

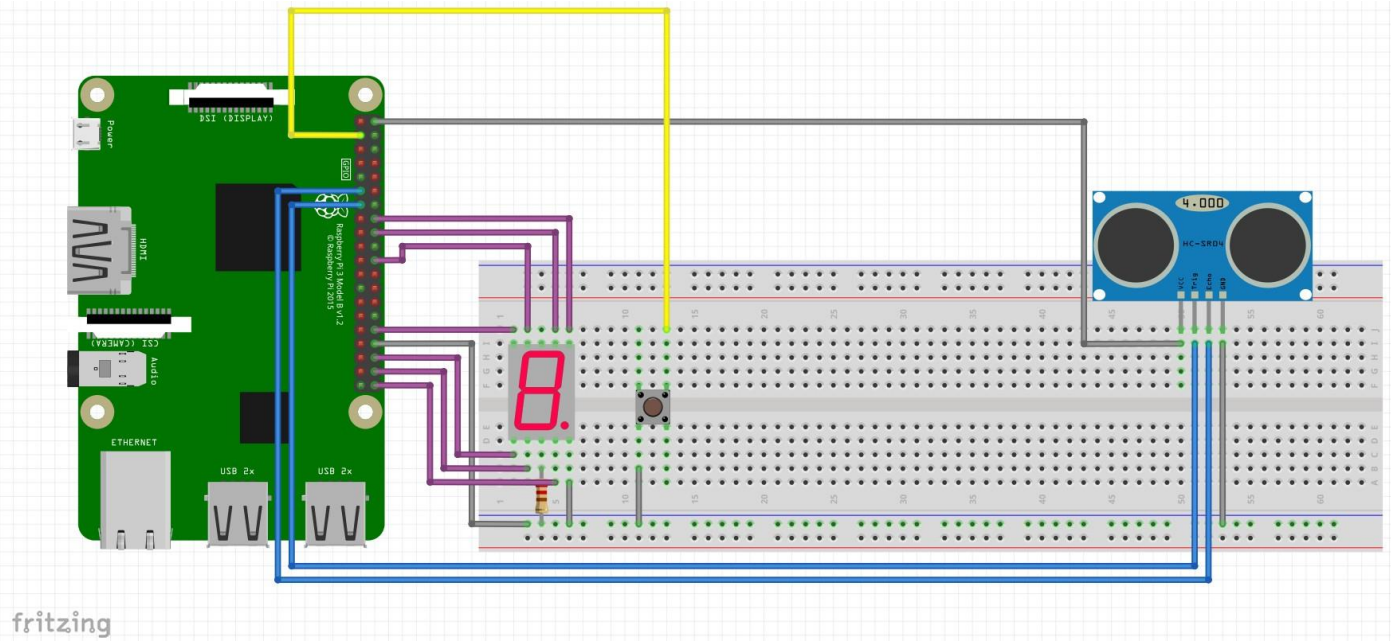
實驗二：Key, 7-segment, and Ultrasonic

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一、電路圖



找不到一樣大顆的按鈕圖例 QAQQQ 只好用小顆的代替。

二、程式

需求
(1) 7-segment 顯示"0"，Terminal 顯示 ultrasonic 偵測到障礙物的距離。 (2) Key pressed，7-segment 顯示"1"(0+1)，Terminal 顯示 ultrasonic 偵測到障礙物的距離 repeat (1)到(2)，7-segment 顯示累加的效果:0, 1, 2, 3, 4, 5, 6, 7, 8, 9, a, b, c, d, e, f, 0, 1, 2, ……
程式說明
步驟(1)對應函式 stepInit()，步驟(2)對應函式 main()中的函式 原需求可理解為按鈕按下後執行 「Terminal 顯示 ultrasonic 偵測到障礙物的距離」和「七解碼顯示 $[(\text{計數器數值}+1)\%16]$ 」 在 stepInit()先初始化所有數值和 pin 接著呼叫第一次的 ultrasonicDistance()計算距離 此後每次按下按鈕都會呼叫 keyAndSevenSegmentControl() 執行 ultrasonicDistance()計算距離和 sevenSegmentControl()更新七解碼狀態

