Rensselaer 2020 REU Notebook

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1 Project description

May 27, 2020

The aim of this REU project is to quantify the information present in images by the principled application of methods from statistical physics. The approach is to find a suitable notion of entropy which captures the salient features of particular kinds of images. We will consider a variety of features motivated by intuition or domain knowledge, and then move to machine learning as a tool for discovering other features.

2 Getting started

May 27, 2020

The initial goal is to characterize the most naïve calculation, which I'll call the *intensity entropy*. This does *not* take into account the spatial correlation of pixels in an image.

3 Intensity-level entropy

Given a discrete random variable X with support \mathfrak{X} , the *Shannon entropy* is

$$H = \sum_{x \in \mathcal{X}} -P(x) \ln P(x).$$

The *intensity-level entropy* is the Shannon entropy of the empirical distribution of intensity values.

```
import numpy as np

def shannon_entropy(h):
    """The Shannon entropy in bits"""
    return -sum(p*np.log2(p) if p > 0 else 0 for p in h)

def intensity_distribution(data):
    """The intensity distribution of 8-bit `data`."""
    hist, _ = np.histogram(data, bins=range(256+1), density=True)
    return hist

def intensity_entropy(data):
    """The intensity-level entropy of 8-bit image data"""
    return shannon_entropy(intensity_distribution(data))

def intensity_expected(f, data):
    """The intensity_distribution expected value of `f`."""
    return sum(p*f(p) for p in intensity_distribution(data))
```

4 Effect of smoothing on intensity-level entropy

```
import numpy as np
import numpy.linalg as linalg
```

```
import matplotlib.pyplot as plt
from PIL import Image, ImageFilter, ImageOps
from src.utilities import *
from src.intensity_entropy import *
```

4.1 Natural image

```
img = ImageOps.grayscale(Image.open('test.jpg'))
scale = max(np.shape(img))
data = np.array(img)
img
```



intensity_entropy(img)

7.51132356216608

The problem with the intensity entropy is that it is usually near maximum (8 bits for these grayscale images).

```
def intensity_blur(img, scales, display=True):
    scale = max(np.shape(img))

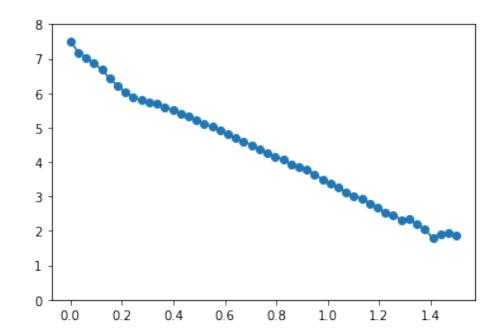
results = []
for k in scales:
    simg = img.filter(ImageFilter.GaussianBlur(k * scale))
    data = np.array(simg)
    ihist, ibins = np.histogram(data, bins=range(256+1), density=True)
    S = shannon_entropy(ihist)
    if display:
        hist = plt.hist(ibins[:-1], ibins, weights=ihist, alpha=0.5)
```

```
results.append((k, simg, hist, S))
else:
results.append((k, S))

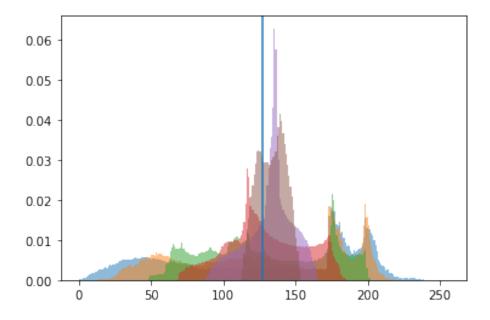
if display:
plt.axvline(x=np.mean(np.array(img)))

return results
results = intensity_blur(img, np.linspace(0, 1.5, num=50), False)

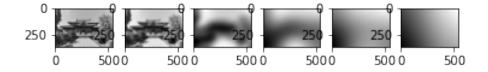
plt.plot(*np.transpose(results), 'o-')
plt.ylim((0, 8))
plt.xlabel = "Smoothing"
plt.ylabel = "Intensity Entropy (bits)"
```



```
rimgs = [img for _, img, _, _ in intensity_blur(img, [0, 0.01, 0.05, 0.125, 0.25, 0.5])] plt.show()
```

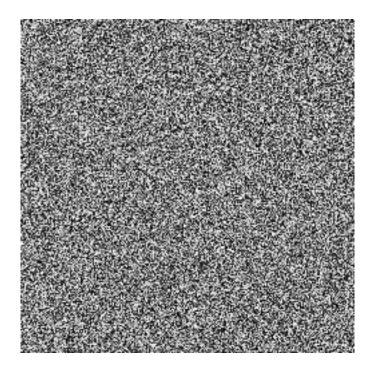


```
__, axarr = plt.subplots(1, len(rimgs))
tor i, subimg in enumerate(rimgs):
axarr[i].imshow(subimg, cmap='gray')
plt.show()
```



4.2 Random pixel values

- rsize = 250
- ${\tiny \footnotesize 2 \qquad \text{randimg = Image.fromarray((256*np.random.rand(*2*[rsize])).astype('uint8'))}}$
- 3 randimg



4.2.1 Beware: GIGO

The boundary effects and discrete kernel of ImageFilter.GaussianBlur renders the data unreliable after the "minimum" of the intensity entropy with smoothing. This is immediately clear after even small smoothing for random pixel values, since there are no spatial correlations.

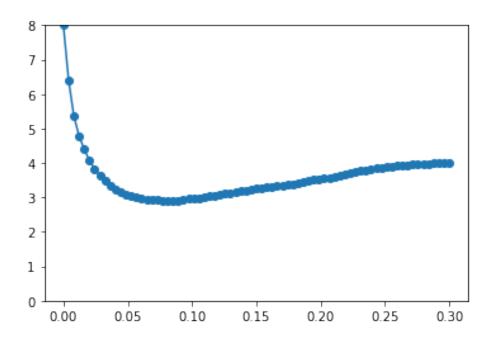
```
results = intensity_blur(randimg, np.linspace(0, 0.3, num=75), False)

plt.plot(*np.transpose(results), 'o-')

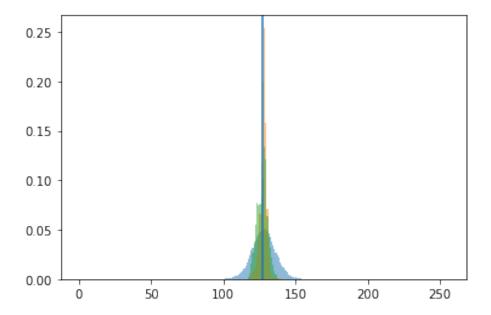
plt.ylim((0, 8))

plt.xlabel = "Smoothing"

plt.ylabel = "Intensity Entropy (bits)"
```

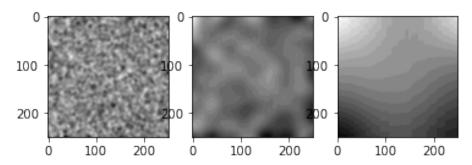


- rimgs = [img for _, img, _, _ in intensity_blur(randimg, [0.01, 0.05, 0.25])]
- plt.show()



- _, axarr = plt.subplots(1, len(rimgs))
- for i, subimg in enumerate(rimgs):

```
axarr[i].imshow(subimg, cmap='gray')
plt.show()
```



The rightmost image should be uniform: the renormalization emphasizes incorrect deviations. These are what keep the intensity entropy from vanishing.

4.3 Comparing different levels of smoothing

Is composing n Gaussian blurs with variance σ^2 the same as doing one with variance $n\sigma^2$ (considering the boundary effects and discrete kernel)?

```
nsmooths = 10
cimg = img
oneimg = cimg.filter(ImageFilter.GaussianBlur(np.sqrt(nsmooths)*2))
npeimg
```



```
nimg = cimg
for _ in range(nsmooths):
```

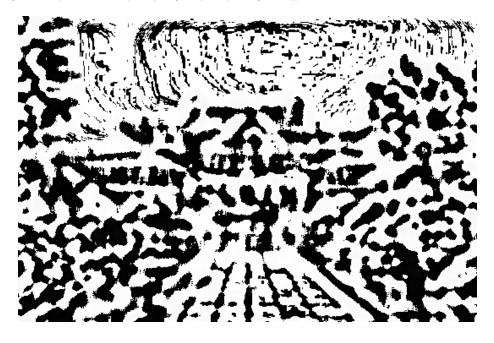
nimg = nimg.filter(ImageFilter.GaussianBlur(2))

₄ nima



Answer: No The differences between results at different scales can be pretty wack.

 ${\tt Image.fromarray((255*rescale(np.array(nimg) - np.array(oneimg))).astype('uint8'))}$





5 Local metrics

May 28, 2020 Given an image $I: X \times Y \to \mathbb{Z}_n$, we will now consider *local metrics* for the information it contains

I want to be careful in understanding the statistical assumptions I am making, so I'll try to be explicit about distinguishing true distributions from empirical distributions, and how the assumptions behind postulating the existence of empirical distributions relate to the actual calculation being done. This should also aid in learning more solid probability theory.

5.1 Induced metrics

Definition 1 (Lists). Given a set *S*, the collection of lists of elements from *S* is

$$\mathsf{List}(S) = \bigcup_{n \in \mathbb{Z}_{\geq 0}} S^n,$$

where a list (tuple) $s \in S^n$ is a map $s : \mathbb{Z}_n \to S$ and |s| = n.

Definition 2 (Image distributions). An *image distribution* is a map D that takes an image I and produces a random variable $D(I): \Omega \to E$.

We are constructing empirical distributions from image data according to some map $M: \text{Img} \to \text{List}(\Omega)$, which produces the list of values V = M(I). Then the probability of D(I) taking a value in a subset $S \subseteq E$ is

$$P(X \in S) = \frac{1}{|V|} \sum_{s \in S} |V^{-1}(\{s\})|.$$

Example 1. The intensity-level entropy is a function of the *nonnegative* random variable from the image distribution of intensity values. That is, the map M takes an image and returns the list of its intensity values.

Definition 3 (Induced image distributions). Given an image distribution D, and a subset $S \subseteq \text{dom } I$, we construct the *induced image distribution* $D|_S$ by

$$D|_{S}(I) = D(I|_{S}).$$

Definition 4 (Induced random variable). Given an image I, an image distribution D and collection of subsets $\{S_i\}$ of dom I, a function H admits the random variables

$$H_i = (H \circ D|_{S_i})(I)$$

Definition 5. The *r-box* at (x, y) is $B_r(x, y) = [x - r, x + r] \times [y - r, y + r]$.

Given two real random variables A and B with joint PDF $f_{A,B}(a,\ b)$, the PDF of their sum is

$$f_{A+B}(c) = \int_{-\infty}^{\infty} da \, f_{A,B}(a, a-c) = \int_{-\infty}^{\infty} db \, f_{A,B}(b-c, b). \tag{1}$$

For independent A and B, Eq. 1 reduces to $f_{A+B} = f_A * f_B$ over the marginals.

