

Online Appendix: Learning from Quant (Qual)-itative Information

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1. Mathematical Appendix

Proof of Theorem (1). The extrema of a functional of the form $J[y] = \int_a^b H(y(x), y'(x), x) dx$ with boundary conditions $y(a) = y_a$ and $y(b) = y_b$ is given by the solution to the differential equation $H_y(y(x), y'(x), x) - \frac{d}{dx} H_{y'}(y(x), y'(x), x) = 0$ where $H_y, H_{y'}$ are the partial derivatives of H with respect to y and y' (See Dacorogna (1992, Theorem 2.1)). For the particular case in which the functional is of the form of equation (3) the Euler-Lagrange equation can be written as:

$$\frac{d^2 G}{dx^2} \frac{dF}{dx} - \frac{dG}{dx} \frac{d^2 F}{dx^2} = 0$$

or for a normal prior with mean μ and variance σ^2

$$\frac{d^2 G}{dx^2} + \left(\frac{x - \mu}{\sigma^2}\right) \frac{dG}{dx} = 0$$

The integrating factor $\exp\{\frac{x^2 - 2\mu x}{2\sigma^2} + C\}$ where C is a constant can be rewritten as $C_1 \exp\{\frac{1}{2}(\frac{x - \mu}{\sigma})^2\}$ where $C_1 = \exp\{-(\frac{\mu^2}{2\sigma^2} + C)\}$. This leads to the following general solution:

$$\frac{dG}{dx} = C_2 \exp\{-\frac{1}{2}(\frac{x - \mu}{\sigma})^2\} \quad (1)$$

The value of the constant C_2 can be calculated based on the boundary conditions. There is no guarantee for the function $\frac{dG}{dx}$ to be smooth, however we can

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split the differential equation into two differential equations with boundaries at $(-\infty, \tilde{\alpha}]$ and $(\tilde{\alpha}, \infty)$ as follows:

For the interval $(-\infty, \tilde{\alpha}]$

$$C_2 \int_{-\infty}^{\tilde{\alpha}} \exp\{-\frac{1}{2}(\frac{x-\mu}{\sigma})^2\} dx = \frac{1}{2} \rightarrow C_2 = \frac{1}{2\sqrt{2\pi}\sigma\Phi(\frac{\tilde{\alpha}-\mu}{\sigma})}$$

and the interval $(\tilde{\alpha}, \infty)$

$$C_2 \int_{-\infty}^{\tilde{\alpha}} \exp\{-\frac{1}{2}(\frac{x-\mu}{\sigma})^2\} dx = \frac{1}{2} \rightarrow C_2 = \frac{1}{2\sqrt{2\pi}\sigma(1 - \Phi(\frac{\tilde{\alpha}-\mu}{\sigma}))}$$

replacing both solutions to C_2 in equation (1) gives us the p.d.f. in Theorem (1), finally integrating from $(-\infty, x)$ gives us the c.d.f.

Lemma 1. $z\Phi(z) + \phi(z) \geq 0$

PROOF.

$$z\Phi(z) + \phi(z) = \int_{-\infty}^z z\phi(x)dx + \phi(z) \geq \int_{-\infty}^z x\phi(x)dx = -\phi(x)|_{-\infty}^z + \phi(x) = 0$$

1

PROOF. of Theorem (2): If x has the p.d.f. in ??

$$\begin{aligned} \Psi(t) &= \mathbb{E}(e^{tx}) \\ &= \int_{-\infty}^{\infty} e^{tx} \frac{dG(x)}{dx} dx \\ &= \frac{1}{\sqrt{8\pi}\sigma} \left(\int_{-\infty}^{\tilde{\alpha}} \frac{1}{\Phi(\frac{\tilde{\alpha}-\mu}{\sigma})} e^{tx - \frac{1}{2}(\frac{x-\mu}{\sigma})^2} dx + \int_{\tilde{\alpha}}^{\infty} \frac{1}{(1 - \Phi(\frac{\tilde{\alpha}-\mu}{\sigma}))} e^{tx - \frac{1}{2}(\frac{x-\mu}{\sigma})^2} dx \right) \end{aligned}$$

