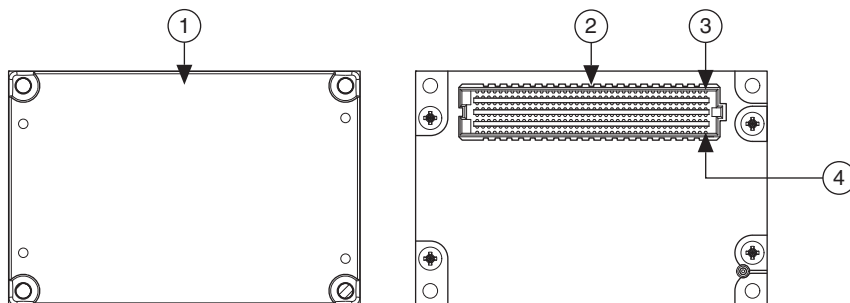


# SPECIFICATIONS

# NI sbRIO-9651

System on Module OEM Device

**Figure 1.** sbRIO-9651 SOM



- 1 Heat Spreader
- 2 J1 8 × 40 320-pin Connector

- 3 Pin 8
- 4 Pin 1

The NI sbRIO-9651 System on Module (SOM) provides an embedded real-time processor and reconfigurable FPGA. The sbRIO-9651 SOM requires a user-designed carrier board to provide power and I/O interfaces. You can optimize the carrier board to implement the exact functions your application requires. You can design the carrier board size and connector locations to fit the packaging or enclosure of your specific system.

This document provides dimensions, pinout information, functional specifications, and electrical specifications for the sbRIO-9651 SOM. The specifications listed in this document are typical for the -40 °C to 85 °C local ambient operating temperature range unless otherwise noted.



**Note** Refer to the documents listed in the [Additional Documentation Resources](#) section of this document for more information as you design, prototype, and implement your sbRIO-9651 SOM application. In particular, refer to the *NI sbRIO-9651 System on Module Carrier Board Design Guide* for detailed information about carrier board design techniques, guidelines, and requirements.

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## Part Numbers and Accessories

Table 1 lists purchasable sbRIO-9651 SOM kits and important accessories.

**Table 1.** sbRIO-9651 SOM Part Numbers and Accessories

Component	Manufacturer, Part Number
Kits	
sbRIO-9651 SOM Development Kit	NI, 783525-01
sbRIO-9651 OEM Kit	NI, 783525-02
Accessories	
M3 × 7.15 mm (0.281 in.) stainless standoffs, male-female, nylon threadlock	NI, 157543-020 (20 pieces) NI, 157543-500 (500 pieces)
Heat sink*	AlphaNovatech, S01LZZ0E-A
* The sbRIO-9651 SOM development kit includes a heat sink.	

# Selecting an Appropriate Mating Connector

The J1 connector on the sbRIO-9651 SOM is a Molex 45971-4185 320-pin, 8 × 40 position, SEARAY open-pin-field-array connector. To interface with the J1 connector, your carrier board design must implement a mating connector that is compatible with the Molex 45971 series or Samtec SEAF series. Table 2 lists compatible mating connectors, such as the Molex 45970 series or Samtec SEAM series.



**Note** Refer to the *NI sbRIO-9651 System on Module Carrier Board Design Guide* for more information about implementing a mating connector.

**Table 2.** sbRIO-9651 SOM Connector and Compatible Mating Connectors

Connector	Manufacturer, Part Number
sbRIO-9651 SOM J1 connector	Molex, 45971-4185 (equivalent to Samtec SEAF-40-05.0-S-08-2-A-K-TR)
Recommended mating connector*	Molex, 45970-4130
Alternative 7-mm stack height mating connectors	Molex, 45970-4185 Samtec, SEAM-40-02.0-S-08-2-A-K-TR
* Compatible connectors are available in multiple stack height and termination options. NI has secured a special Molex connector part number, 45970-4130, with a 7-mm mated pair stack height. The recommended connector is distributed through TTI, Inc. at NI-negotiated pricing and with shortened lead times. Contact TTI, Inc. directly to obtain the negotiated pricing. Online pricing might not reflect negotiated pricing. Consult Molex or Samtec for alternative stack heights and terminations.	

## Selecting Appropriate Standoffs

The Molex 45970 series and Samtec SEAM series connectors are available in multiple heights. The height of the mating connector you select determines the height of the standoffs you need.

To prevent over-insertion, the SEARAY connector design requires that standoffs never be less than the stack height. Because standard nominal tolerances might result in a standoff being shorter than the stack height, NI requires that you use standoffs that are 0.15 mm (0.006 in.) taller than the combined height of the J1 connector on the sbRIO-9651 SOM and the mating SEARAY connector. Therefore, to determine the required standoff height, you must add the heights of the mated connectors plus an additional 0.15 mm (0.006 in.). Refer to Samtec documentation for more information about SEARAY standoff requirements.

Table 3 provides an example standoff height calculation using a Molex 45970-4130 mating connector.

**Table 3.** Example Connector Configuration and Calculated Standoff Height

Component	Manufacturer, Part Number	Height
J1 connector on the sbRIO-9651 SOM	Molex, 45971-4185	5.00 mm (0.197 in.)
Mating connector	Molex, 45970-4130	2.00 mm (0.079 in.)
Required additional standoff height	—	0.15 mm (0.006 in.)
<b>Total calculated standoff height</b>	—	<b>7.15 mm (0.281 in.)</b>

Standoffs of 7.15 mm (0.281 in.) height are available from NI and listed in Table 1. Consult Molex or Samtec for alternative heights and options. You must observe keepouts and maximum heights with all connector combinations.

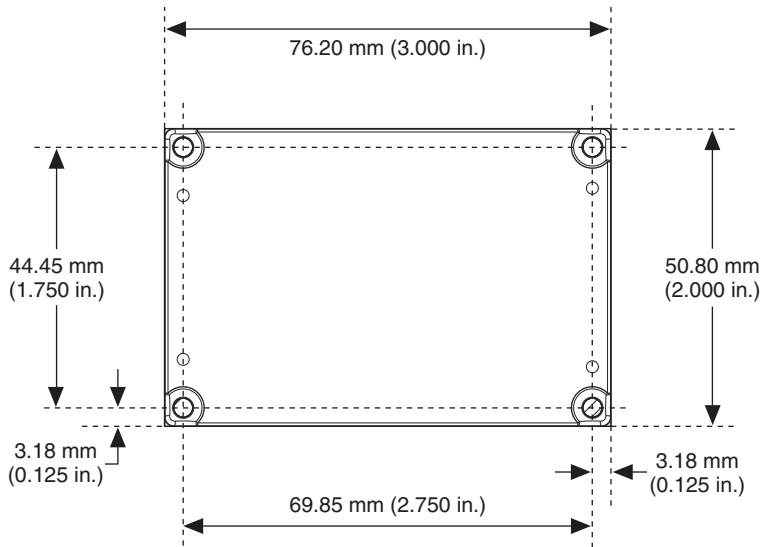
## Dimensions

Figures 2 through 4 show the physical dimensions of the sbRIO-9651 SOM.

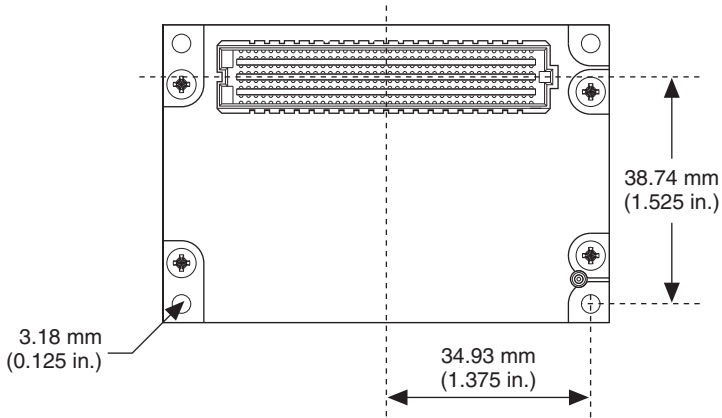


**Note** For two-dimensional drawings and three-dimensional models, visit [ni.com/dimensions](https://ni.com/dimensions) and search for 9651.

