

UNIVERSITY OF SOUTHAMPTON

Modular Robot

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ABSTRACT

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This work is all about ...

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Listings

Chapter 1

Introduction

1.1 Biological Inspiration

Our biological inspiration ...

1.2 Existing Technologies

Information on similar systems already available ...

1.3 Project Specification

What our robot has to be able to do and what makes it special ...

Chapter 2

System Overview

an overview of the system ...

Chapter 3

Electromechanical Design

3.1 Servo

Servos ...

3.2 Chassis

Chassis ...

3.3 Prototyping

Prototyping ...

3.4 Subsections

Subsections ...

3.5 Summary etc

Summary ...

Chapter 4

Module Electronics Design

4.1 Overview

Overview ...

4.2 Communication

Communication ...

4.3 Sensors

Sensors ...

4.4 PCB Design

PCB Design ...

4.5 Summary etc

Summary ...

Chapter 5

Simulation

5.1 Overview

Overview ...

5.2 Modelling

Modelling ...

5.3 Movement

Shake it ...

5.4 Communication

Communication ...

5.5 Gaits

Gaits ...

5.6 Summary etc

Summary ...

Chapter 6

Results

Chapter 7

Project Management

Chapter 8

Conclusions

It works.

Chapter 9

Further Work

Appendix A

Breakdown of Labour

The butler did it ...

Appendix B

Minutes

around 60 seconds ...

Appendix C

Budget

Spending of monies . . .

Appendix D

Gantt Charts

When it all happened ...

Bibliography

S.R. Gunn. Pdflatex instructions, 2001.