¹I thank Dilip Sarwate for his elegant proof available in math.stackexchange.com

To derive the m.g.f. let us focus first on the term:

$$\begin{aligned}
& \int \exp \left\{ tx - \frac{1}{2\sigma^2}(x^2 - 2x\mu + \mu^2) \right\} dx \\
& \int \exp \left\{ -\frac{1}{2\sigma^2}(x^2 - 2x\mu - 2x\sigma^2\mu + \mu^2) \right\} dx \\
& \int \exp \left\{ -\frac{1}{2\sigma^2}(x^2 - 2x(\mu + \sigma^2 t) + \mu^2) \right\} dx \\
& \int \exp \left\{ -\frac{1}{2\sigma^2}(x^2 - 2x(\mu + \sigma^2 t) + (\mu + \sigma^2 t)^2 - (\mu + \sigma^2 t)^2 + \mu^2) \right\} dx \\
& \int \exp \left\{ -\frac{1}{2\sigma^2}((x - (\mu + \sigma^2 t))^2 - (\mu + \sigma^2 t)^2 + \mu^2) \right\} dx
\end{aligned}$$

Moving out of the integral all terms that do not depend on x, and plugging it into the original expression:

$$\begin{aligned}
& \frac{e^{-\frac{(\mu^2 - (\mu + \sigma^2 t)^2)}{2\sigma^2}}}{2} \left(\frac{1}{\Phi(\frac{\bar{\alpha} - \mu}{\sigma})} \int_{-\infty}^{\bar{\alpha}} \frac{1}{\sqrt{2\pi}\sigma^2} e^{-\frac{1}{2}(\frac{x - (\mu + \sigma^2 t)}{\sigma})^2} dx + \frac{1}{(1 - \Phi(\frac{\bar{\alpha} - \mu}{\sigma}))} \int_{\bar{\alpha}}^{\infty} \frac{1}{\sqrt{2\pi}\sigma^2} e^{-\frac{1}{2}(\frac{x - (\mu + \sigma^2 t)}{\sigma})^2} dx \right) \\
& \frac{e^{-\frac{(\mu^2 - (\mu + \sigma^2 t)^2)}{2\sigma^2}}}{2} \left(\frac{\Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{\Phi(\frac{\bar{\alpha} - \mu}{\sigma})} + \frac{1 - \Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{(1 - \Phi(\frac{\bar{\alpha} - \mu}{\sigma}))} \right) \\
& \frac{e^{-\frac{\mu^2 - \mu^2 - 2\mu\sigma^2 t + \sigma^4 t^2}{2\sigma^2}}}{2} \left(\frac{\Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{\Phi(\frac{\bar{\alpha} - \mu}{\sigma})} + \frac{1 - \Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{(1 - \Phi(\frac{\bar{\alpha} - \mu}{\sigma}))} \right) \\
& \Psi(t) = \frac{e^{\mu t + \frac{\sigma^2 t^2}{2}}}{2} \left(\frac{\Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{\Phi(\frac{\bar{\alpha} - \mu}{\sigma})} + \frac{1 - \Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{(1 - \Phi(\frac{\bar{\alpha} - \mu}{\sigma}))} \right)
\end{aligned}$$

PROOF. of Theorem (3): The first and second derivatives of $\Psi(t)$ are:

$$\begin{aligned}
& \frac{d}{dt} \Psi(t) = \frac{\exp\{\mu t + \frac{\sigma^2 t^2}{2}\}}{2} \times \\
& \left((\mu + \sigma^2 t) \left(\frac{\Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{\Phi(\frac{\bar{\alpha} - \mu}{\sigma})} + \frac{1 - \Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{(1 - \Phi(\frac{\bar{\alpha} - \mu}{\sigma}))} \right) - \sigma \left(\frac{\phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{\Phi(\frac{\bar{\alpha} - \mu}{\sigma})} - \frac{\phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{1 - \Phi(\frac{\bar{\alpha} - \mu}{\sigma})} \right) \right) \\
& \frac{d^2}{dt^2} \Psi(t) = \frac{\exp\{\mu t + \frac{\sigma^2 t^2}{2}\}}{2} \times \\
& \left(2(\mu + \sigma^2 t) \sigma \left(\frac{\phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{1 - \Phi(\frac{\bar{\alpha} - \mu}{\sigma})} - \frac{\phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{\Phi(\frac{\bar{\alpha} - \mu}{\sigma})} \right) + \sigma^2 \left(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma} \right) \left(\frac{\phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{1 - \Phi(\frac{\bar{\alpha} - \mu}{\sigma})} - \frac{\phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{\Phi(\frac{\bar{\alpha} - \mu}{\sigma})} \right) \right. \\
& \left. + \sigma^2 \left(\frac{\Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{\Phi(\frac{\bar{\alpha} - \mu}{\sigma})} + \frac{1 - \Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{(1 - \Phi(\frac{\bar{\alpha} - \mu}{\sigma}))} \right) + (\mu + \sigma^2 t)^2 \left(\frac{\Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{\Phi(\frac{\bar{\alpha} - \mu}{\sigma})} + \frac{1 - \Phi(\frac{\bar{\alpha} - (\mu + \sigma^2 t)}{\sigma})}{(1 - \Phi(\frac{\bar{\alpha} - \mu}{\sigma}))} \right) \right)
\end{aligned}$$

