 1 2 1; 1 3 1 ; 2 1 1 ; 2 2 1 ; 3 1 1 ;
 3 2 1
```

```

For X share_credit([1, 2, 3], 8, [1 - 4, 2 - 2, 3 - 2])
 choose_val([1, 2, 3], 1, 8, 4)
For Y share_credit([1, 2, 3], 4, [1 - 2, 2 - 1, 3 - 1])
 choose_val([1, 2, 3], 1, 4, 2)
For Z share_credit([1, 2, 3], 2, [1 - 1, 2 - 1])
 choose_val([1, 2, 3], 1, 2, 1)
1 1 1; 1 1 2; 1 2 ??? With value 2 having credit 1 for Y
For Z share_credit([1, 2, 3], 1, [1 - 1])
 choose_val([1, 2, 3], 1, 1, 1)

```

## Examples lds search

```
?- share_credit([1, 2, 3, 4, 5, 6, 7, 8, 9], 5,
 Dlist).
Dlist = [1 - 5, 2 - 4, 3 - 3, 4 - 2, 5 - 1]

?- share_credit([1, 2, 3], 5, Dlist).
Dlist = [1 - 5, 2 - 4, 3 - 3]

?- search([X-[1,2], Y-[1,2], Z-[1,2], U-[1,2], V-
 [1,2]], 2).
% 6 solutions 1 1 1 1 1; 1 1 1 1 2; 1 1 1 2 1;
1 1 2 1 1; 1 2 1 1 1; 2 1 1 1 1
```

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## 4. Getting an idea of the amount of search

- by counting the number of backtracks
- you need some system predicates like ...  
[eclipse 3]: N is 3, setval(count,N), inval(count),  
getval(count, M).  
N = 3 M = 4  
% N is the number of times the query Q succeeds

```
succeed(Q,N) :-
 (setval(count,0),
 Q,
 inval(count), % count the number of successes
 fail
);
 true
),
getval(count,N).
```

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## Counting the number of backtracks

```
search(List, Backtracks) :-
 init_backtracks,
 (fromto(List, Vars, Rest, [])
 do
 choose_var(Vars, Var-Domain, Rest),
 choose_val(Domain, Val),
 Var = Val,
 count_backtracks
),
 get_backtracks(Backtracks).

init_backtracks :- setval(backtracks,0).
get_backtracks(B) :- getval(backtracks,B).
count_backtracks :- on_backtracking(inval(backtracks)).
on_backtracking(_). % Until a failure happens do nothing.
% The second clause is entered
on_backtracking(Q) :- % on backtracking.
 once(Q), % Query Q is called, but only once.
 fail. % Backtracking continues afterwards.
```

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## 2. DELAYING CONSTRAINTS USING THE SUSPEND LIBRARY

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## 2. Delaying automatically constraints using the suspend library

- Why delay a constraint?
- What do we do with delayed constraints?
- Still only passive constraints
- First step towards realizing constraint programming; used by more sophisticated constraint solvers
- Core constraints and user defined constraints
- Examples using the `suspend` library

## Interleaving generate and test

```
solve(List) :-
 declareDomain(List), %info about domains
 search(List), %launch search process
 testConstraints(List).
```

What can be changed??

```
:- library(my_library). % e.g. suspend
solve(List) :-
 declareDomain(List), %info about domains
 generateConstraints_andcosts(List, Cost),
 search(List, Cost). %launch search process
```

## Library issues

```
[eclipse 1]: 2 < Y + 1, Y = 3.
instantiation fault in +(Y, 1, _173)
Abort
```

```
[eclipse 2]: suspend:(2 < Y + 1), Y = 3.
Y = 3
Yes
```

% delays the `</2` constraint until it becomes ground

## Meta-interpreter for Prolog with built-ins

```
% solve(X) :-
% the query X succeeds for the Prolog
% program accessible by clause/2.
solve(true) :- !.
solve((A,B)) :- !, solve(A), solve(B).
solve(A) :- rule(A, B), solve(B).
```

```
rule(A,B) :-
 functor(A,F,N), is_dynamic(F/N),
 clause(A,B). % user defined
rule(A,true) :- A. % for built-ins
```



## Meta-interpreter for the suspend library

```
% pass delayed goals around; delay; re-activate/trigger
solve(true, Susp, Susp):- !.
solve((A,B), SuspIn, SuspOut) :- !,
 solve(A, SuspIn, Susp2), solve(B, Susp2, SuspOut).
solve(A, Susp, (A, Susp)) :- postpone(A),!.
solve(H, SuspIn, SuspOut) :- rule(H, B),
 solve(SuspIn, true, Susp2),
 solve(B, Susp2, SuspOut).

