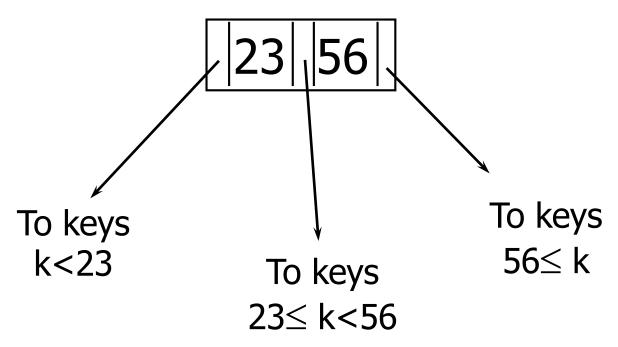
B+Tree

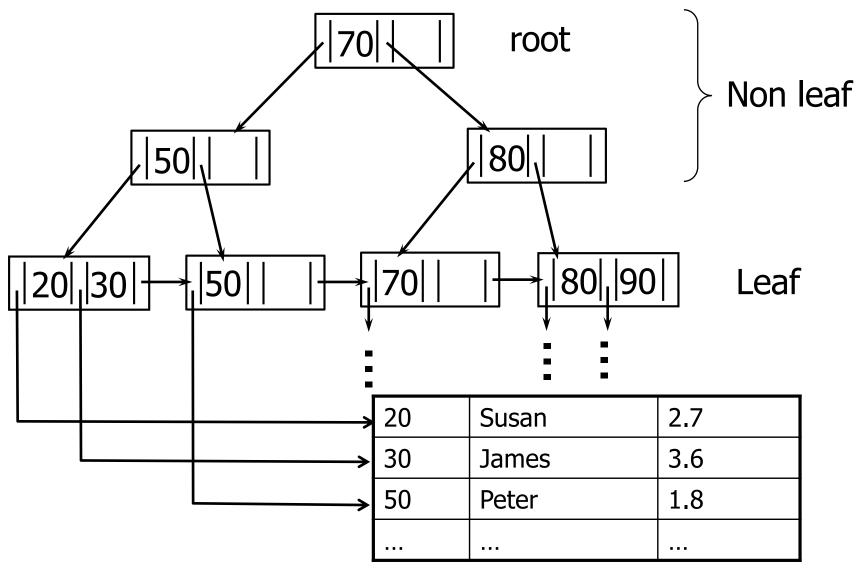
- Most popular index structure in RDBMS
- Advantage
 - Suitable for dynamic updates
 - Balanced
 - Minimum space usage guarantee
- Disadvantage
 - Non-sequential index blocks

B+ tree: generalizing B trees: e.g., n=3 in practice much larger



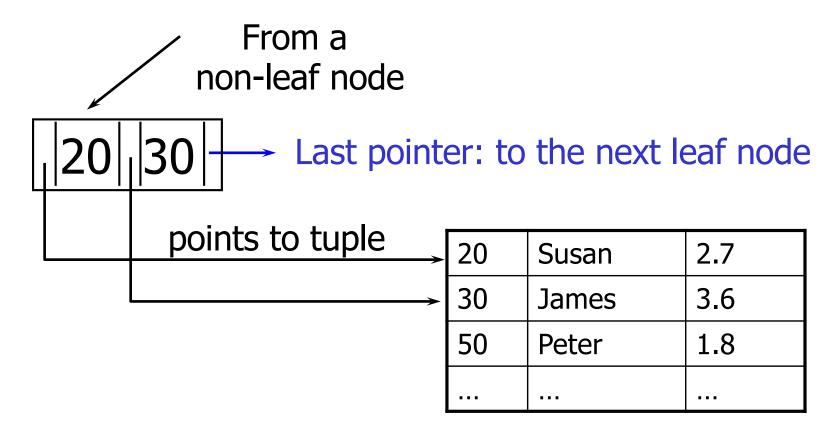
- Points to the nodes one-level below
 - No direct pointers to tuples
- At least half of the ptrs used (precisely, \[\ln/2 \])
 - except root, where at least 2 ptrs used

B+Tree Example (n=3)



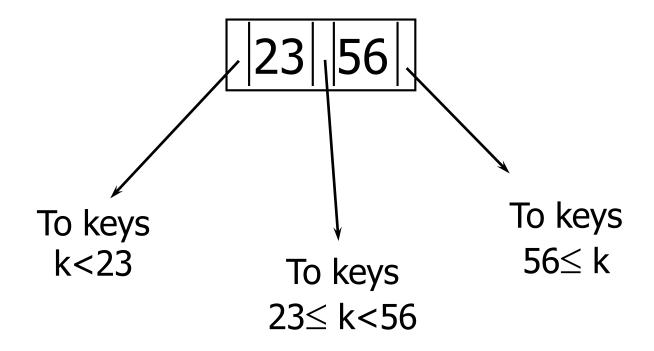
Balanced: All leaf nodes are at the same level

Sample Leaf Node (n=3)



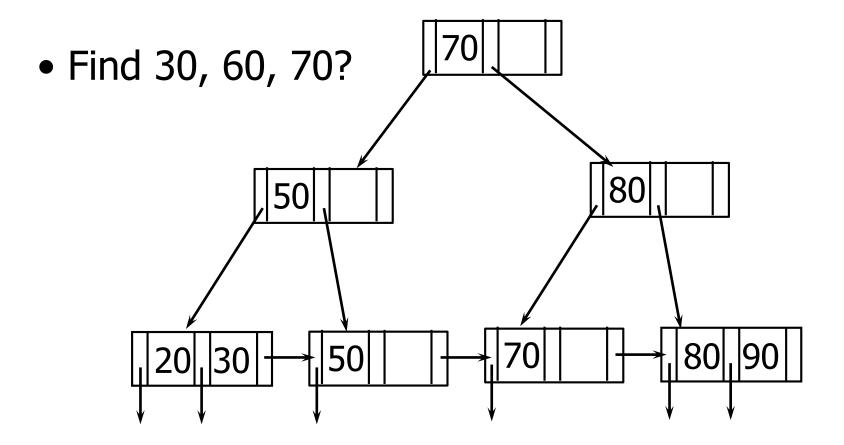
- n: max # of pointers in a node
- All pointers (except the last one) point to tuples
- At least half of the pointers are used.
 (more precisely, \((n+1)/2 \) pointers)

Sample Non-leaf Node (n=3)



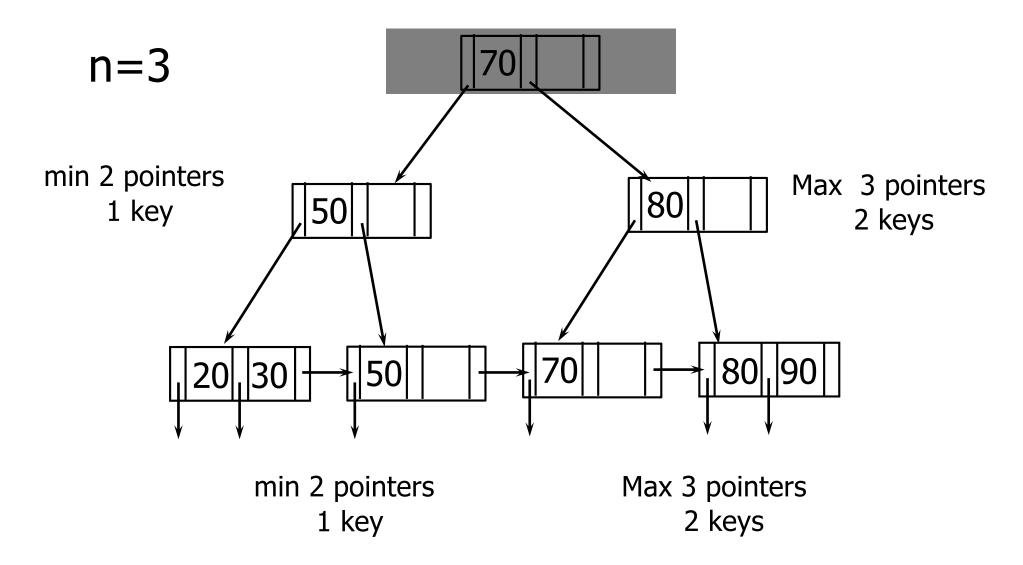
- Points to the nodes one-level below
 - No direct pointers to tuples
- At least half of the ptrs used (precisely, \[\ln/2 \])
 - except root, where at least 2 ptrs used

Search on B+tree



• Find a greater key and follow the link on the left (Algorithm: Figure 12.10 on textbook)

Nodes but the root are never too empty



Nodes are never too empty

Use at least

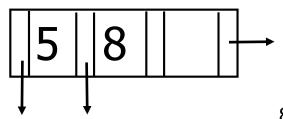
Non-leaf: \[\lambda / 2 \] pointers

Leaf: $\lceil (n+1)/2 \rceil$ pointers

 $\begin{array}{c|c}
 & \text{full node} \\
 & n=4 \\
\hline
 & Non-leaf
\end{array}$

min. node

Leaf



Number of Ptrs/Keys for B+tree

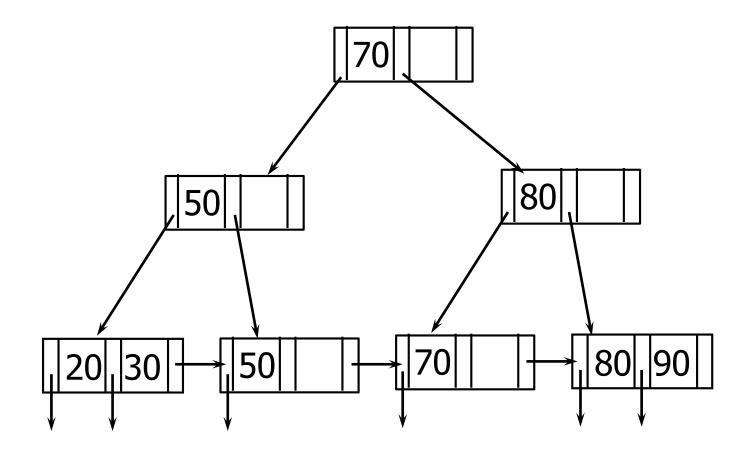
	Max Ptrs	Max keys	Min ptrs	Min keys
Non-leaf (non-root)	n	n-1	「n/2	「n/2 -1
Leaf (non-root)	n	n-1	「(n+1)/2 ☐	「(n-1)/2 ☐
Root	n	n-1	2	1

B+Tree Insertion

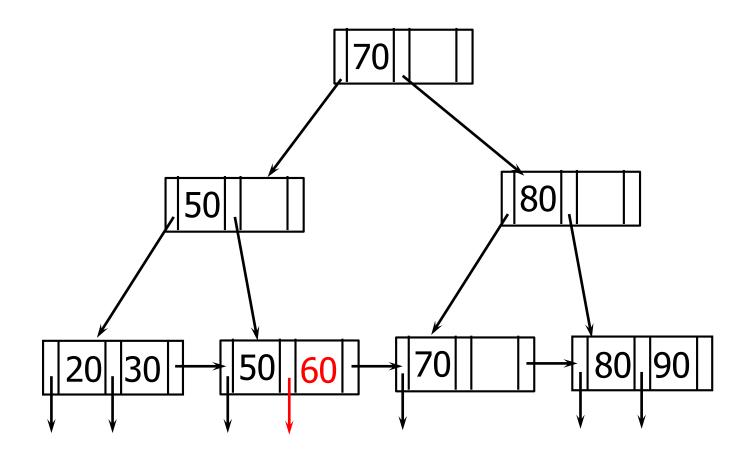
- (a) simple case (no overflow)
- (b) leaf overflow
- (c) non-leaf overflow
- (d) new root

