

Lab Report

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Week 4

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■ Title

- Applying transformations to basic primitives (a line, a circle and a polygon) about an arbitrary point in space.

Procedure

We build up on the work done in the previous class and again use a combination of in built matrix transformations along with some hard coded matrix multiplications to do the requisite modeling transformations.

The transformation about an arbitrary point \mathbf{P} involves the following :

1. Apply a translation operation

$$T_t$$

to the origin so that it is shifted to \mathbf{P}

2. Apply your regular transformation operations
3. Apply

$$T_t^{-1}$$

to bring the system back to original coordinate system.

There for, to apply a transformation \mathbf{T} to a model \mathbf{X} , obtaining $\mathbf{X'}$, we do the following

$$X' = T_t^{-1} T T_t X$$

Transformation Matrices

1. Scaling

$$\begin{bmatrix} 0.33 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

2. Reflection

$$\begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

3. Shear

$$\begin{bmatrix} 1 & 0 & 0 \\ 0.5 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

4. Rotation

$$\begin{bmatrix} \cos(45) & -\sin(45) & 0 \\ \sin(45) & \cos(45) & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

5. Translation

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0.1 \\ 0 & 0 & 1 \end{bmatrix}$$

6. Co-ordinate shift Let us take $(0.5, 0.5)$ as our arbitrary point. We need to apply the following transformation to shift origin.

$$\begin{bmatrix} 1 & 0 & 0.5 \\ 0 & 1 & 0.5 \\ 0 & 0 & 1 \end{bmatrix}$$

Drawing the Basic Shapes in OpenGL

The following are the functional parts of the code required to plot the shapes.

Line

We create two points and draw a line between them.

```
1 glVertex3f(0.0, 0.0, 0.0);  
2 glVertex3f(0.5, -0.5, 0);
```

Circle

We create a 0.5 radius circle using $\sin(i)$ and $\cos(i)$ values as follows.

```
1 for(i=0; i<10*3.14; i+=0.0001){  
2     glVertex3f(cos(i)/2, sin(i)/2, 0.0);  
3 }
```

Polygon

The polygon is created using the following lines.

```
1 glBegin(GL_LINES);  
2 glVertex3f(0.5, 0.5, 0.0);  
3 glVertex3f(0.0, 0.0, 0.0);  
4 glVertex3f(0.0, 0.0, 0.0);  
5 glVertex3f(-0.5, 0.5, 0.0);  
6 glVertex3f(-0.5, 0.5, 0.0);  
7 glVertex3f(-0.7, -0.5, 0.0);  
8 glVertex3f(-0.7, -0.5, 0.0);  
9 glVertex3f(-0.2, -0.6, 0.0);  
10 glVertex3f(-0.2, -0.6, 0.0);  
11 glVertex3f(0.5, 0.5, 0.0);
```

Transformation Code in OpenGL

The transformation is fed by an input of options which is dealt by the following switch case mechanism. Observe **line 06** and **line 44**.

```

1 static void Key(unsigned char key, int x, int y)
2 {
3     GLfloat m[] = {1, 0, 0, 0, 3, 1, 0, 0, 0, 0, 1, 0, 0, 0, 0, 1};
4     GLfloat n[] = {1, 0, 0, 0, -3, 1, 0, 0, 0, 0, 1, 0, 0, 0, 0, 1};
5     glTranslatef(0.5, 0.5, 0);
6     glMatrixMode(GL_MODELVIEW);
7     switch (key) {
8         case '1':
9             glScalef(0.33, 1, 1);
10            glutPostRedisplay();
11            break;
12        case '2':
13            glScalef(3, 1, 1);
14            glutPostRedisplay();
15            break;
16        case '3':
17            glRotatef(45, 0, 0, 1);
18            glutPostRedisplay();
19            break;
20        case '4':
21            glMultMatrixf(m);
22            glutPostRedisplay();
23            break;
24        case '5':
25            glMultMatrixf(n);
26            glutPostRedisplay();
27            break;
28        case '6':
29            glScalef(-1, 1, 1);
30            glutPostRedisplay();
31            break;
32        case '7':
33            glTranslatef(0, 0.1, 0);
34            glutPostRedisplay();
35            break;
36        case '8':
37            glTranslatef(0, -0.1, 0);
38            glutPostRedisplay();
39            break;
40        case 27:
41            exit(0);
42        }
43    }
44    glTranslatef(0.5, 0.5, 0);

