

initial conditions

$$\begin{aligned}
 (1) \quad \bar{p}_d \frac{1}{\bar{c}_n} &= \beta \frac{A}{d_t} + \beta \frac{1}{\bar{c}_n} \cdot \bar{p}_d (1-\delta) \\
 (2) \quad \bar{p}_k \frac{1}{\bar{c}_n} &= \beta \cdot \frac{1}{\bar{c}_n} [\bar{r} + \bar{p}_k (1-\delta)] \\
 (3) \quad \bar{y} &= \bar{c}_n + \bar{c}_d + \bar{i} \\
 (4) \quad \bar{c}_d &= \bar{p}_d \cdot \bar{d} \cdot \delta \\
 (5) \quad \bar{i} &= \bar{p}_k \cdot \bar{k} \cdot \delta \\
 (6) \quad \bar{r} &= 2 (\bar{k}_n)^{\alpha-1} (\bar{h}_n)^{1-\alpha} \\
 (7) \quad \bar{w} &= (1-\alpha) (\bar{k}_n)^\alpha (\bar{h}_n)^{1-\alpha} \\
 (8) \quad \bar{r} &= 2 \bar{p}_d (\bar{k}_d)^{\alpha-1} (\bar{h}_d)^{1-\alpha} \\
 (9) \quad \bar{w} &= (1-\alpha) \bar{p}_d (\bar{k}_d)^\alpha (\bar{h}_d)^{1-\alpha} \\
 (10) \quad \bar{r} &= 2 \bar{p}_k (\bar{k}_k)^{\alpha-1} (\bar{h}_k)^{1-\alpha} \\
 (11) \quad \bar{w} &= (1-\alpha) \bar{p}_k (\bar{k}_k)^\alpha (\bar{h}_k)^{1-\alpha} \\
 (12) \quad 1 &= \bar{h}_n + \bar{h}_d + \bar{h}_k \\
 (13) \quad \bar{k} &= \bar{k}_n + \bar{k}_d + \bar{k}_k \\
 (14) \quad \delta \bar{k} &= \bar{k}_k^{\alpha-1} \bar{h}_k^{1-\alpha} \\
 (15) \quad \delta \bar{d} &= \bar{k}_d^{\alpha-1} \bar{h}_d^{1-\alpha} \\
 (16) \quad \bar{c}_n &= \bar{k}_n^{\alpha-1} \bar{h}_n^{1-\alpha} \\
 (17) \quad \bar{z} &= 0
 \end{aligned}$$

From (1) $\frac{\bar{r}}{\bar{w}} = \frac{2}{1-\alpha} \left(\frac{\bar{h}_k}{\bar{k}_k} \right) = \frac{2}{1-\alpha} \frac{\bar{h}_d}{\bar{k}_d} = \frac{2}{1-\alpha} \frac{\bar{h}_n}{\bar{k}_n}$ (1°)

From (2) $1 = \beta \frac{\bar{r}}{\bar{p}_k} + \beta (1-\delta)$

From (10) $\frac{\bar{r}}{\bar{p}_k} = \frac{2}{1-\alpha} \left(\frac{\bar{h}_k}{\bar{k}_k} \right)^{1-\alpha} = 2 \left(\frac{\bar{h}_n}{\bar{k}_n} \right)^{1-\alpha}$ (2°)

From (6) $\bar{r} = 2 \left(\frac{\bar{h}_n}{\bar{k}_n} \right)^{1-\alpha}$ (3°)

$\Rightarrow \frac{\bar{r}}{\bar{p}_k} = \bar{r} \Rightarrow \bar{p}_k = 1$ (4°)

$\Rightarrow \bar{r} = \frac{1}{\beta} - (1-\delta)$ (5°)

From (3°) $\bar{r} = 2 \cdot \left(\frac{\bar{h}_n}{\bar{k}_n} \right)^{1-\alpha}$

