

# Computing skew-stickiness

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# Outline of this talk

- The skew-stickiness ratio (SSR)
- The SSR from the characteristic function
- The SSR in affine forward variance models
- Forest expansion of the SSR
  - The small time limit
  - Dependence on the forward variance curve
  - Path dependence of the SSR
- The time series of SSR from Vola Dynamics

# Implied volatility

According to the definition of implied volatility  $\sigma_{BS}(k, T)$ , the market price of an option is given by

$$C(S, K, T) = C_{BS}(S, K, T, \sigma_{BS}(k, T))$$

where  $C_{BS}$  denotes the Black-Scholes formula and  $k = \log K/S$  is the log-strike.

# Updating European option prices

Market makers, when updating option prices using the Black-Scholes formula, typically consider two effects:

- The explicit spot effect

$$\frac{\partial C}{\partial S} \delta S$$

and

- The change in implied volatility conditional on a change in the spot

$$\frac{\partial C}{\partial \sigma} \mathbb{E} [\delta \sigma | \delta S].$$

# Estimating $\mathbb{E} [\delta\sigma(T)|\delta X]$

- ATM implied volatilities  $\sigma_t(T) = \sigma_{BS,t}(0, T)$  and stock prices are both observable.
- Market makers can estimate the second component using a simple regression:

$$\delta\sigma_t(T) = \beta_t(T) \frac{\delta S_t}{S_t} + \text{noise} =: \beta_t(T) \delta X_t + \text{noise}.$$

- Then

$$\beta_t(T) = \frac{\mathbb{E}_t [d \langle \sigma(T), X \rangle_t]}{\mathbb{E}_t [d \langle X \rangle_t]}.$$

# The skew-stickiness ratio

- For a given time to expiration  $T$ , we define the ATM volatility skew

$$\mathcal{S}_t(T) = \left. \frac{\partial}{\partial k} \sigma_{\text{BS}}(k, T) \right|_{k=0}.$$

- Bergomi [[Ber09](#), [Ber16](#)] calls

$$\mathcal{R}_t(T) = \frac{\beta_t(T)}{\mathcal{S}_t(T)}$$

the *skew-stickiness ratio* or *SSR*.

# Forward variance models

- Let  $S$  be a strictly positive continuous martingale.
  - Then  $X := \log S$  is a semimartingale with quadratic variation process  $\langle X \rangle$ .
- Defining  $V_t dt := d\langle X \rangle_t$ , forward variances are given by  $\xi_t(u) := \mathbb{E}[V_u | \mathcal{F}_t]$ ,  $u > t$ .
  - Forward variances are tradable assets (unlike spot variance).
  - We get a family of martingales indexed by their individual time horizons  $u$ .
- Following [BG12], it is natural to specify the dynamics of  $\xi_t(u)$  for each  $u > t$ .

# Our assumed model

- We would like to compute the SSR under stochastic volatility.
- Specifically, in a forward variance model of the form

$$\begin{aligned}\frac{dS_t}{S_t} &= \sqrt{V_t} dZ_t \\ d\xi_t(u) &= f_t(\xi) \kappa(u-t) dW_t,\end{aligned}\tag{1}$$

where  $X = \log S$ ,  $V_t dt = d\langle X \rangle_t$ , and  $d\langle Z, W \rangle_t = \rho dt$ .

- Such a model is scale-invariant, with  $\xi$  adapted to the filtration generated by  $W$ .



# Implied volatility from the characteristic function

- Let  $\Sigma_t(k, T) = \sigma_{BS,t}(k, T)^2 (T - t)$ .
- The Lewis representation of the option price gives Equation (5.7) of [Gat06],

$$\begin{aligned} & \int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[ e^{-i a k} e^{-\left(a^2 + \frac{1}{4}\right) \Sigma_t(k, T)} \right] \\ &= \int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[ e^{-i a k} \varphi_t(T; a - i/2) \right]. \end{aligned} \quad (2)$$

- An implicit relationship between  $\Sigma_t(k, T)$  and the characteristic function:

# Computation of $\mathcal{S}_t(T)$

- Differentiating (2) wrt  $k$ , and performing the integration on the LHS, we obtain (5.8) of [Gat06]:

$$\begin{aligned} \mathcal{S}_t(T) \\ = -e^{\Sigma_t(0,T)/8} \sqrt{\frac{2}{\pi}} \frac{1}{\sqrt{T-t}} \int_{\mathbb{R}^+} \frac{a da}{a^2 + 1/4} \Im[\varphi_t(T; a - i/2)]. \end{aligned} \quad (3)$$

- An explicit expression for the skew.

