

Computing skew-stickiness

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Outline of this talk

- The skew-stickiness ratio (SSR)
- The SSR from the characteristic function
- The SSR in affine forward variance models
- Forest expansion of the SSR
 - The small time limit
 - Dependence on the forward variance curve
 - Path dependence of the SSR
- The time series of SSR from Vola Dynamics

Implied volatility

According to the definition of implied volatility $\sigma_{\text{BS}}(k, T)$, the market price of an option is given by

$$C(S, K, T) = C_{\text{BS}}(S, K, T, \sigma_{\text{BS}}(k, T))$$

where C_{BS} denotes the Black-Scholes formula and $k = \log K/S$ is the log-strike.

Updating European option prices

Market makers, when updating option prices using the Black-Scholes formula, typically consider two effects:

- The explicit spot effect

$$\frac{\partial C}{\partial S} \delta S$$

and

- The change in implied volatility conditional on a change in the spot

$$\frac{\partial C}{\partial \sigma} \mathbb{E} [\delta \sigma | \delta S].$$

Estimating $\mathbb{E} [\delta\sigma(T) | \delta X]$

- ATM implied volatilities $\sigma_t(T) = \sigma_{BS,t}(0, T)$ and stock prices are both observable.
- Market makers can estimate the second component using a simple regression:

$$\delta\sigma_t(T) = \beta_t(T) \frac{\delta S_t}{S_t} + \text{noise} =: \beta_t(T) \delta X_t + \text{noise}.$$

- Then

$$\beta_t(T) = \frac{\mathbb{E}_t [d \langle \sigma(T), X \rangle_t]}{\mathbb{E}_t [d \langle X \rangle_t]}.$$

The skew-stickiness ratio

- For a given time to expiration T , we define the ATM volatility skew

$$\mathcal{S}_t(T) = \left. \frac{\partial}{\partial k} \sigma_{\text{BS}}(k, T) \right|_{k=0}.$$

- Bergomi [Ber09, Ber16] calls

$$\mathcal{R}_t(T) = \frac{\beta_t(T)}{\mathcal{S}_t(T)}$$

the *skew-stickiness ratio* or *SSR*.

Forward variance models

- Let S be a strictly positive continuous martingale.
 - Then $X := \log S$ is a semimartingale with quadratic variation process $\langle X \rangle$.
- Defining $V_t dt := d\langle X \rangle_t$, forward variances are given by $\xi_t(u) := \mathbb{E}[V_u | \mathcal{F}_t]$, $u > t$.
 - Forward variances are tradable assets (unlike spot variance).
 - We get a family of martingales indexed by their individual time horizons u .
- Following [BG12], it is natural to specify the dynamics of $\xi_t(u)$ for each $u > t$.

Our assumed model

- We would like to compute the SSR under stochastic volatility.
- Specifically, in a forward variance model of the form

$$\frac{dS_t}{S_t} = \sqrt{V_t} dZ_t$$
$$d\xi_t(u) = f_t(\xi) \kappa(u - t) dW_t, \quad (1)$$

where $X = \log S$, $V_t dt = d\langle X \rangle_t$, and $d\langle Z, W \rangle_t = \rho dt$.

- Such a model is scale-invariant, with ξ adapted to the filtration generated by W .

Implied volatility from the characteristic function

- Let $\Sigma_t(k, T) = \sigma_{BS,t}(k, T)^2 (T - t)$.
 - The Lewis representation of the option price gives Equation (5.7) of [Gat06],

$$\begin{aligned} & \int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[e^{-i a k} e^{-\left(a^2 + \frac{1}{4}\right) \Sigma_t(k, T)} \right] \\ &= \int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[e^{-i a k} \varphi_t(T; a - i/2) \right]. \end{aligned} \quad (2)$$

- An implicit relationship between $\Sigma_t(k, T)$ and the characteristic function:

Computation of $\mathcal{S}_t(T)$

- Differentiating (2) wrt k , and performing the integration on the LHS, we obtain (5.8) of [Gat06]:

$$\begin{aligned} \mathcal{S}_t(T) &= -e^{\Sigma_t(0,T)/8} \sqrt{\frac{2}{\pi}} \frac{1}{\sqrt{T-t}} \int_{\mathbb{R}^+} \frac{a \, da}{a^2 + 1/4} \Im [\varphi_t(T; a - i/2)]. \end{aligned} \quad (3)$$

- An explicit expression for the skew.