6 Kernels

Generalized to arbitrary functions on subregions of images.

```
import numpy as np

def box(x, y, r):
    return np.s_[max(0, x-r) : x+r+1, max(0, y-r) : y+r+1]

def mapbox(r, f, a):
    return np.reshape([f(a[box(*i, r)]) for i in np.ndindex(np.shape(a))], np.shape(a))

def mapboxes(rs, f, a):
    return (mapbox(r, f, a) for r in rs)

def mapallboxes(f, a):
    return mapboxes(range(max(np.shape(a))), f, a)

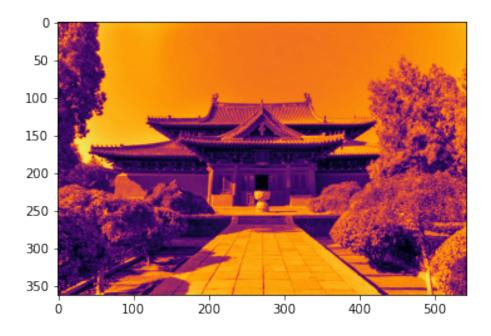
def mapblocks(h, w, f, a):
    return np.array([[f(y) for y in np.array_split(x, w, axis=1)]
    for x in np.array_split(a, h)])
```

7 Boxcar intensity-level entropy

```
import numpy as np
import numpy.linalg as linalg
import matplotlib.pyplot as plt
from PIL import Image, ImageFilter, ImageOps
from src.utilities import *
from src.intensity_entropy import *
from src.kernels import *
plt.rcParams['image.cmap'] = 'inferno'
```

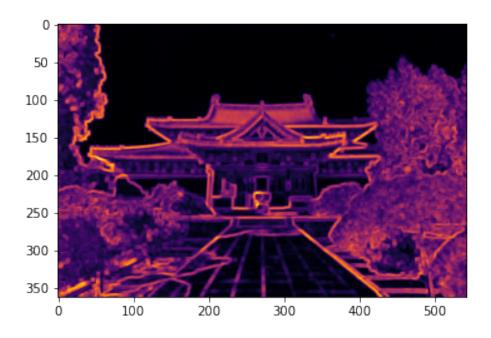
Let's compare the boxcar images for intensity entropy to those for a positive function on an image (the standard deviation) and for different functions of the induced intensity distribution.

```
img = ImageOps.grayscale(Image.open('test.jpg'))
scale = max(np.shape(img))
data = np.array(img)
plt.imshow(img);
```



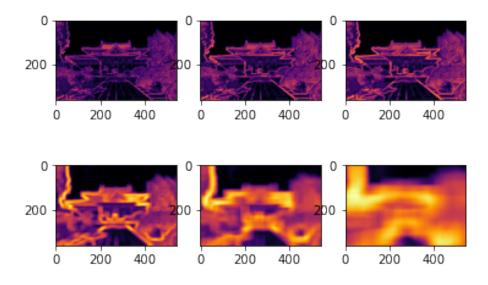
7.1 Standard deviation

plt.imshow(mapbox(2, np.std, np.array(img)));



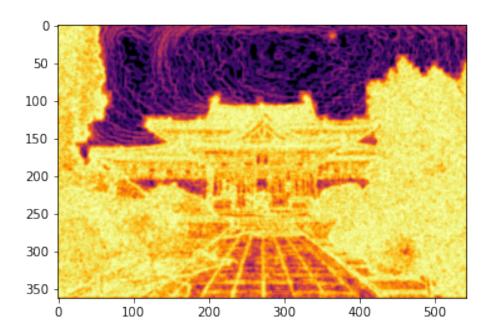
```
boxos = list(mapboxes([1,2,3,10,20,50], np.std, np.array(img)))
```

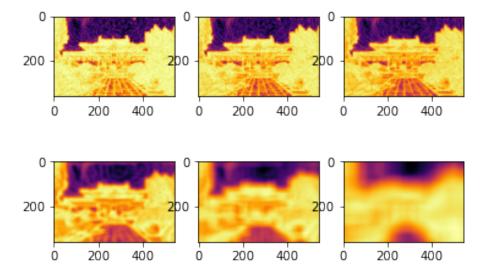
```
__, axarr = plt.subplots(2, np.ceil(len(boxos)/2).astype('int'))
for i, subimg in enumerate(boxos[:3]):
    axarr[0,i].imshow(subimg)
for i, subimg in enumerate(boxos[3:]):
    axarr[1,i].imshow(subimg)
plt.show()
```



7.2 Intensity entropy

plt.imshow(mapbox(2, intensity_entropy, np.array(img)));



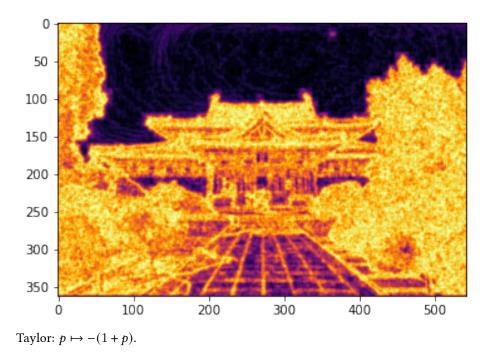


7.3 Replace surprisal with other functions

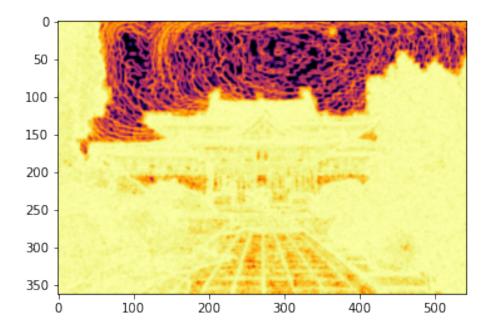
To what extent do the surprisal-related results depend upon the specific form of the surprisal $x \mapsto -\log(x)$ in the expected value of the intensity distribution? We will replace the expected surprisal with the expected f, for different functions f on the empirical probabilities of a pixel taking some intensity.

Laurent: $p \mapsto -1 + 1/p$.

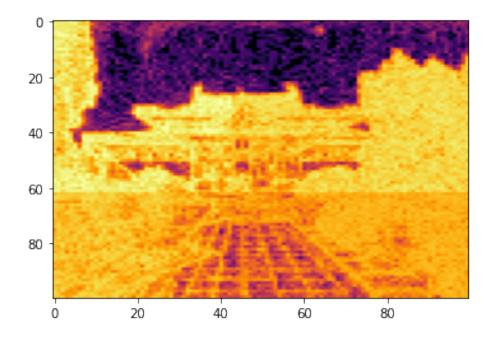
plt.imshow(mapbox(2, lambda I: intensity_expected(lambda p: -1 + 1/p if p > 0 else 0, I), np.array(img)));

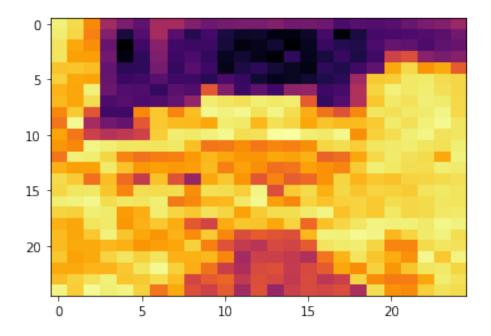


plt.imshow(mapbox(2, lambda I: intensity_expected(lambda p: -(1+p), I), np.array(img)));



7.4 Intensity entropy on disjoint blocks





8 Fractal dimensions

May 29, 2020 The previous results hint at characterizing the growth of the intensity entropy with different discretizations.

Definition 6. The *Rényi entropy of order* $\alpha \geq 0$ of a discrete random variable X with support $\mathfrak X$ is

$$H_{\alpha}(X) = \frac{1}{1-\alpha} \log \sum_{x \in \mathfrak{X}} P(x)^{\alpha} = \frac{\alpha}{1-\alpha} \log ||P||_{\alpha},$$

where $\|P\|_{\alpha}$ denotes the α -norm of the vector of probability values. The limit $\alpha \to 1$ reproduces the Shannon entropy.

Definition 7. Given a real random variable *X*, define a discretized random variable

$$\langle X \rangle_{\varepsilon} = \frac{\lfloor \varepsilon X \rfloor}{\varepsilon}.$$

Then the generalized dimension of X is

$$d_{\alpha}(X) = \lim_{\varepsilon \to 0} \frac{H_{\alpha}(\langle X \rangle_{\varepsilon})}{\log \varepsilon} = \lim_{\varepsilon \to 0} \frac{\alpha}{1 - \alpha} \log (\|\langle X \rangle_{\varepsilon}\|_{\alpha} - \varepsilon).$$

The case $\alpha \to 1$ is the *information dimension* of X. The generalized dimension may be estimated from linear regression of $H_{\alpha}(\langle X \rangle_{\varepsilon})$ with $\log \varepsilon$ as the independent variable.

9 Fractal dimension regression

```
import numpy as np
import numpy.linalg as linalg
import matplotlib.pyplot as plt
from PIL import Image, ImageFilter, ImageOps
from scipy import interpolate
from src.intensity_entropy import *
from src.kernels import *
plt.rcParams['image.cmap'] = 'inferno'

img = ImageOps.grayscale(Image.open('test.jpg'))
scale = max(np.shape(img))
data = np.array(img)
image_import integrate
from src.kernels import *
plt.rcParams['image.cmap'] = 'inferno'
```



9.1 Box-counting dimension

```
def boxdim(data):

εs = np.linspace(2, min(np.shape(data)))

boxes = [np.log(np.sum(mapblocks(

ε, ε, lambda x: 1 if np.any(x) else θ, data))) for ε in εs]

loges = np.log(εs)

endes = loges[[θ, -1]]

dimfit = np.polyfit(np.log(εs), boxes, 1) # [slope, intercept]

plt.plot(endes, dimfit[θ]*endes + dimfit[1])

plt.plot(loges, boxes, '+')

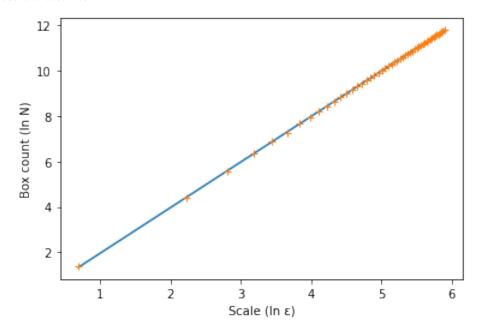
plt.xlabel('Scale (ln ε)')

plt.ylabel('Box count (ln N)')

return dimfit[θ]
```

1 boxdim(data)

2.0087040269581435

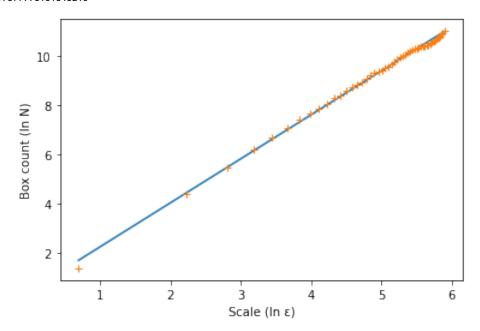


- sky = data.copy()
 sky[sky < 128+32] = 0
 Image.fromarray(sky)</pre>



1 boxdim(sky)

1.7877778191348215

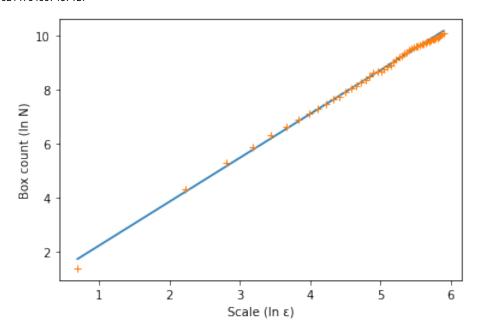


- nosky = data.copy() nosky[nosky < 128+64] = 0 Image.fromarray(nosky)



boxdim(nosky)

1.6214794967487127

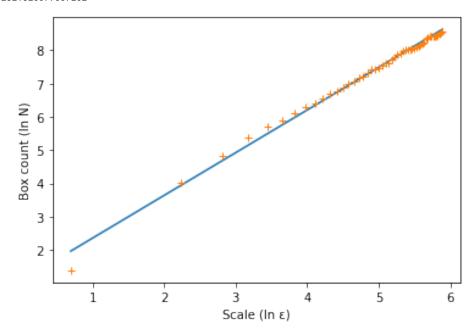


- dots = data.copy()
 dots[nosky < 128+64+16] = 0
 Image.fromarray(dots)</pre>



boxdim(dots)

1.2821025677557252



9.2 Information dimension

```
def discretize(f, a, b, \epsilon, N=20):
    return [integrate.simps(f(np.linspace(c - \epsilon/2, c + \epsilon/2, N)), dx=\epsilon / (N - 1))
             for c in np.arange(a + \epsilon/2, b, \epsilon)]
def infodim(dist, s=1e-5):
    1 = len(dist)
    spl = interpolate.splrep(range(l), dist, s=s)
    f = lambda x: interpolate.splev(x, spl)
    \epsilon s = 1 / np.linspace(10, 1)
    loges = -np.log2(es)
    endes = loges[[0, -1]]
    entropies = [shannon_entropy(discretize(f, 0, 1, \epsilon)) for \epsilon in \epsilons]
    dimfit, cov = np.polyfit(logss, entropies, 1, cov='unscaled')
    plt.plot(endss, dimfit[0]*endss + dimfit[1])
    plt.plot(logss, entropies, '+')
    plt.xlabel('Scale (lg E)')
    plt.ylabel('Shannon entropy (bits)')
    return dimfit[0], cov[0,0]
```

The Gaussian distribution

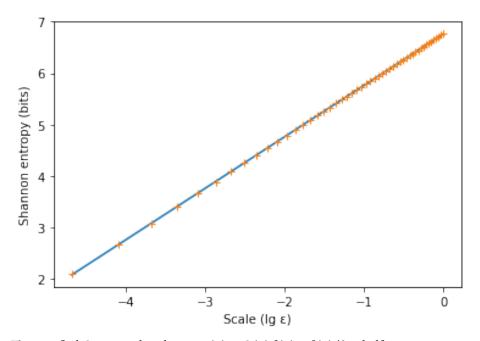
$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$

is continuous, so its information dimension is 1.

```
def gaussian(μ, σ, x):
return np.exp(-(x - μ)**2 / (2*σ**2)) / (σ*np.sqrt(2*np.pi))

infodim((10/256) * gaussian(θ, 1, np.linspace(-5, 5, 256)))
```

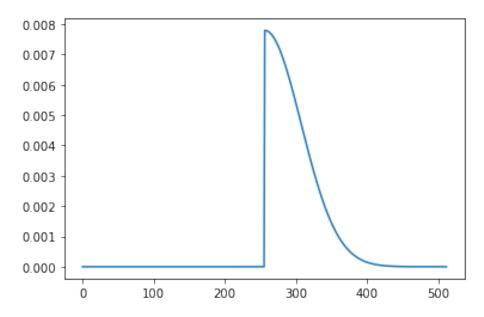
(1.0014184290221988, 0.015707497682893923)



The rectified Gaussian distribution $g(x) = \Theta(x)f(x) + \delta(x)/2$ is half-continuous, so its information dimension is 1/2.