(a) Simple case(no overflow)

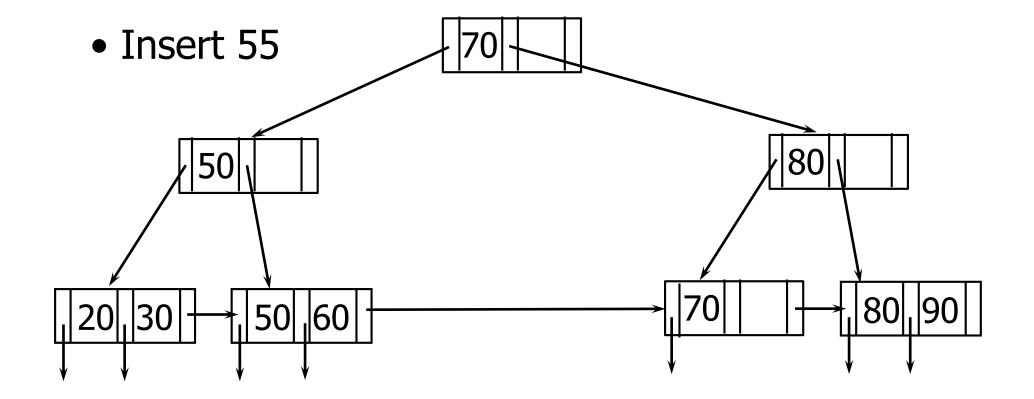
Insertion (Simple Case)



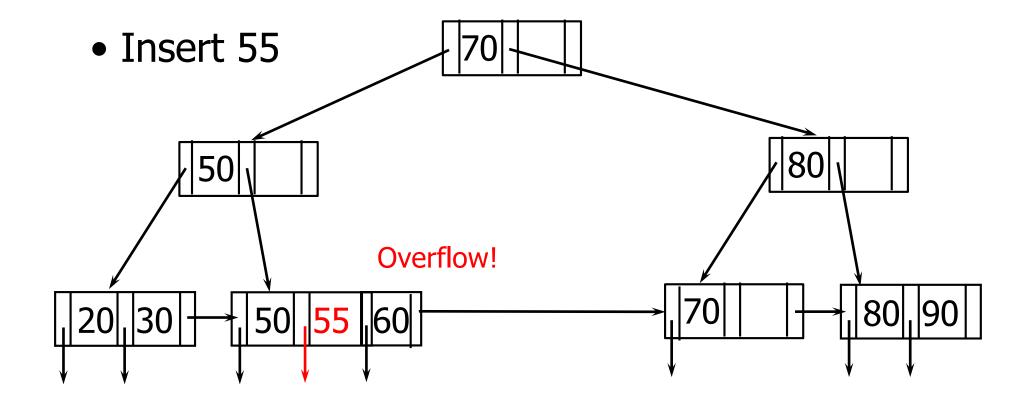
Insertion (Simple Case)



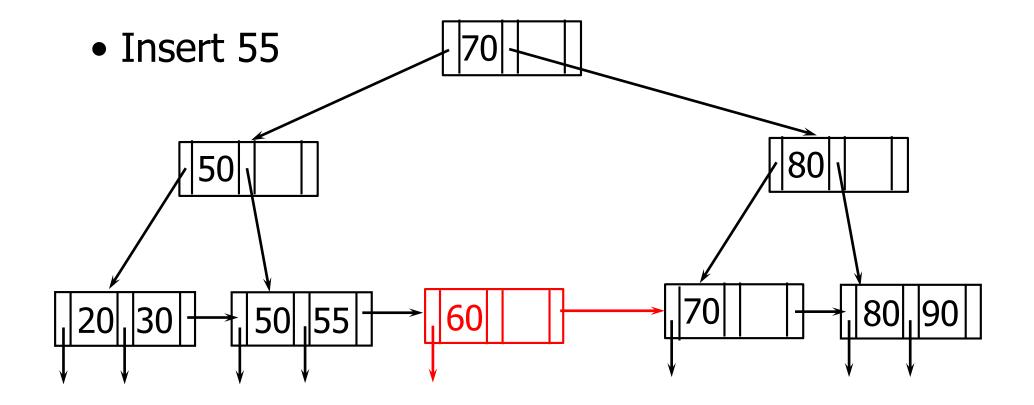
(b) Leaf overflow

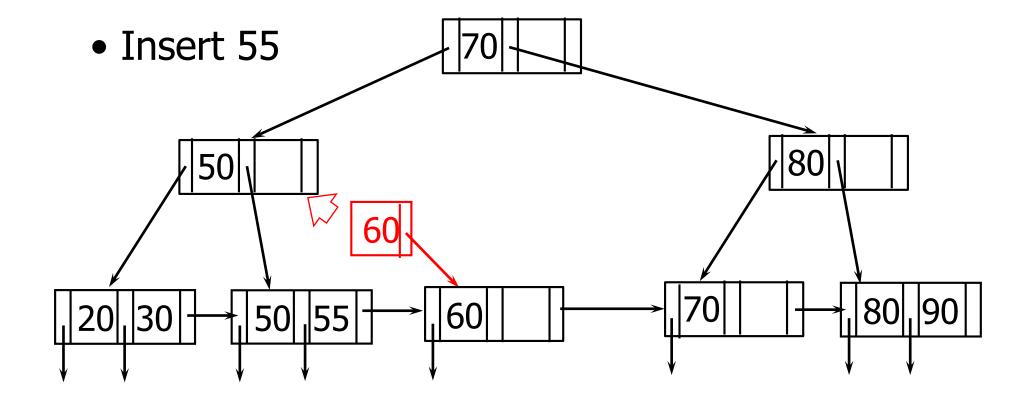


• No space to store 55

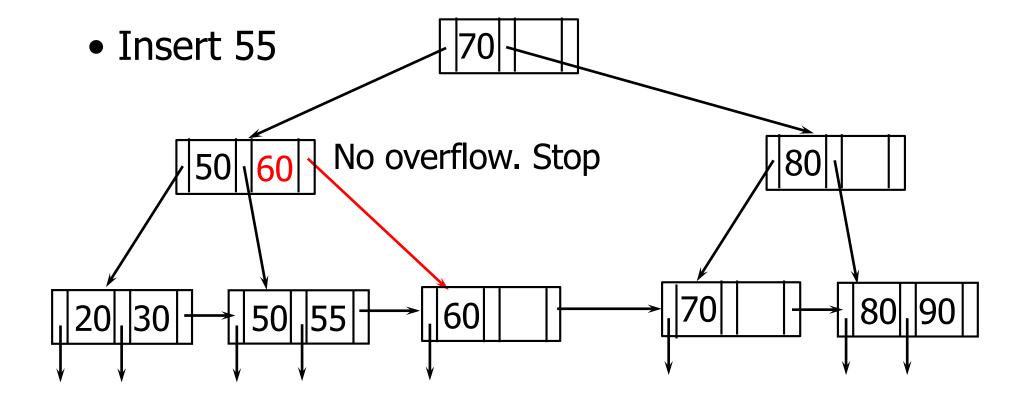


Split the leaf into two. Put the keys half and half





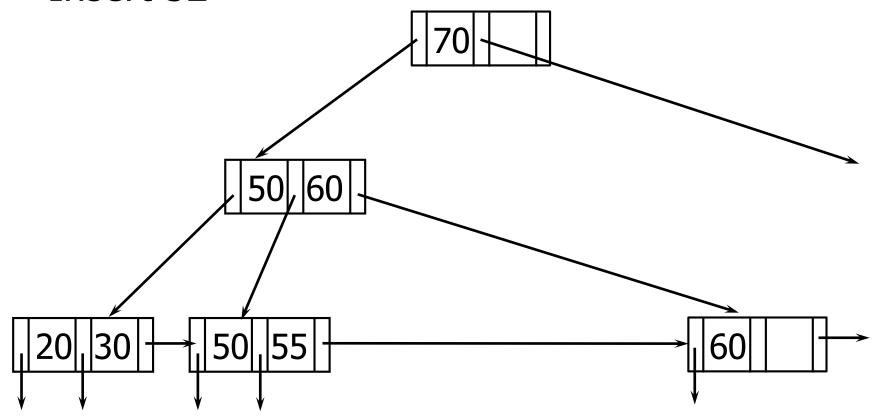
Copy the first key of the new node to parent



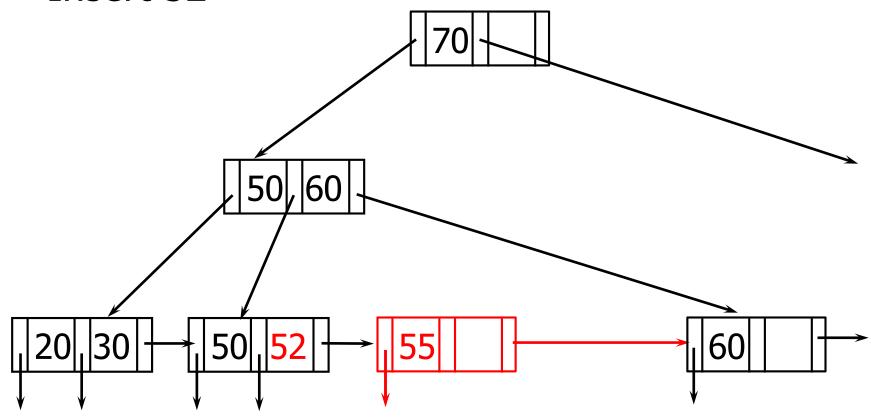
• Q: After split, leaf nodes always half full?

