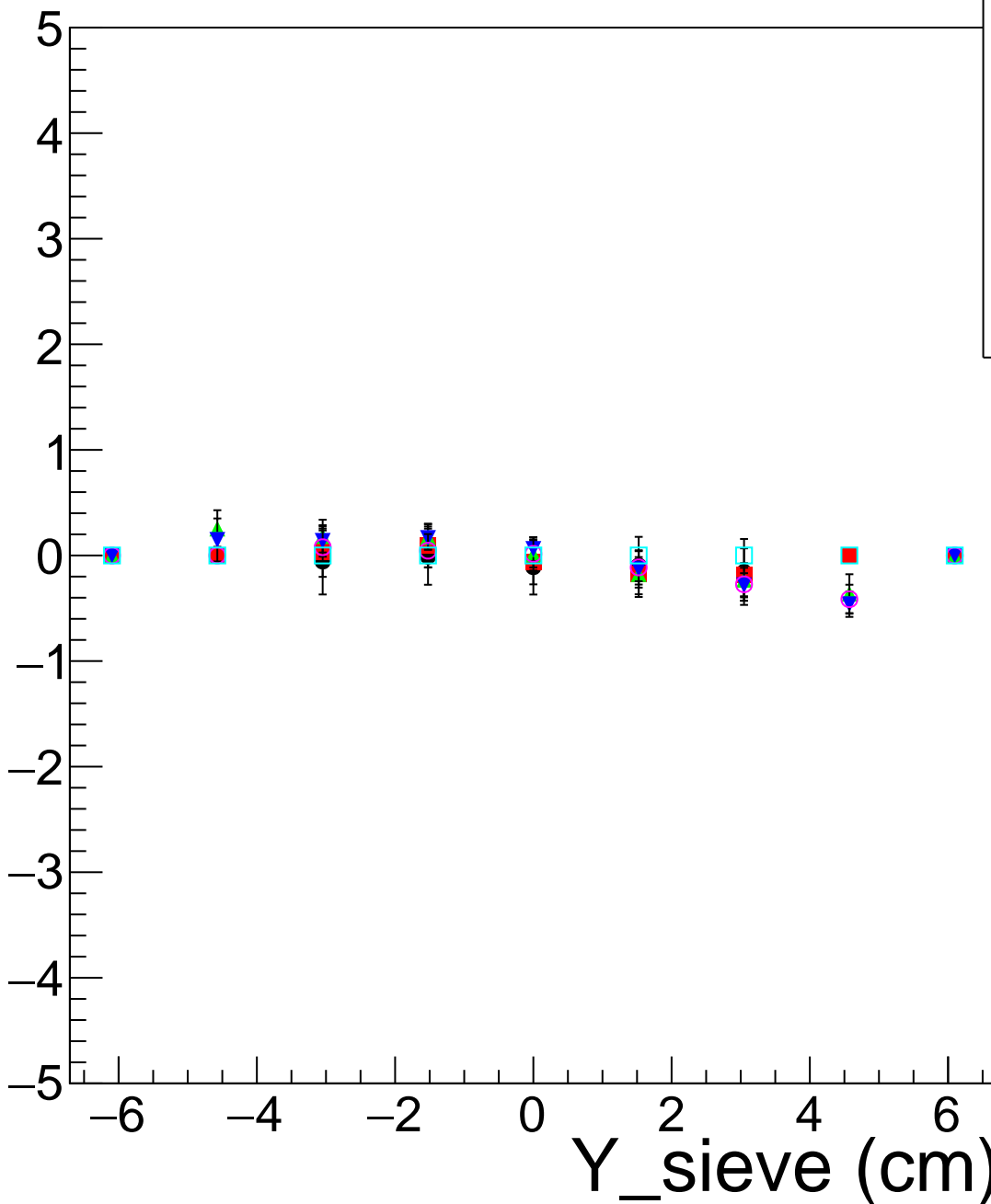


Ztar = 0.0 HMS Angle = 16.50

Ytar - Y_true (cm)



- Delta = -9.0
- Delta = -6.5
- ▲ Delta = -2.5
- ▼ Delta = 2.5
- Delta = 7.5
- Delta = 5.0