

Fiona

psat 7.

1. a). when ρ is unchanged & σ_ε ^{increases} ~~changes~~, the shape of z_t changes because there's more variance in the random part of the shock. when ρ is increased & σ is unchanged, z_t becomes bigger on average, while maintaining the same shape, because z_t is less random and more reliant on previous z_{t-1} .

b). As shown in class, for AR.

$$E[z_t^2] = \frac{\sigma_\varepsilon^2}{1-\rho^2}, \quad E[z_t, z_{t+1}] = \rho \cdot \frac{\sigma_\varepsilon^2}{1-\rho^2}$$

For MC:

$$E[z_t^2] = \sum z^2 \cdot p(z) = (-\Delta)^2 \cdot \pi_{11} + (\Delta)^2 \cdot (1-\pi_{11}) = \Delta^2$$

$$E[z_t^2]_{AR} = E[z_t^2]_{MC} = \frac{\sigma_\varepsilon^2}{1-\rho^2} = \Delta^2 \Rightarrow \Delta$$

$$\begin{aligned} \underline{MC}: E[z'z] &= \sum z'z_{t,h} p(z'z_{t,h}) \\ &= (-\Delta)(-\Delta) \cdot \pi_{11} + (-\Delta)(+\Delta) (1-\pi_{11}) \\ &= (2\pi_{11}-1) \Delta^2 = \rho \cdot \frac{\sigma_\varepsilon^2}{1-\rho^2} \\ &= (+\Delta)(-\Delta) \pi_{22} + (+\Delta)(+\Delta) (1-\pi_{22}) \\ &= (-2\pi_{22}) \Delta^2 = \rho \cdot \frac{\sigma_\varepsilon^2}{1-\rho^2} \end{aligned}$$

$$\Rightarrow \pi_{11} = \frac{\rho+1}{2} = 0.975$$

$$\pi_{22} = \frac{1-\rho}{2} = 0.025$$

$$\Rightarrow \Delta = \sqrt{\frac{\sigma_\varepsilon^2}{1-\rho^2}} = 0.0224$$

It's a bad approximation, after all z can only take 2 values. The transition matrix says that if z is in high state, then it has a low probability of staying in high state, while if it's

in low state, it has ~~very~~^a very high probability of staying there. I guess that explains why I'm getting a line in the low & no matter what the initial condition is.

$$\begin{bmatrix} 1-\pi_{11} & \pi_{12} \end{bmatrix} \times \begin{bmatrix} -\Delta \\ \Delta \end{bmatrix} = \begin{bmatrix} (1-\pi_{11})\Delta - \Delta(1-\pi_{11}) \\ (1-\pi_{12})\Delta - \Delta\pi_{12} \end{bmatrix}$$

$$\begin{cases} p\Delta + \varepsilon_{t+1} = - \\ -p\Delta + \varepsilon_{t+1} = \end{cases} \quad (1)$$

$$(1) - (2) \quad 2p = \pi_{11} - 1 + \pi_{11} - 1 + \pi_{12} + \pi_{12} = 2(\pi_{12} + \pi_{11} - 1)$$

$$\pi_{11} + \pi_{12} = p + 1$$

$$(1) + (2) \quad 2\varepsilon_{t+1} = \Delta [\pi_{11} + 1 - \pi_{12} - 1 + \pi_{11} - \pi_{12}]$$

$$\varepsilon_{t+1} = \Delta (\pi_{11} + \pi_{12}) = \Delta (p + 1)$$

$$\Delta = \varepsilon_{t+1} / (p + 1)$$

$$\text{Subst } \Delta \text{ in } (1) \quad \frac{p \cdot \varepsilon_{t+1}}{p+1} + \varepsilon_{t+1} = -\pi_{11} \cdot \frac{\varepsilon_{t+1}}{p+1} - \frac{\varepsilon_{t+1}}{p+1} (1 - \pi_{11})$$

$$p\varepsilon_{t+1} + \varepsilon_{t+1}(p+1) = -\pi_{11} \cdot \varepsilon_{t+1} - \varepsilon_{t+1} + \varepsilon_{t+1} \cdot \pi_{11}$$

$$2p\varepsilon_{t+1} + \varepsilon_{t+1} = \pi_{11} \cdot \varepsilon_{t+1}$$

$$\pi = \frac{1}{2}p +$$

please see other sheet.