evaluating the first derivative at $t = 0$

$$\tilde{\mu} = \mu + \frac{\sigma \phi(\frac{\bar{\alpha}-\mu}{\sigma})}{2} \left(\frac{1}{1 - \Phi(\frac{\bar{\alpha}-\mu}{\sigma})} - \frac{1}{\Phi(\frac{\bar{\alpha}-\mu}{\sigma})} \right)$$

now to get the second moment we evaluate the second derivative at $t = 0$ which gives us:

$$\mu^2 + \sigma^2 + \mu\sigma \left(\frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{1 - \Phi(\frac{\bar{\alpha}-\mu}{\sigma})} - \frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{\Phi(\frac{\bar{\alpha}-\mu}{\sigma})} \right) + \frac{\sigma^2}{2} \left(\frac{\bar{\alpha} - \mu}{\sigma} \right) \left(\frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{1 - \Phi(\frac{\bar{\alpha}-\mu}{\sigma})} - \frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{\Phi(\frac{\bar{\alpha}-\mu}{\sigma})} \right)$$

Subtracting the square of the first moment $\tilde{\mu}^2$ I obtain

$$\tilde{\sigma}^2 = \sigma^2 + \frac{\sigma^2}{2} \left(\frac{\bar{\alpha} - \mu}{\sigma} \right) \left(\frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{1 - \Phi(\frac{\bar{\alpha}-\mu}{\sigma})} - \frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{\Phi(\frac{\bar{\alpha}-\mu}{\sigma})} \right) - \frac{\sigma^2}{4} \left(\frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{1 - \Phi(\frac{\bar{\alpha}-\mu}{\sigma})} - \frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{\Phi(\frac{\bar{\alpha}-\mu}{\sigma})} \right)^2$$

and after some algebra

$$\tilde{\sigma}^2 = \sigma^2 \left(1 + \frac{1}{2} \left(\frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{1 - \Phi(\frac{\bar{\alpha}-\mu}{\sigma})} - \frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{\Phi(\frac{\bar{\alpha}-\mu}{\sigma})} \right) \left(\left(\frac{\bar{\alpha} - \mu}{\sigma} \right) - \frac{1}{2} \left(\frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{1 - \Phi(\frac{\bar{\alpha}-\mu}{\sigma})} - \frac{\phi(\frac{\bar{\alpha}-\mu}{\sigma})}{\Phi(\frac{\bar{\alpha}-\mu}{\sigma})} \right) \right) \right)$$

PROOF. of Theorem (4): After receiving the quantitative signal r_1 investors posterior at time 1 is normally distributed with mean $(\alpha_0 + \frac{\omega}{\gamma + \omega} r_1)$ and standard deviation $\frac{1}{\sqrt{\gamma + \omega}}$ (See. Berk and Green (2004) Proposition (1)). Replacing this as μ and σ into the equation of the mean gives the desired result.

PROOF. of Theorem (5): The sign of $\frac{\partial F}{\partial \tilde{\alpha}} = \frac{1}{a q_0} \frac{\partial \alpha_1}{\partial \tilde{\alpha}}$ is equal to the sign of $\frac{\partial \alpha_1}{\partial \tilde{\alpha}}$, defining $\Phi = \Phi(J(\tilde{\alpha}, r_1, \alpha_0))$, $\phi = \phi(J(\tilde{\alpha}, r_1, \alpha_0))$ and $z = J(\tilde{\alpha}, r_1, \alpha_0)$

$$\begin{aligned} \frac{\partial \alpha_1}{\partial \tilde{\alpha}} = & \\ & \frac{1}{2} \times \\ & \left(\frac{(-z\Phi(-2\Phi^2 + 3\Phi - 1)\phi + (2\Phi^2 - 2\Phi + 1)\phi^2)}{(\Phi - 1)^2\Phi^2} \right) \end{aligned}$$

since $\phi > 0$ the sign of the derivative depends on the sign of the following expression:

$$f(z) = \Phi z (2\Phi^2 - 3\Phi + 1) + (2\Phi^2 - 2\Phi + 1)\phi$$

which can be factorized as:

$$f(z) = (z\Phi + \phi)(2\Phi^2 - 2\Phi + 1) - z\Phi^2$$

In order to prove that the expression is strictly positive I will prove that the function is (i) continuous, (ii) it tends to zero in the limits $\pm\infty$, (iii) there $\exists z \in \mathbb{R} : f(z) > 0$ and (iv) the function has no real roots. This implies that the function never crosses the x-axis which means it is strictly positive everywhere.

