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受注番号: ORDER No.								
御注文主: CUSTOMER						YA:	SKAV	VA
御使用先: USER					,	株式会社 安川	電機	
SR100 Stand	ard Error Co	de List						
	(Controller	Type : ERM	IR-AS Se	eries)				
目次 CONTENTS								
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Revision Records

Drawing No.		Item	Povisod	Approved
HE1400563		SR100 Standard Error Code List	Revised by	Approved by
Date	Rev.	Revised contents	Dy	Бy
Aug.01.2012	0		-	-

[1] Introduction

This manual describes the error codes of the Yaskawa Transfer Manipulator. Use this manual with the following.

- · Teaching Pendant Instruction
- · Communication Specification

[2] Basic Specifications

- 1) Each error is categorized into 5 levels (Shown below). When an error occurred, the error code is displayed in 7-SEG LED (hereafter referred to as LED) and the process predetermined for each error level is executed.
- 2) When multiple errors occurred, the error that has the highest error level is displayed on LED display. When the errors have the same error level, follow the rule described below. In case the error level is higher than "serious error" defined in the table bellow, the older error is displayed. In case the error level is "warning", the newer error code is displayed.
- 3) Up to 128 errors are saved in error history which can read by the teaching pendant. The history can be viewed using the teaching pendant's "Error history reference command". If the controller power is turned off, the error history is cleared.
- 4) Up to 128 errors are saved in error history that can read by the host command. The history can be viewed using the host command "RERR command". If the controller power is turned off, the error history is cleared.
- 5) Servo control (motor driver) and hardware error information are monitored and detected in real time.
- 6) The error levels and the controller behavior of each error level are shown in the following table.

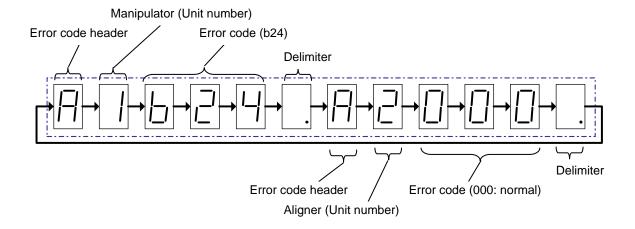
Fanou Louis	Severit	Behavior at error occurrence		F Ol	LED	D I		
Error Level	code	Servo power	ALAR M	WARN Signal	Error Clear	Indication	Remarks	
F : Fatal Error	5	Servo OFF	ON	-	Not available	Yes	Robot system is totally disabled.	
A2 : Serious Error 2	4	Servo OFF	ON	-	Not available	Yes	Manipulator is totally disabled.	
A1: Serious Error 1	3	Servo OFF	ON	-	Available	Yes	Manipulator is temporarily disabled	
W2 : Warning 2	2	-	-	ON	Available	Yes	Manipulator is able to run, however, commands cannot be	
W1: Warning 1	1	-	-	-	-	No	Except the above (Communication related error)	

Note) Depending of the root cause, error may be redetected after clearing it.

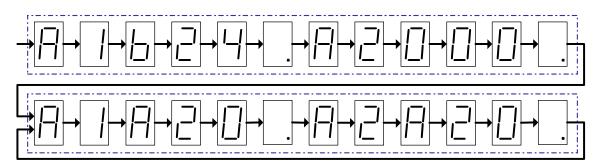
[3] 7-segment LED Indicators

Error codes that are displayed will begin with "A" displayed, then the unit number, followed by the error code. Finally, a "." is appended at the end. Each digit is displayed for 1 second.

Example 1) If Z-axis (Robot) + Direction software limit error (b24) occurs, the below information is repeatedly displayed.

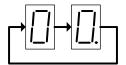


Example 2) If an emergency stop error (A20) occurs while example 1 is displayed, after displaying the contents of example 1 to the end, the contents of A20 will be repeatedly displayed.



Example 3) No error state

Display [0.](The dot blink every 1 second).



[4] Axis Number and Supported Axes for Servo Error Codes (100's to 500's)

The following table shows the axis number and supported axes for the servo error codes:

Unit No.	Unit	* Symbol for Servo Error Code (100's to 500's)				
Offic INO.	Offic	1st axis	2nd axis	3rd axis	4th axis	5th axis
1	Manipulator	Rotation	Extension	Hand 1	Hand 2	Z
2	pre-aligner	Rotation	-	-	-	-