2. Firm $\max_{k_t^d, h_t^d} e^{z_t(s_t)} [k_t^d(s_t)]^d [h_t^d(s_t)]^{1-d} - r_t(s_t) k_t^d(s_t) - w_t(s_t) h_t^d(s_t)$

$$\frac{\partial \Pi(k_t, h_t)}{\partial k_t^d} = d e^{z_t(s_t)} \cdot k_t^{d-1}(s_t) h_t^{1-d}(s_t) - r_t(s_t) = 0$$

$$\frac{\partial \Pi(k_t, h_t)}{\partial h_t^d} = (1-d) e^{z_t(s_t)} \cdot k_t^d(s_t) \cdot h_t^{-d}(s_t) - w_t(s_t) = 0$$

$$\Rightarrow \begin{cases} r_t(s_t) = d \cdot e^{z_t(s_t)} \cdot k_t^{d-1}(s_t) \cdot h_t^{1-d}(s_t) \\ w_t(s_t) = (1-d) e^{z_t(s_t)} \cdot k_t^d(s_t) \cdot h_t^{-d}(s_t) \end{cases}$$

Consumer:

$$\max_{\{C_t, l_t, k_{t+1}\}} \sum_{t=0}^{\infty} \beta^t U(C_t, l_t) \pi_t \quad \text{s.t.} \quad h_t + l_t + c_t = 1 \quad \&$$

$$C_t + k_{t+1} = k_t (1-\delta) + r_t k_t + w_t h_t$$

$$L = \sum_{t=0}^{\infty} \beta^t U(C_t, l_t) \pi_t + \sum_{t=0}^{\infty} \lambda_t \{C_t + k_{t+1} - k_t (1-\delta) - r_t k_t - w_t h_t\}$$

$$\frac{\partial L}{\partial C_t} = \beta^t U_C(C_t, l_t) \pi_t - \lambda_t = 0$$

$$\frac{\partial L}{\partial l_t} = \beta^t U_l(C_t, l_t) \pi_t - w_t \lambda_t = 0$$

$$\frac{\partial L}{\partial k_{t+1}} = -\lambda_t + \sum_{t+1} \lambda_{t+1} [(1-\delta) + r_t] = 0$$

$$\Rightarrow \left\{ \begin{aligned} w_t &= \frac{\beta^t U_l(C_t, l_t) \pi_t}{\beta^t U_C(C_t, l_t) \pi_t} = \frac{U_l}{U_C} \end{aligned} \right\}$$

Euler:

$$\beta^t U_C(C_t, l_t) \pi_t = \beta^{t+1} \sum_{t+1} U_C(C_{t+1}, l_{t+1}) \pi_{t+1} [(1-\delta) + r_t] \cdot \pi_t(S_{t+1}|S_t)$$

$$\left\{ U_C(C_t, l_t) = \beta \cdot E_t[U_C(C_{t+1}, l_{t+1}) \cdot (1-\delta + r_t)] \right\} \quad (3)'$$

suppose $u(c, l) = \log c + A \log l$

$$U_C = \frac{1}{C_t}$$

$$\Rightarrow \text{Euler: } \left\{ \frac{1}{C_t} = \beta E_t \left\{ \frac{1}{C_{t+1}} [r_{t+1} + (1-\delta)] \right\} \right\} \quad (3)''$$

$$w_t = \frac{U_l}{U_C} = \frac{1}{C_t} \cdot \frac{A}{A} \cdot l_t$$

When market clears,

$$\Rightarrow w_t = \frac{U_l}{U_C} = \frac{1}{C_t} \cdot \frac{A}{A} \cdot l_t$$

$$\Rightarrow \left\{ \frac{1}{C_t} = \frac{A}{(1-\delta) e^{z_t} k_{t-1}^{\alpha} h_t^{1-\alpha}} \right\} \quad (4)$$

$$\left\{ \begin{aligned} k_t^d &= k_{t-1} \\ \Rightarrow w_t &= (1-\delta) e^{z_t} k_{t-1}^{\alpha} h_t^{1-\alpha} \end{aligned} \right. \quad (1)$$

$$\Rightarrow r_t = \alpha e^{z_t} k_{t-1}^{\alpha-1} h_t^{1-\alpha} \quad (2)$$

As $w_t(1)$, $r_t(2)$ & Euler $(3)'$ are the same as the partial efficient situation detailed in lecture note, the system is partial efficient. (except in lecture notes $k_t^d = k_t$, but here it's $k_t^d = k_{t-1}$, the rest is the same). The welfare theorem holds.