From (4°) $\bar{r} = 2 \cdot \left(\frac{\bar{r} (1-\alpha)}{\bar{w} \alpha} \right)^{1-\alpha}$

$\Rightarrow \bar{w}^{1-\alpha} = 2 \cdot \bar{r}^{-\alpha} \cdot \left(\frac{1-\alpha}{\alpha} \right)^{1-\alpha}$

$\bar{w} = \frac{1-\alpha}{\alpha} \cdot \sqrt[1-\alpha]{2 \cdot \bar{r}^{-\alpha}}$ (6°)

From (4) + (6) $\bar{c}_n = \left(\frac{\bar{h}_n}{\bar{k}_n} \right)^{1-\alpha} \bar{k}_n = \left(\frac{\bar{r}}{\bar{w}} \cdot \frac{1-\alpha}{\alpha} \right)^{1-\alpha} \bar{k}_n$ (7°)

$\bar{c}_d = \left(\frac{\bar{h}_d}{\bar{k}_d} \right)^{1-\alpha} \bar{k}_d = \left(\frac{\bar{r}}{\bar{w}} \cdot \frac{1-\alpha}{\alpha} \right)^{1-\alpha} \bar{k}_d$ (8°)

$\bar{i} = \left(\frac{\bar{h}_k}{\bar{k}_k} \right)^{1-\alpha} \bar{k}_k = \left(\frac{\bar{r}}{\bar{w}} \cdot \frac{1-\alpha}{\alpha} \right)^{1-\alpha} \bar{k}_k$ (9°)

Then we know $\bar{c}_n, \bar{c}_d, \bar{i} \Rightarrow$ then we know $\bar{p}_d, \bar{p}_k, \bar{p}_i$

$\frac{\bar{p}_d \cdot \bar{d}}{\bar{c}_n} = \beta A + \beta (1-\delta) \frac{\bar{p}_d \cdot \bar{d}}{\bar{c}_n}$

$\frac{\bar{c}_d}{\bar{c}_n} = \delta \cdot \beta A + \beta (1-\delta) \frac{\bar{c}_d}{\bar{c}_n}$

$\Rightarrow A = \frac{[1-\beta(1-\delta)]}{\delta \beta \frac{\bar{c}_n}{\bar{c}_d}}$

From data, $\bar{c}_n = \bar{c}_d : \bar{i} = 3.91 : 0.61 : 1 = \bar{h}_n : \bar{h}_d : \bar{h}_k$

$\Rightarrow \bar{h}_n + \bar{h}_d + \bar{h}_k = 1$

$\bar{h}_k = 0.18 \quad \bar{h}_d = 0.11 \quad \bar{h}_n = 0.71$

$$1) \frac{\bar{P}_d}{\bar{C}_n} \cdot e^{\tilde{P}_{d,t} - \tilde{C}_{n,t}} = \beta \frac{A}{d} \cdot e^{-\tilde{d}_t} + \beta E \left\{ \frac{\bar{P}_d}{\bar{C}_n} \cdot e^{\tilde{P}_{d,t+1} - \tilde{C}_{n,t+1}} \right\}$$

$$0 = E \left\{ \beta \frac{\bar{P}_d}{\bar{C}_n} (1-\delta) \cdot e^{\tilde{P}_{d,t+1} - \tilde{C}_{n,t+1}} + \beta \frac{A}{d} \cdot e^{-\tilde{d}_t} - \frac{\bar{P}_d}{\bar{C}_n} e^{\tilde{P}_{d,t} - \tilde{C}_{n,t}} \right\}$$

$$0 = E \left\{ \beta \frac{\bar{P}_d}{\bar{C}_n} (1-\delta) (1 + \tilde{P}_{d,t+1} - \tilde{C}_{n,t+1}) + \beta \frac{A}{d} \cdot (1 - \tilde{d}_t) - \frac{\bar{P}_d}{\bar{C}_n} (1 + \tilde{P}_{d,t} - \tilde{C}_{n,t}) \right\}$$