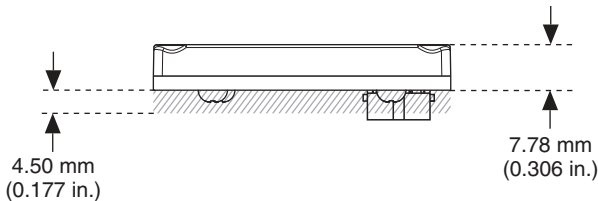
**Figure 2.** sbRIO-9651 SOM Top View with Dimensions



**Figure 3.** sbRIO-9651 SOM Bottom View with Dimensions



**Figure 4.** sbRIO-9651 SOM Side View with Dimensions



**Note** Do not place components other than the SEARAY connector and mounting standoffs within 4.5 mm (0.177 in.) of the secondary-side printed circuit board surface. This keepout allows components on the sbRIO-9651 SOM to be up to 2.5 mm (0.098 in.) tall and provides a 2 mm (0.079 in.) air gap to prevent electrical shorting. The maximum component height for your carrier board in the area below the sbRIO-9651 SOM is the total SEARAY stack height less 4.5 mm (0.177 in.).

## Software Requirements

Install or verify that you have installed the following software:

- LabVIEW 2014 or later
- LabVIEW Real-Time Module 2014 or later
- LabVIEW FPGA Module 2014 or later
- NI-RIO Device Drivers August 2014 or later

# Functional Specifications

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## Processor

Type.....	Xilinx Zynq-7000, XC7Z020 All Programmable SoC
Architecture .....	ARM Cortex-A9
Speed.....	667 MHz
Cores .....	2
Operating system .....	NI Linux Real-Time (32-bit)
Nonvolatile memory .....	512 MB <sup>1</sup> , SLC NAND Flash
Volatile memory (DRAM) .....	512 MB, DDR3
Real-time clock	
Accuracy .....	5 ppm
Flash reboot endurance .....	100,000 cycles <sup>2</sup>

For information about the life span of the nonvolatile memory and about best practices for using nonvolatile memory, visit [ni.com/info](http://ni.com/info) and enter the Info Code SSDBP.

## Reconfigurable FPGA

Type.....	Xilinx Zynq-7000, XC7Z020 All Programmable SoC
Number of logic cells.....	85,000
Number of flip-flops .....	106,400
Number of 6-input LUTs .....	53,200
Number of DSP slices (18 × 25 multipliers).....	220
Available block RAM .....	560 KB
Number of DMA channels.....	16
Number of logical interrupts.....	32

---

<sup>1</sup> Formatted capacity of nonvolatile memory may be slightly less than this value.

<sup>2</sup> You can increase the flash reboot endurance value by performing field maintenance on the device. If you expect that your application may exceed the maximum cycle count listed in this document, contact National Instruments support for information about how to increase the reboot endurance value.

# Fixed Behavior Signals

The J1 connector dedicates pins for the following fixed I/O signals:

- Primary Ethernet (GBE0) support
- UART/Console Out (Serial1) support
- USB (USB0 and USB1) support
- SDIO support

## Primary Ethernet (GBE0) Support



**Note** You must connect this interface to voltage-mode-PHY-compatible Ethernet magnetics. The *NI sbRIO-9651 System on Module Carrier Board Design Guide* provides design guidelines, requirements for routing signals, and recommendations for appropriate magnetics and connectors. The following specifications depend on a suitable carrier board design that follows these guidelines and requirements.

Network interface .....	10Base-T, 100Base-TX, 1000Base-T Ethernet
Compatibility .....	IEEE 802.3
Communication rates .....	10 Mbps, 100 Mbps, 1,000 Mbps auto-negotiated, half-/full-duplex

## Primary Ethernet LED Behavior

The J1 connector provides signals for implementing Ethernet LEDs on a carrier board.

The GBE0\_ACT\_LEDg signal indicates the link status and activity of the Ethernet connection, as described in Table 4

**Table 4.** Ethernet Link Activity LED Behavior

Link State	GBE0_ACT_LEDg Behavior
No link	Low
Link, but no activity	High
Link with activity	Toggling

The GBE0\_SPEED\_LEDg and GBE0\_SPEED\_LEDy signals indicate the link speed of the Ethernet connection, as described in Table 5.

**Table 5.** Ethernet Speed LED Behavior

Link Speed	GBE0_SPEED_LEDg*	GBE0_SPEED_LEDy*
No link	Low	Low
10Base-T	Low	Low

**Table 5.** Ethernet Speed LED Behavior (Continued)

Link Speed	GBE0_SPEED_LEDg*	GBE0_SPEED_LEDy*
100Base-TX	High	Low
1000Base-T	Low	High
* When enabled, GBE1 speed LEDs behave the same as GBE0 speed LEDs.		

## UART/Console Out (Serial1) Support



**Note** You must connect this interface to an appropriate RS-232 serial transceiver on your carrier board design. The *NI sbRIO-9651 System on Module Carrier Board Design Guide* provides design guidelines, requirements for routing signals, and recommendations for a serial transceiver. The following specifications depend on a suitable carrier board design that follows these guidelines and requirements and utilizes the recommended or an equivalent transceiver.

Maximum baud rate ..... 230,400 bps  
Data bits ..... 5, 6, 7, 8  
Stop bits ..... 1, 2  
Parity ..... Odd, Even, Mark, Space  
Flow control ..... RTS/CTS, XON/XOFF, DTR/DSR, None<sup>1</sup>

### Console Out

When Console Out is enabled, the Serial1 interface functions as a console for the operating system. You can use a serial-port terminal program to read the IP address, read the firmware version, and access the console. Ensure that the serial-port terminal program is configured with the following settings:

- 115,200 bps
- Eight data bits
- No parity
- One stop bit
- No flow control

You can use Measurement & Automation Explorer (MAX) software or the SYS\_RST# signal to enable Console Out. Refer to the [SYS\\_RST#](#) section of this document for more information about how to enable Console Out.

<sup>1</sup> To enable hardware flow control and modem lines for the Serial1 interface, you must use the sbRIO CLIP Generator application. Refer to the *NI Single-Board RIO CLIP Generator Help*, described in the [Additional Documentation Resources](#) section of this document, for more information about using the sbRIO CLIP Generator application.



# USB (USB0 and USB1) Support



**Note** The *NI sbRIO-9651 System on Module Carrier Board Design Guide* provides design guidelines, requirements for routing signals, and recommendations for an appropriate connector. The following specifications depend on a suitable carrier board design that follows these guidelines and requirements.

Number of interfaces

USB Host/Device ..... 1 (USB0)

USB Host-only ..... 1 (USB1)

USB interface ..... USB 2.0, Hi-Speed

Maximum data rate ..... 480 Mb/s per interface

## Configuring the USB0 Mode

You can configure the USB0 interface to be a USB Host port or a USB Device port, as shown in Table 6. This mode is set when the system boots and does not change dynamically.



**Note** USB On-The-Go (OTG) is not supported.

**Table 6.** Configuring the USB0 Mode

Mode	How to Enable
USB Host	Connect the USB0_MODE signal to digital ground on your carrier board
USB Device	Connect the USB0_MODE signal to the VCC_3V3 rail on your carrier board

## SDIO Support



**Note** The *NI sbRIO-9651 System on Module Carrier Board Design Guide* provides design guidelines, requirements for routing signals, and recommendations for an appropriate connector. The following specifications depend on a suitable carrier board design that follows these guidelines and requirements.

Supported standards ..... SD, SDHC<sup>1</sup>

Throughput<sup>2</sup>

Read ..... 12.0 MB/s max

Write ..... 9.0 MB/s max

<sup>1</sup> Both standard SD and microSD interfaces are supported.

<sup>2</sup> Throughput was benchmarked using the NI 780246-01 2 GB SD card and the 783658-01 16 GB SDHC card. Similar performance is expected on other high-performance SD/SDHC cards. Throughput depends on the removable storage used. Refer to the manufacturer specifications for the removable storage you use for more information about the expected performance of your application.

