

Leftmotor = Motor(forward=20, backward=21)  
 Rightmotor = Motor(forward=19, backward=26)  
 Leftbutton = Button(16)  
 FullColorled = RGBLED(red=12, green=6, blue=13)  
 Rightbutton = Button(5)  
 SensorDistance = DistanceSensor(echo=11, trigger=7)  
 SensorLight = LightSensor(8)  
 leds = LEDBoard(25, 24, 9, 10, 15, 18, 17, 22, 27, 23)  
 buzzer = Buzzer(4)

