

Remoción de anomalías

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0.2 PERCEPCION COMPUTACIONAL

0.3 GRUPO 9

0.3.1 Anomalia: Sal y pimienta (generado)

Se utilizaran dos imagenes a color a las que se les generara artificailmente una anomalia aleatoria de puntos negros y blancos, despues se utilizata una tecnica de HIstograma para recuperar en medida de lo posigle la imagen original.

Este proyecot incluye un archivo requiremets.txt y un README relacionados con las dependencias y la ejecucion del documento

```
[1]: # python librearies
from random import randrange, choice
# External libraries
from PIL import Image
from matplotlib import image
from matplotlib import pyplot
from numpy import asarray, array, copy, mean, isnan, linalg

[2]: image_easy_colors = Image.open('gato_blanco.jpeg', mode='r', formats=['jpeg'])
image_easy_array = asarray(image_easy_colors)
image_grey_cat = Image.open('gato_gris.jpeg')
image_grey_cat_array = asarray(image_grey_cat)
print(image_easy_colors.mode)
image_easy_colors
```

RGB

[2]:



```
[3]: print(image_grey_cat.mode)  
image_grey_cat
```

RGB

[3]:



- 0.3.2 Antes de agregar el ruido a la imagen es necesario mapear la imagen en un vector representativo a la imagen
- 0.3.3 Las imagenes estan seleccionadas en formato jpeg RGB, el trabajo con png y la libreria de Pillow para retornar las imagenes no funciono correctamente
- 0.3.4 El formato RGB mapea cada pizel en un grupo de 3 valores, Rojo, Verde y Azul de 0 a 255 en cada uno de ellos.
- 0.3.5 Un pixel negro se representa como [0, 0, 0] y un pixel blanco con [255, 255, 255], conforme al modelo RGB (sistema de color aditivo)

0.4 Creando la anomalia sal y pimienta

```
[4]: def random_tuple(range_top_x, range_top_y):
    _x = randrange(range_top_x)
    _y = randrange(range_top_y)
    return (_x, _y)

def add_salt_and_pepper(image_array, percentage_of_anomaly:int =10):
    black_pixel = array([0,0,0])
    white_pixel = array([255, 255, 255])
    salt_and_paper_arr = [black_pixel, white_pixel]
    cols = len(image_array)
    rows = len(image_array[0])
    num_anomalous_pixels = int((cols * rows) * (percentage_of_anomaly/100))
    position_of_anomalies = [random_tuple(cols, rows) for i in
    ↪range(num_anomalous_pixels)]
    _image_array = copy(image_array)
    for position in position_of_anomalies:
        _image_array[position[0], position[1]] = choice(salt_and_paper_arr)
    return _image_array
anomalous_image = add_salt_and_pepper(image_grey_cat_array)
```

```
[5]: _ = Image.fromarray(anomalous_image)
print(anomalous_image.shape)
-
```

(168, 300, 3)

[5]:



0.4.1 Ahora se extraen todos los vecinos de cada pixel

```
[6]: def pos_eval(position, border_row, border_col):
    is_valid = True
    if position[0] < 0 or position[1] < 0:
        is_valid = False
        return is_valid
    if position[0] >= border_row or position[1] >= border_col:
        is_valid = False
    return is_valid

def mean_from_points(points:list, index:int):
    values = [value[index] for value in points]
    return mean(values)

#fix by average of pixels around right, left, top, bottom, right-top, ↵
↵right-bottom, left-right, left-bottom
def pixel_points_for_mean(image_array, row, col, border_row, border_col):
    pixel = image_array[row, col]
    pixels_to_average = []
    # Movements
    row_down = row - 1
    row_up = row + 1
    col_left = col - 1
    col_right = col + 1
    # positions to evaluate
    right_pos = (row, col_right)
    left_pos = (row, col_left)
    top_pos = (row_up, col)
    bottom_pos = (row_down, col)
    right_top_pos = (row_up, col_right)
```

```

right_button_pos = (row_down, col_right)
left_top_pos = (row_up, col_left)
left_button_pos = (row_down, col_left)
possitions = [
    right_pos,
    left_pos,
    top_pos,
    button_pos,
    right_top_pos,
    right_button_pos,
    left_top_pos,
    left_button_pos
]
valid_possitions = []
for position in possitions:
    if pos_eval(position, border_row, border_col):
        valid_possitions.append(position)
return valid_possitions

```

```

[7]: def image_neighbours(image_array):
    neighbords = {}
    border_row = len(image_array)-1
    border_col = len(image_array[0])-1
    print(f"border_row: {border_row}")
    print(f"border_col: {border_col}")
    for row in range(border_row):
        for col in range(border_col):
            neighbords.update({(row,col): pixel_points_for_mean(image_array,
↪row, col, border_row, border_col)})
    return neighbords
neighbords = image_neighbours(anomalous_image)
# neighbords
print(neighbords[(166, 298)])

```

```

border_row: 167
border_col: 299
[(166, 297), (165, 298), (165, 297)]

