MLX90614 Device Driver 1.0.0

Generated by Doxygen 1.8.16

Thu Sep 26 2019 09:03:02

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1 MLX90614 Device Driver

This library was written to enable remote sensing of the temperature of the rotors of outrunner style brushless DC motors used in remotely piloted aircraft, for the purpose of real time data logging and air to ground telemetry.

These sensors use the SMB bus protocol to communicate. This is similar, though not identical, to the I2C bus. There is enough similarity to enable the Arduino standard Wire library to communicate with the device, however not all features can be implemented, for example it is not possible to read the flags register with standard Wire functions. 2 pins are required to interface the device to an Arduino - the SDA and SCL lines.

Installing

Download the distribution package *MLX90614.rar* and decompress it. Rename the uncompressed folder /*mlx90614*. Check that the /*mlx90614* folder contains the following files;

src/MLX90614.cpp src/MLX90614.h src/Crc8.cpp src/Crc8.h src/property.h doc/MLX90614.chm doc/MLX90614.pdf Doxyfile keywords.txt library.properties LICENSE.md README.md

Place the /mlx90614 library folder into your arduinosketchfolder/libraries/ folder.

You may need to create the libraries subfolder if its your first library. Restart the IDE.

You can also optionally install this library using the Arduino IDE built-in installer.

Documentation

MLX90614.chm and MLX90614.pdf contain the documentation for the classes.

A Doxygen script is included to enable generation of documentation. You will need the graph tool, the dot tool, and the help compiler, in addition to editing the paths to these tools in the script to suit your environment.

Author

John Fitter B.E., Eagle Air Australia Pty. Ltd. This library was inspired by a library written by Adafruit Industries.

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Version 3, 29 June 2007

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3 Class Index

3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

| CRC8 | 10 |
|--------------------------------|----|
| MLX90614 | 14 |
| Property < Type, ClassHolder > | 36 |

4 File Index

4.1 File List

Here is a list of all files with brief descriptions:

```
Crc8.cpp
8 bit CRC helper/utility class - CPP Source file

40

Crc8.h
8 bit CRC helper/utility class - CPP Header file

42

MLX90614.cpp
Melexis MLX90614 Family Device Driver Library - CPP Source file

45

MLX90614.h

52

Property.h
```

5 Class Documentation

5.1 CRC8 Class Reference

#include <Crc8.h>

Public Member Functions

```
• CRC8 (uint8_t polynomial=CRC8_DEFAULTPOLY)
```

CRC8 class constructor.

• uint8_t crc8 (void)

Return the current value of the CRC.

• uint8_t crc8 (uint8_t data)

Update the current value of the CRC.

void crc8Start (uint8_t poly)

Initialize the CRC8 object.

Private Attributes

```
• uint8_t _crc
```

• uint8_t _poly

5.1.1 Detailed Description

Definition at line 37 of file Crc8.h.

5.1.2 Constructor & Destructor Documentation

```
5.1.2.1 CRC8() CRC8::CRC8 (
uint8_t poly = CRC8_DEFAULTPOLY)
```

CRC8 class constructor.

Parameters

| in | poly | 8 bit CRC polynomial to use. |
|----|------|------------------------------|
|----|------|------------------------------|

Definition at line 36 of file Crc8.cpp.

00036 {crc8Start(poly);}

References crc8Start().

Here is the call graph for this function:



5.1.3 Member Function Documentation

```
5.1.3.1 crc8() [1/2] uint8_t CRC8::crc8 ( uint8_t data )
```

Update the current value of the CRC.

Parameters

```
in data New 8 bit data to be added to the CRC.
```

Returns

8 bit CRC current value.

```
Definition at line 49 of file Crc8.cpp.
```

References <u>crc</u>, and <u>poly</u>.

```
5.1.3.2 crc8() [2/2] uint8_t CRC8::crc8 ( void )
```

Return the current value of the CRC.

Returns

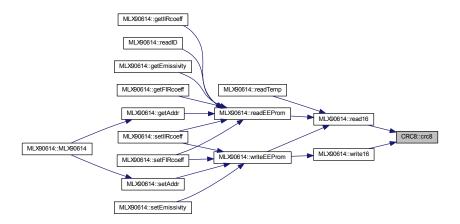
8 bit CRC current value.

```
Definition at line 42 of file Crc8.cpp.
```

References _crc.

Referenced by MLX90614::read16(), and MLX90614::write16().

Here is the caller graph for this function:



Initialize the CRC8 object.

Parameters

| in | poly | 8 bit CRC polynomial to use. |
|----|------|------------------------------|
|----|------|------------------------------|

```
Definition at line 61 of file Crc8.cpp.
```

```
00061

00062 _poly = poly;

00063 _crc = 0;

00064 }
```

References _crc, and _poly.

Referenced by CRC8().

Here is the caller graph for this function:



5.1.4 Member Data Documentation

```
5.1.4.1 _crc uint8_t CRC8::_crc [private]
```

Definition at line 44 of file Crc8.h.

Referenced by crc8(), and crc8Start().

```
5.1.4.2 _poly uint8_t CRC8::_poly [private]
```

Definition at line 45 of file Crc8.h.

Referenced by crc8(), and crc8Start().

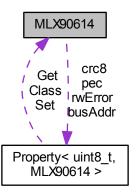
The documentation for this class was generated from the following files:

- Crc8.h
- Crc8.cpp

5.2 MLX90614 Class Reference

```
#include <MLX90614.h>
```

Collaboration diagram for MLX90614:



Public Types

- enum tempUnit_t { MLX90614_TK, MLX90614_TC, MLX90614_TF }
- enum tempSrc_t { MLX90614_SRCA, MLX90614_SRC01, MLX90614_SRC02 }

Public Member Functions

• MLX90614 (uint8_t i2caddr=MLX90614_I2CDEFAULTADDR)

MLX90614 Device class constructor.

• boolean begin ()

Initialize the device and the i2c interface.

- boolean isReady (void)
- uint64_t readID (void)

Retrieve the chip ID bytes.

uint8_t getIIRcoeff (void)

Get the coefficients of the IIR digital filter.

uint8_t getFIRcoeff (void)

Get the coefficients of the FIR digital filter.

float getEmissivity (void)

Get the emissivity (ε) of the object.

void setIIRcoeff (uint8_t csb=4)

Set the coefficients of the IIR digital filter.

void setFIRcoeff (uint8_t csb=7)

Set the coefficients of the FIR digital filter.

void setEmissivity (float emiss=1.0)

Set the emissivity (ε) of the object.

• uint16 t readEEProm (uint8 t)

Return a 16 bit value read from EEPROM.

void writeEEProm (uint8_t, uint16_t)

Write a 16 bit value to EEPROM after first clearing the memory.

double readTemp (tempSrc_t=MLX90614_SRC01, tempUnit_t=MLX90614_TC)

Return a temperature from the specified source in specified units.

• double convKtoC (double)

Convert temperature in K to ℃.

double convCtoF (double)

Public Attributes

- Property < uint8_t, MLX90614 > busAddr
- Property< uint8_t, MLX90614 > rwError
- Property< uint8_t, MLX90614 > crc8
- Property< uint8_t, MLX90614 > pec

Private Member Functions

uint16_t read16 (uint8_t)

Return a 16 bit value read from RAM or EEPROM.

• void write16 (uint8_t, uint16_t)

Write a 16 bit value to memory.

- uint8_t getRwError (void)
- uint8_t getCRC8 (void)
- uint8_t getPEC (void)
- uint8_t getAddr (void)

Return the device SMBus address.

void setAddr (uint8_t)

Set device SMBus address.

Private Attributes

- boolean _ready
- uint8_t _addr
- uint8_t _rwError
- uint8_t _crc8
- uint8_t _pec

5.2.1 Detailed Description

Examples

MelexisTest.ino.

Definition at line 104 of file MLX90614.h.

5.2.2 Member Enumeration Documentation

$\textbf{5.2.2.1} \quad \textbf{tempSrc_t} \quad \texttt{enum MLX90614::tempSrc_t}$

Enumerations for temperature measurement source.

Enumerator

| MLX90614_SRCA | Chip (ambient) sensor |
|----------------|-----------------------|
| MLX90614_SRC01 | IR source #1 |
| MLX90614_SRC02 | IR source #2 |

```
Definition at line 134 of file MLX90614.h.
```

```
00141 boolean _ready;
```

5.2.2.2 tempUnit_t enum MLX90614::tempUnit_t

Enumerations for temperature units.

Enumerator

| MLX90614_TK | degrees Kelvin |
|-------------|--------------------|
| MLX90614_TC | degrees Centigrade |
| MLX90614_TF | degrees Fahrenheit |

Definition at line 129 of file MLX90614.h.

00131 (MLX90614_SRCA, 00132 MLX90614_SRC01,

```
/**< Chip (ambient) sensor */
/**< IR source #1 */</pre>
```

5.2.3 Constructor & Destructor Documentation

```
5.2.3.1 MLX90614() MLX90614::MLX90614 (
uint8_t i2caddr = MLX90614_I2CDEFAULTADDR )
```

MLX90614 Device class constructor.

Parameters

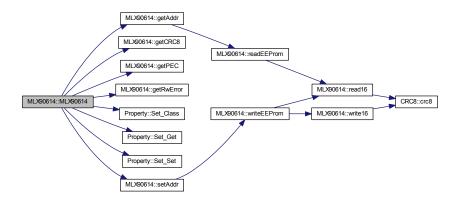
| | in | i2caddr | Device address (default: published value). | 1 |
|--|----|---------|--|---|
|--|----|---------|--|---|

Definition at line 50 of file MLX90614.cpp.

```
00050
00051
00052
          busAddr.Set_Class(this);
00053
          busAddr.Set_Get(&MLX90614::getAddr);
00054
          busAddr.Set_Set(&MLX90614::setAddr);
00055
00056
          rwError.Set_Class(this);
00057
         rwError.Set_Get(&MLX90614::getRwError);
00058
00059
         pec.Set_Class(this);
00060
         pec.Set_Get(&MLX90614::getPEC);
00061
00062
          crc8.Set_Class(this);
00063
         crc8.Set_Get(&MLX90614::getCRC8);
00064
00065
          _addr = i2caddr;
00066
          _ready = false;
00067 }
```

References _addr, _ready, busAddr, crc8, getAddr(), getCRC8(), getPEC(), getRwError(), pec, rwError, Property < Type, ClassHolder >::Set_Class(), Property < Type, ClassHolder >::Set_Get(), Property < Type, ClassHolder >::Set_Set_and setAddr().

Here is the call graph for this function:



5.2.4 Member Function Documentation

```
5.2.4.1 begin() boolean MLX90614::begin (
```

Initialize the device and the i2c interface.

Examples

MelexisTest.ino.

Definition at line 72 of file MLX90614.cpp.

```
00072

00073

00074    _rwError = _pec = _crc8 = 0;

00075    return _ready = true;

00076 }
```

References _crc8, _pec, _ready, and _rwError.

```
5.2.4.2 convCtoF() double MLX90614::convCtoF ( double degC)
```

Convert temperature in °C to °F.