Computation of the regression coefficient $\beta_t(T)$

- In a model of the form (1), $\sigma_t(T)$ can only depend on the forward variances $\{\xi_t(u) : u > t\}$.
- With $X = \log S$, as in Equation (9.5) of [Ber16],

$$\beta_t(T) = \frac{\mathbb{E}_t [d \langle \sigma(T), X \rangle_t]}{\mathbb{E}_t [d \langle X \rangle_t]}.$$

- Recall that by assumption,

$$\frac{dS_t}{S_t} = dX_t + \text{BV} = \sqrt{V_t} dZ_t,$$

$$d\xi_t(u) = f_t(\xi) \kappa(u - t) dW_t,$$

where BV denotes a bounded variation term.

- Applying Itô's Formula, denoting the Fréchet derivative by δ ,

$$\begin{aligned} d \langle \sigma(T), X \rangle_t &= \int_t^T du \frac{\delta \sigma_t(T)}{\delta \xi_t(u)} d \langle \xi(u), X \rangle_t \\ &= \sqrt{V_t} \int_t^T du \frac{\delta \sigma_t(T)}{\delta \xi_t(u)} \rho f_t(\xi) \kappa(u-t) dt. \end{aligned}$$

- This gives

$$\beta_t(T) = \frac{\rho}{\sqrt{V_t}} \int_t^T \frac{\delta \sigma_t(T)}{\delta \xi_t(u)} f_t(\xi) \kappa(u-t) du. \quad (4)$$

Nicer notation

- Let us define the operator

$$D_t^\xi := \frac{1}{\sqrt{V_t}} \int_t^T du f_t(\xi) \kappa(u-t) \frac{\delta}{\delta \xi_t(u)}.$$

- With this notation (4) becomes

$$\beta_t(T) = \rho D_t^\xi \sigma_t(T).$$

Computation of $\beta_t(T)$

- Functionally differentiating (2) with respect to $\xi_t(u)$ at $k = 0$,

$$\begin{aligned} & \int_{\mathbb{R}^+} da \Re \left[\frac{\delta \Sigma_t(0, T)}{\delta \xi_t(u)} e^{-\frac{1}{2}(a^2 + \frac{1}{4}) \Sigma_t(0, T)} \right] \\ &= \int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[\frac{\delta}{\delta \xi_t(u)} \varphi_t(T; a - i/2) \right]. \end{aligned}$$

- The LHS may be integrated explicitly to give

$$\begin{aligned} & \frac{\delta \sigma_t(T)}{\delta \xi_t(u)} \\ &= e^{\frac{1}{8} \Sigma_t(0, T)} \sqrt{\frac{2}{\pi}} \frac{1}{\sqrt{T-t}} \int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[\frac{\delta}{\delta \xi_t(u)} \varphi_t(T; a - i/2) \right]. \end{aligned}$$

- We get

$$\begin{aligned}\beta_t(T) &= \frac{\rho}{\sqrt{V_t}} \int_t^T \frac{\delta\sigma_t(T)}{\delta\xi_t(u)} f_t(\xi) \kappa(u-t) du \\ &= \rho e^{\frac{1}{8} \Sigma_t(0, T)} \sqrt{\frac{2}{\pi}} \frac{1}{\sqrt{T-t}} \int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[D_t^\xi \varphi_t(T; a - i/2) \right].\end{aligned}\tag{5}$$

A formula for the SSR $\mathcal{R}_t(T)$

- Substituting from (3) and (5), we obtain the formal expression

$$\mathcal{R}_t(T) = -\frac{\int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \rho \Re \left[D_t^\xi \varphi_t(T; a - i/2) \right]}{\int_{\mathbb{R}^+} \frac{a da}{a^2 + 1/4} \Im [\varphi_t(T; a - i/2)]}.$$

