

```
(*Compute Jacobian of ODE system assuming Gaussian bcr0 and cd0 signaling
with eqs S1 - S5 from Martinez2012
```

```
References:
```

```
https://resources.wolframcloud.com/FunctionRepository/resources/JacobianMatrix/
```

```
https://mathematica.stackexchange.com/questions/5790/how-to-make-jacobian-automatically-in-m
*)
```

```
Clear["Global`*"]
```

```
dissociation[k_, ui_] :=  $\frac{k^2}{k^2 + u_i^2}$  ;
```

```
protein[k_, ui_] :=  $\frac{u_i^2}{k^2 + u_i^2}$  ;
```

```
In[ ]:= (*Equations S1 - S5 in Martinez2012
```

```
NOTE: I use capital subscripts to avoid mathematica treating subscripts as state vars
*)
```

```
bcr0 = bcr0MaxSignal*PDF[NormalDistribution[
    bcr0MaxSignalCenteredOnTimestep,
    bcr0MaxSignalTimestepStd], t];
```

```
BCR = bcr0*dissociation[kb, b];
```

```
cd0 = cd0MaxSignal*PDF[
    NormalDistribution[
    cd0MaxSignalCenteredOnTimestep,
    cd0MaxSignalTimestepStd], t];
```

```
CD40 = cd0*dissociation[kb, b];
```

```
u = {p, b, r};
```

```
ds = {
     $\mu p + \sigma p \text{dissociation}[kb, b] + \sigma p \text{protein}[kr, r] - \lambda p p,$ 
     $\mu b + \sigma b \text{dissociation}[kp, p] \text{dissociation}[kb, b] \text{dissociation}[kr, r] - (\lambda b + \text{BCR}) b,$ 
     $\mu r + \sigma r \text{protein}[kr, r] + \text{CD40} - \lambda r r$ 
};
```

```
jacobianDs = Grad[ds, u];
```

```
In[•]:= jacobianDs[[1]]
```

$$Out[*]= \left\{ -\lambda p, -\frac{2 \text{ b k b}^2 \sigma p}{(\text{b}^2 + \text{k b}^2)^2}, -\frac{2 \text{ r}^3 \sigma p}{(\text{k r}^2 + \text{r}^2)^2} + \frac{2 \text{ r } \sigma p}{\text{k r}^2 + \text{r}^2} \right\}$$

```
In[•]:= jacobianDs[[2]]
```

$$Out[*]= \left\{ -\frac{2 \text{ kb}^2 \text{ kp}^2 \text{ kr}^2 \text{ p} \sigma \text{ b}}{(b^2 + \text{kb}^2)(\text{kp}^2 + \text{p}^2)(\text{kr}^2 + r^2)}, -\frac{\sqrt{2} \text{ b}^2 \text{ bcr0MaxSignal} \text{ e}^{-\frac{(-\text{bcr0MaxSignalCenteredOnTimestep})^2}{2 \text{ bcr0MaxSignalTimestepStd}}} \text{ kb}^2}{\text{bcr0MaxSignalTimestepStd} (b^2 + \text{kb}^2)^2 \sqrt{\pi}} - \right.$$

$$\frac{\text{bcr0MaxSignal} \text{ e}^{-\frac{(-\text{bcr0MaxSignalCenteredOnTimestep})^2}{2 \text{ bcr0MaxSignalTimestepStd}}} \text{ kb}^2}{\text{bcr0MaxSignalTimestepStd} (b^2 + \text{kb}^2) \sqrt{2 \pi}} - \lambda \text{ b} -$$

$$\left. \frac{2 \text{ b kb}^2 \text{ kp}^2 \text{ kr}^2 \sigma \text{ b}}{(b^2 + \text{kb}^2)^2 (\text{kp}^2 + \text{p}^2)(\text{kr}^2 + r^2)}, -\frac{2 \text{ kb}^2 \text{ kp}^2 \text{ kr}^2 \text{ r} \sigma \text{ b}}{(b^2 + \text{kb}^2)(\text{kp}^2 + \text{p}^2)(\text{kr}^2 + r^2)^2} \right\}$$

```
In[•]:= jacobianDs[[3]]
```

$$Out[*] = \left\{ 0, -\frac{\sqrt{2} \text{ b cd0MaxSignal } e^{-\frac{(-\text{cd0MaxSignalCenteredOnTimestep})^2}{2 \text{ cd0MaxSignalTimestepStd}}}}{\text{cd0MaxSignalTimestepStd} (b^2 + kb^2)^2 \sqrt{\pi}}, -\lambda r - \frac{2 r^3 \sigma r}{(kr^2 + r^2)^2} + \frac{2 r \sigma r}{kr^2 + r^2} \right\}$$

(\*To be converted to prettier equations later\*)

```
TeXForm[jacobianDs // MatrixForm]
```

`Out[•]//TeXForm=`[illegible]

```

2} b^2 \text{bcr0MaxSignal} \text{kb}^2
e^{\frac{(t-\text{bcr0MaxSignalCenteredOn}
Timestep))^2}{2
\text{bcr0MaxSignalTimestepStd}^2}}{\sqrt{
\pi }} \text{bcr0MaxSignalTimestepStd}
\left(b^2+\text{kb}^2\right)^2-\frac{2 b
\text{kb}^2 \text{kp}^2 \text{kr}^2
\text{\sigma}
$b}}{\left(b^2+\text{kb}^2\right)^2
\left(\text{kp}^2+p^2\right)
\left(\text{kr}^2+r^2\right)}-\text{\lambda}
da $b$ & -\frac{2 \text{kb}^2 \text{kp}^2
\text{kr}^2 r \text{\sigma}
$b}}{\left(b^2+\text{kb}^2\right)
\left(\text{kp}^2+p^2\right)
\left(\text{kr}^2+r^2\right)^2} \backslash
0 & -\frac{\sqrt{2} b \text{cd0MaxSignal}
\text{kb}^2
e^{\frac{(t-\text{cd0MaxSignalCenteredOnT}
imestep))^2}{2
\text{cd0MaxSignalTimestepStd}^2}}}{\sqrt{
\pi }} \text{cd0MaxSignalTimestepStd}
\left(b^2+\text{kb}^2\right)^2 & \frac{2
r \text{\sigma}
$r}}{\text{kr}^2+r^2}-\frac{2 r^3
\text{\sigma}
$r}}{\left(\text{kr}^2+r^2\right)^2}-\text{
{\lambda} $r} \backslash
\end{array}
\right)

```