程式

```
import RPi.GPIO as GPIO
import math
from time import time
from time import sleep

GPIO.setmode(GPIO.BCM)
pin_segA = 24
pin_segB = 23
pin_segC = 21
pin_segD = 20
pin_segE = 16
pin_segF = 25
pin_segG = 12
pin_ultraTrig = 27
pin_ultraEcho = 17
pin_key = 2
sevenSegmentPin = [
    pin_segG, pin_segF, pin_segE, pin_segD,
    pin_segC, pin_segB, pin_segA
]

sevenSegmentStringDict = {
    0: "0111111",
    1: "0000110",
    2: "1011011",
    3: "1001111",
    4: "1100110",
    5: "1101101",
    6: "1111101",
    7: "0000111",
    8: "1111111",
    9: "1101111",
    10: "1110111",
    11: "1111100",
    12: "0111001",
    13: "1011110",
    14: "1111001",
    15: "1110001"
}
```

```

userPressCount = 0

def stepInit():
    try:
        GPIO.setup(pin_key, GPIO.IN, GPIO.PUD_UP)
        GPIO.setup(pin_ultraEcho, GPIO.IN)
        GPIO.setup(pin_ultraTrig, GPIO.OUT)
        for pin in sevenSegmentPin:
            GPIO.setup(pin, GPIO.OUT)
        print("==== GPIO.setup done =====")
        for pinIndex in range(7):
            value = int(sevenSegmentStringDict[0][pinIndex])
            GPIO.output(sevenSegmentPin[pinIndex], value)
        print("==== 7-Segment setup done =====")
        GPIO.output(pin_ultraTrig, False)
        print("==== ultraTrig setup done =====")
        global userPressCount
        userPressCount = 0
        print("==== variable setup done =====")
        print("\n\n")
        print("=====")
        print("=====")
        print("==== press button to get distance ===")
        print("==== press keyboard ^C to finish ===")
        print("=====")
        print("=====")
        print("\n\n")
    except:
        print("now at state stepInit()")

def sevenSegmentControl(number):
    try:
        for pinIndex in range(7):
            value = int(sevenSegmentStringDict[number][pinIndex])
            GPIO.output(sevenSegmentPin[pinIndex], value)
    except:
        print("now at state sevenSegmentControl()")
        print("now number = ", number)

```

```

def ultrasonicEcho(value, timeout):
    count = timeout
    while GPIO.input(pin_ultraEcho) != value and count > 0:
        count = count - 1

def ultrasonicDistance():
    try:
        GPIO.output(pin_ultraTrig, True)
        sleep(0.001)
        GPIO.output(pin_ultraTrig, False)
        ultrasonicEcho(True, 5000)
        start = time()
        ultrasonicEcho(False, 5000)
        end = time()
        distance = round(((end-start) * 34000 / 2), 3)
        print("the distance = ", distance, " cm")
    except:
        print("now at state ultrasonicDistance()")

def keyAndSevenSegmentControl(pin_key):
    ultrasonicDistance()
    global userPressCount
    userPressCount += 1
    userPressCount %= 16
    sevenSegmentControl(userPressCount)

def main():
    stepInit()
    try:
        ultrasonicDistance()
        GPIO.add_event_detect(pin_key, GPIO.FALLING, callback=keyAndSevenSegmentControl, bouncetime=200)
        while (True):
            pass
    except KeyboardInterrupt:
        print("\n\n", "===== user STOP =====")
    except:
        print("\n\n", "===== other Exception =====")
    finally:
        GPIO.cleanup()
        print("===== GPIO cleanup done =====")
        print("===== end of main() =====")

```

```
main()
```

需求

- (1) 7-Segment 由 Key 來控制
- (2) Ultrasonic 不再被 Key 控制，而是獨立在主程式運作，每隔 3 秒顯示障礙物的距離

程式說明

原需求可理解為「Terminal 顯示 ultrasonic 偵測到障礙物的距離」和「按鈕計數器」兩個功能同時獨立運作，也就是需要兩條 thread 0u0
keyAndSevenSegmentControl() 僅留下計數、sevenSegmentControl() 的功能
而 ultrasonicDistance() 獨立於主程式中運作

以下原始碼僅展示改寫的部分 0u0

即 stepInit()、keyAndSevenSegmentControl()、main()