postpone(suspend:A) :- not ground(A).

rule(A,B) :-
 functor(A,F,N), is_dynamic(F/N),
 clause(A,B).
rule(suspend:A, true) :- !, A.
rule(A, true) :- A.
```

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## Core constraints in ECLiPSe

- Available in all the constraint solvers where they make sense
  - Boolean constraints
  - Arithmetic constraints
  - Variable declarations
  - so-called Reified constraints
- The programmer uses them to model the CSP (generate constraints) and can send them to several constraint solvers, also to the **suspend** library

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## Boolean constraints

```
[eclipse 1]: suspend:(X or Y), X = 0. % 0 for false
X = 0
Y = Y
Delayed goals: suspend: (0 or Y) % waits grounding
Yes

[eclipse 2]: suspend:(X or Y), X = 0, Y = 1.
X = 0
Y = 1
Yes
% also and/2, neg/1, =>/2
```

What happens with a core constraint that becomes fully instantiated?

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## Known: Arithmetic comparison predicates

- |                         |     |
|-------------------------|-----|
| ■ Less than             | <   |
| ■ Less than or equal    | =<  |
| ■ Equality              | =:= |
| ■ Disequality           | =\= |
| ■ Greater than or equal | >=  |
| ■ Greater than          | >   |

Available as core constraints: **suspend:(1+Y>3)**

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## Shorthands for arithmetic constraints

once the suspend library is loaded

`1 + 2 $= Y` is a shorthand for

`suspend:( 1 + 2 := Y)`

also `$<`, `$=<`, `$\=$`, `$>=`, `$>` (for reals)

also for integers `#<`, `#=<`, `#\=$`, `#>=`, `#>`, `#=`

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## Quicksort with delayed tests

```
% qs(Xs, Ys) :-
% Ys is an =<-ordered permutation of the list Xs.
qs([], []).
qs([X | Xs], Ys) :- part(X, Xs, Littles, Bigs),
 qs(Littles, Ls), qs(Bigs, Bs),
 app(Ls, [X | Bs], Ys).
% part(X, Xs, Ls, Bs) :-
% Ls is a list of elements of Xs which are < X,
% Bs is a list of elements of Xs which are >= X
part(_, [], [], []).
part(X, [Y | Xs], [Y | Ls], Bs) :-
 X $> Y, part(X, Xs, Ls, Bs).
part(X, [Y | Xs], Ls, [Y | Bs]) :-
 X $=< Y, part(X, Xs, Ls, Bs).

[eclipse 5]: qs([3.14,Y,1,5.5],[T,2,U,Z]). %???
```

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## Variable declarations: just unary constraints

- are not really relevant for suspend context; only used as a test whether the variable becomes correctly instantiated.

```
[S,E,N,D,M,O,R,Y] :: 0..9 % over an integer interval
```

```
[eclipse 1]: X :: 1..9, X = 5
X = 5
```

Yes

```
[eclipse 2]: X :: 1..9, X = 0
```

No

```
[eclipse 3]: X $:: 1..9, X = 2.5 % over a real interval
X = 2.5 % or use reals as bounds
```

Yes

```
[eclipse 4]: X :: 1 .. 9, X = 2.5.
No (0.00s cpu)
```

```
[eclipse 5]: reals(X), X = [1,2.3], reals(Y), Y = [1,a].
%kind of type declaration thus [1,a]???
```

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## Reified constraints

- are constraints that can be switched to true or false by setting an extra Boolean variable
- all the core constraints can be reified
- [eclipse 11]: `$>(5,4,1)`.  
Yes
- [eclipse 12]: `$>(4,5,1)`.  
No
- [eclipse 12]: `$>(4,5,Bool)`.  
Bool = 0
- [eclipse 13]: `$:: (X,1..9,0)`, `X = 10`.  
Yes

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## Reification (once more)

- From Latin
- *res* thing + *facere* to make
- reification can be 'translated' as thing-making; the turning of something abstract into a concrete thing or object.

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## User defined suspensions