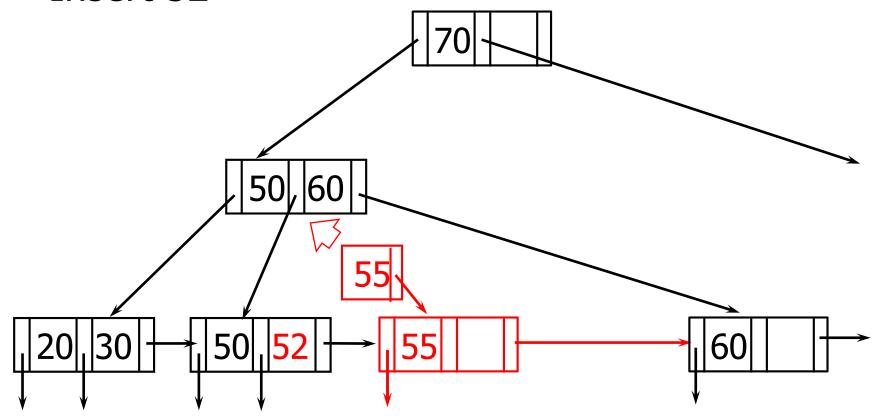
(c) Non-leaf overflow

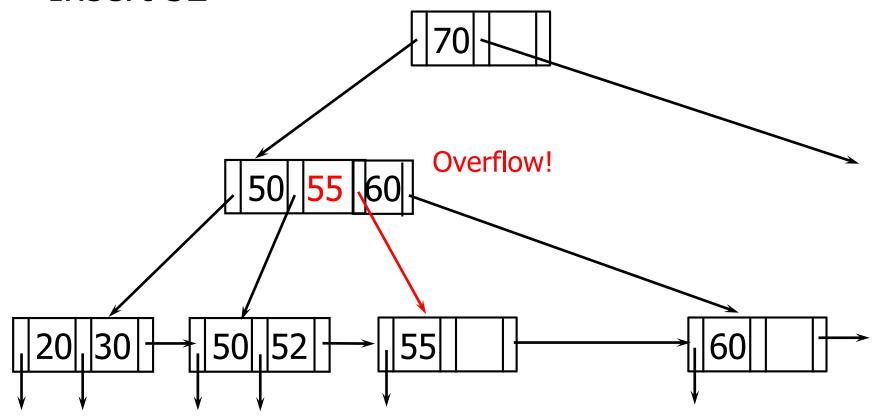
• Insert 52



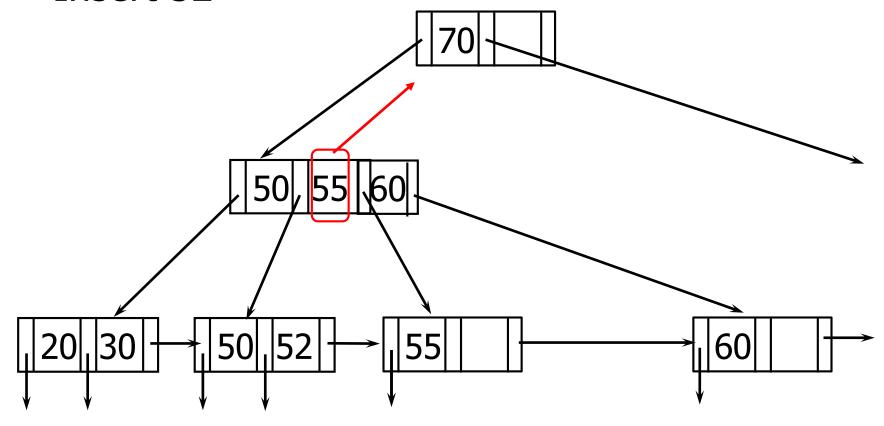
Leaf overflow. Split and copy the first key of the new node



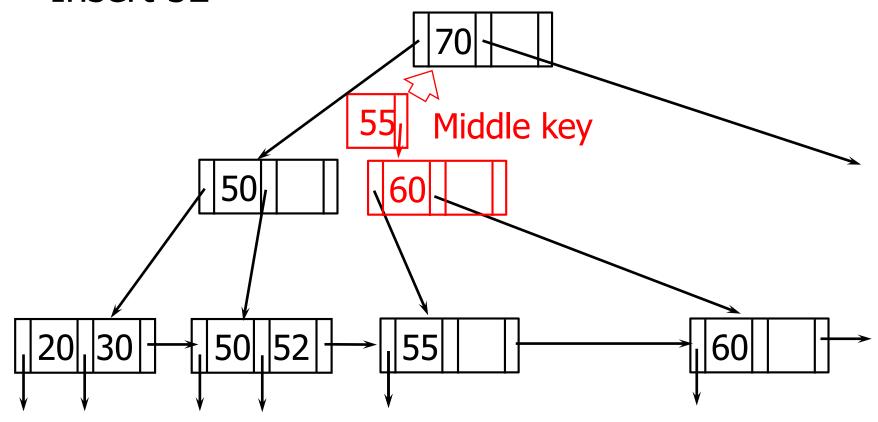


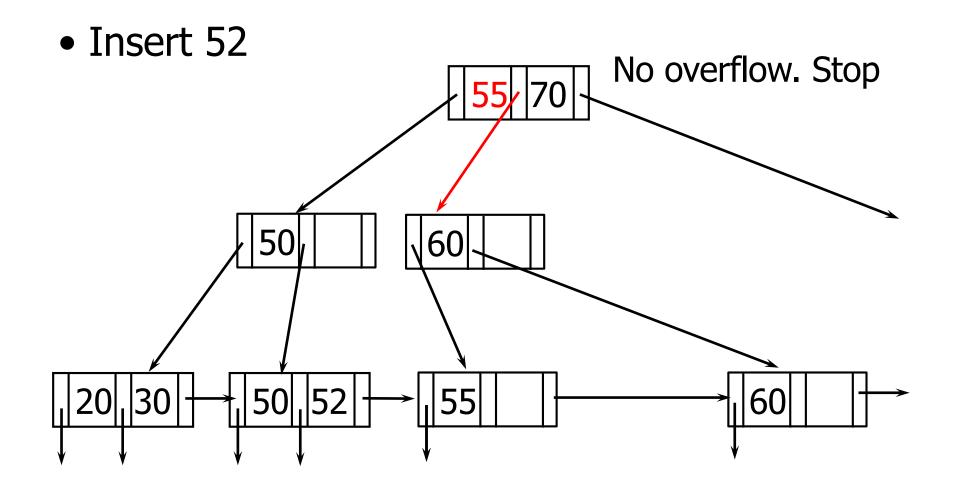


• Insert 52



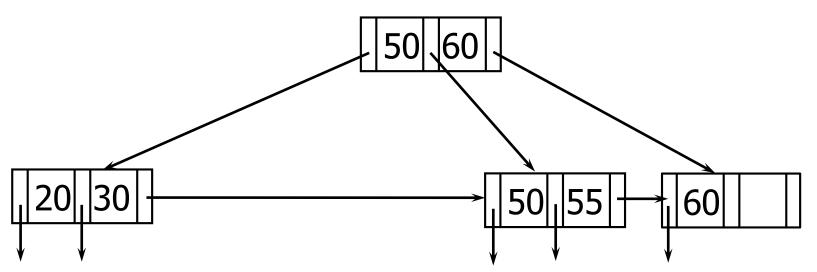
Split the node into two. <u>Move</u> up the key in the middle.

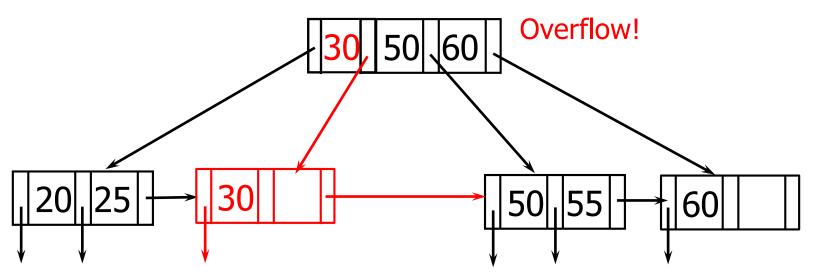


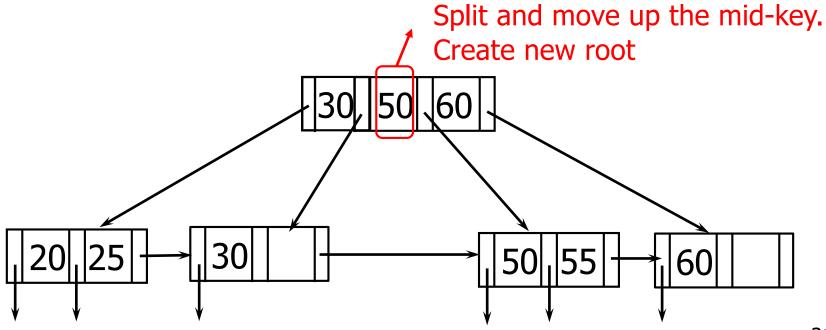


Q: After split, non-leaf at least half full?

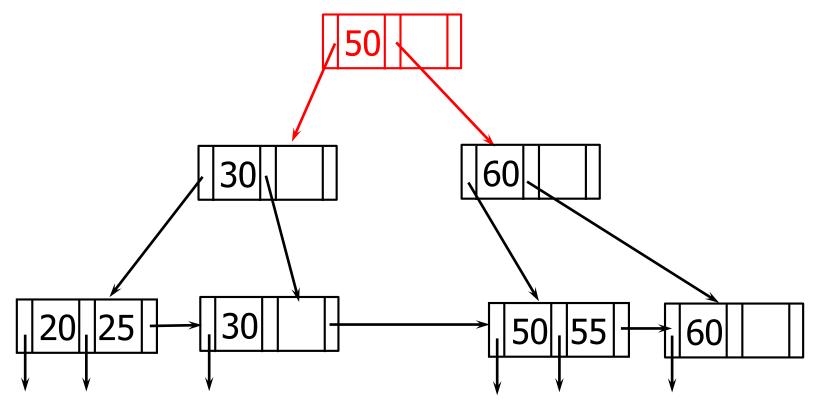
(d) New root







- Insert 25
- Q: At least 2 ptrs at root?



B+Tree Insertion

- Leaf node overflow
 - The first key of the new node is <u>copied</u> to the parent
- Non-leaf node overflow
 - The middle key is <u>moved</u> to the parent
- Detailed algorithm: see textbook

B+Tree Deletion

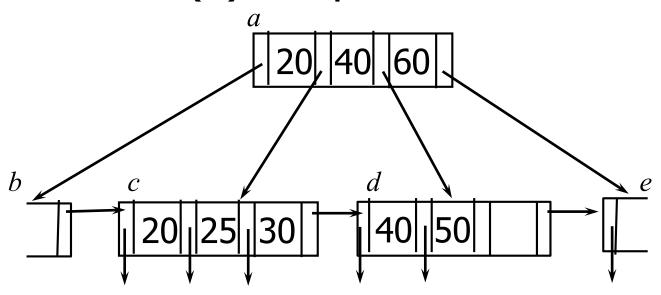
- (a) Simple case (no underflow)
- (b) Leaf node, coalesce with neighbor
- (c) Leaf node, redistribute with neighbor
- (d) Non-leaf node, coalesce with neighbor
- (e) Non-leaf node, redistribute with neighbor

In the examples, n = 4

- Underflow for non-leaf when fewer than $\lceil n/2 \rceil = 2$ ptrs
- Underflow for leaf when fewer than $\lceil (n+1)/2 \rceil = 3$ ptrs
- Nodes are labeled as a, b, c, d, ...