# Computation of the regression coefficient $\beta_t(T)$

- In a model of the form (1),  $\sigma_t(T)$  can only depend on the forward variances  $\{\xi_t(u) : u > t\}$ .
- With  $X = \log S$ , as in Equation (9.5) of [Ber16],

$$\beta_t(T) = \frac{\mathbb{E}_t[d \langle \sigma(T), X \rangle_t]}{\mathbb{E}_t[d \langle X \rangle_t]}.$$

- Recall that by assumption,

$$\begin{aligned} \frac{dS_t}{S_t} &= dX_t + \text{BV} = \sqrt{V_t} dZ_t, \\ d\xi_t(u) &= f_t(\xi) \kappa(u - t) dW_t, \end{aligned}$$

where BV denotes a bounded variation term.

- Applying Itô's Formula, denoting the Fréchet derivative by  $\delta$ ,

$$\begin{aligned} d \langle \sigma(T), X \rangle_t &= \int_t^T du \frac{\delta \sigma_t(T)}{\delta \xi_t(u)} d \langle \xi(u), X \rangle_t \\ &= \sqrt{V_t} \int_t^T du \frac{\delta \sigma_t(T)}{\delta \xi_t(u)} \rho f_t(\xi) \kappa(u - t) dt. \end{aligned}$$

- This gives

$$\beta_t(T) = \frac{\rho}{\sqrt{V_t}} \int_t^T \frac{\delta \sigma_t(T)}{\delta \xi_t(u)} f_t(\xi) \kappa(u - t) du. \quad (4)$$

# Nicer notation

- Let us define the operator

$$D_t^\xi := \frac{1}{\sqrt{V_t}} \int_t^T du f_t(\xi) \kappa(u - t) \frac{\delta}{\delta \xi_t(u)}.$$

- With this notation (4) becomes

$$\beta_t(T) = \rho D_t^\xi \sigma_t(T).$$

# Computation of $\beta_t(T)$

- Functionally differentiating (2) with respect to  $\xi_t(u)$  at  $k = 0$ ,

$$\begin{aligned} & \int_{\mathbb{R}^+} da \Re \left[ \frac{\delta \Sigma_t(0, T)}{\delta \xi_t(u)} e^{-\frac{1}{2} \left( a^2 + \frac{1}{4} \right) \Sigma_t(0, T)} \right] \\ &= \int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[ \frac{\delta}{\delta \xi_t(u)} \varphi_t(T; a - i/2) \right]. \end{aligned}$$

- The LHS may be integrated explicitly to give

$$\begin{aligned} & \frac{\delta \sigma_t(T)}{\delta \xi_t(u)} \\ &= e^{\frac{1}{8} \Sigma_t(0, T)} \sqrt{\frac{2}{\pi}} \frac{1}{\sqrt{T-t}} \int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[ \frac{\delta}{\delta \xi_t(u)} \varphi_t(T; a - i/2) \right]. \end{aligned}$$

- We get

$$\begin{aligned}\beta_t(T) &= \frac{\rho}{\sqrt{V_t}} \int_t^T \frac{\delta\sigma_t(T)}{\delta\xi_t(u)} f_t(\xi) \kappa(u-t) du \\ &= \rho e^{\frac{1}{8}\Sigma_t(0,T)} \sqrt{\frac{2}{\pi}} \frac{1}{\sqrt{T-t}} \int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[ D_t^\xi \varphi_t(T; a - i/2) \right].\end{aligned}\tag{5}$$

# A formula for the SSR $\mathcal{R}_t(T)$

- Substituting from (3) and (5), we obtain the formal expression

$$\mathcal{R}_t(T) = - \frac{\int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \rho \Re \left[ D_t^\xi \varphi_t(T; a - i/2) \right]}{\int_{\mathbb{R}^+} \frac{a da}{a^2 + 1/4} \Im [\varphi_t(T; a - i/2)]}.$$

