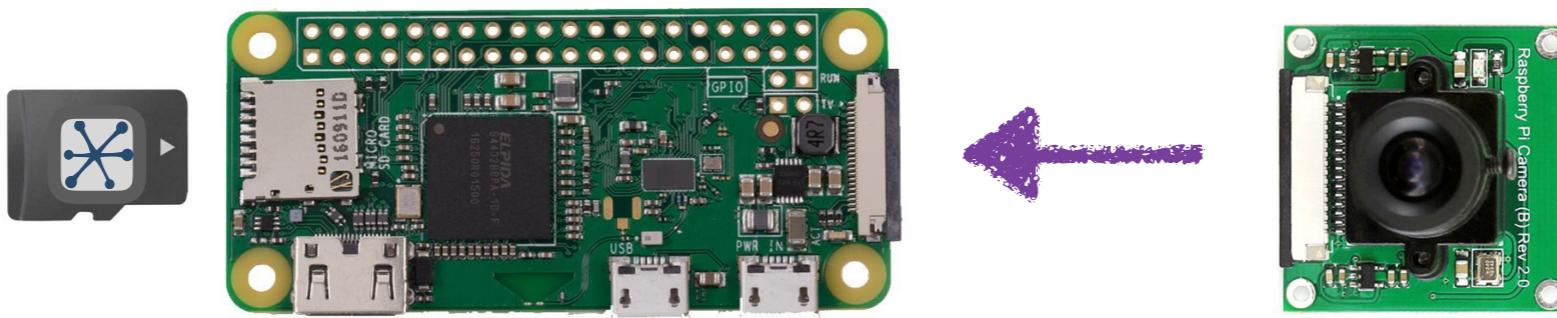


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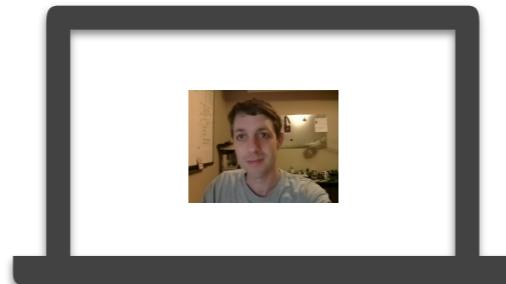


Nerves Training Part 6: Streaming video

Goal



USB w/ virtual serial port
and virtual Ethernet



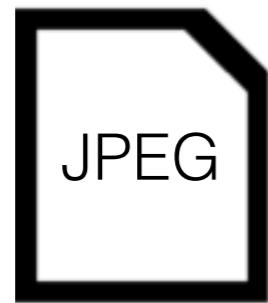
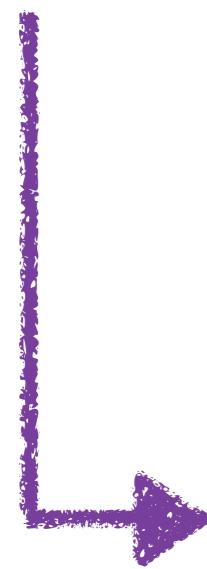
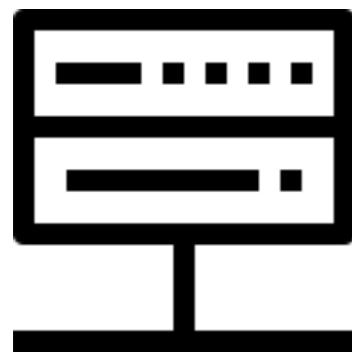
Streaming video

- Lots of options and tradeoffs
- High latency protocols
 - Movies and live “TV” content (i.e., Netflix)
 - Can support CDNs for distribution
 - Apple HLS, Microsoft Smooth Streaming, Adobe HDS
- Low latency protocols
 - Video conferencing and webcam streaming
 - Usually optimized for delivery to a small number of viewers

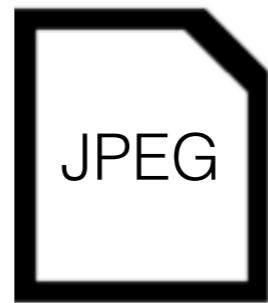
Low latency streaming

- Video encoding
 - H.264 - almost ubiquitous now
 - Motion JPEG - still around
- Transport
 - RTP - Real-time Transport Protocol (UDP)
 - WebRTC - stream to browsers
 - HTTP