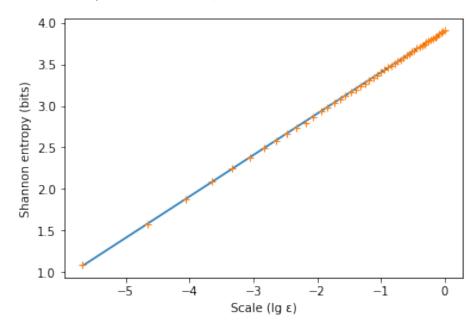
```
dist = np.concatenate([[0]*256, (5/256)*gaussian(0, 1, np.linspace(0, 5, 256))])
```

plt.plot(dist);



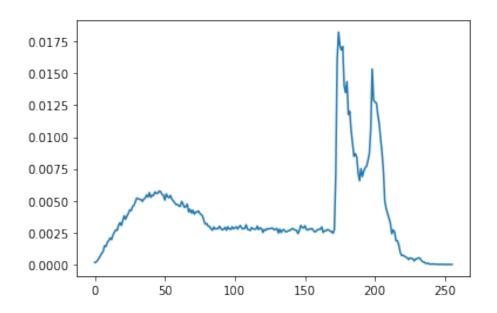
infodim(dist)

$(0.4979088715795226,\ 0.012313889825394398)$



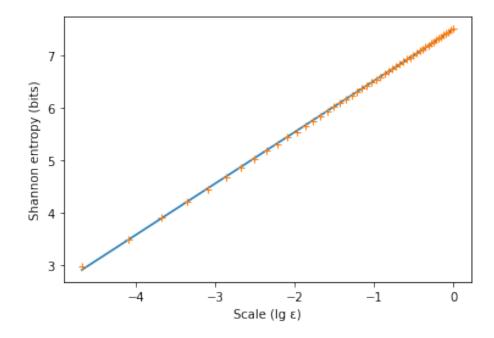
Now that we've validated infodim, what does it say about the intensity distribution of an image?

- dist = intensity_distribution(img)
- plt.plot(dist);



1 infodim(dist)

(0.98265843047326, 0.015707497682893923)



10 Probability and inference

May 30, 2020

Let's look at a simple inference problem before considering images. This example illustrates how the approach founded on probability theory differs from the naïve statistical approach usually taken by physicists.

Example 2 (Biased coin tosses). Consider tossing a biased coin N times to obtain n heads. What is the probability p' that the next coin toss comes up heads?

The temptation is to claim n/N as the probability, but this is *incorrect* if we want to allow all consistent biases. The problem with this solution is that the most probable bias is assumed to be the true bias.

The probability of getting m heads if a single head has probability p is

$$P(m \mid p) = \binom{N}{m} p^m (1-p)^{N-m}.$$

We have no other information, so we assume that all of the biases are equally likely. This means that P(p) is constant (the uniform prior). The distribution of biases p given the observation of m heads is then

$$P(p \mid m) = \frac{P(m \mid p)P(p)}{P(m)} = \frac{P(m \mid p)P(p)}{\int_0^1 d\tilde{p} P(m \mid \tilde{p})P(\tilde{p})} = \frac{P(m \mid p)}{\int_0^1 d\tilde{p} P(m \mid \tilde{p})}.$$

We compute that

$$P(m) = \binom{N}{m} \int_{0}^{1} dp \ p^{m} (1-p)^{N-m} = \binom{N}{m} \frac{m!(N-m)!}{(N+1)!} = \frac{1}{N+1},$$

so the next coin toss is heads with probability

$$p' = \int_{0}^{1} dp \, P(\text{head} \mid n, \, p) P(p \mid n) = \int_{0}^{1} dp \, p \, P(p \mid n)$$
$$= \int_{0}^{1} dp \, p(N+1) \binom{N}{n} p^{n} (1-p)^{N-n} = \frac{n+1}{N+2}.$$

For n=3 and N=10, p'=0.33. This is a more conservative estimate than p'=0.30 from the most probable bias.

11 Ising images

June 1, 2020 What happens if we apply a model from statistical physics to an image?

12 Ising images

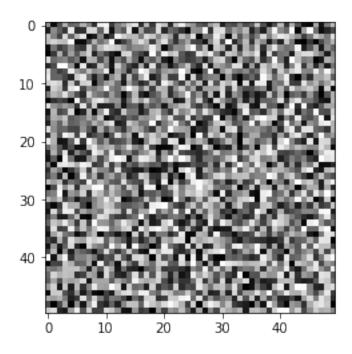
```
import numpy as np
import numpy.linalg as linalg
import matplotlib.pyplot as plt
from PIL import Image, ImageFilter, ImageOps
import imageio
plt.rcParams['image.cmap'] = 'gray'

from ipywidgets import IntProgress
from IPython.display import display
import time
```

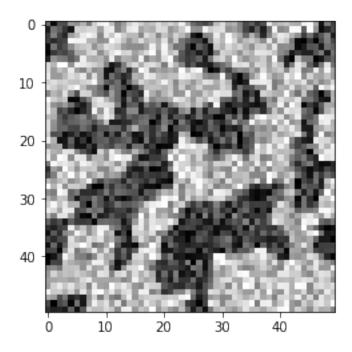
12.1 Standard Ising (on a torus)

In grayscale for fun.

```
def neighbors(a, i, j):
    \textbf{return} \  \, \text{np.hstack}([a[:,j].take([i-1,i+1], \ mode='wrap'),
                       a[i,:].take([j-1,j+1], mode='wrap')])
def energy(img, i, j):
    return -1 + np.sum(np.abs(img[i, j] - neighbors(img, i, j)))
def isingstep(\beta, img):
    w, h = np.shape(img)
    i = np.random.randint(w)
    j = np.random.randint(h)
    E0 = energy(img, i, j)
    img[i, j] *= -1
    E1 = energy(img, i, j)
P = np.exp(-β*(E1 - E0)) if E1 > E0 else 1
    if np.random.rand() > P: # Restore old
       img[i, j] *= -1
    return img
img = 2*np.random.rand(50, 50) - 1
plt.imshow(img);
```



```
n = 100000
for i in range(n):
    isingstep(3 * (np.pi / 2) / np.arctan(n - i), img)
    plt.imshow(img);
```



12.2 Image-edge Ising

```
edges = Image.open("ising-edges.png")
dedata = np.array(edges) > 128
dedges
```



```
def eenergy(img, edges, i, j):
    """Edge-modified Ising energy: 0 on edge."""

if edges[i, j]:
    return 0

w, h = np.shape(img)

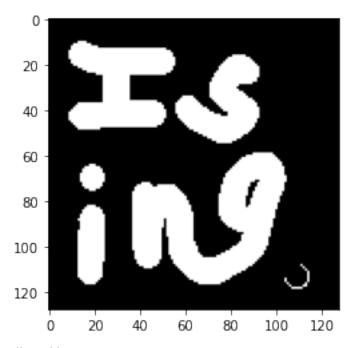
c = img[i, j]

1 = img[i-1, j] if i > 0 else img[w-1, j]

r = img[i+1, j] if i < w-1 else img[0, j]

t = img[i, j-1] if j > 0 else img[i, h-1]
```

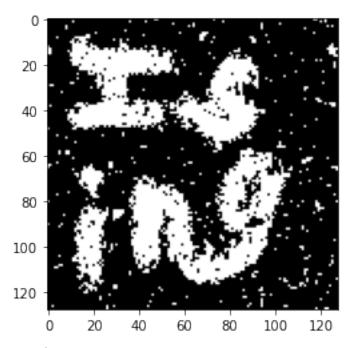
```
b = img[i, j+1] if j < h-1 else img[i, 0]
10
         return -img[i, j] * (1 + r + t + b)
11
12
     def nenergy(img, edges, i, j):
13
         """Neighbor-modified Ising energy: 0 interactions with edges."""
         if edges[i, j]:
15
             return 0
17
         w, h = np.shape(img)
         c = img[i, j]
         1 = r = t = b = 0
20
         if i > 0:
           1 = img[i-1, j] if not edges[i-1, j] else 0
22
         else:
23
            1 = img[w-1, j] if not edges[w-1, j] else 0
24
25
         if i < w - 1:
           r = img[i+1, j] if not edges[i+1, j] else 0
27
         else:
            r = img[0, j] if not edges[0, j] else 0
29
         if j > 0:
31
           t = img[i, j-1] if not edges[i, j-1] else 0
32
         else:
33
            t = img[i, h-1] if not edges[i, h-1] else 0
34
35
         if j < h - 1:
            b = img[i, j+1] if not edges[i, j+1] else 0
37
         else:
             b = img[i, 0] if not edges[i, 0] else 0
39
40
         return -img[i, j] * (1 + r + t + b)
41
42
     def eisingstep(\beta, img, edges):
         w, h = np.shape(img)
44
        i = np.random.randint(w)
45
        j = np.random.randint(h)
46
        E0 = nenergy(img, edges, i, j)
47
        img[i, j] *= -1
48
         E1 = nenergy(img, edges, i, j)
49
         P = np.exp(-\beta^*(E1 - E0)) if E1 > E0 else 1
        if np.random.rand() > P: # Restore old
            img[i, j] *= -1
        return img
53
54
     def frame(writer, data):
         writer.append_data((255 * ((eimg + 1) / 2)).astype('uint8'))
    img = Image.open("ising-letters.png")
     eimg = -1 + 2 * (np.array(img) / 255)
     plt.imshow(eimg);
```



movie.gif: Full neighbor Ising.

