

Jose Rizal University

Line Follower Robot

A Documentation Submitted to the
Faculty of the College of Computer Studies and Engineering

In Partial Fulfillment
Of the Requirements for the Degree

Bachelor of Science in Computer Engineering

By

WARRIORS

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Aimed to: Assist the students by assembling a line follower robot which will be accurate in following a line which will then get to the end of the line. We looked into and used a LineUtilizing microcontroller, the following robot. programs, as well as Microcontroller interface has been looked throughout the implementation.





FIRST SESSION AND 2ND SESSION PICTURES