Parameters

| in | degC | Temperature in ℃. |
|----|------|-------------------|
|----|------|-------------------|

Returns

Temperature in °F.

Examples

MelexisTest.ino.

Definition at line 395 of file MLX90614.cpp. 00395 {return (degC * 1.8) + 32.0;}

Referenced by readTemp().

Here is the caller graph for this function:



```
5.2.4.3 convKtoC() double MLX90614::convKtoC ( double degK)
```

Convert temperature in ${}^{\circ}\!K$ to ${}^{\circ}\!C$.

Parameters

| in d | legK | Temperature in ℃. |
|------|------|-------------------|
|------|------|-------------------|

Returns

Temperature in ℃.

Examples

MelexisTest.ino.

Definition at line 388 of file MLX90614.cpp. 00388 {return degK - 273.15;}

Referenced by readTemp().

Here is the caller graph for this function:



Return the device SMBus address.

SMB bus address getter

Remarks

- Must be only device on the bus.
- Sets the library to use the new found address.

Returns

Device address.

Definition at line 256 of file MLX90614.cpp.

```
uint8_t tempAddr = _addr;
00258
00259
            _rwError = 0;
00260
           // It is assumed we do not know the existing slave address so the broadcast address is used. // This will throw a r/w error so errors will be ignored.
00261
00262
           _addr = MLX90614_BROADCASTADDR;
00263
00264
00265
            \ensuremath{//} Reload program copy with the existing slave address.
           _addr = lowByte(readEEProm(MLX90614_ADDR));
00266
00267
00268
            return _addr;
00269 }
```

References _addr, _rwError, MLX90614_ADDR, MLX90614_BROADCASTADDR, and readEEProm().

Referenced by MLX90614().

Here is the call graph for this function:



Here is the caller graph for this function:



```
5.2.4.5 getCRC8() uint8_t MLX90614::getCRC8 ( void ) [inline], [private]
```

8 bit CRC getter

Definition at line 154 of file MLX90614.h.

Referenced by MLX90614().

Here is the caller graph for this function:



```
5.2.4.6 getEmissivity() float MLX90614::getEmissivity ( void )
```

Get the emissivity (ε) of the object.

Emissivity getter

Remarks

The emissivity is stored as a 16 bit integer defined by the following:

```
\varepsilon = \text{dec2hex[round(65535 x emiss)]}
```

Returns

Physical emissivity value in range 0.1 ... 1.0

Definition at line 126 of file MLX90614.cpp.

```
00126
00127
00128    _rwError = 0;
00129    uint16_t emiss = readEEProm(MLX90614_EMISS);
00130    if(_rwError) return (float)1.0;
00131    return (float)emiss / 65535.0;
00132 }
```

References _rwError, MLX90614_EMISS, and readEEProm().

Here is the call graph for this function:



Get the coefficients of the FIR digital filter.

IIR coefficient getter

Remarks

The FIR digital filter coefficient N is bits 10:8 of ConfigRegister1 The value of N is set as follows: N = 2 $^{\land}$ (csb + 3) The manufacturer does not recommend N < 128

Definition at line 214 of file MLX90614.cpp.

References _rwError, MLX90614_CONFIG, and readEEProm().

Here is the call graph for this function:



```
5.2.4.8 getIIRcoeff() uint8_t MLX90614::getIIRcoeff ( void )
```

Get the coefficients of the IIR digital filter.

IIR coefficient getter

Remarks

The IIR digital filter coefficients are set by the LS 3 bits of ConfigRegister1

Returns

Filter coefficient table index. Range 0...7

Definition at line 172 of file MLX90614.cpp.

References rwError, MLX90614 CONFIG, and readEEProm().

Here is the call graph for this function:



PEC getter

Definition at line 155 of file MLX90614.h.

Referenced by MLX90614().

Here is the caller graph for this function:



```
5.2.4.10 getRwError() uint8_t MLX90614::getRwError ( void ) [inline], [private]
```

R/W error flags getter

Definition at line 153 of file MLX90614.h.

Referenced by MLX90614().

Here is the caller graph for this function:



Return a 16 bit value read from RAM or EEPROM.

Parameters

```
in cmd Command to send (register to read from).
```

Returns

Value read from memory.

Definition at line 276 of file MLX90614.cpp.

```
00276
00277
          uint16_t val;
CRC8 crc(MLX90614_CRC8POLY);
00278
00279
00280
          // Send the slave address then the command and set any error status bits returned by the write.
00281
          Wire.beginTransmission(_addr);
00282
          Wire.write(cmd);
          _rwError |= (1 « Wire.endTransmission(false)) » 1;
00283
00284
00285
          // Experimentally determined delay to prevent read errors (manufacturer's data sheet has
00286
          // left something out).
```

```
00287
          delayMicroseconds(MLX90614_XDLY);
00288
00289
          // Resend slave address then get the 3 returned bytes.
00290
          Wire.requestFrom(_addr, (uint8_t)3);
00291
00292
          // Data is returned as 2 bytes little endian.
00293
          val = Wire.read();
00294
          val |= Wire.read() « 8;
00295
          // Rread the PEC (CRC-8 of all bytes).
00296
          _pec = Wire.read();
00297
00298
00299
          // Clear r/w errors if using broadcast address.
00300
          if(_addr == MLX90614_BROADCASTADDR) _rwError &= MLX90614_NORWERROR;
00301
00302
          // Build our own CRC-8 of all received bytes.
00303
          crc.crc8(_addr « 1);
00304
          crc.crc8(cmd);
00305
          crc.crc8((_addr « 1) + 1);
00306
          crc.crc8(lowByte(val));
00307
          _crc8 = crc.crc8(highByte(val));
00308
00309
          \ensuremath{//} Set error status bit if CRC mismatch.
          if(_crc8 != _pec) _rwError |= MLX90614_RXCRC;
00310
00311
00312
          return val;
00313 }
```

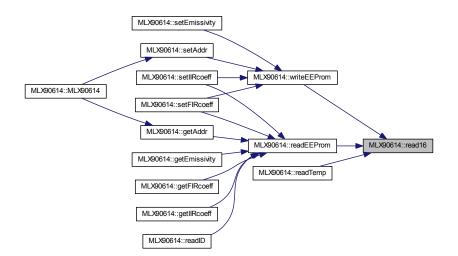
References _addr, _crc8, _pec, _rwError, CRC8::crc8(), MLX90614_BROADCASTADDR, MLX90614_CRC8POLY, MLX90614_NORWERROR, MLX90614_RXCRC, and MLX90614_XDLY.

Referenced by readEEProm(), readTemp(), and writeEEProm().

Here is the call graph for this function:



Here is the caller graph for this function:



```
5.2.4.13 readEEProm() uint16_t MLX90614::readEEProm ( uint8_t addr )
```

Return a 16 bit value read from EEPROM.

Parameters

| in | addr | Register address to read from. |
|----|------|--------------------------------|
|----|------|--------------------------------|

Returns

Value read from EEPROM.

Examples

MelexisTest.ino.

Definition at line 350 of file MLX90614.cpp. 00350 {return read16(addr | 0x20);}

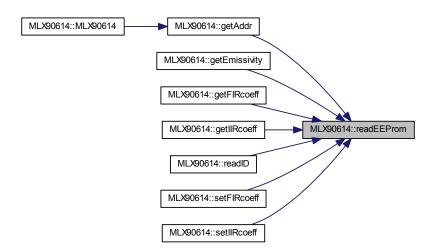
References read16().

Referenced by getAddr(), getEmissivity(), getFIRcoeff(), getIIRcoeff(), readID(), setFIRcoeff(), and setIIRcoeff().

Here is the call graph for this function:



Here is the caller graph for this function:



```
5.2.4.14 readID() uint64_t MLX90614::readID ( void )
```

Retrieve the chip ID bytes.

Chip ID getter

Returns

Chip ID as a 64 bit word.

Examples

MelexisTest.ino.

Definition at line 401 of file MLX90614.cpp.

References MLX90614_ID1, and readEEProm().

Here is the call graph for this function:



Return a temperature from the specified source in specified units.

Remarks

- Temperature is stored in ram as a 16 bit absolute value to a resolution of 0.02 K
- Linearized sensor die temperature is available as Ta (ambient).
- One or two object temperatures are linearized to the range -38.2 °C...125 °C

Parameters

| in | tsrc | Internal temperature source to read, default #1. |
|----|-------|--|
| in | tunit | Temperature units to convert raw data to, default ℃. |

Returns

Temperature.

Examples

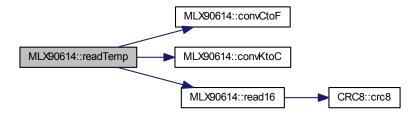
MelexisTest.ino.

Definition at line 90 of file MLX90614.cpp.

```
00091
            double temp;
00092
00093
            _rwError = 0;
00094
           switch(tsrc) {
               case MLX90614_SRC01 : temp = read16(MLX90614_TOBJ1); break;
case MLX90614_SRC02 : temp = read16(MLX90614_TOBJ2); break;
00095
00096
                default : temp = read16(MLX90614_TA);
00097
00098
           temp *= 0.02;
00099
00100
           switch(tunit) {
00101
               case MLX90614_TC : return convKtoC(temp);
00102
                case MLX90614_TF : return convKtoC(convCtoF(temp));
00103
00104
            return temp;
00105 }
```

References _rwError, convCtoF(), convKtoC(), MLX90614_SRC01, MLX90614_SRC02, MLX90614_TA, MLX90614_TC, MLX90614_TF, MLX90614_TOBJ1, MLX90614_TOBJ2, and read16().

Here is the call graph for this function:



```
5.2.4.16 setAddr() void MLX90614::setAddr ( uint8_t addr ) [private]
```

Set device SMBus address.

SMB bus address setter

Remarks

- · Must be only device on the bus.
- Must power cycle the device after changing address.

Parameters

| ſ | in | addr | New device address. | Range 1127 |] |
|---|----|------|---------------------|------------|---|
|---|----|------|---------------------|------------|---|

Definition at line 232 of file MLX90614.cpp.

```
00233
00234
00235
          _rwError = 0;
00236
          // It is assumed we do not know the existing slave address so the broadcast address is used.
00237
          // First ensure the new address is in the legal range (1..127)
00238
          if (addr &= 0x7f) {
              _addr = MLX90614_BROADCASTADDR;
00239
              writeEEProm(MLX90614_ADDR, addr);
00240
00241
00242
              // There will always be a r/w error using the broadcast address so we cannot respond
00243
              // to r/w errors. We must just assume this worked.
00244
00245
00246
          } else _rwError |= MLX90614_INVALIDATA;
00247 }
```

References _addr, _rwError, MLX90614_ADDR, MLX90614_BROADCASTADDR, MLX90614_INVALIDATA, and writeEEProm().

Referenced by MLX90614().

Here is the call graph for this function:



Here is the caller graph for this function:



```
5.2.4.17 setEmissivity() void MLX90614::setEmissivity ( float emiss = 1.0)
```

Set the emissivity (ε) of the object.