```

Transformation Code in MATLAB

Again observe line numbers - **1**, **2**, **33** and **34** to see how the origin shift operation is working.

```

1 trans = [1, 0, 2; 0, 1, 3; 0, 0, 1];
2 rtrans = [1, 0, -2; 0, 1, -3; 0, 0, 1];
3
4 prompt = 'Input';
5 in=-1;
6 while in ~= 0
7     in = input(prompt);
8     if in==1
9         % scaling
10        T = [2, 0, 0; 0, 1.5, 0; 0, 0, 1];
11    elseif in==-1
12        % rev scaling
13        T = [0.5, 0, 0; 0, 2/3, 0; 0, 0, 1];
14    elseif in==2
15        % reflection
16        T = [-1, 0, 0; 0, 1, 0; 0, 0, 1];
17    elseif in==3
18        % shear
19        T = [1, 1, 0; 0, 1, 0; 0, 0, 1];
20    elseif in==-3
21        % rev shear
22        T = [1, -1, 0; 0, 1, 0; 0, 0, 1];

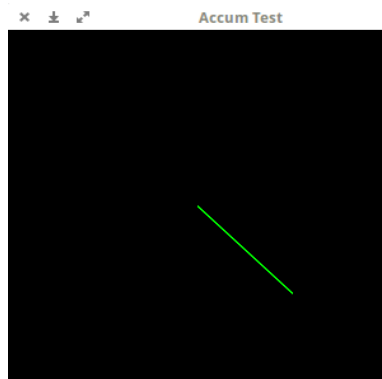
```

```

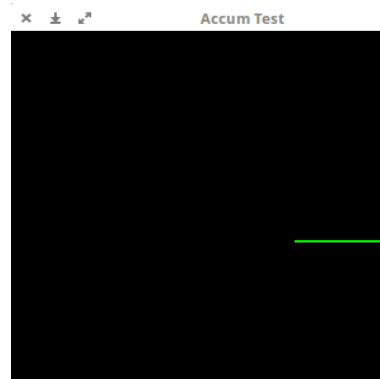
23 elseif in==4
24     % rotation
25     T = [cosd(45), -sind(45), 0; sind(45), cosd(45), 0; 0, 0, 1];
26 elseif in==5
27     % translation
28     T = [1, 0, 1; 0, 1, 0.5; 0, 0, 1];
29 elseif in==6
30     % rev translation
31     T = [1, 0, -1; 0, 1, -0.5; 0, 0, 1];
32 end
33 pts = trans*T*trtrans*pts;
34 plot(pts(1,:), pts(2,:), 'r*-');
35 axis([-10, 10, -10, 10]);
36 display(pts)
37 end