```

0.4.2 Ahora que los vecinos estan definidos para cada pixel se va a evaluar el el mean de cada valor de r, g y b en cada posicion

```

[8]: def get_pixels_by_neighbords(neighbords, anomalous_image):
    neighbords_pixels_dict = {}
    for position in neighbords.keys():
        list_of_neighbords = neighbords[position]
        neighbords_pixels = []

```

```

        for neighbord_possition in list_of_neighbords:

            try:
                pixel=anomalous_image[neighbord_possition[0],
↪neighbord_possition[1]]
                neighbords_pixels.append(pixel)
            except:
                pass
            neighbords_pixels_dict.update({position: neighbords_pixels})
        return neighbords_pixels_dict

def get_mean_for_neighbords(pixels_by_neighbords:dict, anomalous_image):
    average_values = {}
    rgb_mean = {
        'r': 0,
        'g': 0,
        'b': 0
    }
    for possition in pixels_by_neighbords.keys():
        if possition in neighbords:
            pixel_neighbords = neighbords[possition]
            if pixel_neighbords:
                this_rgb_mean = rgb_mean.copy()
                this_rgb_mean['r'] =
↪mean_from_points(pixels_by_neighbords[possition], 0)
                this_rgb_mean['g'] =
↪mean_from_points(pixels_by_neighbords[possition], 1)
                this_rgb_mean['b'] =
↪mean_from_points(pixels_by_neighbords[possition], 2)
                average_values.update({position: this_rgb_mean})
    return average_values

```

```

[9]: pixels_by_neighbords = get_pixels_by_neighbords(neighbords, anomalous_image)
    print(pixels_by_neighbords[(165, 297)])

```

```

[array([30, 25, 19], dtype=uint8), array([20, 15, 9], dtype=uint8), array([41,
36, 30], dtype=uint8), array([59, 54, 48], dtype=uint8), array([52, 47, 41],
dtype=uint8), array([55, 50, 44], dtype=uint8), array([24, 19, 13],
dtype=uint8), array([59, 54, 48], dtype=uint8)]

```

```

[10]: pixel_neighbords_mean = get_mean_for_neighbords(pixels_by_neighbords,
↪anomalous_image)

```

```

[11]: print(pixel_neighbords_mean[(165, 297)])
    # pixel_neighbords_mean

```

```
{'r': 42.5, 'g': 37.5, 'b': 31.5}
```

0.5 Ahora tenemos el mean de cada pixel basado en sus vecinos, pero no todos los pixeles necesitan cambiar necesariamente, solo si el color actual y el del mean son demasiado diferentes, para eso habra que encontrarlos, una aproximacion podria ser calcular la distancia vectorial entre los colores, es tal vez muy costoso computacionalmente.

0.5.1 El criterio de distancia se puede modificar

```
[12]: def pixel_distance_replacer(anomalous_image, pixel_neighbors_mean,
    ↪distance_max=100):
    fixed_image = copy(anomalous_image)
    for pixel_poss in pixel_neighbors_mean.keys():
        try:
            current_pixel = anomalous_image[pixel_poss[0], pixel_poss[1]]
            neighbors_pixel_suggested = array(
                [
                    pixel_neighbors_mean[pixel_poss]['r'],
                    pixel_neighbors_mean[pixel_poss]['g'],
                    pixel_neighbors_mean[pixel_poss]['b']
                ]
            )

            distance = linalg.norm(current_pixel- neighbors_pixel_suggested)
            if distance > distance_max:
                fixed_image[pixel_poss[0], pixel_poss[1]] =
    ↪neighbors_pixel_suggested
        except:
            pass
    return fixed_image
```

```
[13]: fixed_image = pixel_distance_replacer(anomalous_image, pixel_neighbors_mean,
    ↪200)
    _ = Image.fromarray(fixed_image)
    _.save('gato_gris_fixed.jpeg')
    -
```

[13]:



0.6 Proceso completo de recuperacion

```
[14]: def histogram(anomalous_image, resolution=200):  
        neighbors = image_neighbours(anomalous_image)  
        pixels_by_neighbors = get_pixels_by_neighbors(neighbors, anomalous_image)  
        pixel_neighbors_mean = get_mean_for_neighbors(pixels_by_neighbors, ↵  
↵anomalous_image)  
        return pixel_distance_replacer(anomalous_image, ↵  
↵pixel_neighbors_mean, resolution )
```

0.7 Repitiendo el proceso para el gato blanco

```
[15]: image_easy_colors
```

```
[15]:
```



Anadiendo ruido

```
[16]: gato_blanco_ruido = add_salt_and_pepper(image_easy_array,percentage_of_anomaly↵
↵=10)
_ = Image.fromarray(gato_blanco_ruido)
_
```

[16]:



```
[25]: _recovered = histogram(gato_blanco_ruido, 150)
_ = Image.fromarray(_recovered)
_.save('gato_blanco_fixed.jpeg')
_
```

border_row: 229

border_col: 218

[25]:



[]: