

## QUICK SORT

```
#include <iostream.h>
#include <conio.h>
#include <time.h>
#include <stdlib.h>
#define MAX 500
void qsort(int [],int,int);
int partition(int[],int,int);
void main()
{
    clrscr();
    int a[MAX],i,n;
    clock_t s,e,z;
    s=clock();
    cout<<"Enter the value of n:";
    cin>>n;
    for(i=0;i<n;i++)
        a[i]=rand()%100;
    cout<<"Before Sorting:"<<"\t"<<"\n";
    for(i=0;i<n;i++)
        cout<<a[i]<<"\t";
    qsort(a,0,n-1);
    cout<<"After Sorting:"<<"\t"<<"\n";
    for(i=0;i<n;i++)
        cout<<a[i]<<"\t";
    e=clock();
    z=e-s;
    cout<<"\n"<<"Time taken:"<<z/ CLOCKS_PER_SEC<<"sec";
    getch();
}

void qsort(int a[],int low,int high)
{
    int j;
    if(low<high)
    {
        j=partition(a,low,high);
        qsort(a,low,j-1);
        qsort(a,j+1,high);
    }
}
```

```
}
```

```
int partition(int a[],int low,int high)
```

```
{
```

```
int pivot,i,j,temp;
```

```
pivot =a[low];
```

```
i=low+1;
```

```
j=high;
```

```
while(1)
```

```
{
```

```
while (pivot>a[i]&& i<=high)
```

```
i++;
```

```
while (pivot<a[j])
```

```
j--;
```

```
if(i<j)
```

```
{
```

```
temp=a[i];
```

```
a[i]=a[j];
```

```
a[j]=temp;
```

```
}
```

```
else
```

```
{
```

```
temp=a[j];
```

```
a[j]=a[low];
```

```
a[low]=temp;
```

```
return j;
```

```
}
```

```
}
```

```
}
```

## OUTPUT

Enter the value of n:5

Before Sorting:

40 30 82 90 56

After Sorting:

30 40 56 82 90

Time taken:2.362637

## TOPOLOGICAL ORDERING OF VERTICES

```
#include <iostream.h>
#include <conio.h>
int a[10][10],n,indegree[10];
void find_indegree()
{
    int j,i,sum;
    for(j=0;j<n;j++)
        sum+=a[i][j];
    indegree[j]=sum;
}
void topology()
{
    int i,u,v,t[10],s[10],top=-1,k=0;
    find_indegree();
    for(i=0;i<n;i++)
    {
        if(indegree[i]==0)
            s[++top]=i;
    }
    while(top!=-1)
    {
        u=s[top--];
        t[k++]=u;
        for(v=0;v<n;v++)
        {
            if(a[u][v]==1)
            {
                indegree[v]-=1;
                if(indegree[v]==0)
                    s[++top]=u;
            }
        }
    }
    cout<<"The topological sequence is:"<<"\n";
    for(i=0;i<n;i++)
        cout<<t[i]<<"\t";
}
```

```
void main()
{
int i,j;
cout<<"Enter the no.of nodes:"<<"\n";
cin>>n;
cout<<"Enter the adjacency matrix:"<<"\n";
for(i=0;i<n;i++)
{
for(j=0;j<n;j++)
cin>>a[i][j];
}
topology();
getch();
}
```

## OUTPUT

Enter the no of nodes:5

Enter the adjacency matrix:

0 0 1 0 0

0 0 1 0 0

0 0 0 1 1

0 0 0 0 1

0 0 0 0 0

The topological sequence is:

2 1 3 4 5

## TRAVELLING SALESMAN PROBLEM

```
#include <iostream.h>
#include <conio.h>
int a[10][10],completed[10],n,cost=0;
void takeinput()
{
    clrscr();
    int i,j;
    cout<<"Enter the no of villagers:";
    cin>>n;
    cout<<"\nEnter cost matrix\n";
    for(i=0;i<n;i++)
    {
        cout<<"Enter the elements of row:"<<i+1<<"\n";
        for(j=0;j<n;j++)
            cin>>a[i][j];
        completed[i]=0;
    }
    cout<<"\nThe Cost List is:";
    for(i=0;i<n;i++)
    {
        cout<<"\n";
        for(j=0;j<n;j++)
            cout<<"\t"<<a[i][j];
    }
}
int least(int c)
{
    int i,nc=999;
    int min=999,kmin;
    for(i=0;i<n;i++)
    {
        if((a[c][i]!=0)&&(completed[i]==0))
        if((a[c][i]+a[i][c]<min))
        {
            min=a[i][0]+a[c][i];
            kmin=a[c][i];
            nc=i;
        }
    }
}
```

```

}
}
if(min!=00)
cost+=kmin;
return nc;
}
void mincost(int city)
{
int i,ncity;
completed[city]=1;
cout<<city+1<<"--->";
ncity=least(city);
if(ncity==999)
{
ncity=0;
cout<<ncity+1;
cost+=a[city][ncity];
return;
}
mincost(ncity);
}
int main()
{
takeinput();
cout<<"\nThe Path is:";
mincost(0);
cout<<"\nThe Minimum cost is:"<<cost;
getch();
return 0;
}

```



## OUTPUT

Enter the no of villagers:2

Enter cost matrix

Enter the elements of row1:

1

2

Enter the elements of row2:

2

3

The cost List is:

1 2

2 3

The path is:1→2→1

The minimum cost is:5

## PRIM'S ALGORITHM

```
#include <iostream.h>
#include <conio.h>
int ne=1,min_cost=0;
void main()
{
clrscr();
int n,i,j,min,cost[20][20],a,b,u,v,source,visited[20];
cout<<"Enter the number of matrices:\n";
cin>>n;
cout<<"Enter the cost of matrix:\n";
for(i=1;i<=n;i++)
{
for(j=1;j<=n;j++)
{
cin>>cost[i][j];
if(cost[i][j]==0)
cost[i][j]=999;
}
}
for(i=0;i<n;i++)
visited[i]=0;
cout<<"Enter the root node:";
cin>>source;
visited[source]=1;
cout<<"\nMinimum cost Spanning Tree:\n";
while(ne<n)
{
min=999;
for(i=1;i<=n;i++){
for(j=1;j<=n;j++)
{
if(cost[i][j]<min)
if(visited[i]!=0)
{
min=cost[i][j];
a=u=i;
b=v=j;
```

```

}
}
}
if(visited[u]==0 || visited[v]==0)
{
cout<<"\nEdge"<<ne++<<"\t("<<a<<"---"<<b<<")"<<min;
min_cost=min_cost+min;
visited[b]=1;
}
cost[a][b]=cost[b][a]=999;
}
cout<<"\nMinimum Cost="<<min_cost<<"\n";
getch();
}

```

## OUTPUT

Enter the number of matrices:4

Enter the cost of matirx:

0 1 4 5

1 0 2 3

4 2 0 7

5 3 7 0

Enter the root node:2

Minimum cost Spanning Tree:

Edge(1→2)1

Edge(2→3)2

Edge(2→4)3

Minimum Cost=6

## DIJKSTRA'S ALGORITHM

```
#include<iostream.h>
void dij(int,int[20][20],int[20],int[20],int);
void main()
{
int i,j,n,visited[20],source,cost[20][20],d[20];
cout<<"enter no. of vertices:";
cin>>n;
cout<<"enter the cost adjacency matrix\n";
for(i=1;i<=n;i++)
{
for(j=1;j<=n;j++)
{
cin>>cost[i][j];
}
}
cout<<"\nEnter the source node:";
cin>>source;
dij(source,cost,visited,d,n);
for(i=1;i<=n;i++)
if(i!=source)
cout<<"\n shortest path from"<<source<<"to"<<i<<"is"<<d[i];}
void dij(int source,int cost[20][20],int visited[20],int d[20],int n)
{
int i,j,min,u,w;
for(i=1;i<=n;i++)
{
visited[i]=0;
d[i]=cost[source][i];
}
visited[source]=1;
d[source]=0;
for(j=1;j<=n;j++)
{
min=999;
for(i=1;i<=n;i++)
{
if(!visited[i])
{
```

```
if(d[i]<min)
{
min=d[i];
u=i;
}
}
}
visited[u]=1;
for(w=1;w<=n;w++)
{
if(cost[u][w]!=999 &&visited[w]==0)
{
if(d[w]>cost[u][w]+d[u])
d[w]=cost[u][w]+d[u];
}
}
}
}
```

## OUTPUT

Enter the no.of matirces:3

Enter the adjacency matrix:

0 5 12 17 999

999 0 999 8 7

999 999 0 9 999

999 999 999 0 999

999 999 999 999 0

Enter the source node:1

Shortest path from 1 to 2 is 5

Shortest path from 1 to 3 is 12

Shortest path from 1 to 4 is 13

Shortest path from 1 to 5 is 12

## N-QUEEN PROBLEM

```
#include<iostream.h>
#include<conio.h>
#include<math.h>
void queen(int ,int);
int place(int ,int);
int x[15],count=1;
void main()
{
    int i,j,n;
    clrscr();
    cout<<"\n\t\t N QUEEN PROBLEM";
    cout<<"\nEnter the no of queen:\n";
    cin>>n;
    queen(1,n);
    getch(); }
void queen(int k,int n)
{
    int j,i,m;
    for(i=1;i<=n;i++)
    {
        if(place(k,i))
        {
            x[k]=i;
            if(k==n)
            {
                cout<<"\n\t Feasible Solution:"<<count++;
                for(j=1;j<=n;j++){
                    cout<<"\n\t\t row"<<j<<"--column"<<x[j]<<":\t|";
                    for(i=1;i<=n;i++)
                    {
                        if(i==x[j])
                            cout<<"Q|";
                        else
                            cout<<".|";
                    }
                }
            }
        }
    }
    getch();
```



```
}  
else  
    queen(k+1,n);  
}  
}}  
int place(int k,int i)  
{  
    int j;  
    for(j=1;j<=k-1;j++)  
        if((x[j]==i)|| (abs(x[j]-i)==abs(j-k)))  
            return 0;  
    return 1;  
}
```

## OUTPUT

Enter the no.of queen:4

Feasible Solution:1

Row1–Column2:|.Q|.|.|

Row2–Column4:|.|.|.Q|

Row3–Column1:|Q|.|.|.|

Row4–Column3:|.|.Q|.|

## 4-QUEEN PROBLEM

```
queens(N, Queens) :-  
    length(Queens, N),  
    board(Queens, Board, 0, N, _, _),  
    queens(Board, 0, Queens).
```

```
board([], [], N, N, _, _).  
board(_|Queens, [Col-Vars|Board], Col0, N, _|VR, VC) :-  
    Col is Col0+1,  
    functor(Vars, f, N),  
    constraints(N, Vars, VR, VC),  
    board(Queens, Board, Col, N, VR, _|VC).
```

```
constraints(0, _, _, _) :- !.  
constraints(N, Row, [R|Rs], [C|Cs]) :-  
    arg(N, Row, R-C),  
    M is N-1,  
    constraints(M, Row, Rs, Cs).
```

```
queens([], _, []).  
queens([C|Cs], Row0, [Col|Solution]) :-  
    Row is Row0+1,  
    select(Col-Vars, [C|Cs], Board),  
    arg(Row, Vars, Row-Row),  
    queens(Board, Row, Solution).
```

## OUTPUT

Queen = [2, 4, 1, 3] .

