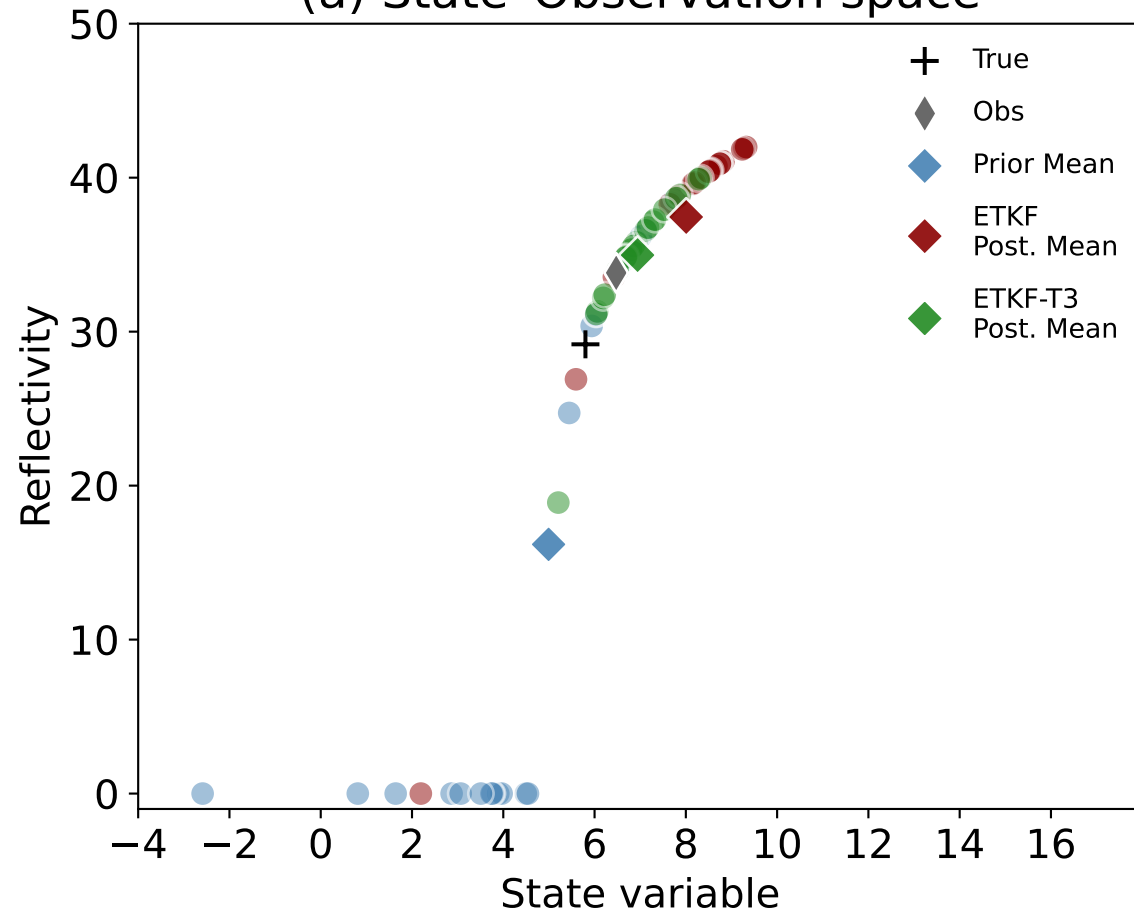
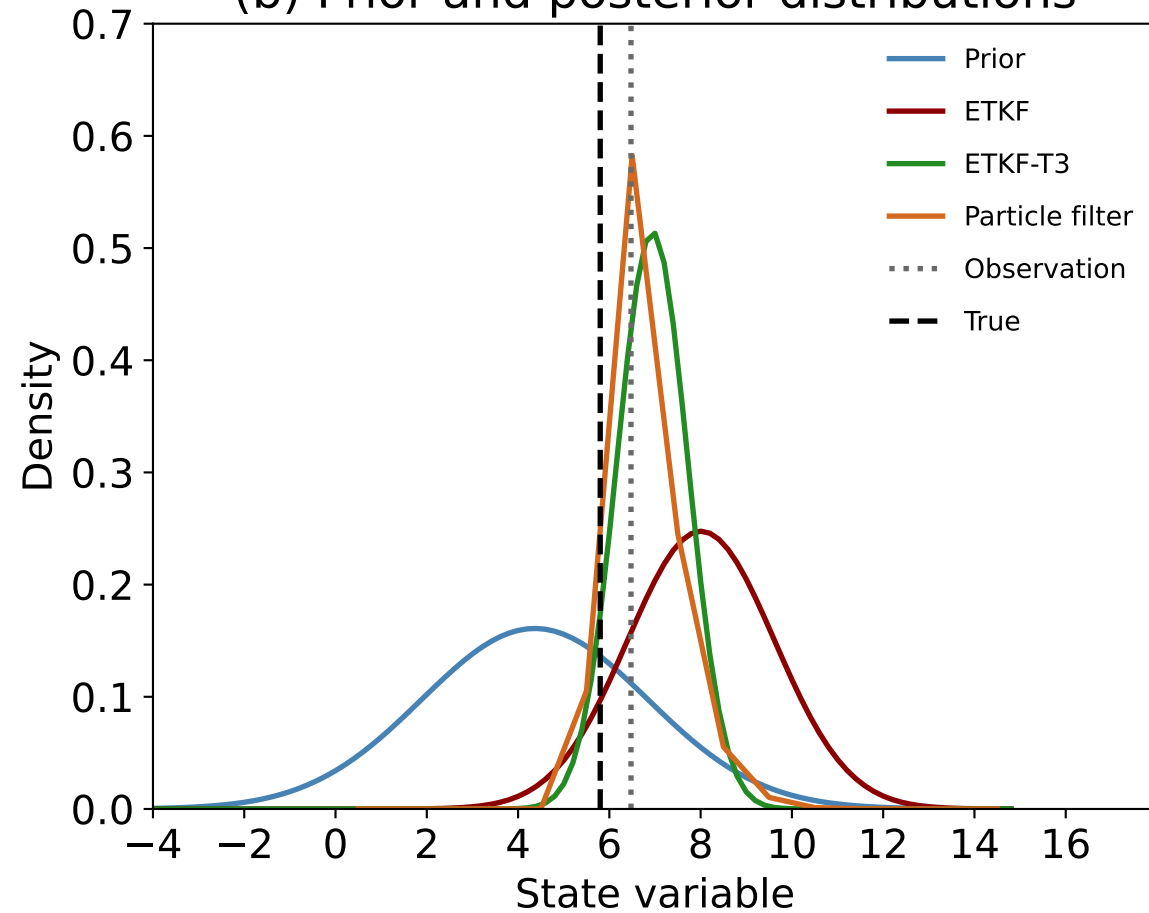


(a) State-Observation space



(b) Prior and posterior distributions



(c) Pseudo-time evolution

