**Nuts and Bolts of Deploying Real Cloudproxy Applications**

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**Overview**

Cloudproxy is a software system that provides *authenticated* isolation, confidentiality and integrity of program code and data for programs even when these programs run on remote computers operated by powerful, and potentially malicious system administrators. Cloudproxy defends against observation or modification of program keys, program code and program data by persons (including system administrators), other programs or networking infrastructure. In the case of the cloud computing model, we would describe this as protection from co-tenants and data center insiders. To achieve this, Cloudproxy uses two components: a “Host System” (raw hardware, Virtual Machine Manager, Operating System) which provides capabilities described below to the protected program or “Hosted System” (VM, Application, Container).

This document focuses on installation and deployment tradeoffs for Cloudproxy applications. We hope these instructions allows rapid installation and configuration of Cloudproxy nodes on standard Intel Hardware with Trusted Hardware support; this requires SMX and either TPM 1.2 or TPM 2.0 support. See appendix I for a far from exhaustive list of supported hardware. We assume readers are familiar with [4] which explains Cloudproxy basic concept like measurement and principal names and eplains how to build Cloudproxy applications.

Readers can consult [1] for a fuller description. Source code for Cloudproxy as well as all the samples and documentation referenced here is in [2].

**Downloading and compiling Cloudproxy**

First, you should download the Cloudproxy repository from [2]. To do this, assuming you have git repository support, type

git clone <https://github.com/jlmucb/cloudproxy>,

or,

go get <https://github.com/jlmucb/cloudproxy>.

This latter command will also install the needed go libraries. You can also download a zipped repository from github. You should probably install this in ~/src/github.com/jlmucb (which we refer to as $CLOUDPROXYDIR) to save go compilation problems later. It’s a good idea to put go binaries in ~/bin as is common in Go. Follow the installation instructions in $CLOUDPROXYDIR/Doc; that directory also contains [1] and an up to date version of [4].

You must also install the Go development tools (and C++ development tools if you use the C++ version) as well as protobuf, gtest and gflags as described in the Go documentation.

We will continue to use the simpleexample application described in [4].

**Overview of installation on Linux**

The figure below should be familiar from [4].

![](data:application/pdf;base64,)

![](data:application/pdf;base64,)

**Overview of installing Linux**

1. Install Linux. TPM2.0 requires a Version 4 kernel.
2. Install the Linux Kernel Development environment
3. Activate the TPM using the BIOS interface, using HW manufacturer’s instructions.
4. Take ownership of the TPM and generate the appropriate keys
5. Build TBOOT
6. Configure Grub
7. Build Initramfs

**TPM 1.2 Installation**

install trousers

sudo agt-get install trousers

sudo agt-get install tpm-dev

sudo agt-get install tpm-tools

sudo agt-get install libtspi-dev

Enable and activate the TPM in BIOS and make sure TXT and vt-d is enabled too. After enabling the TPM in BIOS, type:

sudo bash

tscd start

tpm\_takeownership -z -y

tpm\_getpubek

Note: If someone has already taken ownership, you must disable the tpm and reenable it. You may have to remove power to reset the TPM and you may have to create an endorsement key using tpm\_createek

You can activate the TPM from software (trousers) if you are in single user mode. The sequence of instructions is:

telinit S or boot to single user mode

ifup lo

start tcsd

tpm\_setpresence --assert

tpm\_setenable --enable --force

tpm\_setactive --activate --force

reboot

First we must initialize the TPM physical chip with the tpm\_clear command, which returns the

TPM to the default state, which is unowned, disabled and inactive. That command wipes all the

ownership information from the TPM, invalidates all the keys and data tied to the TPM and

even disables and deactivates the TPM.

# tpm\_clear --force

Tspi\_TPM\_ClearOwner failed: 0x00000007 - layer=tpm, code=0007 (7), TPM is disabled

We can see that the TPM is disabled, which is why we can’t clear it. This can happen if

we forget to actually enable the TPM in BIOS. The first thing to do would be to actually

enable the TPM in BIOS. But if the TPM has been initialized before, we would receive the

output that can be seen below:

# tpm\_clear --force

TPM Successfully Cleared. You need to reboot to complete this operation. After reboot

the TPM will be in the default state: unowned, disabled and inactive.

This would require us to reboot the computer for changes to take effect. When clearing the

TPM we’ll return it to the default state, which is unowned, disabled and inactive, as

already mentioned. To enable the TPM afterwards, we need the owner password. But since

the TPM owner has been cleared, there is no owner password and we can set a new one

without entering the old one. We can also receive an error like the following:

# tpm\_clear --force

Tspi\_TPM\_ClearOwner failed: 0x0000002d - layer=tpm, code=002d (45), Bad physical presence value

DO NOT SET ANY PASSWORD for the TPM.

# tpm\_takeownership -z -y

If we later want to change either of the commands, we can do it with the tpm\_changeownerauth

command. If we pass the –owner argument to the tpm\_changeownerauth command we’ll be

changing the administration password and if we pass the –srk into the tpm\_changeownerauth

command we’ll be changing the SRK password. We can see the example of both commands in

the output below:

# tpm\_changeownerauth --owner

Enter owner password:

Enter new owner password:

Confirm password:

# tpm\_changeownerauth --srk

Enter owner password:

Enter new SRK password:

Confirm password:

There are 5 keys in TPM:

TPM Endorsement Key (EK): This key is created by the manufacturer and cannot be removed.

Sometimes it can be changed by the owner of the computer.

TPM Storage Key (SRK): Is the 2048 bit RSA key created when configuring the ownership.

This key is stored inside the chip and can be removed. The key is used to encrypt the

Storage Key (SK) and Attestation Identity Key (AIK).# tpm\_setenable --enable

Enter owner password:

Disabled status: false

# tpm\_setactive

Enter owner password:

Persistent Deactivated Status: false

Volatile Deactivated Status: false

There are usually two Endorsement Keys (EK): the public and private one. The private key is always stored at the TPM and cannot even be seen by anyone, while the public key can be displayed with the tpm\_getpubek command.

# tpm\_getpubek

Tspi\_TPM\_GetPubEndorsementKey failed: 0x00000008 - layer=tpm, code=0008 (8), The TPM target command has been disabled

Enter owner password:

Public Endorsement Key:

Version: 01010000

Usage: 0x0002 (Unknown)

Flags: 0x00000000 (!VOLATILE, !MIGRATABLE, !REDIRECTION)

AuthUsage: 0x00 (Never)

Algorithm: 0x00000020 (Unknown)

Encryption Scheme: 0x00000012 (Unknown)

Signature Scheme: 0x00000010 (Unknown)

Public Key:

a350b3a3 3edddc30 06248f4f 5d3eb80a 34fcbea0 83dde002 8dffa703 e116f8b0

eb1962ee a65998b3 384aeb6e 85486be9 0316a6ca a189a5ba 2217b2a2 9da014db

dfbe7731 fb675e7a 438c4775 deea54fb 0c75de5d ba961950 3eda4555 d27a9a30

e94d39d0 a4ea314d a70eaf08 e49dd354 d57ed34d 234220d9 604471a9 86173050

9ff9b0e5 b65cb4b5 5f46a7f9 4378bd7e 8c61b91b ad312974 fef5d70f 84f4484f

e5c95300 0eef76f2 1667443f dc2fa82e 351d945e 6b5f75e8 828d010f 61541552

[...]