Emissivity setter

Remarks

The emissivity is stored as a 16 bit integer defined by the following:

```
\varepsilon = \text{dec2hex[round(65535 x emiss)]}
```

Parameters

| in | emiss | Physical emissivity value in range 0.11.0, default 1.0 |
|----|-------|--|
|----|-------|--|

Definition at line 113 of file MLX90614.cpp.

References _rwError, MLX90614_EMISS, MLX90614_INVALIDATA, and writeEEProm().

Here is the call graph for this function:



```
5.2.4.18 setFIRcoeff() void MLX90614::setFIRcoeff ( uint8_t csb = 7)
```

Set the coefficients of the FIR digital filter.

IIR coefficient setter

Remarks

The FIR digital filter coefficient N is bits 10:8 of ConfigRegister1 The value of N is set as follows: N = 2 $^{\land}$ (csb + 3) The manufacturer does not recommend N < 128

Parameters

in csb See page 12 of datasheet. Range 0...7, default = 7 (N = 1024)

Definition at line 190 of file MLX90614.cpp.

```
00190
00191
00192
          _rwError = 0;
00193
00194
          // Ensure legal range by clearing all but the LS 3 bits.
00195
          csb &= 7;
00196
00197
          // Get the current value of ConfigRegister1
00198
          uint16_t reg = readEEProm(MLX90614_CONFIG);
00199
00200
          // Clear bits 10:8, mask in the new value, then write it back.
00201
          if(!_rwError) {
00202
              reg &= 0xf8ff;
```

References _rwError, MLX90614_CONFIG, readEEProm(), and writeEEProm().

Here is the call graph for this function:



```
5.2.4.19 setllRcoeff() void MLX90614::setIIRcoeff ( uint8_t csb = 4 )
```

Set the coefficients of the IIR digital filter.

IIR coefficient setter

Remarks

The IIR digital filter coefficients are set by the LS 3 bits of ConfigRegister1 The value of the coefficients is set as follows:

```
a2 = 0.5
csb = 0
         a1 = 0.5
     1
              0.25
                          0.75
     2
              0.167
                          0.833
              0.125
                          0.875
     4
              1
                          0 (IIR bypassed)
     5
              0.8
                          0.2
              0.67
                          0.33
      6
              0.57
                          0.43
```

Parameters

```
in csb See page 12 of datasheet. Range 0...7, default = 4 (IIR bypassed)
```

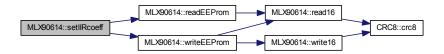
Definition at line 149 of file MLX90614.cpp.

```
00149
00150
00151
          _rwError = 0;
00152
          // Ensure legal range by clearing all but the LS 3 bits.
00153
00154
          csb \&= 7:
00155
00156
          // Get the current value of ConfigRegister1
00157
          uint16_t reg = readEEProm(MLX90614_CONFIG);
00158
00159
          // Clear bits 2:0, mask in the new value, then write it back.
00160
         if(!_rwError) {
00161
             req &= 0xfff8;
00162
              reg |= (uint16_t)csb;
00163
              writeEEProm(MLX90614_CONFIG, reg);
```

```
00164 }
00165 }
```

References _rwError, MLX90614_CONFIG, readEEProm(), and writeEEProm().

Here is the call graph for this function:



```
5.2.4.20 write16() void MLX90614::write16 ( uint8_t cmd, uint16_t data ) [private]
```

Write a 16 bit value to memory.

Parameters

| i | n | cmd | Command to send (register to write to). |
|---|---|------|---|
| i | n | data | Value to write. |

```
Definition at line 320 of file MLX90614.cpp.
```

```
00320
00321
           CRC8 crc(MLX90614_CRC8POLY);
00322
00323
            // Build the CRC-8 of all bytes to be sent.
00324
            crc.crc8(_addr « 1);
00325
            crc.crc8(cmd);
           crc.crc8(lowByte(data));
_crc8 = crc.crc8(highByte(data));
00326
00327
00328
00329
            // Send the slave address then the command.
00330
           Wire.beginTransmission(_addr);
00331
           Wire.write(cmd);
00332
            // Write the data low byte first.
00333
00334
            Wire.write(lowByte(data));
00335
           Wire.write(highByte(data));
00336
           // Then write the crc and set the r/w error status bits.
Wire.write(_pec = _crc8);
_rwError |= (1 « Wire.endTransmission(true)) » 1;
00337
00338
00339
00340
00341
            // Clear r/w errors if using broadcast address.
00342
            if(_addr == MLX90614_BROADCASTADDR) _rwError &= MLX90614_NORWERROR;
00343 }
```

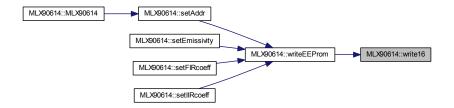
References_addr, _crc8, _pec, _rwError, CRC8::crc8(), MLX90614_BROADCASTADDR, MLX90614_CRC8POLY, and MLX90614_NORWERROR.

Referenced by writeEEProm().

Here is the call graph for this function:



Here is the caller graph for this function:



```
5.2.4.21 writeEEProm() void MLX90614::writeEEProm ( uint8_t reg, uint16_t data )
```

Write a 16 bit value to EEPROM after first clearing the memory.

Remarks

- Erase and write time 5ms per manufacturer specification
- Manufacturer does not specify max or min erase/write times

Parameters

| in | reg | Address to write to. |
|----|------|----------------------|
| in | data | Value to write. |

Examples

MelexisTest.ino.

Definition at line 360 of file MLX90614.cpp.

```
00360
00361 uint16_t val;
00362 reg |= 0x20;
```

```
00363
00364
           // Read current value, compare to the new value, and do nothing on a match or if there are
00365
           // read errors set the error status flag only.
           val = read16(reg);
00366
00367
          if((val != data) && !_rwError) {
00368
               // On any R/W errors it is assumed the memory is corrupted.   
// Clear the memory and wait Terase (per manufacturer's documentation).
00369
00370
00371
               write16(reg, 0);
00372
               delay(5);
00373
               if(_rwError) _rwError |= MLX90614_EECORRUPT;
00374
00375
               // Write the data and wait Twrite (per manufacturer's documentation)
00376
               // and set the r/w error status bits.
00377
               write16(reg, data);
00378
               delay(5);
00379
               if(_rwError) _rwError |= MLX90614_EECORRUPT;
00380
           }
00381 }
```

References _rwError, MLX90614_EECORRUPT, read16(), and write16().

Referenced by setAddr(), setEmissivity(), setFIRcoeff(), and setIIRcoeff().

Here is the call graph for this function:



Here is the caller graph for this function:



5.2.5 Member Data Documentation

5.2.5.1 _addr uint8_t MLX90614::_addr [private]

Slave address

Definition at line 145 of file MLX90614.h.

Referenced by getAddr(), MLX90614(), read16(), setAddr(), and write16().

```
5.2.5.2 _crc8 uint8_t MLX90614::_crc8 [private]
```

8 bit CRC

Definition at line 147 of file MLX90614.h.

Referenced by begin(), read16(), and write16().

```
5.2.5.3 _pec uint8_t MLX90614::_pec [private]
```

PEC

Definition at line 148 of file MLX90614.h.

Referenced by begin(), read16(), and write16().

```
5.2.5.4 _ready boolean MLX90614::_ready [private]
```

Definition at line 144 of file MLX90614.h.

Referenced by begin(), and MLX90614().

```
5.2.5.5 _rwError uint8_t MLX90614::_rwError [private]
```

R/W error flags

Definition at line 146 of file MLX90614.h.

Referenced by begin(), getAddr(), getEmissivity(), getFIRcoeff(), getIIRcoeff(), read16(), read1emp(), setAddr(), setEmissivity(), setFIRcoeff(), setIIRcoeff(), write16(), and writeEEProm().

```
5.2.5.6 busAddr Property<uint8_t, MLX90614> MLX90614::busAddr
```

SMBus address property

Definition at line 123 of file MLX90614.h.

Referenced by MLX90614().

```
5.2.5.7 crc8 Property<uint8_t, MLX90614> MLX90614::crc8
8 bit CRC property
Examples
     MelexisTest.ino.
Definition at line 125 of file MLX90614.h.
Referenced by MLX90614().
5.2.5.8 pec Property<uint8_t, MLX90614> MLX90614::pec
PEC property
Examples
     MelexisTest.ino.
Definition at line 126 of file MLX90614.h.
Referenced by MLX90614().
5.2.5.9 rwError Property<uint8_t, MLX90614> MLX90614::rwError
R/W error flags property
Examples
     MelexisTest.ino.
Definition at line 124 of file MLX90614.h.
```

Definition at line 124 of the MLA90614.11.

Referenced by MLX90614().

The documentation for this class was generated from the following files:

- MLX90614.h
- MLX90614.cpp

5.3 Property < Type, ClassHolder > Class Template Reference

#include <Property.h>

Public Member Functions

- Property ()
- Property (ClassHolder *ClassA, Type(ClassHolder::*GetA)(), void(ClassHolder::*SetA)(Type Val))
- void Set Get (Type(ClassHolder::*GetA)())
- void Set_Set (void(ClassHolder::*SetA)(Type Val))
- void Set Class (ClassHolder *Holder)
- Type operator= (const Type &In)
- Type operator= (Property &In)
- operator Type ()

Private Attributes

```
• Type(ClassHolder::* Get )()
```

- void(ClassHolder::* Set)(Type Val)
- ClassHolder * Class

5.3.1 Detailed Description

```
template<typename Type, typename ClassHolder> class Property< Type, ClassHolder>
```

Definition at line 8 of file Property.h.

5.3.2 Constructor & Destructor Documentation

```
5.3.2.1 Property() [1/2] template<typename Type, typename ClassHolder>
Property< Type, ClassHolder >::Property ( ) [inline]

Definition at line 15 of file Property.h.
00015 : Get(NULL), Set(NULL), Class(NULL) {}
```

5.3.3 Member Function Documentation

```
5.3.3.1 operator Type() template<typename Type, typename ClassHolder>
Property< Type, ClassHolder >::operator Type ( ) [inline]
Definition at line 49 of file Property.h.
00049
             return Get ? (Class->*Get)(): 0;
00051
5.3.3.2 operator=() [1/2] template<typename Type, typename ClassHolder>
Type Property< Type, ClassHolder >::operator= (
              const Type & In ) [inline]
Definition at line 37 of file Property.h.
             if ( Set ) (Class->*Set)(In);
00038
00039
             return In;
         }
00040
5.3.3.3 operator=() [2/2] template<typename Type, typename ClassHolder>
Type Property< Type, ClassHolder >::operator= (
              Property< Type, ClassHolder > & In ) [inline]
Definition at line 43 of file Property.h.
             if ( Set ) (Class->*Set)(In);
00044
00045
             return In;
00046
5.3.3.4 Set Class() template<typename Type, typename ClassHolder>
void Property< Type, ClassHolder >::Set_Class (
              {\tt ClassHolder} \ * \ {\tt Holder} \ ) \quad [{\tt inline}]
Definition at line 32 of file Property.h.
00033
             Class = Holder;
00034
Referenced by MLX90614::MLX90614().
```

Here is the caller graph for this function:



Referenced by MLX90614::MLX90614().