- By definition of the cumulant generating function ψ , $\varphi = e^\psi$ and so we get

Proposition 3.1: SSR from the characteristic function

$$\mathcal{R}_t(T) = -\frac{\int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[\rho D_t^\xi \psi_t(T; a - i/2) \exp \{ \psi_t(T; a - i/2) \} \right]}{\int_{\mathbb{R}^+} \frac{a da}{a^2 + 1/4} \Im [\exp \{ \psi_t(T; a - i/2) \}]}.$$
(6)

Explicit computation in affine forward variance models

- In AFV models, $d\xi_t(u) = \kappa(u - t) \sqrt{V_t} dW_t$, so $f_t(\xi) = \sqrt{V_t}$.
- From [GKR19],

$$\psi_t(T; a) = \log \varphi_t(T; a) = \int_t^T \xi_t(s) g(T - s; a) ds, \quad (7)$$

where g satisfies the convolution Riccati equation

$$g(\tau; a) = -\frac{1}{2} a(a+i) + i\rho a (\kappa \star g)(\tau; a) + \frac{1}{2} (\kappa \star g)(\tau; a)^2. \quad (8)$$

- Functionally differentiating (7) gives, for $u \in [t, T]$,

$$\frac{\delta}{\delta \xi_t(u)} \psi_t(T; a) = g(T - u; a).$$

- Thus,

$$D_t^\xi \psi_t(T; a - i/2) = (\kappa \star g)(T - t; a - i/2).$$

- Then, from (6), we obtain

SSR in affine forward variance models

$$\mathcal{R}_t(T) = -\frac{\int_{\mathbb{R}^+} \frac{da}{a^2 + \frac{1}{4}} \Re \left[\rho(\kappa \star g)(T - t; a - i/2) e^{\int_t^T \xi_t(s) g(T-s; a-i/2) ds} \right]}{\int_{\mathbb{R}^+} \frac{a da}{a^2 + 1/4} \Im \left[e^{\int_t^T \xi_t(s) g(T-s; a-i/2) ds} \right]}. \quad (9)$$

- Given a solution $g(\cdot)$ of the convolution Riccati equation (8), we may evaluate (9) numerically.
 - In particular, $\mathcal{R}_t(T)$ may be evaluated in the rough Heston model.

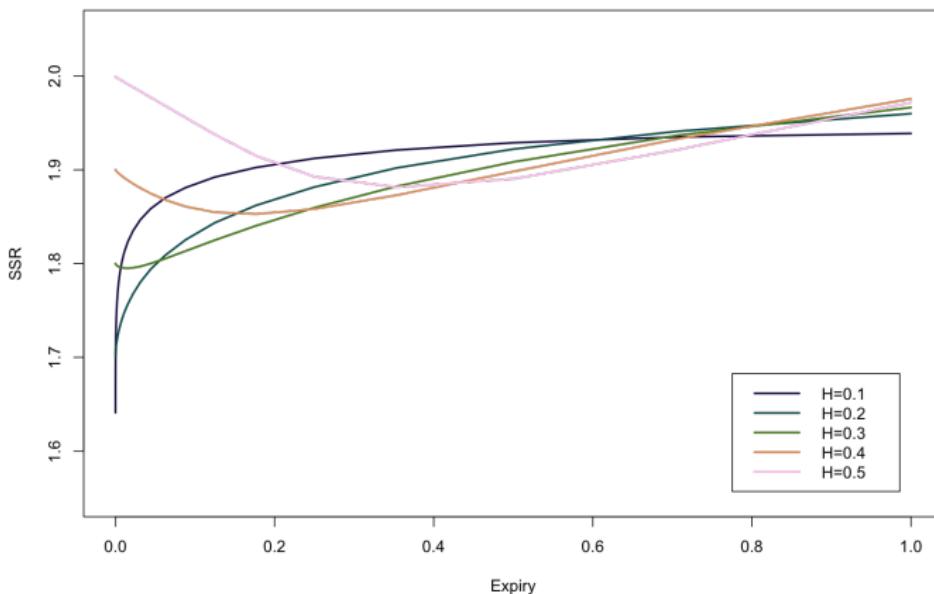
SSR under rough Heston ($\lambda = 0$) for various H 

Figure 1: The rough Heston SSR with $\xi = 0.025$, $\rho = -0.8$, $\nu = 0.4$ and the Padé (5,5) approximation [GR19, GR24] of the rough Heston solution.

