

Chapter 4

INTEGRAL TRANSFORMS

Lecture 16

4.3 Laplace Transform

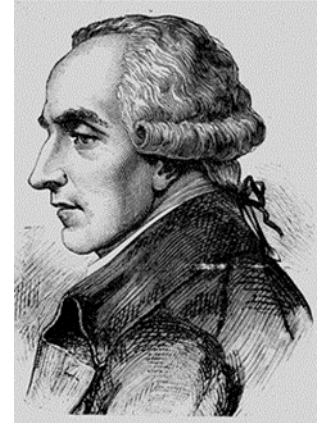


Joseph Fourier

(1768-1830)

Math/Physics

Fourier Series/Transform



Pierre-Simon Laplace

(1749-1827)

Math/Physic

Laplace Transform

Laplace Equation

(Scalar Potential Theory)

Scaling

$$\mathcal{L}[f(at)] = \frac{1}{a} F\left(\frac{s}{a}\right) \quad (4.43)$$

Shifting

$$\mathcal{L}[f(t-a)u(t-a)] = e^{-as} F(s), \quad a > 0 \quad (4.44)$$

Attenuation

$$\mathcal{L}[e^{-at} f(t)] = F(s+a), \quad a > 0 \quad (4.45)$$

Derivative

$$\mathcal{L}\left[\frac{df(t)}{dt}\right] = sF(s) - f(0) \quad (4.46)$$

$$\mathcal{L}[f^{(n)}(t)] = s^n F(s) - \sum_{k=1}^n s^{n-k} f^{(k-1)}(0)$$

Integral

$$\mathcal{L}\left[\int_0^t d\tau f(\tau)\right] = \frac{F(s)}{s} \quad (4.47)$$

Time Product

$$\mathcal{L}[t^n f(t)] = (-1)^n F^{(n)}(s) \quad (4.48)$$

Time Division

$$\mathcal{L}\left[\frac{1}{t} f(t)\right] = \int_s^\infty ds' F(s') \quad (4.49)$$

Periodic Function

$$\mathcal{L}[f(t) = f(t+T)] = \frac{1}{1-e^{-Ts}} \int_0^T dt f(t) \quad (4.50)$$

Initial/Final Values

$$f(0^+) = \lim_{s \rightarrow \infty} sF(s) \quad (4.51)$$

$$f(\infty) = \lim_{s \rightarrow 0} sF(s)$$

Inverse Laplace Transform: Partial Fraction Decomposition

For many problems, the LT is given by a ratio of two polynomials

$$F(s) = \frac{P_m(s)}{Q_n(s)} = \frac{p_0 + p_1s + p_2s^2 + \cdots + p_ms^m}{q_0 + q_1s + q_2s^2 + \cdots + q_ns^n}, \quad m < n \quad (4.52)$$

where without loss of generality we may assume that the degree of $P(s)$ is lower than that of $Q(s)$. By factoring $Q(s)$, we have in general

$$Q_n(s) = q_n (s - s_1)^{r_1} (s - s_2)^{r_2} \cdots (s - s_i)^{r_i} \cdots (s - s_n)^{r_n} \quad (4.53)$$

Here, s_i is the c_i^{th} -th order zeros (poles) of $Q(s)$ ($F(s)$),* and we have

$$F(s) = \left[\frac{S_1^{(1)}}{(s - s_1)} + \frac{S_1^{(2)}}{(s - s_1)^2} + \cdots + \frac{S_1^{(r_1)}}{(s - s_1)^{r_1}} \right] + \left[\frac{S_2^{(1)}}{(s - s_2)} + \frac{S_2^{(2)}}{(s - s_2)^2} + \cdots + \frac{S_2^{(r_2)}}{(s - s_2)^{r_2}} \right] \\ + \cdots + \left[\frac{S_n^{(1)}}{(s - s_n)} + \frac{S_n^{(2)}}{(s - s_n)^2} + \cdots + \frac{S_n^{(r_n)}}{(s - s_n)^{r_n}} \right] \quad (4.54)$$

* It should be noted that unfortunately there is no general zero-finding algorithm for n^{th} -order polynomials except for $n \leq 4$.

which is given in a compact form by

$$F(s) = \sum_{i=1}^n \left[\sum_{j=1}^{r_n} \frac{S_i^{(j)}}{(s-s_i)^j} \right] \quad (4.55)$$

include negative
Laurent expansion \subset *Taylor expansion* \rightarrow *Analytic part*

Inverse Laplace Transform: Residue Method

Now it should be noted that the summation in the parenthesis in (4.55) corresponds to a Principal part of Laurent series expansion for s_i (Lecture-8) and therefore we can use the Residue theorem.