```

Examples

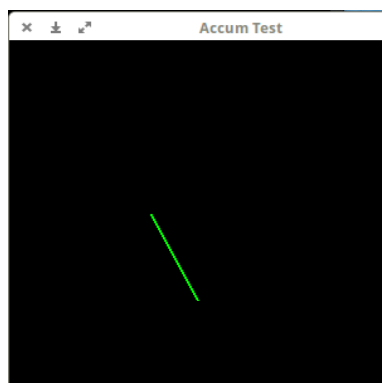


(a) Initial Line

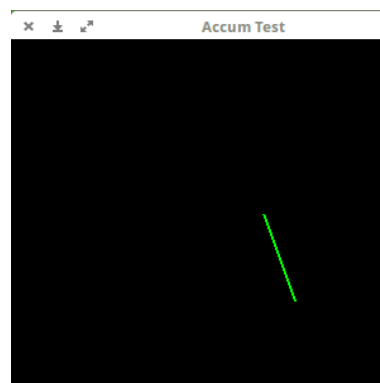


(b) Line : Rotation

FIGURE 1 – Transformations on Line : Rotation

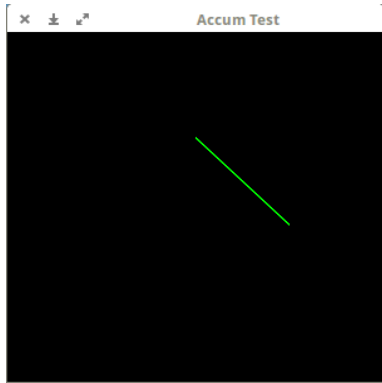


(a) Line : Shear

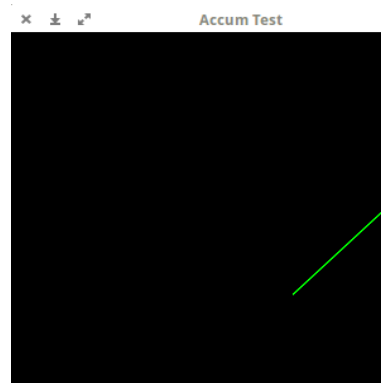


(b) Line Scale

FIGURE 2 – Transformations on Line : Shear, Scale

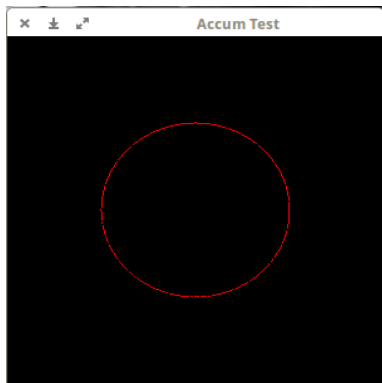


(a) Line : Translate

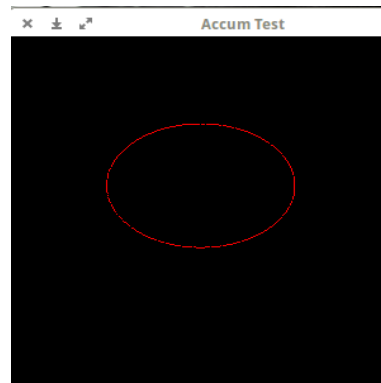


(b) Line : Reflect

FIGURE 3 – Transformations on Line : Translate, Reflect

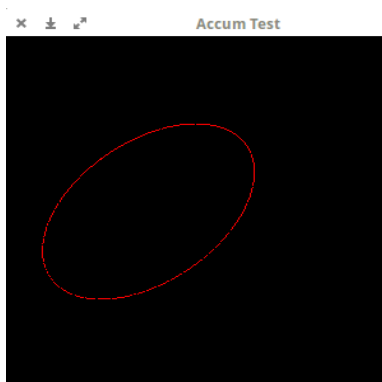


(a) Initial Circle

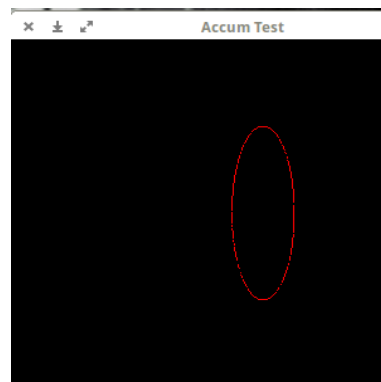


(b) Circle : Rotation

FIGURE 4 – Transformations on Circle : Rotation

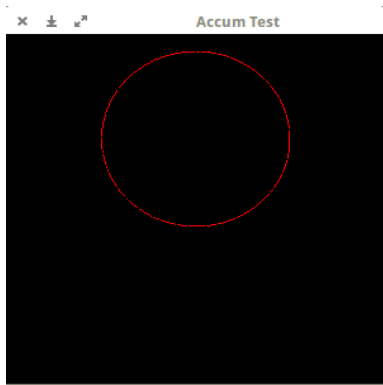


(a) Circle : Shear