The diamond product

Definition

Given two continuous semimartingales A, B with integrable covariation process $\langle A, B \rangle$, the diamond product of A and B is another continuous semimartingale given by

$$(A \diamond B)_t(T) := \mathbb{E} [\langle A, B \rangle_{t,T} | \mathcal{F}_t] = \mathbb{E} [\langle A, B \rangle_T | \mathcal{F}_t] - \langle A, B \rangle_t,$$

where $\langle A, B \rangle_{t,T} = \langle A, B \rangle_T - \langle A, B \rangle_t$.

Diamond trees and forests

- The diamond product of two trees \mathbb{T}_1 and \mathbb{T}_2 is represented by *root joining*,

$$\mathbb{T}_1 \diamond \mathbb{T}_2 = \bullet \vee \circ.$$

- The two binary trees \mathbb{T}_1 and \mathbb{T}_2 are represented as the single leaves \bullet and \circ .
- We regard linear combinations of diamond trees as *forests*.
- In what follows,

- $\circ = X_t$,
- $\bullet = M_t(T) = (X \diamond X)_t(T) = \int_t^T \xi_t(u) du$.

The $\tilde{\mathbb{F}}$ -forest expansion

With $M_t(T) = \int_t^T \xi_t(u) du$, the $\tilde{\mathbb{F}}$ -expansion of [AGR2020] reads:

The forest expansion

The cumulant generating function (CGF) is given by

$$\psi_t(T; a) = \log \mathbb{E}_t \left[e^{iaX_T} \right] = iaX_t - \frac{1}{2}a(a+i)M_t(T) + \sum_{\ell=1}^{\infty} \tilde{\mathbb{F}}_{\ell}(a). \quad (10)$$

where the $\tilde{\mathbb{F}}_{\ell}$ satisfy the recursion

$$\tilde{\mathbb{F}}_0 = -\frac{1}{2}a(a+i)M_t = -\frac{1}{2}a(a+i) \bullet \text{ and for } k > 0,$$

$$\tilde{\mathbb{F}}_{\ell} = \frac{1}{2} \sum_{j=0}^{\ell-2} \left(\tilde{\mathbb{F}}_{\ell-2-j} \diamond \tilde{\mathbb{F}}_j \right) + ia \left(X \diamond \tilde{\mathbb{F}}_{\ell-1} \right).$$

Second order computation of $\mathcal{R}_t(T)$

- Consider a formal expansion according to values of ℓ .
- From (10), to second order in the forest expansion,

$$\psi_t(T; a - i/2)$$

$$= -\frac{1}{2} \left(a^2 + \frac{1}{4} \right) \left\{ \bullet + \left(i a + \frac{1}{2} \right) \bullet \circ \circ - \frac{1}{4} \left(a^2 + \frac{1}{4} \right) \bullet \circ \bullet - (a - i/2)^2 \bullet \circ \circ \right\}$$

- The forest expansion (10) is effectively a small ν (vol-of-vol) expansion where for fixed a , the $\tilde{\mathbb{F}}_\ell(\tau)$ scale as $\tau^{\ell\alpha+1}$ as $\tau \downarrow 0$.
- When computing $\mathcal{R}_t(T)$ using (6), different powers of a will, after integration, generate different powers of τ .
- In our paper, we take powers of a into account to get a next-to-leading-order small τ expansion.
- Let's continue with our expansion to second order in ν ...