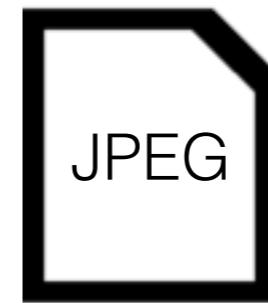
MJPEG over HTTP



-----boundary



-----boundary



-----boundary



```
<html>  
  <head>  
    <title>Video!</title>  
  </head>  
  
  <body>  
      
  </body>  
</html>
```

MJPEG over HTTP

- Pros
 - Not much code
 - It's just JPEGs
- Cons
 - High bandwidth for low resolution
 - No timing information
 - Head of line blocking

Attach the camera

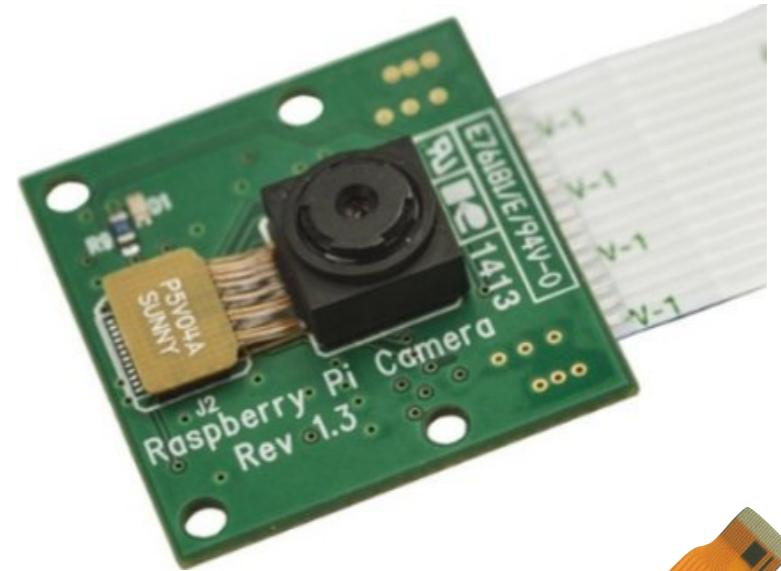
- Raspberry Pi Camera V2
- Raspberry Pi Zero to camera cable
- Two 2-56 3/8" screws
- Two 2-56 hex nuts