```
[eclipse 4]: suspend(x := 10, 3, x -> inst).
```

```
x = x
```

```
Delayed goals: x := 10
```

```
[eclipse 5]: suspend(x := 10, 3, x -> inst), x is
2 + 8.
```

```
x = 10
```

```
Yes
```

2<sup>nd</sup> argument is priority of the goal when it wakes up

3<sup>rd</sup> argument is wakeup condition **Term** -> **Cond**

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xor(X,Y) has to wake up when both  
variables are instantiated

```
susp_xor(X,Y) :-
 (nonvar(X) ->
 susp_y_xor(X,Y)
);
 suspend(susp_y_xor(X,Y), 3, x -> inst)
).
```

```
susp_y_xor(X,Y) :-
 (nonvar(Y) ->
 xor(X,Y)
);
 suspend(xor(X,Y), 3, Y -> inst)
).
xor(1,0).
xor(0,1).
```

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## Examples

```
?- susp_xor(X, Y).
```

```
X = X Y = Y
```

```
There is 1 delayed goal. (0) <3> susp_y_xor(X, Y)
```

```
?- susp_xor(X, Y), X = 0.
```

```
X = 0
```

```
Y = Y
```

```
There is 1 delayed goal. (0) <3> xor(0, Y)
```

```
?- susp_xor(X, Y), Y = 1.
```

```
X = X
```

```
Y = 1
```

```
There is 1 delayed goal. (0) <3> susp_y_xor(X, 1)
```

```
?- suspend(xor(X, Y), 3, [X, Y] -> inst), Y = 0. % one of [X,Y]
```

```
X = 1 Y = 0
```

```
Yes (0.00s cpu)
```

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## Generating CSPs

- $x \neq y, y \neq z, x \neq z;$   
 $x \in \{0,1\}, y \in \{0,1\}, z \in \{0,1\}$

```
[eclipse 1]: [X,Y,Z] :: 0..1, X #\= Y, Y #\= Z,
 X #\= Z.
```

```
X = X Y = Y Z = Z
```

There are 4 delayed goals.

```
(0) <2> suspend : ([X, Y, Z] :: 0 .. 1)
(0) <2> suspend : (X #\= Y)
(0) <2> suspend : (Y #\= Z)
(0) <2> suspend : (X #\= Z)
```

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## Generating CSPs

- $x_1 < x_2, x_2 < x_3, \dots, x_{n-1} < x_n;$   
 $x_1 \in \{1..1000\}, \dots, x_n \in \{1..1000\}$
- ```
[eclipse 2]: List = [X,Y,Z,U,V,W], List :: 1..1000,  
             ordered(List).
```

```
ordered(List) :-  
    ( fromto(List,[E1|Rest],Rest,[])  
      do  
        ordered2(E1, Rest)  
      ).
```

```
ordered2(_, []).  
ordered2(X, [Y|_]) :- X #< Y.
```

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`diff_list(List)` succeeds when `List` is a list
of different values

- write it

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Generating CSPs

- Why suspend?? what to delay??
- Results in an adequate reordering of the goals so that they are evaluated as soon as their arguments have become instantiated.
- Examples:
 - SEND+MORE=MONEY
 - Map colouring
 - N-queens
- Array representation in ECLiPSe

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SMM: representation 1

- 1 equality constraint

$$\begin{aligned} &1000.S + 100.E + 10.N + D \\ &+ 1000.M + 100.O + 10.R + E \\ = &10000.M + 1000.O + 100.N + 10.E + Y, \end{aligned}$$

- 2 disequality constraints: $S \neq 0$, $M \neq 0$

- And 28 disequality constraints $x \neq y$ for x, y ranging over the set $\{S, E, N, D, M, O, R, Y\}$

```
solve(List) :-  
  declareDomain(List),  
  generateConstraints(List),  
  search(List).
```

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SMM with :-lib(suspend)

```
send(List):-  
  List = [S,E,N,D,M,O,R,Y],  
  List :: 0..9,  
  diff_list(List),  
          1000*S + 100*E + 10*N + D  
          + 1000*M + 100*O + 10*R + E  
  $= 10000*M + 1000*O + 100*N + 10*E + Y,  
  S $ \= 0, M $ \= 0,  
  search(List).  
search(List) :-  
  ( foreach(Var,List) do select_val(0, 9, Var) ).
```

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select_val(Min,Max,Val)

% Min, Max are ground arithmetic expressions
% and Val is an integer between Min and Max inclusive.