# Support Signals

The J1 connector dedicates pins for the following fixed support signals:

- SYS\_RST#
- CARRIER\_RST#
- STATUS\_LED
- TEMP\_ALERT
- FPGA\_CFG
- DIO\_35\_PUDC



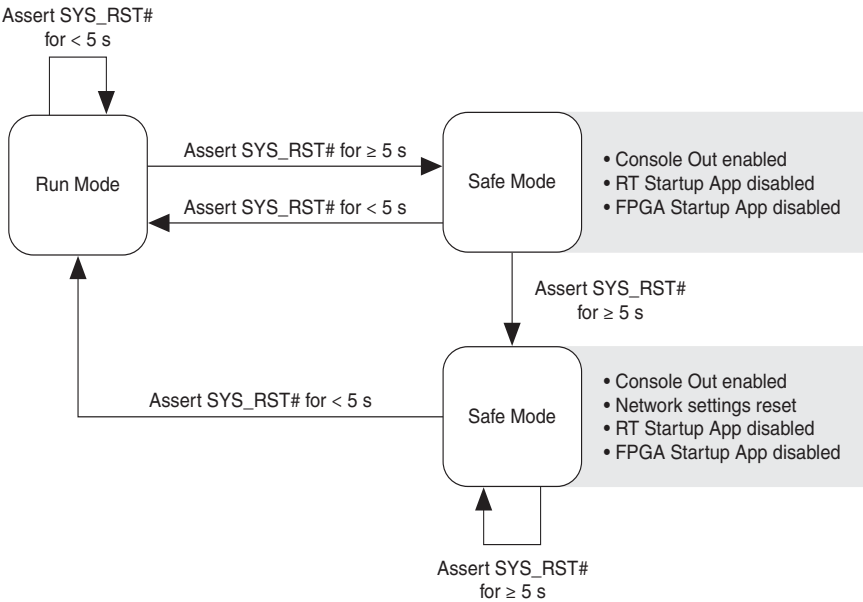
**Note** The # character at the end of a signal name indicates that the signal asserts low.

## SYS\_RST#

The SYS\_RST# signal is a system reset signal for resetting the sbRIO-9651 SOM processor and FPGA. Asserting this signal causes the CARRIER\_RST# signal to also assert. The SYS\_RST# signal asserts low.

The amount of time for which this signal asserts determines the specific reset behavior, as shown in Figure 5.

**Figure 5. SYS\_RST# Behavior**



The STATUS\_LED signal deasserts when the SYS\_RST# signal asserts and remains deasserted until either five seconds have elapsed or the SYS\_RST# signal deasserts. The STATUS\_LED signal remains asserted until the operating system on the sbRIO-9651 SOM processor has loaded. When the operating system has loaded, the STATUS\_LED signal follows one of the patterns described in Table 7.

You can assert the SYS\_RST# signal before you apply power to the sbRIO-9651 SOM. The sbRIO-9651 SOM remains in reset until the SYS\_RST# signal deasserts. If you assert the SYS\_RST# signal before power is applied, then you must deassert the SYS\_RST# signal within five seconds.

## Configuring Device Startup Options

You can configure device startup options in MAX by completing the following steps:

1. In the MAX configuration tree, select your device under **Remote Systems**.
2. Select the **System Settings** tab.
3. Configure the following options under **Startup Settings**:
  - Safe Mode
  - Console Out
  - Disable RT Startup App
  - Enable Secure Shell (SSH) Logins
  - Disable FPGA Startup App

Refer to the *Measurement & Automation Explorer Help* for more information about these settings.

## CARRIER\_RST#

The CARRIER\_RST# signal indicates that main power is inadequate or that the sbRIO-9651 SOM is in reset. Asserting the SYS\_RST# signal causes this signal to also assert. The CARRIER\_RST# signal asserts low.

You can use this signal to reset interfaces that must be initialized on the carrier board. Refer to the *NI sbRIO-9651 System on Module Carrier Board Design Guide* for more information.

# STATUS\_LED

The STATUS\_LED signal indicates the status of the sbRIO-9651 SOM boot process and Safe Mode state, as Table 7 describes. This signal asserts high.

**Table 7.** STATUS\_LED Patterns and Indications

LED Pattern	Indication
Off	The device is in Run Mode because software is installed and the operating system is running.
2	<p>The device is in Safe Mode because software is not installed, which is the factory default state, or software has been improperly installed on the device.</p> <p>An error can occur when an attempt to upgrade the software is interrupted. Reinstall software on the device. Refer to the <i>Measurement &amp; Automation Explorer Help</i> for information about installing software on the device.</p>
3	<p>The device is in user-directed Safe Mode, or the device is in Install Mode to indicate that software is currently being installed. The device enters user-directed Safe Mode when the SYS_RST# signal asserts for longer than five seconds or when you enable Safe Mode in MAX.</p> <p>Refer to the <i>Measurement &amp; Automation Explorer Help</i> for information about Safe Mode.</p>
4	The device is in Safe Mode because it has crashed twice without rebooting or cycling power between crashes. This usually indicates that the device has run out of memory or that your LabVIEW Real-Time application has crashed. Review your LabVIEW Real-Time application to resolve any memory leaks.
Continuously flashing	The device has detected an unrecoverable error. If possible, format the device. If the problem persists, contact National Instruments for support.
Solid	The device is currently booting. This pattern also indicates when the SYS_RST# signal has been asserted for longer than five seconds.

## TEMP\_ALERT

The TEMP\_ALERT signal indicates that the onboard CPU/FPGA or Primary System temperature has exceeded the minimum or maximum temperature specifications of the sbRIO-9651 SOM. This signal is asserted high. Refer to the [Environmental](#) section of this document for the minimum and maximum temperature specifications.



**Note** This signal is functional only when polling the TempReadings Property Node in LabVIEW Real-Time. This Property Node is part of the NI System Configuration API. The TEMP\_ALERT state updates only when you access the TempReadings Property Node. If your LabVIEW Real-Time application does not implement this functionality, the TEMP\_ALERT signal does not assert when an over- or under-temperature event occurs. Visit [ni.com/info](http://ni.com/info) and enter the Info Code `sbriosensors` for example code and more information about how to use the TEMP\_ALERT signal.

## FPGA\_CFG

The FPGA\_CFG signal indicates when the FPGA is configured. For the fixed behavior interfaces on the sbRIO-9651 SOM to function correctly, the FPGA must be configured with a bitfile. If you do not provide a user bitfile, the sbRIO-9651 SOM loads a default bitfile. The FPGA\_CFG signal asserts when a user bitfile or the default bitfile loads. This signal asserts high.

This signal is actively driven only when asserted. The sbRIO-9651 provides a pull-down to keep the signal low when deasserted.

## DIO\_35\_PUDC

The DIO\_35\_PUDC signal is an FPGA Digital I/O (DIO) that also sets the Pull-up During Configuration (PUDC) state on the FPGA. To ensure that the sbRIO-9651 SOM operates correctly, this signal must be high when the FPGA is not configured. The sbRIO-9651 SOM provides a pull-up on DIO\_35\_PUDC. This pin may be left disconnected on your carrier board.

NI recommends that you use this signal as an output without external pull-down resistors. If you use this signal as an input, you must ensure that the signal is high when the FPGA is not configured, including initial power on.

# User-Defined FPGA Signals

The J1 connector provides several banks of FPGA Digital I/O (DIO) pins that you configure for purposes specific to your application. You can use these signals to implement the following interfaces:

- Secondary Ethernet (GBE1) support
- Additional UART (Serial2 through Serial6) support
- CAN (CAN0 and CAN1) support
- FPGA DIO

## Secondary Ethernet (GBE1) Support



**Note** This interface is a GMII interface that. When you enable this interface, you must connect it to the NI-recommended Ethernet PHY. The *NI sbRIO-9651 System on Module Carrier Board Design Guide* provides design guidelines, requirements for routing signals, and recommendations for an appropriate Ethernet PHY, appropriate magnetics, and an appropriate connector. The following specifications depend on a suitable carrier board design that follows these guidelines and requirements.

Network interface .....	10Base-T, 100Base-TX, 1000Base-T Ethernet
Compatibility .....	IEEE 802.3
Communication rates .....	10 Mbps, 100 Mbps, 1,000 Mbps auto-negotiated, half-/full-duplex

## Secondary Ethernet LED Behavior

You can configure FPGA pins on the J1 connector to provide Ethernet speed LED signals for secondary Ethernet.

These signals have the same behavior as the Primary Ethernet speed LED signals. Refer to Table 5, *Ethernet Speed LED Behavior*, in the *Primary Ethernet LED Behavior* section of the *Primary Ethernet (GBE0) Support* section of this document for more information.

To implement an activity LED for secondary Ethernet, refer to the *NI sbRIO-9651 System on Module Carrier Board Design Guide*.

# Additional UART (Serial2 through Serial6) Support



**Note** You must connect each of these interfaces to an appropriate RS-232 or RS-485 serial transceiver on your carrier board design. The *NI sbRIO-9651 System on Module Carrier Board Design Guide* provides design guidelines, requirements for routing signals, and recommendations for a serial transceiver. The following specifications depend on a suitable carrier board design that follows these guidelines, requirements, and recommended or equivalent transceivers.

