



(a) Input Map



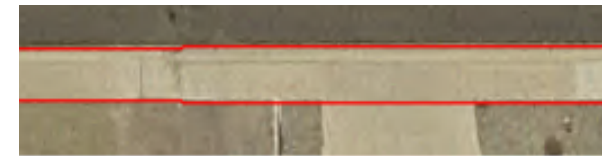
(b) Initial Trajectory



(c) Ribbon Image Generation



(d) Density Estimation  
for pixels



(e) Apply DP Solution



(f) Reshape Sidewalk