Example) Momentary overload of extension axis: 271 Error

[5] Error Codes

Error	Level	Error Name	Description
code 000	_	Normal	·
020	W2	Secondary power off	Motion command failed due to servo power off.
020	W2	Secondary power on	Setting command failed due to servo power on.
040	W2	In TEACH Mode	Command was rejected because host command was sent when the
040	VVZ	III TEACH Mode	controller was in TEACH mode.
050	W2	Unit is in motion	Command was rejected because a unit is executing a motion command
			when host sent another motion command to the same unit.
051	W2	Unable to set pitch between	Host attempted to set pitch between slot when pitch generation method
052	W2	slots Unable to restart motion	was set to "automatic calculation mode". RESTART command was rejected because immediately after power on
032	VVZ	Onable to restart motion	or the error occur.
053	W2	Ready position move	Get/Put (or exchange) command was rejected because "move to ready
		incomplete	position" command had not been executed before that.
055	W2	Improper station type	Inaccessible station type is specified.
058	W2	Command not supported 1-1	Command was rejected because the command sent is not supported by
			specified unit.
059	W2	Invalid transfer point	"Motion between Transfer Points" command was rejected because an
054	14/0	Lin and marking failed	invalid point was specified.
05A	W2	Linear motion failed	Cannot move since manipulator arm is in the range (or the posture)
OEC	W2	Unable to reference wafer	where linear motion cannot be executed. Wafer alignment had not been executed.
05C	VV Z	alignment result	water alignment had not been executed.
05d	W2	Unable to perform arm	Arm calibration was rejected because the pre-aligner stage has not
osa	***	calibration	been recorded.
05E	W2	Unable to read mapping data	The mapping data reference command was rejected because the
002		Chable to road mapping data	mapping has not been executed ever.
05F	W2	Data Upload/Download in	Command is rejected because data upload/download command was in
		progress	progress.
061	W2	Unable to motion	Unable to home safely from current manipulator posture.
070	W2	Bottom slot position record	Command was rejected because the bottom slot position had not been
		incomplete	recorded.
071	W2	Top slot position record	Command was rejected because the top slot position had not been
		incomplete	recorded when pitch generation method was set to "automatic
			calculation mode".
088	W2	Position generating error 1	The transfer position (posture) calculated by the teaching position
000	MA	Position generating error 2	exceeded the motion limitation. The transfer position (posture) calculated by the teaching position
089	W2	Position generating error 2	exceeded the motion limitation.
08A	W2	Position generating error 3	The transfer position (posture) calculated by the teaching position
007	***	. comon gonorating onto o	exceeded the motion limitation.
08b	W2	Position generating error 4	The transfer position (posture) calculated by the teaching position
00.0		generaling energi	exceeded the motion limitation.
08C	W2	Position generating error 5	The transfer position (posture) calculated by the teaching position
			exceeded the motion limitation.
08d	W2	Position generating error 6	The transfer position (posture) calculated by the teaching position
			exceeded the motion limitation.
090	W2	Host parameter out of range	The parameter setting of the communication command from host is out
		All	of range.
0A0	W2	Alignment motion error	Alignment motion was not executed because ple-aligner is not ready to
050	14/0	Tooch position adjustment	run in put motion command with alignment angle.
0E0	W2	Teach position adjustment	The adjustment offset amount exceeded the limitation.
0F0	W1	offset amount limit error Voltage drop warning	Input voltage became too low.
UFU	VV I	vollage drop warriing	input voltage became too low.

[Error Code of Servo Axis]