www.pololu.com

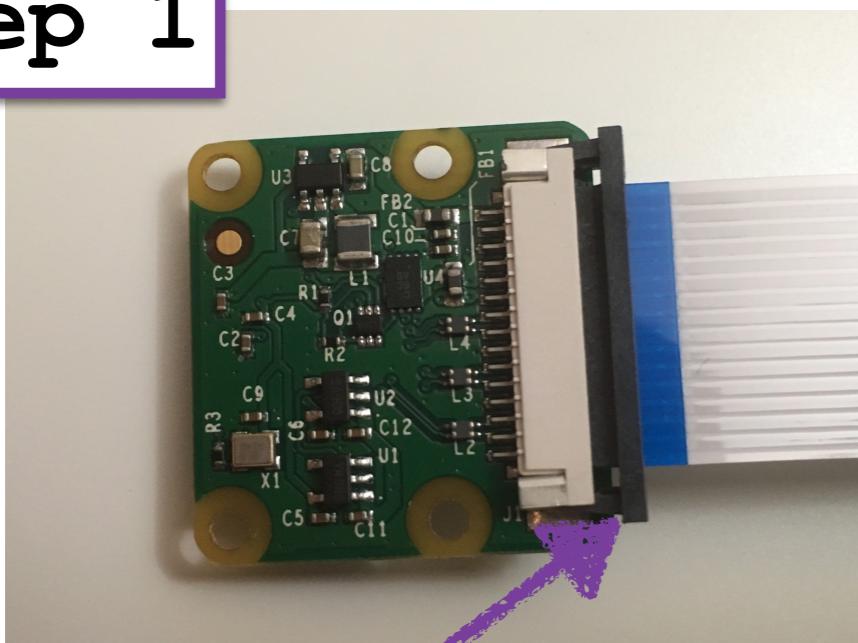


www.pololu.com

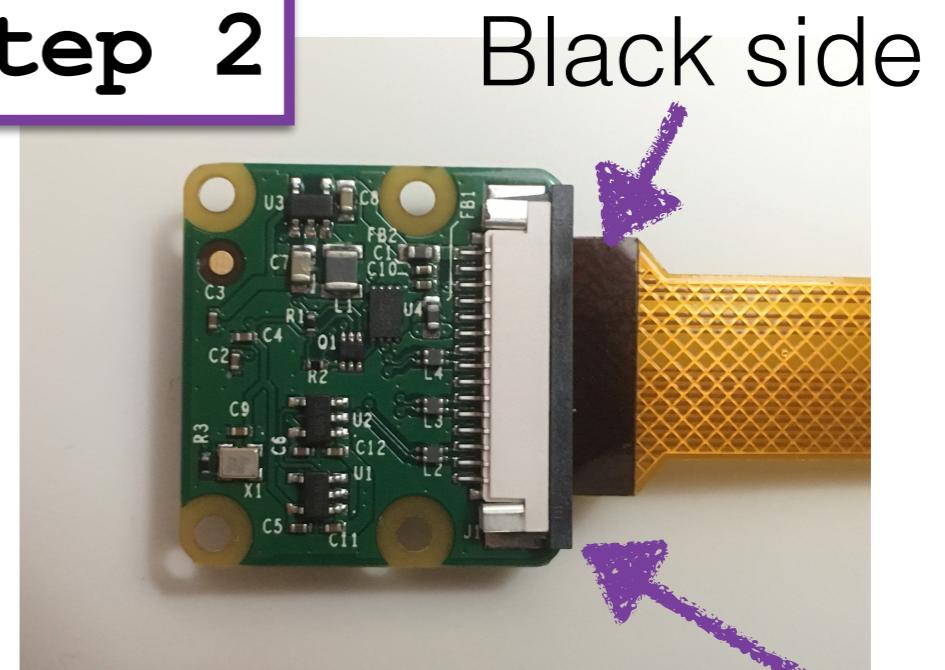


Attach the camera

Step 1

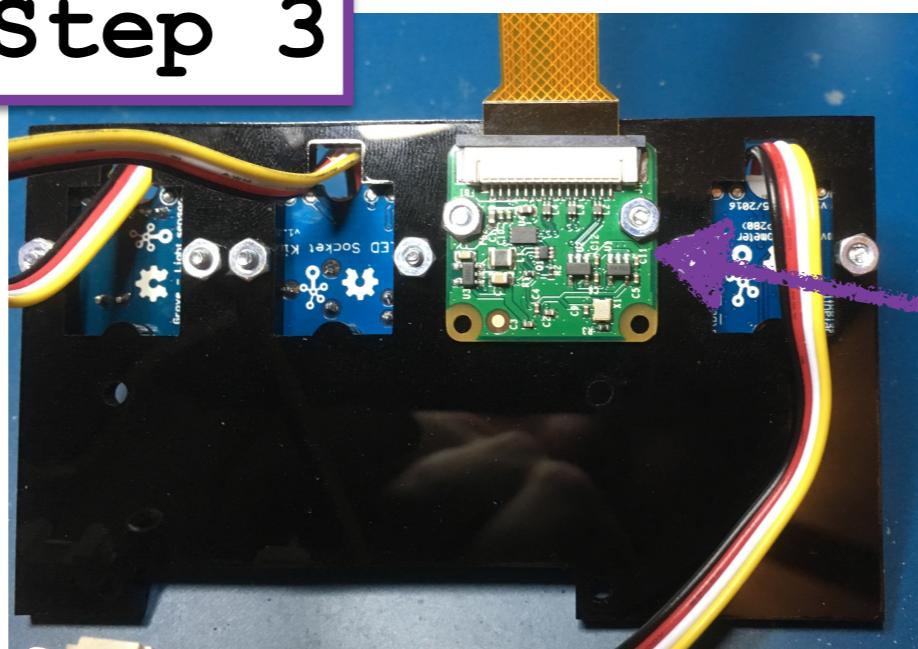


Step 2