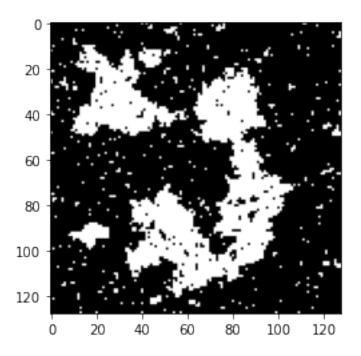
```
n = 1000000
f = IntProgress(min=0, max=1 + (n-1) // 1000) # instantiate the bar
display(f)
with imageio.get_writer('movie.gif', mode='I') as writer:
frame(writer, eimg)
for i in range(n):
    eisingstep(0.5 * (np.pi / 2) / np.arctan(n - i), eimg, edata)
if i % 1000 = 0:
    f.value += 1
    frame(writer, eimg)
plt.imshow(eimg);
```

IntProgress(value=0, max=1000)



imovie.gif: Normal Ising.

```
n = 1000000
img = eimg
with imageio.get_writer('imovie.gif', mode='I') as writer:
frame(writer, img)
for i in range(n):
isingstep(0.5 * (np.pi / 2) / np.arctan(n - i), img)
if i % 1000 = 0:
frame(writer, img)
plt.imshow(img);
```



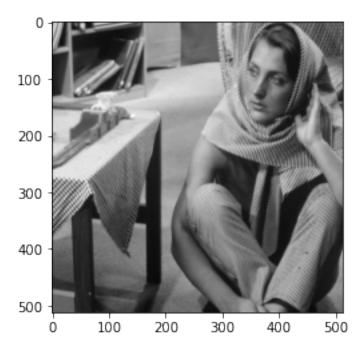
12.3 Image-metric Ising

12.3.1 Unrestricted swapping motion

Swapping preserves the intensity distribution.

```
def sienergy(img, init, i, j):
         """Inversion-symmetric image energy"""
         \verb"eq" = takewrap(img, i, j) = takewrap(init, i, j)
         return -np.abs(np.sum(2*eq - 1))
     def ienergy(img, init, i, j):
         """Image energy based on 3x3 block deviation"""
         return np.abs(init[i, j] - img[i, j])
     def swisingstep(\beta, img, edges):
         w, h = np.shape(img)
         i0 = np.random.randint(w)
         i1 = np.random.randint(w)
13
         j0 = np.random.randint(h)
         j1 = np.random.randint(h)
         E\theta = ienergy(img, edges, i0, j0) + ienergy(img, edges, i1, j1)
         img[i0, j0], img[i1, j1] = img[i1, j1], img[i0, j0]
         E1 = ienergy(img, edges, i0, j0) + ienergy(img, edges, i1, j1)
```

```
P = np.exp(-\beta^*(E1 - E0)) if E1 > E0 else 1
19
         if np.random.rand() > P: # Restore old
             img[i0, j0], img[i1, j1] = img[i1, j1], img[i0, j0]
21
         return img
22
     def nnisingstep(\beta, img, edges):
24
25
         w, h = np.shape(img)
         i0 = np.random.randint(w)
26
         i1 = int((i0 + np.sign(np.random.rand() - 1/2)) % w)
27
         j0 = np.random.randint(h)
28
         j1 = int((j0 + np.sign(np.random.rand() - 1/2)) % h)
29
         E0 = ienergy(img, edges, i0, j0) + ienergy(img, edges, i1, j1)
         img[i0, j0], img[i1, j1] = img[i1, j1], img[i0, j0]
31
         E1 = ienergy(img, edges, i0, j0) + ienergy(img, edges, i1, j1)
         P = np.exp(-\beta*(E1 - E0)) if E1 > E0 else 1
         if np.random.rand() > P: # Restore old
34
             img[i0, j0], img[i1, j1] = img[i1, j1], img[i0, j0]
         return img
     img = Image.open("barbara.png")
     eimg = -1 + 2 * (np.array(img) / 255)
     initimg = eimg.copy()
     plt.imshow(initimg);
```

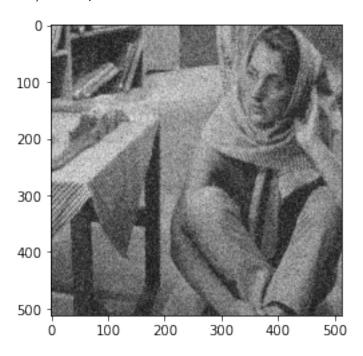


swmovie.gif: Image metric Ising (arbitrary swaps with ienergy).

```
n = 2000000
f = IntProgress(min=0, max=(1 + (n-1) // 1000)) # instantiate the bar
display(f)
with imageio.get_writer('swmovie.gif', mode='I') as writer:
```

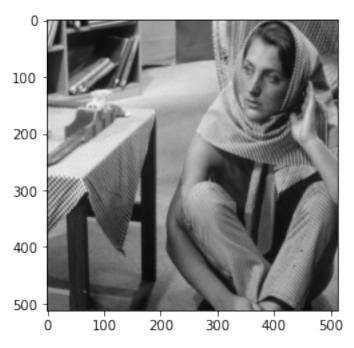
```
frame(writer, eimg)
         for i in range(n):
            k = i/n
            swisingstep(3, eimg, initimg)
            if i % 1000 = 0:
                f.value += 1
10
                frame(writer, eimg)
11
          for i in range(n):
12
             k = i/n
13
              swisingstep(4*(1 - k) + 1e-3*k, eimg, initimg)
    #
              if i % 1000 = 0:
15
                  f.value += 1
                  frame(writer, eimg)
17
          for i in range(n):
              k = i/n
              swisingstep(1e-3*(1-k)+4*k, eimg, initimg)
              if i % 1000 = 0:
21
                  f.value += 1
22
                  frame(writer, eimg)
23
     plt.imshow(eimg);
```

IntProgress(value=0, max=2000)



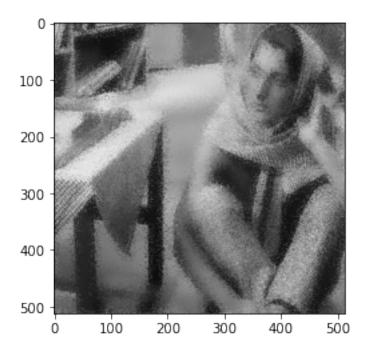
12.3.2 Nearest-neighbor swapping motion

```
img = Image.open("barbara.png")
eimg = -1 + 2 * (np.array(img) / 255)
initimg = eimg.copy()
plt.imshow(initimg);
```



 ${\tt nnmovie.gif:}\ Image\ metric\ Ising\ (neighborly\ swaps\ with\ ienergy).$

```
n = 2000000
     f = IntProgress(min=0, max=3*(1 + (n-1) // 1000)) # instantiate the bar
     with imageio.get\_writer('nnmovie.gif', mode='I') as writer:
         frame(writer, eimg)
         for i in range(n):
             k = i/n
             nnisingstep(5*(1 - k) + 1e-4*k, eimg, initimg)
             if i % 1000 = 0:
                 f.value += 1
10
                 frame(writer, eimg)
         for i in range(n):
12
             nnisingstep(1e-4, eimg, initimg)
13
             if i % 1000 = 0:
                 f.value += 1
15
                 frame(writer, eimg)
         for i in range(n):
17
             k = i/n
             nnisingstep(1e-4*(1 - k) + 5*k, eimg, initimg)
             if i % 1000 = 0:
                 f.value += 1
                 frame(writer, eimg)
22
     plt.imshow(eimg);
```



13 Statistical Mechanics of Images

June 3, 2020 Given the qualitative success of the image-metric based Ising images, we consider generalizations.

Definition 8. An *N*-element image space over metric spaces (K, d) and (P, a) is the space $Img = (P \times K)^N$. A corresponding image is an element of Img.

The space P determines the spatial arrangement of the image, and is usually two-dimensional Euclidean space. We usually consider the subset of an image space where the P-coordinates are fixed, in a grid layout. The space K determines the qualities of an image at a point in P. This is usually a color or intensity space, and in practical applications is a machine integer like $128 \in \mathbb{Z}_{256}$.

Definition 9. An *image system* on an image space Img consists of a *ground image* $I_0 \in \text{Img}$ and a *dispersion relation* $E : \mathbb{R} \to \mathbb{R}$. This defines the *energy* of an image I as

$$E(I) = \sum_{(p_0, k_0) \in I_0} \sum_{k \in \{k: (p_0, k) \in I\}} E(d(k_0, k)).$$

Example 3. For usual images in $((\mathbb{Z}_n \times \mathbb{Z}_m) \times \mathbb{Z}_{256})^N$, where N = nm and the positions of I_0 and I coincide (indexed by i and j), we have

$$E(I) = \sum_{i=1}^{n} \sum_{j=1}^{m} E(d(k_0^{ij}, k^{ij})) = \sum_{i=1}^{n} \sum_{j=1}^{m} \varepsilon \left| k_0^{ij} - k^{ij} \right|^1,$$

with typical choices of E and d.

In the binary case $(K = \mathbb{Z}_2)$, we have N independent two-level systems.

Example 4 (Grayscale images). Consider a pixel of a ground grayscale image, with integer value $k_0 \in \{0, \ldots, K-1\}$ for even K. There are then

$$2g = 2 \begin{cases} k_0, & k_0 < K/2 \\ K - k_0 - 1, & \text{else} \end{cases}$$

energy values that occur twice, and K - 2g energy values that occur once (like |x| on an interval like [-3, 8]). Thus the partition function for this single pixel is

$$\begin{split} Z_g &= \sum_{k=-g}^{K-g-1} e^{-\beta \varepsilon |k|} = 1 + \sum_{k=1}^g e^{-\beta \varepsilon k} + \sum_{k=1}^{K-g-1} e^{-\beta \varepsilon k} \\ &= 1 + \frac{e^{-\beta g \varepsilon} \left(e^{\beta g \varepsilon} - 1 \right)}{e^{\beta \varepsilon} - 1} + \frac{e^{-\beta (K-g-1)\varepsilon} \left(e^{\beta (K-g-1)\varepsilon} - 1 \right)}{e^{\beta \varepsilon} - 1} \end{split}$$

and the partition function for the whole image is

$$Z = \prod_{g=0}^{-1+K/2} Z_g^{NP(g)},$$

where NP(g) is the number of pixels in the ground image with the given g-value. We then see that

$$\ln Z = \sum_{g=0}^{-1+K/2} NP(g) \ln Z_g = N \left\langle \ln Z_g \right\rangle_G,$$

where G is the random variable that takes the value g with probability P(g). It then follows that $\langle E/N \rangle = \langle E_g \rangle_G$ and $S/N = \langle S_g \rangle_G$ as usual for extensive variables.

14 Thermodynamic quantities for images from a microscopic model

June 4, 2020 Since we are thinking of images as statistical entities, what is the corresponding microscopic model? Given such a model, what quantities do we consider in thermal equilibrium, and how can we understand different ensembles?

14.1 Quantum filled-site model (FSM)

Definition 10 (FsM). We define a lattice model corresponding to a *ground image* I_0 as follows. Each pixel with value $k_0 \in K \subseteq \mathbb{Z}$ in the image corresponds to a *site*, which is a discrete system with K levels. The energy of level k is $E_{k_0}(k) = \varepsilon |k - k_0|^r$. We

 $^{^{1}}$ If we want to consider colors, then K is a metric space and we replace $k-k_{0}$ with the metric.

usually have r = 1 or 2. We suppose that the levels are filled by fermions that interact according to the Hamiltonian

$$\mathsf{H} = \sum_{k \in K} \sum_{i} V c_{ik}^{\dagger} c_{ik} - \sum_{\ell \in \mathcal{N}_k} \sum_{j \in \mathcal{N}_i} t_{\ell} c_{ik}^{\dagger} c_{j\ell}.$$

For $K \subseteq \mathbb{Z}$, $\mathcal{N}_k = k + \{-1, 0, 1\}$.

14.2 Observables and thermodynamic state variables

Several observables of the FSM are of interest:

• Pixel colors. The occupations n_k of different levels at a *single* site induce a distribution on K. In equilibrium, the mean level

$$\langle k \rangle \equiv \frac{\sum_{k \in K} k n_k}{\sum_{k \in K} n_k}$$

should be near k_0 , since the energy of a level is symmetric about k_0 . As the temperature increases, so will the variance of the mean level. On the flip side, does *varying* k_0 for many pixels quasistatically (changing the ground image) do work on the system? Yes, but is this consistent with what we expect?

- Color distribution. The net occupations m_k of different levels across *all* sites induce a distribution on K. In the special case of gray images (so levels are intensity), the entropy of the induced random variable is intensity entropy that we have studied previously. This is distribution is stationary when different levels cannot interact, but is it so at finite temperature?
- **Opacity**. The net occupancy of a *site* could be connected to its opacity. In equilibrium, this should be similar across all sites. Then regions with *no* particles during nonequilibrium processes make sense. The picture of a gas with fluctuating density that emits light comes to mind. When at maximum opacity, the gas in that region cannot be compressed further, and cannot accept more particles. The canonical density properties of a photon gas (like energy density) might be a good reason to choose the particles to be bosons.
- Number of pixels. We could vary the total number of pixels different ways. One way is to have a continuous ground image, and choose different grid discretizations. Another way is to have a large ground image grid and vary the zoom level. It would be sensible to combine these sorts of transformations with pixel color transformations, since they include translation and rotation as special cases. This seems most most similar to varying the volume of a gas. Including opacity makes fast adiabatic piston motion volume changes like V → 2V make sense.
- Number of particles. Depending on if we allow interactions between levels, it may be appropriate to consider chemical potentials. Either for all particles, or for each color. Could this be conjugate to opacity?

• The usual. Given that quasistatic transformation of the other quantities does work the way we expect, we can consider the usual response variables like heat capacities and compressibilities. There is also the thermodynamic entropy.