Multiplying (4.55) by $(s-s_i)^{j-1}$, we have

$$(s-s_i)^{j-1} F(s) = \sum_{i=1}^n \left[\sum_{j=0}^{r_n} \frac{S_i^{(j)}}{s-s_i} \right] \quad (4.56)$$

Therefore we find that $A_i^{(j)}$ is just the **residue** of $(s-s_i)^{j-1} F(s)$ at each **simple pole** at s_i :

$$S_i^{(j)} = \text{Res} \left[(s-s_i)^{j-1} F(s) \right]_{s=s_i} = \frac{1}{(r_n-j)!} \lim_{s \rightarrow s_i} \frac{d^{r_n-j}}{ds^{r_n-j}} \left[(s-s_i)^{r_n} F(s) \right] \quad (4.57)$$

Ex) Simple poles

$$F(s) = \frac{1}{(s-2)(s-3)} = \frac{A}{s-2} + \frac{B}{s-3}$$

$$A = (s-2)F(s)\Big|_{s=2} = -1 \quad \rightarrow \quad f(t) = -e^{2t} + e^{3t}$$

$$B = (s-3)F(s)\Big|_{s=3} = 1$$

Ex) Simple and Double poles

$$F(s) = \frac{s^2 + s + 1}{s^2(s-1)^2} = \frac{A_1}{s} + \frac{A_2}{s^2} + \frac{B_1}{(s-1)} + \frac{B_2}{(s-1)^2}$$

two terms

$$A_1 = \frac{1}{1!} \frac{d}{ds} \frac{s^2 + s + 1}{(s-1)^2} \Big|_{s=0} = 3, \quad A_2 = \frac{1}{0!} \frac{s^2 + s + 1}{(s-1)^2} \Big|_{s=0} = 1 \quad \rightarrow \quad f(t) = 3 + t - 3e^t + 3te^t$$

$$B_1 = \frac{1}{1!} \frac{d}{ds} \frac{s^2 + s + 1}{s^2} \Big|_{s=1} = -3, \quad B_2 = \frac{1}{0!} \frac{s^2 + s + 1}{s^2} \Big|_{s=1} = 3$$

Classical 1-D Damped Oscillator

Damped oscillator is a model system in classical physics, and its dynamics is given by a simple Newton's equation with a frictional force,

$$m \frac{d^2 x(t)}{dt^2} + \gamma \frac{dx(t)}{dt} + kx(t) = 0$$

with the initial conditions of $x(0) = x_0$ and $v(0) = 0$.

Solution) Taking LT, for a small damping ($\gamma^2 < 4km$), we have

$$m[s^2 X(s) - sx_0] + \gamma[sX(s) - x_0] + kX(s) = 0$$

$$\rightarrow X(s) = \frac{ms + \gamma}{ms^2 + \gamma s + k} = \frac{s + \gamma/m}{\left(s + \frac{\gamma}{2m}\right)^2 + \left(\frac{k}{m} - \frac{\gamma^2}{4m^2}\right)}$$

and we find

$$x(t) = x_0 \exp\left(-\frac{\gamma}{2m}t\right) [\cos \omega_1 t - \phi]$$

$$\text{with } \omega_0^2 = \frac{k}{m}, \quad \omega_1^2 = \frac{k}{m} - \frac{\gamma^2}{4m^2} > 0, \quad \phi = \tan^{-1}\left(\frac{\gamma}{2m\omega_1}\right)$$

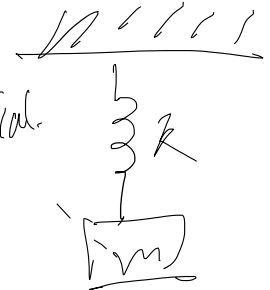
FT, LT
important theorem.

friction = dissipate energy to air molecule

Hook's law.

kinetic \leftrightarrow potential.

initial velocity.



Energy dissipated to thermal energy.