## TIC TAC TOE

```
win(Board, Player) :- rowwin(Board, Player).
win(Board, Player) :- colwin(Board, Player).
win(Board, Player) :- diagwin(Board, Player).
```

```
rowwin(Board, Player) :- Board = [Player,Player,Player,_,_,_,_,_].
rowwin(Board, Player) :- Board = [_,_,_Player,Player,Player,_,_,_].
rowwin(Board, Player) :- Board = [_,_,_,_,_Player,Player,Player].
```

```
colwin(Board, Player) :- Board = [Player,_,_,Player,_,_,Player,_,_].
colwin(Board, Player) :- Board = [_Player,_,_,Player,_,_,Player,_,_].
colwin(Board, Player) :- Board = [_,_Player,_,_,Player,_,_,Player,_,_].
```

```
diagwin(Board, Player) :- Board = [Player,_,_,_,Player,_,_,_,Player].
diagwin(Board, Player) :- Board = [_,_Player,_,_,Player,_,_,_,_].
other(x,o).
other(o,x).
```

```
game(Board, Player) :- win(Board, Player), !, write([player, Player, wins]).
game(Board, Player) :-
    other(Player,Otherplayer),
    move(Board,Player,Newboard),
    !,
    display(Newboard),
    game(Newboard,Otherplayer).
```

```
move([b,B,C,D,E,F,G,H,I], Player, [Player,B,C,D,E,F,G,H,I]).
move([A,b,C,D,E,F,G,H,I], Player, [A,Player,C,D,E,F,G,H,I]).
move([A,B,b,D,E,F,G,H,I], Player, [A,B,Player,D,E,F,G,H,I]).
move([A,B,C,b,E,F,G,H,I], Player, [A,B,C,Player,E,F,G,H,I]).
move([A,B,C,D,b,F,G,H,I], Player, [A,B,C,D,Player,F,G,H,I]).
move([A,B,C,D,E,b,G,H,I], Player, [A,B,C,D,E,Player,G,H,I]).
move([A,B,C,D,E,F,b,H,I], Player, [A,B,C,D,E,F,Player,H,I]).
move([A,B,C,D,E,F,G,b,I], Player, [A,B,C,D,E,F,G,Player,I]).
move([A,B,C,D,E,F,G,H,b], Player, [A,B,C,D,E,F,G,H,Player]).
```

```
display([A,B,C,D,E,F,G,H,I]) :- write([A,B,C]),nl,write([D,E,F]),nl,
write([G,H,I]),nl,nl.
```

```
selfgame :- game([b,b,b,b,b,b,b,b],x).
```

```
x_can_win_in_one(Board) :- move(Board, x, Newboard), win(Newboard, x).
```

```
orespond(Board,Newboard) :-  
    move(Board, o, Newboard),  
    win(Newboard, o),  
    !.
```

```
orespond(Board,Newboard) :-  
    move(Board, o, Newboard),  
    not(x_can_win_in_one(Newboard)).
```

```
orespond(Board,Newboard) :-  
    move(Board, o, Newboard).
```

```
orespond(Board,Newboard) :-  
    not(member(b,Board)),  
    !,  
    write('Cats game!'), nl,  
    Newboard = Board.
```

```
xmove([b,B,C,D,E,F,G,H,I], 1, [x,B,C,D,E,F,G,H,I]).  
xmove([A,b,C,D,E,F,G,H,I], 2, [A,x,C,D,E,F,G,H,I]).  
xmove([A,B,b,D,E,F,G,H,I], 3, [A,B,x,D,E,F,G,H,I]).  
xmove([A,B,C,b,E,F,G,H,I], 4, [A,B,C,x,E,F,G,H,I]).  
xmove([A,B,C,D,b,F,G,H,I], 5, [A,B,C,D,x,F,G,H,I]).  
xmove([A,B,C,D,E,b,G,H,I], 6, [A,B,C,D,E,x,G,H,I]).  
xmove([A,B,C,D,E,F,b,H,I], 7, [A,B,C,D,E,F,x,H,I]).  
xmove([A,B,C,D,E,F,G,b,I], 8, [A,B,C,D,E,F,G,x,I]).  
xmove([A,B,C,D,E,F,G,H,b], 9, [A,B,C,D,E,F,G,H,x]).  
xmove(Board, _, Board) :- write('Illegal move.'), nl.
```

```
playo :- explain, playfrom([b,b,b,b,b,b,b,b]).
```

```
explain :-  
    write("You play X by entering integer positions followed by a period."),  
    nl,  
    display([1,2,3,4,5,6,7,8,9]).
```

```
playfrom(Board) :- win(Board, x), write("You win!").  
playfrom(Board) :- win(Board, o), write("I win!").
```

```
playfrom(Board) :- read(N),  
    xmove(Board, N, Newboard),  
    display(Newboard),  
    orespond(Newboard, Newnewboard),  
    display(Newnewboard),  
    playfrom(Newnewboard).
```

## OUTPUT

playo.