15 Progress summary (from beginning)

June 6, 2020

Over the last two weeks, I calculated some metrics on images and did some basic simulations. The most important metric was the intensity entropy, which is used as the "entropy" of an image in the maximum entropy method (MEM) of image reconstruction used by astronomers. This was calculated for a whole image and locally in different regions of an image. On the topic of scaling, fractal dimensions were explored. The box-counting dimension was computed for different images, and the information dimension of the intensity distribution was considered. I also did readings on probability theory and machine learning, since the usual frequentist approach that experimental physicists take is not applicable. Variants of Ising models were simulated for images, which led to the postulation of a microscopic model for varying images (the FSM), which is similar to a Hubbard model. The implications of this approach remain to be explored.

16 Progress summary

June 12, 2020

This week, I investigated different methods for obtaining thermodynamic quantities from simulations. The issue is that quantities like entropy and the Helmholtz free energy depend on global properties of the phase space (the probability or density of a microstate), and thus cannot be constructed as cumulants of microstates during a simulation. A related issue is the improbability of "tunneling" across energy barriers when taking the usual temperature-weighted steps.

These considerations motivate histogram-based methods, like the Wang-Landau algorithm that I implemented. Instead of operating in the canonical ensemble, we take a biased random walk on energies so that the result is a flat histogram of visited energies. The density of states from this process may then be used to compute a canonical partition function. Modifications where we keep a joint density of states with respect to another variable make other ensembles accessible.

Further progress with the Wang-Landau algorithm was slowed by a discrepancy in the steps needed between Wang and Landau's results and mine for the 32 by 32 Ising ferromagnet. Their original paper claims a 0.035 % average error in the density of states after only 700 000 total spin flips. This is far fewer than the spin flips I needed, and another paper that looks at the scaling of the tunneling time (spin flips to go from ground to anti-ground state) might corroborate this. Their tunneling times are all well above 1 720 000 (an eighth of their $\tau_{\rm exact}$) for the same simulation. Success in the Wang-Landau algorithm requires visiting all energies many times, so execution takes several tunneling times. We are still trying to resolve this discrepancy, as well

²10.1103/PhysRevLett.86.2050

^{310.1103/}PhysRevLett.92.097201

as other vague details from the original paper, like the possible choice of energy bins for continuous systems and unspecified edge behavior for energy intervals.

I have looked at other histogram methods like WHAM, as well as parallel tempering (replica exchange MCMC). Both parallel tempering and the Wang-Landau algorithm are attractive because they are easily parallelizable. I have also come back to considering the MAXENT/MEM image reconstruction technique and the issues of entropy and feature representation again.

17 Description of MAXENT

June 13, 2020

I describe the basic idea of the Maxent reconstruction technique, and implement the most naïve approach. This makes it clear that a better optimization algorithm is needed. The idea here is less to make it work than to get an idea of how it works, and then use a better software package later on if we do end up using Maxent.

18 Maximum-entropy reconstruction

```
import numpy as np
import matplotlib.pyplot as plt
from scipy import signal, misc
```

Given a measurement D of a system I_0 , we wish to reconstruct I_0 from D. We take the Bayesian approach and find the I that maximizes $P(I|D) \propto P(D|I)P(I)$, where the likelihood is related to the error in D due to I and the prior is $P(I) = \exp(\lambda S(I))$, where S is some notion of the entropy of an image. If $D = T(I_0)$, then $P(D|I) = \exp(-E(T(I), D))$, for some metric E on D's. From the form of the objective $\ln P(D|I) + \ln(I) = -E(T(I), D) + \lambda S(I)$, we see that the entropy acts as a regularizer.

The astronomers have both I and D as intensity lists $\mathbb{Z}_N \to \mathbb{R}_{\geq 0}$, where

$$S(I) = \sum_{i} I_i \ln I_i$$

and

$$E(D', D) = \sum_{i} \exp\left(-\frac{(D'_{i} - D_{i})^{2}}{2\sigma_{i}}\right)$$

(with empirical σ_i). The transformation T is convolution with the point spread function of the telescope.

To perform the optimization, we need not only the functions S and E, but also a procedure to modify candidate images.

```
def maxent_objective(D, I, λ): # For minimization
    return D.E(I.transform()) - λ*I.S

# # Greedy for now, but can be something like simulated annealing
def maxent(D, I, λ = 1, N = 1_000_000, ε = 1e-8):
f0 = np.inf
f = maxent_objective(D, I, λ)
```

```
i = 0
while ε < f0 - f and i < N:
I.propose()
fv = maxent_objective(D, I, λ)
if fv < f: # Greedy
f0, f = f, fv
I.accept()
i += 1
if i % (N // 20) = 0:
print("Maxent: {} / {}".format(i, N, f0 - f))
return I, i, f</pre>
```

18.1 Example: 1D Point from Gaussian

```
class Gaussian:
         def __init__(self, \mu=0, \sigma=1):
             self.\mu = \mu
             self.\sigma = \sigma
         def E(self, Gv):
             return (self.\mu - Gv.\mu)**2 + (self.\sigma - Gv.\sigma)**2
    class Point:
       def __init__(self, x=0):
            self.x = x
10
            self.dx = 0
            self.S = self.entropy()
12
       def propose(self):
13
          self.dx = np.random.rand() - 0.5
            self.S = self.entropy()
15
       def accept(self):
           self.x += self.dx
17
            self.dx = 0 # Idempotence
        def entropy(self):
         return -(self.x - 10)**2 # Opposite from true max
       def transform(self):
            return Gaussian(μ = self.x + self.dx)
    D = Gaussian(0, 1)
     I = Point(9)
     I0, _, _ = maxent(D, I, \lambda = 1, N = 1_000_000, \epsilon = 1e-4)
3
```

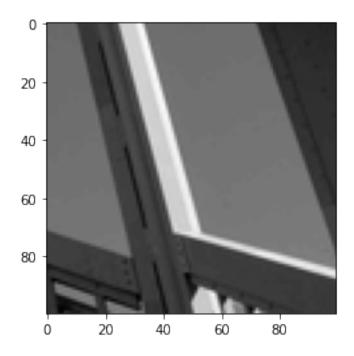
Maxent: i: 1000000 / 1000000, Δf: 0.011299906795997572

4.268883578482481

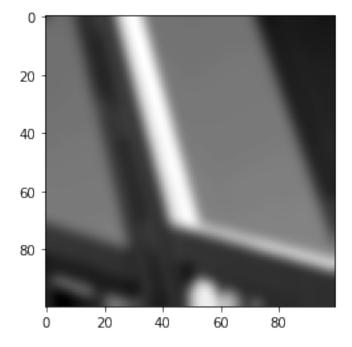
Results are sort of near 5. The optimization is terrible, but you get the idea: the entropy shifts the best point away from zero.

18.2 Example: Image from PSF convolution (measurement)

```
class DImage:
       def __init__(self, I):
    self.I = I
        def E(self, Dv):
           return np.sum((self.I - Dv.I)**2)
    class IImage:
       def __init__(self, I):
           self.I = I
           self.w, self.h = np.shape(I)
           self.i, self.j = 0, 0
11
           self.I0 = 0
12
           self.Iv = 0
          n = int(np.sqrt(self.w * self.h))
         self.G = signal.windows.gaussian(n // 10, n // 50)
           self.S = self.entropy()
      def propose(self):
17
          self.i, self.j = np.random.randint(self.w), np.random.randint(self.h)
          I0 = self.I[self.i, self.j]
          self.I0 = I0
           self.Iv = np.random.randint(256)
           self.S = self.entropy()
      def accept(self):
           self.I[self.i, self.j] = self.Iv
       def entropy(self):
           return -np.sum(np.log(self.I + 1)) + self.I0*np.log(self.I0 + 1) - self.Iv*np.log(self.Iv + 1)
26
        def transform(self):
27
         Iv = self.I.copy()
           Iv[self.i, self.j] = self.Iv
            return DImage(signal.sepfir2d(Iv, self.G, self.G))
plt.imshow(I.I, cmap='gray');
```

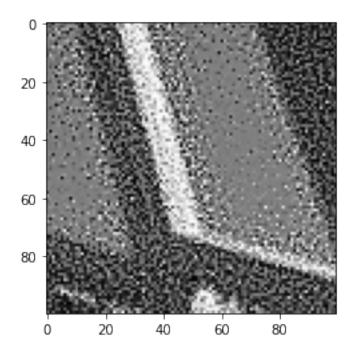


plt.imshow(I.transform().I, cmap='gray');



1 I = IImage(misc.ascent()[250:350,250:350])

```
Iguess = IImage(128 * np.ones((I.w, I.h), dtype=int))
IO, _, _ = maxent(I.transform(), Iguess, \lambda = 1e-9, N = 1_000_000, \epsilon = 1e-20) # Just do the max iterations
Maxent: 50000 / 1000000
Maxent: 100000 / 1000000
Maxent: 150000 / 1000000
Maxent: 200000 / 1000000
Maxent: 250000 / 1000000
Maxent: 300000 / 1000000
Maxent: 350000 / 1000000
Maxent: 400000 / 1000000
Maxent: 450000 / 1000000
Maxent: 500000 / 1000000
Maxent: 550000 / 1000000
Maxent: 600000 / 1000000
Maxent: 650000 / 1000000
Maxent: 700000 / 1000000
Maxent: 750000 / 1000000
Maxent: 800000 / 1000000
Maxent: 850000 / 1000000
Maxent: 900000 / 1000000
Maxent: 950000 / 1000000
Maxent: 1000000 / 1000000
Maxent: i: 1000000 / 1000000, Δf: 4.847227362683043
plt.imshow(I0.I, cmap='gray');
```



19 "Greedy" painting-like pictures

June 14, 2020

We noticed that swapping neighboring pixels in the previous simulations produced images that looked somewhat like paintings. There are other ways to make images look like paintings, and this is one of them. We randomly draw a shape of fixed size on the image. The color of the shape is the mean color of the image in the rectangle where the shape is drawn. This is done many times, and the size of the shapes gradually decreases. I call this "greedy" because choosing the mean color is the locally optimal color. This method has the advantage of being similar to the process of painting, which is why it is presented instead of the usual "oilify" filters in image processing software. An improvement would try to draw shapes that reflect the shapes of the subject matter, and perhaps add other texture. These kinds of considerations might require more global strategies.

20 Greedy Cubism

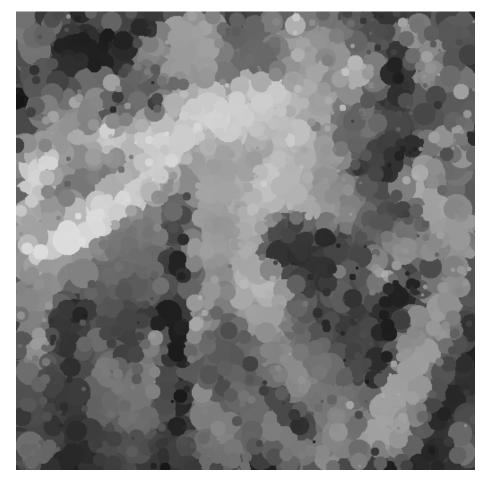
Draw an image by greedily drawing cubes.

```
import numpy as np
import matplotlib.pyplot as plt
from PIL import Image, ImageOps, ImageDraw
from scipy import signal, misc

img = Image.open("barbara.png")
```

```
def greedy_cubes(img, N):
    xs, ys = img.size
    art = Image.new(img.mode, (xs, ys))
    draw = ImageDraw.Draw(art)
    rmax = int(np.sqrt(xs*ys) / 10)
    r = rmax
    ε = 10
    for i in range(N):
        x = np.random.randint(xs)
         y = np.random.randint(ys)
         [ \texttt{np.mean(c)} \ \textbf{for} \ \texttt{c} \ \textbf{in} \ \texttt{cimg.split()} ]
         r = int(rmax * (1 - (i/(N+1))**2)) + 1
         box = [x - r, y - r, x + r, y + r]
         \verb|color = tuple(int(np.round(np.mean(c)))| | \textit{for c in } img.crop(box=box).split())|
         draw.ellipse(box, fill=color)
    return art
art = greedy_cubes(img, 10000)
```

ı art



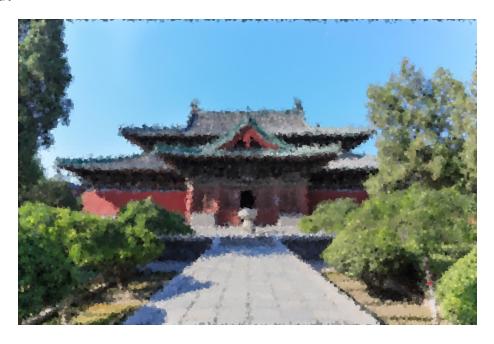
cimg = Image.open('test.jpg')

2 cimg



 $_{1}$ art = greedy_cubes(cimg, 1000000)

2 art



21 Exact density of states for gray and Bw images

June 16, 2020

In doing the future statistical simulations of images, we would like to know the density of states g(E) in our site-based model. This is the number of ways to choose the N pixel values m_n from $0, \ldots, M$ so that

$$E = \sum_{n=1}^{N} \left| m_n - m_n^* \right|,$$

where $0 \le E \le MN$ and m_n^* is the value of the ground image at pixel n. While the solution to follow works for arbitrary values of m_n^* , the results are simplest (no multinomial coefficients) if we consider $m_n^* = 0$ or M or $m_n^* = M/2$. That is, the image is all black or white (BW) or gray. Then we have

$$E = \sum_{n=1}^{N} g' m_n$$

with $m_n = 0, ..., M$ and g' = 1 (BW) or $m_n = 0, ..., M/2$ and g' = 2 (gray).⁴ In that case, we'll consider BW for concreteness.

