

Pyplis* | A Python based software package for the analysis of volcanic SO₂ emissions using UV SO₂ cameras

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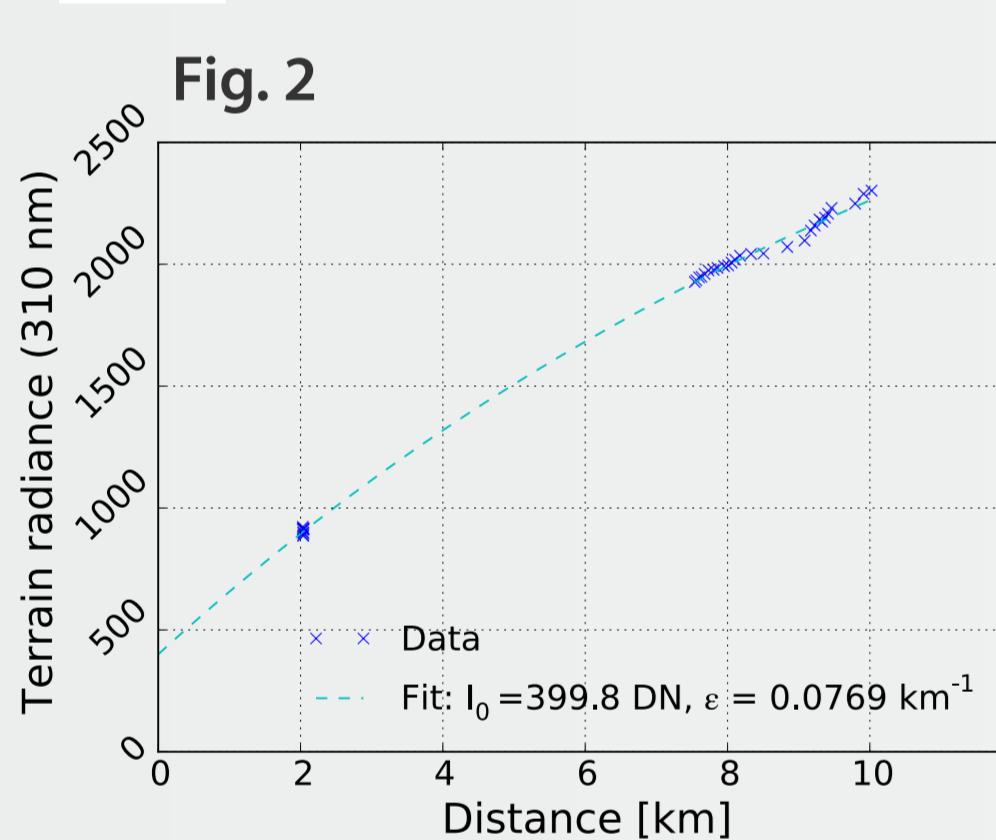
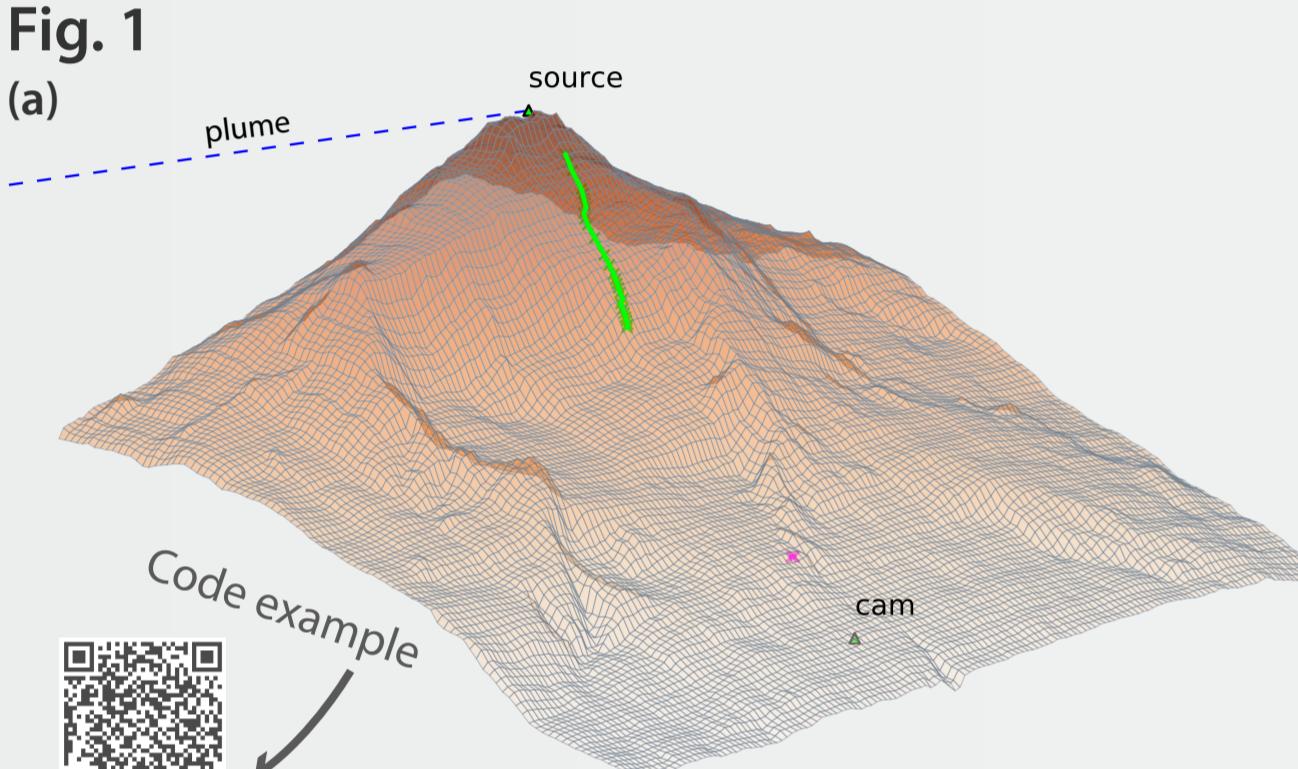