Loosen connector
and remove cable

Step 3

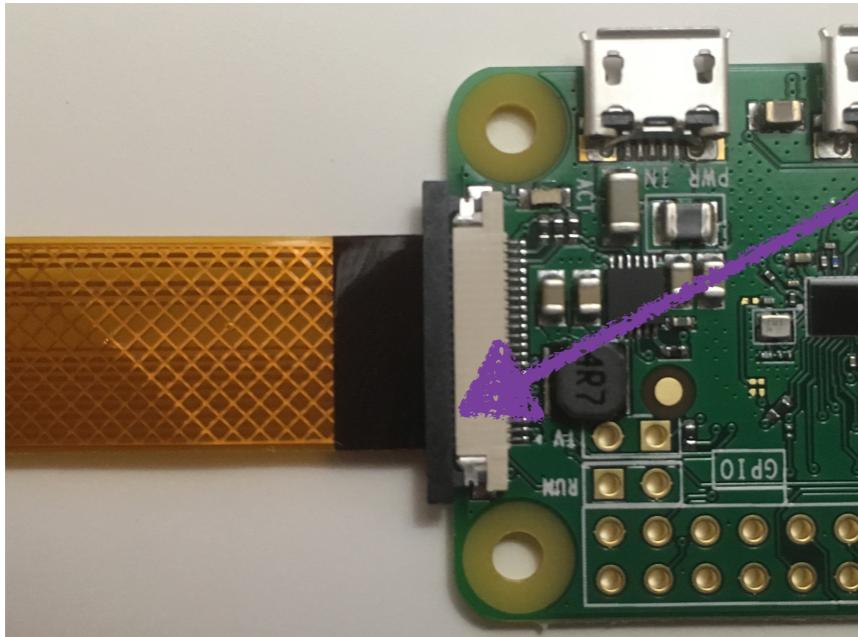


Insert snuggly and
close connector

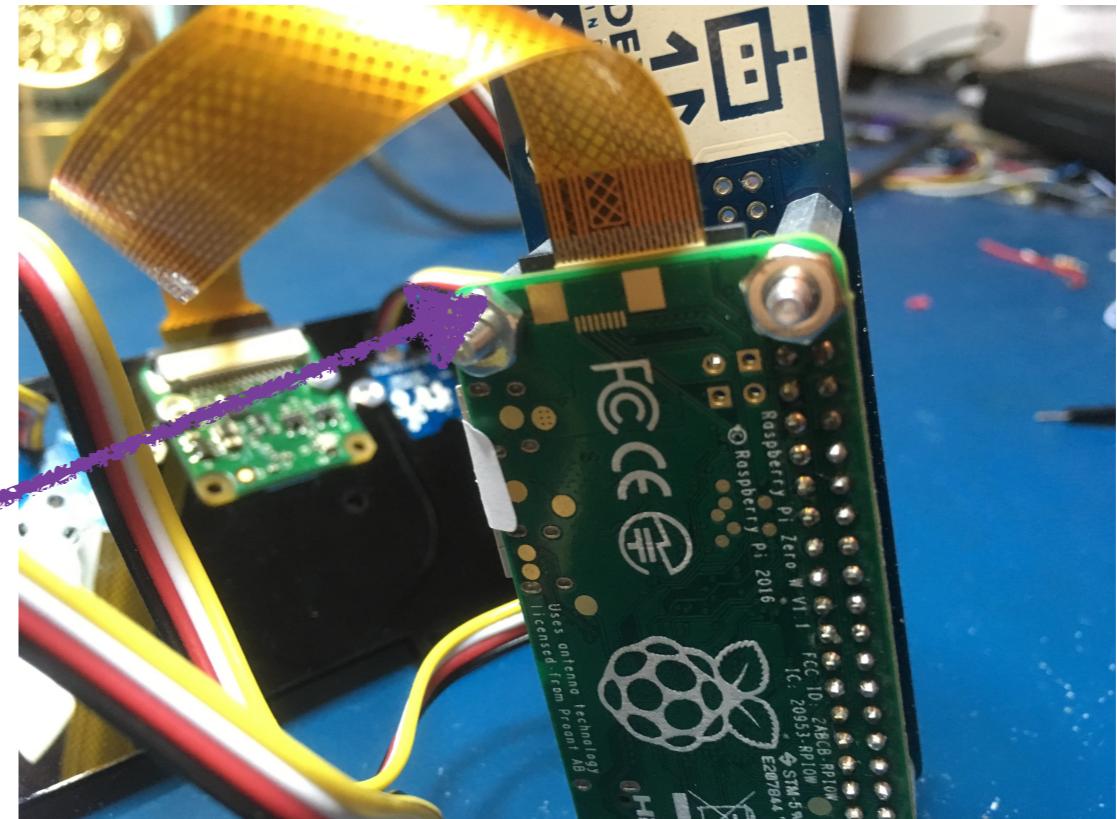
Carefully fasten
to front plate with
2-56 screws