**Tboot**

Trousers and trousers-devel packages must already be installed in order to build lcptools.

Tboot requires an ACM Module that sets up the machine for TXT. The appropriate

SINIT Module can be downloaded from <http://software.intel.com/en-us/articles/intel-trusted-execution-technology/>. Tboot will show the appropriate device ID in its output if it is booted with

the incorrect version of sinit. Use txt-stat (installed with tboot) to read the most recent tboot logs. The current version of tboot requires version 17 or greater of the SINIT module. A copy of the module we used is in this distribution.

Building Tboot

cd tbootprep/tboot-1.7.0

make

make install

To build the LCPTools

cd lcptools

make

You may build a Launch Control Policy (LCP) which controls what can be booted. If you have no LCP, the default policy will be applied and this should work! If not, there are instructions on creating policy at the bottonm of this file. Latest tboot test was tboot-1.7.3.2 with SINIT67.BIN.

Next you must modify grub so that you can choose the tbooted linux from the boot window.

If the verified launch policy is non-empty, it is extended into PCR 17 by default. Subsequent loaded modules are extended into PCR 18 by default (Check this!). This behavior can be changed with the VLP.

The Grub(2) configuration file is usually in /boot/grub and is called grub.cfg. It is updated automatically when a kernel is updated or when you run update-grub.

Tboot module must be added as the 'kernel' in the grub.conf file.

Note that the Lenovo T410 is known not to work with the Intel IOMMU; it will not successfully boot with TBOOT.

The final grub configuration file will look something like:

menuentry 'Ubuntu Linux 3.0.0-16-generic with TXT' --class ubuntu --class gnu-linux --class gnu --class os {

recordfail

set gfxpayload=text

insmod gzio

insmod part\_msdos

insmod ext2

set root='(hd0,msdos5)'

search --no-floppy --fs-uuid --set=root 8ab78657-8561-4fa8-af57-bff736275cc6

echo 'Multiboot'

multiboot /boot/tboot.gz /boot/tboot.gz logging=vga,memory,serial

echo 'Linux'

module /boot/vmlinuz-3.0.0-16-generic /boot/vmlinuz-3.0.0-16-generic root=UUID=8ab78657-8561-4fa8-af57-bff736275cc6 ro splash vt.handoff=7 intel\_iommu=on

echo 'initrd'

module /boot/initrd.img-3.0.0-16-generic /boot/initrd.img-3.0.0-16-generic

echo 'sinit'

module /boot/sinit51.bin /boot/sinit51.bin

Modify grub.conf to load the policy data file:

Edit grub.conf and add the following:

module /list.data

where you should use the path to this file.

Copy sinit into /boot and change run grub.conf then run update-grub.

Check the /boot directory to make sure tboot.gz is there.

The utility txt-stat in the utils subdirectory of tboot, can be used to view the DRTM boot log.

Reported problems with TPM's

The TPM, driver/char/tpm/tpm.c, depends on TPM chip to report timeout values for timeout\_a, b, and d. The Atmel TPM in Dell latitude 6430u, reports wrong timeout values (10 ms each), instead of TCG specified (750ms, 2000ms, 750ms, 750ms for timeout\_a/b/c/d respectively). You can fix the driver code and it will work.

A permissive Tboot policy is required for the non-hypervisor solutions. In this case, the system will boot whatever it finds, but it will still perform measured launch, and clients interacting with the system will still be able to check that the right software was booted by checking the PCRs. Once the hypervisor is written, a more restrictive launch control policy is possible and maybe desirable.

Put 11\_tboot in /etc/grub.d

Information on PCR Usage on TPM 1.2

PCR 17 will be extended with the following values (in this order):

- The values as documented in the MLE Developers Manual

- SHA-1 hash of: tboot policy control value (4 bytes) SHA-1 hash of tboot policy (20 bytes)

: where the hash of the tboot policy will be 0s if TB\_POLCTL\_EXTEND\_PCR17 is clear

PCR 18 It will be extended with the following values (in this order):

- SHA-1 hash of tboot (as calculated by lcp\_mlehash)

- SHA-1 hash of first module in grub.conf (e.g. Xen or Linux kernel)

PCR \* : tboot policy may specify modules' measurements to be extended into PCRs specified in the policy

The default tboot policy will extend, in order, the SHA-1 hashes of all modules (other than 0) into PCR 19.

-------------------------------------------------------------------------------

The LCP consists of policy elements.

To specify launch policy via a list of hashes:

0. sudo bash

1. lcp\_mlehash -c "command line for tboot from grub.cfg" /boot/tboot.gz > mle\_hash

- the command line in this case is the string from /boot/grub/grub.cfg

- after multiboot tboot.gz, e.g., "logging=vga,memory,serial"

- copy and paste:

./lcp\_mlehash -c "logging=vga" /boot/tboot.gz>mle\_hash

2. lcp\_crtpolelt --create --type mle --ctrl 0x00 --minver 17 --out mle.elt mle\_hash

- copy and paste

./lcp\_crtpolelt --create --type mle --ctrl 0x00 --minver 17 --out mle.elt mle\_hash

3. lcp\_crtpollist --create --out list\_unsig.lst mle.elt pconf.elt

- copy and paste

./lcp\_crtpollist --create --out list\_unsig.lst mle.elt pconf.elt

4. lcp\_crtpol2 --create --type list --pol list.pol --data list.data list\_unsig.lst

- copy and paste

./lcp\_crtpol2 --create --type list --pol list.pol --data list.data list\_unsig.lst

5. cp list.pol /boot

- copy and paste

cp owner\_list.data /boot

Next create a verified Launch policy:

1. tb\_polgen/tb\_polgen --create --type nonfatal vl.pol

- copy and paste

../tb\_polgen/tb\_polgen --create --type nonfatal vl.pol

2. tb\_polgen/tb\_polgen --add --num 0 --pcr 18 --hash image

--cmdline "the command line from linux in grub.conf"

--image /boot/vmlinuz-2.6.18.8

vl.pol

- copy and paste

../tb\_polgen/tb\_polgen --add --num 0 --pcr 18 --hash image --cmdline "root=UUID=cf6ae6b5-abb5-4d5d-b823-bd798a0621de ro quiet splash $vt\_handoff" --image /boot/vmlinuz-3.5.0-23-generic vl.pol

3. tb\_polgen/tb\_polgen --add --num 1 --pcr 19 --hash image

--cmdline ""

--image /boot/initrd-2.6.18.8

vl.pol

- copy and paste

../tb\_polgen/tb\_polgen --add --num 1 --pcr 19 --hash image --image /boot/initrd-3.5.0-23-generic vl.pol

If any mle can be launched:

./lcp\_crtpol2 --create --type any --pol any.pol

Define tboot error TPM NV index:

1. lcptools/tpmnv\_defindex -i 0x20000002 -s 8 -pv 0 -rl 0x07 -wl 0x07

-p TPM-password

- copy and paste

../lcptools/tpmnv\_defindex -i 0x20000002 -s 8 -pv 0 -rl 0x07 -wl 0x07

Define LCP and Verified Launch policy indices:

1. lcptools/tpmnv\_defindex -i owner -s 0x36 -p TPM-owner-password

- copy and paste

../lcptools/tpmnv\_defindex -i owner -s 0x36 -p TPM-owner-password

2. lcptools/tpmnv\_defindex -i 0x20000001 -s 256 -pv 0x02 -p TPM-owner-password

- copy and paste

../lcptools/tpmnv\_defindex -i 0x20000001 -s 256 -pv 0x02 -p TPM-owner-password

Write LCP and Verified Launch policies to TPM:

(modprobe tpm\_tis; tcsd;)

1. lcptools/lcp\_writepol -i owner -f [any.pol|list.pol] -p TPM-password

- copy and paste

../lcp\_writepol -i owner -f list.pol -p <ownerauth password>

2. If there is a verified launch policy:

lcptools/lcp\_writepol -i 0x20000001 -f vl.pol -p TPM-password

- copy and paste

../lcptools/lcp\_writepol -i 0x20000001 -f vl.pol -p TPM-password

Use lcp\_crtpollist to sign the list:

1. openssl genrsa -out privkey.pem 2048

2. openssl rsa -pubout -in privkey.pem -out pubkey.pem

3. cp list\_unsig.lst list\_sig.lst

4. lcp\_crtpollist --sign --pub pubkey.pem --priv privkey.pem --out list\_sig.lst

Use openssl to sign the list:

1. openssl rsa -pubout -in privkey.pem -out pubkey.pem

2. cp list\_unsig.lst list\_sig.lst

3. lcp\_crtpollist --sign --pub pubkey.pem --nosig --out list\_sig.lst

4. openssl genrsa -out privkey.pem 2048

5. openssl dgst -sha1 -sign privkey.pem -out list.sig list\_sig.lst

6. lcp\_crtpollist --addsig --sig list.sig --out list\_sig.lst

**TPM 2.0 Installation**

**InitRamfs**

The initial ramdisk, or initrd, is a temporary file system commonly used in the boot process of the Linux kernel. The kernel typically uses the ramdisk for making preparations before the real root file system can be mounted.

ecompress and unpack the existing initramfs

cd /tmp

mkdir init

cd init

cp /boot/initramfs.img-`uname -r` initrd.gz

gunzip -c -9 initrd.gz | cpio -i -d -H newc --no-absolute-filenames

Copy the dynamic link libraries for the executables into the filesystem

Change the initscript (init) to run dmcrypt and change the way the system disk is mounted.

vim init

Here is a simple script that works:

-- start simple script

#!/bin/sh

[ -d /dev ] || mkdir -m 0755 /dev

[ -d /root ] || mkdir -m 0700 /root

[ -d /sys ] || mkdir /sys

[ -d /proc ] || mkdir /proc

[ -d /tmp ] || mkdir /tmp

mkdir -p /var/lock

mount -t sysfs -o nodev,noexec,nosuid sysfs /sys

mount -t proc -o nodev,noexec,nosuid proc /proc

# Some things don't work properly without /etc/mtab.

ln -sf /proc/mounts /etc/mtab

grep -q '\<quiet\>' /proc/cmdline || echo "Loading, please wait..."

# Note that this only becomes /dev on the real filesystem if udev's scripts

# are used; which they will be, but it's worth pointing out

if ! mount -t devtmpfs -o mode=0755 udev /dev; then

echo "W: devtmpfs not available, falling back to tmpfs for /dev"

mount -t tmpfs -o mode=0755 udev /dev

[ -e /dev/console ] || mknod -m 0600 /dev/console c 5 1

[ -e /dev/null ] || mknod /dev/null c 1 3

fi

mkdir /dev/pts

mount -t devpts -o noexec,nosuid,gid=5,mode=0620 devpts /dev/pts || true

mount -t tmpfs -o "nosuid,size=20%,mode=0755" tmpfs /run

mkdir /run/initramfs

# compatibility symlink for the pre-oneiric locations

ln -s /run/initramfs /dev/.initramfs

/sbin/ifconfig lo 127.0.0.1

# can set up other networks here as needed, e.g., on eth0

# mount /boot as a place to put keys between reboots (e.g., for tcService.exe)

mkdir /boot

mount /dev/sda1 /boot

/bin/busybox sh

-- end simple script

- untested:

swapoff -a

cryptsetup [-c aes -h sha256] -s 128 -d /dev/urandom create swap /dev/sda1

mkswap /dev/mapper/swap

swapon /dev/mapper/swap

Put initramfs back together

find . | cpio -H newc -o|gzip -9 > ../initrd.img-new

Copy it to the boot directory

sudo cp initrd.gz /boot/initrd.img-staticLinux

Change /etc/grub.d to use this new initramfs.

Consult: http://manpages.ubuntu.com/manpages/karmic/man8/initramfs-tools.8.html

mkdir initramfs{,-old}

cd initramfs

gunzip -c -9 /boot/initrd.img-2.6.32-5-686 \

| cpio -i -d -H newc --no-absolute-filenames

find > ../initramfs.content

cd ../initramfs-old

gunzip -c -9 /boot/initrd.img-2.6.32-5-686.bak \

| cpio -i -d -H newc --no-absolute-filenames

find > ../initramfs-old.content

cd ..

diff -u initramfs-old.content initramfs.content

**Building KVM Kernel and Guest partition**

Here is a quick description of how to build the kernel for host and guest.

variables: $KERNEL is the kernel source directory (e.g., /usr/src/linux-3.11.0), $CODE is the fileProxy Code directory (e.g.,~/src/fileProxy/Code)

export KERNEL="/usr/src/linux-lts-quantal-3.5.0"

export CODE="/home/jlm/fpDev/fileProxy/Code"

- Make sure you have all the prerequisites for building the kernel

- get the kernel source and make its root directory be $KERNEL

- navigate to ${CODE}/kvm/host-kernel

- execute the commands

- ./apply-patches.sh $KERNEL

- ./copy\_to\_kernel.sh $KERNEL

make menuconfig

disable loadable module support

edit config CONFIG\_ACPI=n

The apply-patches.sh command might fail, depending on the vintage of the kernel you have. If the patches fail, they are fairly easy to fix by hand. You can look at the patches to see what they do:

- the Makefile in ${KERNEL}/drivers/misc needs to have three extra lines, one obj-y += DIR for each of the three directories we added (\*tcio\*)

- the Makefile in ${KERNEL}/arch/x86/kvm needs to add vmdd.o to the dependencies of kvm.o

- ${KERNEL}/arch/x86/kvm/x86.c needs to have the lines added from the patch in ${CODE}/kvm/host-kernel/arch/x86/kvm/x86.c.patch (just acouple of lines)

- copy a working config over to $KERNEL as .config. This is more important than it may seem at first glance. Often dependencies in make menuconfig make getting an appropriate configuration (e.g.-one that CONFIG\_INTEL\_TXT=y) difficult. A sample .config file (for Linux 3.5.7) is in config.sample in this directory. NOTE: If you're building in the VM make sure you copy a .config from a working VM kernel.