## Maximum number of interfaces

RS-232 .....	3 (Serial2, Serial3, Serial4) <sup>1</sup>
RS-485 .....	2 (Serial5, Serial6)

Maximum baud rate ..... 230,400 bps

Data bits ..... 5, 6, 7, 8

Stop bits ..... 1, 2

Parity..... Odd, Even, Mark, Space

RS-232 flow control ..... RTS/CTS, XON/XOFF, DTR/DSR, None

RS-485 flow control ..... XON/XOFF

RS-485 transmission modes ..... 2-wire, 2-wire auto, 4-wire

# CAN (CAN0 and CAN1) Support



**Note** You must connect this interface to an appropriate CAN transceiver on your carrier board design. The *NI sbRIO-9651 System on Module Carrier Board Design Guide* provides design guidelines, requirements for routing signals, and recommendations for a CAN transceiver. The following specifications depend on a suitable carrier board design that follows these guidelines and requirements and utilizes the recommended or an equivalent transceiver.

Maximum number of CAN interfaces ..... 2 (CAN0, CAN1)

## Baud rate

Maximum.....	1 Mbps
Minimum .....	10 kbps

<sup>1</sup> The maximum number of RS-232 interfaces does not include the Serial1 fixed behavior UART interface.

# FPGA DIO



**Note** Refer to the *NI sbRIO-9651 System on Module Carrier Board Design Guide* for information about FPGA DIO best practices.

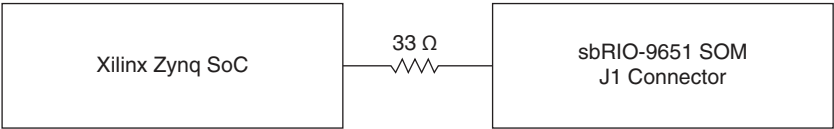
Total number of DIO channels.....	160
Number of DIO channels per bank	
Bank 0 .....	16 single-ended lines
Bank 1 .....	48 single-ended lines or 24 differential pairs
Bank 2 .....	48 single-ended lines or 24 differential pairs
Bank 3 .....	48 single-ended lines or 24 differential pairs
Characteristic impedance of DIO lines	
Bank 0 .....	50 $\Omega$
Bank 1, 2, and 3	
As single-ended lines .....	50 $\Omega$
As differential pairs.....	100 $\Omega$



**Note** Banks 1, 2, and 3 feature user-defined I/O voltage signaling levels. Your carrier board design must provide power for these lines on a per-bank basis at 3.3 V, 2.5 V, 1.8 V, 1.5 V, or 1.2 V signaling levels.

The DIO lines in Bank 0 are routed as single-ended traces. Figure 6 shows the circuitry of one 3.3 V DIO channel in Bank 0. The lines in Bank 0 include an onboard series termination resistor located at the Xilinx Zynq SoC.

**Figure 6.** 3.3 V DIO Channel in Bank 0



The DIO lines in Banks 1, 2, and 3 are routed as loosely coupled differential pairs from the Xilinx Zynq SoC to the J1 connector. Each DIO\_XX line has a corresponding negative pair, DIO\_XX\_N. You can configure each pair in the sbRIO CLIP Generator application to operate as differential pairs or single-ended signals. Figure 7 shows the circuitry of one DIO channel pair in Bank 1, 2, or 3.

**Figure 7.** DIO Channel Pair in Bank 1, 2, or 3

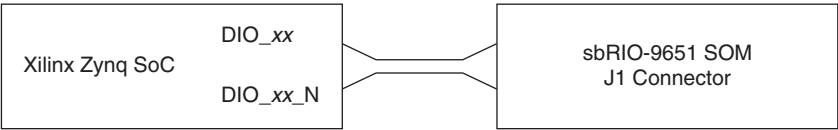




Table 8 lists the DIO pins on the J1 connector and the corresponding FPGA I/O banks, power rails, and the trace lengths on the sbRIO-9651 SOM for each group of pins.

**Table 8.** FPGA DIO Pins and Trace Lengths

Pins	FPGA I/O Bank	Power Rail	Shortest Trace Length on sbRIO-9651 SOM	Longest Trace Length on sbRIO-9651 SOM	Length Matching within Differential Pairs
DIO_0 ... DIO_15	Bank 0	VCC_3V3	31.24 mm (1.23 in.)	42.16 mm (1.66 in.)	—
DIO_16 ... DIO_39_SRCC DIO_16_N ... DIO_39_N	Bank 1	VIO_BANK1	33.78 mm (1.33 in.)	37.34 mm (1.47 in.)	0.25 mm (0.01 in.)
DIO_40 ... DIO_63_SRCC DIO_40_N ... DIO_63_N	Bank 2	VIO_BANK2	24.13 mm (0.95 in.)	26.42 mm (1.04 in.)	0.25 mm (0.01 in.)
DIO_64 ... DIO_87_SRCC DIO_64_N ... DIO_87_N	Bank 3	VIO_BANK3	28.70 mm (1.13 in.)	30.99 mm (1.22 in.)	0.25 mm (0.01 in.)

## FPGA DIO Clock Capabilities

Some FPGA DIO pins have the following FPGA clocking capabilities:

- **Single-region clock capable (SRCC)**—These pins provide a direct connection to the global clock distribution buffers in the FPGA. The pins also connect to the regional buffers on a specific bank of pins. Each SRCC pin has an `_SRCC` suffix in the pin name.
- **Multi-region clock capable (MRCC)**—These pins provide a direct connection to the global clock distribution buffers in the FPGA. The pins also connect to the regional and multi-regional buffers on a specific bank of pins. Each MRCC pin has an `_MRCC` suffix in the pin name.



**Note** When you import a clock into LabVIEW FPGA, NI recommends that you use SRCC or MRCC pins.

Refer to the Xilinx *7 Series FPGAs Clocking Resources User Guide*, UG472, for more information about clock-capable I/O.

## Ground Connections

The sbRIO-9651 SOM provides the following ground connections:

- The mounting holes and heat spreader are connected to chassis ground.
- All grounds on the J1 connector are connected to digital ground.
- Chassis ground is capacitively coupled to digital ground near each mounting hole.

Refer to the *NI sbRIO-9651 System on Module Carrier Board Design Guide* for more information about grounding best practices.

# Electrical Specifications

## Input Power Requirements

The sbRIO-9651 SOM requires multiple power supply rails, which are provided by the carrier board. Table 9 lists the power pin assignments on the J1 connector.

**Table 9.** Input Power Requirements

Input Rail	Minimum Voltage	Maximum Voltage	Nominal Voltage	Maximum Power	Bulk Capacitance*
VCC_3V3	3.201 V	3.465 V	3.3 V	7 W	370 μF
VIO_BANK1	Refer to footnote † of this table for information about these values.		1.2 V to 3.3 V†	900 mW	110 μF
VIO_BANK2			1.2 V to 3.3 V†	900 mW	110 μF
VIO_BANK3			1.2 V to 3.3 V†	900 mW	110 μF

\* The bulk capacitance specified is the onboard capacitance on each input power supply rail of the sbRIO-9651 SOM. This value is specified for consideration when designing power supplies on a carrier board.

† The nominal input voltage for each VIO\_BANK input rail can be 1.2 V, 1.5 V, 1.8 V, 2.5 V, or 3.3 V. The voltage you implement for a bank must match the requirements for the Xilinx I/O standard that have been assigned to the bank in the sbRIO CLIP Generator. Refer to the [Nominal Input Voltage Requirements](#) section of this document for minimum and maximum supply voltages for each Xilinx I/O standard.



**Note** These specifications approximate the maximum power requirement for each input rail on an sbRIO-9651 SOM with worst-case silicon manufacturing process and maximum junction temperatures. For a more accurate estimate of the power consumption for a specific application, NI recommends that you directly measure the power the sbRIO-9651 SOM consumes when running your application in an environment that is representative of the intended use case. You can use the Xilinx Power Estimator to calculate the VIO\_BANK input rail power for a given configuration.

# Nominal Input Voltage Requirements

Table 10 describes the tolerances for each nominal input voltage value for a VIO\_BANK input power supply rail.



