Massive 3D Depositor Senior Capstone Design

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# Abstract

# Problem Definition

## Identification of Need or Opportunity

Over the past decade, 3D printing has become a popular manufacturing technique, due to its rapid per-unit production speed and low cost. However, traditional FDM printing is shied away from for heavy duty use due to the low printing temperatures (~200 °C) available on most printers, and commercial-grade, high temperature printers cost in the five figures. In this report, we outline the steps needed to build a 3D printer capable to printing large items (1’x1’x4’) at high temperatures (400 °C) while costing less than $5,000.

# Basic Research

## Existing Solutions

Below is a table of existing solutions of printer that can print PEEK

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| PEEK Printer Name | Build Volume (mm^3) | Max Extruder Temp | Max Bed Temp | Max Chamber Temp | Price |
| Intamsys Funmat HT | 1.76E+07 | 450 | 160 | 90 | 6,000 |
| Tractus3D T850P | 3.14E+07 | 450 | 175 | 80 | 15,000 |
| CreatBot PEEK-300 | 3.60E+07 | 500 | 200 | 120 | 17,000 |
| Apium P220 | 4.77E+06 | 540 | 160 | 220 | 46,000 |
| Zortrax Endureal | 3.60E+07 | 480 | 220 | 200 | 58,000 |
| Roboze One+400 Xtreme | 1.65E+07 | 500 | 150 | N/A | 50,000 |
| 3ntr Spectral 30 | 2.70E+07 | 500 | 300 | 250 | 110,000 |
| Essentium HSE 180 HT | 2.07E+08 | 550 | 100 | 200 | 149,000 |
| 3DGence Industry F340 | 2.65E+07 | 500 | 160 | 85 | 30,000 |
| MiniFactory Ultra | 1.07E+07 | 480 | 250 | 250 | 50,000 |
| Stratasys Fortus 450mc | 5.85E+07 | 450 | 250 | 350 | 160,000 |
| Aon-M2+ | 1.30E+08 | 450 | 200 | 135 | 50,000 |

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Averages** | 5.01E+07 | 490 | 193 | 165 | 61,000 |
| **M3DD Printer** | 1.12E+08 | 450 | 200 | 80 | 5,000 |

## Market Analysis

# Design Requirements

Functional Requirements

* System should respond to movement commands in the X,Y, Z, and Extruder directions
* System should be able to heat nozzle up to 450 °C, bed up to 200 °C, and chamber up to 80 °C
* System should be able to print all common filament types (PLA, ABS, PETG) with and without the heated chamber
* System should be able to print PEEK and PSU objects
* System should have a total usable print volume of 300x280x1330mm
* System should be able to operate at the maximum chamber temperature for at least 3 days continuously without overheating or having part failure
* System will have thermal protection for the hotend, heated bed, and chamber
* System will have fused connections in the event of a short circuit

Usability Requirements

* System should be able to operate on a local 15A breaker without the heated chamber and with the heated chamber on two separate 15A circuits

User experience requirements

* User can control the temperature and movement of the system locally through the LCD
* User can control nozzle, bed, and chamber temperature, X,Y and Z movement system, send commands, start, stop and monitor prints, through a web interface

# Initial Concept Generation

# Preliminary Analysis

Power Analysis

We plan on splitting up the power up onto 3 circuits to satisfy the design requirements. We are having 2 AC circuits for our chamber heating elements, and then a 3rd AC circuit for all other components. The heating elements of the space heaters we are planning on using are 1500W each. At 120V, this yields per space heater. We are assuming to use 2 space heaters, although we won’t be able to know for sure until we complete full thermal analysis.

For the DC components, we need to pick an adequate power supply. Below is a table of the power draw requirement estimates for each component. For the voltage conversions, we are assuming a conversion efficiency of 90% for our buck converters.

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| Part | Voltage/unit | Amperage/unit (with conversion efficiency included) | Quantity | Total Amperage Used |
| Name 17 2A motor | 24 | 2 | 3 | 144 |
| Nema 17 motor (high power) | 24 | 0.58 | 2 | 27.84 |
| SKR Board | 24 | 0.5 | 1 | 7.2 |
| Heater Cartidge | 24 | 2.08 | 1 | 49.92 |
| Space heater fans | 12 | 0.33 | 2 | 10.386 |
| RPi | 5 | 0.5 | 1 | 2.5 |
| LED Strip | 5 | 0.06 | 5 |  |
| Peltier Plates (@ 5V) | 5 | 1.5 | 2 | 15 |
| Bed heater element (AC power) | AC | 4.1 | 1 | 98.4 |

Total wattage used: 355.246

The power supply we chose was a Meanswell 24V/21A power supply.