(i) f is continuous since it is a composition of continuous functions ϕ , Φ and z .

(ii) Its behaviour approaching $\pm\infty$ is:

$$\begin{aligned} \lim_{z \rightarrow \pm\infty} f(z) &= \lim_{z \rightarrow \pm\infty} 2z\Phi^3 - 2z\Phi^2 + z\Phi + 2\phi\Phi^2 - 2\phi\Phi + \phi - z\Phi^2 \\ &= \lim_{z \rightarrow \pm\infty} z\Phi(1 - \Phi)(1 - 2\Phi) + 0 \end{aligned}$$

since the limit of the term $2\phi\Phi^2 - 2\phi\Phi + \phi$ is 0 when $z \rightarrow \pm\infty$.

I use the fact that if $z \geq 1 \rightarrow (1 - \Phi(z)) \leq \phi(z)$ and that $\lim_{z \rightarrow \infty} z^k \phi(z) = 0$ for $k > 0$, we know that $\lim_{z \rightarrow \infty} z(1 - \Phi(z)) = 0$ and since $\Phi(z) = 1 - \Phi(-z)$ we know that $\lim_{z \rightarrow -\infty} z\Phi = 0$, plugging this limits into the limit of $z\Phi(1 - \Phi)(1 - 2\Phi)$ shows that the limit of $f(z)$ is zero in $\pm\infty$.

(iii, iv) I can show that the function is strictly positive for all $z < 0$ and since the function is even there are no real roots. I start by looking at the sign of the following functions: $z\Phi + \phi \geq 0$ from Proposition (1), $2\Phi^2 - 2\Phi + 1 > 0$ since it has no real roots and its convex, and $-z\Phi^2 > 0$ when $z < 0$. Finally we just need to prove that the function is even, we can use the fact that ϕ is even and that $\Phi(-z) = 1 - \Phi(z)$.

$$\begin{aligned} f(-z) &= (-z(1 - \Phi) + \phi)(2(1 - \Phi)^2 - 2(1 - \Phi) + 1) + z(1 - \Phi)^2 \\ &= (z\Phi + \phi - z)(2(1 - 2\Phi + \Phi^2) + 2\Phi - 2 + 1) + z(1 - 2\Phi + \Phi^2) \\ &= (z\Phi + \phi - z)(2\Phi^2 - 4\Phi + 2 + 2\Phi - 2 + 1) + z(1 - 2\Phi + \Phi^2) \\ &= (z\Phi + \phi - z)(2\Phi^2 - 2\Phi + 1) + z(1 - 2\Phi + \Phi^2 + \Phi^2 - \Phi^2) \\ &= (z\Phi + \phi)(2\Phi^2 - 2\Phi + 1) - z\Phi^2 \\ &= f(z) \end{aligned}$$

Which means that there are no real roots, and the function is strictly positive also for $z > 0$, which concludes the proof.

PROOF. of Proposition 2. Defining:

$$\begin{aligned}\mu &= W_1 + X_1\alpha_1 \\ \sigma^2 &= X_1^2(\sigma_1^2 + \sigma_\epsilon^2) \\ \bar{\alpha} &= W_1 + X_1\tilde{\alpha} \\ \sigma_\alpha^2 &= (\sigma_1^2 + \sigma_\epsilon^2)\end{aligned}$$

And replacing $t = -\gamma$ we have that the expected utility of the investor is equal to:

$$\frac{\exp\{-(W_1 + X_1\alpha_1)\gamma + \frac{X_1^2\sigma_\alpha^2\gamma^2}{2}\}}{2} \left(\frac{\Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha} + X_1\sigma_\alpha\gamma)}{\Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha})} + \frac{1 - \Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha} + X_1\sigma_\alpha\gamma)}{(1 - \Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha}))} \right)$$