- First we simplify the numerator of (6):

$$\begin{aligned} & \Re \left[e^{\psi_t(T; a - i/2)} D_t^\xi \left\{ \bullet + (ia + \frac{1}{2}) \bullet \swarrow \bullet \right\} \right] \\ & \approx e^{-\frac{1}{2}(a^2 + \frac{1}{4})M} D_t^\xi \left\{ \bullet + \frac{1}{2} \bullet \swarrow \bullet \right\}. \end{aligned}$$

- Then we simplify the denominator:

$$\Im \left[e^{\psi_t(T; a - i/2)} \right] = -\frac{1}{2} e^{-\frac{1}{2}(a^2 + \frac{1}{4})M} a \left(a^2 + \frac{1}{4} \right) \left\{ \bullet \swarrow \bullet + \bullet \swarrow \bullet \right\}.$$

- This gives

Second order forest expansion of SSR

$$\mathcal{R}_t(T) \approx \frac{M_t(T) \rho D_t^\xi \left\{ \bullet + \frac{1}{2} \bullet \swarrow \bullet \right\}}{\bullet \swarrow \bullet + \bullet \swarrow \bullet}.$$

Computation of $\mathcal{R}_t(T)$ to leading order

- Writing out $D^\xi \bullet$ and $\circ \triangleright \circ$ explicitly gives:

Lemma 4.1

To leading order,

$$\mathcal{R}_t(T) = \frac{M_t(T)}{\sqrt{V_t}} \frac{\int_t^T f_t(\xi) \kappa(u-t) du}{\int_t^T ds \int_s^T \mathbb{E}_t [\sqrt{V_s} f_s(\xi)] \kappa(u-s) du}. \quad (11)$$

The small time limit

- In the limit $T \rightarrow t$, we obtain

Corollary

Let $\tau = T - t$. Then

$$\lim_{T \rightarrow t} \mathcal{R}_t(T) = \tau \frac{d}{d\tau} \log \left(\int_0^\tau ds \int_0^s \kappa(u) du \right).$$

- The following corollary confirms a formal computation of Fukasawa in Remark 2.10 of [Fuk21].

Corollary

Let $\kappa(s) = s^{\alpha-1} L_\kappa(s)$ where L_κ is a slowly varying function. Then

$$\lim_{T \rightarrow t} \mathcal{R}_t(T) = \alpha + 1.$$

Dependence of $\mathcal{R}_t(T)$ on $\xi_t(u)$

- We rewrite the leading order expression (11) suggestively in the form

$$\mathcal{R}_t(T) = \frac{\left(\int_t^T \xi_t(s) ds \right) \int_t^T \sqrt{V_t} f_t(\xi) \kappa(u-t) du}{V_t \int_t^T ds \int_s^T \mathbb{E}_t [\sqrt{V_s} f_s(\xi)] \kappa(u-s) du}.$$

- We observe that this expression should be rather insensitive to the level of the forward variance curve.
- However, $\mathcal{R}_t(T)$ is sensitive to the shape of $\xi_t(u)$.
 - A monotonic increasing forward variance curve will cause the SSR to increase relative to the flat curve case, and vice versa.

The affine case

- In the case of AFV models,

$$\mathcal{R}_t(T) = \frac{\left(\int_t^T \xi_t(s) ds \right) \tilde{\kappa}(T-t)}{\int_t^T \xi_t(s) \tilde{\kappa}(T-s) ds},$$

where $\tilde{\kappa}(\tau) = \int_0^\tau \kappa(s) ds$.

- If the forward variance curve is flat with $\xi_t(u) = \bar{V}$, the SSR does not depend on the level \bar{V} at all!
- However, once again, $\mathcal{R}_t(T)$ does depend on the shape of $\xi_t(u)$.

An example: Rough Heston

- In Figure 2, with parameters $H = 0.1$; $\nu = 0.4$; $\rho = -.8$ we plot the rough Heston SSR using the AFV formula (9).
- We assuming three different forward variance curves of the form:

$$\xi_t(u) = (V_t - \bar{V}) e^{-\lambda t} + \bar{V},$$

with $\bar{V} = 0.025$, $\lambda = 7$ and $V_t = 0.025$ (flat), $V_t = 0.005$ (contango), and $V_t = 0.045$ (backwardation).