Main Features

- △ Easy setup of various data formats and camera specifications
- △ Detailed 3D geometrical calculations
- △ Routine for image based correction of the signal dilution effect
- △ Flexible options for retrieval of plume background intensities
- △ Engines for automated cell and DOAS calibration
- △ Optical flow and cross correlation based plume velocity retrievals
- △ Simultaneous emission rate retrievals for multiple retrieval lines

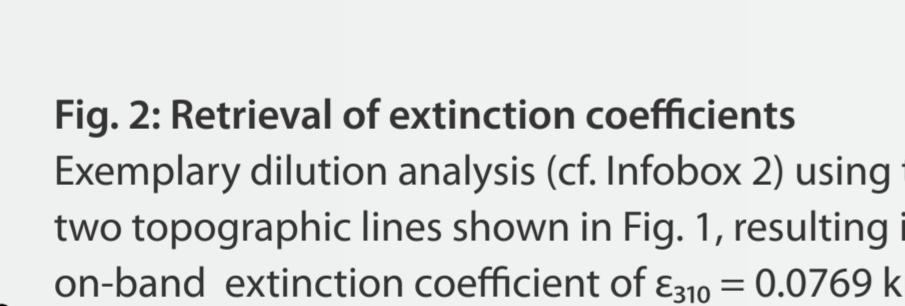
* due to a naming conflict, the software was renamed from *piscope* to *pyplis*

Measurement geometry and signal dilution correction



$$\text{Equation 1} | \text{Atmospheric scattering model}$$

$$I_{\text{meas}}(\lambda) = I_0(\lambda)e^{-\epsilon(\lambda)d} + I_A(\lambda)(1 - e^{-\epsilon(\lambda)d})$$



Infobox 1 | Geometrical calculations

Plume distances (required for emission rate retrieval) are retrieved on a pixel-level based on camera coordinates and plume azimuth. More features include:

- Retrieval of camera viewing direction using distinct features in the images (e.g. volcano summit)
- Retrieval of distances to local terrain features in the images on pixel-level (see Fig. 1)

Fig. 1a: 3D terrain map of the measurement setup including 2 topographic profile lines (green and magenta, defined in the image, cf. Fig. 1b) used for the signal dilution analysis (Fig. 2)

Fig. 1b: Exemplary on-band (310 nm) image. Due to SO₂ absorption the Etna plume appears darker than the sky background. Measured intensities along the two indicated lines are used to estimate the scattering extinction (cf. Fig. 2).