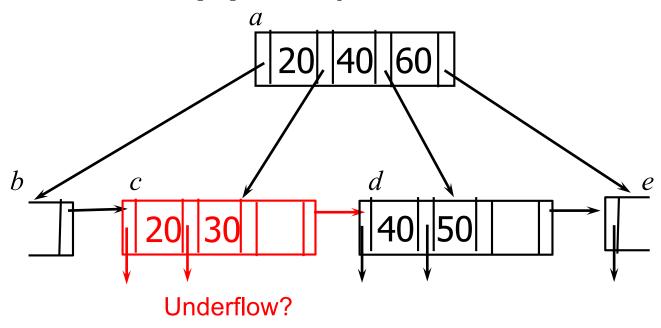
(a) Simple case(no underflow)

(a) Simple case



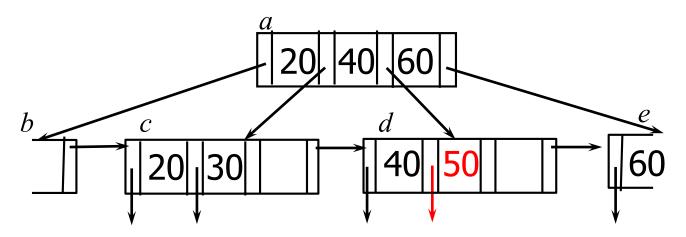
• Delete 25

(a) Simple case

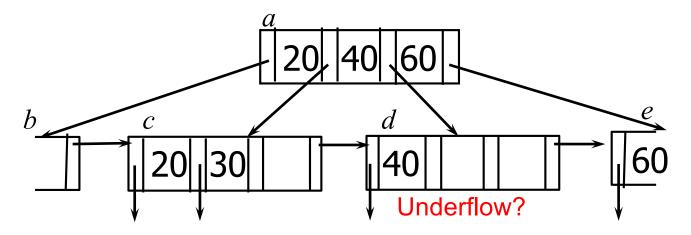


- Delete 25
 - Underflow? Min 3 ptrs. Currently 3 ptrs

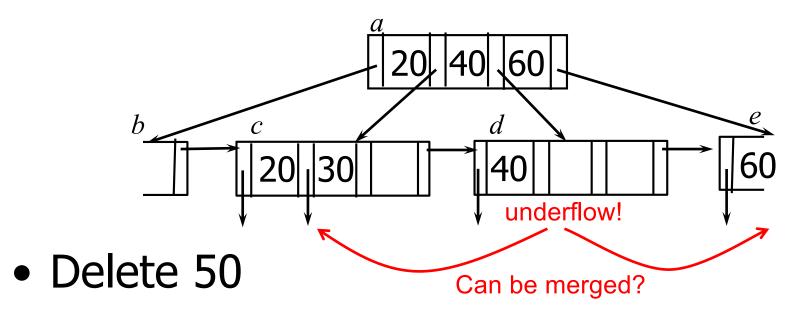
(b) Leaf node, coalesce with neighbor



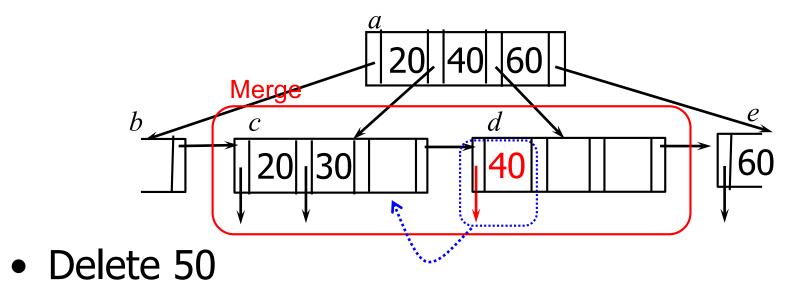
• Delete 50



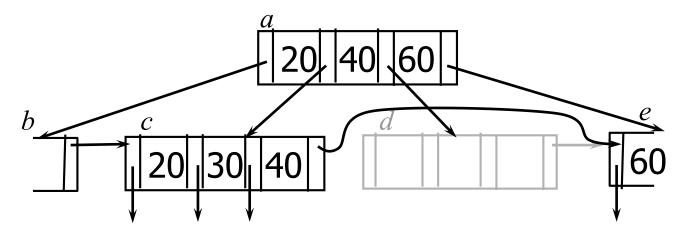
- Delete 50
 - Underflow? Min 3 ptrs, currently 2.



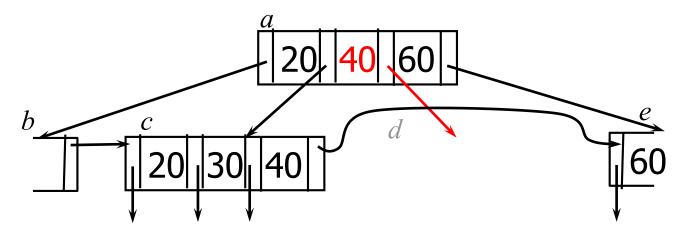
Try to merge with a sibling



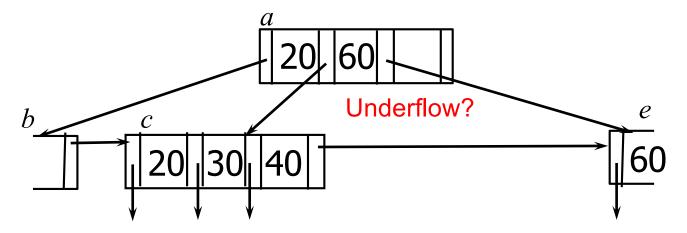
Merge c and d. Move everything on the right to the left.



- Delete 50
 - Once everything is moved, delete d

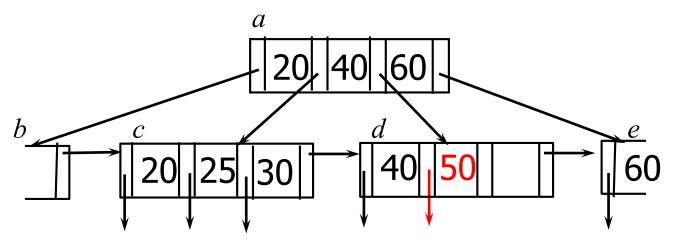


- Delete 50
 - After leaf node merge,
 - From its parent, <u>delete the pointer and key to the</u> deleted node

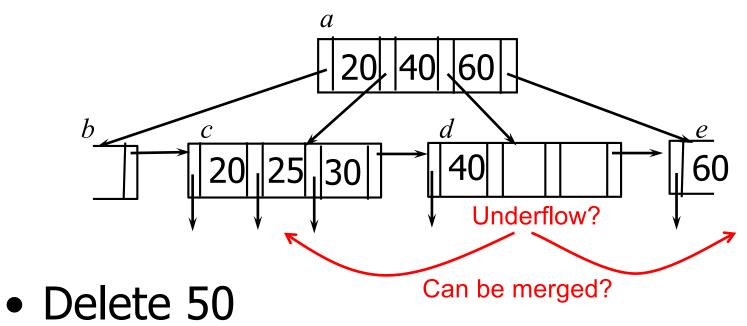


- Delete 50
 - Check underflow at a. Min 2 ptrs, currently 3

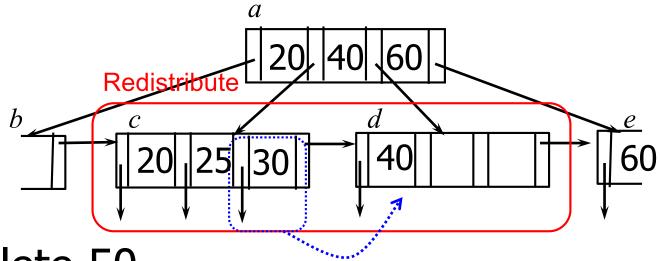
(c) Leaf node, redistribute with neighbor



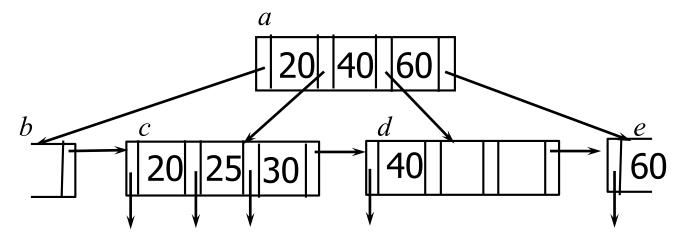
• Delete 50



- Underflow? Min 3 ptrs, currently 2
- Check if d can be merged with its sibling c
 or e
- If not, redistribute the keys in d with a sibling
 - Say, with *c*



- Delete 50
 - Redistribute c and d, so that nodes c and d
 are roughly "half full"
 - Move the key 30 and its tuple pointer to the d

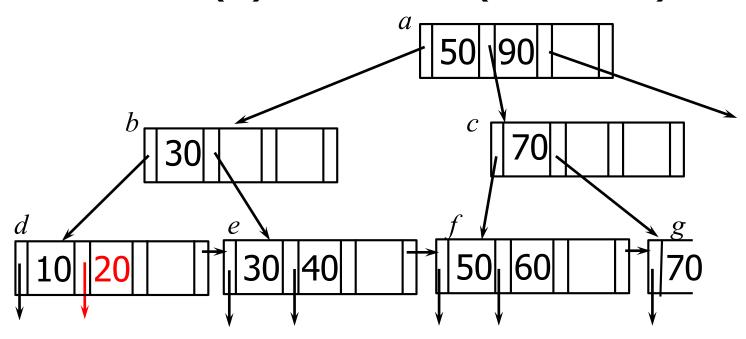


- Delete 50
 - Update the key in the parent

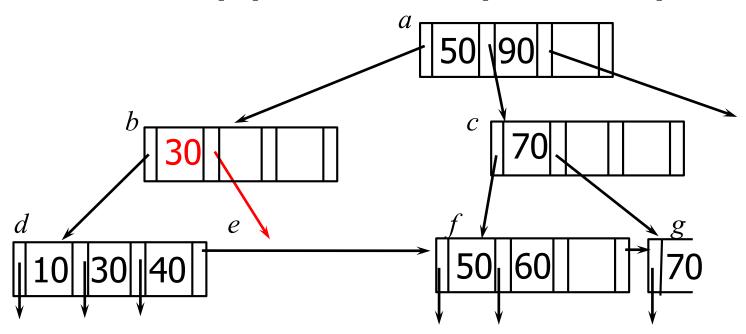
(c) Redistribute (leaf) 30 Underflow? 20 40 60 30 40 60

- Delete 50
 - No underflow at a. Done.