	or Code of Servo Axis]				
Error	Level	Error Name	Description		
code			•		
*06		Amplifier Type Mismatch	Amplifier type does not match.		
*07		Encoder Type Mismatch	Encoder type does not match.		
*10	A1	Overflow Current	Overflow current has run.		
*30	A1	Regeneration Error Detected	The regenerative circuit error is detected.		
*40	A1	Excess Voltage (converter)	Converter voltage is abnormally high.		
*41	A1	Insufficient Voltage	Converter voltage is low.		
*45		Brake circuit error 1	The brake is locked.		
*46		Converter ready signal error	Error occurs in converter.		
*47		Input power error	Error occurs in input power.		
*48	A1	9	Error occurs in converter main circuit.		
*49	Λ.4	error	From acquire in amplifier		
		Amplifier ready signal error Excessive Speed	Error occurs in amplifier.		
*51			Motor speed is excessively high. A torque that exceeds largely the rated value is applied for several or		
*71	A1	Momentary Overload (Motor)			
*72	A1	Continuous Overload (Motor)	several tens of seconds. A torque that largely exceeds the rated value is applied continuously.		
*78	A1	Overload (Converter)	Converter has overloaded.		
*7b		Amplifier overheat	Amplifier Overheat occurred.		
*7C	A1	Continuous Overload	A torque that exceeds largely the rated value is applied for several or		
, 0	Α.	(Amplifier)	several tens of seconds.		
*7d	A1	Momentary Overload	A torque that largely exceeds the rated value is applied continuously.		
*81	A1	Absolute Encoder Back-up	All power for the absolute encoder is down, and position data was		
		Error	cleared.		
*83	A1	Absolute Encoder Battery	The absolute value encoder's backup battery's voltage is low.		
*84	A1	Encoder Data Error 2-1	Internal data error of the encoder.		
*85	A1	Encoder Excessive Speed	Encoder was rotating at high speed during powering-up.		
*86	A1	Encoder Overheat	Over-heat of any type of encoder.		
*88	A1	Encoder error 1	Encoder error occurs.		
*89	A1	Encoder Command failed	Error occurs in response of encoder		
*8A	A1	Encoder multi-turn range	Encoder multi-turn range error occurred.		
*8C	A1	Encoder Reset not completed	Encoder Reset is not completed.		
*98	A1	Servo parameter error 1	Servo parameter is abnormal.		
*9A	A1	Feedback Over Flow	Feedback overflow occurs.		
*b4	A1	Servo Control Board Failure	Microprogram transfer error occurs.		
*bC		Encoder error 2	Encoder error occurs.		
*C1		Motor runaway detection	Servo motor ran out of control.		
*C9		Encoder Communication	Communication error between encoder and servo control board.		
*CE	A1	Encoder error 3	Encoder error occurs.		
*CF	A1	Encoder error 4	Encoder error occurs.		
*d0	A1	Position deviation error	The position deviation pulse has exceeded the set value.		
*d1	A1	Position deviation saturation	The position deviation saturated.		
*d2	A1	Motor directive position error	Motor directive position error occur.		
*d4	A1	Servo Tracking Error	Servo Tracking Error.		
*F1	A1	Phase loss	Phase loss (converter)		
E*1	A1	Positioning Timeout	After command is transmitted, the axis positioning cannot be completed.		
E*d	A1	Command not supported 1-2	Not ready for sending command to servo control board.		
E*E	A1	Communication Error	Communication error between the main control board and the servo		
E*E	۸.4	(internal controller) 1-1	control board happened		
E*F	A1	•	No response from servo control board.		
L		timeout 1.			

[Servo Error Code]

	Servo Error Code]				
Error	Level	Error Name	Description		
701	A2	ROM Error	Servo control board or ROM is defective.		
703	A2	Communication Error	Communication error between the main control board and the servo		
		(internal controller) 2-1	control board happened.		
704	A2	Communication Error	Communication error between the main control board and the servo		
	_	(internal controller) 2-2	control board happened.		
705	A2	Communication Error	Communication error between the main control board and the converter		
700	4.0	(internal controller) 2-3	happened.		
706	A2	Servo system error 1	System error occurred in servo control board.		
707	A2	Servo system error 2 Current feedback error	System error occurred in servo control board. The current is abnormal.		
709	A2				
70A 70b	A2 A2	Power Lost Rush Current Prevention	Power lost is detected. The rush current provention relay is abnormal.		
700	AZ		The rush current prevention relay is abnormal.		
70C	A2	Relay Abnormal Converter mismatch	The converter type is mismatched.		
70F	A2		No response from servo control board.		
701	72	timeout 2.	Two response from serve control board.		
713	A2	DB error	DB is abnormal.		
714		Converter charge Error	Converter charge error occurs.		
715	A2	Servo OFF Status Error 1	Hard wire base block error occurs.		
716	A2	Servo ON Status Error 1	Hard wire base enable error occurs.		
717	A2	Servo OFF Status Error 2	Base block error occurs.		
718	A2	Servo ON Status Error 2	Base enable error occurs.		
719	A2	Servo On Abnormal	Request hard wire base block release, but does not release.		
71A	A2	Brake circuit error 2	Brake lock error occurs.		
71b	A2	Brake circuit error 3	Brake unlock error occurs.		
71C	A2	Power relay error	Power relay is abnormal.		
721	A2	Servo parameter error 2	Servo parameter is abnormal.		
722	A2	Servo parameter error 3	Servo parameter is abnormal.		
725	A2	Converter Overheat	Detected the converter overheat.		
726	A2	Communication Error	Detected the undefined command.		
		(internal controller) 2-4			
727	A2	Command not supported 1-2	Detected the unsupported command.		
728	A2	Communication Error	Detected the data abnormal of the command.		
729	A2	(internal controller) 2-5 Servo system error 3	System error occurred in servo control board.		
72A	A2	Servo system error 4	System error occurred in servo control board.		
72b	A2	Servo parameter error 4	Servo parameter value is abnormal.		
730	A2	Amp module disconnected.	Amp module is not installed.		
732		Servo parameter error 5	Servo parameter is abnormal.		
733	A2	Servo parameter error 6	Servo parameter is abnormal.		
734	A2	Servo parameter error 7	Servo parameter is abnormal.		
735		Servo parameter error 8	Servo parameter is abnormal.		
73F	A2	Undefined Error	Receive the undefined error from the servo control board.		
740	A2	Encoder Status Error	PG ON Error occurs.		
741	A2	Servo system error 5	Requested the multiple servo on.		
742	A2	Servo system error 6	System error occurred in servo control board.		
743	A2	Servo system error 7	System error occurred in servo control board.		
744	A2	Servo system error 8	System error occurred in servo control board.		
745	A2	Servo system error 9	System error occurred in servo control board.		
746	A2	Servo system error 10	System error occurred in servo control board.		
74A	A2	Servo system error 11	System error occurred in servo control board.		
74b	A2	Servo system error 12	System error occurred in servo control board.		
74C	A2	Servo system error 13	System error occurred in servo control board.		
74d	A2	Servo system error 14	System error occurred in servo control board.		

