Problem Set 7

April 5, 2019

(1) CP 9.2 *Solving Poisson's equation with over-relaxation and the Gauss-Seidel method* The electric potential in a region with no charge is given by the solution to the Laplace equation

$$\nabla^2 V = 0$$
.

subject to boundary conditions. This equation can be solved numerically by dividing the region into bins, and setting the potential in each bin equal to the average of its non-diagonal neighbors. If you iterate the process, potential values eventually converge. This process can be sped up if you use the Gauss-Seidel (GS) method. In the GS method, as you move across the bins, taking the averages, you use the new updated values for the trailing bins in the averaging. You can combine this with over-relaxation, in which you overshoot the average by a little bit. This can improve the speed by an order of magnitude.

Below, I solve Laplace's equation for a box, where 3 sides are grounded and the top edge is at 1V.

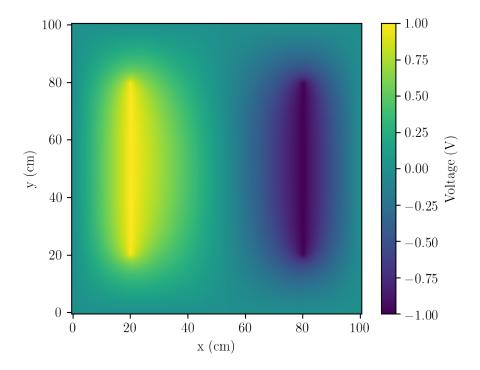
```
phi[:,-1] = V
         # Main loop
         delta = 1.0
         while delta > tol:
             # save a copy for error estimation
             copy = np.copy(phi)
             # calculate new values of the potential
             for i in range(1,M):
                 for j in range(1,M):
                     phi[i,j] = (1+w)/4*(phi[i+1,j] + phi[i-1,j] + 
                                           phi[i,j+1] + phi[i,j-1]) - \
                                           w*phi[i,j]
             # max difference
             delta = np.max(np.abs(phi-copy))
In [22]: # plot the results
         plt.imshow(phi.T,origin="lower",interpolation="gaussian")
         plt.xlabel("x (cm)")
         plt.ylabel("y (cm)")
         cb = plt.colorbar()
         cb.set_label("Voltage (V)")
         plt.show()
                                                                  1.0
                100
                                                                  - 0.8
                 80 \cdot
                 60
                 40 ·
                 20 -
                                                                 - 0.2
                                                                  0.0
                            20
                                   40
                                           60
                                                   80
                                                           100
                    0
```

x (cm)

(2) CP 9.3 Solving Poisson's equation with over-relaxation and the Gauss-Seidel method

The structure of this problem (and its solution) is identical to the previous problem. This time, the edges of the box are all grounded, and there are two plate capacitors in the box, held at $\pm 1V$.

```
In [23]: # constants
        M = 100 # bins per side
         V = 1.0
         w = 0.9
         tol = 1e-2 # error tolerance
         # potential values
         phi = np.zeros([M+1,M+1],float)
         phi[20,20:-20] = 1
         phi[80,20:-20] = -1
         # Main loop
         delta = 1.0
         while delta > tol:
             # save a copy for error estimation
             copy = np.copy(phi)
             # calculate new values of the potential
             for i in range(1,M):
                 for j in range(1,M):
                     if (i != 20 and i != M-20) or (j < 20 or j > M-20):
                         phi[i,j] = (1+w)/4*(phi[i+1,j] + phi[i-1,j] + 
                                             phi[i,j+1] + phi[i,j-1]) - \
                                             w*phi[i,j]
             # max difference
             delta = np.max(np.abs(phi-copy))
In [24]: # plot the results
        plt.imshow(phi.T,origin="lower",interpolation="gaussian")
         plt.xlabel("x (cm)")
         plt.ylabel("y (cm)")
         cb = plt.colorbar()
         cb.set_label("Voltage (V)")
         plt.show()
```



(3) **CP 9.4** Flow of heat in the Earth's crust

The diffusion of heat is determined by the heat equation

$$\frac{\partial T}{\partial t} = D \frac{\partial^2 T}{\partial x^2},$$

where D is the thermal diffusivity. You can solve this equation by splitting the domain x into N points. You can then estimate the second derivative using secants:

$$\frac{\partial^2 \phi}{\partial x^2} = \frac{1}{a^2} [\phi(x+a,t) + \phi(x-a,t) - 2\phi(x,t)],$$

where a is the point separation. We can then treat the value of ϕ at each point as an independent variable, and solve the system as a system of simultaneous ODE's, which can be done with Euler's method.