Here is the caller graph for this function:



Definition at line 18 of file Property.h.

Definition at line 28 of file Property.h.

Referenced by MLX90614::MLX90614().

Here is the caller graph for this function:



5.3.4 Member Data Documentation

```
5.3.4.1 Class template<typename Type, typename ClassHolder> ClassHolder* Property< Type, ClassHolder >::Class [private]
```

Definition at line 12 of file Property.h.

Referenced by Property< uint8_t, MLX90614 >::operator uint8_t(), Property< uint8_t, MLX90614 >::operator=(), Property< uint8_t, MLX90614 >::Set_Class(), and Property< uint8_t, MLX90614 >::Set_Property_Control().

```
5.3.4.2 Get template<typename Type, typename ClassHolder>
Type(ClassHolder::* Property< Type, ClassHolder >::Get) () [private]
```

Definition at line 10 of file Property.h.

Referenced by Property< uint8_t, MLX90614 >::operator uint8_t(), Property< uint8_t, MLX90614 >::Set_Get(), and Property< uint8_t, MLX90614 >::Set_Property_Control().

```
5.3.4.3 Set template<typename Type, typename ClassHolder> void(ClassHolder::* Property< Type, ClassHolder >::Set) (Type Val) [private]
```

Definition at line 11 of file Property.h.

Referenced by Property < uint8_t, MLX90614 >::operator=(), Property < uint8_t, MLX90614 >::Set_Property_Control(), and Property < uint8_t, MLX90614 >::Set_Set().

The documentation for this class was generated from the following file:

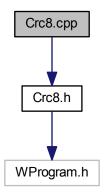
• Property.h

6 File Documentation

6.1 Crc8.cpp File Reference

8 bit CRC helper/utility class - CPP Source file.

#include "Crc8.h"
Include dependency graph for Crc8.cpp:



6.1.1 Detailed Description

8 bit CRC helper/utility class - CPP Source file.

Author

J. F. Fitter jfitter@eagleairaust.com.au

Version

1.0

Date

2014-2017

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Definition in file Crc8.cpp.

6.2 Crc8.cpp

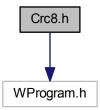
```
00002
         \brief
                   8 bit CRC helper/utility class - CPP Source file.
00003
                    CRC8.CPP
         \file
00004
                    J. F. Fitter <jfitter@eagleairaust.com.au>
         \author
00005
         \version
00006
                    2014-2017
00007
         \copyright Copyright © 2017 John Fitter. All right reserved.
80000
     * \par
00009
                    License
00010
                    This program is free software; you can redistribute it and/or modify it under the terms of the GNU Lesser General Public License as published by the Free
00011 *
00012
                    Software Foundation; either version 2.1 of the License, or (at your option)
00013 *
                    any later version.
00014 *
00015 *
                    This Program is distributed in the hope that it will be useful, but WITHOUT ANY WARRANTY; without even the implied warranty of MERCHANTABILITY or FITNESS FOR A
00016
00017
                    PARTICULAR PURPOSE. See the GNU Lesser General Public License for more details
00018
                    at http://www.gnu.org/copyleft/gpl.html
00019
00020 *
                    You should have received a copy of the GNU Lesser General Public License along
00021
                    with this library; if not, write to the Free Software Foundation, Inc.,
                    51 Franklin St, Fifth Floor, Boston, MA 02110-1301 USA
00022
00023
00025
00026 #include "Crc8.h"
00027
00029 /* CRC8 helper class functions.
00031
00032 /**
00033 \,\,^{\star} \brief CRC8 class constructor. 00034 \,\,^{\star} \param [in] poly 8 bit CRC polynomial to use.
00035
00036 CRC8::CRC8(uint8_t poly) {crc8Start(poly);}
00037
00038 /**
00039 * \brief
00040 * \return
                         Return the current value of the CRC.
                         8 bit CRC current value.
00041 */
00042 uint8_t CRC8::crc8(void) {return _crc;}
00043
00044 /**
00048 */
00049 uint8_t CRC8::crc8(uint8_t data) {
00050
      uint8_t i = 8;
00051
00052
          crc ^= data;
         while(i--) _crc = _crc & 0x80 ? (_crc « 1) ^ _poly : _crc « 1;
00053
00054
         return _crc;
00055 }
00056
00057 /**
00060 */
00061 void CRC8::crc8Start(uint8_t poly) {
00062 _poly = poly;
00063
         _crc = 0;
00064 }
00065
```

6.3 Crc8.h File Reference

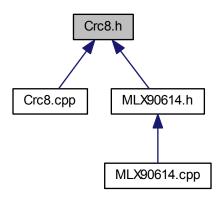
8 bit CRC helper/utility class - CPP Header file.

6.3 Crc8.h File Reference 43

#include "WProgram.h"
Include dependency graph for Crc8.h:



This graph shows which files directly or indirectly include this file:



Classes

• class CRC8

Macros

• #define CRC8_DEFAULTPOLY 7

6.3.1 Detailed Description

8 bit CRC helper/utility class - CPP Header file.

```
Author
```

J. F. Fitter jfitter@eagleairaust.com.au

Version

1.0

Date

2014-2017

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Definition in file Crc8.h.

6.3.2 Macro Definition Documentation

6.3.2.1 CRC8_DEFAULTPOLY #define CRC8_DEFAULTPOLY 7

Default CRC polynomial = X8+X2+X1+1

Definition at line 35 of file Crc8.h.

6.4 Crc8.h 45

6.4 Crc8.h

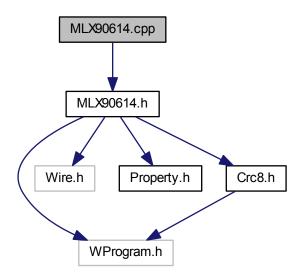
```
00001 #ifndef _CRC8_H_
00002 #define _CRC8_H_
00004 /***
            00005
          \brief 8 bit CRC helper/utility class - CPP Header file.
00006 *
           \file
                       CRC8.H
00007 *
                       J. F. Fitter <jfitter@eagleairaust.com.au>
           \author
80000
           \version
00009
                       2014-2017
           \date
00010 *
          \copyright Copyright © 2017 John Fitter. All right reserved.
00011
00012
          \par
                       License
00013
                       This program is free software; you can redistribute it and/or modify it under
                       the terms of the GNU Lesser General Public License as published by the Free Software Foundation; either version 2.1 of the License, or (at your option)
00014
00015
00016
                       any later version.
00017 *
00018 *
                       This Program is distributed in the hope that it will be useful, but WITHOUT ANY
                       WARRANTY; without even the implied warranty of MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the GNU Lesser General Public License for more details
00019 *
00020 *
00021 *
                       at http://www.gnu.org/copyleft/gpl.html
00022 *
          \par
00023
                       You should have received a copy of the GNU Lesser General Public License along
                       with this library; if not, write to the Free Software Foundation, Inc., 51 Franklin St, Fifth Floor, Boston, MA 02110-1301 USA
00024
00025
00026
00027
00028
00029 #if (ARDUINO >= 100)
00030
          #include "Arduino.h"
00031 #else
         #include "WProgram.h"
00032
00033 #endif
00034
00035 #define CRC8_DEFAULTPOLY 7 /**< Default CRC polynomial = X8+X2+X1+1 */
00036
00037 class CRC8 {
00038 public:
         CRC8(uint8_t polynomial = CRC8_DEFAULTPOLY);
00039
          uint8_t crc8(void);
uint8_t crc8(uint8_t data);
00041
00042
          void
                    crc8Start(uint8_t poly);
00043 private:
00044
          uint8_t _crc;
00045
          uint8_t _poly;
00046 };
00047
00048 #endif /* _CRC8_H_ */
```

6.5 LICENSE.md File Reference

6.6 MLX90614.cpp File Reference

Melexis MLX90614 Family Device Driver Library - CPP Source file.

#include "MLX90614.h"
Include dependency graph for MLX90614.cpp:



6.6.1 Detailed Description

Melexis MLX90614 Family Device Driver Library - CPP Source file.

Details

Based on the Melexis MLX90614 Family Data Sheet 3901090614 Rev 004 09jun2008.

- The current implementation does not manage PWM (only digital data by I2C).
- Sleep mode is not implemented yet.

Note

THIS IS ONLY A PARTIAL RELEASE. THIS DEVICE CLASS IS CURRENTLY UNDERGOING ACTIVE DEVELOPMENT AND IS STILL MISSING SOME IMPORTANT FEATURES. PLEASE KEEP THIS IN MIND IF YOU DECIDE TO USE THIS PARTICULAR CODE FOR ANYTHING.

Author

 $\textbf{J. F. Fitter} \quad \texttt{jfitter@eagleairaust.com.au}$

6.7 MLX90614.cpp 47

Version

1.0

Date

2014-2017

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Definition in file MLX90614.cpp.