作業完整原始碼：https://colab.research.google.com/drive/1VnnKBSRmvi67gN_Qd4MrEBaymkH_Hn0T?usp=sharing

程式

```
def stepInit():
    try:
        GPIO.setup(pin key, GPIO.IN, GPIO.PUD UP)
        GPIO.setup(pin ultraEcho, GPIO.IN)
        GPIO.setup(pin_ultraTrig, GPIO.OUT)
        for pin in sevenSegmentPin:
            GPIO.setup(pin, GPIO.OUT)
        print("===== GPIO.setup done =====")
        for pinIndex in range(7):
            value = int(sevenSegmentStringDict[0][pinIndex])
            GPIO.output(sevenSegmentPin[pinIndex], value)
        print("===== 7-Segment setup done =====")
        GPIO.output(pin_ultraTrig, False)
        print("===== ultraTrig setup done =====")
        global userPressCount
        userPressCount = 0
        print("===== variable setup done =====")
        print("\n\n")
        print("=====")
        print("=====")
        print("=== press button to ++ the number ===")
        print("==== press keyboard ^C to finish ===")
        print("=====")
        print("=====")
        print("\n\n")
    except:
        print("now at state stepInit()")
```

```

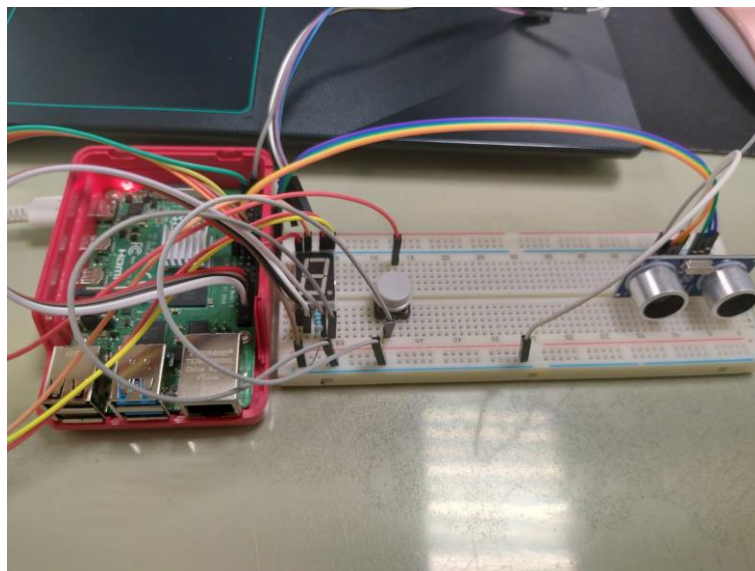
def keyAndSevenSegmentControl(pin key):
    # ultrasonicDistance()
    global userPressCount
    userPressCount += 1
    userPressCount %= 16
    sevenSegmentControl(userPressCount)

def main():
    stepInit()
    try:
        GPIO.add_event_detect(pin_key, GPIO.FALLING, callback=keyAndSevenSegmentControl, bouncetime=200)
        while (True):
            ultrasonicDistance()
            sleep(3)
    except KeyboardInterrupt:
        print("\n\n")
        print("==== user STOP =====")
    except:
        print("\n\n")
        print("==== other Exception =====")
    finally:
        GPIO.cleanup()
        print("==== GPIO cleanup done =====")
        print("==== end of main() =====")

main()

```

三、影片連結



YouTube 影片連結：<https://youtu.be/f457qV9jYiA>（原實驗 shell）

YouTube 影片連結：<https://youtu.be/F0ysTouVhgo>（原實驗麵包板）

分開控制的就沒錄了，想說影片也看不出來_(:3」∠)_

四、困難

不小心又一次過了，完全沒有卡關、(❀°▽°)ノ

硬要說遇到什麼困難，就是按鈕的腳太短，好難插到麵包板上、拔起來都用噴的。

五、心得

本來想說加一下家裡的網路，結果又回到 ping 不到板板的地獄了。

隔天看了一下路由器發現他是 5G 的，而且因為家裡的印表機要連線所以不能改 2.4G 試試，只好連回自己手機的網路了 QuQ

雖然不確定是不是頻率的問題，但我學會了遠距不要亂改網路設定，不然會嚇到寢食難安 QuQ