You play X by entering integer positions followed by a period.

[1,2,3]

[4,5,6]

[7,8,9]

|: 5.

[b,b,b]

[b,x,b]

[b,b,b]

[o,b,b]

[b,x,b]

[b,b,b]

|: 2.

[o,x,b]

[b,x,b]

[b,b,b]

[o,x,b]

[b,x,b]

[b,o,b]



## ALPHA BETA PRUNING

:-dynamic true/1, does/2.

role(player).

init(step(0)).

init(cell(1, 1, 1)). init(cell(1, 2, 2)). init(cell(1, 3, 3)).

init(cell(2, 1, 7)). init(cell(2, 2, 8)). init(cell(2, 3, 4)).

init(cell(3, 1, 6)). init(cell(3, 2, 5)). init(cell(3, 3, b)).

legal(player, move(Row, Col)) :-

true(cell(U, Col, b)),

(succ(Row, U) ; pred(Row, U)).

legal(player, move(Row, Col)) :-

true(cell(Row, V, b)),

(succ(Col, V) ; pred(Col, V)).

next(step(X)) :-

true(step(Y)),

X is Y + 1.

next(cell(X, Y, b)) :-

does(player, move(X, Y)).

next(cell(U, Y, Z)) :-

does(player, move(X, Y)),

true(cell(U, Y, b)),

true(cell(X, Y, Z)),

Z \= b.

next(cell(X, V, Z)) :-

does(player, move(X, Y)),

true(cell(X, V, b)),

true(cell(X, Y, Z)),

Z \= b.

next(cell(U, V, Z)) :-

true(cell(U, V, Z)),

does(player, move(X, Y)),

(X \= U ; Y \= V),

true(cell(X1, Y1, b)),

(X1 \= U ; Y1 \= V).

goal(player, 100) :-

inorder.

goal(player, 0) :-

\+inorder.

terminal :- inorder.

```

terminal :- true(step(4)).
inorder :- true(cell(1, 1, 1)), true(cell(1, 2, 2)), true(cell(1, 3, 3)),
true(cell(2, 1, 8)), true(cell(2, 2, b)), true(cell(2, 3, 4)),
true(cell(3, 1, 7)), true(cell(3, 2, 6)), true(cell(3, 3, 5)).
succ(1, 2).
succ(2, 3).
pred(2, 1).
pred(3, 2).
%% Heuristic using Manhattan distance, also called taxicab geometry
heuristic(State, [goal(player, Value)]) :-
maplist(taxicab_dist, State, Distances),
sum_list(Distances, TotalDistances),
Value is 100 - TotalDistances.
taxicab_dist(step(_), 0).
taxicab_dist(cell(Row, Col, Tile), Distance) :-
member(cell(RowDest, ColDest, Tile),
[cell(1, 1, 1), cell(1, 2, 2), cell(1, 3, 3),
cell(2, 1, 8), cell(2, 2, b), cell(2, 3, 4),
cell(3, 1, 7), cell(3, 2, 6), cell(3, 3, 5)]),
abs(Row - RowDest, Y),
abs(Col - ColDest, X),
Distance is X + Y.

```

## OUTPUT

```
time(solve_dfs(Path)).  
Path = [  
  does(player,move(3,2)),  
  does(player,move(3,1)),  
  does(player,move(2,1)),  
  does(player,move(2,2))  
]  
2 one:  
time(solve_bfs(Path)).  
Path = [  
  does(player,move(3,2)),  
  does(player,move(3,1)),  
  does(player,move(2,1)),  
  does(player,move(2,2))  
]
```