- run

- yes "" | make oldconfig

- yes "" | make localmodconfig

- make (with a -j factor appropriate for your machine)

- sudo make modules\_install

- sudo make install

- and you should have a copy of the new kernel in /boot, ready to go.

- update the tboot script for this kernel and try to tboot it.

**Building and provisioning the Guest OS**

Make sure your VM has at least 20MB of disk

1. Install via virt-manager a fresh VM from a CD.

2. SSH the jlmcrypt directory into the VM.

apt-get install openssh-server

sudo service ssh start

sudo stop ssh

sudo start ssh

sudo restart ssh

sudo status ssh

ssh jlm@192.168.122.244

sftp

put jlmcrypt.tar .

3. Save the VM Image in virtmanager. You can find the IP address to SSH to by going into the VM and typing ifconfig -a.

4. Save the original libvirt xml to a safe place. For example,

virsh dumpxml KvmTestGuest > /home/jlm/jlmcrypt/vms/KvmTestGuestImage.xml

5. Copy the kernel-image file and initramfs file for the CloudProxy partition to the place you want to save them. In this example, I use /home/jlm/jlmcrypt/vms/kernel and /home/jlm/jlmcrypt/vms/initram.

6. Change the boot options for your vm (in virt-manager, for example) so that it does the direct kernel/initram boot using the files named in step 6.

7. Save the new libvirt xml to a safe place. For example,

virsh dumpxml KvmTestGuest > /home/jlm/jlmcrypt/vms/KvmTestGuestBoot.xml.

8. Copy the direct boot xml into a template file that you will reference

when you tcLaunch the VM. For example, cp /home/jlm/jlmcrypt/vms/KvmTestGuestBoot.xml /home/jlm/jlmcrypt/vms/KvmTestGuestTemplate.xml

9.Edit the template file.

Replace the value of the name tag (which should have the name of

vm originally) with %s. For example,

<name>%s</name>

Replace the kernel and image tag values with %s, getting

<kernel>%s</kernel>

<initrd>%s</initrd>

Replace the disk source file value with %s, getting:

<disk type='file' device='disk'>

<driver name='qemu' type='raw'/>

<source file='%s'/>

<target dev='hda' bus='ide'/>

<address type='drive' controller='0' bus='0' unit='0'/>

</disk>

Running the newly-installed guest

sudo /usr/local/kvm/bin/qemu-system-x86\_64 vdisk.img -m 384

Download and install KVM: You can use the package included in Ubuntu 7.10, just execute: apt-get install kvm You can also download the last release of KVM and compile it.

You also need the linux-headers packages for the Kernel you are using.

First of all, we need the KVM package. You can find the actual release at http://sourceforge.net/projects/kvm/. Download it to your server:

wget link/to/file /usr/src/

Now unpack the content.

cd /usr/src/

tar -xzf file.tar.gz

cd folder/to/kvm

Before compiling KVM make sure that your CPU supports virtualization and if that option is activated in the BIOS. Compile KVM.

./configure

make

make install

Now load the KVM modules:

If you have an Intel CPU load:

modprobe kvm

modprobe kvm\_intel

If you have an AMD CPU load:

modprobe kvm

modprobe kvm\_amd

Creating the network bridge First, install bridge-utils: apt-get install bridge-utils

If you want to connect to your virtual machine later, you need to set up a network bridge. Edit /etc/network/interfaces like this (make sure to insert your public IP Address):

auto lo

iface lo inet loopback

auto br0

iface br0 inet static

address xxx.xxx.xxx.xxx

netmask xxx.xxx.xxx.xxx

gateway xxx.xxx.xxx.xxx

bridge\_ports eth0

bridge\_stp off

bridge\_maxwait 5

Also edit /etc/qemu-ifup like this:

#!/bin/sh

/sbin/ifconfig $1 0.0.0.0 promisc up

/usr/sbin/brctl addif br0 $1

sleep 2

I recommend restarting your server at this point. If you are able to reconnect, your bridge is working.

Creating a virtual disk for a virtual machine & install a system into it. Create an .img file for installation. This file acts as a virtual disk for your vm.

**Configuring a domain**

**The role of the Domain service**

**Key management**

Key management supports the storage, distribution and critically, the rotation of symmetric content keys. In most of our programs, keys and content types (like files) are objects and have domain-wide hierarchical universal names and epochs. Epochs are monotonically increased. For example, a file used by several cloudproxy programs may contains customer information like customer names, addresses, etc. Since these are stored objects, they are encrypted and integrity protected and typically stored redundantly at several network accessible locations. The file /jlm/file/us-zone/customer-file-location1, epoch 2, type: file refers to the file with the indicated name; the epoch indicates the version of the file, different versions of the file are usually encrypted with different keys. These encryption keys also have domain-wide hierarchical universal names and epochs. Encryption keys protect other objects like keys or files. To decrypt a file, we need a chain of keys starting at the sealing key for the Cloudproxy program on a given node and terminating in the desired object (say a file). Each node of the chain consists of the name of the protector object, the protected objects and an encrypted blob consisting of the protected object encrypted (and integrity protected) by the protector key.

For example

/jlm/program-name/master-sealing-key, epoch 5, type: aes-128-gcm

/jlm/key/us-zone/customer-folder-keys, epoch 2, type: aes-128-gcm

/jlm/key/us-zone/customer-file-key, epoch 3, type: aes-128-gcm

/jlm/file/us-zone/customer-file-location1, epoch 2, type: file

Often domains will want to partition keys to provide resilience by *protection zones.* One common way to do this is to have different keys for different geographic locations. This is easily accomplished by reserving a level of the hierarchical object namespace for the zone name as is done above.

Although the foregoing name, epoch based mechanisms facilitate key rotation, it is not a complete solution. Let’s first consider, given this framework, how we might rotate keys.

There are two common circumstances where new keys are introduced into a Cloudproxy environment. First, keys should be rotated regularly as part of good cryptographic hygiene and second, when programs change, their measurements change which means they can no longer access sealed data for earlier versions of the program. In both cases, similar techniques can be used to carry out the key rotation.

Key Rotation and software upgrades

See go/support/support\_libraries /protected-objects and go/support/support\_libraries/ rotation\_support for support routines to maintain and encrypt content keys and build chains of keys like:

Protector Object: /jlm/program-name/master-sealing-key, epoch 5, type: aes-128-gcm

Protected Object: /jlm/key/us-zone-key, epoch 2, type: aes-128-gcm

Encrypted Protected Object

Protector Object: /jlm/key/us-zone-key, epoch 2

Protected Object: /jlm/key/us-zone-key/customer-folder-key, epoch 3, type: aes-128-gcm

Encrypted Protected Object

Protector Object: /jlm/key/us-zone-key/ customer-folder-key, epoch 3

Protected Object: /jlm/key/us-zone-key/customer-folder-key/customer-file-key, epoch 2, type: aes-128-gcm

Encrypted Protected Object

Protector Object: /jlm/key/us-zone/customer-file-key, epoch 3, type: aes-128-gcm

Protected Object: /jlm/file/us-zone/customer-file-location1, epoch 2, type: file

*Using a keystore*

A sample keystore with the required functionality is implemented in go/support/infrastructure\_support/CPSecretServer. Needless to say, this program itself would likely be implemented as a cloudproxy program.