We encode the energy as an exponent, so that g(E) is the coefficient of x^E in the polynomial

$$p(x) \equiv \left(x^0 + x^1 + \dots + x^M\right)^N,$$

since each inner sum represents different assignments of a pixel value and the products will produce terms that represent all different combinations of values. We then expand to find

$$\begin{split} p(x) &= \left(\frac{1 - x^{M+1}}{1 - x}\right)^{N} \\ &= \sum_{k=0}^{N} \sum_{j=0}^{\infty} (-1)^{k} \binom{N}{k} x^{(M+1)k} \cdot (-1)^{j} \binom{-N}{j} x^{j} \\ &= \sum_{k=0}^{N} \sum_{j=0}^{\infty} (-1)^{k} \binom{N}{k} \binom{N+j-1}{j} x^{(M+1)k+j}. \end{split}$$

The value of j in the inner sum for x to have power E is j = E - k(M+1), so the coefficient of x^E in p(x) is

$$g(E) = \sum_{k=0}^{N} (-1)^k \binom{N}{k} \binom{N+E-k(M+1)-1}{E-k(M+1)}.$$

(Due to the stucture of the binomial coefficients, we may let the summation extend over all $k \in \mathbb{Z}$ for further manipulation.)

 $^{^4}$ This gives m=0 degeneracy 2, which is not strictly correct but matters little.

22 Comparison to Wang and Landau's results

June 18, 2020

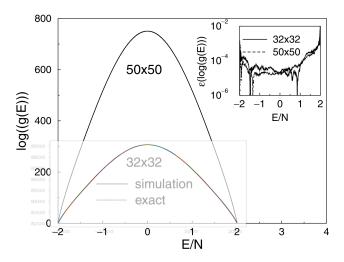


Figure 1: Our results agree with Wang and Landau's results, though it took more iterations than they reported to reproduce.

23 Progress summary

June 19, 2020

This week, I further prepared to study the thermodynamics of our image systems. I derived the exact density of states for the all-black image, and the same technique (generating functions) could be used with computer enumeration of integer partitions to obtain the density of states for an arbitrary image system. I also spent more time improving my implementation of the Wang-Landau algorithm. It is now able to simulate arbitrary energy bins and divide different energy intervals across multiple CPU cores and combine them back together. The python code was made type-stable so that functions and the simulation state can be JITed by a LLVM-based compiler (Numba). These two improvements increased the speed of the simulations by more than a factor of 10. With some more tweaks and code to automate the preparation of parallel kernels and manage results, we should be able to easily perform these simulations for many parameter values with high statistics.

24 Simulations for canonical ensemble averages

June 22, 2020 We implement some simulation software for the Wang-Landau algorithm.

24.1 Organized parallel simulations

We need some utility functions that

- Manage passing simulation parameters to parallel processes
- Run the parallel processes with correct input and distinct random states
- Save parameters and results to files automatically (without overwriting previous results)
- Log results while running simulations
- · Join parallel results back together

Since the simulation systems (Numba jitclass objects) are not picklable (Python's serialization used to communicate between processes by multiprocessing), the relevant parameters to reconstruct a system are passed between processes. We require that all systems be accessible from the systems module, so that we may pass and save the class name as a way of accessing the specification of the system.

```
import numpy as np
from multiprocessing import Pool
from scipy.signal import windows
import time
import os, struct # for `urandom`
import pprint # for parameters
import tempfile
import h5py, hickle
if 'src' not in sys.path: sys.path.append('src')
import systems
def make_params(system):
    return {system.__class__._name__:
            {k: v for k, v in zip(system.state_names(), system.state())}}
def make_system(system_params, system_prep = lambda x:x):
    return system_prep([getattr(systems, cls)(**state)
                         for cls, state in system_params.items()][0])
\textbf{def make\_psystems(params, psystem\_prep): \#:: params \rightarrow (system \rightarrow [system]) \rightarrow [params]
    log = params.get('log', False)
    if log:
        print('Finding parallel bin systems ... ', end='', flush=True)
    psystems = psystem_prep(make_system(params['system']), **params['parallel'])
    if log:
        print('done.')
    return [(make_params(s), *r) for s, *r in psystems]
def urandom_reseed():
    """Reseeds numpy's RNG from `urandom` and returns the seed."""
    seed = struct.unpack('I', os.urandom(4))[0]
    np.random.seed(seed)
    return seed
def worker(simulation, psystem, params):
    log = params.get('log', False)
```

```
urandom_reseed()
         psystem_params, *args = psystem
         system = make_system(psystem_params)
11
12
             print('(', end='', flush=True)
         # Individual simulation output is too much when running parallel simulations.
14
         params['simulation'].update({'log': False})
15
         results = simulation(system, *args, **params['simulation'])
16
             print(')', end='', flush=True)
18
         return results
19
     def show_params(params):
21
         print('Run parameters')
         print('----')
23
         pprint.pp(params, sort_dicts=False)
24
25
         print()
     def save_results(results, params, log=False, prefix='simulation-', dir='data'):
         with tempfile.NamedTemporaryFile( # Note: dir shadows dir()
28
             mode='wb', prefix=prefix, suffix='.h5', dir=dir, delete=False) as f:
             with h5py.File(f, 'w') as hkl:
30
                 if log:
31
                     print('Writing results ... ', end='', flush=True)
                 hickle.dump({
33
                     'parameters': params,
34
                      'results': results
                 }, hkl)
                 relpath = os.path.relpath(f.name)
                 if log:
38
                     print('done: ', relpath)
39
         return relpath
41
     def run(params, simulation, system_prep,
             psystem_prep = lambda x:x, result_wrapper = lambda x:x, **kwargs):
43
         params.update(kwargs)
44
         parallel = 'parallel' in params
45
         log = params.get('log', False)
         if log:
             show_params(params)
48
         if parallel:
             psystems = make_psystems(params, psystem_prep)
         else:
52
             psystem = make_system(params['system'], system_prep)
53
54
55
             if parallel:
                 print('Running || ', end='', flush=True)
57
             else:
58
                 print('Running ...')
             start_time = time.time()
         if parallel:
62
             with Pool() as pool:
63
                 results = pool.starmap(worker, ((simulation, args, params) for args in psystems))
64
             results = [result_wrapper(r) for r in results]
```

```
else:
66
             results = result_wrapper(simulation(*psystem, **params['simulation'], **kwargs))
67
68
             seconds = int(time.time() - start_time)
             if parallel:
                 print(' || done in', seconds, 'seconds.')
73
                 print('... done in', seconds, 'seconds.')
74
         # Save single-shot results in a singleton list so that we can analyze parallel and
         # single results the same way.
         rdict = {'results': results if parallel else [results]}
         save_params = params.pop('save', False)
         if save params:
             relpath = save_results(results, params, log, **save_params)
             rdict.update({'file': relpath})
         return rdict
```

We can choose overlapping bins for the parallel processes to negate boundary effects.

```
def extend_bin(bins, i, k = 0.05):
    if len(bins) ≤ 2: # There is only one bin
        return bins
    k = max(0, min(1, k))
    return (bins[i] - (k*(bins[i] - bins[i-1]) if 0 < i else 0),
        bins[i+1] + (k*(bins[i+2] - bins[i+1]) if i < len(bins) - 2 else 0))</pre>
```

Often parallel results are the value of a real function on some grid or list of bins. Given that many of these pieces may overlap, we must combine them back together into a full solution. This requires first transforming the results so that they are comparable, and then performing the combination. The most common case is repetition of the same real-valued experiment. No transformation is required, and we simply average all the results. Even better, we may assign the values within each piece a varying credence from 0 to 1 and perform weighted sums.

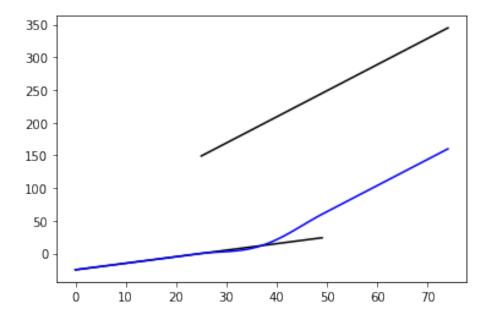
We must join results that are only known up to an additive constant. We must then assign an offset to each solution, where one of the offsets may be taken to be zero without loss of generality. The algorithm below implements the offsets that minimize the weighted mean-squared error of the overlap regions

$$\varepsilon = \sum_{i < j,k} ((y_{ik} + c_i) - (y_{jk} + c_j))^2 w_{ik} w_{jk},$$

where i and j index different (overlapping) results, k indexes the full grid, and w_{ik} is the nonnegative weight assigned to index k of result i. Since we usually have results defined on a subset of the whole grid, we assign weights to the subset and set the other weights to be zero, so that the missing values y_{ik} outside the known subset are irrelevant.

```
def join_results(xs, ys, wf = windows.hann):
    xf = np.array(sorted(set().union(*xs)))
```

```
xi = [np.intersect1d(xf, x, return_indices=True)[1] for x in xs]
3
         n, m = len(xf), len(xs)
         ws = np.zeros((m, n))
         wc = np.zeros((m, n))
         for i in range(m):
            l = len(xs[i])
            ws[i, xi[i]] = wf(1)
             wc[i, xi[i]] = np.ones(1)
         unweighted = np.sum(wc, \theta) \leq 1
12
13
         \Delta ys = np.zeros(m)
         for i in range(m):
15
            \Sigma c = \Sigma w = 0
            for j in range(i):
                a = Δys[j] * np.ones(n)
                 a[xi[j]] += ys[j]
                a[xi[i]] -= ys[i]
                w = ws[i,:] * ws[j,:]
                Σc += np.dot(a, w)
2.2
                Σw += np.sum(w)
23
             \Delta ys[i] = \Sigma c / \Sigma w if i > 0 else 0
         yf = np.zeros(n)
        for i in range(m):
            w = ws[i, xi[i]]
            # The weights are meaningful only as relative weights at overlap points.
           # We must avoid division by zero at no-overlap points with weight zero.
            # Note that overlap points with all weights zero will be an issue, as
             # the weights in that situation are meaningless.
32
             w[(w = 0) % unweighted[xi[i]]] = 1
33
             yf[xi[i]] += (ys[i] + Δys[i]) * w
            ws[i, xi[i]] = w
35
         Σws = np.sum(ws, 0)
         yf /= Σws
37
         return xf, yf, Δys
         Demonstration of joining overlapping results.
     if __name__ = '__main__':
         from matplotlib import pyplot as plt
         xs = [np.arange(testn), np.arange(testn // 2, testn + testn // 2)]
         ys = [np.arange(testn) - testn // 2, 4*np.arange(testn // 2, testn + testn // 2) + (testn - 1)]
         axs, ays, _ = join_results(xs, ys)
         for x, y in zip(xs, ys):
           plt.plot(x, y, 'black')
         plt.plot(axs, ays, 'blue');
```



24.2 Systems for organized simulation

```
import sys
if 'src' not in sys.path: sys.path.append('src')
```

List of imports for all relevant systems.

```
from statistical_image import *
from ising_model import *
```

24.2.1 Specification

Extensions

- Encode this specification and the requirements of simulations as abstract base classes?
- Consider changing to numba.typed.Dict in the future if the API is guaranteed to be stable.