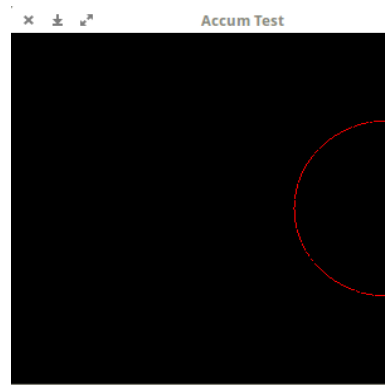


(b) Circle Scale

FIGURE 5 – Transformations on Circle : Shear, Scale

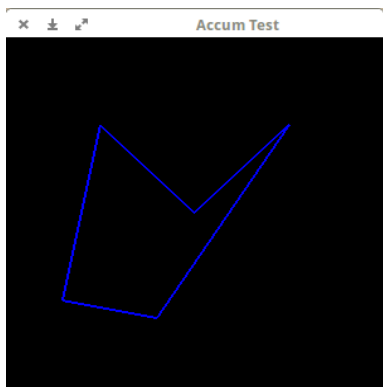


(a) Circle : Translate

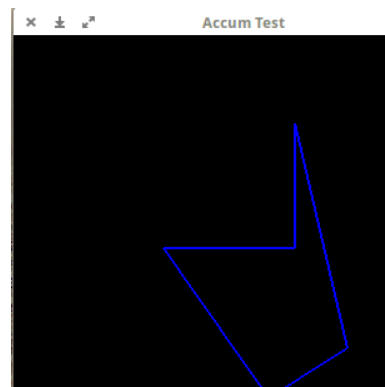


(b) Circle : Reflect

FIGURE 6 – Transformations on Circle : Translate, Reflect

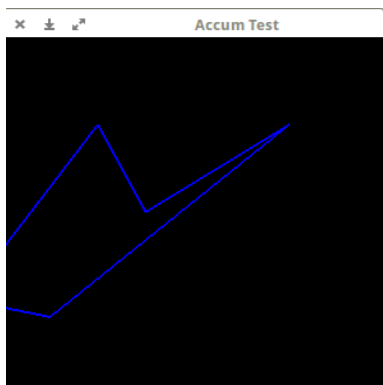


(a) Initial polygon

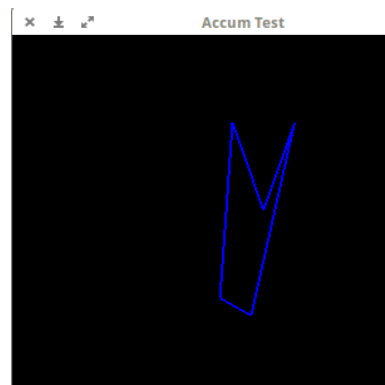


(b) polygon : Rotation

FIGURE 7 – Transformations on polygon : Rotation

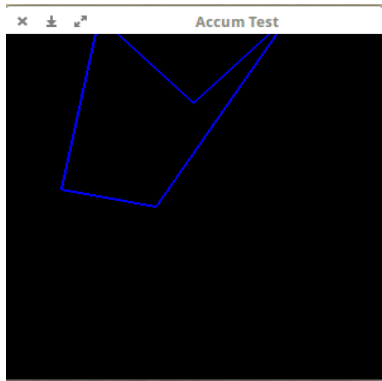


(a) Polygon : Shear

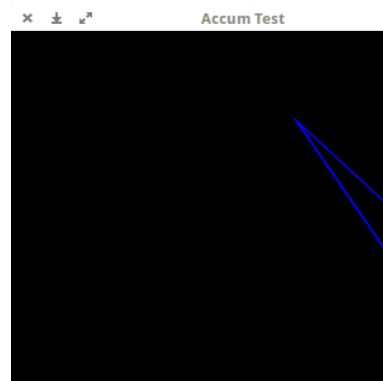


(b) Polygon : Scale

FIGURE 8 – Transformations on Polygon : Shear, Scale

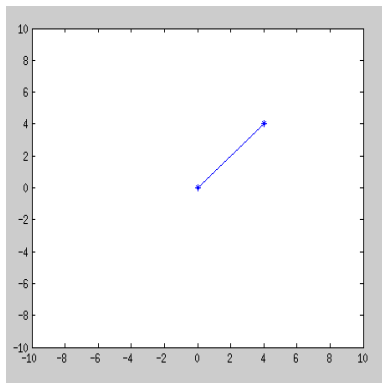


(a) Polygon : Translate

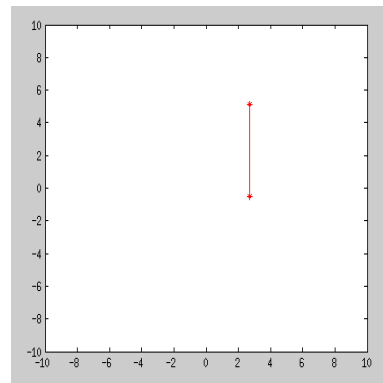


(b) Polygon : Reflect