[PAIF Board Error]

ir board Errorj				
Level	Error Name	Description		
W2	Communication Error	PAIF board received an undefined command.		
W2	Communication Error	PAIF board detected that the command's parameter value is out of		
	(internal controller) 3-2	range.		
W2	Command not supported 3-1	Detected the unsupported command.		
W2	Data buffer full	The data buffer is full.		
W2	Command not supported 3-2	Detected the unsupported command.		
W2	Encoder data error 3-1	The encoder data is abnormal.		
W2	Command not supported 3-3	Detected the unsupported command.		
W2	Communication Error	The PA board has not become ready.		
	(internal controller) 3-3			
W2	Communication Error	The PA board is not responding.		
	(internal controller) 3-4			
W2	CCD sensor abnormal 1	The CCD sensor head power supply voltage is low.		
W2	CCD sensor abnormal 2	CCD light source LED is off.		
W2	CCD sensor abnormal 3	CCD light source LED light intensity dropped.		
A1	PAIF board Failure 1	Watch dog of PAIF board was detected.		
A1	PAIF board Failure 2	Low Voltage was detected.		
A1	PAIF board Failure 3	Exception interrupt occurs.		
A1	CCD sensor abnormal 4	LED turn on but the light intensity is zero.		
W2	PAIF board disconnected	PAIF board is not installed.		
W2	PAIF board Failure 4	Over voltage was detected.		
W2	PAIF board Failure 5	The data acquisition failed.		
	W2 W1 W2	Level Error Name W2 Communication Error W2 Communication Error (internal controller) 3-2 W2 Command not supported 3-1 W2 Data buffer full W2 Command not supported 3-2 W2 Encoder data error 3-1 W2 Command not supported 3-3 W2 Communication Error (internal controller) 3-3 W2 Communication Error (internal controller) 3-4 W2 CCD sensor abnormal 1 W2 CCD sensor abnormal 2 W2 CCD sensor abnormal 3 A1 PAIF board Failure 1 A1 PAIF board Failure 3 A1 CCD sensor abnormal 4 W2 PAIF board failure 4		

Error	Level	Error Name	Description
900	W1	Character Interval Timeout	Host command message was interrupted.
910	W1	Received Data Checksum Error	The sum value of data received from the host is invalid.
920	W1	Unit Number Error	The command for an undefined unit was received from the host.
930	W1	Undefined Command Received	Received command from the host is undefined.
940	W1	Message Parameter Error	The parameter attached to the command received from the host is
950	W1	Receiving Time-out Error for Confirmation of Execution	The confirmation report of execution completion is not received from the host.
960	W1	Completion Incorrect sequence number	Incorrect sequence number in received command message from host.
961	W1	Duplicated message	Sequence number was the same as the one on previous received command message from host.
970	W1	Delimiter error	There is no delimiter.
9A1	W2	Message buffer overflow	Message buffer was full when the controller received the command from host.
9C0	W2	LAN device setting error	LAN device setting is invalid.
9C1	W2	IP address error	Set IP address is invalid.
9C2	W2	Subnet mask error	Set subnet mask is invalid.
9C3	W2	Default gateway error	Set default gate way is invalid.
9d0	W2	Ethernet receive error	Host message reception failure (Ethernet).
9E0	W2	During operation the maintenance tool	The request from the host is not acceptable because during operate the maintenance tool.
9E1	W2	The data abnormal	Because internal data was damaged when data is acquired with the maintenance tool, it could not be acquired.