6.7 MLX90614.cpp

```
00001 /***
00002
          \brief
                     Melexis MLX90614 Family Device Driver Library - CPP Source file
00003
00004
          \par
00005
                     Based on the Melexis MLX90614 Family Data Sheet 3901090614 Rev 004 09jun2008.
00006
          \li
                      The current implementation does not manage PWM (only digital data by I2C).
00007
         \li
                     Sleep mode is not implemented yet.
80000
00009
                     THIS IS ONLY A PARTIAL RELEASE. THIS DEVICE CLASS IS CURRENTLY UNDERGOING
         \note
00010
                      ACTIVE DEVELOPMENT AND IS STILL MISSING SOME IMPORTANT FEATURES. PLEASE KEEP
00011
                      THIS IN MIND IF YOU DECIDE TO USE THIS PARTICULAR CODE FOR ANYTHING.
00012
00013
         \file
                     MLX90614.CPP
00014
          \author
                      J. F. Fitter <jfitter@eagleairaust.com.au>
00015
                      1.0
          \version
          \date
00016
                      2014-2017
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                      any later version.
00023
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         \par
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00029
00030
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00031
                      with this library; if not, write to the Free Software Foundation, Inc.,
00032
                      51 Franklin St, Fifth Floor, Boston, MA 02110-1301 USA
00033
```

```
00035
00036 #include "MLX90614.h"
00037
00039 /* MLX90614 Device class functions.
00041 /**
00042 \star \example{lineno} 00043 \star
                              MelexisTest.ino
                              An example of how to use the MLX90614 class.
00044 */
00045
00046 /**
00047 * \brief
                              MLX90614 Device class constructor.
00048 * \param [in] i2caddr Device address (default: published value).
00050 MLX90614::MLX90614(uint8_t i2caddr) {
00051
00052
          busAddr.Set_Class(this);
          busAddr.Set_Get(&MLX90614::getAddr);
00053
00054
         busAddr.Set_Set(&MLX90614::setAddr);
00055
00056
         rwError.Set_Class(this);
         rwError.Set_Get(&MLX90614::getRwError);
00057
00058
00059
         pec.Set_Class(this);
00060
         pec.Set_Get(&MLX90614::getPEC);
00061
00062
         crc8.Set_Class(this);
         crc8.Set_Get(&MLX90614::getCRC8);
00063
00064
00065
          _addr = i2caddr;
00066
         _ready = false;
00067 }
00068
00069 /**
00070 \star \brief Initialize the device and the i2c interface. 00071 \star/
00072 boolean MLX90614::begin(void) {
00073
00074
          _rwError = _pec = _crc8 = 0;
00075
         return _ready = true;
00076 }
00077
00078 /**
00079
     * \brief
                             Return a temperature from the specified source in specified units.
00080 *
          \remarks
00081 *
          \li
                             Temperature is stored in ram as a 16 bit absolute value to a
                             resolution of 0.02°K
00082 *
00083 *
                             Linearized sensor die temperature is available as Ta (ambient).
00084 * \li
                             One or two object temperatures are linearized to the
00085 *
                             range -38.2° C...125° C
00086 *
          \param [in] tsrc
                             Internal temperature source to read, default #1.
00087 *
         \param [in] tunit Temperature units to convert raw data to, default ° C.
00088 *
          \return
                             Temperature.
00089 */
00090 double MLX90614::readTemp(tempSrc_t tsrc, tempUnit_t tunit) {
00091
         double temp;
00092
           rwError = 0;
00093
00094
          switch(tsrc) {
             case MLX90614_SRC01 : temp = read16(MLX90614_TOBJ1); break;
case MLX90614_SRC02 : temp = read16(MLX90614_TOBJ2); break;
00095
00096
00097
             default : temp = read16(MLX90614_TA);
00098
00099
         temp *= 0.02;
00100
         switch(tunit) {
          case MLX90614_TC : return convKtoC(temp);
00101
             case MLX90614_TF : return convKtoC(convCtoF(temp));
00102
00103
00104
          return temp;
00105 }
00106
00107 /**
00108 *
          \brief
                             Set the emissivity (ε) of the object.
                             The emissivity is stored as a 16 bit integer defined by the following:
00109 *
          \remarks
00110 *
                             <tt>&epsilon; = dec2hex[round(65535 x emiss)]</tt>
00111 *
00112 */
          \param [in] emiss Physical emissivity value in range 0.1 ...1.0, default 1.0
00113 void MLX90614::setEmissivity(float emiss) {
00114
00115
          _{rwError} = 0;
         uint16_t e = int(emiss * 65535. + 0.5);
if((emiss > 1.0) || (e < 6553)) _rwError |= MLX90614_INVALIDATA;</pre>
00116
00117
00118
          else writeEEProm(MLX90614_EMISS, e);
00119 }
00120 /**
```

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```
00121 *
                              Get the emissivity (ε) of the object.
          \brief
                              The emissivity is stored as a 16 bit integer defined by the following: <tt>&epsilon; = dec2hex[round(65535 x emiss)]</tt>
00122 *
          \remarks
00123 *
          \return
                              Physical emissivity value in range 0.1 ...1.0
00124 *
00125 */
00126 float MLX90614::getEmissivity(void) {
00127
00128
00129
          uint16_t emiss = readEEProm(MLX90614_EMISS);
          if(_rwError) return (float)1.0;
return (float)emiss / 65535.0;
00130
00131
00132 }
00133
00134 /**
00135 * \brief
                             Set the coefficients of the IIR digital filter.
00136 *
          \remarks
                             The IIR digital filter coefficients are set by the LS 3 bits of ConfigRegister1
                             The value of the coefficients is set as follows:
00137 *
          \n
00138 * \n <tt>\verbatim
00139 csb = 0 a1 = 0.5
                       0.25
                                 0.75
00140
00141
                       0.167
                                   0.833
00142
             3
                       0.125
                                   0.875
00143
             4
                                   0 (IIR bypassed)
                       0.8
00144
             5
                                   0.2
00145
                       0.67
                                   0.33
                       0.57
                                   0.43 \endverbatim </tt>
00146
00147 *
00148 */
         \param [in] csb See page 12 of datasheet. Range 0...7, default = 4 (IIR bypassed)
00149 void MLX90614::setIIRcoeff(uint8_t csb) {
00150
00151
           rwError = 0:
00152
00153
          \ensuremath{//} Ensure legal range by clearing all but the LS 3 bits.
00154
          csb &= 7;
00155
          // Get the current value of ConfigRegister1
00156
00157
          uint16 t reg = readEEProm(MLX90614 CONFIG);
00158
00159
          // Clear bits 2:0, mask in the new value, then write it back.
00160
          if(!_rwError) {
00161
              reg &= 0xfff8;
              reg |= (uint16_t)csb;
writeEEProm(MLX90614_CONFIG, reg);
00162
00163
00164
          }
00165 }
00166
00167 /**
00168 * \brief
                             Get the coefficients of the IIR digital filter.
                             The IIR digital filter coefficients are set by the LS 3 bits of ConfigRegister1
00169 *
          \remarks
00170 *
                             Filter coefficient table index. Range 0...7
          \return
00171
00172 uint8_t MLX90614::getIIRcoeff(void) {
00173
00174
          _rwError = 0;
00175
00176
          // Get the current value of ConfigRegister1 bits 2:0
00177
          uint8_t iir = readEEProm(MLX90614_CONFIG) & 7;
00178
00179
          if(_rwError) return 4;
00180
          return iir;
00181 }
00182
00183 /**
00184 *
          \brief
                             Set the coefficients of the FIR digital filter.
00185 *
                             The FIR digital filter coefficient N is bits 10:8 of ConfigRegister1
          \remarks
00186 *
                             The value of N is set as follows: nbsp; < tt > N = 2 ^ (csb + 3) < / tt > 0
          \n
                             The manufacturer does not recommend   <tt>N < 128</tt>
00187
          ١'n
          \param [in] csb See page 12 of datasheet. Range 0...7, default = 7 (N = 1024)
00188 *
00189 */
00190 void MLX90614::setFIRcoeff(uint8_t csb) {
00191
00192
          _rwError = 0;
00193
          // Ensure legal range by clearing all but the LS 3 bits.
00194
00195
          csb \&= 7;
00196
00197
          // Get the current value of ConfigRegister1
00198
          uint16_t reg = readEEProm(MLX90614_CONFIG);
00199
00200
          // Clear bits 10:8, mask in the new value, then write it back.
00201
          if(! rwError) {
00202
              reg &= 0xf8ff;
00203
              reg |= (uint16_t)csb « 8;
00204
              writeEEProm(MLX90614_CONFIG, reg);
00205
          }
00206 }
00207
```

```
00208 /**
00209 * \brief
                            Get the coefficients of the FIR digital filter.
                            The FIR digital filter coefficient N is bits 10:8 of ConfigRegister1 The value of N is set as follows: n > 1  (csb + 3) (/tt>
00210 *
          \remarks
00211 *
          \n
00212
          \n
                            The manufacturer does not recommend   <tt> N < 128 </tt>
00213 */
00214 uint8_t MLX90614::getFIRcoeff(void) {
00215
00216
         _rwError = 0;
00217
          // Get the current value of ConfigRegister1 bits 10:8
00218
00219
         uint8 t fir = (readEEProm(MLX90614 CONFIG) » 8) & 7;
00220
00221
          if(_rwError) return 7;
00222
          return fir;
00223 }
00224
00225 /**
00226 *
          \brief
                            Set device SMBus address.
00227 *
          \remarks
00228 *
                            Must be only device on the bus.
00229
          \li
                            Must power cycle the device after changing address.
00230 *
          \param [in] addr New device address. Range 1...127
00231 */
00232 void MLX90614::setAddr(uint8_t addr) {
00233
00234
          _{rwError} = 0;
00235
00236
          // It is assumed we do not know the existing slave address so the broadcast address is used.
00237
          // First ensure the new address is in the legal range (1..127) \,
00238
          if(addr &= 0x7f) {
00239
              _addr = MLX90614_BROADCASTADDR;
00240
              writeEEProm(MLX90614_ADDR, addr);
00241
00242
              // There will always be a r/w error using the broadcast address so we cannot respond
              // to r/w errors. We must just assume this worked.
00243
00244
              _addr = addr;
00245
00246
          } else _rwError |= MLX90614_INVALIDATA;
00247 }
00248
00249 /**
00250 *
          \brief
                            Return the device SMBus address.
00251 *
          \remarks
00252
          \li
                            Must be only device on the bus.
00253
          \li
                            Sets the library to use the new found address.
00254 * \return
                            Device address.
00255 */
00256 uint8 t MLX90614::getAddr(void) {
00257
         uint8_t tempAddr = _addr;
00258
00259
00260
00261
          // It is assumed we do not know the existing slave address so the broadcast address is used.
00262
         // This will throw a r/w error so errors will be ignored.
00263
          _addr = MLX90614_BROADCASTADDR;
00264
00265
          // Reload program copy with the existing slave address.
00266
         _addr = lowByte(readEEProm(MLX90614_ADDR));
00267
00268
          return addr;
00269 }
00270
00271 /**
00272 * \brief
                            Return a 16 bit value read from RAM or EEPROM.
00273 *
          \param [in] cmd Command to send (register to read from).
          \return
00274 *
                            Value read from memory.
00275 */
00276 uint16_t MLX90614::read16(uint8_t cmd) {
00277
         uint16_t val;
00278
          CRC8 crc(MLX90614_CRC8POLY);
00279
00280
          // Send the slave address then the command and set any error status bits returned by the write.
00281
          Wire.beginTransmission(_addr);
00282
          Wire.write(cmd);
          _rwError |= (1 « Wire.endTransmission(false)) » 1;
00283
00284
00285
          // Experimentally determined delay to prevent read errors (manufacturer's data sheet has
00286
          // left something out)
          delayMicroseconds (MLX90614_XDLY);
00287
00288
00289
          // Resend slave address then get the 3 returned bytes.
00290
          Wire.requestFrom(_addr, (uint8_t)3);
00291
00292
          // Data is returned as 2 bytes little endian.
00293
          val = Wire.read();
00294
          val |= Wire.read() « 8;
```

6.7 MLX90614.cpp 51

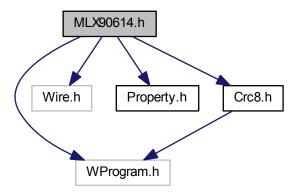
```
00295
          // Rread the PEC (CRC-8 of all bytes).
00296
00297
          _pec = Wire.read();
00298
00299
          // Clear r/w errors if using broadcast address.
00300
          if(_addr == MLX90614_BROADCASTADDR) _rwError &= MLX90614_NORWERROR;
00302
          // Build our own CRC-8 of all received bytes.
00303
          crc.crc8(_addr « 1);
00304
          crc.crc8(cmd);
00305
          crc.crc8((_addr « 1) + 1);
00306
          crc.crc8(lowByte(val));
          _crc8 = crc.crc8(highByte(val));
00307
00308
          \ensuremath{//} Set error status bit if CRC mismatch.
00309
00310
          if(_crc8 != _pec) _rwError |= MLX90614_RXCRC;
00311
00312
          return val;
00313 }
00314
00315 /**
                            Write a 16 bit value to memory.
00316 * \brief
          \param [in] cmd Command to send (register to write to).
00317 *
          \param [in] data Value to write.
00318 *
00319 */
00320 void MLX90614::write16(uint8_t cmd, uint16_t data) {
00321
          CRC8 crc(MLX90614_CRC8POLY);
00322
00323
          // Build the CRC-8 of all bytes to be sent.
00324
          crc.crc8(_addr « 1);
00325
          crc.crc8(cmd);
00326
          crc.crc8(lowByte(data));
00327
         _crc8 = crc.crc8(highByte(data));
00328
00329
          // Send the slave address then the command.
          Wire.beginTransmission(_addr);
00330
00331
         Wire.write(cmd);
00332
00333
          // Write the data low byte first.
00334
          Wire.write(lowByte(data));
00335
          Wire.write(highByte(data));
00336
00337
          // Then write the crc and set the r/w error status bits.
00338
         Wire.write(_pec = _crc8);
         _rwError |= (1 « Wire.endTransmission(true)) » 1;
00339
00340
00341
          // Clear r/w errors if using broadcast address.
          if(_addr == MLX90614_BROADCASTADDR) _rwError &= MLX90614_NORWERROR;
00342
00343 }
00344
00345 /**
00346 * \brief
                            Return a 16 bit value read from EEPROM.
00347 *
          \param [in] addr Register address to read from.
00348 * \return
00349 */
                            Value read from EEPROM.
00350 uint16_t MLX90614::readEEProm(uint8_t addr) {return read16(addr | 0x20);}
00351
00352 /**
00353 * \brief
00354 * \remark
                            Write a 16 bit value to EEPROM after first clearing the memory.
          \remarks
00355 *
          \li
                            Erase and write time 5ms per manufacturer specification
00356
          \li
                            Manufacturer does not specify max or min erase/write times
00357
          \param [in] reg
                            Address to write to.
         \param [in] data Value to write.
00358
00359 */
00360 void MLX90614::writeEEProm(uint8_t reg, uint16_t data) {
00361
         uint16_t val;
         reg |= 0x20;
00362
00363
00364
         // Read current value, compare to the new value, and do nothing on a match or if there are
00365
          // read errors set the error status flag only.
00366
         val = read16(reg);
00367
         if((val != data) && !_rwError) {
00368
00369
              // On any R/W errors it is assumed the memory is corrupted.
00370
              // Clear the memory and wait Terase (per manufacturer's documentation).
00371
              write16(reg, 0);
00372
              delay(5);
00373
              if(_rwError) _rwError |= MLX90614_EECORRUPT;
00374
00375
              // Write the data and wait Twrite (per manufacturer's documentation)
00376
              // and set the r/w error status bits.
              write16(reg, data);
00377
00378
              delay(5);
00379
              if(_rwError) _rwError |= MLX90614_EECORRUPT;
00380
          }
00381 }
```