(d) Non-leaf node, coalesce with neighbor

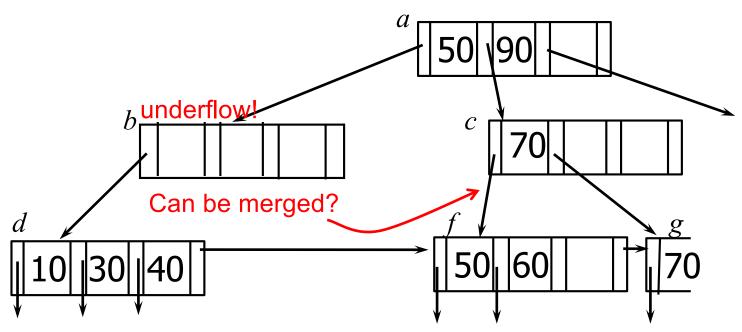


- Delete 20
 - Underflow! Merge *d* with *e*.
 - Move everything in the right to the left



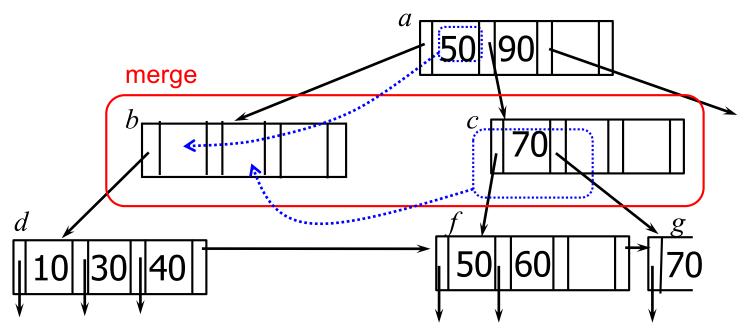
Delete 20

 From the parent node, delete pointer and key to the deleted node



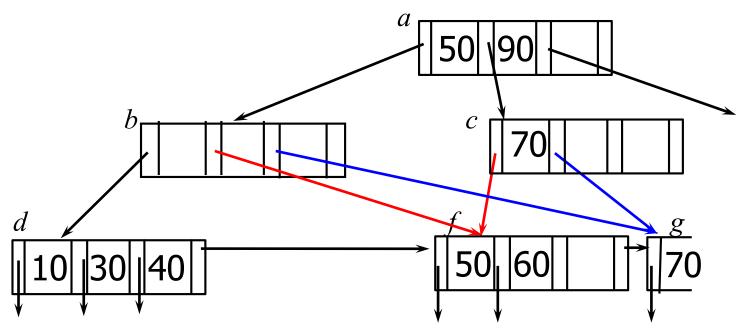
Delete 20

- Underflow at b? Min 2 ptrs, currently 1.
- Try to merge with its sibling.
 - Nodes b and c: 3 ptrs in total. Max 4 ptrs.
 - Merge b and c.



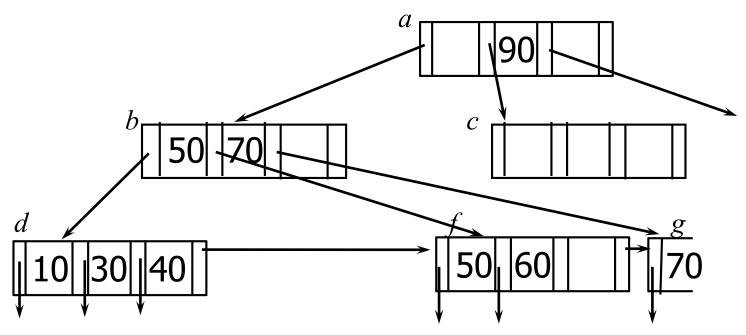
- Delete 20
 - Merge b and c
 - Pull down the mid-key 50 in the parent node
 - Move everything in the right node to the left.
- Very important: when we merge <u>non-leaf nodes</u>, we always pull down the mid-key in the parent and place it in the merged node.

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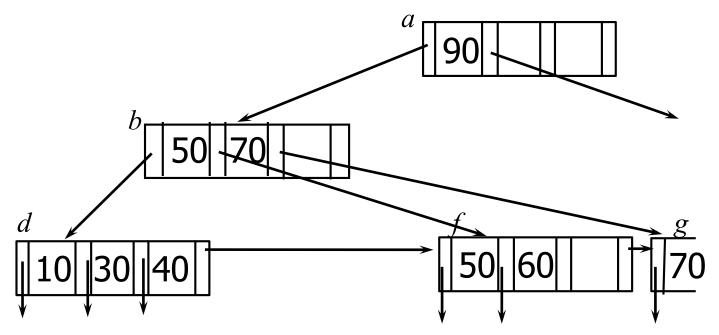


- Delete 20
 - Merge b and c
 - Pull down the mid-key 50 in the parent node
 - Move everything in the right node to the left.
- Very important: when we merge <u>non-leaf nodes</u>, we always pull down the mid-key in the parent and place it in the merged node.

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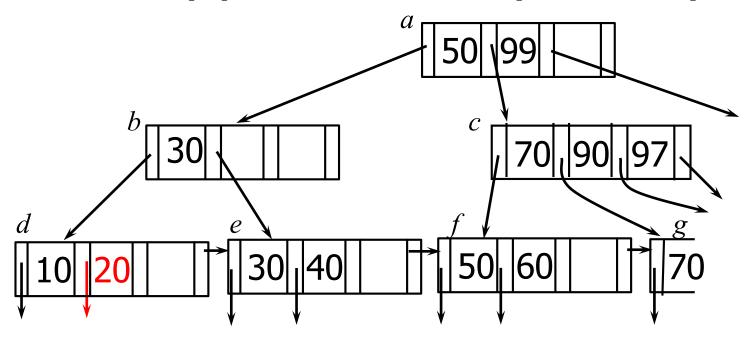


- Delete 20
 - Delete pointer to the merged node.

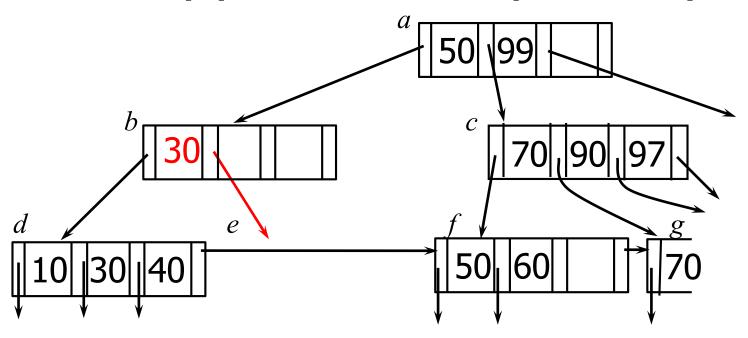


- Delete 20
 - Underflow at a? Min 2 ptrs. Currently 2. Done.

(e) Non-leaf node, redistribute with neighbor

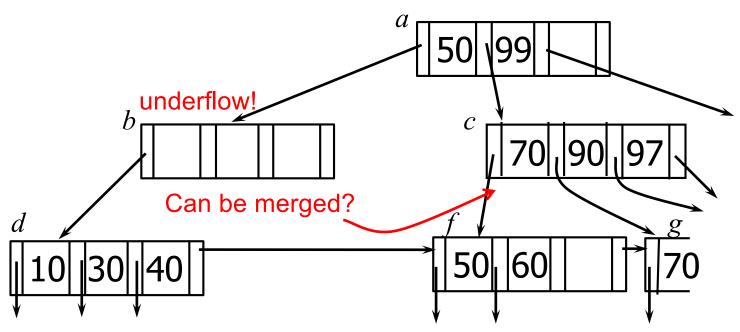


- Delete 20
 - Underflow! Merge *d* with *e*.



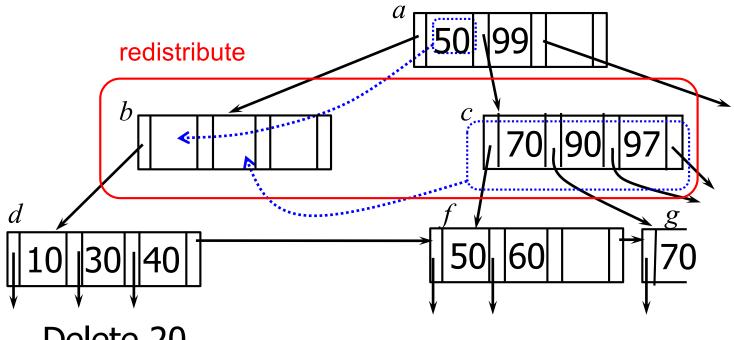
Delete 20

 After merge, remove the key and ptr to the deleted node from the parent



Delete 20

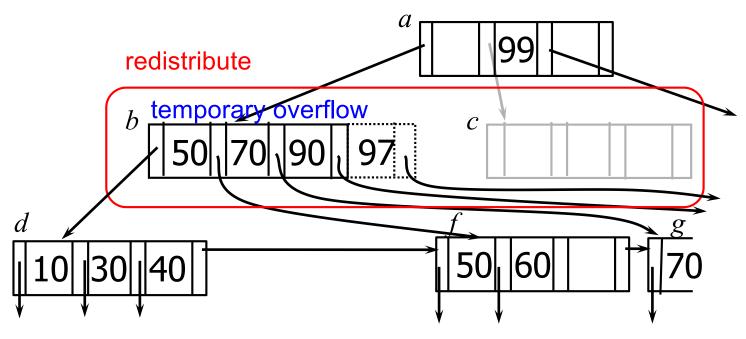
- Underflow at b? Min 2 ptrs, currently 1.
- Merge b with c? Max 4 ptrs, 5 ptrs in total.
- If cannot be merged, redistribute the keys with a sibling.
 - Redistribute b and c



Delete 20

Redistribution at a non-leaf node is done in two steps.

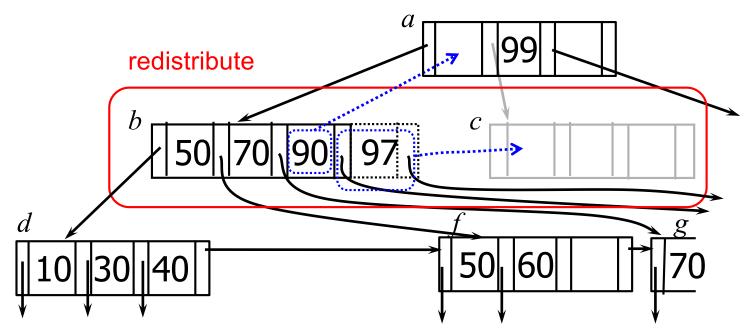
Step 1: Temporarily, make the left node b "overflow" by pulling down the mid-key and moving everything to the left.



Delete 20

Step 2: Apply the "overflow handling algorithm" (the same algorithm used for B+tree insertion) to the overflowed node

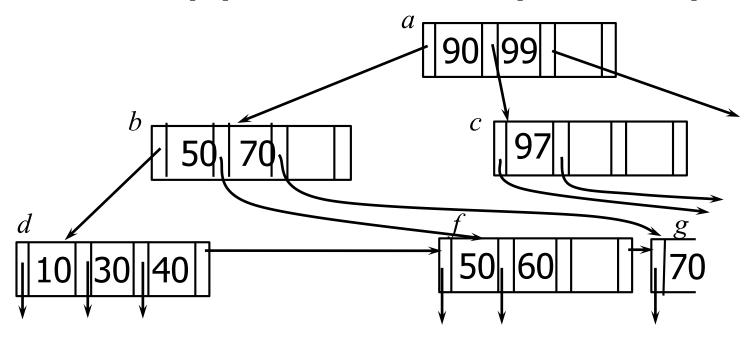
Detailed algorithm in the next slide



Delete 20

Step 2: "overflow handling algorithm"

- Pick the mid-key (say 90) in the node and move it to parent.
- Move everything to the right of 90 to the empty node c.



- Delete 20
 - Underflow at a? Min 2 ptrs, currently 3. Done

Important Points

• Remember:

- For <u>leaf node</u> merging, we <u>delete</u> the mid-key from the parent
- For <u>non-leaf node</u> merging/redistribution, we <u>pull</u> <u>down</u> the mid-key from their parent.

In practice

- Coalescing is often not implemented
 - Too hard and not worth it

Where does *n* come from?