- We observe that the SSR is very sensitive to the shape of the forward variance curve.

An example: Rough Heston

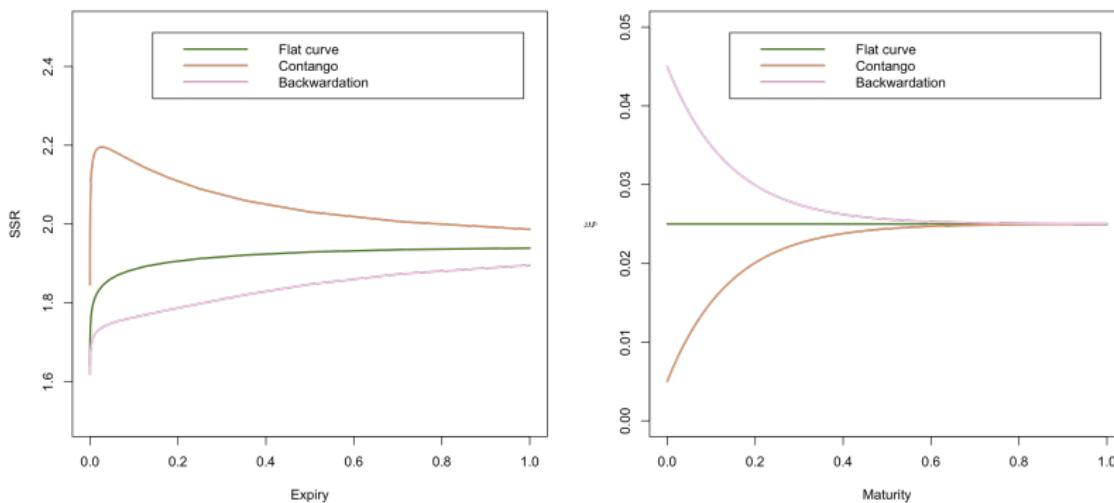


Figure 2: The rough Heston SSR with various forward variance curves, and parameters $H = 0.1$; $\nu = 0.4$; $\rho = -.8$. The left-hand plot is of the SSRs and the right-hand plot shows the assumed forward variance curves.

Path-dependence of the SSR

- In an AFV model, with $dW_t = \rho dZ_t + \sqrt{1 - \rho^2} dZ_t^\perp$,

$$\begin{aligned}\xi_t(u) &= \bar{\xi} + \int_{-\infty}^t \kappa(u - r) \sqrt{V_r} dW_r \\ &= \bar{\xi} + \rho \int_{-\infty}^t \kappa(u - r) \frac{dS_r}{S_r} + \text{independent noise.}\end{aligned}$$

- The forward variance curve depends on a weighted average of historical stock returns.
- Thus $\mathcal{R}_t(T)$ also depends on weighted average historical stock returns.
 - If recent returns are very negative, we expect $\xi_t(u)$ to be backwardated, lowering $\mathcal{R}_t(T)$, and vice versa.
- This argument goes through for every forward variance model.
 - The forward variance curve is a noisy transform of the historical series of stock returns.

Dependence of the SSR on the kernel

- We choose three rough Heston parameter sets that generate approximately the same 1m, 3m ,6m and 12m smiles.
 - $\lambda = 0, 1, 2$ respectively.