**Note** Tolerances are based on -3% and +5% of the nominal input voltage.

**Table 10.** Nominal Input Voltage Tolerances

Nominal Input Voltage	Minimum Input Voltage	Maximum Input Voltage
3.3 V	3.201 V	3.465 V
2.5 V	2.425 V	2.625 V
1.8 V	1.746 V	1.890 V
1.5 V	1.455 V	1.575 V
1.2 V	1.164 V	1.260 V

## Power Sequencing Requirements

The recommended power-on sequence is to bring up the VIO\_BANK1 input rail before or at the same time as the VCC\_3V3 input rail. You can power the VIO\_BANK2 and VIO\_BANK3 input rails before or after the VCC 3V3 input rail. The power-off sequence is the opposite of the power-on sequence.

If any combination of the VCC\_3V3, VIO\_BANK1, VIO\_BANK2, or VIO\_BANK3 input rails have the same nominal voltage level, you can power them from the same supply and ramp them simultaneously.

Following the recommended power sequencing minimizes the current draw and eliminates glitches in I/O by ensuring that I/O pins are tri-stated during power-on.



**Note** For any VIO\_BANK input rail voltages of 3.3 V, NI recommends that you use the same power supply for the VIO\_BANK and VCC\_3V3 input rails. If you must use a separate 3.3 V power supply, then the voltage difference between the VIO\_BANK input rail and the VCC\_3V3 input rail must not exceed 2.625 V for more than 500 ms per power cycle. You can allocate the time in any percentage between the power-on and power-off ramps.

# Power Supply Ramp Times

Table 11 specifies the ramp times for each input power supply rail.

**Table 11.** Power Supply Ramp Times

Power Supply	Minimum Time	Maximum Time
VCC_3V3 ramp time from GND to 90% of VCC_3V3	0.2 ms	50.0 ms
VIO_BANK ramp time from GND to 90% of VIO_BANK	0.2 ms	50.0 ms

# Xilinx I/O Standards Nominal Voltage Requirements

Table 12 specifies the nominal voltage for each Xilinx I/O standard you can select for a VIO\_BANK input power supply rail in the sbRIO CLIP Generator.

**Table 12.** Xilinx I/O Standards Voltage Requirements

Xilinx I/O Standard	Nominal Voltage
LVTTL	3.3 V
LVCMOS33	3.3 V
LVCMOS25	2.5 V
LVCMOS18	1.8 V
LVCMOS15	1.5 V
LVCMOS12	1.2 V
LVDS_25	2.5 V
MINI_LVDS_25	2.5 V

# VBAT Requirements

The J1 connector provides a pin for VBAT power, which can be connected to a battery to power the real-time clock while the sbRIO-9651 SOM is unpowered.

Table 13 lists the VBAT power specifications.

**Table 13.** VBAT Power Specifications

Specification	Minimum	Typical	Maximum
VBAT input voltage	2.875 V	3.0 V	5.5 V
sbRIO-9651 SOM powered VBAT current	—	25 nA	100 nA
sbRIO-9651 SOM unpowered VBAT current	—	2.6 $\mu$ A average	4.2 $\mu$ A average

## FPGA Voltage Levels

### FPGA DIO Voltage Levels

Tables 14 and 15 describe the FPGA input and output voltage levels for each Xilinx I/O standard you can select for a DIO pin in the sbRIO CLIP Generator.



**Note** Refer to the *Xilinx Zynq-7000 All Programmable SoC (Z-7010, Z-7015, and Z-7020): DC and AC Switching Characteristics* product specification, DS187, for information about additional standards supported by the Zynq FPGA I/O.

**Table 14. FPGA I/O Levels (1 of 2)**

I/O Standard	Input Voltage Low, V <sub>IL</sub> (V)		Input Voltage High, V <sub>IH</sub> (V)		Output Voltage Low, V <sub>OL</sub> Max (V)	Output Voltage High, V <sub>OH</sub> Min (V)	Drive Strength (mA)
	Min	Max	Min	Max			
LVTTL	-0.30	0.80	2.00	3.45	0.40	2.40	4, 8, 12, 16, 24
LVC MOS33	-0.30	0.80	2.00	3.45	0.40	VIO - 0.40	4, 8, 12, 16
LVC MOS25	-0.30	0.70	1.70	VIO + 0.30	0.40	VIO - 0.40	4, 8, 12, 16
LVC MOS18	-0.30	35% of VIO	65% of VIO	VIO + 0.30	0.45	VIO - 0.45	4, 8, 12, 16, 24
LVC MOS15	-0.30	35% of VIO	65% of VIO	VIO + 0.30	25% of VIO	75% of VIO	4, 8, 12, 16
LVC MOS12	-0.30	35% of VIO	65% of VIO	VIO + 0.30	0.40	VIO - 0.40	4, 8, 12

### Table 15. FPGA I/O Levels (2 of 2)

[illegible]

# Fixed Behavior Signal I/O Levels

Tables 16 and 17 describe the FPGA input and output voltage levels, respectively, for fixed behavior signals.

**Table 16.** Fixed Behavior Signal Input Voltages

Signal	V <sub>IL</sub> (V)		V <sub>IH</sub> (V)	
	Min	Max	Min	Max
USB0_MODE	-0.30	0.40	2.50	3.60
USB0_VBUS	-0.30	0.20	4.75	5.50
SD_CMD SD_D0 ... SD_D3 SD_CD# SD_WP SYS_RST# SERIAL1_RX	-0.30	0.80	2.00	3.45

**Table 17.** Fixed Behavior Signal Output Voltages

Signal	V <sub>OL</sub> Max (V)	V <sub>OH</sub> Min (V)	Max Sink Current (mA)	Max Source Current (mA)
GBE0_SPEED_LEDg GBE0_SPEED_LEDy USB0_CPEN SD_D0 ... SD_D3 SD_CMD SD_CLK SD_PWR_EN CARRIER_RST# STATUS_LED TEMP_ALERT SERIAL1_RX	0.400	2.735	8	-8
FPGA_CFG	Not actively driven low. Pull-down on signal.	2.735	—	-8



Table 18 lists the signals that provide pull resistors.

**Table 18.** Signals with Pull Resistors

Signal	Pull Value Typ ( $\Omega$ )	Pull Resistor Rail
CARRIER_RST#	1.0 k	GND
SD_PWR_EN FPGA_CFG	4.7 k	GND
SYS_RST# SD_CD# SD_WP	4.7 k	VCC_3V3
USB0_MODE	100.0 k	VCC_3V3
DIO_35_PUDC	4.7 k	VIO_BANK1

# Physical Characteristics

Board dimensions ..... 50.8 mm (2.0 in.) × 76.2 mm (3.0 in.)

Weight..... 77 g (2.72 oz)

## Mounting

Fastener torque ..... 0.76 N · m (6.70 lb · in.)

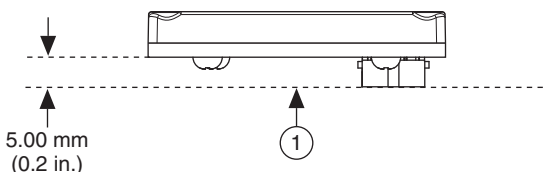
# Environmental

The sbRIO-9651 SOM includes three onboard temperature monitoring sensors to simplify validation of a thermal solution. The sensors measure the internal system temperature under the heat spreader, the junction temperature of the CPU/FPGA, and a secondary-side printed circuit board temperature. The sensors provide an indication of thermal performance and are used to validate the system along with the local ambient operating temperature.

Local ambient operating temperature near device  
(IEC 60068-2-1, IEC 60068-2-2) ..... -40 °C to 85 °C

The primary option for measuring the local ambient operating temperature is to place a thermocouple in the location shown in Figure 8.

**Figure 8.** Measuring the Local Ambient Operating Temperature



1 Measure local ambient operating temperature here.



**Note** Measure the local ambient temperature by placing a thermocouple near the center of the printed circuit board 5.0 mm (0.2 in.) from the board surface. This temperature must not exceed 85 °C. Alternatively, you can rely on the reported Secondary System temperature to provide a conservative estimate of the local ambient temperature.

Maximum reported onboard sensor temperature

CPU/FPGA temperature ..... 98 °C

Primary System temperature ..... 85 °C



**Note** Ensure that the local ambient, reported CPU/FPGA, and reported Primary System temperatures do not exceed any of the maximum temperatures listed in this document. For more information about how to access the onboard sensors, visit [ni.com/info](http://ni.com/info) and enter the Info Code `sbriosensors`.