A system for simulation is a Numba jitclass that implements state, state_names, and copy functions. Given an instance s of a system class System , these functions should satisfy

```
id_systems = [
s,
s.copy(), # deep
System(*s.state()),
System(**{k: v for k, v in zip(s.state_names(), s.state())})

1 = len({t.state() for t in id_systems}) = len({t.state_names() for t in id_systems})
```

By default, we have

```
class System: # ...
def copy(self):
return self.__class__(*self.state())
```

In addition, different simulations may require more methods to be implemented.

24.2.2 Wang-Landau

A Wang-Landau simulation requires a System to have the variables E, Ev, and sweep_steps, and to implement the methods energy_bins, energy, propose, and accept.

24.2.3 System: The 2D Ising model

```
import numpy as np
     from numba.experimental import jitclass
     from numba import int64
     integer = int64
     __all__ = ['IsingModel']
     @jitclass([
         ('spins', integer[:,:]),
         ('L', integer),
         ('sweep_steps', integer),
         ('E', integer),
('Ev', integer),
         ('dE', integer),
         ('i', integer),
         ('j', integer)
     ])
11
     class IsingModel:
12
         def __init__(self, spins):
13
            shape = np.shape(spins)
14
            if len(shape) \neq 2 or shape[0] \neq shape[1]:
15
                 raise ValueError('IsingModel spin array is not a square.')
16
           self.spins = spins
           self.L = shape[0]
18
             self.sweep_steps = shape[0]**2
             self.E = self.energy()
             self.Ev = self.E
21
            self.dE = 0
22
            self.i = 0
23
            self.j = 0
         def state(self):
25
             return (self.spins.copy(),)
         def state_names(self):
            return ('spins',)
         def copy(self):
            return IsingModel(*self.state())
30
         def energy_bins(self):
31
           Ex = 2 * self.L**2
32
             \Delta E = 4
33
             Es = np.arange(-Ex, Ex + \DeltaE + 1, \DeltaE)
             # Penultimate indices are not attainable energies
35
             return np.delete(Es, [1, -3])
```

```
def neighbors(self, i, j):
37
             return np.array([
38
                 self.spins[i-1, j],
39
                 self.spins[(i+1) % self.L, j],
                 self.spins[i, j-1],
                 self.spins[i, (j+1) % self.L],
42
             ])
43
         def energy(self):
44
             E = 0
45
             for i in range(self.L):
                 for j in range(self.L):
47
                     E -= np.sum(self.spins[i, j] * self.neighbors(i, j))
             return E // 2
49
         def propose(self):
             i, j = np.random.randint(self.L), np.random.randint(self.L)
51
             self.i, self.j = i, j
52
             dE = 2 * np.sum(self.spins[i, j] * self.neighbors(i, j))
53
             self.dE = dE
54
             self.Ev = self.E + dE
55
         def accept(self):
56
             self.spins[self.i, self.j] *= -1
57
             self.E = self.Ev
     24.2.4 System: Statistical Image
     import numpy as np
     from numba.experimental import jitclass
     from numba import int64
     integer = int64
     __all__ = ['StatisticalImage']
     @jitclass([
         ('I0', integer[:]),
         ('I', integer[:]),
('N', integer),
         ('M', integer),
         ('sweep_steps', integer),
         ('E', integer),
('Ev', integer),
         ('dE', integer),
         ('dx', integer),
11
         ('i', integer)
     ])
13
     class StatisticalImage:
14
         def __init__(self, I0, I, M):
15
             if len(I0) \neq len(I):
16
                 raise ValueError('Ground image I0 and current image I should have the same length.')
             if M < 0:
18
                raise ValueError('Maximum site value must be nonnegative.')
19
             self.I0 = I0
            self.I = I
21
             self.N = len(I0)
22
             self.M = M
23
             self.sweep_steps = len(I0)
24
             self.E = self.energy()
             self.Ev = self.E
```

self.dE = 0

```
self.dx = 0
28
            self.i = 0
29
        def state(self):
            return self.I0.copy(), self.I.copy(), self.M
31
        def state_names(self):
           return 'I0', 'I', 'M'
33
34
        def copy(self):
           return StatisticalImage(*self.state())
35
        def energy_bins(self):
            E\theta = \theta
            Ef = np.sum(np.maximum(self.I0, self.M - self.I0))
38
            \Delta E = 1
39
            return np.arange(E0, Ef + ΔE + 1, ΔE)
        def energy(self):
            return np.sum(np.abs(self.I - self.I0))
        def propose(self):
43
           i = np.random.randint(self.N)
          self.i = i
45
          x0 = self.I0[i]
           x = self.I[i]
            r = np.random.randint(2)
           if x = 0:
               dx = r
           elif x = self.M:
               dx = -r
52
            else:
53
               dx = 2*r - 1
          dE = np.abs(dx) if x0 = x else (dx if x0 < x else -dx)
55
           self.dx = dx
            self.dE = dE
57
            self.Ev = self.E + dE
       def accept(self):
            self.I[self.i] += self.dx
            self.E = self.Ev
```

24.3 The Wang-Landau algorithm (density of states)

We determine thermodynamic quantities from the partition function by obtaining the density of states from a simulation.

```
from numba import njit
import numpy as np

import sys
if 'src' not in sys.path: sys.path.append('src')
import simulation as sim

Utility functions for the simulation.

Unjit(inline='always')
def bisect_right(a, x, lo=0, hi=None):
if lo < 0:
raise ValueError('lo must be non-negative')
if hi is None:
hi = len(a)
while lo < hi:
```

```
mid = (lo + hi) // 2
              if x < a[mid]:</pre>
                  hi = mid
              else:
11
                  lo = mid + 1
         return lo
13
14
     @njit
15
     def binindex(a, x):
          return bisect_right(a, x, lo=0, hi=len(a) - 1) - 1
     @njit
     def flat(H, \varepsilon = 0.2):
          """Determines if a histogram is approximately flat to within \epsilon of the mean height."""
          return not np.any(H < (1 - \epsilon) * np.mean(H)) and np.all(H \neq 0)
```

24.3.1 Algorithm

A Wang-Landau algorithm, with quantities as logarithms and with monte-carlo steps proportional to $f^{-1/2}$ (a "Zhou-Bhat schedule").

We use energy bins encoded by numbers E_i for $i \in [0, N]$, so that there are N bins. The energies E covered by bin i satisfy $E_i \le E < E_{i+1}$. For the bounded discrete systems that we are considering, we must choose E_N to be an arbitrary number above the maximum energy.

```
def system_prep(system):
         return system, system.energy_bins()
     def simulation(system, Es,
                    max_sweeps = 1_000_000,
                     flat_sweeps = 1,
                     eps = 1e-8,
                    logf0 = 1,
                     flatness = 0.2.
                     log = False
                    ):
         Run a Wang-Landau simulation on system with energy bins Es to determine
         the system density of states g(E).
13
14
            system: The system to perform the simulation on (see systems module).
15
             Es: The energy bins of the system to access. May be a subset of all bins.
            max_sweeps: The scale for the maximum number of MC sweeps per f-iteration.
                 The actual maximum iterations may be fewer, but approaches max_sweeps
18
                 exponentially as the algorithm executes.
            flat_sweeps: The number of sweeps between checks for histogram flatness.
                In AJP [10.1119/1.1707017], Landau et. al. use 10_000 sweeps.
             eps: The desired tolerance in f. Wang and Landau [WL] use 1e-8 in the original
                paper [10.1103/PhysRevLett.86.2050].
             logf0: The initial value of ln(f). WL set to 1.
             flatness: The desired flatness of the histogram. WL set to 0.2 (80% flatness).
             log: Whether or not to print results of each f-iteration.
         Returns:
```

```
A tuple of results with entries:
29
             Es: The energy bins the algorithm was passed.
30
             S: The logarithm of the density of states (microcanonical entropy).
31
             H: The histogram from the last f-iteration.
32
             converged: True if each f-iteration took fewer than the maximum sweeps.
34
         Raises:
35
         ValueError: One of the parameters was invalid.
36
37
        if (max_sweeps \leq 0
38
             or flat_sweeps \leq 0
39
             or eps \leq 1e-16
             or not (0 < \log 10 \le 1)
41
             or not (0 \le \text{flatness} < 1):
             raise ValueError('Invalid Wang-Landau parameter.')
43
44
         # Initial values
         M = max_sweeps * system.sweep_steps
46
         flat_iters = flat_sweeps * system.sweep_steps
47
         logf = 2 * logf0 # Compensate for first loop iteration
48
         logftol = np.log(1 + eps)
49
         converged = True
         steps = 0
         E0 = Es[0]
53
        Ef = Es[-1]
54
         N = len(Es) - 1
         S = np.zeros(N) # Set all initial g's to 1
56
         H = np.zeros(N, dtype=np.int32)
         i = binindex(Es, system.E)
58
59
        if log:
60
             fiter = 0
             print("Wang-Landau START")
62
             print("fiter\t steps\t\t max steps")
63
             print("----\t\t -----")
65
         while logftol < logf:</pre>
             H[:] = 0
67
             logf /= 2
68
             iters = 0
             niters = int((M + 1) * np.exp(-logf / 2))
70
            if log:
                fiter += 1
72
             while (iters % flat_iters \neq 0 or not flat(H, flatness)) and iters < niters:
73
                 system.propose()
                 Ev = system.Ev
75
                 j = binindex(Es, Ev)
                 if E0 \le Ev < Ef and (
                     S[j] < S[i] or np.random.rand() \leq np.exp(S[i] - S[j]):
                     system.accept()
                     i = j
                 H[i] += 1
                 S[i] += logf
82
                 iters += 1
83
             steps += iters
84
             if niters \leq iters:
```

```
converged = False
86
             if log:
                 print(fiter, "\t", iters, "\t", niters)
88
         if log:
             print("Done: ", steps, " total MC iterations;",
                   "converged." if converged else "not converged.")
         return Es, S, H, steps, converged
93
     def wrap_results(results):
         return {k: v for k, v in zip(('Es', 'S', 'H', 'steps', 'converged'), results)}
     24.3.2 Parallel decomposition
     def find_bin_systems(system, Es, Ebins, sweeps = 1_000_000, method = 'w1'):
         Find systems with energies in the bins given by `Es` by stepping `sys`.
         Args:
             system: The initial system to search from. This is usually a ground state.
             Es: The energies of the system.
             Ebins: The energy bins to find systems for.
             sweeps: The maximum number of MC sweeps to try.
             method: The string name of the search method to try.
11
                 'wl': Wang-Landau steps where we prefer energies we have not visited
                 'increasing': Only accept increases in energy. This only works for
                     steps that are not trapped by local maxima of energy.
         Returns:
            A list of independent systems with energies in Ebins.
17
             ValueError: The method argument was invalid.
20
             RuntimeError: Bin systems could not be found after N steps.
22
         if method = 'wl':
23
            S = np.zeros(len(Es), dtype=np.int32)
         systems = [None] * (len(Ebins) - 1)
25
         n = 0
         N = sweeps * system.sweep_steps
         1 = len(Ebins) - 1
         systems = [system] * 1
         empty = np.repeat(True, 1)
30
         i = binindex(Es, system.E)
         while np.any(empty) and n < N:</pre>
32
             for s in range(1):
33
                 if empty[s] and Ebins[s] \leq system.E < Ebins[s + 1]:
34
                     systems[s] = system.copy()
35
                     empty[s] = False
37
             system.propose()
             j = binindex(Es, system.Ev)
39
             if method = 'wl':
40
                 if S[j] < S[i]:</pre>
                     i = j
                     system.accept()
```

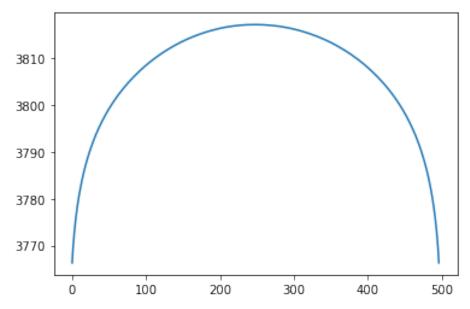
```
S[i] += 1
44
             elif method = 'increasing':
45
                 if system.E < system.Ev:</pre>
                    system.accept()
             else:
                 raise ValueError('Invalid method argument for finding bin systems.')
             n += 1
        if N \leq n:
             raise RuntimeError('Could not find bin systems (hit step limit).')
54
     def psystem_prep(system, bins = 8, overlap = 0.1, sweeps = 1_000_000, method = 'w1', **kwargs):
         Es = system.energy_bins() # Intrinsic to the system
         Ebins = np.linspace(Es[0], Es[-1], bins + 1) # For parallel subsystems
         systems = find_bin_systems(system, Es, Ebins, sweeps, method)
        binEs = [(lambda E0, Ef: Es[(E0 \leq Es) & (Es \leq Ef)])(*sim.extend_bin(Ebins, i, overlap))
                  for i in range(len(Ebins) - 1)]
         return zip(systems, binEs)
     def run(params, **kwargs):
         return sim.run(params, simulation, system_prep, psystem_prep, wrap_results, **kwargs)
     def join_results(results, *args, **kwargs):
         return sim.join_results(*zip(*[(r['Es'][:-1], r['S']) for r in results]), *args, **kwargs)
     24.4 Thermal calculations on images
     from numba import njit
     from numba.experimental import jitclass
     from numba import int64
    integer = int64
     import numpy as np
     from scipy import interpolate, special
    import os
    import tempfile
     import h5py, hickle
    import pprint
     import sys
     if 'src' not in sys.path: sys.path.append('src')
     import simulation as sim
    import wanglandau as wl
```