Error	Level	Faren Neme	Description
code	Levei	Error Name	Description
A01	A2	Re-detection of a power	The fall of power supply voltage was re-detected.
		Supply voltage fall	
A10	A1	External emergency stop	External emergency stop (EXESP) enabled by I/O.
A20	A1	T.P emergency stop	T.P emergency stop button was pressed.
A21	A1	Interlock board failure 0	Detected the interlock board failure.
A30	A1	Emergency stop	Emergency stop is commanded from the host.
A40	W2	Controller Fan 1 Error	Error occurred in controller cooling fan 1.
A41	W2	Controller Fan 2 Error	Error occurred in controller cooling fan 2.
A42	W2	Controller Fan 3 Error	Error occurred in controller cooling fan 3.
A45	W2	Unit fan 1 error	Unit fan 1 is defective.
A46	W2	Unit fan 2 error	Unit fan 2 is defective.
A4F	W2	Controller Battery Alarm	Controller's memory backup battery is low.
AC0	A1	Safety fence signal detection	An safety fence (SAFF) signal is input from the I/O.
AC9	A1	Protection stop signal	Protection stop (ONEN) signal is input from the I/O.
AE0	W2	HOST Mode Switching error	The mode is switched to "HOST" while being controlled from the
			teaching pendant.
AE1	W2	ÿ	The mode is switched to "TEACH" while being controlled from the host.
AE8	W2	Deadman switch error	Deadman switch was released during teach pendant operation.
AF0	A2	Interlock board failure 1	Detected the interlock board failure.
AF1	A2	Interlock board failure 2	Detected the interlock board failure.
AF2	A2	Interlock board failure 3	Detected the interlock board failure.
AF3	A2	Interlock board failure 4	Detected the interlock board failure.
AF4	A2	Interlock board failure 5	Detected the interlock board failure.
AF5	A2	Interlock board failure 6	Detected the interlock board failure.
AF6	A2	Interlock board failure 7	Detected the interlock board failure.
AF8	A2	Input compare error 1	Cross-check compare error for the teach pendant emergency stop
AF9	A2	Input compare error 2	Cross-check compare error for the interlock input signal 1.
AFA	A2	Input compare error 3	Cross-check compare error for the external emergency stop signal
AFb	A2	Input compare error 4	Cross-check compare error for the deadman switch signal.
AFC	A2	Input compare error 5	Cross-check compare error for the safety fence signal (SAFF).
AFd	A2	Input compare error 6	Cross-check compare error for the Protection stop signal (ONEN).
AFE	A2	Input compare error 7	Cross-check compare error for the interlock input signal 2.
AFF	A2	Input compare error 8	Cross-check compare error for the interlock input signal 3.

Error	Level	Error Name	Description
b10	A1	Axis-1 Speed Limit Detection	Axis 1 exceeds the allowable speed.
b11	A1	Axis-2 Speed Limit Detection	Axis 2 exceeds the allowable speed.
b12	A1	Axis-3 Speed Limit Detection	Axis 3 exceeds the allowable speed.
b13	A1	Axis-4 Speed Limit Detection	Axis 4 exceeds the allowable speed.
b14	A1	Axis-5 Speed Limit Detection	Axis 5 exceeds the allowable speed.
b20	W2	Axis-1 Positive (+) Direction	Exceeds Axis-1 motion range in the positive direction.
		Software-limit Detection 1	
b21	W2	Axis-2 Positive (+) Direction	Exceeds Axis-2 motion range in the positive direction.
		Software-limit Detection 1	
b22	W2	Axis-3 Positive (+) Direction	Exceeds Axis-3 motion range in the positive direction.
haa	14/2	Software-limit Detection 1	Exceeds Axis-4 motion range in the positive direction.
b23	W2	Axis-4 Positive (+) Direction Software-limit Detection 1	Exceeds Axis-4 motion range in the positive direction.
b24	W2	Axis-5 Positive (+) Direction	Exceeds Axis-5 motion range in the positive direction.
D2-1		Software-limit Detection 1	2.00000 7 Me o motor range in the positive uncottern
b28	W2	Axis-1 Positive (+) Direction	Exceeds Axis-1 motion range in the positive direction when the mapping
		Software-limit Detection 2	motion start.
b29	W2	Axis-2 Positive (+) Direction	Exceeds Axis-2 motion range in the positive direction when the mapping
		Software-limit Detection 2	motion start.
b2A	W2	Axis-3 Positive (+) Direction	Exceeds Axis-3 motion range in the positive direction when the mapping
hah	W2	Software-limit Detection 2	motion start.
b2b	VVZ	Axis-4 Positive (+) Direction Software-limit Detection 2	Exceeds Axis-4 motion range in the positive direction when the mapping motion start.
b2C	W2	Axis-5 Positive (+) Direction	Exceeds Axis-5 motion range in the positive direction when the mapping
220	***	Software-limit Detection 2	motion start.
b30	W2	Axis-1 Negative (-) Direction	Exceeds Axis-1 motion range in the negative direction.
		Software-limit Detection 1	Ů
b31	W2	Axis-2 Negative (-) Direction	Exceeds Axis-2 motion range in the negative direction.
		Software-limit Detection 1	
b32	W2	Axis-3 Negative (-) Direction	Exceeds Axis-3 motion range in the negative direction.
b33	W2	Software-limit Detection 1 Axis-4 Negative (-) Direction	Exceeds Axis-4 motion range in the negative direction.
D33	VVZ	Software-limit Detection 1	Exceeds Axis-4 motion range in the negative direction.
b34	W2	Axis-5 Negative (-) Direction	Exceeds Axis-5 motion range in the negative direction.
		Software-limit Detection 1	3
b38	W2	Axis-1 Negative (-) Direction	Exceeds Axis-1 motion range in the negative direction when the
		Software-limit Detection 2	mapping motion start.
b39	W2	Axis-2 Negative (-) Direction	Exceeds Axis-2 motion range in the negative direction when the
L 0 A	14/0	Software-limit Detection 2	mapping motion start.
b3A	W2	Axis-3 Negative (-) Direction Software-limit Detection 2	Exceeds Axis-3 motion range in the negative direction when the mapping motion start.
b3b	W2	Axis-4 Negative (-) Direction	Exceeds Axis-4 motion range in the negative direction when the
200		Software-limit Detection 2	mapping motion start.
b3C	W2	Axis-5 Negative (-) Direction	Exceeds Axis-5 motion range in the negative direction when the
		Software-limit Detection 2	mapping motion start.
b40	W2	Access Permission Signal 1	Time-out of access permission signal 1 occurred.
1.44	14/0	Time-out Error	Time out of access name is in a local Control of
b41	W2	Access Permission Signal 2	Time-out of access permission signal 2 occurred.
b42	W2	Time-out Error Access Permission Signal 3	Time-out of access permission signal 3 occurred.
N72	112	Time-out Error	Timo out of access permission signal o occurred.
b43	W2	Access Permission Signal 4	Time-out of access permission signal 4 occurred.
		Time-out Error	,
b44	W2	Access Permission Signal 5	Time-out of access permission signal 5 occurred.
	_	Time-out Error	
b45	W2	Access Permission Signal 6	Time-out of access permission signal 6 occurred.
b 40	14/0	Time-out Error	Time out of appear norminging signal 7 assured
b46	W2	Access Permission Signal 7	Time-out of access permission signal 7 occurred.
		Time-out Error	