**Note** NI sbRIO device thermal performance is greatly influenced by several factors, including resource utilization, mounting, and adjacent power dissipation. Together, these factors can substantially affect the achievable external ambient temperature at which the maximum local and reported temperatures are reached. Additional thermal design will likely be required to remain within the maximum allowed temperature ranges. For information and examples regarding the effect of these design factors, visit [ni.com/info](http://ni.com/info) and enter the Info Code `sbriocooling`. For device-specific guidelines about enabling proper thermal design, refer to the *NI sbRIO-9651 System on Module Carrier Board Design Guide*.

Storage temperature

(IEC 60068-2-1, IEC 60068-2-2) ..... -40 °C to 85 °C

Operating humidity (IEC 60068-2-56) ..... 10% RH to 90% RH, noncondensing

Storage humidity (IEC 60068-2-56) ..... 5% RH to 95% RH, noncondensing

Pollution Degree (IEC 60664) ..... 2

Maximum altitude ..... 5,000 m

Indoor use only.

# Environmental Management

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NI is committed to designing and manufacturing products in an environmentally responsible manner. NI recognizes that eliminating certain hazardous substances from our products is beneficial to the environment and to NI customers.

For additional environmental information, refer to the *Minimize Our Environmental Impact* web page at [ni.com/environment](http://ni.com/environment). This page contains the environmental regulations and directives with which NI complies, as well as other environmental information not included in this document.

## Waste Electrical and Electronic Equipment (WEEE)



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## Safety Guidelines

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Operate the sbRIO-9651 SOM only as described in the user documentation.



**Caution** The sbRIO-9651 SOM must be installed in a suitable enclosure prior to use.



**Caution** National Instruments makes no product safety, electromagnetic compatibility (EMC), or CE marking compliance claims for the sbRIO-9651 SOM. The end-product supplier is responsible for conformity to any and all compliance requirements.



**Caution** Exercise caution when designing an enclosure for the sbRIO-9651 SOM. Auxiliary cooling may be necessary to keep the sbRIO-9651 SOM within the specified operating temperature range. Refer to the [Environmental](#) section of this document for more information about the maximum operating temperature rating. For information and examples regarding factors that can affect thermal performance, visit [ni.com/info](http://ni.com/info) and enter the Info Code `sbriocooling`.



**Caution** Do not operate the sbRIO-9651 SOM in a manner not specified in the user documentation. Product misuse can result in a hazard. You can compromise the safety protection built into the product if the product is damaged in any way. If the product is damaged, return it to National Instruments for repair.

# J1 Connector Signal Groups

Table 19 lists the pins and signals on the J1 connector, grouped by interface type.



**Note** Refer to the *NI sbRIO-9651 System on Module Carrier Board Design Guide* for more information about each signal group and how to implement a particular signal in a carrier board design.

**Table 19.** J1 Connector Pins and Signal Groups

Signal Name	Pin #	Signal Name	Pin #	Signal Name	Pin #
<b>Primary Ethernet (GBE0)</b>					
GBE0_MDI0_P	1	GBE0_MDI2_P	3	GBE0_SPEED_LEDg	5
GBE0_MDI0_N	9	GBE0_MDI2_N	11	GBE0_SPEED_LEDy	13
GBE0_MDI1_P	18	GBE0_MDI3_P	20	GBE0_ACT_LEDg	6
GBE0_MDI1_N	26	GBE0_MDI3_N	28		
<b>USB0 Host/Device</b>					
USB0_DP	33	USB0_MODE	65	USB0_VBUS	81
USB0_DN	41	USB0_CPEN	73		
<b>USB1 Host</b>					
USB1_DP	35	USB1_CPEN	50	USB1_VBUS	58
USB1_DN	43				
<b>Serial1 UART (Console Out)</b>					
Serial1_TX	52	Serial1_RX	60		
<b>SDIO</b>					
SD_CLK	15	SD_WP	40	SD_D1	22
SD_CMD	31	SD_PWR_EN	38	SD_D2	24
SD_CD#	32	SD_D0	8	SD_D3	30
<b>Support</b>					
STATUS_LED	14	CARRIER_RST#	37	FPGA_CFG	53
SYS_RST#	47	TEMP_ALERT	46		

**Table 19. J1 Connector Pins and Signal Groups (Continued)**

Signal Name	Pin #	Signal Name	Pin #	Signal Name	Pin #
Power Input					
VCC_3V3	80	VIO_BANK1	120	VIO_BANK3	240
VCC_3V3	88	VIO_BANK1	128	VIO_BANK3	248
VCC_3V3	96	VIO_BANK2	168	VBAT	64
VCC_3V3	104	VIO_BANK2	176		
DIO Bank 0					
DIO_0	66	DIO_6	76	DIO_12	78
DIO_1	74	DIO_7	69	DIO_13	63
DIO_2	59	DIO_8	85	DIO_14	79
DIO_3	75	DIO_9	54	DIO_15_MRCC	87
DIO_4	83	DIO_10	62		
DIO_5	68	DIO_11	70		
DIO Bank 1					
DIO_16	105	DIO_24	155	DIO_32	102
DIO_16_N	113	DIO_24_N	163	DIO_32_N	94
DIO_17	129	DIO_25	100	DIO_33	126
DIO_17_N	137	DIO_25_N	92	DIO_33_N	118
DIO_18	153	DIO_26	124	DIO_34	150
DIO_18_N	161	DIO_26_N	116	DIO_34_N	142
DIO_19	98	DIO_27	148	DIO_35_PUDC	174
DIO_19_N	90	DIO_27_N	140	DIO_35_N	166
DIO_20	122	DIO_28	172	DIO_36_SRCC	111
DIO_20_N	114	DIO_28_N	164	DIO_36_N	119
DIO_21	146	DIO_29	109	DIO_37_MRCC	135
DIO_21_N	138	DIO_29_N	117	DIO_37_N	143
DIO_22	107	DIO_30	133	DIO_38_MRCC	159
DIO_22_N	115	DIO_30_N	141	DIO_38_N	167

**Table 19. J1 Connector Pins and Signal Groups (Continued)**

Signal Name	Pin #	Signal Name	Pin #	Signal Name	Pin #
DIO_23	131	DIO_31	157	DIO_39_SRCC	152
DIO_23_N	139	DIO_31_N	165	DIO_39_N	144
<b>DIO Bank 2</b>					
DIO_40	177	DIO_48	203	DIO_56	198
DIO_40_N	185	DIO_48_N	211	DIO_56_N	190
DIO_41	201	DIO_49	227	DIO_57	222
DIO_41_N	209	DIO_49_N	235	DIO_57_N	214
DIO_42	225	DIO_50	196	DIO_58	246
DIO_42_N	233	DIO_50_N	188	DIO_58_N	238
DIO_43	170	DIO_51	220	DIO_59	183
DIO_43_N	162	DIO_51_N	212	DIO_59_N	191
DIO_44	194	DIO_52	244	DIO_60_SRCC	207
DIO_44_N	186	DIO_52_N	236	DIO_60_N	215
DIO_45	218	DIO_53	181	DIO_61_MRCC	231
DIO_45_N	210	DIO_53_N	189	DIO_61_N	239
DIO_46	242	DIO_54	205	DIO_62_MRCC	200
DIO_46_N	234	DIO_54_N	213	DIO_62_N	192
DIO_47	179	DIO_55	229	DIO_63_SRCC	224
DIO_47_N	187	DIO_55_N	237	DIO_63_N	216
<b>DIO Bank 3</b>					
DIO_64	249	DIO_72	299	DIO_80	294
DIO_64_N	257	DIO_72_N	307	DIO_80_N	286
DIO_65	273	DIO_73	268	DIO_81	318
DIO_65_N	281	DIO_73_N	260	DIO_81_N	310
DIO_66	297	DIO_74	292	DIO_82	255
DIO_66_N	305	DIO_74_N	284	DIO_82_N	263
DIO_67	266	DIO_75	316	DIO_83	279
DIO_67_N	258	DIO_75_N	308	DIO_83_N	287

**Table 19. J1 Connector Pins and Signal Groups (Continued)**

Signal Name	Pin #	Signal Name	Pin #	Signal Name	Pin #
DIO_68	290	DIO_76	253	DIO_84_SRCC	303
DIO_68_N	282	DIO_76_N	261	DIO_84_N	311
DIO_69	314	DIO_77	277	DIO_85_MRCC	272
DIO_69_N	306	DIO_77_N	285	DIO_85_N	264
DIO_70	251	DIO_78	301	DIO_86_MRCC	296
DIO_70_N	259	DIO_78_N	309	DIO_86_N	288
DIO_71	275	DIO_79	270	DIO_87_SRCC	320
DIO_71_N	283	DIO_79_N	262	DIO_87_N	312

Table 20 lists the pins that are connected to GND and pins that are reserved and should be left disconnected.