Taking the derivative with respect to X_1 gives us:

$$\begin{aligned}& \left(\frac{\gamma\sigma_\alpha\phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha} + X_1^*\gamma\sigma_\alpha)}{\Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha})} - \frac{\gamma\sigma_\alpha\phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha} + X_1^*\gamma\sigma_\alpha)}{1 - \Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha})} \right) \\ & + (X_1^*\sigma_\alpha^2\gamma^2 - \alpha_1\gamma) \left(\frac{1 - \Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha} + X_1^*\sigma_\alpha\gamma)}{1 - \Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha})} + \frac{\Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha} + X_1^*\sigma_\alpha\gamma)}{\Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha})} \right) = 0 \\ & \phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha} + X_1^*\gamma\sigma_\alpha) \left(\frac{1}{\Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha})} - \frac{1}{1 - \Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha})} \right) \\ & + (X_1^*\sigma_\alpha\gamma - \frac{\alpha_1}{\sigma_\alpha}) \left(\frac{1 - \Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha} + X_1^*\sigma_\alpha\gamma)}{1 - \Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha})} + \frac{\Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha} + X_1^*\sigma_\alpha\gamma)}{\Phi(\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha})} \right) = 0\end{aligned}$$

Defining $\frac{\tilde{\alpha}-\alpha_1}{\sigma_\alpha} = z_\alpha$, $\Phi^\alpha = \frac{1}{\Phi(z_\alpha)} - \frac{1}{1-\Phi(z_\alpha)}$, $\Phi_1^\alpha = \frac{1}{\Phi(z_\alpha)}$, and $\Phi_2^\alpha = \frac{1}{1-\Phi(z_\alpha)}$ the first order condition becomes:

$$\phi(z_\alpha + X_1\gamma\sigma_\alpha)\Phi^\alpha + (X_1\sigma_\alpha\gamma - \frac{\alpha_1}{\sigma_\alpha})(\Phi_2^\alpha(1 - \Phi(z_\alpha + X\sigma_\alpha\gamma)) + \Phi_1^\alpha(\Phi(z_\alpha + X\sigma_\alpha\gamma))) = 0$$

or

$$\phi(z_\alpha + X_1\gamma\sigma_\alpha)\Phi^\alpha + (X_1\sigma_\alpha\gamma - \frac{\alpha_1}{\sigma_\alpha})(\Phi_2^\alpha + \Phi^\alpha\Phi(z_\alpha + X\sigma_\alpha\gamma)) = 0$$

re arranging terms the optimal holding is the solution to the following system of equations

$$\begin{aligned}\phi(y)\Phi^\alpha + (y - \frac{\tilde{\alpha}}{\sigma_\alpha})(\Phi_2^\alpha + \Phi^\alpha\Phi(y)) &= 0 \\ y &= z_\alpha + X_1\sigma_\alpha\gamma\end{aligned}$$

PROOF. of Theorem 6: The Nash equilibrium is the solution to the equations:

$$qF(r_1, \tilde{\alpha} + \Delta) + (1 - q)F(r, \tilde{\alpha}) = F(r, \tilde{\alpha})$$

and,

$$pEU(W_2(X(r_1, \tilde{\alpha} + \Delta)), r_1, \tilde{\alpha}) + (1 - p)EU(W_2(X(r_1, \tilde{\alpha})), r_1, \tilde{\alpha}) = EU(W_2(X(r_1, \tilde{\alpha})) - C, r_1, \tilde{\alpha})$$

solving for p and q gives the desired result.

PROOF. of Theorem 7:

- $\frac{\partial q}{\partial K} = \frac{F(r_1, \tilde{\alpha} + \Delta) - F(r, \tilde{\alpha})}{(F(r_1, \tilde{\alpha} + \Delta) - F(r, \tilde{\alpha}) + K)^2} > 0$
- The sign of $\frac{\partial p}{\partial C}$ can be inferred by observing that the larger C is, the difference

$$EU(W_2(X(r_1, \tilde{\alpha})), r_1, \tilde{\alpha}) - EU(W_2(X(r_1, \tilde{\alpha})) - C, r_1, \tilde{\alpha})$$

becomes larger and therefore the derivative is positive.

- $\frac{\partial q}{\partial \tilde{\alpha}} = \frac{K(\frac{\partial F(r_1, \tilde{\alpha})}{\partial \tilde{\alpha}} - \frac{\partial F(r_1, \tilde{\alpha} + \Delta)}{\partial \tilde{\alpha}})}{(F(r_1, \tilde{\alpha} + \Delta) - F(r, \tilde{\alpha}) + K)^2} < 0$ if F is convex on $\tilde{\alpha}$ (e.g. $\frac{\partial F(r_1, \tilde{\alpha})}{\partial \tilde{\alpha}} - \frac{\partial F(r_1, \tilde{\alpha} + \Delta)}{\partial \tilde{\alpha}} < 0$) and 0 if F is linear on $\tilde{\alpha}$.

References

Dacorogna, B. (1992). *Introduction to the Calculus of Variations*.