Error code	Level	Error Name	Description
b47	W2	Access Permission Signal 8	Time-out of access permission signal 8 occurred.
		Time-out Error	
b48	W2	Access Permission Signal 9	Time-out of access permission signal 9 occurred.
		Time-out Error	
b49	W2	Access Permission Signal 10	Time-out of access permission signal 10 occurred.
		Time-out Error	
b4A	W2	Access Permission Signal 11	Time-out of access permission signal 11 occurred.
		Time-out Error	
b4b	W2	Access Permission Signal 12	Time-out of access permission signal 12 occurred.
		Time-out Error	
b4C	W2	Access Permission Signal 13	Time-out of access permission signal 13 occurred.
		Time-out Error	
b4d	W2	Access Permission Signal 14	Time-out of access permission signal 14 occurred.
		Time-out Error	
b4E	W2	Access Permission Signal 15	Time-out of access permission signal 15 occurred.
		Time-out Error	
b4F	W2	Access Permission Signal 16	Time-out of access permission signal 16 occurred.
		Time-out Error	
b70	W2	SS signal detection	SS (software stop) signal was detected during operation.

Error code	Level	Error Name	Description
b80	W2	Fork 1/Pre-aligner: Wafer	The vacuum/grip sensor does not turn on within the specified time.
		Presence Confirmation Time-	
		out Error 1	
b81	W2	Fork 1/Pre-aligner: Wafer	The vacuum/grip sensor does not turn off within the specified time.
		Absence Confirmation Time-	
1-00	14/0	out Error 1	The water process (sheep a consequence at the constitution the
b82	W2	Fork 1/Pre-aligner: Wafer Presence Confirmation Time-	The wafer presence/absence sensor does not turn on within the specified time.
		out Error 2	specified time.
b83	W2	Fork 1/Pre-aligner: Wafer	The wafer presence/absence sensor does not turn off within the
		Absence Confirmation Time-	specified time.
		out Error 2	·
b8F	W2	Fork 1: Plunger non-operation	The plunger of Fork 1 did not move in the observed time.
	1110	error	
b90	W2	Fork 2: Wafer Presence	The vacuum/grip sensor does not turn on within the specified time.
b91	W2	Confirmation Time-out Error 1 Fork 2: Wafer Absence	The vacuum/grip sensor does not turn off within the specified time.
551	112	Confirmation Time-out Error 1	The factaring of sensor accorded tall on within the specified time.
b92	W2	Fork 2: Wafer Presence	The wafer presence/absence sensor does not turn on within the
		Confirmation Time-out Error 2	specified time.
b93	W2	Fork 2: Wafer Absence	The wafer presence/absence sensor does not turn off within the
		Confirmation Time-out Error 2	
b9F	W2		The plunger of Fork 2 did not move in the observed time.
bA0	W2	error Fork 1/Pre-aligner: Wafer	The vacuum/grip sensor or wafer presence/absence sensor turns off
DAU	VVZ	Absence Error	while the manipulator(Fork1)/Pre-aligner is transferring a wafer.
bA1	W2	Fork 1: Sensor Status	The vacuum/grip sensor of Fork 1 is on while the wafer
		Mismatch	presence/absence sensor is off.
bb0	W2	Fork 2: Wafer Absence Error	The suction/grip sensor or wafer presence/absence sensor turns off
			while Fork 2 is holding and transferring a wafer.
bb1	W2	Fork 2: Sensor Status	The suction/grip sensor of Fork 2 is on while the wafer
bF0	W2	Mismatch Stopped by HOLD signal	presence/absence sensor is off. Motion request is transmitted while the manipulator is being stopped by
DI U	***	Stopped by FIOLD signal	HOLD signal.
C80	W2	The alignment data error	Insufficient effective data for wafer alignment.
C90	W2	Notch/Orientation flat position	The notch/orientation flat position was not able to be distinguished.
		analysis error 1	
CA0		Center position detection	An accurate wafer center position could not be detected.
Cb0	W2	Excessive wafer eccentric	The wafer eccentric amount is excessive.