**Table 20. J1 Connector GND and Reserved Pins**

Pin #	Pin #	Pin #	Pin #	Pin #	Pin #	Pin #	Pin #
<b>GND</b>							
2	36	77	110	154	197	241	278
4	39	82	112	156	199	243	280
7	42	84	121	158	202	245	289
10	44	86	123	160	204	247	291
12	45	89	125	169	206	250	293
16	48	91	127	171	208	252	295
17	49	93	130	173	217	254	298
19	51	95	132	175	219	256	300

**Table 20.** J1 Connector GND and Reserved Pins (Continued)

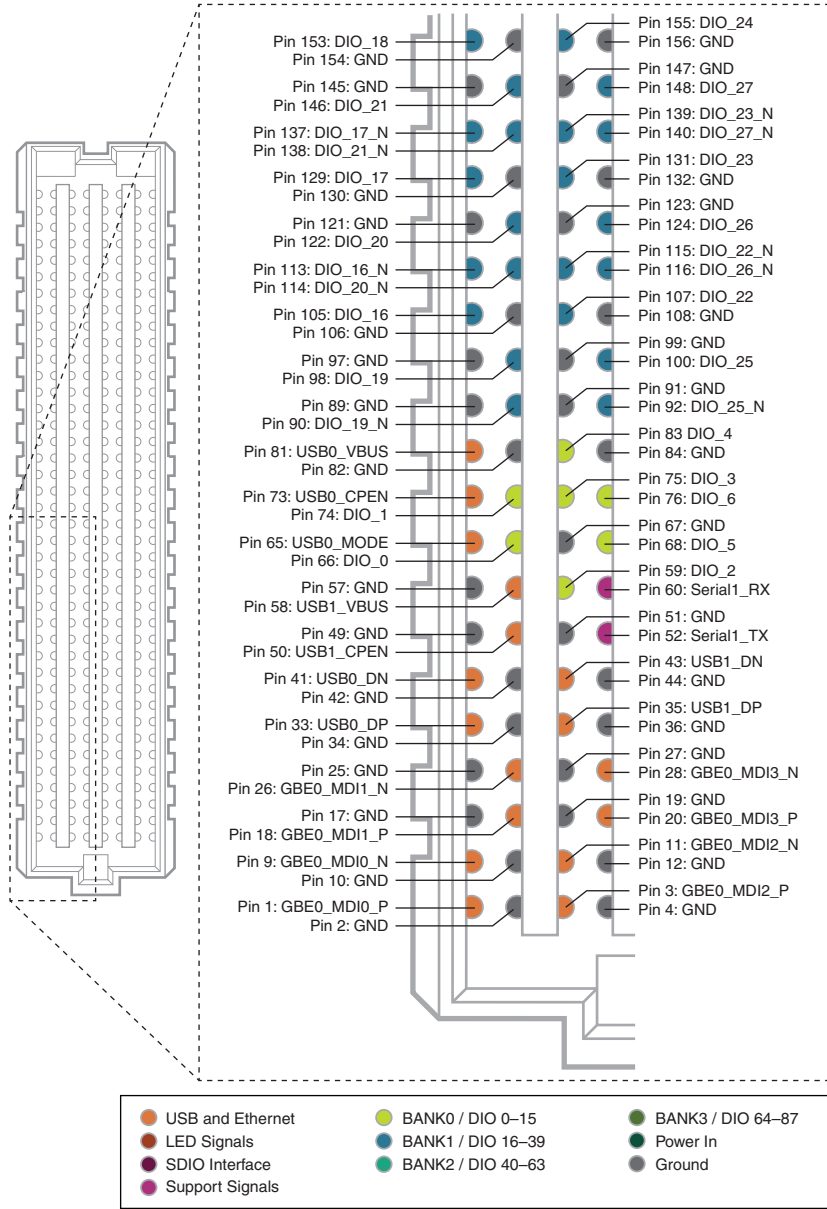
Pin #	Pin #	Pin #	Pin #	Pin #	Pin #	Pin #	Pin #
21	55	97	134	178	221	265	302
23	57	99	136	180	223	267	304
25	61	101	145	182	226	269	313
27	67	103	147	184	228	271	315
29	71	106	149	193	230	274	317
34	72	108	151	195	232	276	319
RESERVED-NC							
56							



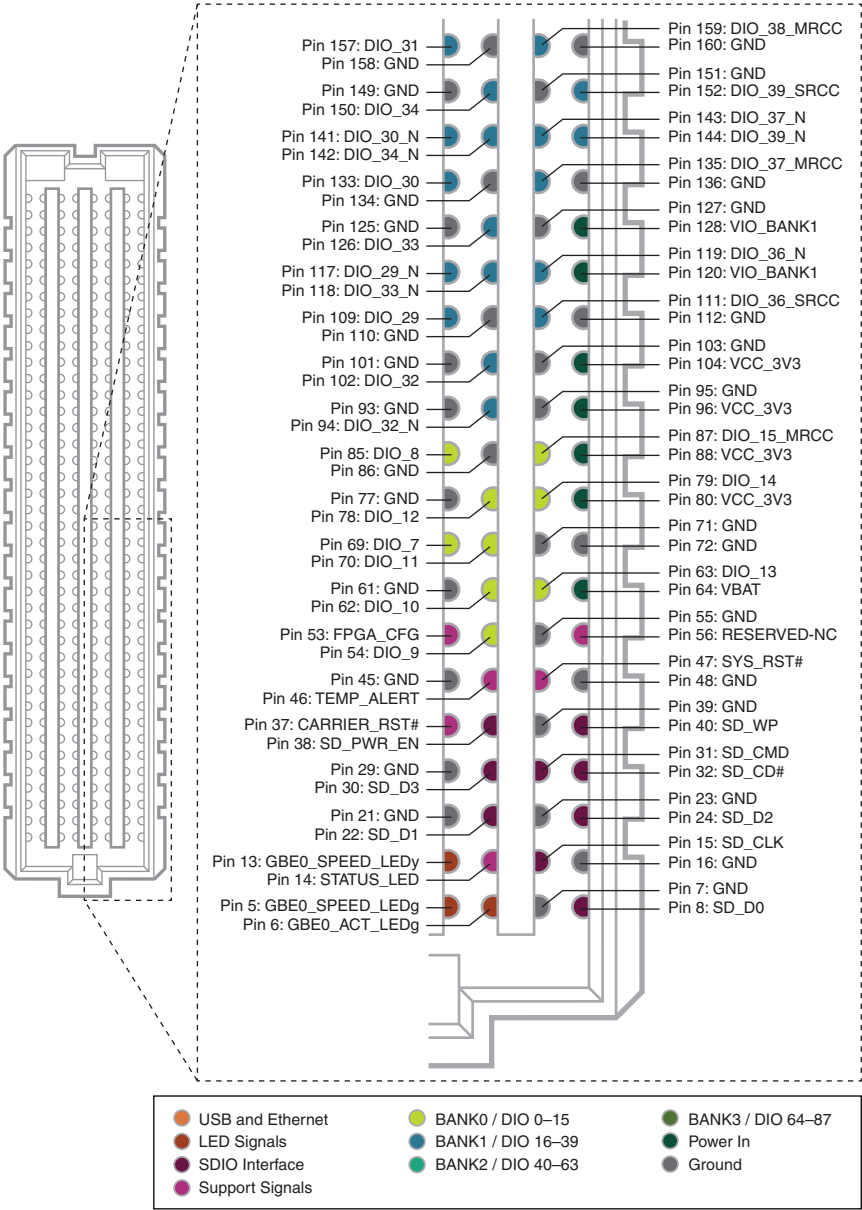
# J1 Connector Pinout

Figures 10 through 12 show the individual pins on the J1 connector.