```
00382
00383 /**
00384 * \brief Convert temperature in 00385 * \param [in] degK Temperature in °K. 00386 * \return Temperature in °C.
                                     Convert temperature in ° K to ° C.
00388 double MLX90614::convKtoC(double degK) {return degK - 273.15;}
00389
00390 /**
00391 * \prief Convert temperature in 00392 * \param [in] degC Temperature in ° C. 00393 * \return Temperature in ° F.
                                      Convert temperature in °C to °F.
00394 */
00395 double MLX90614::convCtoF(double degC) {return (degC * 1.8) + 32.0;}
00396
00397 /**
00398 * \brief
00399 * \return
00400 */
                                      Retrieve the chip ID bytes.
Chip ID as a 64 bit word.
00401 uint64_t MLX90614::readID(void) {
00402
           uint64_t ID = 0;
00403
             // If we are lucky the compiler will optimise this. for(uint8_t i = 0; i < 4; i++) ID = (ID \ll 16) | readEEProm(MLX90614_ID1 + i);
00404
00405
00406
              return ID;
00407 }
00408
```

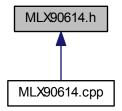
6.8 MLX90614.h File Reference

```
#include "WProgram.h"
#include <Wire.h>
#include "Property.h"
#include "Crc8.h"
```

Include dependency graph for MLX90614.h:



This graph shows which files directly or indirectly include this file:



Classes

class MLX90614

Macros

- #define MLX90614_I2CDEFAULTADDR 0x5A
- #define MLX90614_BROADCASTADDR 0
- #define MLX90614_CRC8POLY 7
- #define MLX90614 XDLY 25
- #define MLX90614_RAWIR1 0x04
- #define MLX90614_RAWIR2 0x05
- #define MLX90614_TA 0x06
- #define MLX90614_TOBJ1 0x07
- #define MLX90614 TOBJ2 0x08
- #define MLX90614_TOMAX 0x00
- #define MLX90614_TOMIN 0x01
- #define MLX90614_PWMCTRL 0x02
- #define MLX90614_TARANGE 0x03
- #define MLX90614 EMISS 0x04
- #define MLX90614_CONFIG 0x05
- #define MLX90614_ADDR 0x0E
- #define MLX90614_ID1 0x1C
- #define MLX90614_ID2 0x1D
- #define MLX90614_ID3 0x1E
- #define MLX90614 ID4 0x1F
- #define MLX90614_RFLAGCMD 0xF0
- #define MLX90614_EEBUSY 0x80
- #define MLX90614_EE_DEAD 0x20
- #define MLX90614_INIT 0x10
- #define MLX90614_NORWERROR 0
- #define MLX90614_DATATOOLONG 1
- #define MLX90614_TXADDRNACK 2
- #define MLX90614_TXDATANACK 4
- #define MLX90614_TXOTHER 8
- #define MLX90614_RXCRC 0x10
- #define MLX90614_INVALIDATA 0x20
- #define MLX90614_EECORRUPT 0x40
- #define MLX90614_RFLGERR 0x80

6.8.1 Macro Definition Documentation

6.8.1.1 MLX90614_ADDR #define MLX90614_ADDR 0x0E

EEPROM reg - SMBus address

Examples

MelexisTest.ino.

Definition at line 76 of file MLX90614.h.

6.8.1.2 MLX90614_BROADCASTADDR #define MLX90614_BROADCASTADDR 0

Device broadcast slave address

Examples

MelexisTest.ino.

Definition at line 53 of file MLX90614.h.

6.8.1.3 MLX90614_CONFIG #define MLX90614_CONFIG 0x05

EEPROM reg - Configuration register

Definition at line 75 of file MLX90614.h.

6.8.1.4 MLX90614_CRC8POLY #define MLX90614_CRC8POLY 7

CRC polynomial = X8+X2+X1+1

Definition at line 54 of file MLX90614.h.

6.8.1.5 MLX90614_DATATOOLONG #define MLX90614_DATATOOLONG 1

R/W error bitmask - Data is too long

Examples

MelexisTest.ino.

Definition at line 91 of file MLX90614.h.

6.8.1.6 MLX90614_EE_DEAD #define MLX90614_EE_DEAD 0x20

R/W flag bitmask - EEProm double error has occurred

Definition at line 86 of file MLX90614.h.

6.8.1.7 MLX90614_EEBUSY #define MLX90614_EEBUSY 0x80

Read flags - bitmask. R/W flag bitmask - EEProm is busy (writing/erasing)

Definition at line 85 of file MLX90614.h.

6.8.1.8 MLX90614_EECORRUPT #define MLX90614_EECORRUPT 0x40

R/W error bitmask - The EEProm is likely to be corrupted

Examples

MelexisTest.ino.

Definition at line 97 of file MLX90614.h.

 $\textbf{6.8.1.9} \quad \textbf{MLX90614_EMISS} \quad \texttt{\#define MLX90614_EMISS 0x04}$

EEPROM reg - Object emissivity register

Definition at line 74 of file MLX90614.h.

 $\textbf{6.8.1.10} \quad \textbf{MLX90614_I2CDEFAULTADDR} \quad \texttt{\#define MLX90614_I2CDEFAULTADDR} \quad \texttt{0x5A}$

Device default slave address

Definition at line 52 of file MLX90614.h.

 $\textbf{6.8.1.11} \quad \textbf{MLX90614_ID1} \quad \texttt{\#define} \ \texttt{MLX90614_ID1} \quad \texttt{0x1C}$

EEPROM reg - ID numer (w1)

Definition at line 77 of file MLX90614.h.

6.8.1.12 MLX90614_ID2 #define MLX90614_ID2 0x1D

EEPROM reg - ID numer (w2)

Definition at line 78 of file MLX90614.h.

 $\textbf{6.8.1.13} \quad \textbf{MLX90614_ID3} \quad \texttt{\#define} \ \texttt{MLX90614_ID3} \quad \texttt{0x1E}$

EEPROM reg - ID numer (w3)

Definition at line 79 of file MLX90614.h.

6.8.1.14 MLX90614_ID4 #define MLX90614_ID4 0x1F

EEPROM reg - ID numer (w4)

Definition at line 80 of file MLX90614.h.

6.8.1.15 MLX90614_INIT #define MLX90614_INIT 0x10

R/W flag bitmask - POR initialization is still ongoing

Definition at line 87 of file MLX90614.h.

6.8.1.16 MLX90614_INVALIDATA #define MLX90614_INVALIDATA 0x20

R/W error bitmask - RX/TX Data fails selection criteria

Examples

MelexisTest.ino.

Definition at line 96 of file MLX90614.h.

6.8.1.17 MLX90614_NORWERROR #define MLX90614_NORWERROR 0

R/W Error flags - bitmask. R/W error bitmask - No Errors

Examples

MelexisTest.ino.

Definition at line 90 of file MLX90614.h.

6.8.1.18 MLX90614_PWMCTRL #define MLX90614_PWMCTRL 0x02

EEPROM reg - Pulse width modulation output control register

Definition at line 72 of file MLX90614.h.

6.8.1.19 MLX90614 RAWIR1 #define MLX90614_RAWIR1 0x04

RAM addresses. RAM reg - Raw temperature, source #1

Definition at line 63 of file MLX90614.h.

6.8.1.20 MLX90614_RAWIR2 #define MLX90614_RAWIR2 0x05

RAM reg - Raw temperature, source #2

Definition at line 64 of file MLX90614.h.

6.8.1.21 MLX90614_RFLAGCMD #define MLX90614_RFLAGCMD 0xF0

Read R/W Flags register command

Definition at line 82 of file MLX90614.h.

6.8.1.22 MLX90614_RFLGERR #define MLX90614_RFLGERR 0x80

R/W error bitmask - R/W flags register access error

Examples

MelexisTest.ino.

Definition at line 98 of file MLX90614.h.

6.8.1.23 MLX90614_RXCRC #define MLX90614_RXCRC 0x10

R/W error bitmask - Receiver CRC mismatch

Examples

MelexisTest.ino.

Definition at line 95 of file MLX90614.h.

6.8.1.24 MLX90614_TA #define MLX90614_TA 0x06

RAM reg - Linearized temperature, ambient

Definition at line 65 of file MLX90614.h.

6.8.1.25 MLX90614_TARANGE #define MLX90614_TARANGE 0x03

EEPROM reg - Customer dependent ambient temperature range

Definition at line 73 of file MLX90614.h.

6.8.1.26 MLX90614_TOBJ1 #define MLX90614_TOBJ1 0x07

RAM reg - Linearized temperature, source #1

Definition at line 66 of file MLX90614.h.

6.8.1.27 MLX90614_TOBJ2 #define MLX90614_TOBJ2 0x08

RAM reg - Linearized temperature, source #2

Definition at line 67 of file MLX90614.h.

6.8.1.28 MLX90614_TOMAX #define MLX90614_TOMAX 0x00

EEPROM addresses. EEPROM reg - Customer dependent object temperature range maximum

Definition at line 70 of file MLX90614.h.

 $\textbf{6.8.1.29} \quad \textbf{MLX90614_TOMIN} \quad \texttt{\#define MLX90614_TOMIN 0x01}$

EEPROM reg - Customer dependent object temperature range minimum

Definition at line 71 of file MLX90614.h.

6.8.1.30 MLX90614_TXADDRNACK #define MLX90614_TXADDRNACK 2

R/W error bitmask - TX address not acknowledged

Examples

MelexisTest.ino.

Definition at line 92 of file MLX90614.h.

6.8.1.31 MLX90614_TXDATANACK #define MLX90614_TXDATANACK 4

R/W error bitmask - TX data not acknowledged

Examples

MelexisTest.ino.

Definition at line 93 of file MLX90614.h.

6.8.1.32 MLX90614_TXOTHER #define MLX90614_TXOTHER 8

R/W error bitmask - Unknown error

Examples

MelexisTest.ino.

Definition at line 94 of file MLX90614.h.

6.8.1.33 MLX90614_XDLY #define MLX90614_XDLY 25

Experimentally determined delay to prevent read errors after calling Wire.endTransmission() (possibly due to incompatibility between Wire library and SMBus protocol).

Definition at line 55 of file MLX90614.h.

6.9 MLX90614.h

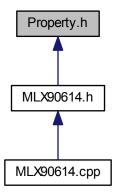
```
00001 #ifndef _MLX90614_H_
00002 #define _MLX90614_H_
00004 /
         \brief
00005
                    Melexis MLX90614 Family Device Driver Library - CPP Source file
          \par
00006
00007
         \par
                     Details
80000
                     Based on the Melexis MLX90614 Family Data Sheet 3901090614 Rev 004 09jun2008.
00009
          \li
                     The current implementation does not manage PWM (only digital data by I2C).
00010
                     Sleep mode is not implemented yet.
00011
                     THIS IS ONLY A PARTIAL RELEASE. THIS DEVICE CLASS IS CURRENTLY UNDERGOING ACTIVE DEVELOPMENT AND IS STILL MISSING SOME IMPORTANT FEATURES. PLEASE KEEP
00012
         \note
00013
                     THIS IN MIND IF YOU DECIDE TO USE THIS PARTICULAR CODE FOR ANYTHING.
00014
00015
00016
                     MLX90614.CPP
00017
          \author
                     J. F. Fitter <jfitter@eagleairaust.com.au>
00018
          \version
                     1.0
          \date
                     2014-2017
00019
          \copyright Copyright © 2017 John Fitter. All right reserved.
00020
00021
00022
00023
                     This program is free software; you can redistribute it and/or modify it under
00024 *
                     the terms of the GNU Lesser General Public License as published by the Free
00025
                     Software Foundation; either version 2.1 of the License, or (at your option)
00026 *
                     any later version.
00027 *
         \par
00028
                     This Program is distributed in the hope that it will be useful, but WITHOUT ANY
00029 *
                     WARRANTY; without even the implied warranty of MERCHANTABILITY or FITNESS FOR A
00030
                     PARTICULAR PURPOSE. See the GNU Lesser General Public License for more details
00031
                     at http://www.gnu.org/copyleft/gpl.html
00032 * \par
00033 *
                     You should have received a copy of the GNU Lesser General Public License along
                     with this library; if not, write to the Free Software Foundation, Inc., 51 Franklin St, Fifth Floor, Boston, MA 02110-1301 USA
00034
00035
00036
      00037
00038