- n determined by
 - Size of a node
 - Size of search key
 - Size of an index pointer
- Q: 1024B node, 10B key, 8B ptr → *n*?
- Computation: 8 bytes for final pointer. Then 1024-8=1016 bytes left for Key+pointer pair, each taking 18 bytes. Thus floor(1016/18)= 56. Thus n=57.
- Or use formulas

Summary on tree index

- Issues to consider
 - Sparse vs. dense
 - Primary (clustering) vs. secondary (non-clustering)
- Indexed sequential file (ISAM)
 - Simple algorithm. Sequential blocks
 - Not suitable for dynamic environment
- B+trees
 - Balanced, minimum space guarantee
 - Insertion, deletion algorithms

Index Creation in SQL

• CREATE INDEX <indexname>
ON (<attr>, <attr>,...)

Example

- CREATE INDEX stidx ON Student(sid)
 - Creates a B+tree on the attributes
 - Speeds up lookup on sid

Primary (Clustering) Index

- MySQL:
 - Primary key becomes the clustering index
- DB2:
 - CREATE INDEX idx ON Student(sid) CLUSTER
 - Tuples in the table are sequenced by sid
- Oracle: Index-Organized Table (IOT)
 - CREATE TABLE T (
 -) ORGANIZATION INDEX
 - B+tree on primary key
 - Tuples are stored at the leaf nodes of B+tree
- Periodic reorganization may still be necessary to improve range scan performance

Next topic

- Hash index
 - Static hashing
 - Extendible hashing

What is a Hash Table?

Hash Table

- Hash function
 - h(k): key \rightarrow integer [0...n]
 - e.g., h(`Susan') = 7
- Array for keys: T[0...n]
- Given a key k, store it in T[h(k)]

h(Susan) = 4 h(James) = 3h(Neil) = 1 01 Neil23 James4 Susan5

Overflow and Chaining

• Insert

$$h(a) = 1$$

$$h(b) = 2$$

$$h(c) = 1$$

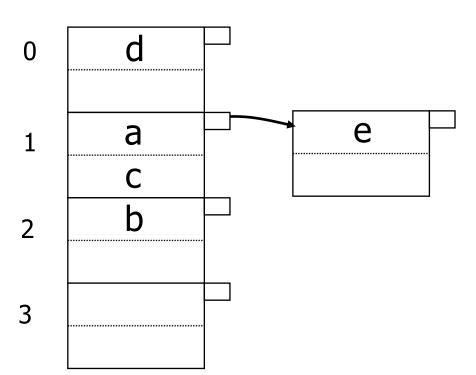
$$h(d) = 0$$

$$h(e) = 1$$

Delete

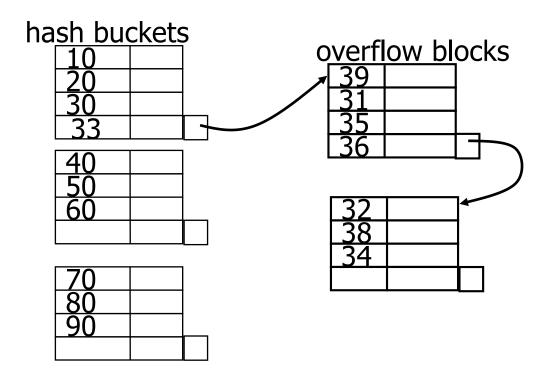
$$h(b) = 2$$

$$h(c) = 1$$



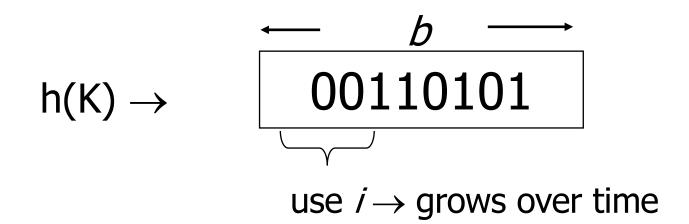
Major Problem of Static Hashing

- How to cope with growth?
 - Data tends to grow in size
 - Overflow blocks unavoidable



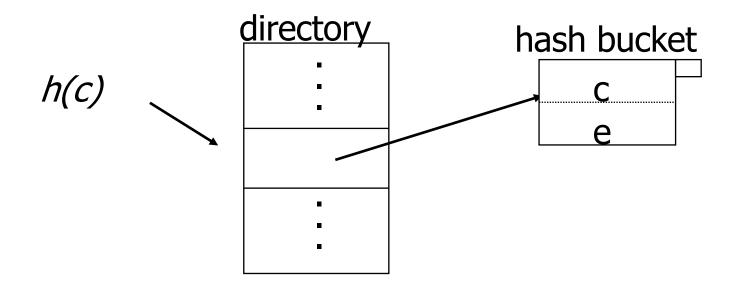
Extendible Hashing (two ideas)

(a) Use i of b bits output by hash function

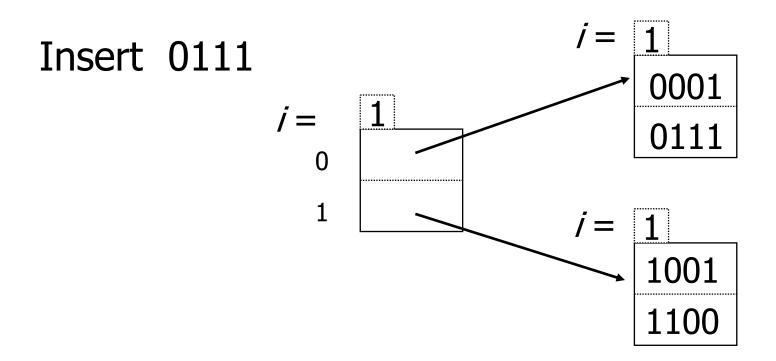


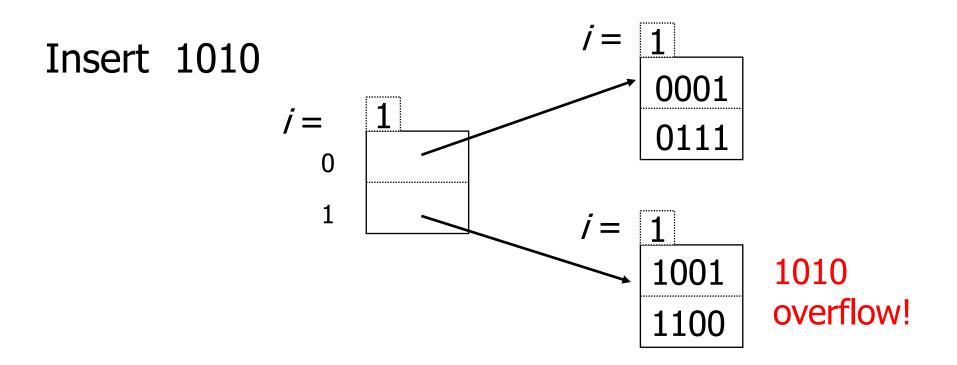
Extendible Hashing (two ideas)

(b) Use directory that maintains pointers to hash buckets (indirection)