![](data:application/pdf;base64,)

Since keys can be fetched anytime after startup and no pre-existing state is required (except for the Program key), key rotation is easy and is focused at the Secret Service. The secret service can also publish alerts when new keys are available. Upgrade when program versions change is also easy. The new version of the program just gets keys from the server. The server is updated with new ACLs as new program versions become available.

*Using policy key disclosure*

![](data:application/pdf;base64,)

See go/support/support\_libraries/secret\_disclosure\_support for sample code to construct and verify a policy-key signed secret-disclosure statement.

Policy-key says PrincipalName can-read /jlm/key/us-zone/customer-folder-key, epoch 2

**Installing and configuring a Cloudproxy supported KVM instance**

**Installing and configuring a Cloudproxy supported TPM hosted Linux**

**Installing and configuring a Linux stacked on KVM**

**Preparing initramfs**

Decompress and unpack the existing initramfs

cd /tmp

mkdir init

cd init

cp /boot/initramfs.img-`uname -r` initrd.gz

gunzip -c -9 initrd.gz | cpio -i -d -H newc --no-absolute-filenames

Copy the dynamic link libraries for the executables into the filesystem

for i in `ldd /home/jlm/jlmcrypt/fileServer.exe | cut -d' ' -f3 | sed 's/^\s\*//g' | egrep -v '^\s\*$'`; do

source=$i

dir=`dirname $i`

mkdir -p $dir

dest=`echo $i | sed 's?^/??g'`

echo "Copying $source to $dest"

cp $source $dest

done

Copy the runtime directory into the filesystem, and get ifconfig, too

mkdir -p home/jlm/jlmcrypt

cp -r /home/jlm/jlmcrypt/\* home/jlm/jlmcrypt/

cp /sbin/ifconfig sbin/ifconfig

You might want to clean out some of the unnecessary files here.

Change the initscript (init) to run dmcrypt and change the way the

system disk is mounted.

vim init

Here is a simple script that works:

-- start simple script

#!/bin/sh

[ -d /dev ] || mkdir -m 0755 /dev

[ -d /root ] || mkdir -m 0700 /root

[ -d /sys ] || mkdir /sys

[ -d /proc ] || mkdir /proc

[ -d /tmp ] || mkdir /tmp

mkdir -p /var/lock

mount -t sysfs -o nodev,noexec,nosuid sysfs /sys

mount -t proc -o nodev,noexec,nosuid proc /proc

# Some things don't work properly without /etc/mtab.

ln -sf /proc/mounts /etc/mtab

grep -q '\<quiet\>' /proc/cmdline || echo "Loading, please wait..."

# Note that this only becomes /dev on the real filesystem if udev's scripts

# are used; which they will be, but it's worth pointing out

if ! mount -t devtmpfs -o mode=0755 udev /dev; then

echo "W: devtmpfs not available, falling back to tmpfs for /dev"

mount -t tmpfs -o mode=0755 udev /dev

[ -e /dev/console ] || mknod -m 0600 /dev/console c 5 1

[ -e /dev/null ] || mknod /dev/null c 1 3

fi

mkdir /dev/pts

mount -t devpts -o noexec,nosuid,gid=5,mode=0620 devpts /dev/pts || true

mount -t tmpfs -o "nosuid,size=20%,mode=0755" tmpfs /run

mkdir /run/initramfs

# compatibility symlink for the pre-oneiric locations

ln -s /run/initramfs /dev/.initramfs

/sbin/ifconfig lo 127.0.0.1

# can set up other networks here as needed, e.g., on eth0

# mount /boot as a place to put keys between reboots (e.g., for tcService.exe)

mkdir /boot

mount /dev/sda1 /boot

/bin/busybox sh

-- end simple script

- untested:

swapoff -a

cryptsetup [-c aes -h sha256] -s 128 -d /dev/urandom create swap /dev/sda1

mkswap /dev/mapper/swap

swapon /dev/mapper/swap

Put initramfs back together

find . | cpio -H newc -o|gzip -9 > ../initrd.img-new

Copy it to the boot directory

sudo cp initrd.gz /boot/initrd.img-staticLinux

Change /etc/grub.d to use this new initramfs.

Booting with initramfs: how to configure the kernel

To configure Linux to boot by mounting an initramfs image internally, set the

following items on the kernel config:

CONFIG\_BLK\_DEV\_INITRD=y

CONFIG\_INITRAMFS\_SOURCE=<Initramfs cpio image path>

After making these changes to the settings, re-compile the kernel. Finally, the kernel

can be booted as follows (for instance, we report a boot on a mb442 by using a "vmlinux" with the above settings enabled):

host% st40load\_gdb -t stmc:mb442:st40 -c sh4tp -b vmlinux mem=64m

No other parameters have to be passed to st40load\_gdb to boot with initramfs, as the

kernel mounts that image automatically.

initramfs: how to create a rootfs image

To boot Linux by using the initramfs image, create a typical ext2 (or ext3) filesystem

structure in which the only difference with respect to the standard ext2/3 root filesystem

used in SysV, or busybox, is related to the init file.

Usually, the init file is placed under /sbin (for both SysV and Busybox). In the initramfs

rootfs image, the init file has to be placed under the root, /, as the kernel tries to

execute /init instead of /sbin/init in case the initramfs image was mounted after boot.

A typical initramfs filesystem structure is as follows:

target% ls

bin dev etc home include init lib mnt proc sys sbin tmp usr var

The tool mkshinitramfs has been created to improve the process of initramfs rootfs

image creation. The current version of the tool is 1.0. To get information about the

tool's parameters, type the following command line:

host# ./mkshinitramfs -h

mkshinitramfs-1.0,

usage: mkshinitramfs [-h|-H Help]

mkshinitramfs [-o|O: <Initramfs CPIO image with switch option to HDD(/dev/sda1)>]

mkshinitramfs [-s|S: <Initramfs CPIO image with shell on Initramfs>]

mkshinitramfs [-p|P: <target rootfs path> | default: /opt/STM/STLinux-2.3/devkit/sh4/target/]

mkshinitramfs [-k|K: <SH kernel version> | default: 2.6.23\_stm23\_0121]

mkshinitramfs [-b|B: <used board> | default: mb442 (STi710x based board)]

mkshinitramfs must be executed as "root" on the host machine in which a full target root

filesystem has previously been installed. It is configured to use default parameters,

as listed in the output from the -h option. To change any of the parameters, apply the

command line options listed in the help.

The tool mkshinitramfs creates a short initramfs. If invoked with the -s option, the

generated initramfs is the final rootfs. If invoked with the -o option, the generated

initramfs is a temporary rootfs to be switched to the real one on the HDD.