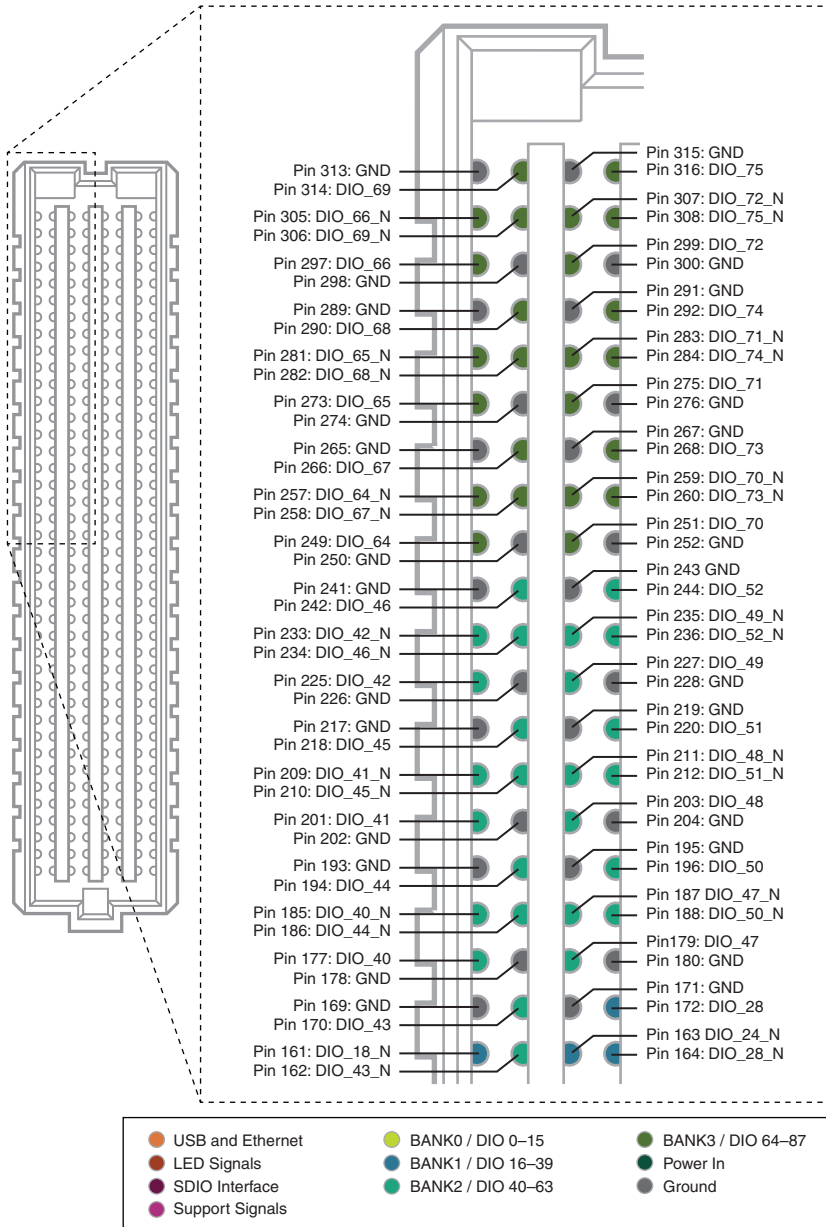
**Figure 9.** sbRIO-9651 SOM J1 Connector Pinout (1 of 4)



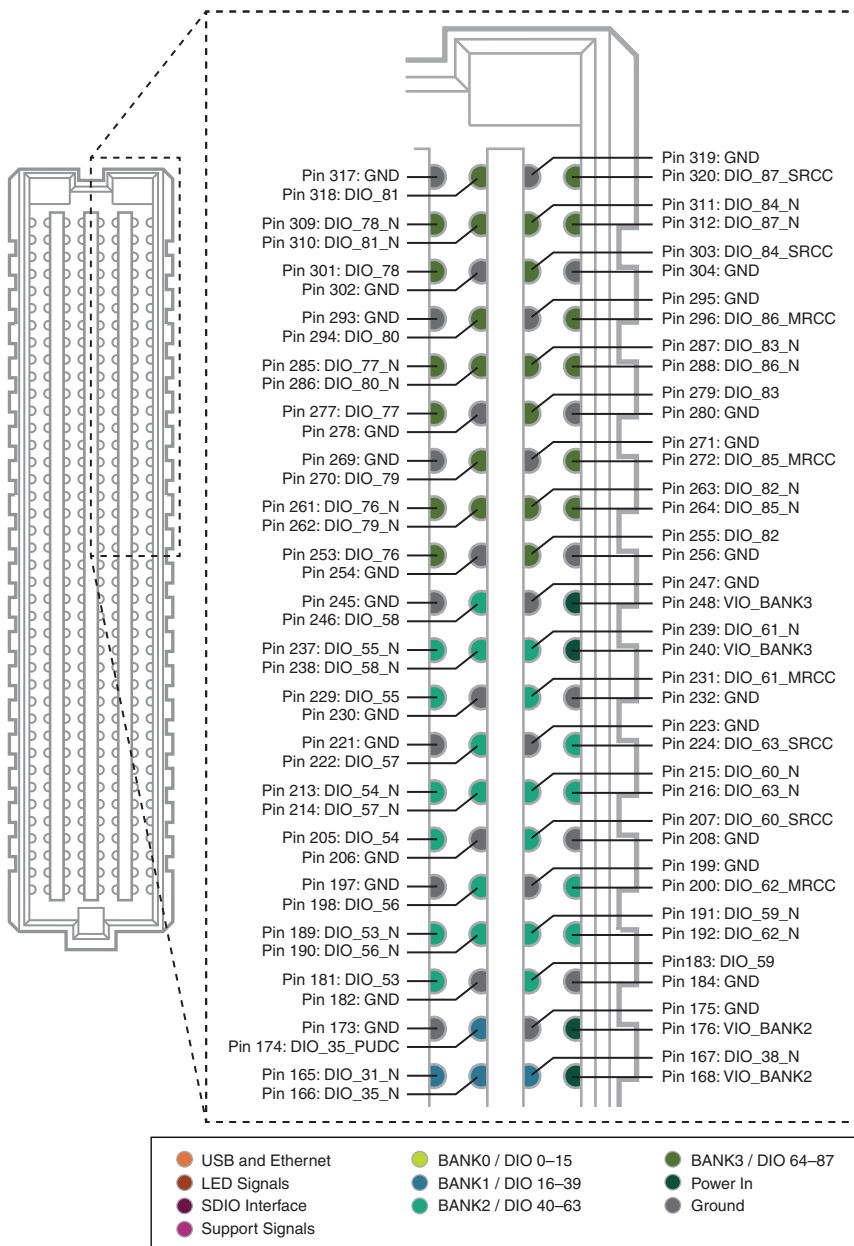
**Figure 10.** sbRIO-9651 SOM J1 Connector Pinout (2 of 4)



**Figure 11. sbRIO-9651 SOM J1 Connector Pinout (3 of 4)**










**Figure 12.** sbRIO-9651 SOM J1 Connector Pinout (4 of 4)







# Additional Documentation Resources

Refer to Figure 13 for additional resources as you design, prototype, and implement your sbRIO-9651 SOM application.

**Figure 13.** sbRIO-9651 SOM Documentation Resources

What Would You Like to Learn More About?	Resources	Availability
NI sbRIO-9651 System on Module OEM Device	<i>NI sbRIO-9651 System on Module OEM Device Specifications</i>	
NI sbRIO-9651 System on Module Development Kit	<i>NI sbRIO-9651 System on Module Development Kit Quick Start Guide</i>	 
Designing a carrier board for your application	<i>NI sbRIO-9651 System on Module Carrier Board Design Guide</i>	
Adding an sbRIO-9651 System on Module target in LabVIEW	<i>LabVIEW Help (NI-RIO)</i>	
Creating a socketed CLIP that defines the I/O configuration to use in your application	<i>NI Single-Board RIO CLIP Generator Help</i>	
NI Training and Support	<a href="http://ni.com/singleboard/setup">ni.com/singleboard/setup</a> <a href="http://ni.com/training">ni.com/training</a> <a href="http://ni.com/support">ni.com/support</a>	

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# Revision History

Table 21 lists changes to this document since its first iteration.

**Table 21.** Revision History

Revision	Edition Date	Changes
B	December 2014	<ul style="list-style-type: none"><li>Corrected the Samtec connector part numbers listed in Table 2.</li><li>Corrected Table 20 to list pin 280 as a GND pin. The previous version of this document incorrectly listed pin 288 as a GND pin. Pin 288 is DIO_86_N, as listed correctly in Table 19.</li></ul>
A	October 2014	—

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