00039 #if (ARDUINO >= 100)
         #include "Arduino.h"
00040
00041 #else
00042
         #include "WProgram.h"
00043 #endif
00044 #include <Wire.h>
00045 #include "Property.h"
00046 #include "Crc8.h"
00049 /* Definitions
00051
00052 #define MLX90614 I2CDEFAULTADDR 0x5A
                                            /**< Device default slave address */
00052 #define MLX90614_BROADCASTADDR 0
                                            /**< Device broadcast slave address */
00054 #define MLX90614_CRC8POLY
                                             /**< CRC polynomial = X8+X2+X1+1 */
                                             /**< Experimentally determined delay to prevent read
00055 #define MLX90614_XDLY
                                     25
00056
                                                  errors after calling Wire.endTransmission()
00057
                                                  <em>(possibly due to incompatibility between Wire
00058
                                                  library and SMBus protocol) </em>. */
00059 /** RAM addresses. */
00060 #define MLX90614_RAWIR1
                                     0x04
                                             /**< RAM reg - Raw temperature, source #1 */
00061 #define MLX90614_RAWIR2
                                     0x05
                                             /\!\star\!\star\!< RAM reg - Raw temperature, source #2 \star/
                                             /**< RAM reg - Linearized temperature, ambient */
00062 #define MLX90614_TA
                                     0x06
                                            /**< RAM reg - Linearized temperature, source #1 */
00063 #define MLX90614_TOBJ1
                                     0 \times 0.7
                                             /**< RAM reg - Linearized temperature, source #2 */
00064 #define MLX90614_TOBJ2
                                     0x08
00065
00066 /** EEPROM addresses. */
00067 #define MLX90614_TOMAX
                                     0x00
                                             /**< EEPROM reg - Customer dependent object temperature range
      maximum */
00068 #define MLX90614_TOMIN
                                     0x01
                                             /**< EEPROM reg - Customer dependent object temperature range
      minimum */
00069 #define MLX90614_PWMCTRL
                                     0x02
                                             /**< EEPROM reg - Pulse width modulation output control
      register */
00070 #define MLX90614_TARANGE
                                             /**< EEPROM reg - Customer dependent ambient temperature range
00071 #define MLX90614_EMISS
                                     0 \times 0.4
                                             /**< EEPROM reg - Object emissivity register */
                                             /**< EEPROM reg - Configuration register */
00072 #define MLX90614_CONFIG
                                     0x05
                                            /**< EEPROM reg - SMBus address */
00073 #define MLX90614 ADDR
                                     0x0E
                                            /**< EEPROM reg - ID numer (w1) */
00074 #define MLX90614_ID1
                                     0x1C
00075 #define MLX90614_ID2
                                            /**< EEPROM reg - ID numer (w2) */
                                     0x1D
                                            /**< EEPROM reg - ID numer (w3) */
/**< EEPROM reg - ID numer (w4) */
00076 #define MLX90614_ID3
                                     0x1E
00077 #define MLX90614_ID4
                                     0x1F
00078
00079 #define MLX90614_RFLAGCMD
                                     0xF0
                                             /**< Read R/W Flags register command */
00081 /** Read flags - bitmask. */
```

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```
0x80 /**< R/W flag bitmask - EEProm is busy (writing/erasing) */
0x20 /**< R/W flag bitmask - EEProm double error has occurred */
0x10 /**< R/W flag bitmask - POR initialization is still ongoing */
00082 #define MLX90614_EEBUSY
00082 #define MLX90614_EE_DEAD
00083 #define MLX90614_EE_DEAD
00084 #define MLX90614 INIT
00084 #define MLX90614_INIT
00085
00086 /** R/W Error flags - bitmask. */
                                                 /**< R/W error bitmask - No Errors */
/**< R/W error bitmask - Data is too long */
00087 #define MLX90614_NORWERROR
                                          Ω
00088 #define MLX90614_DATATOOLONG
00089 #define MLX90614_TXADDRNACK
                                                   /**< R/W error bitmask - TX address not acknowledged */
                                                  /**< R/W error bitmask - TX data not acknowledged */
/**< R/W error bitmask - Unknown error */
00090 #define MLX90614_TXDATANACK
00090 #define MLX90614_TXOTHER
00092 #define MLX90614_INVALIDATA 0x20 /**< R/W error bitmask - Receiver CRC mismatch */
00093 #define MLX90614_INVALIDATA 0x20 /**< R/W error bitmask - RX/TX Data fails selection criteria
00094 #define MLX90614_EECORRUPT
                                        0x40 /**< R/W error bitmask - The EEProm is likely to be corrupted
00095 #define MLX90614_RFLGERR
                                         0x80 /**< R/W error bitmask - R/W flags register access error */
00096
00098 /* MLX90614 Device class.
00100
00101 class MLX90614 {
00102 public:
          MLX90614(uint8_t i2caddr = MLX90614_I2CDEFAULTADDR);
00103
00104
          boolean begin();
boolean isReady(void) { return _ready; };
00105
00106
00107
          uint64_t readID(void);
                                                                          /**< Chip ID getter */
00108
          uint8_t getIIRcoeff(void);
00109
                                                                          /**< IIR coefficient getter */
          uint8_t getFIRcoeff(void);
00110
                                                                          /**< IIR coefficient getter */
00111
                   getEmissivity(void);
                                                                          /**< Emissivity getter */
          float
00112
           void    setIIRcoeff(uint8_t csb = 4);
void    setFIRcoeff(uint8_t csb = 7);
void    setEmissivity(float emiss = 1.0);
00113
                                                                         /**< IIR coefficient setter */
                                                                         /**< IIR coefficient setter */
00114
                                                                         /**< Emissivity setter */
00115
00116
00117
           uint16_t readEEProm(uint8_t);
00118
           void
                    writeEEProm(uint8_t, uint16_t);
00119
00120
           Property<uint8_t, MLX90614> busAddr;
                                                                          /**< SMBus address property */
           Property<uint8_t, MLX90614> rwError;
                                                                         /**< R/W error flags property */
/**< 8 bit CRC property */</pre>
00121
           Property<uint8_t, MLX90614> crc8;
00122
00123
           Property<uint8_t, MLX90614> pec;
                                                                          /**< PEC property */
00124
00125
           /** Enumerations for temperature units. */
00126
           enum tempUnit_t {MLX90614_TK,
                                                                          /**< degrees Kelvin */
                              MLX90614_TC,
00127
                                                                          /**< degrees Centigrade */
00128
                              MLX90614 TF
                                                                          /**< degrees Fahrenheit */
00129
00130
           /** Enumerations for temperature measurement source. */
00131
           enum tempSrc_t {MLX90614_SRCA,
                                                                          /**< Chip (ambient) sensor */
00132
                              MLX90614_SRC01,
                                                                          /**< IR source #1 */
00133
                              MLX90614_SRC02
                                                                          /**< IR source #2 */
00134
                             };
00135
00136
          double    readTemp(tempSrc_t = MLX90614_SRC01, tempUnit_t = MLX90614_TC);
double    convKtoC(double);
double    convCtoF(double);
00137
00138
00139
00140 private:
00141
          boolean _ready;
00142
           uint8_t _addr;
                                                                          /**< Slave address */
00143
           uint8_t _rwError;
                                                                          /**< R/W error flags */
           uint8_t _crc8;
00144
                                                                          /**< 8 bit CRC */
00145
          uint8_t _pec;
                                                                          /**< PEC */
00146
00147
           uint16_t read16(uint8_t);
00148
                   write16(uint8_t, uint16_t);
          void
          uint8_t getRwError(void) {return _rwError;}
uint8_t getCRC8(void) {return _crc8;}
uint8_t getPEC(void) {return _pec;}
00150
                                                                         /**< R/W error flags getter */
00151
                                                                         /**< 8 bit CRC getter */
00152
                                                                         /**< PEC getter */
00153
00154
           uint8_t getAddr(void);
                                                                          /**< SMB bus address getter */
00155
           void
                    setAddr(uint8 t);
                                                                          /**< SMB bus address setter */
00156
00157 };
00158
00159 #endif /* MLX90614 H */
```