FIGURE 9 – Transformations on Polygon : Translate, Reflect

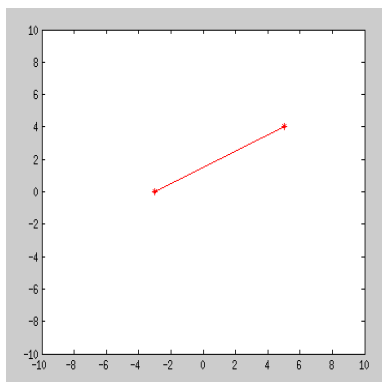


(a) Initial Line

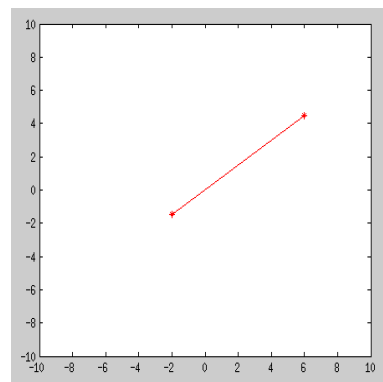


(b) Line : Rotation

FIGURE 10 – Transformations on Line : Rotation

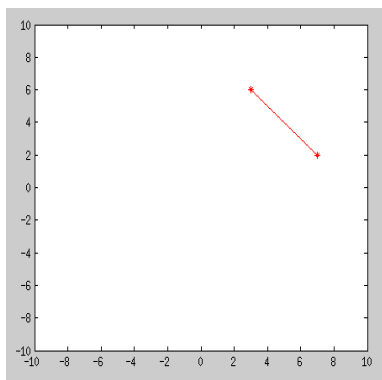


(a) Line : Shear

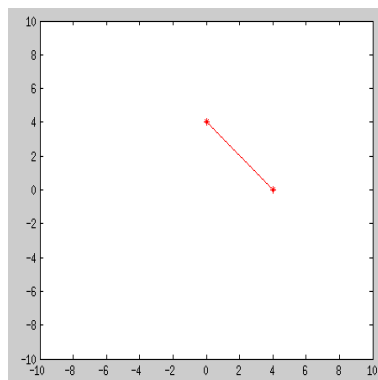


(b) Line Scale

FIGURE 11 – Transformations on Line : Shear, Scale

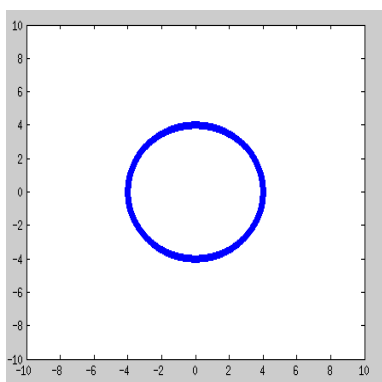


(a) Line : Translate

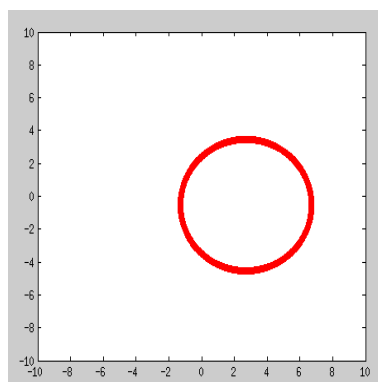


(b) Line : Reflect

FIGURE 12 – Transformations on Line : Translate, Reflect

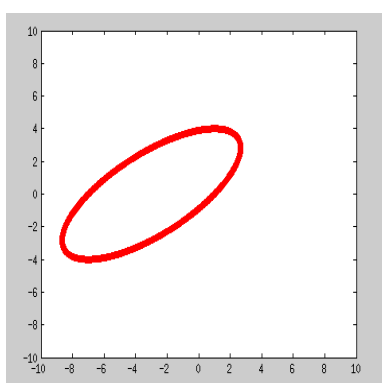


(a) Initial Circle

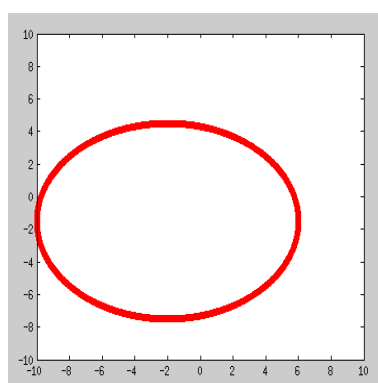


(b) Circle : Rotation

FIGURE 13 – Transformations on Circle : Rotation

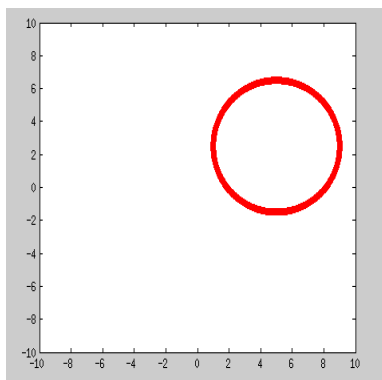