- By definition of the cumulant generating function  $\psi$ ,  $\varphi = e^\psi$  and so we get

**Proposition 3.1: SSR from the characteristic function**

$$\mathcal{R}_t(T) = - \frac{\int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[ \rho D_t^\xi \psi_t(T; a - i/2) \exp \{ \psi_t(T; a - i/2) \} \right]}{\int_{\mathbb{R}^+} \frac{a da}{a^2 + 1/4} \Im [\exp \{ \psi_t(T; a - i/2) \}]}.$$

(6)



# Explicit computation in affine forward variance models

- In AFV models,  $d\xi_t(u) = \kappa(u - t) \sqrt{V_t} dW_t$ , so  $f_t(\xi) = \sqrt{V_t}$ .
- From [GKR19],

$$\psi_t(T; a) = \log \varphi_t(T; a) = \int_t^T \xi_t(s) g(T - s; a) ds, \quad (7)$$

where  $g$  satisfies the convolution Riccati equation

$$g(\tau; a) = -\frac{1}{2} a(a+i) + i \rho a (\kappa \star g)(\tau; a) + \frac{1}{2} (\kappa \star g)(\tau; a)^2. \quad (8)$$

- Functionally differentiating (7) gives, for  $u \in [t, T]$ ,

$$\frac{\delta}{\delta \xi_t(u)} \psi_t(T; a) = g(T - u; a).$$

- Thus,

$$D_t^\xi \psi_t(T; a - i/2) = (\kappa \star g)(T - t; a - i/2).$$

- Then, from (6), we obtain

### SSR in affine forward variance models

$$\mathcal{R}_t(T) = - \frac{\int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[ \rho(\kappa \star g)(T - t; a - i/2) e^{\int_t^T \xi_t(s) g(T-s; a - i/2) ds} \right]}{\int_{\mathbb{R}^+} \frac{a da}{a^2 + 1/4} \Im \left[ e^{\int_t^T \xi_t(s) g(T-s; a - i/2) ds} \right]} \quad (9)$$

- Given a solution  $g(\cdot)$  of the convolution Riccati equation (8), we may evaluate (9) numerically.
  - In particular,  $\mathcal{R}_t(T)$  may be evaluated in the rough Heston model.

# SSR under rough Heston ( $\lambda = 0$ ) for various $H$

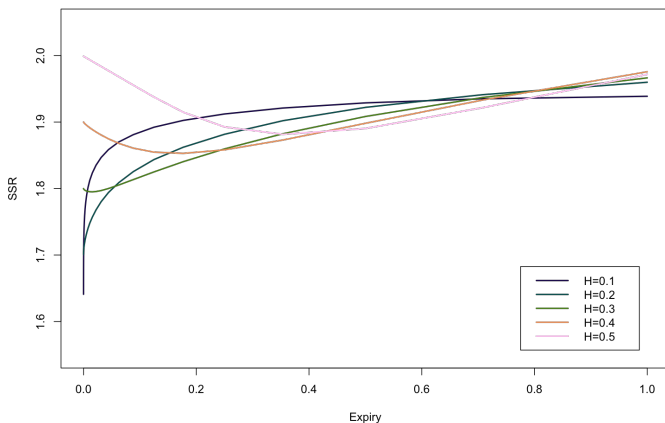


Figure 1: The rough Heston SSR with  $\xi = 0.025$ ,  $\rho = -0.8$ ,  $\nu = 0.4$  and the Padé (5,5) approximation [GR19, GR24] of the rough Heston solution.

# The diamond product

## Definition

Given two continuous semimartingales  $A, B$  with integrable covariation process  $\langle A, B \rangle$ , the diamond product of  $A$  and  $B$  is another continuous semimartingale given by

$$(A \diamond B)_t(T) := \mathbb{E}[\langle A, B \rangle_{t,T} | \mathcal{F}_t] = \mathbb{E}[\langle A, B \rangle_T | \mathcal{F}_t] - \langle A, B \rangle_t,$$

where  $\langle A, B \rangle_{t,T} = \langle A, B \rangle_T - \langle A, B \rangle_t$ .