Plume background analysis

$$\text{Equation 2} | \text{Optical density (OD)}$$

$$\tau = \ln \left(\frac{I_0}{I} \right)$$

I_0 : measured plume intensity

I : corresponding background intensity

$$\text{Equation 3} | \text{SO}_2 \text{ apparent absorbance (AA)}$$

$$\tau_{\text{AA}} = \tau_{\text{on}} - \tau_{\text{off}}$$

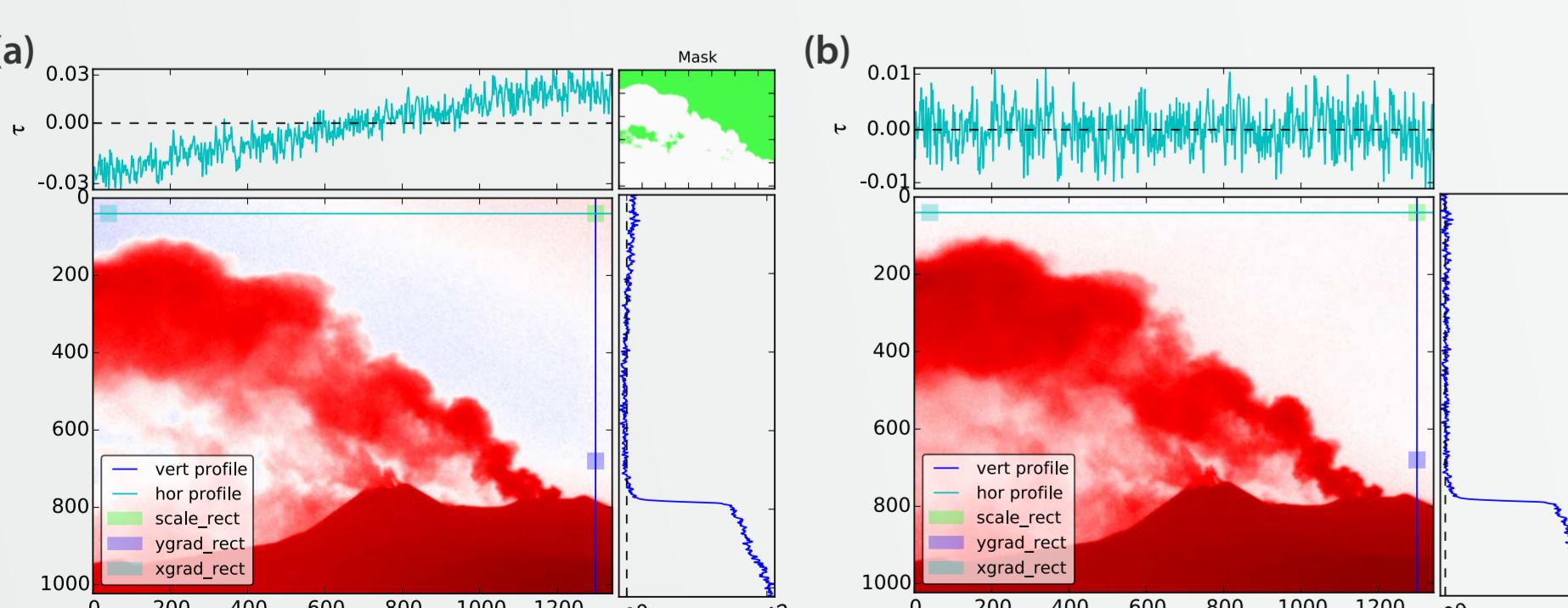


Fig. 3: Exemplary optical density images
Two exemplary on-band OD images calculated using a masked 2D polynomial fit (a) and using an additional sky background image (b), including 2. order horizontal and vertical sky gradient corrections along the indicated vertical and horizontal profile lines.