CC0	W2	Amount	An accurate notch/orientation flat position could not be detected.
000	V V Z	analysis error 2	An accurate notor/one italion hat position could not be detected.
Cd0	W2	Excessive arm correction	The amount corrected by alignment exceeds the allowable range.
		amount	, ,
CE0	W2	Robot pre-aligner distance	Could not execute arm calibration correctly.
		calculation error	
d00	W2	Mapping sensor error	Mapping sensor beam was already blocked at the mapping start
d10	W2	Mapping calibration error	Could not execute mapping calibration properly.
d20 d30	W2 W2	Mapping calibration Mapping sampling data error	Never executed mapping calibration. Sampling data for mapping or mapping calibration are abnormal.
d40	W2	Protruded wafer detection	Detected wafer protrusion when mapping or mapping calibration.
d50	W2	Mapping data chattering	Detected water profitusion when mapping of mapping calibration. Detected chattering when mapping or mapping calibration.
430		detected	2 5 5 5 5 5 6 6 6 6 6 6 6 6 6 6 6 6 6 6
d60	W2	Mapping motion failed	The mapping or the mapping calibration was not enforceable for "Top
			side GET / PUT station".

Error	Level	Error Name	Description
code	4.0	Development and a set welling	·
E90	A2	Parameter set value	System configuration error.
E91	A2	abnormal 1-0 Parameter set value	Manipulator configuration error.
E91	AZ	abnormal 1-1	Manipulator configuration error.
EA0	W2	Parameter set value	Real-type common parameter setting warning.
LAU	***	abnormal 2-0	recal type common parameter setting warning.
EA1	W2	Parameter set value	Integer-type common parameter setting warning.
		abnormal 2-1	miogor type common parameter coming manning.
EA4	W2	Parameter set value	Real-type unit parameter setting warning.
		abnormal 2-4	,, ,
EA5	W2	Parameter set value	Integer-type unit parameter setting warning.
		abnormal 2-5	
Eb0	A2	Parameter set value	Real-type common parameter setting is invalid.
	_	abnormal 3-0	
Eb1	A2	Parameter set value	Integer-type common parameter setting is invalid.
		abnormal 3-1	
Eb4	A2	Parameter set value	Real-type unit parameter setting is invalid.
Eb5	A2	abnormal 3-04 Parameter set value	Integer type unit peremeter cetting is invalid
EDS	AZ		Integer-type unit parameter setting is invalid.
EC0	A2	abnormal 3-5 Parameter set value	Software and setting parameter do not match.
LOU	72	abnormal 4-0	Contware and Setting parameter do not materi.
Ed0	A2	Memory operation error 0	Memory operation error occur.
Ed1	A2	Memory operation error 1	Memory operation error occur.
EE0	A2	File operation error 0	Failed to open file.
EE1	A2	File operation error 1	Failed to close file.
EE2	A2	File operation error 2	Failed to read file.
EE3	A2	File operation error 3	Failed to write file.
EE4	A2	File operation error 4	Failed to delete file.
EE5	A2	File operation error 5	Size of parameter initialization file is invalid.
EE8	A2	File operation error 8	Failed to create folder.
EF0	W2	Invalid data in file 0	Invalid data in "Format request file".
EF1	W2	Invalid data in file 1	Invalid data in "Auto update request file".
EF2	W2	Invalid data in file 2	Invalid data in "Servo parameter file".
EF3	W2	Invalid data in file 3	Invalid data in "Common parameter file".
EF4	W2	Invalid data in file 4	Invalid data in "Unit parameter file".
EF5	W2	Invalid data in file 5	Invalid data in "Position data file".
EF8	W2	Invalid data in file 8	Invalid data in "Servo parameter automatic update file".
EF9	W2	Invalid data in file 9	Invalid data in "Common parameter auto update file".
EFA	W2	Invalid data in file 10	Invalid data in "Unit parameter auto update file".
EFE	W2	Invalid data in file 14	File data abnormality 1 in the controller.
EFF	W2	Invalid data in file 15	File data abnormality 2 in the controller.

