Deep Learning Assignment 3

Anonymous Author(s)

Affiliation Address email

1 1 General Questions

2 (a) Say if the first module is:

$$max(W_1X) \tag{1}$$

- where the W input layer maybe doing summation and summation just like matrix mutiplication does
- 4 WX, and the max function is a non-linear active function modifying the value like a neuron does
- 5 before entering the next module:

$$W_2(max(W_2X)) \tag{2}$$

6 If now we don't have the active function then the formula will looks like:

$$W_2(W_1X) \to \bar{W}X$$
 (3)

7 which eventually all W_i can become a single module \bar{W}

8 2 Softmax regression gradient calculation

9 Given

$$\hat{y} = \sigma(Wx + b)$$
, where $x \in \mathbb{R}^d$, $W \in \mathbb{R}^{k \times d}$, $b \in \mathbb{R}^k$ (4)

where d is the input dimension, k is the number of classes, σ is the softmax function:

$$\sigma(a)_i = \frac{exp(a_i)}{\sum_j exp(a_j)} \tag{5}$$

Which means a given input x will output y with probability of each class

12 **2.1 Derive** $\frac{\partial l}{\partial W_{ij}}$

13 If the given cross-entropy loss defined as followed:

$$l(y, \hat{y}) = -\sum_{i} y_i \log \hat{y_i} \tag{6}$$

As W_{ij} will affect the prediction of class i by multipling index j in x, therefore we can derive:

$$\frac{\partial l}{\partial W_{ij}} = \frac{\partial l}{\partial \hat{y}_i} \frac{\partial \hat{y}_i}{\partial W_{ij}} \tag{7}$$

15 where:

$$l(y, \hat{y}) = -\sum_{i} y_{i} \log \hat{y}_{i} = -(y_{i} \log \hat{y}_{1} + y_{2} \log \hat{y}_{2} + \dots + y_{i} \log \hat{y}_{i} + \dots)$$
 (8)

16 and therefore

$$\frac{\partial l}{\partial \hat{y}_i} = \frac{-y_i}{\hat{y}_i} \tag{9}$$

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And we can rewrite for only for \hat{y}_i :

$$\hat{y_i} = \frac{exp(a_i)}{\Sigma_j exp(a_j)} = \frac{exp(a_i)}{C + exp(a_i)}, \text{ where } C = \sum_{k \neq i} exp(a_k)$$
 (10)

Since

$$\frac{\partial exp(a_i)}{\partial W_{ij}} = W_{ij}exp(a_i) \tag{11}$$

Therefore

$$\frac{\partial \hat{y}_i}{\partial W_{ij}} = W_{ij}\hat{y}_i(1 - \hat{y}_i) \tag{12}$$

Finally, we will get the result of $\frac{\partial l}{\partial W_{i,i}}$:

$$\frac{\partial l}{\partial W_{ij}} = \frac{\partial l}{\partial \hat{y}_i} \frac{\partial \hat{y}_i}{\partial W_{ij}} = -X_j y_i (1 - \hat{y}_i) \tag{13}$$

2.2 What happen when $y_{c_1} = 1, \hat{y}_{c_2} = 1, c_1 \neq c_2$

- This means something like $y = [1, 0, 0]^T$ and $\hat{y} = [0, 0, 1]^T$, and the predict is far different from true lable. This will cause the log part in loss (3) become negative infinity. We may not need to worry this
- 23
- because before one of the class predicted close to 1 and everything else close to 0, it will generate a 24
- great positive loss the class that is miss-predicted trying to make the predict right to true label.

Chain rule 3 26

Variants of pooling

Convolution 28

- (a) As it is using 3x3 kernal along x and y axis of input, which is 5 and 5 respectively. The output of this layer will be $(5-3+1) \times (5-3+1)$ which is 3x3.
- (b) Assuming the kernel operation is point-point multiplication and summation, then the output of this layer is:

32 this layer is:
$$\begin{pmatrix}
109 & 92 & 72 \\
108 & 85 & 74 \\
110 & 74 & 79
\end{pmatrix}$$
34 (c)
$$\begin{pmatrix}
4 & 7 & 10 & 6 & 3 \\
9 & 17 & 25 & 16 & 8 \\
11 & 23 & 34 & 23 & 11 \\
7 & 16 & 24 & 17 & 8 \\
2 & 6 & 9 & 7 & 3
\end{pmatrix}$$

Optimization

Top-k error

t-SNE

Proximal gradient descent

(a) Since Proximal operator is defined as:

$$prox_{h,t}(x) = argmin_z \frac{1}{2} ||z - x||_2^2 + th(z)$$
 (14)

which the optimal condition is to have the gradient w.r.t z equal to 0:

$$0 \in z - x + t\partial h(z) \tag{15}$$

if function $h(z) = ||z||_1$ and $z_i \neq 0$, then:

$$\partial h(z) = sign(x) \tag{16}$$

And therefore the optimal solution z^* will be:

$$z^* = x - t \cdot sign(z^*) \tag{17}$$

Noted that if $z_i^* < 0$, then $x_i < -\lambda$, and if $z_i^* > 0$, then $x_i > \lambda$. This implies $|x_i| > \lambda$ and $sign(z_i^*) = sign(x_i)$, and we can rewrite formula to:

$$z_i^* = x_i - t \cdot sign(x_i) \tag{18}$$

Then if the solution $z_i^* = 0$, the subgradient of 11-norm is in the interval of [-1, 1], and we can write:

$$0 \in -x_i + t \cdot [-1, 1] \implies x_i \in [-t, t] \implies |x_i| \le t \tag{19}$$

Therefore the solution of Proximal operator will be:

$$z_i^* = \begin{cases} 0 & \text{if } |x_i| \le t \\ x_i - t \cdot sign(x_i) & \text{if } |x_i| > t \end{cases}$$
 (20)

which is

$$prox_{h,t}(x) = S_t(x) = (|x| - t)_+ \odot sign(x)$$
 (element-wise) (21)

- which is a soft-threshold fuction with t as threshold value 49
- (b) In the field of signal processing, the true signal usually will be blurred as followed:

$$Ax = b (22)$$

where A is the blur operation, b is the known observed blured-signal. The way to solve true signal x is called deblurring problem:

$$min_x\{F(x) \equiv \frac{1}{2}||b - Ax||_2^2 + \lambda||x||_1\}$$
(23)

- This is ISTA problem, and as we can see the first term is convex and differentiable, and the second
- term is convex and simple 11-norm function. Then the ISTA is become one example of proximal
- gradient descent