Leftmotor = Motor(forward=20, backward=21)

Rightmotor = Motor(forward=19, backward=26)

Leftbutton = Button(16)

FullColorled = RGBLED(red=12, green=6, blue=13)

Rightbutton = Button(5)

SensorDistance = DistanceSensor(echo=11, trigger=7)

SensorLight = LightSensor(8)

leds = LEDBoard(25, 24, 9, 10, 15, 18, 17, 22, 27, 23)

buzzer = Buzzer(4)

Graphical user interface

Description automatically generated with medium confidence