The script mkshinitramfs internally defines some variables that are useful when defining

which files, libraries, scripts and tools are to be placed on the initramfs image.

The variables are:

$DIRS

$BINFILES

$SBINFILES

$ETCFILES1

$USRBINFILES

Version 1.0 of the mkshinitramfs tool can be downloaded from mkshinitramfs tool as a

compressed tar.gz file.

If the initramfs rootfs is created to be used temporarily before switching to the real

target rootfs on a hard disk drive, a setup script is needed, which is then passed to

the chroot in order to setup the final real rootfs properly. This script loads the user

space services needed at runtime, such as klogd, udev, D-Bus, and so forth.

If the -o option is used, mkshinitramfs generates a CPIO image in which the following

command line is inserted after the kernel mounts the initramfs:

mount /dev/sda1 /mnt

chroot /mnt /etc/init.d/rcS-initramfs

**Installing and configuring Docker containers**

**Scale and deployment considerations**

**Just write your applications properly: simple, right?**

**Oops: What to do if there’s a gigantic breach**

**Planned features**

Local state rollback support, a few more crypto algs

**Out of town, call collect**

**Acknowledgements**

**References**

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**[2] CloudProxy Source code,** <http://github.com/jlmucb/cloudproxy>. Kevin Walsh and Tom Roeder were principal authors of the Go version.

**[3] TCG, TPM specs,** <http://www.trustedcomputinggroup.org/resources/tpm_library_specification>

**[4]** **Beekman, Manferdelli, Wagner,** Attestation Transparency: Building secure Internet services for legacy clients**.** AsiaCCS, 2016.

**[5]** Manferdelli, CloudProxy Nuts and Bolts.

[6] Intel, The MLE Development Guide

**Supported Hardware**

**Dmcrypt**

fdisk to make partitions (/dev/sda)

mkfs.ext2 to make file system

change to single user mode

grub-install root-directory=/dev/sda

CRYPTDISKS\_ENABLE=Yes in /etc/defaults/cryptdisks

/etc/crypttab

swap /dev/hda1 /dev/urandom swap

/etc/fstab

/dev/swapper/swap none

swap sw,pri=1 0 0

For swap:

swapoff -a

cryptsetup [-c aes -h sha256] -s 128 -d /dev/urandom create swap /dev/sda1

mkswap /dev/mapper/swap

swapon /dev/mapper/swap

Shell script prototype

#

# For debian, first do the following:

#

# Change to single user mode

# cat /proc/swaps (to find out swap device)

# /sbin/runlevel (to find runlevel)

# /sbin/telinit 1 (to go single user)

# ctrl-alt-f7 puts Linux into console mode.

#

# /etc/defaults/cryptdisks

# CRYPTDISKS\_ENABLE=Yes

# /etc/crypttab

# swap /dev/sda5 /dev/urandom swap

# /etc/fstab

# /dev/mapper/swap none

# swap sw,pri=1 0 0

# /etc/crypttab

# swap /dev/sda5 /dev/urandom cipher=aes-cbc-essiv:sha256,size=256,hash=sha256,swap

# /etc/fstab

# /dev/mapper/cryptoswap none swap sw 0 0

#

# /dev/sda5 is swap device

#

# Ref: The whole disk Nov, 2006, Linux-magazine.com, Michael Nerb

#

swapoff -a

cryptsetup -c aes -h sha256 -s 128 -d /dev/urandom create swap /dev/sda5

mkswap /dev/mapper/swap

swapon /dev/mapper/swap

#

# To remove:

# swapoff /dev/mapper/swap

# cryptsetup [luks] remove swap

**Grub**

**Initram script**

mkdir initramfs{,-old}

cd initramfs

gunzip -c -9 /boot/initrd.img-2.6.32-5-686 \

| cpio -i -d -H newc --no-absolute-filenames

find > ../initramfs.content

cd ../initramfs-old

gunzip -c -9 /boot/initrd.img-2.6.32-5-686.bak \

| cpio -i -d -H newc --no-absolute-filenames

find > ../initramfs-old.content

cd ..

diff -u initramfs-old.content initramfs.content

A sample init that dynamically loads the driver (don't do this) is:

1 Decompress initrd into localdirectory

2 Copy needed drivers in /drvs directory

3 Copy fileProxy/fileClient/tcService binaries in /bin directory and required libraries in

lib and lib64 directories

4 Copied keys to /bin/HWRoot directory

5 Replaced init with my custom init

6 Loaded tcioDD

7 Configured Ethernet

8 Script does not boot all services

9 Package initramfs.igz

10 Copy to /boot

11 Modify entry for OS Tboot section in grub.cfg. replaced initrd by initramfs.igz

12 Reboot machine

13 From cmd line type : /bin/tcService.exe –directory /bin/ &

14 tcService connected to keynegoServer on different machine.

#---start

#!/bin/sh

echo "Test CloudProxy minimal boot environment!"

[ -d /dev ] || mkdir -m 0755 /dev

[ -d /root ] || mkdir -m 0700 /root

[ -d /sys ] || mkdir /sys

[ -d /proc ] || mkdir /proc

[ -d /tmp ] || mkdir /tmp

mkdir -p /proc/net/dev

mkdir -p /var/lock

mount -t sysfs -o nodev,noexec,nosuid sysfs /sys

# Function for dropping to a shell

shell () {

/bin/busybox sh

}

# Basic /dev content, we need it as fast as possible.

mount -t tmpfs dev /dev

mount -t proc proc /proc

test -c /dev/null || mknod /dev/null c 1 3

test -c /dev//tty || mknod /dev/tty c 5 0

test -c /dev/urandom || mknod /dev/urandom c 1 9

test -c /dev/random || mknod /dev/random c 1 8

test -c /dev/zero || mknod /dev/zero c 1 5

test -c /dev/tpm0 || mknod /dev/tpm0 c 10 224

test -c /dev/tcioDD0 || mknod /dev/tcioDD0 c 100 0

#insmod /drvs/tpm\_tis.ko

insmod /drvs/tcioDD.ko

echo "loaded tcioDD drivers..."

insmod /drvs/e1000e.ko

/sbin/ifconfig eth0 192.168.241.11

/sbin/route add default gw 192.168.241.10

/bin/busybox sh

# Clean up.

umount /proc

umount /sys

# Not booting to the real thing at this time.

#---end

Standard initramfs init file:

#!/bin/sh

[ -d /dev ] || mkdir -m 0755 /dev

[ -d /root ] || mkdir -m 0700 /root

[ -d /sys ] || mkdir /sys

[ -d /proc ] || mkdir /proc

[ -d /tmp ] || mkdir /tmp

mkdir -p /var/lock

mount -t sysfs -o nodev,noexec,nosuid sysfs /sys

mount -t proc -o nodev,noexec,nosuid proc /proc

# Some things don't work properly without /etc/mtab.

ln -sf /proc/mounts /etc/mtab

grep -q '\<quiet\>' /proc/cmdline || echo "Loading, please wait..."