$$0 = \underbrace{\beta \frac{\bar{P}_d}{\bar{C}_n} (1-\delta) + \beta \frac{A}{d} - \frac{\bar{P}_d}{\bar{C}_n}}_{=0} + E \left\{ \beta \frac{\bar{P}_d}{\bar{C}_n} (1-\delta) \cdot \tilde{P}_{d,t+1} - \beta \frac{\bar{P}_d}{\bar{C}_n} (1-\delta) \tilde{C}_{n,t+1} - \beta \frac{A}{d} \cdot \tilde{d}_t - \frac{\bar{P}_d}{\bar{C}_n} \cdot \tilde{P}_{d,t} + \frac{\bar{P}_d}{\bar{C}_n} \tilde{C}_{n,t} \right\}$$

$$2) \frac{\bar{P}_k}{\bar{C}_n} \cdot e^{\tilde{P}_{k,t} - \tilde{C}_{n,t}} = \beta E \left\{ \frac{\bar{P}_k}{\bar{C}_n} \cdot e^{\tilde{P}_{k,t+1} - \tilde{C}_{n,t+1}} + \frac{\bar{P}_k (1-\delta)}{\bar{C}_n} \cdot e^{\tilde{P}_{k,t+1} - \tilde{C}_{n,t+1}} \right\}$$

$$\frac{\bar{P}_k}{\bar{C}_n} = \bar{P}_k \quad \bar{P}_k = \beta [\bar{r} + \bar{P}_k (1-\delta)]$$

$$0 = E \left\{ \frac{\beta \bar{P}_k}{\bar{C}_n} \cdot e^{\tilde{P}_{k,t+1} - \tilde{C}_{n,t+1}} + \frac{\beta \bar{P}_k (1-\delta)}{\bar{C}_n} \cdot e^{\tilde{P}_{k,t+1} - \tilde{C}_{n,t+1}} - \frac{\bar{P}_k}{\bar{C}_n} \cdot e^{\tilde{P}_{k,t} - \tilde{C}_{n,t}} \right\}$$

$$0 = \bar{P}_k + \beta \bar{P}_k (1-\delta) - \bar{P}_k + E \left\{ \beta \bar{r} (\tilde{P}_{k,t+1} - \tilde{C}_{n,t+1}) + \beta \bar{P}_k (1-\delta) (\tilde{P}_{k,t+1} - \tilde{C}_{n,t+1}) - \bar{P}_k (\tilde{P}_{k,t} - \tilde{C}_{n,t}) \right\}$$

$$0 = E \left\{ \beta \bar{r} \tilde{P}_{k,t+1} - [\beta \bar{r} + \beta \bar{P}_k (1-\delta)] \tilde{C}_{n,t+1} + \beta \bar{P}_k (1-\delta) \tilde{P}_{k,t+1} - \bar{P}_k \tilde{P}_{k,t} + \bar{P}_k \tilde{C}_{n,t} \right\}$$

$$3) \bar{y} \cdot e^{\tilde{y}_t} = \bar{c}_n \cdot e^{\tilde{c}_{n,t}} + \bar{c}_d \cdot e^{\tilde{c}_{d,t}} + \bar{i} \cdot e^{\tilde{i}_t}$$

$$\bar{y}(1 + \tilde{y}_t) = \bar{c}_n \cdot (1 + \tilde{c}_{n,t}) + \bar{c}_d \cdot (1 + \tilde{c}_{d,t}) + \bar{i} \cdot (1 + \tilde{i}_t)$$

$$\bar{c}_n \cdot \tilde{c}_{n,t} + \bar{c}_d \cdot \tilde{c}_{d,t} + \bar{i} \cdot \tilde{i}_t - \bar{y} \cdot \tilde{y}_t = 0$$

$$4) \bar{c}_d \cdot e^{\tilde{c}_{d,t}} = \bar{p}_d \cdot e^{\tilde{p}_{d,t}} [\bar{d} \cdot e^{\tilde{d}_t} - \bar{d}(1-\delta) e^{\tilde{d}_{t-1}}]$$

