

Homework #4(Week 5) Vector Spaces II – MSCA 32010

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$$1. \quad U_0 = \begin{pmatrix} 1 & 2 & 3 & 0 \\ 0 & 0 & 4 & 0 \end{pmatrix} \quad R_0 = \begin{pmatrix} 1 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

$$R_0 * X = 0 \quad \begin{pmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} * \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \text{so} \quad \begin{cases} x_1 + 2x_2 = 0 \\ x_3 = 0 \end{cases} \quad \text{Then } x = \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix}$$

Check it by $U * x = 0$

$$\begin{pmatrix} 1 & 2 & 3 \\ 0 & 0 & 4 \end{pmatrix} * \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$U_c = \begin{pmatrix} 1 & 2 & 3 & 5 \\ 0 & 0 & 4 & 8 \end{pmatrix} \quad R_d = \begin{pmatrix} 1 & 2 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

$$R_d * x = d \quad \begin{pmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} * \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \end{pmatrix} \quad \text{so} \quad \begin{cases} x_1 + 2x_2 = -1 \\ x_3 = 2 \end{cases} \quad \text{Then } x = \begin{pmatrix} -3 \\ 1 \\ 2 \end{pmatrix}$$

Check it by $U * x = c$

$$\begin{pmatrix} 1 & 2 & 3 \\ 0 & 0 & 4 \end{pmatrix} * \begin{pmatrix} -3 \\ 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 5 \\ 8 \end{pmatrix}$$

2. Yes it is true. If $Ax = b = Cx$, then $Ax = Cx$ and we can say that $A = C$, for a given x

3. There can be 3 independent vectors

$V_2 = v_1 + v_4$ and is not independent

$V_3 = v_1 + v_4 + v_6$ and is not independent

$V_5 = v_4 + v_6$ and is not independent

That leaves us with 3 independent vectors, v_1 , v_4 and v_6 .

You can also put the 6 vectors in a matrix and use Gauss Jordan elimination, which gives us 3 pivots, and 3 free variables, so we have 3 independent vectors.

4a. Basis for the plane $x - 2y + 3z = 0$, we can use 2 special solutions to find a basis for this plane. Using $(0, 1)$ and $(1, 0)$ for y and z , we get

$$s_1 = \begin{pmatrix} 3 \\ 0 \\ 1 \end{pmatrix} \quad s_2 = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} \quad \text{These two vectors form a basis for the plane.}$$

4b. The intersection of the plane and the xy plane is a line. If we set $z=0$, $x-2y = 0 \rightarrow y = x/2$

Then this entire line, which passes through the origin forms the basis of the intersection. If we set $x = 2$, a special solution would be

$$s_1 = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}$$

4c. If 2 vectors are perpendicular, then their dot product equals 0. Since the original equation, is a linear combination of 2 vectors (x, y, z) and $(1, -2, 3)$ that equals 0. Then we can say that these two vectors are perpendicular. The Span of $\{1, -2, 3\}$ are all the vectors perpendicular to the plane. And the vector $(1, -2, 3)$ forms a basis for those vectors.