Connect to the RPi Zero W

Remove the LED (Port D3) and Barometer (I2C Port) connectors



Gently loosen black plastic piece and insert ribbon cable



Close connector so that ribbon cable is locked

Attach the faceplate to the GrovePi Zero/RPi Zero W

- Four 4-40 screws

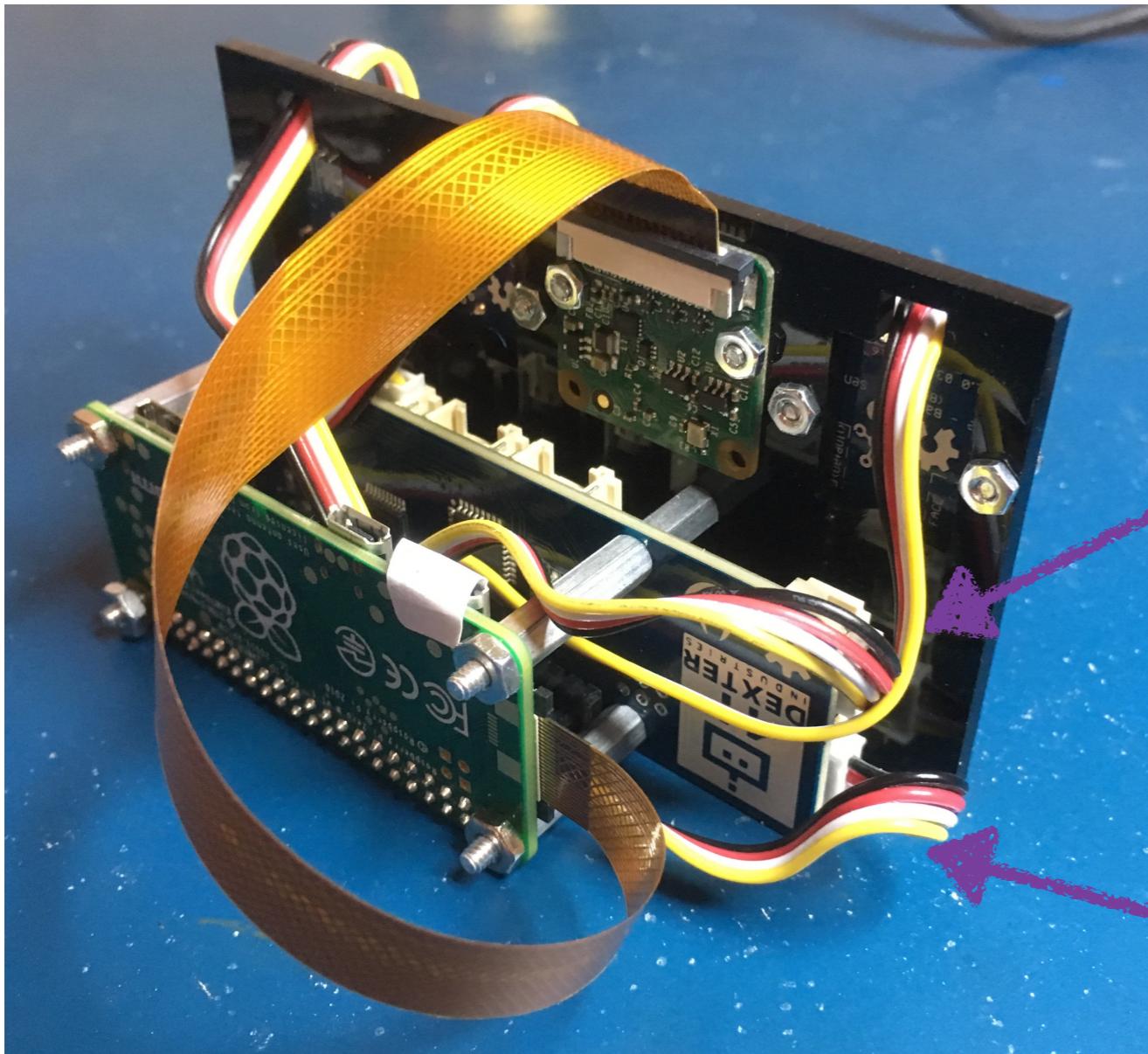


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Attach the faceplate



Reconnect wires and tuck them between GrovePi



LED goes to Port
D3 (top one)