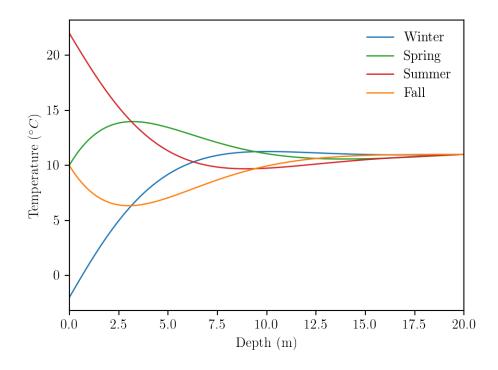
Below I solve the heat equation for the Earth's crust. I model the surface temperature as a function of days t:

$$T_0(t) = 10^{\circ}C + 12^{\circ}C\sin\frac{2\pi t}{365 \text{ days}}.$$

I model the temperature to a depth of 20 m, where the temperature is a constant $11^{\circ}C$. The thermal diffusivity is $D = 0.1 \text{m}^2 \text{day}^{-1}$. I solve for 9 years to allow my arbitrary initial conditions to relax into normal values, then I plot the temperature every three months for a year.

```
In [27]: # constants
         L = 20 \# max \ depth, m
         D = 0.1 # thermal diffusivity, m^2/day
         N = 100 \# number of bins
         a = L/N # bin spacing, m
         h = 1e-1 \# time step, days
         epsilon = h/2
         # temperature fluctation
         T0 = lambda t: 10 + 12*np.sin(2*np.pi*t/365)
         # arrays
         T = np.zeros(N+1,float)
         T[0] = T0(0) # C
         T[1:N] = 10 \# C
         T[N] = 11 \# C
         # times to plot
         tlist = np.array([9,9.25,9.5,9.75,10])*365
         tend = tlist[-1] + epsilon
         Tsave = np.copy(T)
         # Main loop
         t = 0.0
         c = h*D/a**2
         while t < tend:
             # calculate new T values
             T[0] = T0(t)
             for i in range(1,N):
                 T[i] = T[i] + c*(T[i+1] + T[i-1] - 2*T[i])
             t += h
             for ti in tlist:
                 if abs(t-ti) < epsilon:</pre>
                     Tsave = np.vstack((Tsave,T))
         plt.show()
In [28]: x = np.linspace(0, L, len(T))
         plt.plot(x,Tsave[4],c="CO",label="Winter")
         plt.plot(x,Tsave[3],c="C2",label="Spring")
         plt.plot(x,Tsave[2],c="C3",label="Summer")
         plt.plot(x,Tsave[1],c="C1",label="Fall")
         plt.legend()
```

```
plt.xlim(0,20)
plt.xlabel("Depth (m)")
plt.ylabel("Temperature ($^{\circ}C$)")
plt.show()
```



(4) CP 9.5 *The wave equation*

The same methods of the previous section can be used to solve the wave equation

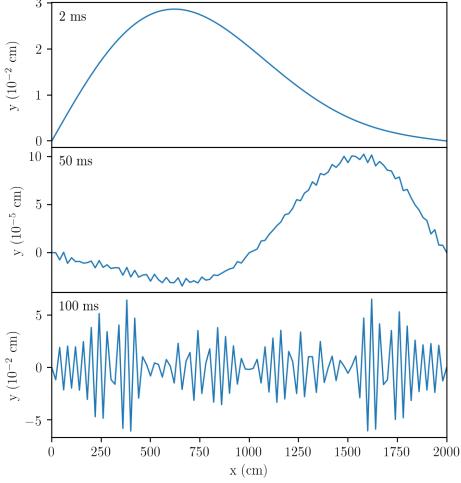
$$\frac{\partial^2 \phi}{\partial x^2} - \frac{1}{v^2} \frac{\partial^2 \phi}{\partial t^2} = 0,$$

however, the solution is unstable. The solution is only accurate for a short amount of time, and the numerical instabilites grow rapidly to overwhelm the behavior. This is seen blow, where I solve the wave equation for waves on a string.

```
In [8]: # constants
    v = 100 # wave speed, m/s
    L = 1 # string length, m
    d = 0.1 # m
    C = 1 # m/s
    sig = 0.3 # m
```

```
a = L/N \# bin spacing
        h = 1e-6 \# s
        epsilon = h/1000
        # initial conditions
        phi0 = lambda x: C*x*(L-x)/L**2*np.exp(-(x-d)**2/(2*sig**2))
        # arrays
        phi = np.zeros(N+1,float)
        psi = phi0(np.linspace(0,L,N+1))
        # times to plot
        tlist = [2e-3,50e-3,100e-3]
        tend = tlist[-1] + epsilon
        save = np.copy(phi)
        # Main loop
        t = 0.0
        while t < tend:
            phi2 = np.copy(phi)
            psi2 = np.copy(psi)
            # calculate new values
            for i in range(1,N):
                psi[i] = psi2[i] + h*v**2/a**2*(phi2[i+1] + phi2[i-1] - 2*phi2[i])
                phi[i] = phi2[i] + h*psi2[i]
            t += h
            for ti in tlist:
                if abs(t-ti) < epsilon:</pre>
                    save = np.vstack((save,phi))
        plt.show()
In [46]: # plot the results
         fig,(ax1,ax2,ax3) = plt.subplots(3,1,figsize=(5.3,6),sharex=True)
         xmax = 100*L # cm
         x = np.linspace(0,xmax,N+1)
         ax1.plot(x,save[1]*1e4)
         ax2.plot(x,save[2]*1e7)
         ax3.plot(x,save[3]*1e4)
         ax1.set_xlim(0,xmax)
```

N = 100 # number of bins



You can see that as time progresses 3 ms \rightarrow 50 ms \rightarrow 100 ms, the numerical instabilities grow.

