

Recall: • We introduced  $X \sim \text{Exp}(\lambda)$  and basic properties ( $E(X)$ , pdf, cdf)

•  $\text{Exp}(\lambda)$  is the only real continuous memoryless r.v.

$$(P(X > t+s | X > t) = P(X > s))$$

→ This has many applications when we want to estimate some probabilities (cf. exs)

• Additional properties: for  $X_i$  independent  $\text{Exp}(\lambda_i)$

-  $\text{Min}(X_i) \sim \text{Exp}(\sum \lambda_i)$  ✓

-  $P(X_1 < X_2)$  ? → today

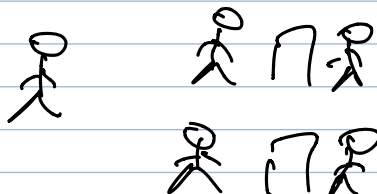
-  $\sum X_i \sim ?$  → today



Rank: • What happens for the memoryless property when the r.v. is discrete i.e.  $\mathbb{N}$

(exercise) → The Geometric distribution is memoryless.

$$(P(X = k) = (1-p)^{k-1} p, 0 < p < 1)$$

• Example:  3 customers

Q: What is the expected time until all 3 customers have left? (2)

- We assume that the service time at both counters is  $\text{Exp}(\lambda)$

• Time until the 1<sup>st</sup> customer leaves?

$$T \sim \min(\text{Exp}(\lambda), \text{Exp}(\lambda)) \sim \text{Exp}(2\lambda)$$

$$\Rightarrow E(T) = \frac{1}{2\lambda}$$

• By the memoryless property, the clock effectively restarts for the remaining customers, so the next customer to leave will do it with an average time =  $\frac{1}{2\lambda}$

• The clock restarts, and the last customer leaves with time  $\sim \text{Exp}(\lambda)$  so in average after  $\frac{1}{\lambda}$

$$\Rightarrow \text{Total mean time} = \frac{1}{2\lambda} + \frac{1}{2\lambda} + \frac{1}{\lambda} = \boxed{\frac{2}{\lambda}}$$

For some similar exercise  $\rightarrow$  HW, pbn 4.

- Probability that  $X_1 < X_2$  when  $X_i \sim \text{Exp}(\lambda_i)$  <sup>(3)</sup>  
(and independent)

Prop: If  $X_1$  and  $X_2$  are independent  $\text{Exp}(\lambda_i)$  r.v.'s  
then  $P(X_1 < X_2) = \frac{\lambda_1}{\lambda_1 + \lambda_2}$

Proof:  $P(X_1 < X_2) = \iint_{x_1 < x_2} f_{X_1}(x_1) f_{X_2}(x_2) dx_1 dx_2$

$$= \int_0^{+\infty} dx_2 f_{X_2}(x_2) \int_0^{x_2} f_{X_1}(x_1) dx_1$$

$$= (\dots) = \frac{\lambda_1}{\lambda_1 + \lambda_2} \quad \square$$

$x_1$  (exercise)

- Sum of independent  $\text{Exp}(\lambda)$

RemK: If  $X$  and  $Y$  are independent continuous real r.v.'s, then the pdf of  $Z = X + Y$  is

$$f_Z(z) = \int_{-\infty}^{+\infty} f_X(z-y) f_Y(y) dy$$

$$= f_X * f_Y(z)$$

↑  
"convolution product of  $f_X$  and  $f_Y$ "

Exercise: If  $X_1 \sim \text{Exp}(\lambda_1)$  and  $X_2 \sim \text{Exp}(\lambda_2)$  and  $\lambda_1 \neq \lambda_2$ , then ④

$$(f_{X_1} * f_{X_2})(t) = \lambda_1 \lambda_2 e^{-\lambda_1 t} \int_0^t e^{-(\lambda_2 - \lambda_1)s} ds$$

(true for all  $\lambda_1, \lambda_2$ )

and for  $(\lambda_1 \neq \lambda_2)$

$$f_{X_1 + X_2}(t) = \frac{\lambda_1}{\lambda_1 - \lambda_2} \lambda_2 e^{-\lambda_2 t} + \frac{\lambda_2 \lambda_1}{\lambda_2 - \lambda_1} e^{-\lambda_1 t}$$

Remark: This formula generalizes to  $n$  distinct  $\text{Exp}(\lambda_i)$   
(see Ross S. 2.4)

What happens when  $\lambda_1 = \lambda_2 = \dots := \lambda$ ?

$$f_{X_1 + X_2}(t) = (f_{X_1} * f_{X_2})(t) = \lambda^2 e^{-\lambda t} \int_0^t e^{-\cancel{(\lambda - \lambda)}s} ds$$

$$\text{so } \underline{f_{X_1 + X_2}(t) = \lambda^2 e^{-\lambda t} \cdot t} \quad (t \geq 0)$$

By induction, one can show

$$f_{X_1 + \dots + X_n} = \lambda e^{-\lambda t} \frac{(\lambda t)^{n-1}}{(n-1)!}$$

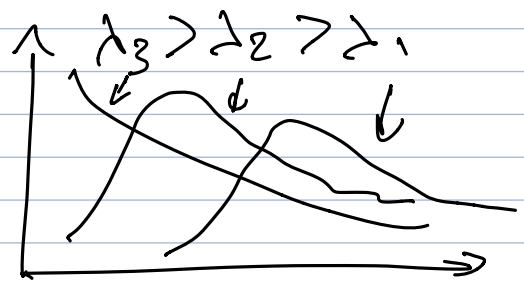
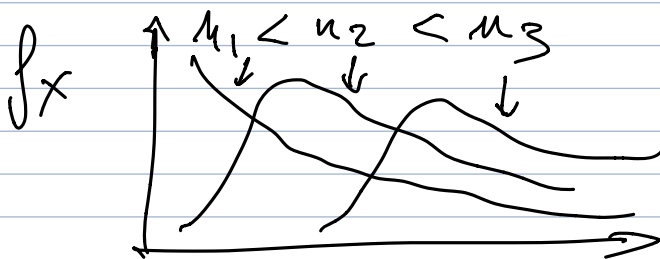
→ We recognize here the "Gamma" distribution  
 $\Gamma(n, \lambda)$

Prop: If  $X_1, \dots, X_n$  are independent  $\text{Exp}(\lambda)$  r.v.'s, then  $\sum_{i=1}^n X_i \sim \Gamma(n, \lambda)$ ,  
 i.e. the pdf of the sum is  $f(t) = \lambda e^{-\lambda t} \frac{(\lambda t)^{n-1}}{(n-1)!}$  (5)

Remark: Mean and var of  $\Gamma(n, \lambda)$

$$\begin{aligned}
 - E(X) &= \sum_{i=1}^n E(X_i) = \frac{n}{\lambda} \\
 - \text{Var}(X) &= \sum_{i=1}^n \text{Var}(X_i) = \frac{n}{\lambda^2} \quad \text{by independence}
 \end{aligned}$$

$\rightarrow$  When  $n \uparrow$  mean and variance  $\uparrow$   
 $\lambda \uparrow$  mean and variance  $\rightarrow$



Upon considering such a sum of i.i.d  $\text{Exp}(\lambda)$  r.v.'s,  
we'll have a first description of the Poisson process