# Diamond trees and forests

- The diamond product of two trees  $\mathbb{T}_1$  and  $\mathbb{T}_2$  is represented by *root joining*,

$$\mathbb{T}_1 \diamond \mathbb{T}_2 = \text{root joining of two trees}.$$

- The two binary trees  $\mathbb{T}_1$  and  $\mathbb{T}_2$  are represented as the single leaves ● and ●.
- We regard linear combinations of diamond trees as *forests*.
- In what follows,
  - =  $X_t$ ,
  - =  $M_t(T) = (X \diamond X)_t(T) = \int_t^T \xi_t(u) du$ .

# The $\tilde{\mathbb{F}}$ -forest expansion

With  $M_t(T) = \int_t^T \xi_t(u) du$ , the  $\tilde{\mathbb{F}}$ -expansion of [AGR2020] reads:

## The forest expansion

The cumulant generating function (CGF) is given by

$$\psi_t(T; a) = \log \mathbb{E}_t \left[ e^{i a X_T} \right] = i a X_t - \frac{1}{2} a (a + i) M_t(T) + \sum_{\ell=1}^{\infty} \tilde{\mathbb{F}}_{\ell}(a). \quad (10)$$

where the  $\tilde{\mathbb{F}}_{\ell}$  satisfy the recursion

$\tilde{\mathbb{F}}_0 = -\frac{1}{2} a (a + i) M_t = -\frac{1}{2} a (a + i) \bullet$  and for  $k > 0$ ,

$$\tilde{\mathbb{F}}_{\ell} = \frac{1}{2} \sum_{j=0}^{\ell-2} \left( \tilde{\mathbb{F}}_{\ell-2-j} \diamond \tilde{\mathbb{F}}_j \right) + i a \left( X \diamond \tilde{\mathbb{F}}_{\ell-1} \right).$$

## Second order computation of $\mathcal{R}_t(T)$

- Consider a formal expansion according to values of  $\ell$ .
- From (10), to second order in the forest expansion,

$$\psi_t(T; a - i/2) = -\frac{1}{2} \left( a^2 + \frac{1}{4} \right) \left\{ \bullet + (i a + \frac{1}{2}) \text{ (edge with grey node) } - \frac{1}{4} \left( a^2 + \frac{1}{4} \right) \text{ (edge with orange node) } - (a - i/2)^2 \text{ (triangle with orange and grey nodes) } \right\}$$

- The forest expansion (10) is effectively a small  $\nu$  (vol-of-vol) expansion where for fixed  $a$ , the  $\tilde{\mathbb{F}}_\ell(\tau)$  scale as  $\tau^{\ell\alpha+1}$  as  $\tau \downarrow 0$ .
- When computing  $\mathcal{R}_t(T)$  using (6), different powers of  $a$  will, after integration, generate different powers of  $\tau$ .
- In our paper, we take powers of  $a$  into account to get a next-to-leading-order small  $\tau$  expansion.
- Let's continue with our expansion to second order in  $\nu$ ...

- First we simplify the numerator of (6):

$$\Re \left[ e^{\psi_t(T; a-i/2)} D_t^\xi \left\{ \bullet + (i a + \frac{1}{2}) \text{ (diagram)} \right\} \right] \\ \approx e^{-\frac{1}{2} \left( a^2 + \frac{1}{4} \right)} M D_t^\xi \left\{ \bullet + \frac{1}{2} \text{ (diagram)} \right\}.$$

- Then we simplify the denominator:

$$\Im \left[ e^{\psi_t(T; a-i/2)} \right] = -\frac{1}{2} e^{-\frac{1}{2} \left( a^2 + \frac{1}{4} \right)} M a \left( a^2 + \frac{1}{4} \right) \left\{ \text{ (diagram)} + \text{ (diagram)} \right\}.$$

- This gives

## Second order forest expansion of SSR

$$\mathcal{R}_t(T) \approx \frac{M_t(T) \rho D_t^\xi \left\{ \bullet + \frac{1}{2} \text{ (diagram)} \right\}}{\text{ (diagram)} + \text{ (diagram)}}.$$



# Computation of $\mathcal{R}_t(T)$ to leading order

- Writing out  $D^{\xi_{\bullet}}$  and  $\bullet$  explicitly gives:

## Lemma 4.1

To leading order,

$$\mathcal{R}_t(T) = \frac{M_t(T)}{\sqrt{V_t}} \frac{\int_t^T f_t(\xi) \kappa(u-t) du}{\int_t^T ds \int_s^T \mathbb{E}_t [\sqrt{V_s} f_s(\xi)] \kappa(u-s) du}. \quad (11)$$

# The small time limit

- In the limit  $T \rightarrow t$ , we obtain

## Corollary

Let  $\tau = T - t$ . Then

$$\lim_{T \rightarrow t} \mathcal{R}_t(T) = \tau \frac{d}{d\tau} \log \left( \int_0^\tau ds \int_0^s \kappa(u) du \right).$$

- The following corollary confirms a formal computation of Fukasawa in Remark 2.10 of [Fuk21].

## Corollary

Let  $\kappa(s) = s^{\alpha-1} L_\kappa(s)$  where  $L_\kappa$  is a slowly varying function. Then

$$\lim_{T \rightarrow t} \mathcal{R}_t(T) = \alpha + 1.$$

## Dependence of $\mathcal{R}_t(T)$ on $\xi_t(u)$

- We rewrite the leading order expression (11) suggestively in the form

$$\mathcal{R}_t(T) = \frac{\left( \int_t^T \xi_t(s) ds \right) \int_t^T \sqrt{V_t} f_t(\xi) \kappa(u-t) du}{V_t \int_t^T ds \int_s^T \mathbb{E}_t [\sqrt{V_s} f_s(\xi)] \kappa(u-s) du}.$$

- We observe that this expression should be rather insensitive to the level of the forward variance curve.
- However,  $\mathcal{R}_t(T)$  is sensitive to the shape of  $\xi_t(u)$ .
  - A monotonic increasing forward variance curve will cause the SSR to increase relative to the flat curve case, and vice versa.

# The affine case

- In the case of AFV models,

$$\mathcal{R}_t(T) = \frac{\left( \int_t^T \xi_t(s) ds \right) \tilde{\kappa}(T-t)}{\int_t^T \xi_t(s) \tilde{\kappa}(T-s) ds},$$

where  $\tilde{\kappa}(\tau) = \int_0^\tau \kappa(s) ds$ .

- If the forward variance curve is flat with  $\xi_t(u) = \bar{V}$ , the SSR does not depend on the level  $\bar{V}$  at all!
- However, once again,  $\mathcal{R}_t(T)$  does depend on the shape of  $\xi_t(u)$ .

## An example: Rough Heston

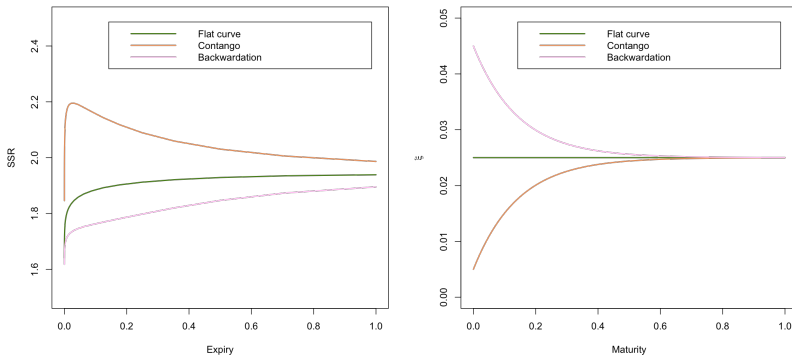
- In Figure 2, with parameters  $H = 0.1$ ;  $\nu = 0.4$ ;  $\rho = -.8$  we plot the rough Heston SSR using the AFV formula (9).
- We assuming three different forward variance curves of the form:

$$\xi_t(u) = (V_t - \bar{V}) e^{-\lambda t} + \bar{V},$$

with  $\bar{V} = 0.025$ ,  $\lambda = 7$  and  $V_t = 0.025$  (flat),  $V_t = 0.005$  (contango), and  $V_t = 0.045$  (backwardation).

- We observe that the SSR is very sensitive to the shape of the forward variance curve.

# An example: Rough Heston



**Figure 2:** The rough Heston SSR with various forward variance curves, and parameters  $H = 0.1$ ;  $\nu = 0.4$ ;  $\rho = -.8$ . The left-hand plot is of the SSRs and the right-hand plot shows the assumed forward variance curves.