Movement Analysis

Thermal Analysis

# Schedule

|  |  |  |  |
| --- | --- | --- | --- |
| Week | Date | Timeline |  |
| Week 1 | 01/18 – 01/21 | Project selection |  |
| Week 2 | 01/24 – 01/28 |  |  |
| Week 3 | 01/31 – 02/04 |  |  |
| Week 4 | 02/07 – 02/11 |  |  |
| Week 5 | 02/14 – 02/18 |  |  |
| Week 6 | 02/21 – 02/25 |  |  |
| Week 7 | 02/28 – 03/04 |  |  |
| Week 8 | 03/07 – 03/11 |  |  |
| Week 9 | 03/14 – 03/18 |  |  |
| Week 10 | 03/21 – 03/25 |  |  |
| Week 11 | 03/28 – 04/01 |  |  |
| Week 12 | 04/04 – 04/08 |  |  |
| Week 13 | 04/11 – 04/15 |  |  |
| Week 14 | 04/18 – 04/22 |  |  |
| Week 15 | 04/25 – 04/29 |  |  |

# Preliminary Budget

|  |  |  |
| --- | --- | --- |
| Name | Cost | Quantity |
| SKR 2 | 49.99 | 1 |
| Rpi | 34.99 | 1 |
| Buck Converter | 9.99 | 1 |
| LCD | 16.95 | 1 |
| SSR | 10.49 | 3 |
| Fuses | 8.47 | 1 |
| Power Supply | 35.99 | 1 |
| Aluminum Extrusions | 23.25 | 2 |
| High power motor | 13.99 | 2 |
| Low power motor | 10.99 | 2 |
| Extruder | 12.99 | 1 |
| Peltier Plates + heatsinks | 31.35 |  |
| 24V fans | 11.99 | 1 |
| pi camera + 6ft cable | 15.04 |  |
| End stops | 9.99 | 2 |
| Mosquito hotend | 149.99 | 1 |
| mosquito thermistor | 69.99 | 1 |
| heater cartridge | 15.99 | 1 |
| led strip | 11.92 | 1 |
| Garolite | 15.95 | 2 |
| Heated bed | 159.99 | 1 |
| wires | 20 | 2 |
| Lead screws | 55 | 2 |
| anti-backlash nuts | 10.98 | 1 |
| Insulation | 100 | 1 |
| Kaolin cloth | 20 | 1 |
| High temp belt | 11.99 | 1 |
| high temp wheels | 21.99 | 1 |
| breaker | 9.99 | 1 |
| outlets | 9.99 | 1 |
| switches | 9.99 | 1 |
| sheet metal | 30 | 1 |
| frame | 0 | 1 |
| bowden setup | 19.99 | 1 |
| printed parts (estimate) | 100 | 1 |
| wifi adapter | 10.55 | 1 |
| bltouch | 40.26 | 1 |
| capacitors | 11.65 | 1 |
| **Total:** | **1626.43** |  |
| **30% price increase** | **2114.359** |  |

# Conclusions and Next Steps

# Bibliography

Massive 3D Depositor

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Introduction

Engineering Design Choices

Frame

For a frame, aluminum extrusions are the de-factor standard for 3D printing frames due to their structural rigidity, low cost, and high functionality. We chose aluminum frames for the movement system an any structural pieces needed in a traditional FDM 3D printer. For the chamber frame, we chose to use a server rack. We found an server rack out-competed aluminum extrusions considering the overall size and mounting ease. This is a piece that would be trivial to replace given the required critical dimensions if another unit needed to be manufactured. The server rack will have insulation mounted to the outside of it and will provide a structural foundation for mounting our aluminum extrusion-based movement system.

Movement system

To move the hotend around the build volume, we are using a cartesian movement system with a pulley/belt combination for the X and Y directions. The X and Y axes were easy to design and build as they fall within the typical size, so we were able to look at comparable products. However, the Z-axis requires a lot of engineering due to it’s unorthodox size. For most cartesian printers, using a lead screw is the best options since it is sturdy and cost-effective. A 5’ lead screw, like we need, will bend in the middle no matter how perfectly the screw is made.

will require a lot of fine-tuning since our lead screw is so long it starts to bend. This is the only movement system that will work for our application. A coreXY printer would require an assembly the size of the bed volume to move through the entire print volume. This drastically increases complexity and would leave no room for auxiliary components like the heating elements. A delta printer would work in theory, but at the height we are printing at

Heating system

Electronics

Power routing

Novel solutions

Movement system

For our X and Y directions, our movement system uses a classic motor/belt combination along with v-rollers as a guide. Our Z direction, we extended

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