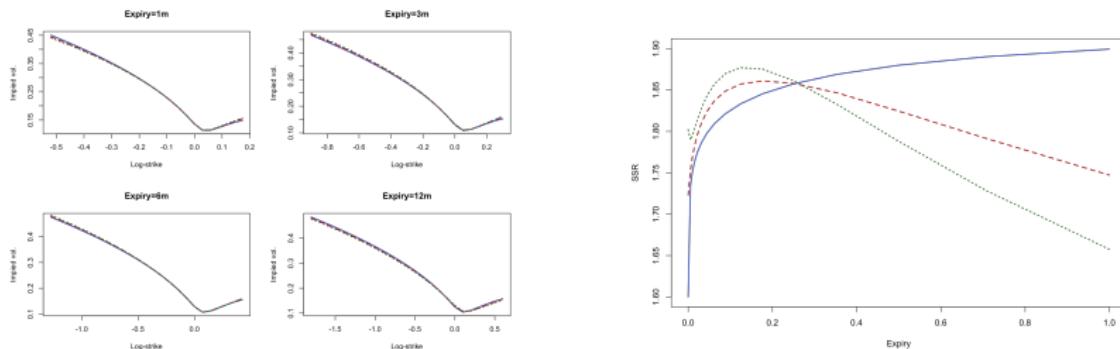


Figure 3: Left: 1m, 3m ,6m and 12m smiles. Right: Corresponding SSR plots.

- This shows that the SSR cannot be deduced in a model-free way from the volatility surface.
 - The SSR is sensitive to precise dynamical assumptions.

Working paper

- For more details and other computations, please see [FG24].

The time series of SSR from Vola Dynamics

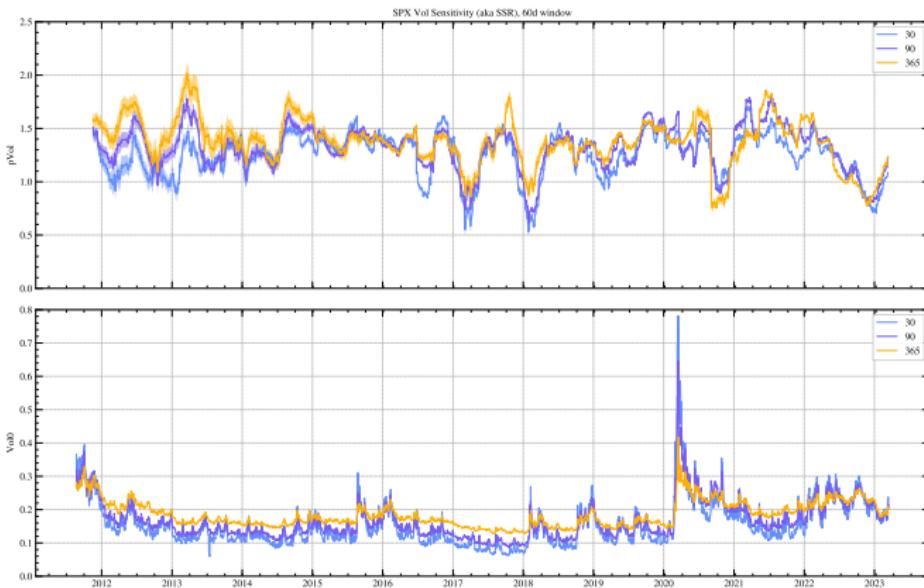


Figure 4: The 30 day, 90 day, and 1 year skew-stickiness ratios (SSR), with a trailing window of 60 days from Vola Dynamics.

Is stochastic volatility consistent with the SSR time series?

- To be consistent with rough volatility, we would need $\mathcal{R}(T) > \frac{3}{2}$.
 - We see that, empirically, $0.9 < \mathcal{R}(T) < 1.7$.
- It certainly seems that the empirically observed SSR is inconsistent with any affine stochastic volatility model.
 - And from [BDDM24], also inconsistent with rough Bergomi.
- Is the empirically observed SSR is consistent with any stochastic volatility model?

- Figure 3 demonstrates that the SSR is highly dependent on assumed model dynamics.
 - This gives us hope that a model may be found that generates SSRs consistent with observation.
- Indeed, very recent results of Shaun Li in his thesis [Li24] suggest that the quintic model can jointly fit SPX and VIX, and generate reasonable values of the SSR!
 - Underlying the analysis is a signature expansion of the characteristic function [AJG24] and a version of our Proposition 3.1.
 - It seems that Equation (6) may be applicable to a much wider class of models than we originally thought.

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