$$\bar{c}_d(1 + \tilde{c}_{d,t}) = \bar{p}_d \cdot \bar{d} (1 + \tilde{p}_{d,t} + \tilde{d}_t) - \bar{p}_d \cdot \bar{d} (1-\delta) (1 + \tilde{p}_{d,t} + \tilde{d}_{t-1})$$

$$\bar{c}_d \cdot \tilde{c}_{d,t} = \bar{p}_d \cdot \bar{d} \cdot \delta \tilde{p}_{d,t} + \bar{p}_d \cdot \bar{d} \tilde{d}_t - \bar{p}_d \cdot \bar{d} (1-\delta) \tilde{d}_{t-1}$$

$$5) \bar{i} \cdot e^{\tilde{i}_t} = \bar{p}_k \cdot e^{\tilde{p}_{k,t}} [\bar{k} \cdot e^{\tilde{k}_t} - (1-\delta) e^{\tilde{k}_{t-1}}]$$

$$\bar{i}(1 + \tilde{i}_t) = \bar{p}_k \bar{k} (1 + \tilde{p}_{k,t} + \tilde{k}_t) - \bar{p}_k \bar{k} (1-\delta) (1 + \tilde{p}_{k,t} + \tilde{k}_{t-1})$$

$$\bar{i} \cdot \tilde{i}_t = \bar{p}_k \cdot \bar{k} \cdot \delta \tilde{p}_{k,t} + \bar{p}_k \cdot \bar{k} \cdot \tilde{k}_t - \bar{p}_k \bar{k} (1-\delta) \tilde{k}_{t-1}$$

$$6) \bar{r} e^{\tilde{r}_t} = \alpha \cdot e^{z_t} (\bar{k}_n)^{\alpha-1} (\bar{h}_n)^{1-\alpha} \cdot e^{(\alpha-1) \tilde{k}_{n,t} + (1-\alpha) \tilde{h}_{n,t}}$$

$$\bar{r}(1 + \tilde{r}_t) = \alpha (\bar{k}_n)^{\alpha-1} (\bar{h}_n)^{1-\alpha} [1 + \tilde{k}_{n,t}(\alpha-1) + \tilde{h}_{n,t}(1-\alpha) + z_t]$$

$$0 = \tilde{k}_{n,t}(\alpha-1) + \tilde{h}_{n,t}(1-\alpha) + z_t - \tilde{r}_t$$

$$7) 0 = \tilde{k}_{n,t} \alpha - \alpha \tilde{h}_{n,t} - \tilde{w}_t + z_t \Rightarrow$$

$$8) \bar{r} e^{\tilde{r}_t} = \alpha \bar{p}_d \cdot e^{\tilde{p}_{d,t} + z_t + (\alpha-1) \tilde{k}_{d,t} + (1-\alpha) \tilde{h}_{d,t}} \cdot \bar{k}_d^{\alpha-1} \bar{h}_d^{1-\alpha}$$

$$\bar{r}(1 + \tilde{r}_t) = \alpha \bar{p}_d \cdot \bar{k}_d^{\alpha-1} \bar{h}_d^{1-\alpha} [1 + \tilde{p}_{d,t} + z_t + (\alpha-1) \tilde{k}_{d,t} + (1-\alpha) \tilde{h}_{d,t}]$$

$$\tilde{r}_t = \alpha \tilde{p}_{d,t} + z_t + (\alpha-1) \tilde{k}_{d,t} + (1-\alpha) \tilde{h}_{d,t}$$

$$0 = \tilde{p}_{d,t} + z_t + (\alpha-1) \tilde{k}_{d,t} + (1-\alpha) \tilde{h}_{d,t} - \tilde{r}_t$$