Infobox 3 | Calculation of optical density (OD) images

The calculation of OD images (Eq. 2) requires knowledge of the sky background intensities behind the plume. These can either be retrieved from the plume images directly (by fitting a 2D polynomial to clear sky areas, cf. Fig. 3a) or using a sky reference image which is scaled using a gas free sky area in the plume image (cf. scale_rect in Fig. 3). The latter may include further corrections to account for variations in the sky background curvature between the two images (cf. Fig. 3b).



$$\text{Equation 4} | \text{SO}_2 \text{ column density (CD)}$$

$$S_{\text{SO}_2} = \int_c c_{\text{SO}_2}(x, y, z) ds$$

$$\text{Equation 4} | \text{Cell calibration}$$

$$S_{\text{SO}_2} : \text{SO}_2 - \text{column density (CD)}$$

$$c : \text{photon trajectory}$$

$$c_{\text{SO}_2} : \text{SO}_2 \text{ concentration distribution}$$

Plume background analysis

Infobox 5 | DOAS calibration

The DOAS calibration is performed using plume SO₂-CDs retrieved with a co-located DOAS spectrometer. Position and shape of the DOAS FOV within the camera images (cf. Fig. 6) can be retrieved using either of the two methods suggested by [2] and [3]. Both methods identify the pixel region showing highest correlation between a time series of DOAS SO₂-CDs and camera images. The calibration curve (Fig. 5) is then retrieved from a time series of AA values (extracted within the DOAS FOV) and the corresponding DOAS SO₂-CDs. The DOAS calibration is more accurate in case aerosols are abundant in the plume [2].

Infobox 6 | Cross correlation

The plume velocity is retrieved from a time-series of images based on the cross correlation lag between the integrated-column-amount (ICA) of two plume intersections (e.g. [4], cf. Fig. 7).

Infobox 7 | Optical flow

Optical flow (OF) algorithms detect motion in consecutive frames allowing for the retrieval of gas velocities on pixel-level (e.g. [5]). An estimate of the gas velocity within low contrast image regions (where the OF algorithm fails to detect motion) can be inferred based on distinct peaks in histograms calculated from the optical flow field (Fig. 8). Pyplis includes an implementation of the Farnebäck optical flow algorithm [6].

Infobox 8 | Optical flow

Exemplary Farnebäck optical flow field (left) including histograms of the flow vector orientation angles (middle) and magnitudes (right) for two different ROIs around the indicated PCS lines (blue, orange).

Infobox 9 | SO₂ emission rate analysis

Emission rates are retrieved from calibrated SO₂-CD images using Eq. 5. The integration can be performed along linear plume intersections (see e.g. Fig. 6). Plume distances are calculated from the measurement geometry (see Infobox 1). Gas velocities can either be retrieved using an optical flow algorithm or using signal cross correlation (cf. Infoboxes 6 & 7).

Infobox 10 | Emission rate integral

Equation 5 | Emission rate integral

$$\Phi(\ell) = f^{-1} \sum_{m=1}^M S_{\text{SO}_2}(m) \cdot \langle \mathbf{v}(m) \cdot \hat{\mathbf{n}} \rangle \cdot d_{\text{pl}}(m) \cdot \Delta s(m)$$

SO₂ emission rate retrieval

Equation 5 | Emission rate integral

$$\Phi(\ell) = f^{-1} \sum_{m=1}^M S_{\text{SO}_2}(m) \cdot \langle \mathbf{v}(m) \cdot \hat{\mathbf{n}} \rangle \cdot d_{\text{pl}}(m) \cdot \Delta s(m)$$

$\Phi(\ell)$: emission rate through PCS line ℓ

f : camera focal length

$S_{\text{SO}_2}(m)$: SO₂ – CD at pixel pos. m on ℓ

$\mathbf{v}(m)$: gas velocity vector at pixel pos. m on ℓ

$\hat{\mathbf{n}}$: normal vector at pixel pos. m on ℓ

$d_{\text{pl}}(m)$: plume distance at pixel pos. m on ℓ

$\Delta s(m)$: discrete integration step at pixel pos. m on ℓ

$\mathbf{v}(m)$: optical flow vector at pixel pos. m on ℓ

$\hat{\mathbf{n}}$: normal vector at pixel pos. m on ℓ

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