# Path-dependence of the SSR

- In an AFV model, with  $dW_t = \rho dZ_t + \sqrt{1 - \rho^2} dZ_t^\perp$ ,

$$\begin{aligned}\xi_t(u) &= \bar{\xi} + \int_{-\infty}^t \kappa(u - r) \sqrt{V_r} dW_r \\ &= \bar{\xi} + \rho \int_{-\infty}^t \kappa(u - r) \frac{dS_r}{S_r} + \text{independent noise.}\end{aligned}$$

- The forward variance curve depends on a weighted average of historical stock returns.
- Thus  $\mathcal{R}_t(T)$  also depends on weighted average historical stock returns.
  - If recent returns are very negative, we expect  $\xi_t(u)$  to be backwardated, lowering  $\mathcal{R}_t(T)$ , and vice versa.
- This argument goes through for every forward variance model.
  - The forward variance curve is a noisy transform of the historical series of stock returns.

# Dependence of the SSR on the kernel

- We choose three rough Heston parameter sets that generate approximately the same 1m, 3m ,6m and 12m smiles.
  - $\lambda = 0, 1, 2$  respectively.

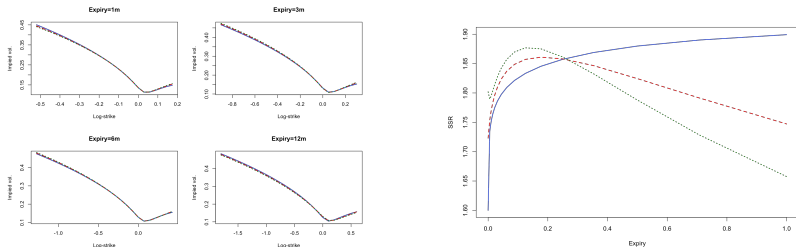


Figure 3: Left: 1m, 3m ,6m and 12m smiles. Right: Corresponding SSR plots.

- This shows that the SSR cannot be deduced in a model-free way from the volatility surface.
  - The SSR is sensitive to precise dynamical assumptions.



# Working paper

- For more details and other computations, please see [FG24].

# The time series of SSR from Vola Dynamics

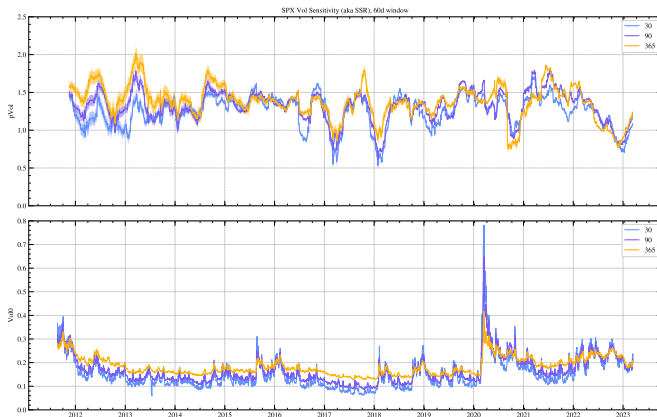


Figure 4: The 30 day, 90 day, and 1 year skew-stickiness ratios (SSR), with a trailing window of 60 days from Vola Dynamics.

# Is stochastic volatility consistent with the SSR time series?

- To be consistent with rough volatility, we would need  $\mathcal{R}(T) > \frac{3}{2}$ .
  - We see that, empirically,  $0.9 < \mathcal{R}(T) < 1.7$ .
- It certainly seems that the empirically observed SSR is inconsistent with any affine stochastic volatility model.
  - And from [BDDM24], also inconsistent with rough Bergomi.
- Is the empirically observed SSR is consistent with any stochastic volatility model?

- Figure 3 demonstrates that the SSR is highly dependent on assumed model dynamics.
  - This gives us hope that a model may be found that generates SSRs consistent with observation.
- Indeed, very recent results of Shaun Li in his thesis [Li24] suggest that the quintic model can jointly fit SPX and VIX, and generate reasonable values of the SSR!
  - Underlying the analysis is a signature expansion of the characteristic function [AJG24] and a version of our Proposition 3.1.
  - It seems that Equation (6) may be applicable to a much wider class of models than we originally thought.

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