$$9) 0 = \tilde{p}_{d,t} + z_t + \alpha \tilde{k}_{d,t} - \alpha \tilde{h}_{d,t} - \tilde{w}_t \quad (1b) \bar{c}_n e^{\tilde{c}_{n,t}} = \bar{k}_n \bar{h}_n^{1-\alpha} e^{z_t + \tilde{k}_{n,t} \alpha + (1-\alpha) \tilde{h}_{n,t}}$$

$$(10) 0 = \tilde{p}_{k,t} + z_t + (\alpha-1) \tilde{k}_{k,t} + (1-\alpha) \tilde{h}_{k,t} - \tilde{r}_t \quad \because \bar{c}_n = \bar{k}_n \bar{h}_n^{1-\alpha}$$

$$(11) 0 = \tilde{p}_{k,t} + z_t + \alpha \tilde{k}_{k,t} - \alpha \tilde{h}_{k,t} - \tilde{w}_t \quad 1 + \tilde{c}_{n,t} = 1 + z_t + \tilde{k}_{n,t} \alpha + (1-\alpha) \tilde{h}_{n,t}$$

$$(12) \bar{h}_n \tilde{h}_{n,t} + \bar{h}_d \tilde{h}_{d,t} - \bar{h}_k \tilde{h}_{k,t} = 0$$

$$(13) \bar{k}_n \tilde{k}_{n,t} + \bar{k}_d \tilde{k}_{d,t} + \bar{k}_{k,t} \tilde{k}_k - \bar{k} \tilde{k}_{t-1} = 0$$

$$(14) \bar{k} [1 + \tilde{k}_t - (1-\delta)(1 + \tilde{k}_{t-1})] = \bar{k}^2 \bar{h}_k^{1-\alpha} [1 + z_t + \alpha \tilde{k}_{k,t} + (1-\alpha) \tilde{h}_{k,t}]$$

$$\because \frac{\bar{k}^2 \bar{h}_k^{1-\alpha}}{\bar{k}} = \delta \Rightarrow \delta + \tilde{k}_t - (1-\delta) \tilde{k}_{t-1} = \delta + z_t + \alpha \tilde{k}_{k,t} + (1-\alpha) \tilde{h}_{k,t}$$

$$(15) \tilde{d}_t - (1-\delta) \tilde{d}_{t-1} = z_t + \alpha \tilde{p}_{d,t} + (1-\alpha) \tilde{h}_{d,t}$$

$$(16.) \tilde{c}_{n,t} = z_t + \tilde{k}_{n,t} \cdot \alpha + (1-\alpha) \tilde{h}_{n,t}$$

$$(17.) \begin{aligned} \tilde{c}_{d,t} &= [\tilde{d}_t - \tilde{d}_{t-1}(1-\delta)] \times \tilde{p}_{d,t} \quad \leftarrow \bar{c}_d = \delta \bar{d} \cdot \bar{p}_d \\ \bar{c}_d \cdot e^{\tilde{c}_{d,t}} &= \bar{d} \bar{p}_d [e^{\tilde{d}_t} - e^{\tilde{d}_{t-1}(1-\delta)}] \times \tilde{p}_{d,t} \cdot e^{\tilde{p}_{d,t}} \quad \frac{\bar{c}_d}{\bar{p}_d \cdot \bar{d}} = \delta \end{aligned}$$

$$\begin{aligned} \delta \cdot (1 + \tilde{c}_{d,t}) &= (1 + \tilde{d}_t + \tilde{p}_{d,t}) - (1-\delta)(1 + \tilde{d}_{t-1} + \tilde{p}_{d,t}) \\ \delta + \delta \tilde{c}_{d,t} &= \delta + \tilde{d}_t + \delta \tilde{p}_{d,t} - (1-\delta) \tilde{d}_{t-1} \\ \tilde{d}_t - (1-\delta) \tilde{d}_{t-1} + \delta \tilde{p}_{d,t} - \delta \tilde{c}_{d,t} &= 0 \end{aligned}$$