24.4.1 Parallel Simulation

```
M = 2**5 - 1
Moff = 0
I0 = Moff * np.ones(N, dtype=int)
system_params = {
    'StatisticalImage': {
        'I0': I0,
        'I': I0.copy(),
        'M': M
   }
}
```

```
1 # L = 16
   # system_params = {
       'IsingModel': {
          'spins': np.ones((L, L), dtype=int)
   #
6
   # }
   params = {
      'system': system_params,
      'simulation': {
         'max_sweeps': 10_000_000,
         'flat_sweeps': 10_000,
         'eps': 1e-9,
         'logf0': 1,
         'flatness': 0.1
      'parallel': {
         'bins': 2,
11
         'overlap': 0.25,
         'sweeps': 1_000_000
13
      },
14
      'save': {
         'prefix': 'simulation-',
16
         'dir': 'data'
      }
18
   }
19
   params.pop('parallel', None) # Single run
   wlresults = wl.run(params, log=True)
   Run parameters
   -----
   'M': 31}},
     'simulation': {'max_sweeps': 10000000,
                  'flat_sweeps': 10000,
                  'eps': 1e-09,
                  'logf0': 1,
                  'flatness': 0.1},
     'save': {'prefix': 'simulation-', 'dir': 'data'},
     'log': True}
   Running ...
   Wang-Landau START
   fiter
           steps
                      max steps
                      -----
        1120000
                   97044906
   1
   2
        480000
                   124608126
   3
        800000
                   141199505
   4
        800000
                   150306090
   5
        1280000
                   155077318
```

```
1600000
6
                  157519430
7
     2080000
                  158754871
8
     3360000
                  159376220
9
     3360000
                  159687805
10
     4320000
                  159843827
     5280000
                  159921895
11
12
     10400000
                  159960943
     19680000
13
                  159980470
14
     17120000
                  159990235
15
     28640000
                  159995118
     17440000
                  159997559
16
17
     98880000
                  159998780
     50240000
                  159999390
18
19
     35840000
                  159999695
20
     159999848
                  159999848
21
     36320000
                  159999924
22
     88960000
                  159999962
23
     63680000
                  159999981
24
     38880000
                  159999991
25
     30880000
                  159999996
26
     125920000
                  159999998
27
     90560000
                  159999999
28
     68800000
                  160000000
29
     19200000
                  160000000
30
     26720000
                  160000000
     57920000
                  160000000
Done: 1110559848 total MC iterations; not converged.
... done in 122 seconds.
Writing results ... done: data/simulation-v7qs5a48.h5
wlEs, S, \DeltaS = wl.join_results(wlresults['results'])
24.4.2 Results
import matplotlib.pyplot as plt
N, M = len(system_params['StatisticalImage']['I0']), system_params['StatisticalImage']['M']
for i, r in enumerate(wlresults['results']):
   plt.plot(r['Es'][:-1], r['S'] + ΔS[i])
```



Fit a spline to interpolate and optionally clean up noise, giving WL g's up to a normalization constant.

```
gspl = interpolate.splrep(w1Es, S, s=0*np.sqrt(2))
wlgs = np.exp(interpolate.splev(w1Es, gspl) - min(S))
```

24.4.3 Exact solution

We only compute to halfway since g is symmetric and the other half's large numbers cause numerical instability.

```
def reflect(a, center=True):
    if center:
        return np.hstack([a[:-1], a[-1], a[-2::-1]])
    else:
        return np.hstack([a, a[::-1]])
```

The exact density of states for uniform values. This covers the all gray and all black/white cases. Everything else (normal images) are somewhere between. The gray is a slight approximation: the ground level is not degenerate, but we say it has degeneracy 2 like all the other sites. For the numbers of sites and values we are using, this is insignificant.

```
def gray_g(E, N, M, exact=True):
    return 2 * bw_g(E, N, M, exact=exact)
def exact_gray_gs(N, M):
    Es = np.arange(N*M + 1)
    gs = np.vectorize(gray_g)(np.arange(1 + N*M // 2), N, M, exact=False)
    return Es, reflect(gs, len(Es) % 2 = 1)
```

Expected results for black/white and gray.

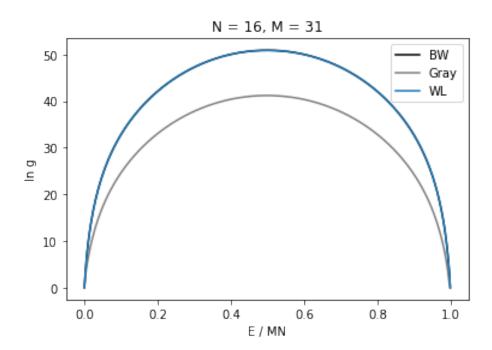
```
bw_Es, bw_gs = exact_bw_gs(N=N, M=M)
gray_Es, gray_gs = exact_gray_gs(N=N, M=-1 + (M + 1) // 2)
```

Choose what to compare to.

```
Es, gs = bw_Es, bw_gs
```

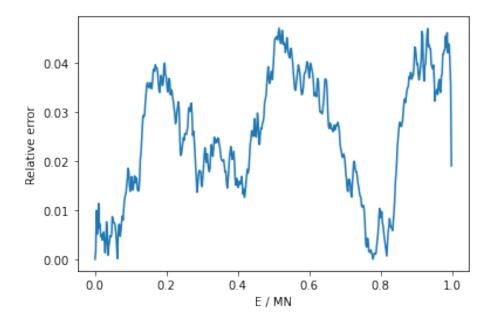
Presumably all of the densities of states for different images fall in the region between the all-gray and all-black/white curves.

```
plt.plot(bw_Es / len(bw_Es), np.log(bw_gs), 'black', label='BW')
plt.plot(gray_Es / len(gray_Es), np.log(gray_gs), 'gray', label='Gray')
plt.plot(wlEs / len(wlEs), S - min(S), label='WL')
plt.xlabel('E / MN')
plt.ylabel('In g')
plt.title('N = {}, M = {}'.format(N, M))
plt.legend();
```



```
plt.plot(wlEs / len(wlEs), np.abs(wlgs - bw_gs) / bw_gs)
plt.ylabel('Relative error')
```

```
# plt.plot(wlEs / len(wlEs), S - np.log(bw_gs) - min(S))
# plt.ylabel('Residuals')
plt.xlabel('E / MN');
```



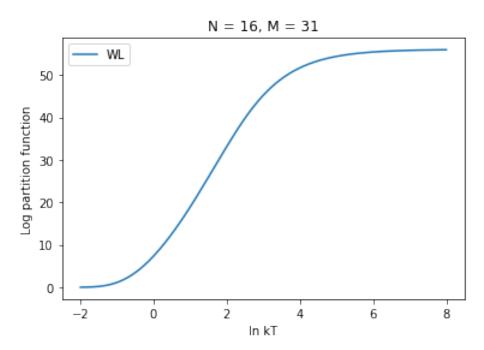
print('End of job.')

End of job.

24.5 Calculating canonical ensemble averages

```
import numpy as np
      import matplotlib.pyplot as plt
      import os
      import h5py, hickle
      import sys
      if 'src' not in sys.path: sys.path.append('src')
      import wanglandau as wl
      class CanonicalEnsemble:
           def __init__(self, Es, lngs, name, \lambda = None):
                self.Es = Es
                self.lngs = lngs
                self.name = name
                \# Choose to scale the exponent of Z to be a convenient size.
                # This can be improved if needed by taking into account typical \beta*Es.
                \texttt{self.} \lambda \ \texttt{=} \ \texttt{max(lngs)} \ \textbf{if} \ \lambda \ \textbf{is} \ \textbf{None else} \ \lambda
           def Z\lambda(self, \beta):
                return np.sum(np.exp(-(\beta * self.Es - self.lngs + self.\lambda)))
           def Z(self, \beta):
11
                return np.exp(self.\lambda) * self.Z\lambda(\beta)
```

```
def average(self, f, \beta):
13
                return np.sum(f(self) * self.gs * np.exp(-\beta * self.Es)) / self.Z(\beta)
14
              return np.sum(f(self) * np.exp(-(\beta * self.Es - self.lngs + self.\lambda))) / self.Z\lambda(\beta)
15
16
             return self.average(lambda ens: ens.Es, β)
         def energy2(self, β):
18
             return self.average(lambda ens: ens.Es**2, β)
         def heat_capacity(self, β):
              return self.energy2(\beta) - self.energy(\beta)**2
         def free_energy(self, \beta):
              return -np.log(self.Z(\beta)) / \beta
23
         def entropy(self, \beta):
              return \beta * self.energy(\beta) + np.log(self.Z(\beta))
     with h5py.File('data/simulation-13t1t_sn.h5', 'r') as f:
         h = hickle.load(f)
         results = h['results']
         params = h['parameters']
     N, M = len(params['system']['StatisticalImage']['IO']), params['system']['StatisticalImage']['M']
     wlEs, S, \DeltaS = wl.join_results(results)
     \beta s = [np.exp(k)  for k in np.linspace(-8, 2, 500)]
     wlens = CanonicalEnsemble(wlEs, S - min(S), 'WL') # Wang-Landau results
# xens = CanonicalEnsemble(Es, gs, 'Exact') # Exact
    # ensembles = [wlens, xens]
     ensembles = [wlens]
          Partition function
     for ens in ensembles:
         plt.plot(-np.log(\betas), np.log(np.vectorize(ens.Z)(\betas)), label=ens.name)
     plt.xlabel("ln kT")
     plt.ylabel("Log partition function")
     plt.title('N = {}, M = {}'.format(N, M))
     plt.legend();
```



Helmholtz free energy

```
for ens in ensembles:

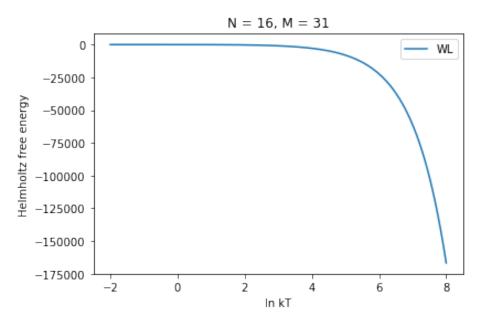
plt.plot(-np.log(βs), np.vectorize(ens.free_energy)(βs), label=ens.name)

plt.xlabel("ln kT")

plt.ylabel("Helmholtz free energy")

plt.title('N = {}, M = {}'.format(N, M))

plt.legend();
```



Heat capacity

```
for ens in ensembles:

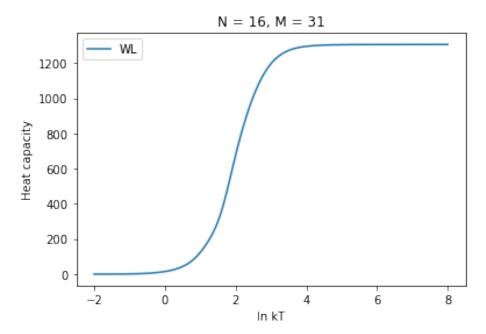
plt.plot(-np.log(βs), np.vectorize(ens.heat_capacity)(βs), label=ens.name)

plt.xlabel("ln kT")

plt.ylabel("Heat capacity")

plt.title('N = {}, M = {}'.format(N, M))

plt.legend();
```



Entropy

```
for ens in ensembles:
    plt.plot(-np.log(βs), np.vectorize(ens.entropy)(βs), label=ens.name)
    plt.xlabel("ln kT")
    plt.ylabel("Canonical entropy")
    plt.title('N = {}, M = {}'.format(N, M))
    plt.legend();
```