(5) CP 9.9 *Solving the Schroedinger Equation with the spectral method* For the wave equation in a box, the general solution to the Schroedinger equation is

$$\psi(x_n, t) = \frac{1}{N} \sum_{k=1}^{N-1} b_k \sin(\pi k n/N) \exp(i\frac{\pi^2 \hbar k^2}{2ML^2} t),$$

where x_n is the position of point n, N is the total number of points, and L is the width of the box.

Notice, that this sum is just a Fourier series! If you know the initial conditions $\psi(x,0)$, you can take the inverse Fourier transform to find the coefficients b_k , and then you immediately have the solution for all future times t. I do this below for the initial condition

$$\psi(x,0) = \exp\left[-\frac{(x-x_0)^2}{2\sigma^2}\right]e^{ikx}.$$

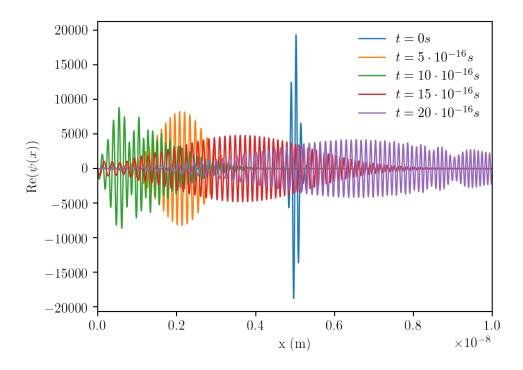
```
In [48]: # constants
        L = 1e-8 \# m
         M = 9.109e-31 \# electron mass, kq
         x0 = L/2 \# m
         sig = 1e-10 \# m
         k = 5e10 \# 1/m
         hbar = 1.05457e-34 \# m^2 * kg/s
         # initial conditions
         f = lambda x: np.exp(-(x-x0)**2/(2*sig**2) + 1j*k*x)
         N = 10000 \# number of points
         x = np.linspace(0,L,N)
         psi0 = f(x)
         # fourier transform
         alpha = dst(np.real(psi0)) # real part
         eta = dst(np.imag(psi0)) # imaginary part
         # calculate Re(psi(t)) via inverse fourier transform
         coeff = lambda t: [alpha[k]*cos(pi**2*hbar*k**2/(2*M*L**2)*t) -
                            eta[k]*sin(pi**2*hbar*k**2/(2*M*L**2)*t)
                            for k in range(len(alpha))]
         psi0 = idst( coeff(0) )
         psi1 = idst(coeff(5e-16))
         psi2 = idst(coeff(10e-16))
         psi3 = idst(coeff(15e-16))
         psi4 = idst(coeff(20e-16))
```

First I plot the real part of the wave-function:

```
In [54]: plt.plot(x,psi0,label="$t=0s$")

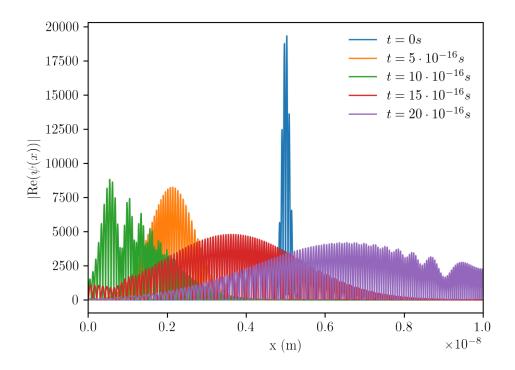
plt.plot(x,psi1,label="$t=5 \cdot 10^{-16}s$")
```

```
plt.plot(x,psi2,label="$t=10 \cdot 10^{-16}s$")
plt.plot(x,psi3,label="$t=15 \cdot 10^{-16}s$")
plt.plot(x,psi4,label="$t=20 \cdot 10^{-16}s$")
plt.legend()
plt.xlim(0,1e-8)
plt.xlabel("x (m)")
plt.ylabel("Re($\psi(x)$)")
plt.show()
```



To make the behavior more transparent, I plot the absolute value of the real part:

```
In [56]: plt.plot(x,abs(psi0),label="$t=0s$")
    plt.plot(x,abs(psi1),label="$t=5 \cdot 10^{-16}s$")
    plt.plot(x,abs(psi2),label="$t=10 \cdot 10^{-16}s$")
    plt.plot(x,abs(psi3),label="$t=15 \cdot 10^{-16}s$")
    plt.plot(x,abs(psi4),label="$t=20 \cdot 10^{-16}s$")
    plt.legend()
    plt.xlim(0,1e-8)
    plt.xlabel("x (m)")
    plt.ylabel("$\$Re(\$\psi(x)\$)\$\$")
    plt.show()
```



It is easy to see that the wave function starts concentrated in the center. It then moves left and then reflects off the wall. As it travels, the wave packet also spreads. This can really be seen in the red and purple plots. The purple plot is interesting on the right, as you can see some destructive interference as the front edge of the wave function begins to reflect off the wall.