6.10 Property.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

class Property < Type, ClassHolder >

6.11 Property.h

```
00001 #ifndef _Property_H_
00002 #define _Property_H_
00003
00004 // Thankyou Joeman for this code - http://forums.codeguru.com/showthread.php?459696-GET-SET-in-C
00005
00006 template<typename Type, typename ClassHolder>
00007
00008 class Property {
00009 private:
00010
           Type (ClassHolder::*Get)();
00011
           void (ClassHolder::*Set)(Type Val);
00012
           ClassHolder * Class;
00014 public:
        Property() : Get(NULL), Set(NULL), Class(NULL) {}
Property(ClassHolder * ClassA, Type (ClassHolder::*GetA)(), void (ClassHolder::*SetA)(Type Val)) :
Class(ClassA), Get(GetA), Set(SetA) {}
00015
00016
00017
           void Set_Property_Control(ClassHolder * ClassA, Type (ClassHolder::*GetA)(), void
00018
        (ClassHolder::*SetA)(Type Val)) {
00019
               Class = ClassA;
                Get = GetA;
00020
                Set = SetA;
00021
           }
00022
00023
00024
           void Set_Get(Type (ClassHolder::*GetA)()) {
00025
               Get = GetA;
00026
00027
           void Set_Set(void (ClassHolder::*SetA)(Type Val)) {
    Set = SetA;
00028
00029
00030
00031
00032
           void Set_Class(ClassHolder * Holder) {
00033
              Class = Holder;
00034
00035
00036
00037
           Type operator = (const Type& In) {
```

```
if ( Set ) (Class->*Set)(In);
00039
             return In;
00040
          }
00041
          // set
00042
00043
          Type operator = (Property& In) {
             if ( Set ) (Class->*Set)(In);
00044
00045
             return In;
00046
          }
00047
         // get
00048
00049
         operator Type() {
00050
             return Get ? (Class->*Get)(): 0;
00051
00052 };
00053
00054 #endif /* _Property_H_ */
```

6.12 README.md File Reference

7 Example Documentation

7.1 MelexisTest.ino

An example of how to use the MLX90614 class.

```
00001 /*********************
00002
                      Melexis MCX90614BAA Test Program - Sensor test implementation.
00003
                     Arduino test implementation of Melexis MCX90614 PIR temperature sensor driver.
00004
                      THIS IS ONLY A PARTIAL RELEASE. THIS DEVICE CLASS IS CURRENTLY UNDERGOING ACTIVE DEVELOPMENT AND IS STILL MISSING SOME IMPORTANT FEATURES. PLEASE KEEP
00005
          \note
00006
00007
                       THIS IN MIND IF YOU DECIDE TO USE THIS PARTICULAR CODE FOR ANYTHING.
80000
00009
00010
          \author
                       J. F. Fitter <jfitter@eagleairaust.com.au>
00011
          \version
                      1.0
00012
                       2014-2017
          \date
          \copyright Copyright (c) 2017 John Fitter. All right reserved.
00013
00014
00015
          \par
00016
                       This program is free software; you can redistribute it and/or modify it under
00017
                       the terms of the GNU Lesser General Public License as published by the Free
00018
                       Software Foundation; either version 2.1 of the License, or (at your option)
00019
                      any later version.
00020
          \par
00021
                       This Program is distributed in the hope that it will be useful, but WITHOUT ANY
00022
                       WARRANTY; without even the implied warranty of MERCHANTABILITY or FITNESS FOR A
00023
                      PARTICULAR PURPOSE. See the GNU Lesser General Public License for more details
00024 *
                       at http://www.gnu.org/copyleft/gpl.html
00025
          \par
00026
                       You should have received a copy of the GNU Lesser General Public License along
00027
                       with this library; if not, write to the Free Software Foundation, Inc.,
00028
                       51 Franklin St, Fifth Floor, Boston, MA 02110-1301 USA
00029
00030
00031
00032 #define MELEXISTEST_C
00033 #define __STDC_LIMIT_MACROS
00034 #define __STDC_CONSTANT_MACROS
00035
00036 #include <Arduino.h>
00037 #include <Wire.h>
00038 #include <MLX90614.h>
00039 #include "printf.h"
00040
00041 MLX90614 mlx = MLX90614 (MLX90614_BROADCASTADDR); // *** must be only one device on bus ***
00042
00043 /**
00044 * \brief Program setup. 00045 */
00046 void setup(void) {
00047
00048
          Wire.begin(); // library does not do this by default
          Serial.begin(115200);
00049
00050
          printf begin():
00051
          mlx.begin();
00052
```

```
Serial.println(F("\nMelexis MLX90614 Temperature Sensor Test Program"));
          Serial.print(F("SMBus address ="));
printf(" %02Xh", (uint8_t)mlx.readEEProm(MLX90614_ADDR));
Serial.print(F(" Chip ID ="));
00054
00055
00056
00057
          00058
00059
00060
                                                (uint16_t)(id » 16), (uint16_t)id);
00061
          dumpEEProm();
00062
          Serial.println("");
00063 }
00064
00065 /**
00066 * \brief Main processing loop.
00067 */
00068 void loop(void) {
00069
          static uint16_t smpcount = 0, errcount = 0;
00070
00071
          // read ambient temperature from chip and print out
00072
          printlnTemp(mlx.readTemp(MLX90614::MLX90614_SRCA, MLX90614::MLX90614_TK), 'A');
00073
          if(mlx.rwError) ++errcount;
00074
00075
          // read object temperature from source \#1 and print out
00076
          printlnTemp(mlx.readTemp(MLX90614::MLX90614_SRC01, MLX90614::MLX90614_TK), '0');
00077
          if(mlx.rwError) ++errcount;
00078
00079
          \ensuremath{//} print running total of samples and errors
00080
          Serial.print(F("
                                   Samples:Errors "));
          printf("%u:%u\r\n", smpcount += 2, errcount);
00081
00082
00083
          // slow down to human speed
00084
          delay(250);
00085 }
00086
00087 /**
00088 * \brief
                            Print a line of temperature, crc, pec, and error string.
          \param [in] temp Temperature \param [in] src Temperature source
00089 *
00091 */
00092 void printlnTemp(double temp, char src) {
00093
          char str[20];
00094
00095
          if(mlx.rwError) Serial.print(F("No valid temperatures
                                                                                                    "));
00096
              if(src == 'A') Serial.print(F("Ambient temperature"));
00097
00098
              else Serial.print(F("Object temperature"));
              printf(" = %sK ", floatToStr(str, temp));
printf("%sC ", floatToStr(str, mlx.convKtoC(temp)));
printf("%sF ", floatToStr(str, mlx.convCtoF(mlx.convKtoC(temp))));
00099
00100
              printf("%sF
00101
00102
00103
          printCRC(mlx.crc8, mlx.pec);
00104
          printErrStr(mlx.rwError);
00105
          Serial.println("");
00106 }
00107
00108 /**
00109 * \brief Print a complete memory dump of the EEPROM.
00110 */
00111 void dumpEEProm() {
00112
          Serial.println(F("EEProm Dump"));
00113
          for(uint8_t j=0; j<8; j++) {
    for(uint8_t i=0; i<4; i++) printf("%02Xh-%04Xh</pre>
00114
00115
                                                                  ", j*4+i, mlx.readEEProm(j*4+i));
00116
              printCRC(mlx.crc8, mlx.pec);
00117
              printErrStr(mlx.rwError);
00118
              Serial.println("");
00119
          }
00120 }
00121
00122 /**
00123 * \brief
                          Utility to stringify a float.
00124 *
          \param [in] str String to receive converted result
00125 *
          \param [in] val Float value
00126 * \return
                          Float as string
00127
00128 char* floatToStr(char *str, double val) {
00129
00130
          sprintf(str, "%4d.%02u", int(val), int(val * 100) % 100);
00131
          return str;
00132 }
00133
00134 /**
00135 * \brief
                           Just print the crc and pec.
          \param [in] crc CRC
00136 *
00137 * \param [in] pec PEC
00138 */
00139 void printCRC(uint8_t crc, uint8_t pec) {printf("crc=%02Xh pec=%02Xh", crc, pec);}
```

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```
00140
00141 /**
00142 * \brief Convert error 00143 * \param [in] err Error flags
                                Convert error flags to diagnostic strings and print.
00144 */
00145 void printErrStr(uint8_t err) {
00147
             Serial.print(F(" *** "));
             if(err == MLX90614_NORWERROR) Serial.print(F("RW Success"));
00148
00149
             else {
                 Serial.print(F("Errors: "));
00150
                  if(err & MLX90614_DATATOOLONG) Serial.print(F("Data too long / "));
if(err & MLX90614_TXADDRNACK) Serial.print(F("TX addr NACK / "));
if(err & MLX90614_TXDATANACK) Serial.print(F("TX data NACK / "));
00151
00152
00153
                 if(err & MLX90614_RXCRC) Serial.print(F("Unknown / "));
if(err & MLX90614_INVALIDATA) Serial.print(F("RX CRC / "));
if(err & MLX90614_EECORRUPT) Serial.print(F("Invalid data / "));
if(err & MLX90614_RFLGERR) Serial.print(F("EEPROM / "));
00154
00155
00156
00157
00158
00159
            }
00160 }
00161
00163 * \brief EEPROM memory contents factory default values. 00164 */
00165 const struct defaultEEPromData {
         uint8_t address;
uint16_t data;
00166
00167
00168 } eDat[] = {\{0x20, 0x9993\}, \{0x21, 0x62E3\}, \{0x22, 0x0201\},
                         {0x23, 0xF71C}, {0x24, 0xFFFF}, {0x25, 0x9FB4}, {0x2E, 0xBE5A}, {0x2F, 0x0000}, {0x39, 0x0000}};
00169
00170
00171
00172 /**
00173 * \brief
                        Set EEPROM memory contents to factory default values.
00174 \, \star \, \remarks \, A device with default adress must not be on the bus.
00175 *
                          \n<tt>Only user allowed memory locations are written.</tt>
00176 */
00177 void setEEPromDefaults(void) {
00178
00179
             for(uint8_t i = 0; i < sizeof(eDat)/sizeof(defaultEEPromData),</pre>
00180
                  !mlx.rwError; i++) {
                  mlx.writeEEProm(eDat[i].address, eDat[i].data);
00181
00182
00183 }
00184
```

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