$$(18.) \begin{aligned} \tilde{v}_t &= [\tilde{k}_t - \tilde{k}_{t-1}(1-\delta)] \times \tilde{p}_{k,t} \\ \tilde{k}_t - (1-\delta) \tilde{k}_{t-1} + \delta \tilde{p}_{k,t} - \delta \tilde{v}_t &= 0 \end{aligned}$$

$$(20.) \begin{aligned} \tilde{c}_{n,t} + \tilde{p}_{d,t} [\tilde{d}_t - \tilde{d}_{t-1}(1-\delta)] + \tilde{p}_{k,t} [\tilde{k}_t - \tilde{k}_{t-1}(1-\delta)] &= r_t \tilde{k}_{t-1} + \tilde{w}_t \\ \bar{c}_n + \bar{p}_d \cdot \delta \bar{d} + \bar{p}_k \cdot \delta \bar{k} &= \bar{r} \bar{k} + \bar{w} \\ \bar{c}_n e^{\tilde{c}_{n,t}} + \bar{p}_d \cdot \bar{d} \cdot e^{\tilde{p}_{d,t}} [e^{\tilde{d}_t} - e^{\tilde{d}_{t-1}(1-\delta)}] + \bar{p}_k \cdot \bar{k} [e^{\tilde{k}_t} - e^{\tilde{k}_{t-1}(1-\delta)}] \cdot e^{\tilde{p}_{k,t}} &= \bar{r} \bar{k} \cdot e^{\tilde{k}_t + \tilde{k}_{t-1}} + \bar{w} e^{\tilde{w}_t} \end{aligned}$$

$$\begin{aligned} \bar{c}_n(1 + \tilde{c}_{n,t}) + \bar{p}_d \cdot \bar{d} (1 + \tilde{p}_{d,t} + \tilde{d}_t) - \bar{p}_d \cdot \bar{d} (1-\delta) (1 + \tilde{p}_{d,t} + \tilde{d}_{t-1}) \\ + \bar{p}_k \cdot \bar{k} (1 + \tilde{p}_{k,t} + \tilde{k}_t) - \bar{p}_k \cdot \bar{k} (1-\delta) (1 + \tilde{p}_{k,t} + \tilde{k}_{t-1}) &= \bar{r} \bar{k} (1 + \tilde{k}_t + \tilde{k}_{t-1}) + \bar{w} (1 + \tilde{w}_t) \\ \bar{c}_n \tilde{c}_{n,t} + \bar{p}_d \cdot \bar{d} \cdot \delta \tilde{p}_{d,t} + \bar{p}_d \cdot \bar{d} \cdot \tilde{d}_t - \bar{p}_d \cdot \bar{d} (1-\delta) \tilde{d}_{t-1} \\ + \bar{p}_k \cdot \bar{k} \cdot \delta \tilde{p}_{k,t} + \bar{p}_k \cdot \bar{k} \cdot \tilde{k}_t - [\bar{p}_k \cdot \bar{k} (1-\delta) + \bar{r} \bar{k}] \cdot \tilde{k}_{t-1} &= \bar{r} \bar{k} \cdot \tilde{k}_t + \bar{w} \tilde{w}_t = 0 \end{aligned}$$

model correation matrx	cn	cd	i	y	
cn	1.00	-0.22	0.23	1.00	
cd	-0.22	1.00	-1.00	-0.20	
i	0.23	-1.00	1.00	0.22	
y	1.00	-0.20	0.22	1.00	
real data correlation	cn	cd	i	y	
cn	1.00	0.76	0.60	0.83	
cd	0.76	1.00	0.47	0.55	
i	0.60	0.47	1.00	0.64	
y	0.83	0.55	0.64	1.00	
	cn_y	cd_y	i_y	y	cd_cn
model relative volatility	0.53	2.93	4.58	1.00	5.53
real relative volatility	1.40	5.01	2.96	1.00	3.57
pct captured	2.65	1.71	0.65		0.65