Barometer goes to the I2C
Port (bottom one)

Create a new nerves_init_gadget project

```
$ cd <workspace>
$ mix nerves.new nerves_cam
$ cd nerves_cam
```

*add nerves_init_gadget to mix.exs and config.exs
copy ssh key config to config/config.exs*

Skip typing

```
$ git clone \
https://bitbucket.org/fhunleth/nervestraining-nerves\_cam.git \
nerves_cam
git checkout step1
```

Add picam and plug to mix.exs

```
def deps(target) do
  [ system(target),
    {:nerves_runtime, "~> 0.3.0"},
    {:bootloader, "~> 0.1"},
    {:nerves_init_gadget, github: "funkle/nerves_init_gadget", branch: "master"},
    {:picam, "~> 0.1"},
    {:cowboy, "~> 1.0.0"},
    {:plug, "~> 1.0"} ]
end
```

Skip typing

```
$ git clone \
https://bitbucket.org/funkle/nerves-training-nerves_cam.git \
nerves_cam
git checkout step2
```

lib/nerves_cam/application.ex

```
# Define workers and child supervisors to be supervised
children = [
  worker(Picam.Camera, []),
  Plug.Adapters.Cowboy.child_spec(:http, NervesCam.Router, [], [port: 80]),
]
```

Skip typing
\$ git checkout step2

lib/nerves_cam/router.ex

```
defmodule NervesCam.Router do
  use Plug.Router

  plug :match
  plug :dispatch

  get "/" do
    markup = """
    <html>
    <head><title>Picam Video Stream</title></head>
    <body>
      Coming soon!
    </body>
    </html>
    """
    conn
    |> put_resp_header("Content-Type", "text/html")
    |> send_resp(200, markup)
  end
end
```

Skip typing

\$ git checkout step2

Try it out

```
$ mix firmware  
  
$ mix firmware.push nerves.local  
-or-  
$ ./upload
```

Open http://nerves.local/ up in your browser

Are we going to take
pictures yet?

lib/nerves_cam/router.ex

```
get "/" do
  markup = """
<html>
<head><title>Picam Video Stream</title></head>
<body>
  
</body>
</html>
"""

  conn
  |> put_resp_header("Content-Type", "text/html")
  |> send_resp(200, markup)
end

forward "/video.mjpg", to: NervesCam.Streamer
```

```
$ git checkout step3
```

lib/nerves_cam/streamer.ex

```
defmodule NervesCam.Streamer do
  import Plug.Conn
  @behaviour Plug

  def init(opts), do: opts
  def call(conn, _opts) do
    conn
    |> put_resp_header("Age", "0")
    |> put_resp_header("Cache-Control", "no-cache, private")
    |> put_resp_header("Pragma", "no-cache")
    |> send_picture
  end

  defp send_picture(conn) do
    jpg = Picam.next_frame
    conn
    |> put_resp_header("Content-Type", "image/jpeg")
    |> send_resp(200, jpg)
  end
end
```

```
$ git checkout step3
```

Try it out

```
$ export MIX_TARGET=rpi0  
$ mix firmware
```

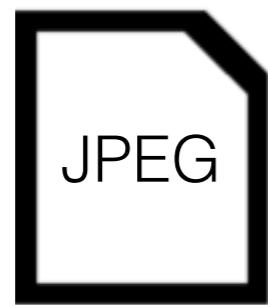
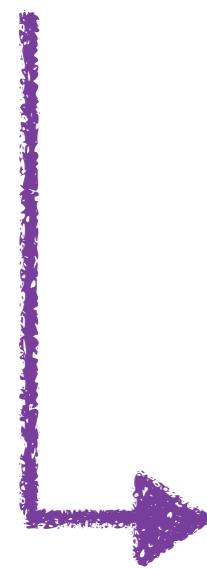
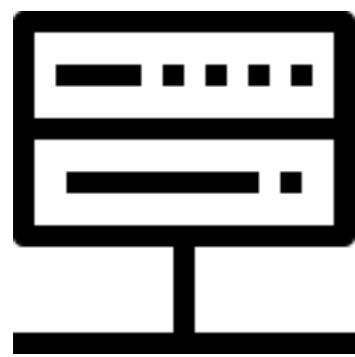
Connect the Raspberry Pi Zero and ping it

```
$ mix firmware.push nerves.local
```