# Note that this only becomes /dev on the real filesystem if udev's scripts

# are used; which they will be, but it's worth pointing out

if ! mount -t devtmpfs -o mode=0755 udev /dev; then

echo "W: devtmpfs not available, falling back to tmpfs for /dev"

mount -t tmpfs -o mode=0755 udev /dev

[ -e /dev/console ] || mknod -m 0600 /dev/console c 5 1

[ -e /dev/null ] || mknod /dev/null c 1 3

fi

mkdir /dev/pts

mount -t devpts -o noexec,nosuid,gid=5,mode=0620 devpts /dev/pts || true

mount -t tmpfs -o "nosuid,size=20%,mode=0755" tmpfs /run

mkdir /run/initramfs

# compatibility symlink for the pre-oneiric locations

ln -s /run/initramfs /dev/.initramfs

# Export the dpkg architecture

export DPKG\_ARCH=

. /conf/arch.conf

# Set modprobe env

export MODPROBE\_OPTIONS="-qb"

# Export relevant variables

export ROOT=

export ROOTDELAY=

export ROOTFLAGS=

export ROOTFSTYPE=

export IP=

export BOOT=

export BOOTIF=

export UBIMTD=

export break=

export init=/sbin/init

export quiet=n

export readonly=y

export rootmnt=/root

export debug=

export panic=

export blacklist=

export resume=

export resume\_offset=

export recovery=

# mdadm needs hostname to be set. This has to be done before the udev rules are called!

if [ -f "/etc/hostname" ]; then

/bin/hostname -b -F /etc/hostname 2>&1 1>/dev/null

fi

# Bring in the main config

. /conf/initramfs.conf

for conf in conf/conf.d/\*; do

[ -f ${conf} ] && . ${conf}

done

. /scripts/functions

# Parse command line options

for x in $(cat /proc/cmdline); do

case $x in

init=\*)

init=${x#init=}

;;

root=\*)

ROOT=${x#root=}

case $ROOT in

LABEL=\*)

ROOT="${ROOT#LABEL=}"

# support any / in LABEL= path (escape to \x2f)

case "${ROOT}" in

\*/\*)

if command -v sed >/dev/null 2>&1; then

ROOT="$(echo ${ROOT} | sed 's,/,\\x2f,g')"

else

if [ "${ROOT}" != "${ROOT#/}" ]; then

ROOT="\x2f${ROOT#/}"

fi

if [ "${ROOT}" != "${ROOT%/}" ]; then

ROOT="${ROOT%/}\x2f"

fi

IFS='/'

newroot=

for s in $ROOT; do

newroot="${newroot:+${newroot}\\x2f}${s}"

done

unset IFS

ROOT="${newroot}"

fi

esac

ROOT="/dev/disk/by-label/${ROOT}"

;;

UUID=\*)

ROOT="/dev/disk/by-uuid/${ROOT#UUID=}"

;;

/dev/nfs)

[ -z "${BOOT}" ] && BOOT=nfs

;;

esac

;;

rootflags=\*)

ROOTFLAGS="-o ${x#rootflags=}"

;;

rootfstype=\*)

ROOTFSTYPE="${x#rootfstype=}"

;;

rootdelay=\*)

ROOTDELAY="${x#rootdelay=}"

case ${ROOTDELAY} in

\*[![:digit:].]\*)

ROOTDELAY=

;;

esac

;;

resumedelay=\*)

RESUMEDELAY="${x#resumedelay=}"

;;

loop=\*)

LOOP="${x#loop=}"

;;

loopflags=\*)

LOOPFLAGS="-o ${x#loopflags=}"

;;

loopfstype=\*)

LOOPFSTYPE="${x#loopfstype=}"

;;

cryptopts=\*)

cryptopts="${x#cryptopts=}"

;;

nfsroot=\*)

NFSROOT="${x#nfsroot=}"

;;

netboot=\*)

NETBOOT="${x#netboot=}"

;;

ip=\*)

IP="${x#ip=}"

;;

boot=\*)

BOOT=${x#boot=}

;;

ubi.mtd=\*)

UBIMTD=${x#ubi.mtd=}

;;

resume=\*)

RESUME="${x#resume=}"

;;

resume\_offset=\*)

resume\_offset="${x#resume\_offset=}"

;;

noresume)

noresume=y

;;

panic=\*)

panic="${x#panic=}"

case ${panic} in

\*[![:digit:].]\*)

panic=

;;

esac

;;

quiet)

quiet=y

;;

ro)

readonly=y

;;

rw)

readonly=n

;;

debug)

debug=y

quiet=n

exec >/run/initramfs/initramfs.debug 2>&1

set -x

;;

debug=\*)

debug=y

quiet=n

set -x

;;

break=\*)

break=${x#break=}

;;

break)

break=premount

;;

blacklist=\*)

blacklist=${x#blacklist=}

;;

netconsole=\*)

netconsole=${x#netconsole=}

;;

BOOTIF=\*)

BOOTIF=${x#BOOTIF=}

;;

hwaddr=\*)

BOOTIF=${x#BOOTIF=}

;;

recovery)

recovery=y

;;

esac

done

if [ -n "${noresume}" ]; then

export noresume

unset resume

else

resume=${RESUME:-}

fi

maybe\_break top

# export BOOT variable value for compcache,

# so we know if we run from casper

export BOOT

# Don't do log messages here to avoid confusing graphical boots

run\_scripts /scripts/init-top

maybe\_break modules

[ "$quiet" != "y" ] && log\_begin\_msg "Loading essential drivers"

load\_modules

[ "$quiet" != "y" ] && log\_end\_msg

[ -n "${netconsole}" ] && modprobe netconsole netconsole="${netconsole}"

maybe\_break premount

[ "$quiet" != "y" ] && log\_begin\_msg "Running /scripts/init-premount"

run\_scripts /scripts/init-premount

[ "$quiet" != "y" ] && log\_end\_msg

maybe\_break mount

log\_begin\_msg "Mounting root file system"

. /scripts/${BOOT}

parse\_numeric ${ROOT}

maybe\_break mountroot

mountroot

log\_end\_msg

maybe\_break bottom

[ "$quiet" != "y" ] && log\_begin\_msg "Running /scripts/init-bottom"

run\_scripts /scripts/init-bottom

[ "$quiet" != "y" ] && log\_end\_msg

# Preserve information on old systems without /run on the rootfs

if [ -d ${rootmnt}/run ]; then

mount -n -o move /run ${rootmnt}/run

else

# The initramfs udev database must be migrated:

if [ -d /run/udev ] && [ ! -d /dev/.udev ]; then

mv /run/udev /dev/.udev

fi

# The initramfs debug info must be migrated:

if [ -d /run/initramfs ] && [ ! -d /dev/.initramfs ]; then

mv /run/initramfs /dev/.initramfs

fi

umount /run

fi

# Move virtual filesystems over to the real filesystem

mount -n -o move /sys ${rootmnt}/sys

mount -n -o move /proc ${rootmnt}/proc

validate\_init() {

checktarget="${1}"