```
select_val(Min, Max, Val) :- Min =< Max, Val is Min.  
select_val(Min, Max, Val) :-  
  Min < Max,  
  Min1 is Min+1,  
  select_val(Min1, Max, Val).
```

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Programs can be found at

- on Toledo: eclipse example programs

- send_more_money_ch9.pl
- map_colouring.pl
- queens_ch9.pl

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Arrays in ECLiPSe : creation

Structures with functor `[]` and `dim/2` built-in

```
[eclipse 1]: dim(Array, [3])  
Array = [](_162,_163,_164)  
Yes
```

```
[eclipse 2]: dim(Array, [3,2])  
Array = []([](_174,_175),[](_171,_172),[](_168,_169))  
Yes
```

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Arrays: set/get value

```
[eclipse 2]: dim(Array, [3,2]),  
subscript(Array,[1,2],5).  
Array = []([](_174,5),[](_171,_172),[](_168,169))  
Yes
```

```
[eclipse 3]: dim(Array, [3,2]),  
subscript(Array,[1,2],5), X is Array[1,2] - 2,  
Y = f(Array[1,2]).
```

```
...  
X = 3  
Y = f(??)           % no evaluation here!!!
```

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Arrays and is/2

```
[eclipse 5]: A = []([](1,2),[](3,4),[](5,X)),  
E1 is A[3,2],  
Row is A[1, 1..2],  
Col is A[2..3, 2],  
Sub is A[2..3,1..2].  
  
.. Row = [1,2], Col = [4,X]  
Sub = [[3,4],[5,X]] % subarray as list of lists
```

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Array iterator: foreachlem/2

```
[eclipse 6]: dim(Array,[3,2]),  
( foreach(E1,[e11,e12,e21,e22,e31,e32]),  
  foreachlem(E1, Array)  
do  
  true  
) ,  
X is Array[2,2].  
  
Array = []([](e11,e12),[](e21,e22),[](e31,e32))  
X = e22
```

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More iterators

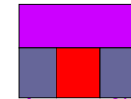
```
[eclipse 1]: ( for(I,1,3)
do
  ( for(J,5,9),
    param(I)
    do
      K is I*J, write(K), write(' ')
    )
  ).
5 6 7 8 9 10 12 14 16 18 15 18 21 24 27

[eclipse 2]: ( multitor([I,J],[1,5],[3,9])
do
  K is I*J, write(K), write(' ')
).
5 6 7 8 9 10 12 ...
```

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Map colouring



- A finite set of regions `Regions % array`
- A (smaller) set of colours `colour(1). %blue`
- A neighbour relation between pairs of regions
`neighbour(1,2). neighbour(1,3).`

Associate a colour with each region so that no two neighbours have the same colour!

Check constraints ASAP!!!

Decision variables? `dim(Regions,[Count])`

Domains? Constraints?

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Map colouring with lib(suspend)

```
colour_map(Regions) :-
  constraints(Regions),
  search(Regions).          % problemspecs : colour/1
                             % neighbour/2

constraints(Regions) :-
  no_of_regions(Count),      % also nb. of regions
  dim(Regions,[Count]),
  ( multitor([I,J],1,Count),
    param(Regions)
  do
    ( neighbour(I, J) -> Regions[I] $= Regions[J]
    ; true
    )
  ).
search(Regions):- ( foreach(elem(R,Regions) do colour(R) ).
```

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N-queens (repr. 2)

- x_i denotes the position of the queen in the i th column. `% 1-dim array`
- Implies that no two queens are placed in the same column.
- For $i \in [1..n]$ and $j \in [1..i-1]$
 - At most one queen per row: $x_i \neq x_j$
 - At most one queen per SE-NW diagonal
 $x_i - x_j \neq i - j$
 - At most one queen per SW-NE diagonal
 $x_i - x_j \neq j - i$

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N-queens with lib(suspend)

```
queens(QueenStruct, Number) :- dim(QueenStruct, [Number]),
    constraints(QueenStruct, Number), search(QueenStruct).

constraints(QueenStruct, Number) :-
    ( for(I,1,Number),
      param(QueenStruct, Number)
    do
        QueenStruct[I] :: 1..Number,
        ( for(J,1,I-1),
          param(I, QueenStruct)
        do
            QueenStruct[I] $\<= QueenStruct[J],
            QueenStruct[I]-QueenStruct[J] $\<= I-J,
            QueenStruct[I]-QueenStruct[J] $\<= J-I
        )
    ).
search(QueenStruct) :- dim(QueenStruct, [N]),
    ( foreach(elem(Col, QueenStruct), param(N)
    do select_val(1, N, Col)
    ).
```