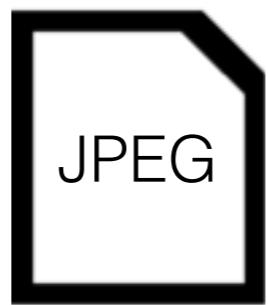
Wait for the Raspberry Pi to reboot

Open a browser and try loading <http://nerves.local/>

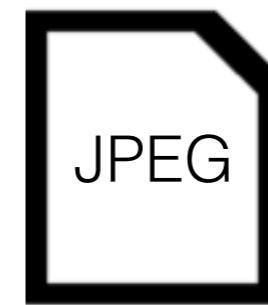
MJPEG over HTTP



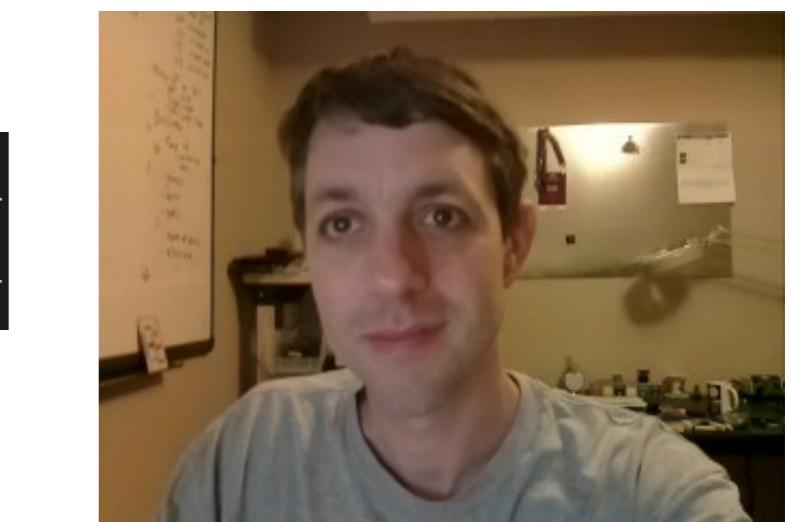
-----boundary



-----boundary



-----boundary



```
<html>  
  <head>  
    <title>Video!</title>  
  </head>  
  
  <body>  
      
  </body>  
</html>
```

lib/nerves_cam/streamer.ex

```
defmodule NervesCam.Streamer do
  import Plug.Conn

  @behaviour Plug
  @boundary "w58EW1cEpjzydSCq"

  def init(opts), do: opts

  def call(conn, _opts) do
    conn
    |> put_resp_header("Age", "0")
    |> put_resp_header("Cache-Control", "no-cache, private")
    |> put_resp_header("Pragma", "no-cache")
    |> put_resp_header("Content-Type", "multipart/x-mixed-replace; boundary=#{@boundary}")
    |> send_chunked(200)
    |> send_pictures
  end

  defp send_pictures(conn) do
    send_picture(conn)
    send_pictures(conn)
  end

  defp send_picture(conn) do
    jpg = Picam.next_frame()
    size = byte_size(jpg)
    header = "-----#{@boundary}\r\nContent-Type: image/jpeg\r\nContent-length: #{size}\r\n\r\n"
    footer = "\r\n"
    with {:ok, conn} <- chunk(conn, header),
         {:ok, conn} <- chunk(conn, jpg),
         {:ok, conn} <- chunk(conn, footer),
         do: conn
    end
  end
end
```

```
$ git checkout step4
```

Try it out

```
$ export MIX_TARGET=rpi0  
$ mix firmware
```

Connect the Raspberry Pi Zero and ping it
\$ mix firmware.push nerves.local

Wait for the Raspberry Pi to reboot
Open a browser and try loading <http://nerves.local/>

Things to try

Connect over the serial port using picocom or screen

```
iex> Picam.set_img_effect(:sketch)
:ok
iex> h Picam.set_img_effect
...
iex> Picam.set_col_effect({128,128})
:ok
```

Check out the docs at
<https://hex.pm/packages/picam>

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Nerves Training Part 6: Streaming video