# Work around absolute symlinks

if [ -d "${rootmnt}" ] && [ -h "${rootmnt}${checktarget}" ]; then

case $(readlink "${rootmnt}${checktarget}") in /\*)

checktarget="$(chroot ${rootmnt} readlink ${checktarget})"

;;

esac

fi

# Make sure the specified init can be executed

if [ ! -x "${rootmnt}${checktarget}" ]; then

return 1

fi

# Upstart uses /etc/init as configuration directory :-/

if [ -d "${rootmnt}${checktarget}" ]; then

return 1

fi

}

# Check init bootarg

if [ -n "${init}" ]; then

if ! validate\_init "$init"; then

echo "Target filesystem doesn't have requested ${init}."

init=

fi

fi

# Common case: /sbin/init is present

if [ ! -x "${rootmnt}/sbin/init" ]; then

# ... if it's not available search for valid init

if [ -z "${init}" ] ; then

for inittest in /sbin/init /etc/init /bin/init /bin/sh; do

if validate\_init "${inittest}"; then

init="$inittest"

break

fi

done

fi

# No init on rootmount

if ! validate\_init "${init}" ; then

panic "No init found. Try passing init= bootarg."

fi

fi

maybe\_break init

# don't leak too much of env - some init(8) don't clear it

# (keep init, rootmnt)

unset debug

unset MODPROBE\_OPTIONS

unset DPKG\_ARCH

unset ROOTFLAGS

unset ROOTFSTYPE

unset ROOTDELAY

unset ROOT

unset IP

unset BOOT

unset BOOTIF

unset UBIMTD

unset blacklist

unset break

unset noresume

unset panic

unset quiet

unset readonly

unset resume

unset resume\_offset

# Chain to real filesystem

exec run-init ${rootmnt} ${init} "$@" ${recovery:+--startup-event=recovery} <${rootmnt}/dev/console >${rootmnt}/dev/console 2>&1

panic "Could not execute run-init."

Wrong:

gunzip initrd.gz

cpio -iv < initrd

From http://reboot.pro/topic/14547-linux-load-your-root-partition-to-ram-and-boot-it/

his tutorial will guide you through the steps to modify your initramfs to load all files from / to a tmpfs. This will only work with Debian 5 or newer and Ubuntu 9 ? or any unix thats supports booting from a initramfs. Since this is a virtual filesystem in RAM, not a virtual harddisk, this has many advantages.

What you need:

\* lots of RAM

\* Debian based distribution or any that supports booting from initramfs

\* mkinitramfs or a tool to build a new initramfs

\* some linux knowledge

\* no need to create an image

\* no need for Grub4Dos

\* no need for a "special driver"

Step 1:

Choose a distribution thats supports booting from initramfs. (like ubuntu)

Step 2:

Install to harddisk. Make sure you split it into multiple partitions (/, /boot, /home, swap, ...).

Step 3:

Boot your new system, install updates, drivers if neccessary (this will improve performance), strip it down to the minimum. Every file will be loaded to RAM ! A fresh install uses about 2 GB auf harddisk-space.

Step 4:

modify /etc/fstab :

\* make a backup

cp /etc/fstab /etc/fstab.bak\* find the line specifing the root partition and change it in:

none / tmpfs defaults 0 0\* save

Step 5:

edit the local script in your initramfs:

cd /usr/share/initramfs-tools/scripts/\* make a backup of /usr/share/initramfs-tools/scripts/local

cp local local.bak\* modify local, find this line:

# FIXME This has no error checking

# Mount root

mount ${roflag} -t ${FSTYPE} ${ROOTFLAGS} ${ROOT} ${rootmnt}\* change it to:

# FIXME This has no error checking

# Mount root

#mount ${roflag} -t ${FSTYPE} ${ROOTFLAGS} ${ROOT} ${rootmnt}

mkdir /ramboottmp

mount ${roflag} -t ${FSTYPE} ${ROOTFLAGS} ${ROOT} /ramboottmp

mount -t tmpfs -o size=100% none ${rootmnt}

cd ${rootmnt}

cp -rfa /ramboottmp/\* ${rootmnt}

umount /ramboottmp

\* save

\* execute, or rebuild initramfs

mkinitramfs -o /boot/initrd.img-ramboot\* replace modified local with original file

cp -f local.bak localStep 6:

\* modify this file (needs a better solution)

/boot/grub/grub.cfg\* copy the first boot entry and replace the /initrd line with this:

/initrd /initrd.img-ramdisk\* label the new entrie as RAMBOOT

This will boot our generated initramfs instead the original one.

Step 7:

\* reboot

\* choose standart boot (no ramdisk)

\* choose RAMBOOT and all your files on the root partition will be loaded to a tmpf

You have 2 possibilities for creating such a file. Allocate the disk space needed by the .img file directly. In this case the file will have a size of 4 GBytes.

dd if=/dev/zero of=disk01.img bs=1G count=4

Create an .img file with a maximal size but the disk space will only be allocated when needed. In this case, the maximum size will be 10 GBytes, but the disk space used will be the space required by the files in the vm.

qemu-img create -f qcow2 disk01.img 10G

Next, we need an ISO file of the system you want to install. Make sure you have downloaded on onto your server.

Let's install the virtual machine. When you don't have physical access to the server, start the installation with the VNC option. So you can connect to the VNC session and you will have the GUI from the installer. In this case we will set the RAM size of the vm to 512 MBytes. At the moment the vm doesn't have access to the network interface. I prefer activating it later, after configuring IP Addresses of the vm.

kvm -hda disk01.img -cdrom os.iso -m 512 -boot d -vnc IP:1

Now you can connect to IP:1 with a VNC client. You can configure your system and network settings at this point. Don't forget to install a SSH Server. After configuring, shut down the vm.

Now we are going to start the vm with networking support. We assign a MAC-Address to the vm network interfaces. This is important if you use more than 1 vm. Every vm will get its MAC-Address.

kvm -hda disk01.img -m 512 -boot c -net nic,vlan=0,macaddr=00:16:3e:00:00:01 -net tap -nographic -daemonize

After some seconds you should be able to connect via ssh to the vm. If not, you can add the -vnc option to check if there are problems.

I had the problem that I couldn't reach my vm over the network after some time. I had to add a different network card emulation to the start command. This solved my problem.

kvm -hda disk01.img -m 512 -boot c -net nic,vlan=0,macaddr=00:16:3e:00:00:01,model=rtl8139 -net tap -nographic -daemonize

If you have the problem that your configured network interface isn't starting, delete the following file (depending on your os):

/etc/udev/rules.d/70-persistent-net.rules

or

/etc/udev/rules.d/z25-persistent-net.rules

You also have the possibility to add more virtual disks to one vm. You can add the following parameter to the start command:

-hdb disk02.img

You can add more virtual machines if you need so. You could also create start scripts for your vms.

1. John is [manferdelli@google.com](mailto:manferdelli@google.com) or [jlmucbmath@gmail.com](mailto:jlmucbmath@gmail.com). Cloudproxy is based on work with Tom Roeder ([tmroeder@google.com](mailto:tmroeder@google.com)) and Kevin Walsh(kevin.walsh@holycross.edu). [↑](#footnote-ref-1)