(a) Circle : Shear

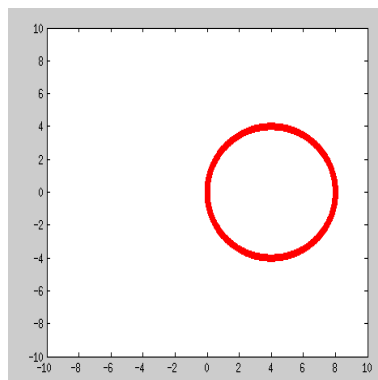


(b) Circle : Scale

FIGURE 14 – Transformations on Circle : Shear, Scale

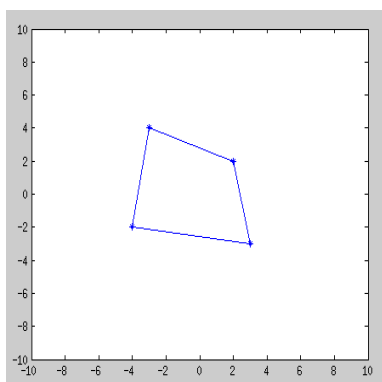


(a) Circle : Translate

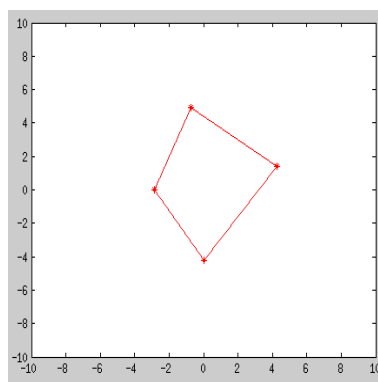


(b) Circle : Reflect

FIGURE 15 – Transformations on Circle : Translate, Reflect

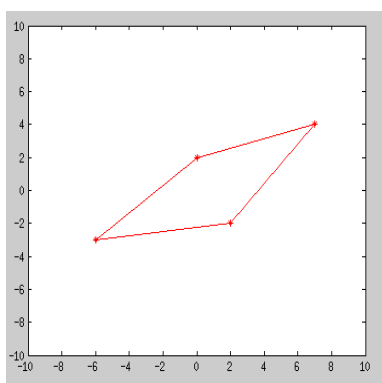


(a) Initial polygon

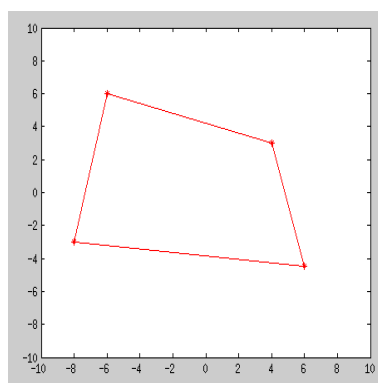


(b) Polygon : Rotation

FIGURE 16 – Transformations on Polygon : Rotation

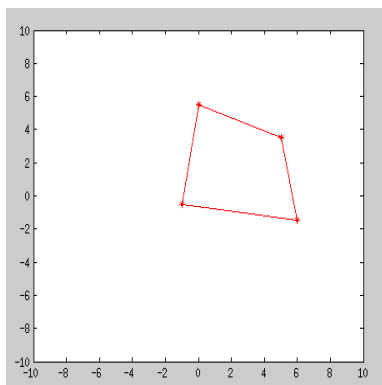


(a) Polygon : Shear

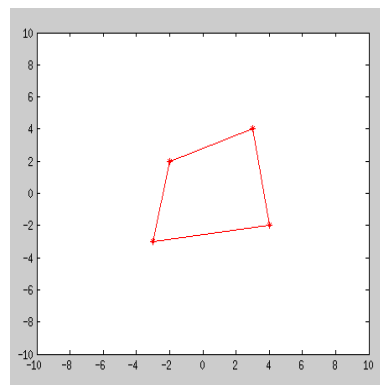


(b) Polygon : Scale

FIGURE 17 – Transformations on Polygon : Shear, Scale



(a) Polygon : Translate



(b) Polygon : Reflect

FIGURE 18 – Transformations on Polygon : Translate, Reflect