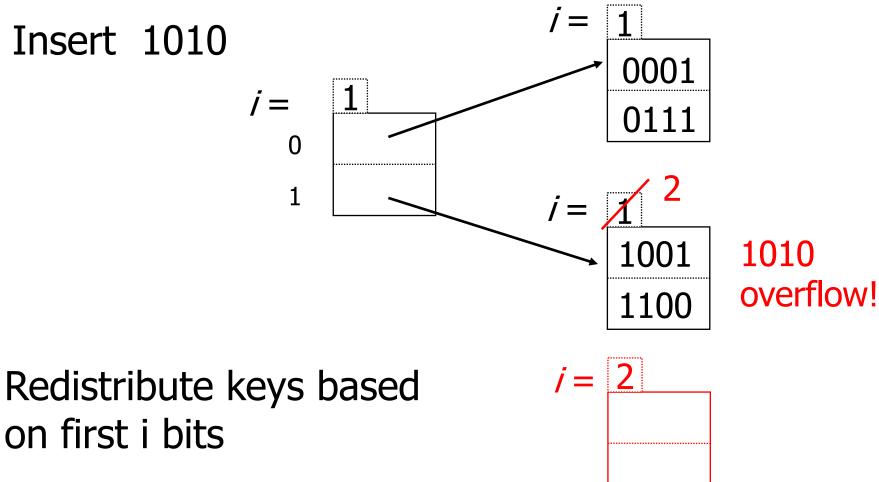


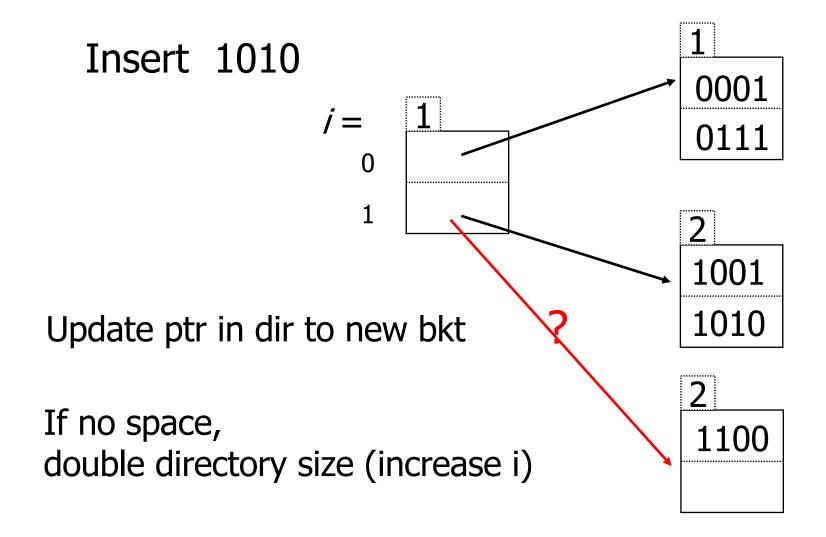
h(k) is 4 bits; 2 keys/bucket

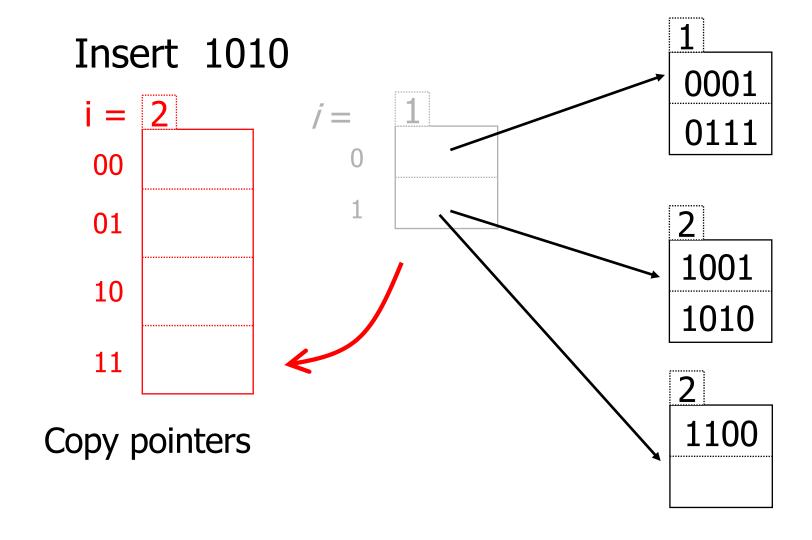


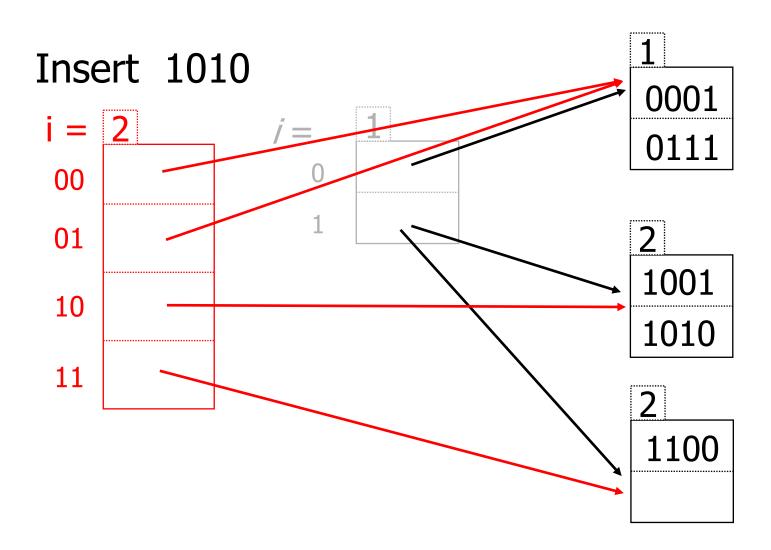


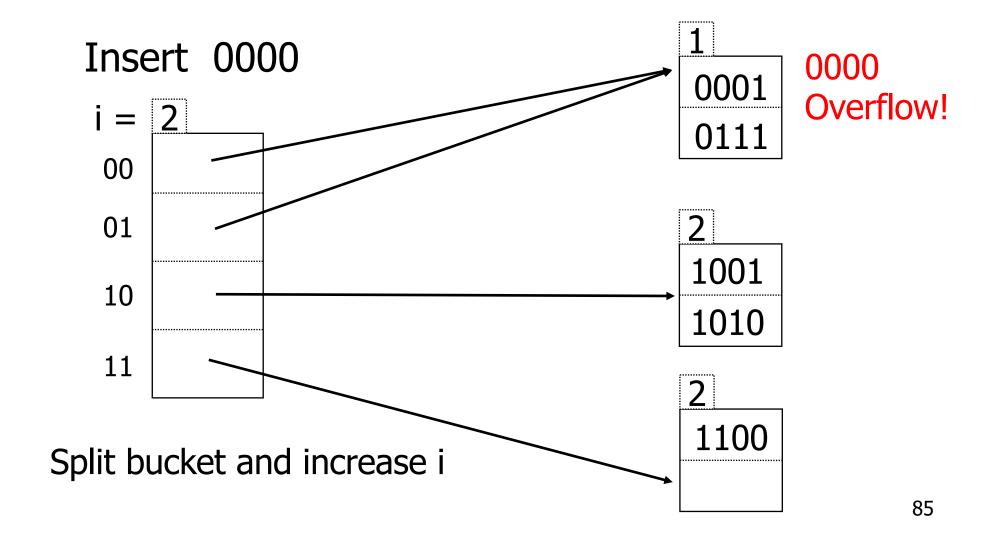
Increase i of the bucket. Split it.