Error			
code	Level	Error Name	Description
F10	A2	System error 1-0	System error 1-0.
F11	A2	System error 1-1	System error 1-1.
F12	A2	System error 1-2	System error 1-2.
F14	A2	System error 1-4	System error 1-4.
F20	A2	System error 2-0	System error 2-0.
F21	A2	System error 2-1	System error 2-1.
F22	A2	System error 2-2	System error 2-2.
F50	F	System error 5-0	System error 5-0.
F51	F	System error 5-1	System error 5-1.
F61	F	System Error 6-1	System Error 6-1.
F62	F	System Error 6-2	System Error 6-2.
F70	F	System Error 7-0	System Error 7-0.
F82	F	System error 8-2	System error 8-2.
F83	F	System error 8-3	System error 8-3.
F84	F	System error 8-4	System error 8-4.
F86	F	System error 8-6	System error 8-6.
F88	F	System error 8-8	System error 8-8.
F90	F	System error 9-0	System trap 9-0.
F91	F	System error 9-1	System trap 9-1.
F92	F	System error 9-2	System trap 9-2.
F93	F	System error 9-3	System trap 9-3.
F94	F	System error 9-4	System trap 9-4.
F95	F	System error 9-5	System trap 9-5.
F98	F	System error 9-8	System trap 9-8.
F99	F	System error 9-9	System trap 9-9.
F9A	F	System error 9-10	System trap 9-10.
F9b	F	System error 9-11	System trap 9-11.
F9C	F	System error 9-12	System trap 9-12.
F9d	F	System error 9-13	System trap 9-13.
FA0	F	System error A-0	System trap A-0.
FA1	F	System error A-1	System trap A-1.
FA2	F	System error A-2	System trap A-2.
FA3	F	System error A-3	System trap A-3.
FA4	F	System error A-4	System trap A-4.
FA8	F	System error A-8	System trap A-8.
FA9	F	System error A-9	System trap A 10
FAA	F	System error A-10	System trap A 11
FAb	F	System error A-11	System trap A-11.
Fb0 Fb1	F	System error b-0 System error b-1	System trap b-0. System trap b-1.
Fb1	F	System error b-8	System trap b-8.
	F		•
Fb9	r	System error b-9	System trap b-9.

Error	Level	Error Name	Description
FC0	F	System error C-0	System trap C-0.
FC4	F	System error C-4	System trap C-4.
FC5	F	System error C-5	System trap C-5.
FC8	F	System error C-8	System trap C-8.
FCC	F	System error C-12	System trap C-12.
Fd0	F	System error d-0	System trap d-0.
Fd1	F	System error d-1	System trap d-1.
Fd2	F	System error d-2	System trap d-2.
Fd3	F	System error d-3	System trap d-3.
Fd4	F	System error d-4	System trap d-4.
Fd5	F	System error d-5	System trap d-5.
Fd6	F	System error d-6	System trap d-6.
Fd7	F	System error d-7	System trap d-7.
Fd8	F	System error d-8	System trap d-8.
Fd9	F	System error d-9	System trap d-9.
FdA	F	System error d-10	System trap d-10.
Fdb	F	System error d-11	System trap d-11.
FdC	F	System error d-12	System trap d-12.
Fdd	F	System error d-13	System trap d-13.
FdE	F	System error d-14	System trap d-14.
FdF	F	System error d-15	System trap d-15.
FE0	F	System error E-0	System trap E-0.
FE2	F	System error E-2	System trap E-2.
FE4	F	System error E-4	System trap E-4.
FE6	F	System error E-6	System trap E-6.
FE8	F	System error E-8	System trap E-8.
FEA	F	System error E-10	System trap E-10.
FEC	F	System error E-12	System trap E-12.