

① Método de EULER IMPLÍCITO

$$y_{k+1} = y_k + f(t_{k+1}, y_{k+1}) \cdot h$$

Aplicação ao oscilador harmônico

Simplex (OHS)

$$\begin{cases} v_{k+1} = v_k + f(t_{k+1}, y_{k+1}, v_{k+1}) \cdot h \end{cases}$$

$$y_{k+1} = y_k + v_{k+1} \cdot h$$

\Leftrightarrow

$$\begin{cases} v_{k+1} = v_k - \omega^2 y_{k+1} \cdot h \end{cases}$$

$$\begin{cases} y_{k+1} = y_k + v_{k+1} \cdot h \end{cases} \Leftrightarrow \text{(OHS)}$$

1) Método 1 \rightarrow implementar um ciclo

$$\begin{cases} \text{---} \\ y_{k+1} = y_k + (v_k - \omega^2 y_{k+1} \cdot h) \cdot h \end{cases}$$

(2)

$$\begin{cases} \text{---} \\ y_{k+1} = y_k + v_k \cdot h - \omega^2 h^2 y_{k+1} \end{cases} \Leftrightarrow$$

$$\begin{cases} \text{---} \\ (1 + \omega^2 h^2) y_{k+1} = y_k + v_k \cdot h \end{cases}$$

$$\begin{cases} \text{---} \\ y_{k+1} = \frac{y_k + v_k \cdot h}{1 + \omega^2 h^2} \end{cases}$$

$$\begin{cases} y_{k+1} = \frac{y_k + v_k \cdot h}{1 + \omega^2 h^2} \\ v_{k+1} = v_k - \omega^2 y_{k+1} \cdot h \end{cases}$$

Pode ser programado!

Implementar no ex: Cludio.Fon.

1) Método 2 → L-II N SOL-VE

$$\begin{cases} \sigma_{k+1} = \sigma_k - \omega^2 y_{k+1} h \\ y_{k+1} = y_k + \sigma_{k+1} h \end{cases} \quad (OHS)$$

⇔

$$\begin{cases} \sigma_{k+1} + \omega^2 y_{k+1} h = \sigma_k \\ y_{k+1} - \sigma_{k+1} h = y_k \end{cases} \quad \Leftrightarrow$$

$$y_{k+1} - \sigma_{k+1} h = y_k$$

$$\omega^2 h y_{k+1} + \sigma_{k+1} = \sigma_k$$

na forma matricial →

Método Euler-Implicito (2)

$$A z = b$$

$$A = \begin{bmatrix} 1 & -h \\ \omega^2 h & 1 \end{bmatrix} \quad z = \begin{bmatrix} y_{k+1} \\ \sigma_{k+1} \end{bmatrix} \quad b = \begin{bmatrix} y_k \\ \sigma_k \end{bmatrix}$$

② Método de CRANK-NICOLSON

$$y_{k+1} = y_k + \frac{h}{2} [f(t_k, y_k) + f(t_{k+1}, y_{k+1})]$$

Aplicação ao oscilador harmônico

Simplex (OTS)

$$v_{k+1} = v_k + [f(t_k, y_k) + f(t_{k+1}, y_{k+1})] \cdot \frac{h}{2}$$

$$y_{k+1} = y_k + [(v_k + v_{k+1})] \cdot \frac{h}{2}$$

⇔

$$y_{k+1} = y_k + (v_k + v_{k+1}) \cdot \frac{h}{2}$$

$$v_{k+1} = v_k - \omega^2 (y_k + y_{k+1}) \cdot \frac{h}{2}$$

⇔

⇔

③ Método 1 - Implementar no Excel

$$v_{k+1} = v_k - \omega^2 \left[y_k + y_{k+1} + (v_k + v_{k+1}) \frac{h}{2} \right] \frac{h}{2}$$

⇔

$$v_{k+1} = v_k - \omega^2 \left(\frac{2}{h} y_k + v_k \frac{h}{2} + v_{k+1} \frac{h}{2} \right) \frac{h}{2}$$

⇔

$$v_{k+1} + \frac{\omega^2 h^2}{4} v_{k+1} = v_k - \frac{\omega^2 h}{2} y_k - \frac{\omega^2 h^2}{4} v_k$$

Método Runge-Kutta

$$\left\{ \begin{aligned} & \Rightarrow \\ & v_{k+1} \left(1 + \frac{w^2 h^2}{4} \right) = -w^2 h y_k + \left(1 - \frac{w^2 h^2}{4} \right) v_k \end{aligned} \right.$$

$$v_{k+1} = \frac{-w^2 h y_k + \left(1 - \frac{w^2 h^2}{4} \right) v_k}{1 + \frac{w^2 h^2}{4}}$$

$$v_{k+1} = \frac{-w^2 h y_k + \left(1 - \frac{w^2 h^2}{4} \right) v_k}{1 + \frac{w^2 h^2}{4}}$$

$$y_{k+1} = y_k + \left[(v_k + v_{k+1}) \right] \cdot \frac{h}{2}$$

Pode ser programado!
(Código em anexo)

2) Método 2 - LINSOLVE (4)

$$\left\{ \begin{aligned} & y_{k+1} = y_k + (v_k + v_{k+1}) \cdot \frac{h}{2} \\ & v_{k+1} = v_k - w^2 (y_k + y_{k+1}) \cdot \frac{h}{2} \end{aligned} \right. \Rightarrow$$

$$y_{k+1} - v_{k+1} \cdot \frac{h}{2} = y_k + v_k \cdot \frac{h}{2} \Rightarrow$$

$$v_{k+1} + w^2 y_{k+1} \frac{h}{2} = v_k - w^2 \frac{h}{2} y_k$$

$$\begin{matrix} k+1 & & k \end{matrix}$$

$$y_{k+1} - \frac{h}{2} \cdot v_{k+1} = y_k + \frac{h}{2} v_k$$

$$w^2 \frac{h}{2} y_{k+1} + v_{k+1} = -w^2 \frac{h}{2} y_k + v_k$$

na forma matricial



$$\begin{bmatrix} 1 \\ \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} y_{k+1} \\ y_{k+1} \\ y_{k+1} \end{bmatrix} = \begin{bmatrix} y_k + \frac{1}{2} \sigma_k \\ -\frac{1}{2} y_k + \frac{1}{2} \sigma_k \\ y_k + \sigma_k \end{bmatrix}$$

A

~~Z~~

indefinite

b

to compute
do it twice
anterior

hinsolve!