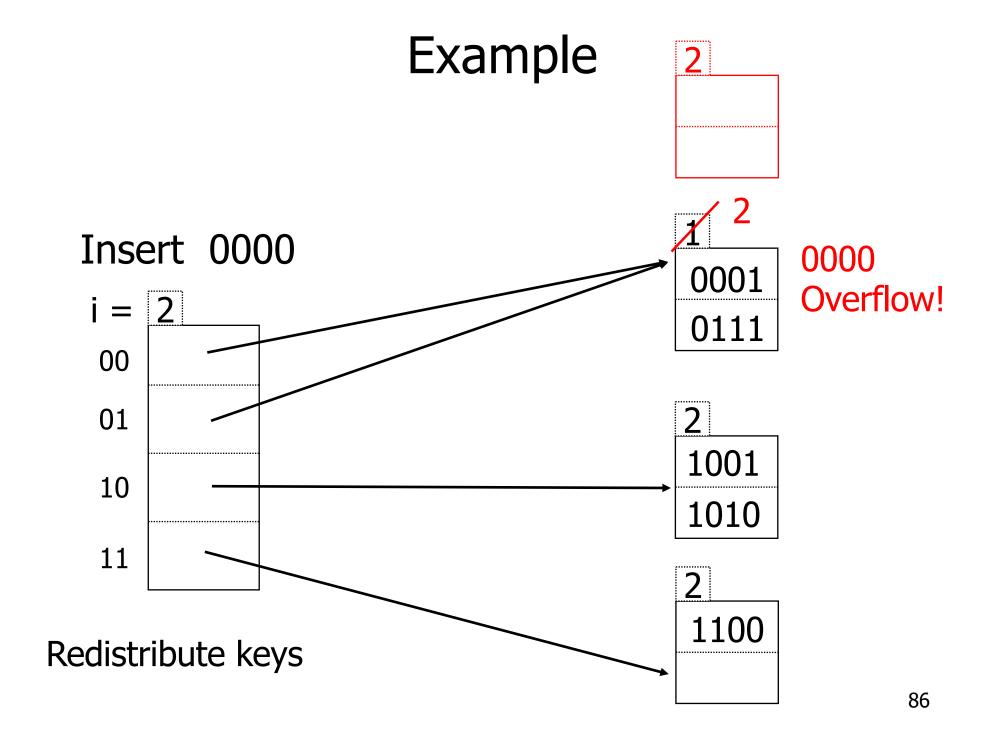


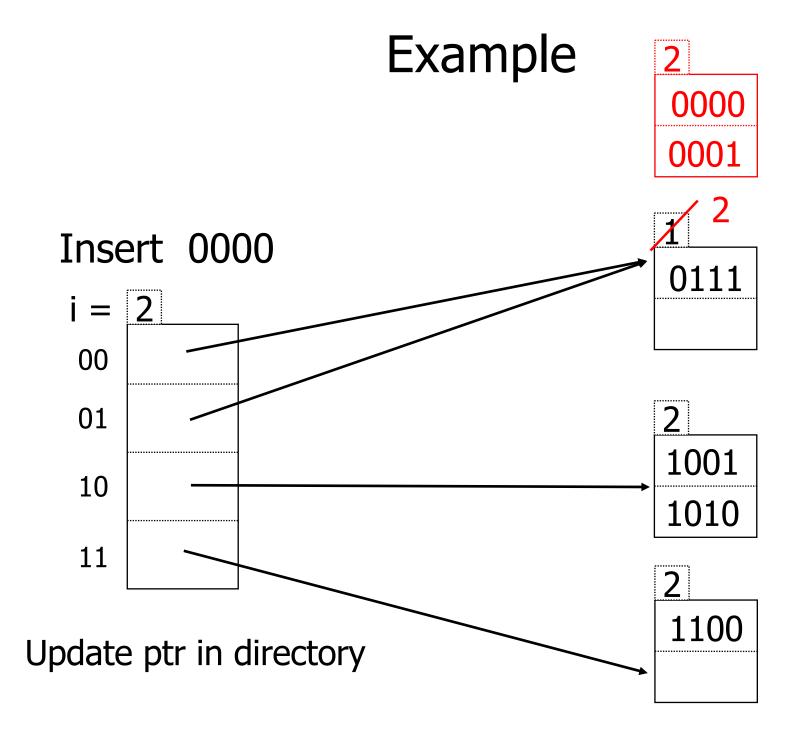


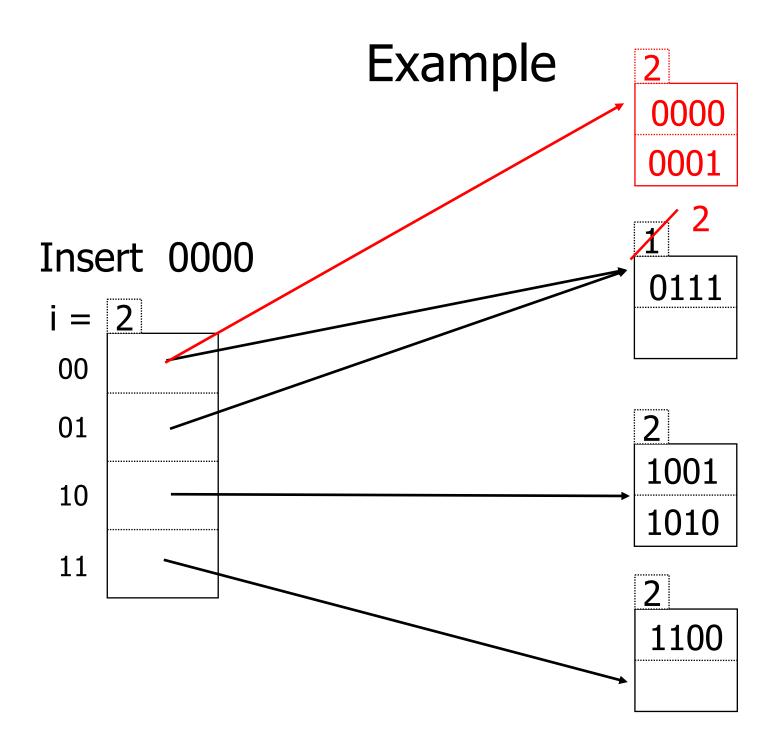


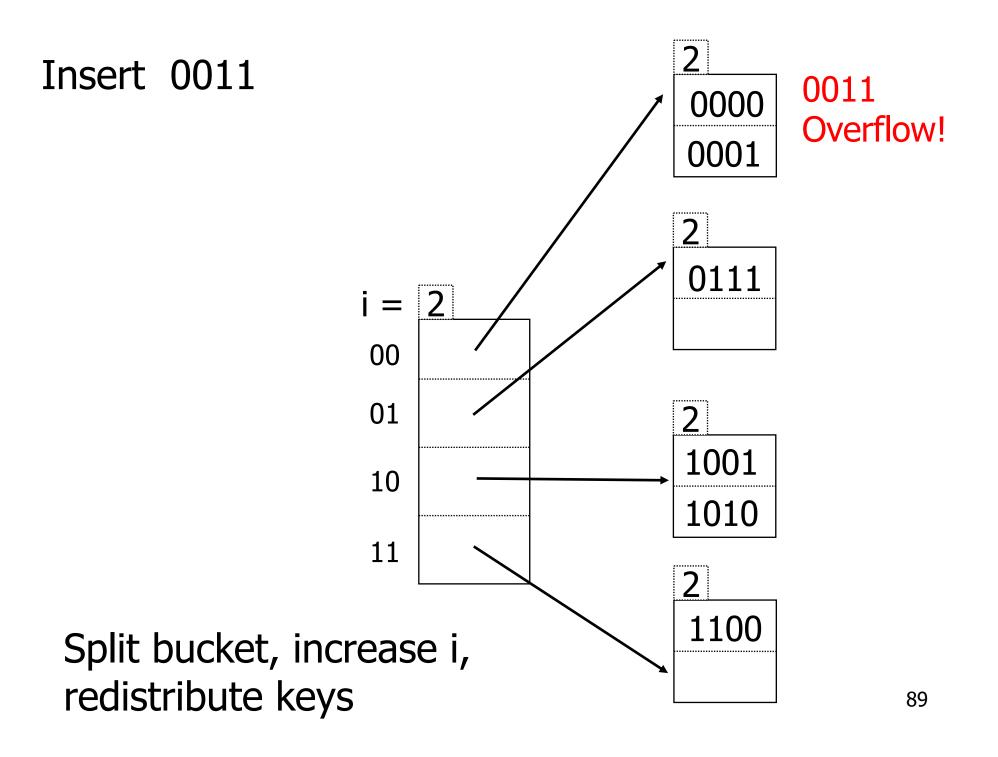




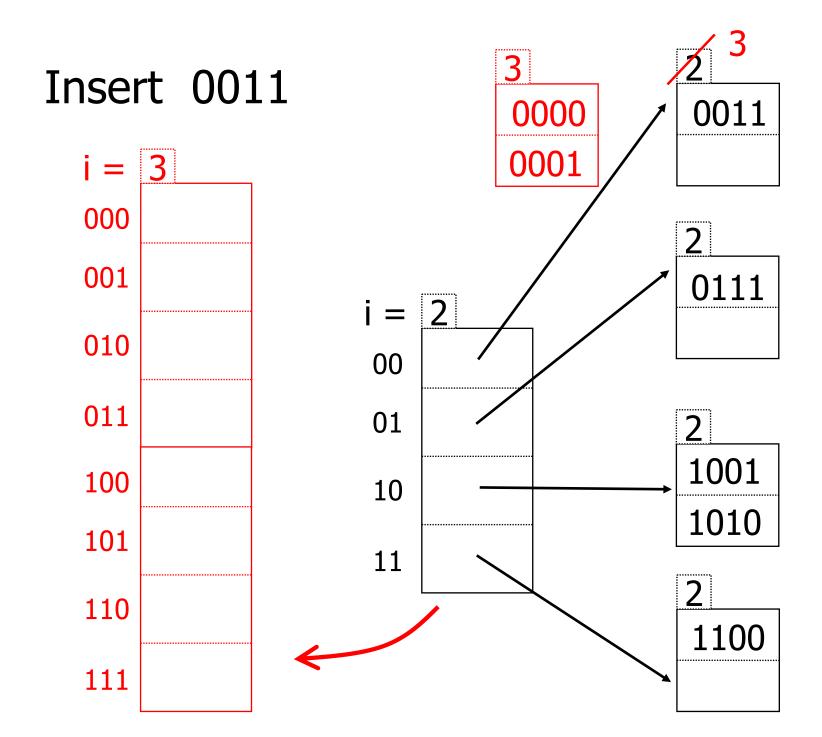


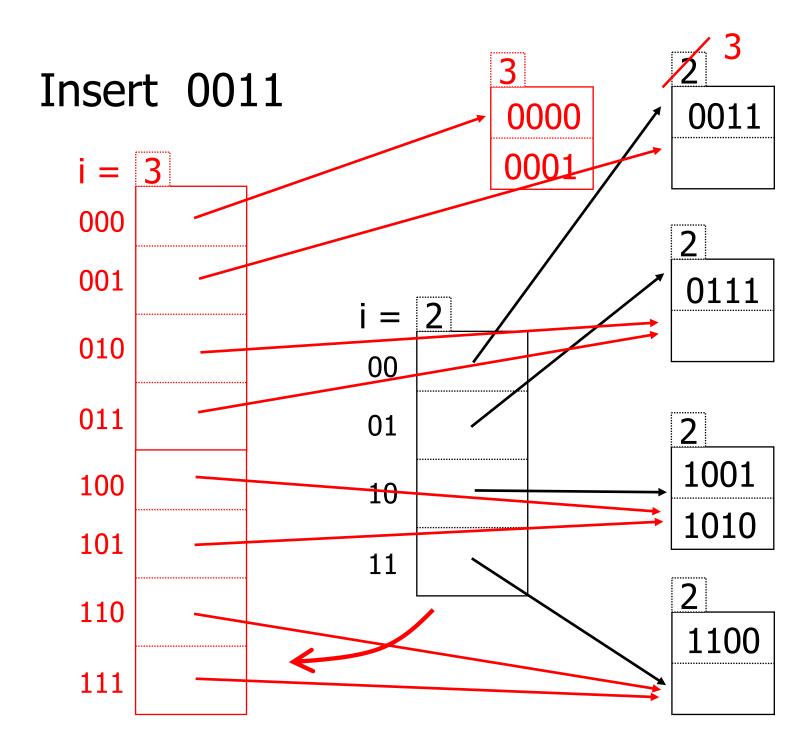






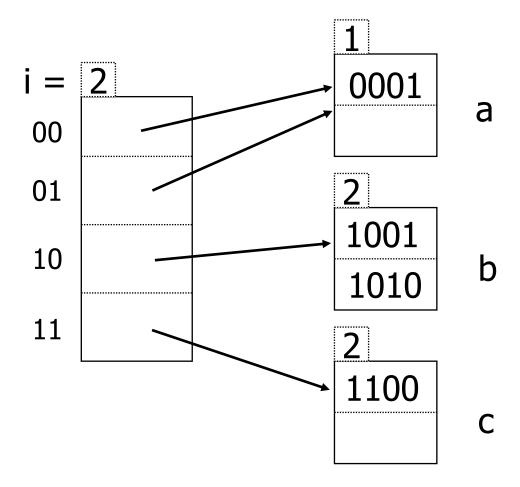
Insert 0011 i = 2 Update ptr in dir If no space, double directory

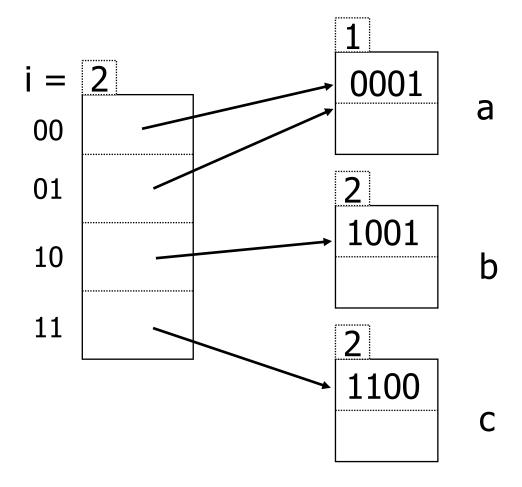




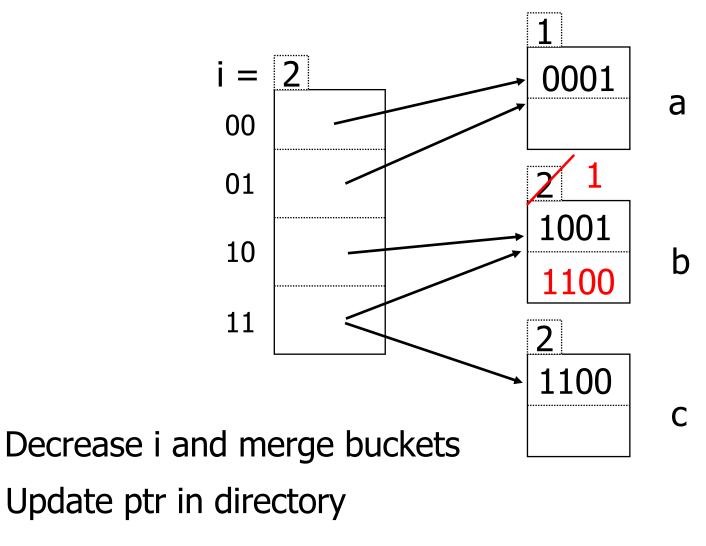
Extendible Hashing: Deletion

- Two options
 - a) No merging of buckets
 - b) Merge buckets and shrink directory if possible

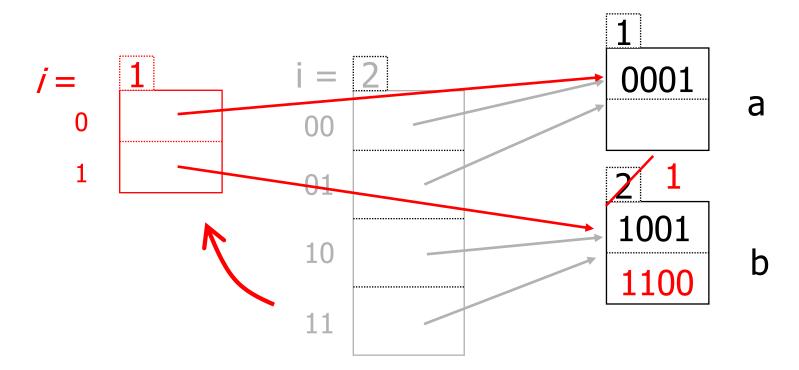




• Can we merge a and b? b and c?



Q: Can we shrink directory?



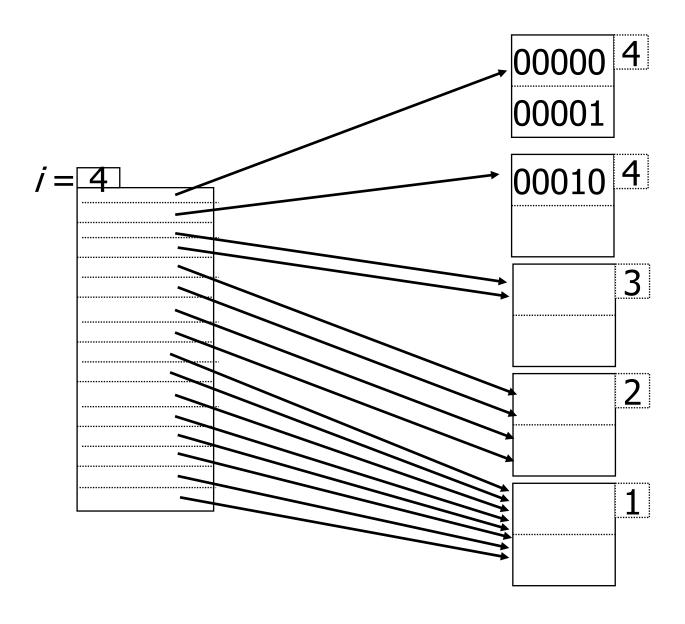
Bucket Merge Condition

- Bucket merge condition
 - Bucket i's are the same
 - First (i-1) bits of the hash key are the same
- Directory shrink condition
 - All bucket i's are smaller than the directory i

Questions on Extendible Hashing

 Can we provide minimum space guarantee?

Space Waste



Hash index summary

- Static hashing
 - Overflow and chaining
- Extendible hashing
 - Can handle growing files
 - No periodic reorganizations
 - Indirection
 - Up to 2 disk accesses to access a key
 - Directory doubles in size
 - Not too bad if the data is not too large

Question on B+tree

• SELECT * FROM Student 70 WHERE sid > 60? 50 80 80 50 60

Hashing vs. Tree

Can an extendible-hash index support?

```
SELECT *
FROM R
WHERE R.A > 5
```

 Which one is better, B+tree or Extendible hashing?

```
SELECT *
FROM R
WHERE R.A = 5
```